

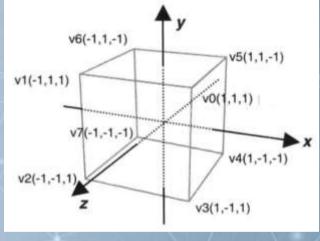
Element Array & External 3D Model & GLSL Syntax

CSU0021: Computer Graphics



Draw a Cube

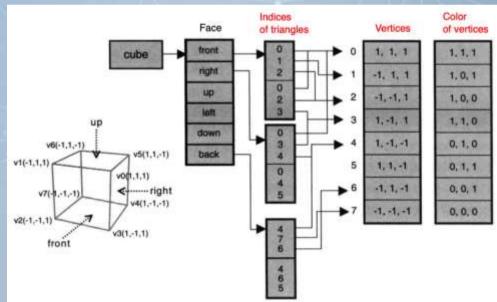
- A cube consists of 6 faces and each face may consist of 2 triangles.
- You have to define and pass 6*2*3 = 36 vertices to VBO and call gl.drawArray(gl.TRIANGLES, 0, 36)
- Many vertices are redundantly defined
 - This way to define an object really wastes the storage



```
var vertices - new Float32Array([
1.0, 1.0, 1.0, -1.0, 1.0, 1.0, -1.0, 1.0, // v0, v1, v2
1.0, 1.0, 1.0, -1.0, -1.0, 1.0, 1.0, -1.0, 1.0, // v0, v2, v3
1.0, 1.0, 1.0, 1.0, -1.0, 1.0, 1.0, -1.0, -1.0, // v0, v3, v4
```

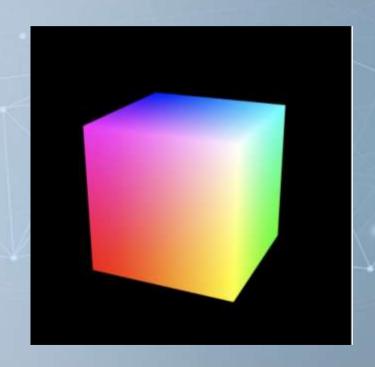
Element Array

- Define the exact same number of vertices of the object
- Still use triangle to define the connectivity. So, construct triangles by indexing to these vertices

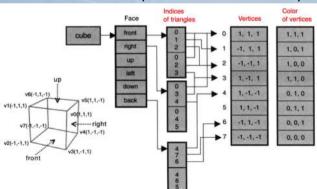


Draw a colored cube

- Files
 - index.html
 - WebGL.js
 - cuon-matrix.js



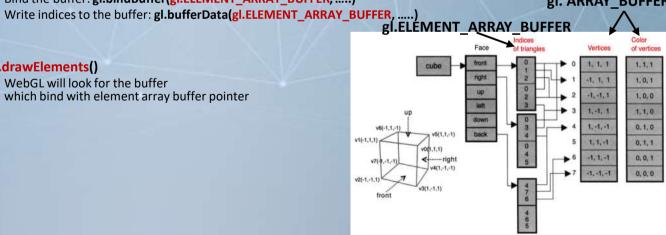
- initVertexBuffers() in WebGL.js
- Prepare the vertex and index arrays
 - We define 8 vertices in "vertices"
 - Each row of "vertices" array includes "x,
 y, z, r, g, b" of a vertex
 - "indicies" array:
 - each row is a face of the cube
 - Each index points to "vertices" array



```
function initVertexBuffers(gl, program){
    var vertices = new Float32Array(
            1.0, 1.0, 1.0, 1.0, 1.0, 1.0,
            -1.0, 1.0, 1.0, 1.0, 0.0, 1.0,
            -1.0, -1.0, 1.0, 1.0, 0.0, 0.0,
            1.0, -1.0, 1.0, 1.0, 1.0, 0.0,
            1.0, -1.0, -1.0, 0.0, 1.0, 0.0,
            1.0, 1.0, -1.0, 0.0, 1.0, 1.0,
            -1.0, 1.0, -1.0, 0.0, 0.0, 1.0,
            -1.0, -1.0, -1.0, 0.0, 0.0, 0.0
    var indices = new Uint8Array(
            0, 1, 2, 0, 2, 3, //front
            0, 3, 4, 0, 4, 5, //right
            0, 5, 6, 0, 6, 1, //up
            1, 6, 7, 1, 7, 2, //left
            7, 4, 3, 7, 3, 2, //bottom
            4, 7, 6, 4, 6, 5
                               //back
```

Array Buffer and Element Array Buffer Creation and Rendering

- Steps to create buffers
 - Create array buffers for "vertices" and "color of vertices" (the same as usual)
 - Create a buffer: gl.createBuffer()
 - Bind the buffer: gl.bindBuffer(gl.ARRAY BUFFER,)
 - Write vertices information to the buffer: gl.bufferData(gl.ARRAY BUFFER,)
 - Assign the buffer to an "attribute" variable in vertex shader: gl.vertexAttribPointer()
 - Enable the attribute variable: gl.enableVertexAttributeArrav()
 - Create element buffer for "indices of triangles"
 - Create buffer: gl.createBuffer()
 - Bind the buffer: gl.bindBuffer(gl.ELEMENT ARRAY BUFFER,)
- Rendering
 - Call gl.drawElements()
 - WebGL will look for the buffer which bind with element array buffer pointer



gl. ARRAY BUFFER

gl.drawElements(mode, count, type, offset)

- https://developer.mozilla.org/en-US/docs/Web/API/WebGLRenderingContext/drawElements
- mode
 - gl.POINTS, gl.LINE_STRIP, gl.LINE_LOOP, gl.LINES, gl.TRIANGLE_STRIP, gl.TRIANGLE_FAN, gl.TRIANGLES
- count:
 - the number of elements to be rendered
- type:
 - type of values in the element array buffer (usually, gl.UNSIGNED_BYTE or gl.UNSIGNED_SHORT)
- offset:
 - a byte offset in the element array buffer (the first index in the element array to draw)

- initVertexBuffer() in WebGL.js
- Array Buffer and Element Array Buffer Creation

An array buffer to store vertices information and assign to "a_Position" variable in shader

An array buffer to store color information and assign to "a_Color" variable in shader

An **element** array buffer to store index information

```
function initVertexBuffers(ql, program)(
   var vertices = new Float32Array(
           1:0, 1:0, 1:0, 1:0, 1:0, 1:0,
           -1.0, 1.0, 1.0, 1.0, 8.0, 1.0,
           -1.0, -1.0, 1.0, 1.0, 0.0, 0.0,
           1.0, -1.0, 1.0, 1.0, 1.0, 0.0,
           1.0, -1.0, -1.0, 0.0, 1.0, 0.0,
           1.0, 1.0, -1.0, 0.0, 1.0, 1.0,
           -1.0, 1.0, -1.0, 0.0, 0.0, 1.0,
           -1.0, -1.0, -1.0, 0.0, 0.0, 0.0
              Note: type we use is unsigned byte
           0, 1, 2, 0, 2, 3, //front
           0, 3, 4, 0, 4, 5, //right
           0, 5, 6, 0, 6, 1, //up
           1, 6, 7, 1, 7, 2, //lest
           7, 4, 3, 7, 3, 2, //hottnm
           4, 7, 6, 4, 6, 5 //hank
   var FSIZE = vertices.BYTES_PER_ELEMENT;
   var vertexBuffer = gl.createBuffer();
   gl.bindBuffer(gl.ARRAY_BUFFER, vertexBuffer);
  gl.bufferData(gl.ARRAY_BUFFER, vertices, gl.STATIC_DRAW);
   var a_Position = gl.getAttribLocation(program, 'a_Position');
   gl.vertexAttribPointer(a Position, 3, gl.FLDAT, false, FSIZE*6, 0);
   gl.enableVertexAttribArray(a Position);
  var colorBuffer = gl;createBuffer();
  gl.bindBuffer(gl.ARRAY_BUFFER, colorBuffer);
   gl.bufferData(gl.ARRAY BUFFER, vertices, gl.STATIC DRAW);
   var a Color = gl.getAttribLocation(program, 'a Color');
   gl.vertexAttribPointer(a_Color, 3, gl.FLOAT, false, FSIZE+6, FSIZE+3);
  gl.enableVertexAttribArray(a_Color);
  var indexBuffer = ql.createBuffer();
   gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, indexBuffer);
   ql.bufferData(ql.ELEMENT_ARRAY_BUFFER, indices, ql.STATIC_DRAW);
   return indices. length;
```

- main() in WebGL.js
- Ask shader to render

Set up and pass mvp matrix to shader

Set up and pass mvp matrix to shader

```
function main(){
   /////Get the canvas context
   var canvas = document.getElementById('webgl');
   vor gl = canvas.getContext('webgl2');
   1f(!al){
       console.log('Failed to get the rendering context for WebGL');
   program = compileShader(gl, VSHADER_SOURCE, FSHADER_SOURCE);
   ql.useProgram(program);
   var n = initVertexBuffers(gl, program);
   gl.clearColor(0,0,0,1);
   gl.enable(gl.DEPTH_TEST);
   var u_MvpMatrix = gl.getUniformLocation(program, 'u_MvpMatrix');
   var mvpMatrix = new Matrix4();//identity matrix
   mvpMatrix.setPerspective(30, 1, 1, 100); //Projection matrix
   mvpMatrix.lookAt(3, 3, 7, 0, 0, 0, 0, 1, 0);//Projection matrix * View matrix
   gl.uniformMatrix4fv(u MvpMatrix, false, mvpMatrix.elements);
   gl.clear(gl.COLOR_BUFFER_BIT | gl.DEPTH_BUFFER_BIT);
   gl.drawElements(gl.TRIANGLES, n, gl.UNSIGNED_BYTE, 0);
```

The type we use for the element array is unsigned type

Let' Try (5mins)

 Check the two variables, "vertices" and "indices", to make sure you know element array well



External Model (Mesh)

- Someone already defines an object for you
 - A mesh is usually approximated by many triangles
 - The model may include
 - Vertices of triangle
 - Normal vector of vertices
 - Texture coordinate of vertices
 - Index array
 - They usually use the way similar to "element array" to store the model
- Many formats
 - 3ds, **obj**, json......

Vertex (v)

- Introduction of Obj file format: http://paulbourke.net/dataformats/obj/
- This cube obj file define
 - Vertices
 - Texture coordinates
 - Normal vector
 - Face indices

Texture coordinate (vt)

> Normal vector (vn)

> > Face (f)

www.blender.org mtllib cube.mtl 1/1/1 5/2/1 1/3/1 3/4/1

Blender v2.80 (sub 75) 083 File: "

Vertex (v)

- "#": comment
- "v" is vertex poisition
- "vt" is texture coordinate but we do not use it this week
- "vn" is normal vector
- "f": faces
 - A cube has 6 face
 - Each face has multiple 4 vertices
- WebGL needs a face defined by a triangle (3 vertices)
 - We can subdivide 1 quad into 2 triangles by ourself

Normal vector (vn)

Texture

coordinate (vt)

Blender v2.88 (sub 75) 083 File: **

www.blender.org mtllib cube.mtl

Face (f)

Vertex (v)

 A vertex of a face is defined by indices which points to "v", "vt", "vn" ...

A vertex could have multiple properties

Texture coordinate (vt)

- f 1 5 7 3 (vertex)
- f 1/1 5/2 7/3 3/4 (vertex/texCoordi)
- f 1/1/1 5/2/1 7/3/1 3/4/1(vertex/texCoordi/normal)
- f 1//1 5//1 7//1 3//1 (vertex/normal)

Normal vector (vn)

vt 8.875000 8.500000
vt 8.875000 8.750000
vn 8.0000 1.0000 8.0000
vn 8.0000 8.0000 1.0000
vn 9.0000 8.0000 8.0000
vn 9.0000 9.0000 8.0000
vn 1.0000 8.0000 8.0000
vn 1.0000 8.0000 8.0000
vn 8.0000 9.0000 -1.0000
usemtl Material
s off
f 1/1/1 5/2/1 7/3/1 3/4/1
f 4/5/2 3/6/2 7/7/2 8/8/2
f 8/8/3 7/7/3 5/9/3 6/10/3
f 6/10/4 2/11/4 4/12/4 8/13/4
f 2/14/5 1/15/5 3/16/5 4/17/5
f 6/18/6 5/19/6 1/20/6 2/11/6

Blender v2.80 (sub 75) 08J File:

www.blender.org mtllib cube.mtl

Face (f)

- The vertex 5/2/1 consists of
 - vertex with index 5
 - texture coordinate with index 2
 - normal vector with index 1
- No color?
 - Yes, no color
 - In most of 3D models, we use an alternative way (texture coordinate and texture image) to define color.
 That is the topic for next week.

Vertex (v)

Texture coordinate (vt)

Normal vector (vn)

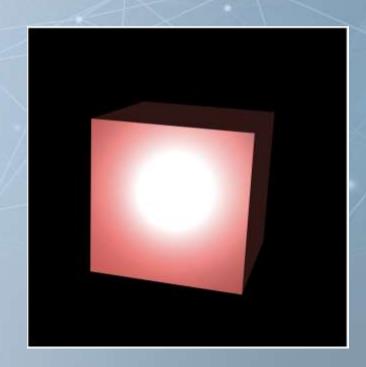
Face (f)

www.blender.org mtllib cube.mt

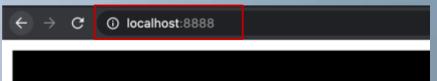
Blender v2.80 (sub 75) 08J File:

Load the cube obj file and render it

- Files
 - index.html
 - WebGL.js
 - cuon-matrix.js
 - cube.obj



- In this example, the browser will load the file, "cube.obj"
- Because of security issue, your browser will block it (file loading) if you directly drag index.html into your browser
- There are multiple ways to solve this issue
 - One of them is using Python to create a local http server and let browser connect to localhost
 - Open terminal (depend on your OS, you may have different way to open terminal and run python)
 - Run "python –m http.server 8888". This command creates a simple http server at port 8888
 - Open browser, link to "localhost:8888"



- parseOBJ() in WebGL.js
 - This function can parse obj files for you
- You pass text of an obj file into this function.
- This function will parse it for you and return the result.
 - Convert quads into triangles
 - Store data by the basic **vertex array** instead of the element array
 - Separate vertex positions, texture coordinates and normal vectors in different javascript arrays
- This function comes from https://webglfundamentals.org/webgl/lessons/webglload-obj.html
 - You can find more explanations there

```
if (le) {
   continue;
}
const [, keyword, unpackedArgs] = n;
const parts = lin.split(/le/).slice(1);
const handler = keywords[keywords];
if (linester) {
   conste.warn('unhandled keywords', keyword); // eslint
   continue;
}
handler(parts, unpackedArgs);
}

return {
   position: webglVertexData(8),
   texcoord: webglVertexData(2),
};
```

You have to put await execution in an async function

Example (Ex07-2)

- main() in WebGL.js
- Load obj file and get text

Load the file: you need await keyword to wait the loading finish and continue

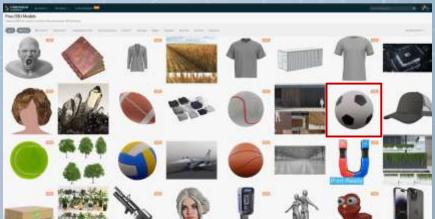
Pass the obj text to the parseOBJ()

Use data from Obj file to initialize vertex buffers

```
async function main()
    unvas = document.getElementById('webgl');
   gl = canvas.getContext('webgl2');
   Efficient) (
       console.log('Failed to get the rendering context for WebGL');
   program = compileShader(gl, VSHADER SOURCE, FSHADER SOURCE);
   gl.useProgram(program);
   program.u_MvpMatrix = gl.getUniformLocation(program, 'u_MvpMatrix');
   program.u_modelMatrix = gl.getUniformLocation(program, 'u_modelMatrix');
   program.u normalMatrix = gl.getUniformLocation(program, 'u normalMatrix');
   program.u LightPosition = gl.getUniforaLocation(program, 'u LightPosition');
   program.u ViewPosition = gl.getUniformLocation[program, 'u_ViewPosition');
   program.u Ka = ol.getUniformLocation(program, 'u Ka');
   program.u Kd = gl.getUniformLocation(program, 'u Kd');
   program, u Ks = gl.getUniformLocation(program, 'u Ks');
   program.u shininess = ql.getUniformLocation(program. 'u shininess');
   program.u_Color = gl.getUniformLocation(program, 'u_Color');
    response = await fetch['cube.ob]')
   text = munit response.text();
   obj = parse08J(text);
   nVertex = initVertexBuffers(gl, program,
                                new Float32Array( obj.position ),
                                new Float32Array( obj.normal )):
   mypMatrix = new Matrix4();
   modelMatrix = new Matrix4();
   normalMatrix = new Matrix4():
   gl.enable(gl.DEPTH_TEST);
   draw()://graw it once before mouse move
   canvas.onmousedown = function(ev)(nouseDown(ev));
   canvas.onmousemove = function(ev)(mouseMove(ev));
   canvas.onnouseup = function(ev){nouseUp(ev)};
```

Let's Try (10mins)

- Make sure you can run this example and see the result
- Load and render another 3D Model: mario.obj
- More 3D models in https://www.turbosquid.com/
 - You may have to register a https://www.turbosquid.com/ account
 - Click "OBJ MODEL" icon. Click "Price", select "free". Find "Football Ball" (soccer)
 - Click "download" -> click "show all" -> Click "Football ball.obj" and download
- Ex07-2 may not work for every models



More for Obj Format

- If you download .obj from clara.io, you usually have one .obj,
 one .mtl and some images in the folder
 - obj: vertex information
 - mtl: material information (for illumination)
 - images: texture images (color information)

```
# Blender v2.74 (sub 0) OBJ File:
                                                                                         # Blender MTL File: 'None'
                                                mario-sculpture.mtl
 www.blender.org
                                                                                        # Material Count: 1
mtllib mario-sculpture.mtl
                                            mario-sculpture.obj
                                                                                        newmtl mario_1
                                             marioD.jpg
                                                                                        Ns 96.078431
                                                                                        Ka 0.000000 0.000000 0.000000
                                                                                        Kd 1.000000 1.000000 1.000000
                                                                                        Ks 0.040000 0.040000 0.040000
                                                                                        Ni 1.000000
                                                                                        d 1.000000
                                                                                        illum 2
                                                                                        map_Kd marioD.jpg
v 2.650452 39.314827 15.560564
v 2.919006 39.315331 15.516424
```

Object with Multiple Pieces (Obj)

- The cube and the mario are special cases
- Many objects consist of multiple pieces
 - The chair: handles, wheels....
- How the obj file describe this type of objects



usually one obj file one mtllib to indicate what the material file is

Object with Multiple Pieces (Obj)

Name of this piece

All information of one piece

Cube.obj contains only one piece

Mtllib ****.mtl o nameOfPiece1 Usemtl Material o nameOfPiece2 vn ...

Usemtl Material

o nameOfPiece3

How the multiple pieces obj file looks like

Information of the 1st piece

Information of the 2nd piece

How the normal is calculated and whether use the material file (we can ignore them this course)

Information of the 3rd 4th 5thpieces

usemtl Material 1/1/1 5/2/1 7/3/1 3/4/1

6/18/6 5/19/6 1/20/6 2/11/6

Blender v2.88 (sub 75) 08J File:

www.blender.org

- Load "sonic.obj" and render
 - sonic consists of 13 pieces

- Files
 - index.html
 - WebGL.js
 - cuon-matrix.js
 - sonic.obj



parseOBJ() in WebGL.js

response = await fetch('sonic.ob!');

text = await response.text();

obj = parseOBJ(text);

console.log(obi);

- Pass whole text of the obj file to parseObj(),
 parseObj() will parse multiple pieces object for you
 - More details:
 https://webglfundamentals.org/webgl/lessons/webgl-load-obj.html

```
WEDGL 1511
*{geometries: Array(13), materialLibs: Array(1)} 💷
 * geometries: Array(13)
    data: {position: Array(2331), texcoord: Array(1554), normal: Array(2331)}
    p groups: ["default"]
      material: "d1419efe dds"
     object: "DrawCall 0278"
    * proto : Object
   1: {object: "DrawCall_0270", groups: Array(1), material: "64124be4_dds", data: {...}}
  >2: {object: "DrowCall_0266", groups: Array(1), material: "64124be4_dds", data: {...}}
  >3: {object: "DrawCall 0276", groups: Array(1), material: "fif6d3cb dds", data: {_}}}
  4: (object: "DrawCall 0275", groups: Array(1), material: "bab97353 dds", data: {...}}
  >5: {object: "DrawCall_0267", groups: Array(1), material: "64124be4_dds", data: (...}}
  >6: (object: "brawCall 0271", groups: Array(1), material: "64124be4_dds", data: {_}}
  >7: {object: "DrmwCall_0269", groups: Array(1), material: "64124be4_dds", data: {...}}
  >8: {object: "DrawCall_0272", graver Array(1), material: "f1f6d3cb_dds", data: {...}}
  9: {object: "DrawCall_0268", g Object Array(1), material: "64124bed_dds", data: {...}}
  → 10: {object: "DrawCall_0274", groups: Array(1), material: "bab97353 dds", data: {...}}
  *11: {object: "DrawCall_0273", groups: Array(1), material: "f1f6d3cb_dds", data: {_}}
  *12: (object: "DrawCall 0277", groups: Array(1), material: "d1419efe dds", data: (...))
    length: 13
  * proto : Array(0)
 * materialLibs: ["sonic-the-hedgehog.mtl"]
 proto_: Object
```

```
// because indices are base 1 let's just fill in the With data
const objPositions = [[0, 0, 0]];
const objTexcoords = [[0, 0]];
const objNormals = [[0, 0, 0]];
// same order as 'T' indices
const objVertexData = [
 obiPositions.
 obiTexcoords.
 obiNormals,
// same order as f indices
let webglVertexData = [
 []. // positions
 11.
const materialLibs = []:
const geometries = [];
let geometry;
let groups = ['detault']:
let material = 'default';
let object = 'default':
const noop = () => {};
function newGeometry() {
 // If there is an existing geometry and it's
 // not empty then start a new one.
 if (geometry && geometry.data.position.length) {
   geometry = underined;
function setGeometry() {
 if (!geometry) {
    const position = []:
    court towespeed - III-
```

function parseOB3(text) {

- main() in WebGL.js
- Idea of creating VBOs and render image
 - We create a vertex buffer for each piece of the sonic
 - When drawing, we use a for loop to send pieces (bind VBO) to draw one by one

Create vertex buffers for each piece and store them in "objComponents"

```
var cameraX = 3, cameraY = 3, cameraZ = 7;
var objScale = 0.05;
var objComponents | [];
async function main()(
    canvas = document.getElementById('webgl');
    gl = canvas.getContext('webgl2');
    11(101){
        console.log('Failed to get the rendering context for WebGL');
    program = compileShader(gl, VSHADER_SOURCE, FSHADER_SOURCE);
    gl.useProgram(program);
    program.a_Position = gl.getAttribLocation(program, 'a_Position');
    program.a_Normal = gl.getAttribLocation(program, 'a_Normal');
    program.u MypMatrix = gl.getUniformLocation(program, 'u NypMatrix');
    program.u_modelMatrix = gl.getUniformLocation(program, 'u_modelMatrix');
    program.u_normalMatrix = gl.getUniformLocation(program, 'u_normalMatrix');
    program.u_LightPosition = gl.getUniformLocation(program, 'u_LightPosition');
    program.u_ViewPosition = gl.getUniformLocation(program, 'u_ViewPosition');
    program.u_Ka = gl.getUniformLocation(program, 'u_Ka');
    program.u_Kd = gl.getUniformLocation(program, 'u_Kd');
    program.u Ks = gl.getUniformLocation(program, 'u Ks');
    program.u_shininess = gl.getUniformLocation(program, 'u_shininess');
    program.u_Color = gl.getUniformLocation(program, 'u_Color');
    response = await fetch('sonic.obj');
    text = swait response.text();
    ob) = parseOBJ(text);
    for( let i=0; i < ob).geometries.length; i ++ ){
      lot o = initVertexBufferForLaterUse(gl,
                                          obj.geometries[i].data.position,
                                          obj.geometries[i].data.normal;
                                          obj.geometries[i].data.texcoord);
      objComponents.push(o);
    mypMatrix = New Matrix4();
    nodelMatrix = new Matrix4();
    normalMatrix = new Matrix4();
    gl.enable(gl.DEPTH_TEST);
```

- draw() in WebGL.js
- Idea of creating VBOs and render image
 - We create a vertex buffer for each piece of the sonic
 - When drawing, we use a for loop to send pieces (bind VBO) to draw one by one

```
notion draw(){
 gl.clearColor(0,0,0,0,1):
 //model Matrix (part of the myp matrix)
 modelMatrix.setRotate(angleY, 1, 0, 0);//for mouse rotation
 modelMatrix.rotate(angleX, 0, 1, 0)://for mouse rotation
 modelMatrix.scale(objScale, objScale, objScale);
 // modelMatrix.translate(0.0, 0.0, -1.0);
 // modelMatrix.scale(1.0, 0.5, 2.0);
 //mvp: projection = view = model natrix
 mypMatrix.setPerspective(30, 1, 1, 100);
 mvpMatrix.lookAt(cameraX, cameraY, cameraZ, 0, 0, 0, 0, 1, 0);
 mvpMatrix.multiply(modelMatrix);
 //normal matrix
 normalMatrix.setInverseOf(modelMatrix);
 normalMatrix.transpose();
 gl.uniform3f(program.u LightPosition, 0, 0, 3);
 gl.uniform3f(program.u ViewPosition, cameraX, cameraY, cameraZ);
 gl.uniform1f(program.u_Ka, 0.2);
 gl.uniform1f(program.u Kd, 0.7);
 gl.uniform1f(program.u_Ks, 1.0);
 gl.uniformif(program.u_shininess, 10.0);
 gl.uniform3f(program.u_Color, 1.0, 0.4, 0.4);
 gl.uniformMatrix4fv(program.u_MvpMatrix, felse, mvpMatrix.elements);
 gl.uniformMatrix4fv(program.u_modelMatrix, false, modelMatrix.elements);
 gl.uniformMatrix4fv(program.u_normalMatrix, false, normalMatrix.elements);
 gl.clear(gl.COCOR_BUFFER_BIT | gl.DEPTH_BUFFER_BIT);
 for( let i=0; i < objComponents.length; i ++ ){
   initAttributeVariable(ql, program,a Position, objComponents[i].vertexBuffer)
   initAttributeVariable(gl, program.a_Normal, objComponents(i).normalBuffer);
   gl.drawArrays(gl.TRIANGLES, 0, objComponents[i].numVertices);
```

- Note
 - The obj parser, parseObj(), we provide is not a complete obj parser. It may not be able to parse some obj files correctly.
 - After you successfully load an obj file and render it, the object may be too small or large to see it on canvas. If you cannot see the object, try to the scale issue.
 - The origin of the object space may not be at center of the object (ex: at the left bottom corner of the object).

Let's try (5 mins)

 Browse the code and sonic.obj file to make sure you know what's going on there.

 Go to clara.io and download another multiple pieces obj file to replace sonic.obj



Basic

Very similar to C language

- Case sensitive
- Strong type language
- One shader has one and only one main()
 - main() has not input arguments and no return value
- Comment: // or /* ... */

Data Type and Basic Variables

- Variable names
 - Same as C
 - Cannot start with "gl_", "webgl_" or "_webgl_"
 - Other keywords

varying	vec2	vec3	vec4	void	while
return	sampler2D	samplerCube	struct	true	uniform
mat2	mat3	mat4	medium	out	precision
Int	invariant	ivec2	ivec3	ivec4	lowp
float	for	highp	Lf	in	inout
const	continue	discard	do	else	false
attribute	bool	break	bvec2	bvec3	bvec4

asm	cast	class	default
double	dvec2	dvec3	dvec4
enum	extern	external	fixed
flat	fvec2	fvec3	fvec4
goto	half	hvec2	hvec3
hvec4	inline	input	interface
long	namespace	noinline	output
packed	public	samplerID	sampler1DShadow
sampler2DRect	sampler2DRectShadow	sampler2DShadow	sampler3D
sampler3DRect	short	sizeof	static
superp	switch	template	this
typedef	union	unsigned	using
volatile			

Data Type and Basic Variables

- Basic types
 - bool: "true" or "false"
 - int
 - float
 - no "double", use "precision" to define the precision of a floating point
 - highp, medium, lowp (we learn this at very beginning of this course)
- Some examples
 - int i = 8;
 - float f1 = 8.0:
 - float f2 = 8;
 - float f3 = 8.0f;
 - float f4 = float(i);
 - float f5 = float(8);
- Type casting
 - int(float): discard decimal part
 - int(bool): true -> 1, false -> 0
 - float(int)
 - float(bool): true -> 1.0, false -> 0.0
 - bool(int): 0 -> false, other values -> true
 - bool(float): 0.0 -> false, other values -> true

Basic operators

```
-- 1-
condition?
expression1:expression2
```

Matrix and Vector

- Vector type:
 - vec2, vec3, vec4 : floating point vector
 - ivec2, ivec3, ivec4 : integer vector
 - bfvec2, bvec3, bvec4 : boolean vector
- Matrix type (floating points only)
 - mat2: 2x2 matrix
 - mat3 : 3x3 matrix
 - mat4 : 4x4 matrix

Vector

- Examples of constructors of vector type
 - vec4 position = vec4(1.0, 2.0, 3.0, 4.0);
 - vec3 v3 = vec3(1.0, 0.0, 0.5);
 - vec2 v2 = vec2(v3); //v2=(1.0, 0.0)
 - -vec4 v4 = vec4(1.0); //v4=(1.0,1.0,1.0,1.0)
 - vec4 vv = 1.0;
 - Vec4 v4b = vec4(v2, v4); //v4b=(1.0, 0.0, 1.0, 1.0)

Vector

- Access elements in vector
- Three syntax sets: just increase the readability of your code
 - x, y, z, w
 - r, g, b, a
 - s, t, p, q
- Examples (basic)
 - vec3 v3 = vec3(1.0, 2.0, 3.0);
 - float f;
 - f = v3.x; (f is 1.0)
 - f = v3.y; (f is 2.0)
 - f = v3.z; (f is 3.0)
 - f = v3.r; (f is 1.0)
 - f = v3.s; (f is 1.0)
 - f = v3.w; (f is 1.0), v3 has no the 4th element

- Examples (swizzling)
 - vec2 v2;
 - v2 = v3.xy; (v2 is [1.0, 2.0])
 - v2 = v3.yz; (v2 is [2.0, 3.0])
 - v2 = v3.xz; (v2 is [1.0, 3.0])
 - v2 = v3.yx; (v2 is [2.0, 1.0])
 - v2 = v3.xx; (v2 is [1.0, 1.0])
 - vec3 v3a = v3.zyx; (v3a is [3.0, 2.0, 1.0])
- Assign (swizzling)
 - vec4 position = vec4(1.0, 2.0, 3.0, 4.0);
 - position.xw = vec2(5.0, 6.0); (position is [5.0, 2.0, 3.0, 6.0])
 - vec3 a = v3.was; , cannot mix alphabets from different sets
- You can also use [] to access any single element in a vector you want (same as accessing 1D array in C)
 - f = v3[1]; (f is 2.0)

Matrix

- Column-major
 - mat4 m4 = mat4(1.0, 2.0, 3.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.0, 11.0, 12.0, 13.0, 14.0, 15.0, 16.0);

```
      1.0
      5.0
      9.0
      13.0

      2.0
      6.0
      10.0
      14.0

      3.0
      7.0
      11.0
      15.0

      4.0
      8.0
      12.0
      16.0
```

Matrix

- Examples of constructors of matrix type
 - vec2 v21 = vec2(1.0, 3.0);
 - vec2 v22 = vec2(2.0, 4.0);
 - mat2 m21 = mat2(v21, v22); $\begin{bmatrix} 1.0 & 2.0 \\ 3.0 & 4.0 \end{bmatrix}$
 - vec4 v4 = vec4(1.0, 3.0, 2.0, 4.0);
 - mat2 m22 = mat2(v4); $\begin{bmatrix} 1.0 & 2.0 \\ 3.0 & 4.0 \end{bmatrix}$
 - mat2 m2 = mat2(1.0, 3.0, v22);
 - mat4 m4 = mat4(1.0);
 - mat4 m44 = mat4(1.0, 2.0, 3.0);

Matrix

- Access elements in matrix
- mat4 m4 = mat4(1.0, 2.0, 3.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.0, 11.0, 12.0, 13.0, 14.0, 15.0, 16.0);
- Use bracket, [], to access elements in matrix
- vec4 v4 = m4[0]; (m4 is [1.0, 2.0, 3.0, 4.0])
- float m23 = m4[1][2]; (m23 is 7.0)
- Float m32 = m4[2].y; (m32 is 10.0)
- The index in [] has to be constant index
 - vec4 v4 = m4[1];
 - const int indexC = 0;
 - vec4 v4a = m4[indexC];
 - vec4 v4b = m4[indexC+1];
 - int index = 0;
 - vec4 v4c = m4[index]; (incorrect: index is not const)

$$m4 = \begin{bmatrix} 1.0 & 5.0 & 9.0 & 13.0 \\ 2.0 & 6.0 & 10.0 & 14.0 \\ 3.0 & 7.0 & 11.0 & 15.0 \\ 4.0 & 8.0 & 12.0 & 16.0 \end{bmatrix}$$

Matrix and Vector Operators

- Example of operators
 - vec3 v3a, v3b, v3c;
 - mat3 m3a, m3b, m3c;
 - float f;
- v3b = v3a + f;
 - v3b.x = v3a.x + f
 - v3b.y = v3a.y + f
 - v3b.z = v3a.z + f
- v3c = v3a + v3b;
 - v3c.x = v3a.x + v3b.x
 - v3c.y = v3a.y + v3b.y
 - v3c.z = v3a.z + v3b.z
- m3b = m3a + f;
 - Add f to all elements of m3a and assign to m3b

Matrix and Vector Operators

- Example of operators
 - vec3 v3a, v3b, v3c;
 - mat3 m3a, m3b, m3c;
 - float f;
- Matrix-vector multiplication
 - m*v
 - v3b = m3a * v3a;
 - v*m
 - v3b = v3a * m3a;
- Matrix-matrix multiplication (m*m)
 - m3c = m3a * m3b;

Struct

Examples

```
struct Light{
vec4 color;
vec3 position;
}
Light | 11, | 12;

struct Light{
vec4 color;
vec3 position;
}
| 11;
```

Construction:

```
l1 = Light(vec4(1.0,0.0,0.0,1.0), vec3(2.0,6.0,1.2));
Access members:
    vec4 color = l1.color;
    vec3 pos = l1.position;
```

Array

- Determine the size of arrays at compile time only (cannot at run time)
- Examples
 - float floatArray[4];
 - vec4 vec4Array[2];
 - int size = 4;
 - vec4 vec4Array[size]; //this determine the size at run time
 - float f = floatArray[2];
 - vec4Array[0] = vec4(4.0,3.0,2.0,1.0); //also for initialization

Branch and Loop

- if, else if, else: same as C
- "switch-case": same as C (but old GLSL version does not support switch-case statement)
- Loop: for, while, do-while
 - break, continue
- "discard"
 - fragment shader only
 - It means that ignore current fragment

Self-defined Function

- Almost the same as C
- You have to declare the function if you use it before you define it.
- Example:

Self-defined Function

- Arguments: always pass by value? No
 - in: pass by value
 - out: pass by reference (no value pass in, but value pass out)
 - inout: pass by reference (value pass in and value pass out)
 - No in, out or inout? "in" is the default mode
- Example:

vec3 phi = example(3.5, true, delta, chi);

- The first two arguments are pass by value
- Value in delta will be passed into the function and any changes in the delta's value changes the delta from the calling statement.
- the chi's value is initialized by the calling statement and any changes made by the function change the chi from the calling statement.

List of Some Build-in Functions

- radiuans(), degrees()
- sin(), cos(), tan(), acos(), atan() ...
- pow(), exp(), log(), exp2(), log2(), sqrt(), inversesqrt()
- abs(), min(), max(), mod(), sign(), floor(), ceil(), clamp(), mix(), fract()
- length(), distance(), dot(), cross(), normalize(), reflect(), refract()
- More......

Scope and More about Variables

Similar to C, GLSL has the concept of variable scope

- const: const variable
- attribute
- uniform
- varying

Macro and Preprocessor

#ifdef

#if

#ifndef

#define

#undef

• • • • •

These slides are not complete GLSL syntax tutorial. So, you cannot learn GLSL language structurally here.

We just quickly provide some information and examples which may be useful for you.

My purpose is to give you the sense about some functions or syntax may exist and give you a chance to check the document.