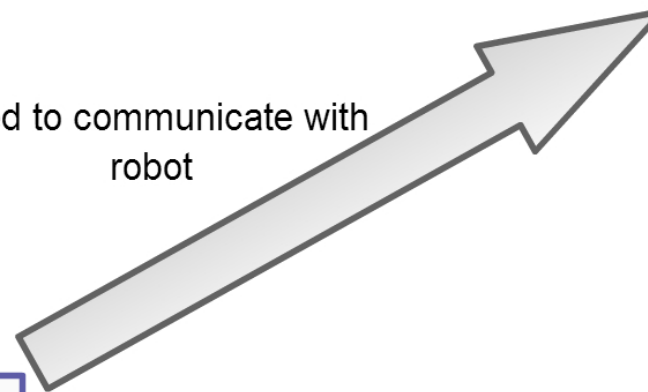
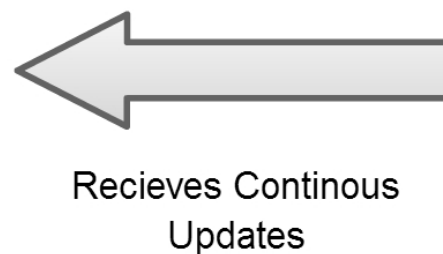
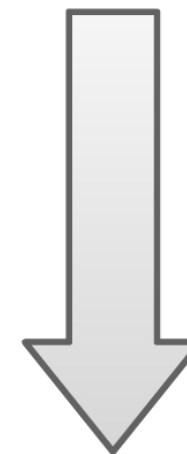


Used to communicate with  
robot



Checks Sensor Value  
through



Send/Receive  
instructions/information

