

review: 1. 链式法则推导 (差分/微分)

2. 反函数

3. Taylor 公式 Newton 二项式

第一型曲线积分

$$\text{定义: } \int_L^B f(x(t), y(t)) / \sqrt{(x'(t))^2 + (y'(t))^2} dt$$

$$= \sum_{n=1}^{\infty} P(x(\eta_i), y(\eta_i)) \int_{\eta_i}^{\eta_{i+1}} \sqrt{(x'(t))^2 + (y'(t))^2} dt$$

$$= \sum_{n=1}^{\infty} P(x(\eta_i), y(\eta_i)) \sqrt{x'(\eta_i)^2 + y'(\eta_i)^2} dt$$

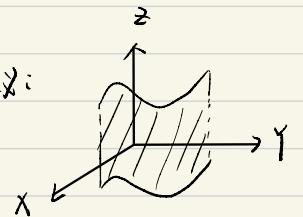
$$\begin{cases} F(x, y) = 0 \\ G(x, y) = 0 \end{cases}$$

$$\frac{\partial(F, G)}{\partial(y, z)} = \begin{vmatrix} \frac{\partial F}{\partial y} & \frac{\partial F}{\partial z} \\ \frac{\partial G}{\partial y} & \frac{\partial G}{\partial z} \end{vmatrix} \neq 0.$$

entire 沿部分单洞映射.

隐函数映射

几何意义:



$$\int_L f(x(t), y(t)) ds = \int_2^B f(\varphi(t), \psi(t)) / \sqrt{(\varphi'(t))^2 + (\psi'(t))^2} dt$$

第二型曲线积分

$$F = (P(x, y), Q(x, y))$$

$$S = (\Delta x, \Delta y)$$

$$\int_S P(x, y) dx + Q(x, y) dy$$

$$\sum_{j=1}^n F_j \cdot S_j = \sum_{j=1}^n \| \vec{v} \|^2 \| S_j \| \text{ det}(F_j, S_j)$$

$$= \sum P(x_j, y_j) \Delta x_j + Q(x_j, y_j) \Delta y_j$$

$$\xrightarrow{\|M\| \rightarrow 0} \int_S P(x, y) dx + Q(x, y) dy$$

换元



$$\begin{cases} x = x(t) \\ y = y(t) \end{cases} \rightarrow \int_L [P(x(t), y(t)) x'(t) + Q(x(t), y(t)) y'(t)] dt$$

$$\lim_{\|M\| \rightarrow 0} \sum_{j=1}^n P(x_j, y_j) \Delta x_j + Q(x_j, y_j) \Delta y_j$$

$\|M\| \rightarrow$ 曲线的精度 \rightarrow 质量
 $t \rightarrow$ 时长 \rightarrow

中值定理

$$= \lim_{\|M\| \rightarrow 0} \sum_{j=1}^n \underbrace{P(x_j, y_j)}_{Q(x_j, y_j) - Q(x_{j-1}, y_{j-1})} \underbrace{\Delta x_j}_{\Delta x_j = X'(m_j) \Delta t_j} + \underbrace{Q(x_j, y_j)}_{Q(x_j, y_j) - Q(x_{j-1}, y_{j-1})} \underbrace{\Delta y_j}_{\Delta y_j = Y'(m_j) \Delta t_j}$$

$$|Q(x_j, y_j) - Q(x_{j-1}, y_{j-1})| \leq M |y_j - y_{j-1}| \leq M \Delta t_j$$

故可用 m_j 代替 m_j'

$$\int_L P \frac{dx}{dt} + Q \frac{dy}{dt} dt$$

$$\therefore \int_L P dx + Q dy = \int_L P dx + Q dy$$



第一、二型曲线积分的关系

$$\int_L P dx + Q dy = \int_L (P \frac{dx}{ds} + Q \frac{dy}{ds}) \cdot ds \quad \begin{cases} x = x(s) \\ y = y(s) \end{cases}, \quad s_0 \leq s \leq s_1$$
$$= \int_L (P \cos\alpha + Q \cos\beta) \cdot ds \quad \frac{dx}{ds} = \cos\alpha, \quad \frac{dy}{ds} = \cos\beta, \quad ds = \sqrt{dx^2 + dy^2}$$

pr+

$$\textcircled{2} \quad f(x,y) = f(y,x)$$

$f(x,y,z)$
三维情况是否可交换.

$$\int_L f(x,y) dx \neq \int_L f(y,x) dy$$

成立

$$\int_L f(x,y) \frac{dx}{ds} ds$$

$$\int_L f(y,x) \frac{dy}{ds} ds$$



计算变积分时，牛顿公式反映了区间上定积分与其端点上原函数之间的联系： $\int_a^b \frac{\partial F(x)}{\partial x} dx = F(b) - F(a)$

格林公式则反映了平面上二重积分与其边界上第二型曲线积分之间的联系： $\iint_D (\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}) d\sigma = \oint_L P dx + Q dy$

格林公式

定义：若函数 $P(x, y)$, $Q(x, y)$ 在闭区域 D 上有连续的一阶偏导数，(正方向为左手法则)

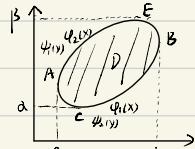
则有 $\iint_D (\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}) d\sigma = \oint_L P dx + Q dy$

L 为区域 D 的边界曲线，并取正方向

平面区域 D 的面积 S_D 的公式： $S_D = \iint_D d\sigma = \frac{1}{2} \oint_L x dy - y dx = \begin{cases} \oint_L x dy \\ \oint_L y dx \end{cases}$

(具体推导与这题的推导相似)

$$\left. \begin{array}{ll} ACB & AEB \\ \varphi_1(x) \leq y \leq \varphi_2(x) & (x \in [a, b]) \\ AE & CBE \\ \varphi_1(y) \leq x \leq \varphi_2(y) & (y \in [\varphi_1(b), \varphi_2(b)]) \end{array} \right.$$



$$\begin{aligned} & \iint_D (\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}) d\sigma = \oint_L P dx + Q dy \\ \text{Proof: } & \iint_D \frac{\partial Q}{\partial x} d\sigma = \int_a^b \int_{\varphi_1(x)}^{\varphi_2(x)} \frac{\partial Q}{\partial x} dx dy \\ & = \int_a^b (Q(\varphi_2(y), y) - Q(\varphi_1(y), y)) dy \\ & = \int_{AE} Q(\varphi_1(y), y) dy - \int_{AC} Q(\varphi_1(y), y) dy \\ & = \int_{CBE} Q(\varphi_1(y), y) dy + \int_{BE} Q(\varphi_1(y), y) dy \\ & = \oint_L Q dy \\ & = \iint_D \frac{\partial P}{\partial y} d\sigma = \int_a^b dx \int_{\varphi_1(x)}^{\varphi_2(x)} \frac{\partial P}{\partial y} dy \\ & = \int_a^b P(x, \varphi_2(x)) - P(x, \varphi_1(x)) dx \\ & = \int_{AE} P(x, \varphi_2(x)) dx - \int_{AC} P(x, \varphi_1(x)) dx \\ & = \int_{CBE} P(x, \varphi_2(x)) dx - \int_{BE} P(x, \varphi_1(x)) dx \\ & = - \oint_L P dx \end{aligned}$$

$$\iint_D (\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}) d\sigma = \oint_L Q dy + P dx$$

凑微分法 (Pay attention)

单连通区域：对于平面区域D内任一闭合曲线，皆可不经过D以外的点而连续收缩于属于D的某一点。

复连通区域：



二维连通(面)

一维连通为线

$f(x,y)$ 在 (x,y) 这点可微

$$\frac{\partial f}{\partial x}(x,y), \frac{\partial f}{\partial y}(x,y)$$

$$f(x_0, y_0) - f(x, y) = A \Delta x + B \Delta y + o(\rho) \quad \rho = \sqrt{\Delta x^2 + \Delta y^2}$$

偏导
连续 \rightarrow 可微 \Leftrightarrow 偏导存在，
(函数的偏导数)
 \downarrow
偏导数。

曲线积分与路线的无关性

定理2：设D是单连通闭区域。若函数 $P(x,y)$, $Q(x,y)$ 在D内连续且具有一阶偏导数

Lagrange.

TAFE：

1) 沿D内任一段光滑封闭曲线L, 有 $\oint_L P dx + Q dy = 0$

2) 对D中任一段光滑曲线L, 曲线积分 $\oint_L P dx + Q dy$ 与路线无关, 只与始、终点有关

3) $P dx + Q dy$ 是D内某一函数 $u(x,y)$ 的全微分, 在D内有 $du = P dx + Q dy$

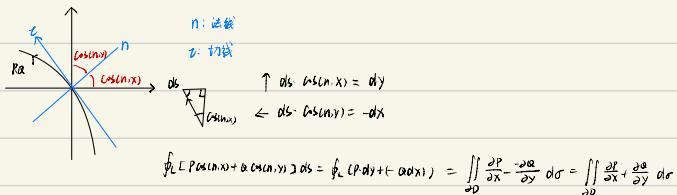
4) D内处处成立 $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$

$$\frac{\int_{x_0}^{x_1} P dx}{\Delta x} = \text{circle}$$

验证格林公式为一形式： $\iint_D (\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y}) dx dy = \oint_D [P(x,y) + Q(x,y)] ds$ (n 为 D 的边界 ∂D 上任一点处的外法线向量)

连通的开集 - 形域

开集及其附属的一闭域



1) \rightarrow 2) :

$$\oint_D P dx + Q dy = \oint_{L_1} P dx + Q dy + \oint_{L_2} P dx + Q dy$$

2) \rightarrow 3) :

已知当曲线为分段光滑无尖点， (x_0, y_0) 为 D 中固定点， (x, y) 为 D 中任意点。

$$dA = u(x_0, y) = \int_{(x_0, y)}^{(x, y)} P dx + Q dy / |U(x, y) - U(x_0, y)| = \int_{AB} P dx + Q dy$$

$$u(x_0, y) = \int_{(x_0, y)}^{(x_0, y)} P dx + Q dy \quad u(x_0, y) = \int_{(x_0, y)}^{(x, y)} P dx + Q dy$$

$$\frac{1}{2} \int_{AB} \frac{\partial u}{\partial x}(x_0, y) dx = \frac{1}{2} \int_{AB} \frac{\partial u}{\partial x}(x) dx = p(x_0, y)$$

$$\text{同理可得 } \frac{\partial u}{\partial y}(x_0, y) = q(x_0, y)$$

看偏导数

⑤

$$\therefore du = P dx + Q dy$$

3) \rightarrow 4) :

$$\text{由 3) 可知 } \exists u(x, y) \text{ st. } \frac{\partial u}{\partial x} = P, \frac{\partial u}{\partial y} = Q$$

$$\text{故 } \frac{\partial P}{\partial y} = \frac{\partial^2 u}{\partial y^2}, \quad \frac{\partial Q}{\partial x} = \frac{\partial^2 u}{\partial x^2}$$

已证明

因为 $P(x, y), Q(x, y)$ 是第一阶偏导数，故 $\frac{\partial^2 u}{\partial y^2}, \frac{\partial^2 u}{\partial x^2}$ 在 D 上连续

$$\frac{\partial Q}{\partial x} = \frac{\partial^2 u}{\partial x \partial y} = \frac{\partial^2 u}{\partial y \partial x} = \frac{\partial P}{\partial y}$$

连续可使用积分恒等性质

4) \rightarrow 1) :

$$\begin{aligned} \frac{\partial u}{\partial x} &= \int_{x_0 x_0} \frac{u(x_0, y) - u(x, y)}{\Delta x} \\ &= \frac{\int_{AB} P dx + Q dy - \int_{AB} P dx + Q dy}{\Delta x} \end{aligned}$$

$$\frac{\partial u}{\partial x} = \frac{\int_{AB} P dx}{\Delta x} = \frac{\int_{AB} P dx}{\Delta x} = p(x_0, y)$$

$$\frac{\partial u}{\partial x} = p(x_0, y)$$

$$\frac{\partial u}{\partial y} = q(x_0, y)$$

设 L 为 D 内沿段光滑曲线， L 所围区域为 Ω 。由于 D 为单连通区域， Ω 在 D 内。

应用 Green 公式，在 Ω 内恒有 $\frac{\partial u}{\partial y} = \frac{\partial v}{\partial x}$ 得 $\oint_L P dx + Q dy = \iint_{\Omega} (\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}) dx dy = 0$

n维空间第一型曲线积分

$$\left\{ \begin{array}{l} x_1 = x_1(t) \\ \vdots \\ x_n = x_n(t) \end{array} \right.$$

$$y = f(x_1, \dots, x_n) \quad \text{中 } \int_L y \, ds$$

对t作分割: $P_0, P_1, P_2, \dots, P_{i-1}, P_i, \dots, P_m, P_m$

$$x_1: x_1(t_0), x_1(t_1), \dots, x_1(t_m)$$

$$\vdots \quad \vdots \quad \vdots \quad \vdots$$

$$x_n: x_n(t_0), x_n(t_1), \dots, x_n(t_m)$$

$$\lim_{\|T\| \rightarrow 0} \sum_{i=1}^m \sqrt{(x_1(\xi_i), x_2(\xi_i), \dots, x_n(\xi_i)) \cdot (x_1'(\xi_i)^2 + \dots + x_n'(\xi_i)^2)} \cdot dt$$

$$= \int_a^b f(x_1(t), x_2(t), \dots, x_n(t)) \sqrt{x_1'(t)^2 + \dots + x_n'(t)^2} \, dt$$

$f(x_0)$ 连续



同理

$$f((x_0-\delta), (x_0+\delta)) \subset U(f(x_0), \varepsilon).$$

小面积微元。

$$J(u, v) = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} \neq 0 \quad \text{二阶导数.}$$

$$\int_a^b f(x) dx \quad x = x(t) \quad x(t) \neq 0 \quad \text{一阶导数}$$

混合偏导数连续必相等。

言，此项目成员对于系统的真正完善还需物理以及地理方面的深入研究。
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关知识，并研读国内外相关文献。

