

S6-ESE-AI

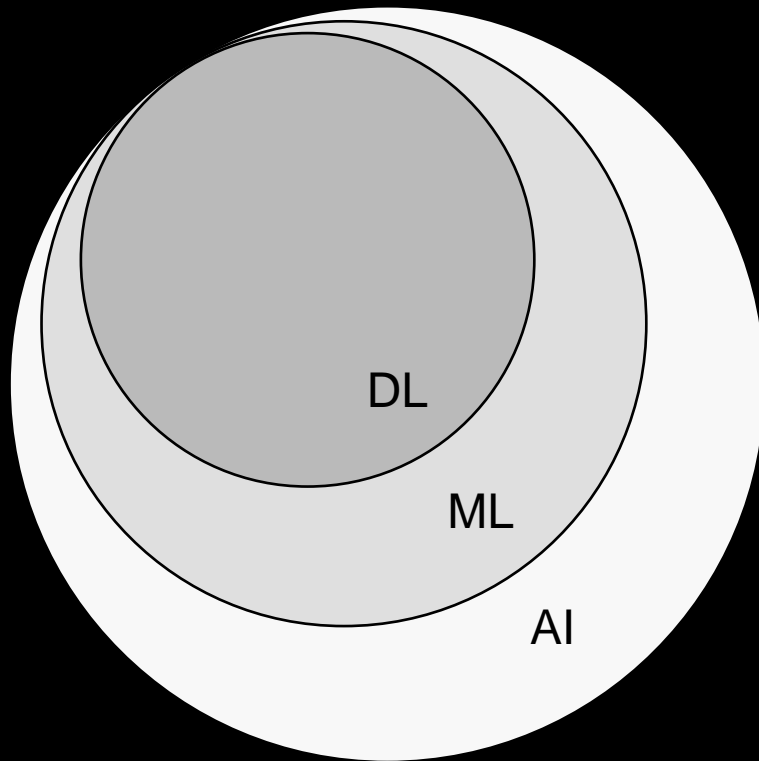
# MACHINE LEARNING BASICS

JEROEN VEEN  
HUGO ARENDS

# AGENDA

- Introduction
- Machine learning approaches
- Workflow
- Workshop organization
- Assignment
- Report template
- k Nearest Neighbor (kNN)
- Setting up your environment

# DEFINING AI, DL & ML



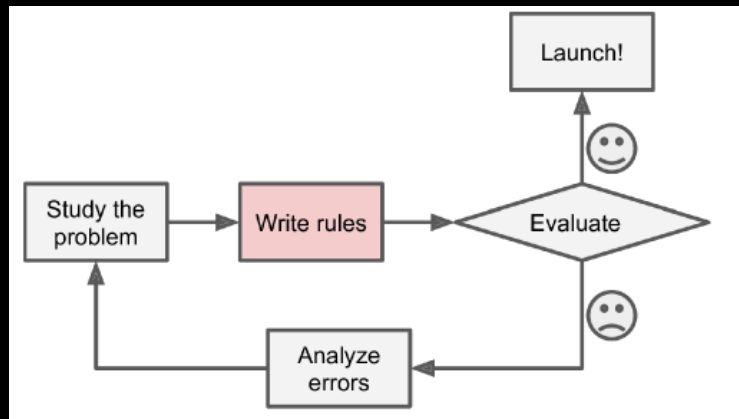
- Strong AI vs Applied AI
- Cognitive replication
- Rational process

## Machine learning

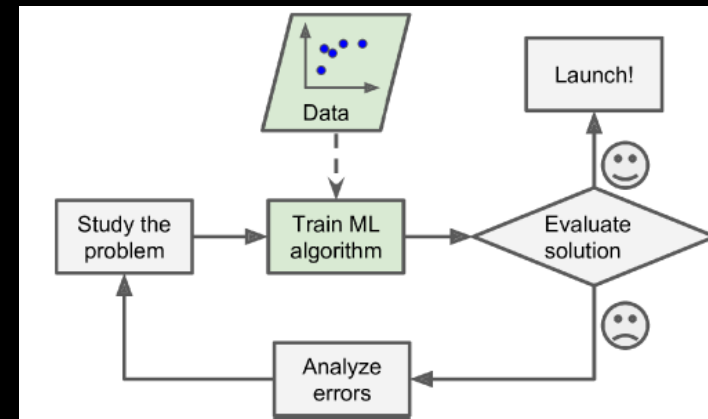
- Performs predictive analysis
- Just fancy math & pattern matching

# WHY MACHINE LEARNING?

- Automated analytical model building
- Deal with fluctuating environments by adapting to new data.
- Getting insights about complex problems and large amounts of data.

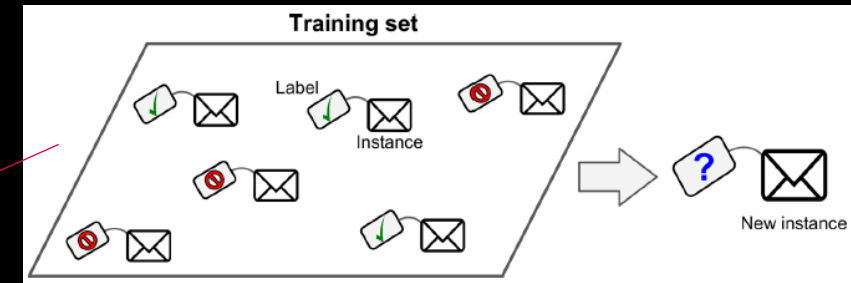
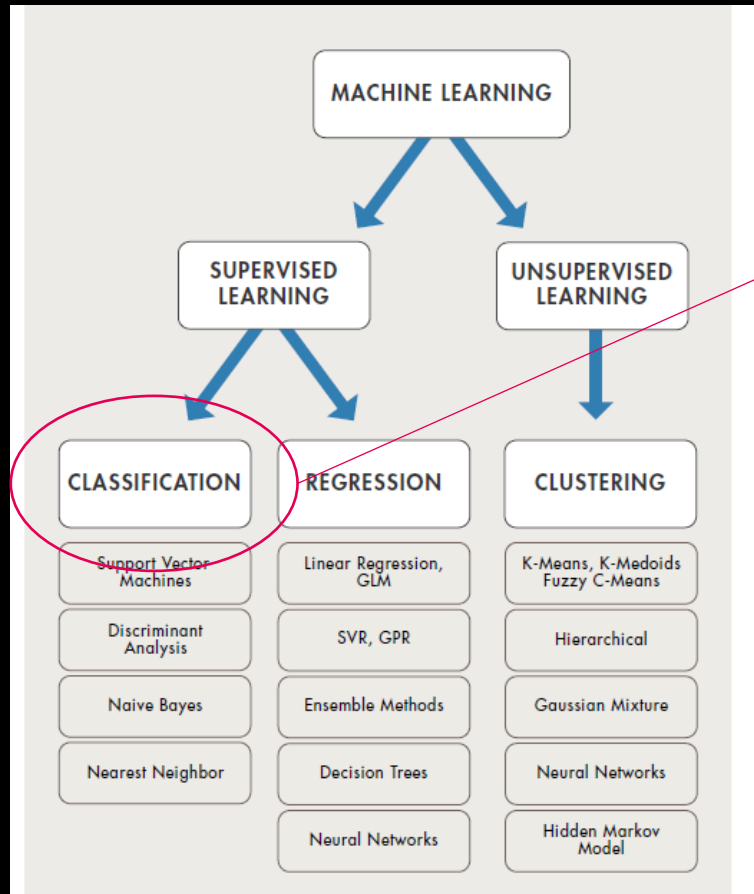


Traditional approach



ML approach

# MACHINE LEARNING APPROACHES



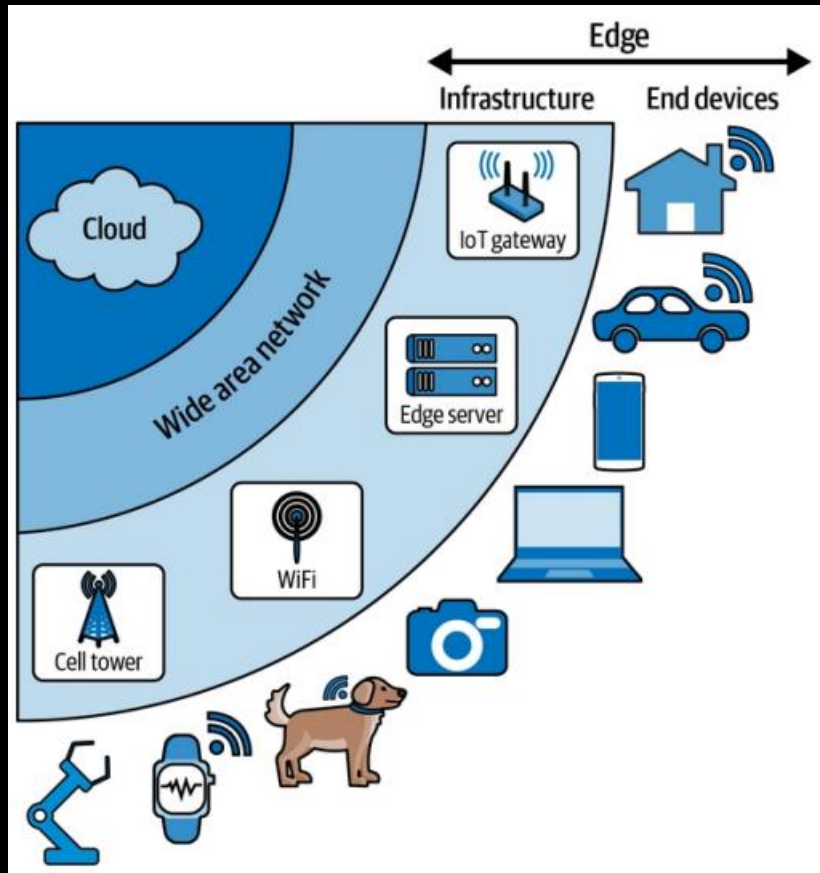
classification

# APPLES AND ORANGES

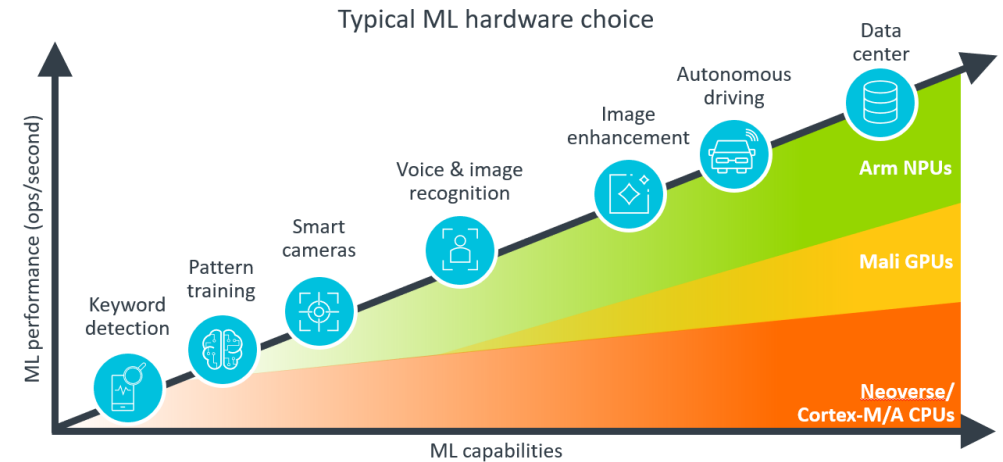
- <https://www.youtube.com/watch?v=cKxRvEZd3Mw&feature=youtu.be>

Weight	Texture	Label
150 g	Bumpy	Orange
170g	Bumpy	Orange
140g	Smooth	Apple
130g	Smooth	Apple
...	...	...

# ML AT THE EDGE



## Multiple ML Use Cases on Edge Devices



Source: Arm NN: the Easy Way to Deploy Edge ML, Steve Roddy, January 2019

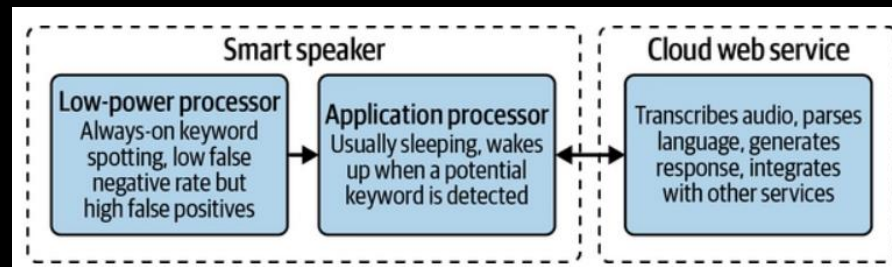
Bandwidth Latency Economics Reliability Privacy

# ML AT THE EDGE

- Focus on sensor data
- Small models
- Just inference, no training
- Evolving field



Source: IRNAS



Source: AI at the Edge, Daniel Situnayake, Jenny Plunkett, January 2023, O'Reilly Media, Inc. ISBN: 9781098120207



## APPLICATIONS

- Sensory and STM's VoiceActivated AI Technologies



## AI-POWERED ENDOSCOPY

- Medtronic's GIGenius, NVIDIA Holoscan



# ADVANCED PERFORMANCE FOR HEARING AIDS

- Starkey Livio Edge AI



# ORGANIZATION OF THE WORKSHOP

- ..\schedule\schedule.xls

# ASSIGNMENT

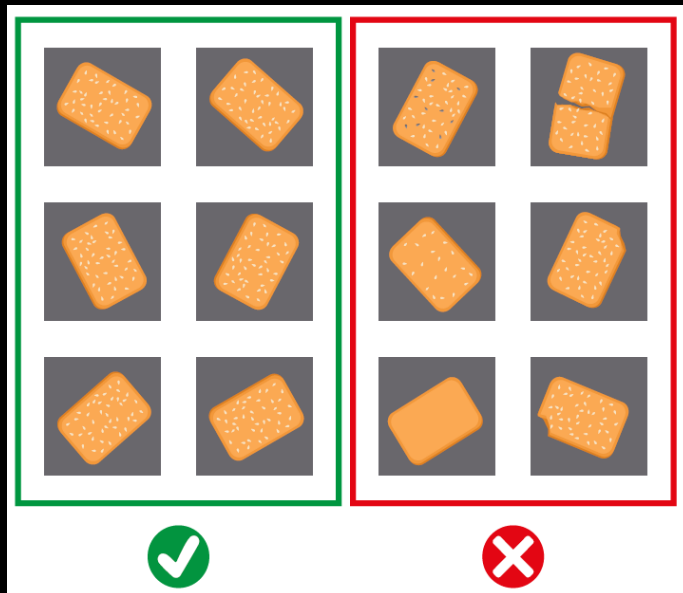
- A project team will consist of 3 students.
- Report building using template
- Individually deliver report via HandIn
- Templates and schedule on Gitlab

# REPORT TEMPLATE AND ASSESSMENT

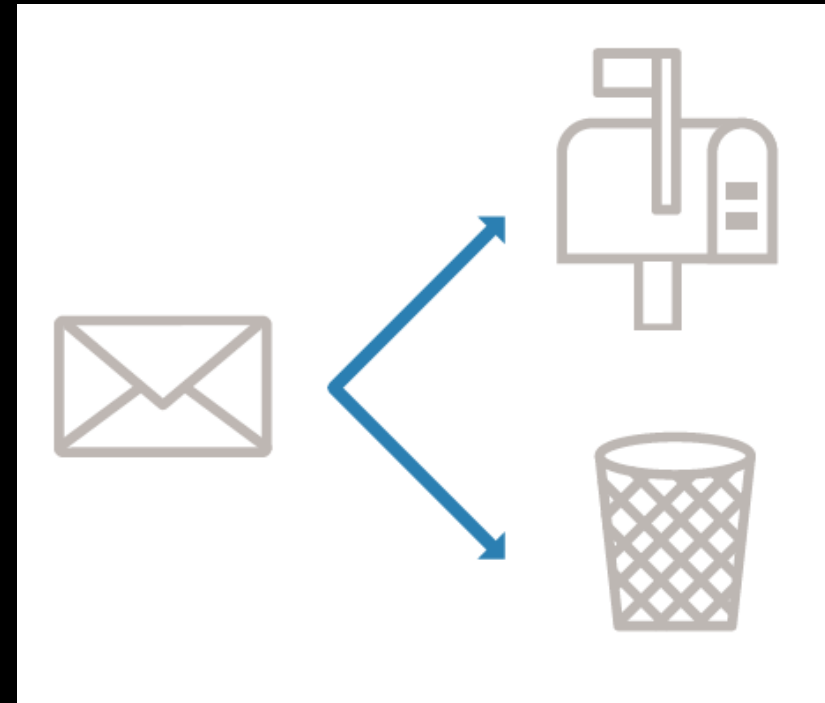
- `..\template\{YEAR}_{YOUR GROUP_NUMBER}_AI_report_{YOUR_NAME}_{YOUR_STUDENT_NUMBER}.docx`

# BINARY CLASSIFICATION

- Sample falls in either of 2 classes



Source: Basler, Artificial Intelligence in Image Processing



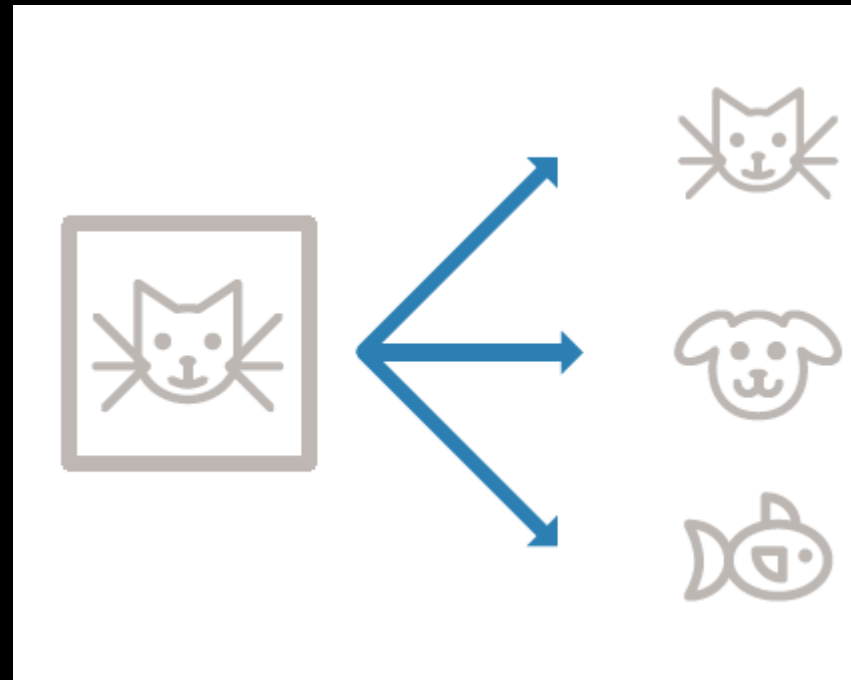
Source: Mathworks, Applying Supervised Learning

# MULTI-CLASS CLASSIFICATION

- Sample falls in either of 3 or more classes



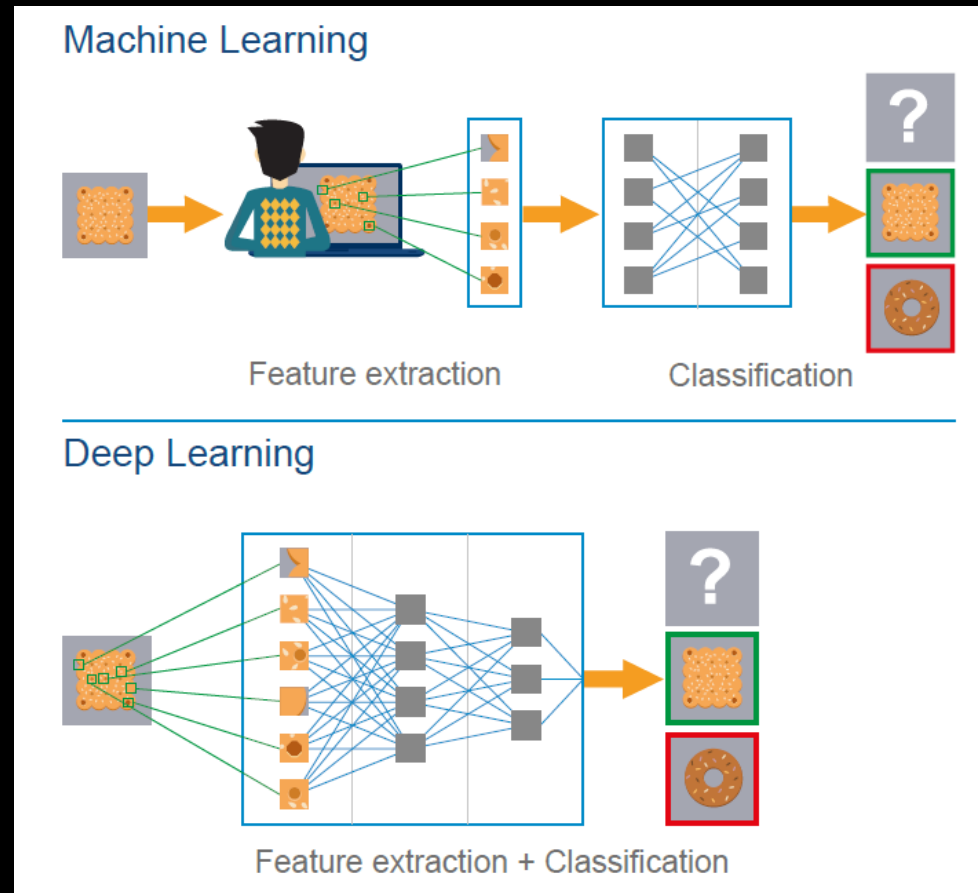
Source: MNIST dataset



Source: Mathworks, Applying Supervised Learning



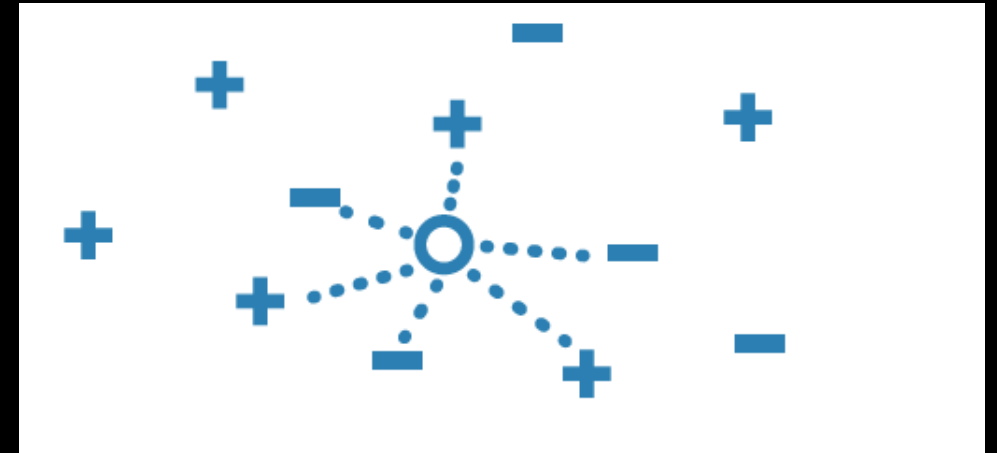
# MACHINE LEARNING VS DEEP LEARNING



## K NEAREST NEIGHBOR (KNN)

- The simplest classifier
- Assume feature vectors near each other are similar
- Categorizes objects based on the classes of their nearest neighbors
- No training required
- Intuitive
- Benchmark

- <https://www.youtube.com/watch?v=AoeEHqVSNOw&t=194s>

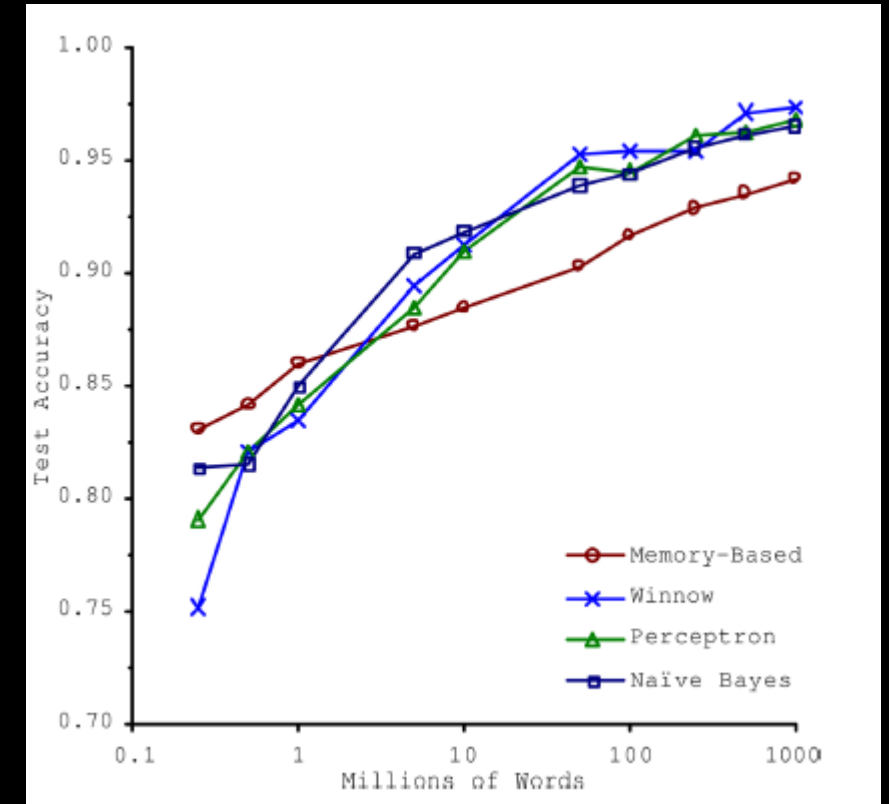


Source: Mathworks, Applying Supervised Learning

“Tell me who your neighbors are, and I’ll tell you who you are”

# DATA

- Data matters more than algorithms!
- Massive amounts of training data is needed
- Labelling is tedious and error prone

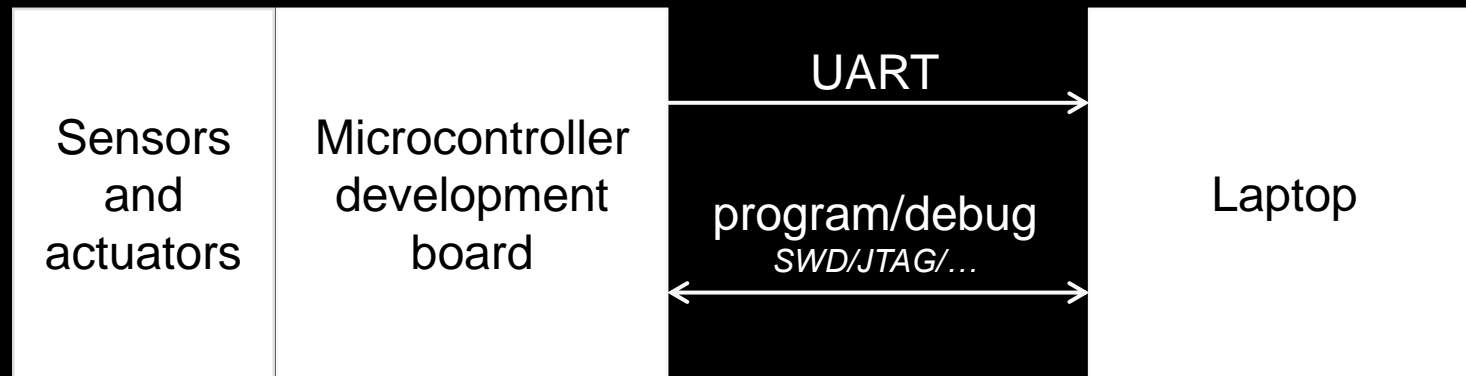


Source: Peter Norvig et al 2009

## WRAP-UP











- Why AI, ML at the edge, ML Workflow
  - Workshop organization, Assignment, Report template
  - Classification, k Nearest Neighbor (kNN)
- 
- Next week: data collection and analysis

# SETTING UP YOUR ENVIRONMENT

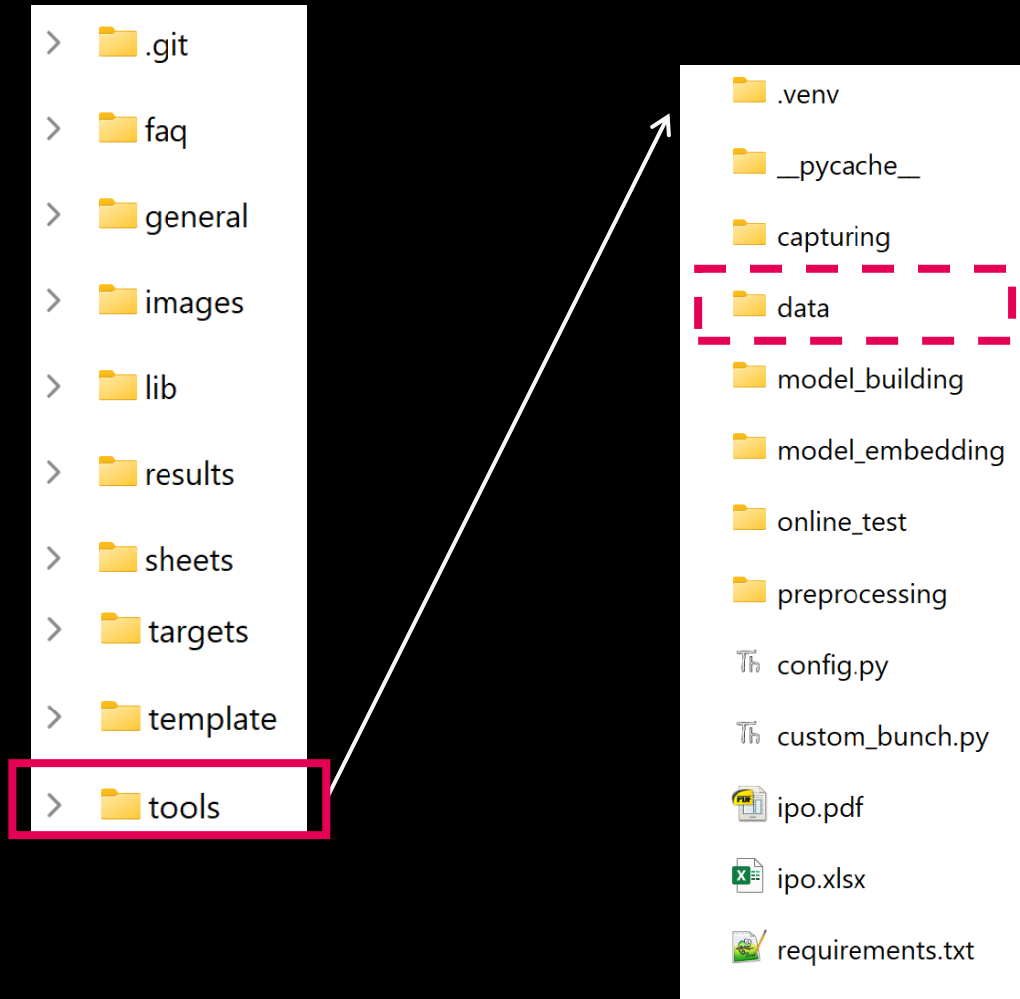


...

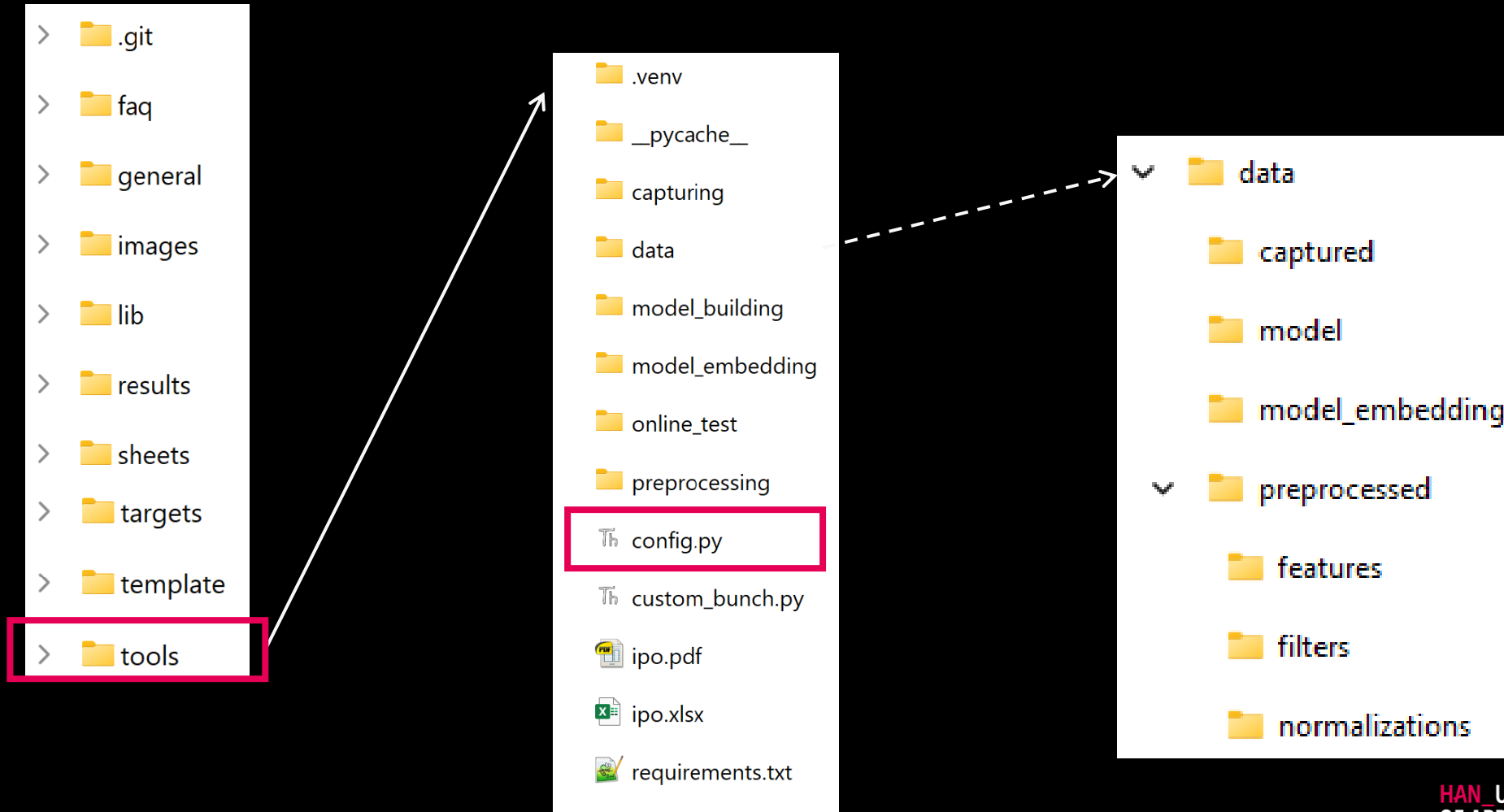
# SETTING UP YOUR ENVIRONMENT

- >  .git
- >  faq
- >  general
- >  images
- >  lib
- >  results
- >  sheets
- >  targets
- >  template
- >  tools

# SETTING UP YOUR ENVIRONMENT

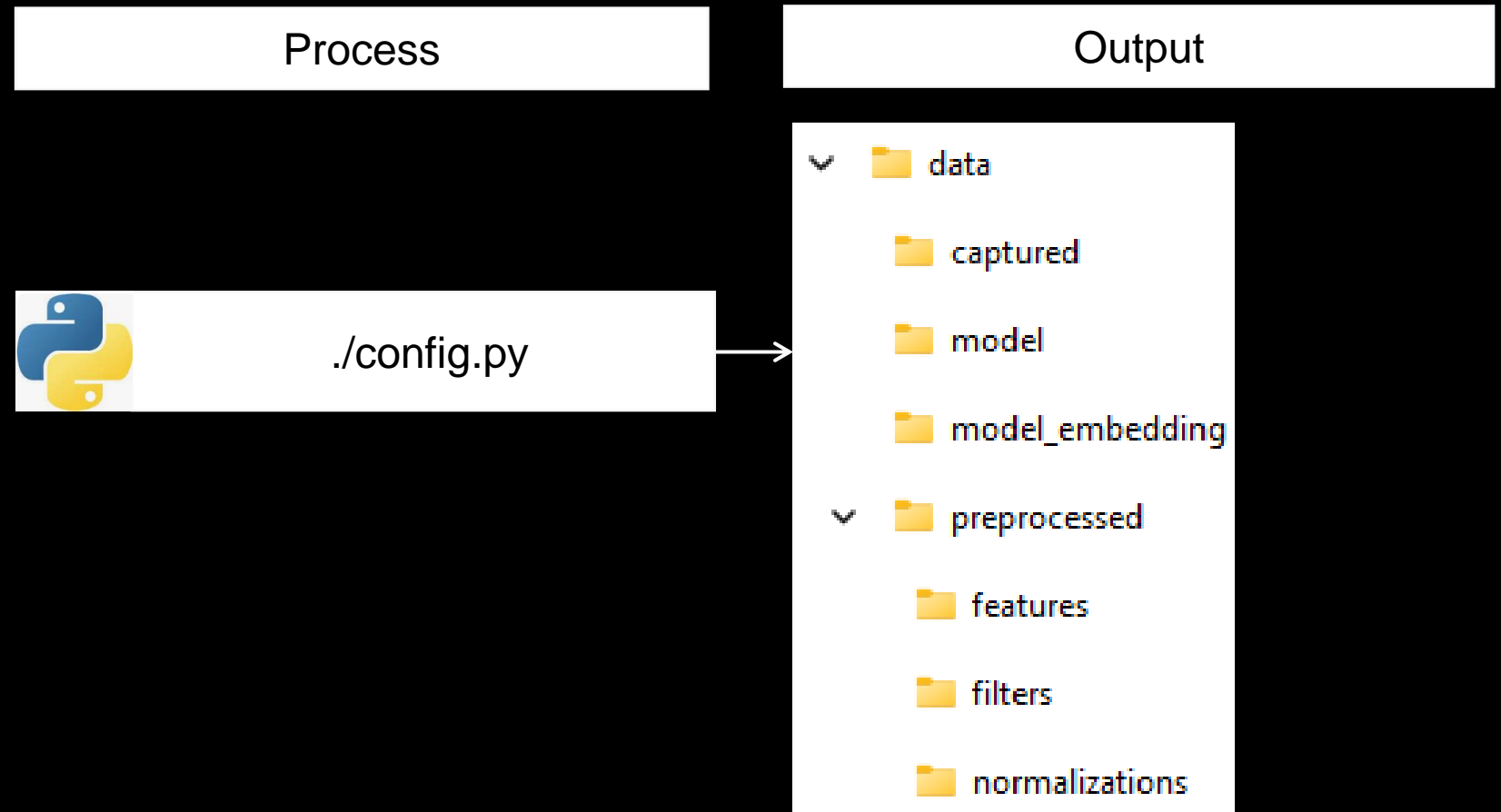


# SETTING UP YOUR ENVIRONMENT





# SETTING UP YOUR ENVIRONMENT



# SETTING UP YOUR ENVIRONMENT

`./tools/ipo.pdf`

*A comprehensive overview of all  
Python scripts*

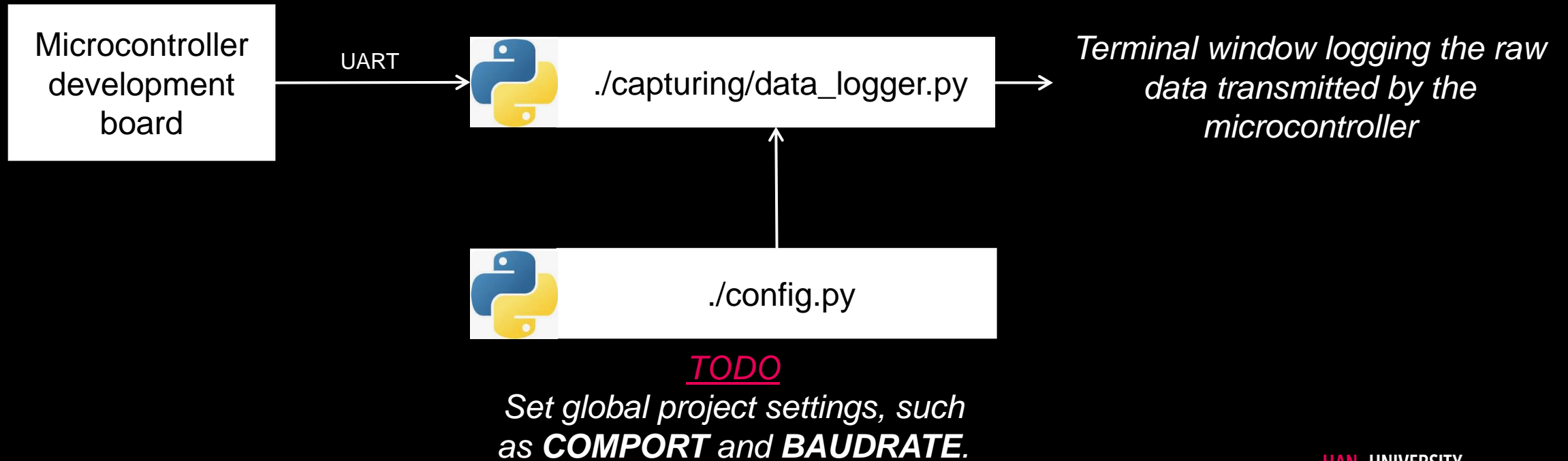


# CAPTURE APPLICATION DESIGN

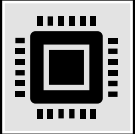
Input

Process

Output



# EMBED



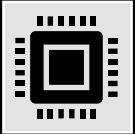
*main.c – RAW example*

```
// Handle the data as soon as new data is available
// mma8451 accelerometer Output Data Rate (ODR) is set to 100 Hz
if(mma8451_ready_flag)
{
    // Set initial timestamp
    ms1 = ms;

    // Clear the flag
    mma8451_ready_flag = false;

    // Reads the data in three global variables: x_out_mg, y_out_mg and
    // z_out_mg
    mma8451_read();
```

# EMBED



*main.c – RAW example at every sample time*

```
// Set final timestamp
```

```
ms2 = ms;
```

```
// Send the data
```

```
// Send the raw data
```

```
printf("%d,%d,%.3f,%.3f,%.3f\n",
```

```
ms1,
```

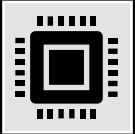
```
ms2,
```

```
(double)(x_out_mg),
```

```
(double)(y_out_mg),
```

```
(double)(z_out_mg));
```

# EMBED



*main.c – RAW example at every sample time*











```
// TODO Implement filter function as required by the application.
```

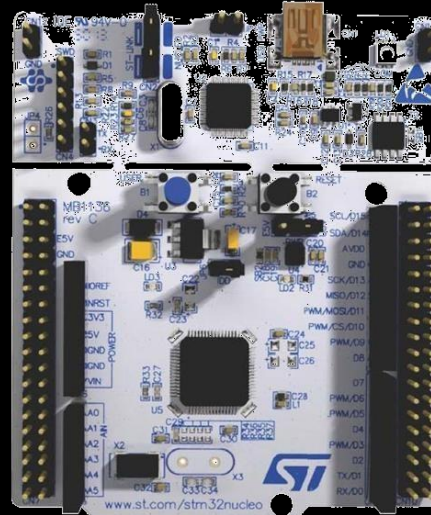
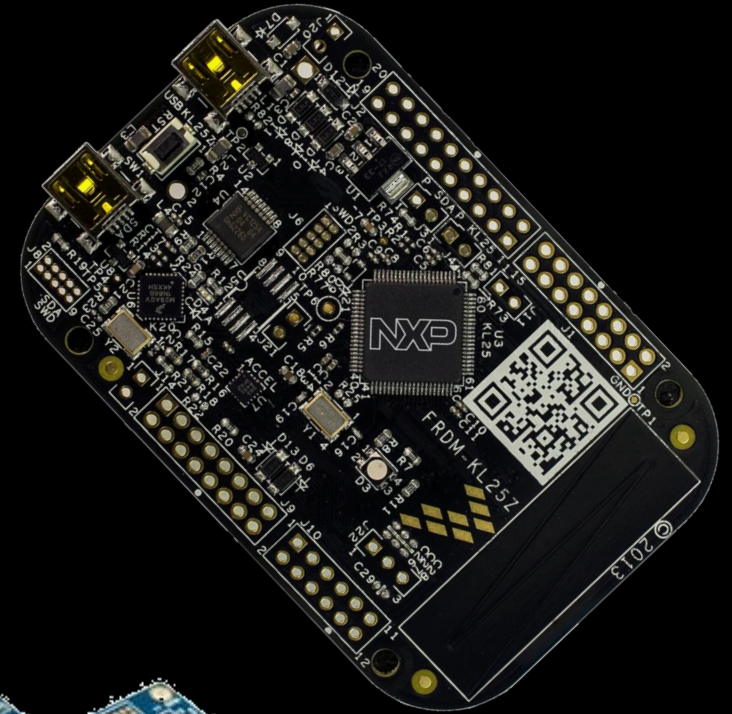
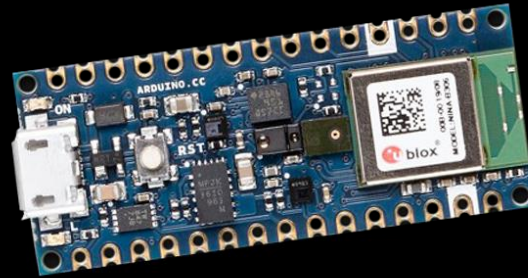
```
// TODO Implement normalization function as required by the  
// application.
```

```
// TODO Finish this example by designing an ML model and implement the  
// generated C code.
```

```
}
```

# SETTING UP YOUR ENVIRONMENT

- >  .git
- >  faq
- >  general
- >  images
- >  lib
- >  results
- >  sheets
- >  targets
- >  template
- >  tools



# RUN

 *Terminal*

```
Opened COM13 @ 115200bps
10912,10912, -1.221,1.465,998.047
10922,10922, -0.732,0.488,997.314
10931,10932,0.244,0.000,998.779
10941,10941, -0.977,1.221,998.535
10951,10951,0.000,1.709,1000.000
10961,10961, -0.244,0.488,997.803
10970,10971, -0.977,0.977,998.291
10980,10980,0.000,1.465,998.779
10990,10990, -0.488,1.709,997.070
11000,11000, -0.977, -0.244,997.314
11009,11010, -0.244,1.465,998.291
11019,11020, -0.488, -0.244,999.268
```



# RUN



Opened COM13 @ 115200bps

```
10912,10912,-1.221,1.465,998.047
10922,10922,-0.732,0.488,997.314
10931,10932,0.244,0.000,998.779
10941,10941,-0.977,1.221,998.535
10951,10951,0.000,1.709,1000.000
10961,10961,-0.244,0.488,997.803
10970,10971,-0.977,0.977,998.291
10980,10980,0.000,1.465,998.779
10990,10990,-0.488,1.709,997.070
11000,11000,-0.977,-0.244,997.314
11009,11010,-0.244,1.465,998.291
11019,11020,-0.488,-0.244,999.268
```

*Communication settings (or  
error message if the comport  
could not be opened)*

# RUN

 *Terminal*

Opened COM13 @ 115200bps

```
10912,10912,-1.221,1.465,998.047
10922,10922,-0.732,0.488,997.314
10931,10932,0.244,0.000,998.779
10941,10941,-0.977,1.221,998.535
10951,10951,0.000,1.709,1000.000
10961,10961,-0.244,0.488,997.803
10970,10971,-0.977,0.977,998.291
10980,10980,0.000,1.465,998.779
10990,10990,-0.488,1.709,997.070
11000,11000,-0.977,-0.244,997.314
11009,11010,-0.244,1.465,998.291
11019,11020,-0.488,-0.244,999.268
```

*Transmitted by microcontroller  
at every sample time*

# RUN

 *Terminal*

```
Opened COM13 @ 115200bps
10912,10912,-1.221,1.465,998.047
10922,10922,-0.732,0.488,997.314
10931,10932,0.244,0.000,998.779
10941,10941,-0.977,1.221,998.535
10951,10951,0.000,1.709,1000.000
10961,10961,-0.244,0.488,997.803
10970,10971,-0.977,0.977,998.291
10980,10980,0.000,1.465,998.779
10990,10990,-0.488,1.709,997.070
11000,11000,-0.977,-0.244,997.314
11009,11010,-0.244,1.465,998.291
11019,11020,-0.488,-0.244,999.268
```

*ms1 and ms2 values  
(comma separated)*

# RUN

 *Terminal*

```
Opened COM13 @ 115200bps
10912,10912,-1.221,1.465,998.047
10922,10922,-0.732,0.488,997.314
10931,10932,0.244,0.000,998.779
10941,10941,-0.977,1.221,998.535
10951,10951,0.000,1.709,1000.000
10961,10961,-0.244,0.488,997.803
10970,10971,-0.977,0.977,998.291
10980,10980,0.000,1.465,998.779
10990,10990,-0.488,1.709,997.070
11000,11000,-0.977,-0.244,997.314
11009,11010,-0.244,1.465,998.291
11019,11020,-0.488,-0.244,999.268
```

*One or more sensor values  
(comma separated)*