

Computer Organization & Assembly Language

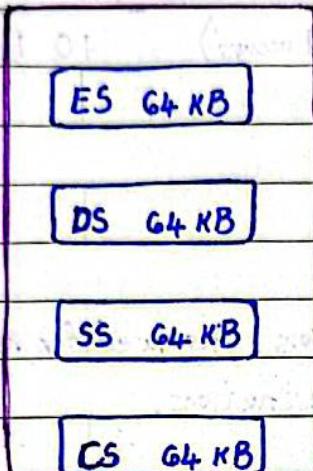
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Assignment #01

Q1:-

FFFFFh (Top Memory) : 1 MB memory space

(a)



Physical Address (Linear):

(Segment \times 10h) + Offset

00000h (Bottom Memory)

Physical Address = (Segment \times 10h) + Offset

\therefore The segment value is shifted left by 4 bits when multiplied by 10h (hex).

8086 uses 20 bits linear address in hex.

(b)

(i) 1234 : 5678

$$\begin{aligned}\text{Physical Address} &= (1234 \times 10h) + 5678h \\ &= 12340h + 5678h \\ &= 179B8h \quad (\text{no wrap-around})\end{aligned}$$

(ii) FFFF : 000F

$$\begin{aligned}\text{Physical Address} &= (FFFF \times 10h) + 000Fh \\ &= FFFF0h + 000Fh \\ &= FFFFFh \quad (\text{no wrap-around})\end{aligned}$$

(iii) F000 : FFF0

$$\begin{aligned}\text{Physical Address} &= (F000 \times 10h) + FFF0h \\ &= F0000h + FFF0h \\ &= FFFFFh \quad (\text{no wrap-around})\end{aligned}$$

(iv) F800 : 9000

$$\text{Physical Address} = (\text{F800} \times 10h) + 9000h$$

$$= \text{F8000h} + 9000h$$

$$= 101000h \quad (\text{wrap-around occurs})$$

$$= 101000h - 100000h$$

$$= 01000h$$

$$\begin{array}{r} \text{F8000h} \\ + 9000h \\ \hline 101000h \end{array}$$

Q2:- General Purpose:

EAX :- Used for arithmetic and logic operations. Also used for return values from functions and used for control instructions.

eg: MOV EAX, 10

ADD EAX, 20

EBX :- Used as a base pointer for the purpose of memory addressing.

eg: MOV EBX, OFFSET arr

MOV EAX, [EBX]

ECX :- Used as a counter in Loops

eg: MOV ECX, 4

loop-example:

ADD EAX, 5

LOOP Loop-example

Index/Base/Stack instruction:

EDX :- Used for multiplication, division and input/output operations.

eg: MOV EDX, 10

IMUL EDX, 5

ESI :- It points the source in string and memory operations.

eg: MOV ESI, OFFSET src

EDI :- It points to the destination in string and memory operations.

eg:- `MOV EDI, OFFSET dest`

ESP :- It points to the top of the stack ; can be used for push/pop function calls.

eg:- `PUSH EAX`
`POP EBX`

EBP :- It is used to reference function parameters and local variables on stack.

eg:- `PUSH EBP`
`MOV EBP, ESP`
`MOV EAX, [EBP + 8]`

EIP :- It holds the address of the next instruction to be executed.

CPU is responsible for updating it automatically after every instruction.

eg:- `JMP myLabel`

Q3:- `0x1234ABCD` starting address = `4000h`

Little Endian:

`4000h` → CD
`4001h` → AB
`4002h` → 34
`4003h` → 12

Big Endian:

`4000h` → 12
`4001h` → 34
`4002h` → AB
`4003h` → CD

Q4:-

(i) `MOV AX, 8F7AH`

∴ `8F7AH` → 1000 1111 0111 1010 b

Hence;

`AX = 8F7AH` (H means in hex)

`CF = 0`

`SF = 0`

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(ii) ADD AX, 7A F8H

$\therefore 8F7A \text{ h}$

Hence;

$+ 7AF8 \text{ h}$

$AX = 0A72 \text{ h}$

$10A72 \text{ h}$

$CF = 1$

$SF = 0$

(iii) MOV BX, OFA77 H

$\therefore FA77 \text{ h} \rightarrow 1111 1010 0111 0111 \text{ b}$

Hence;

$BX = FA77 \text{ H}$

$CF = 01$

$SF = 0$

(iv) INC BX

$\therefore FA77 \text{ H} + 1 = FA88 \text{ H}$

Hence;

$BX = FA88 \text{ H}$

$CF = 01$

$SF = 01$

Q5- (i), (ii) & (iii)

INCLUDE Irvine32.inc

Seconds EQU 60

Minutes EQU 60

Hours EQU 24

Days EQU 7

.data

finalResult DWORD ?

.code

main PROC

```

    mov eax, Seconds
    imul eax, Minutes
    imul eax, Hours
    imul eax, Days

    mov finalresult, eax ; Saving result into memory
    call Write Dec ; printing the result using eax
    call CRLF
    exit

main ENDP
END main

```

Q6:- INCLUDE Irvine32.inc

```

.data
myArray WORD 1, 2, 3, 4, 5, 6, 7, 8, 9, 10
size EQU 10
temp WORD ?

```

~~mov bx, [myArray]~~

~~mov esi, OFFSET myArray~~

~~mov ax, myArray~~

~~mov temp, ax~~

~~mov ecx, size - 1~~

~~mov esi, OFFSET myArray~~

reverseArr:

~~mov ax, [esi + 2]~~

~~mov esi, ax~~

~~add esi, 2~~

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loop reverseArr

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mov ax, temp
mov esi, ax
mov ecx, size
mov esi, OFFSET my Array

printArr:

 mov ax, esi
 movzx eax, ax
 call WriteInt
 call CRLF
 addesi, 2
 loop printArr
 exit

main ENDP

END main

Q1:-

a) For Little endian :-

3000h 3001h 3002h 3003h
D4 C3 B2 A1

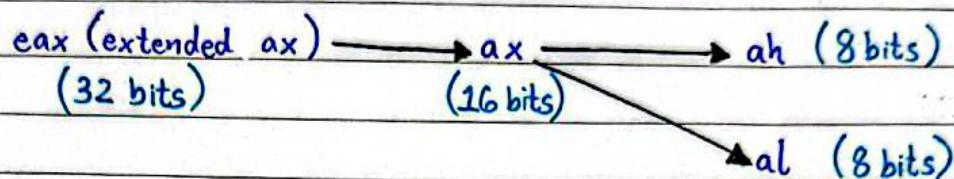
b) For big endian, at lowest address, the Most Significant Byte will be stored and at the highest address, the Least Significant Byte will be stored. (Opposite of Little Endian).

3000h 3001h 3002h 3003h
A1 B2 C3 D4

c) mov eax, [3000h]

Q8:-

The general purpose registers in x86 are 32-bit by default. They can be accessed in smaller chunks for better efficiency and flexibility when storing 16 bits or 8 bits. The x86 architect is compatible with older 16 bit and 8 bit processor; hence the registers can be split as shown:



This design allows program written for older CPUs be still executed which enhances flexibility.

For example, when storing a hex character code for 'C' which is 43h. Using eax (32 bits), the processor will allocate 4 bytes for it even though 43h is 1 byte, which makes operations slower when working with strings or characters.

However, using ah or al (both 8-bits), the processor allocates 1 byte which is the same byte size needed to store 43h (1 byte); hence not wasting any memory unnecessarily.

Q9:- INCLUDE Irvin e32.inc

.data

varA DWORD 10

varB DWORD 50

varC DWORD 5

varD DWORD 15

.code

main PROC

mov eax, varA

add eax, varB

```
    mov ebx, var C
    add ebx, var D
    sub eax, ebx
    mov var A, eax ; moving final result back to varA
    call Write Dec
    exit
main ENDP
END main
```

Q10:- Let's discuss about one-to-one relationship.

- ① One to one relationship is when a single entity is related to only one other entity.

Eg:- A single assembly language instruction corresponds to only a single machine code instruction.

One to many relationship is when a single entity is related to multiple identities.

Eg:- A single high-level language instruction is equal to multiple lines/instructions in assembly and machine code.

- ② Registers are present inside the CPU, hence instant access. Whereas, for memory access, first address is placed on the address bus then assert the processor's read pin. Then it takes one clock cycle for memory chip to respond. Finally, data is copied from databus to destination operand.

- ③ Machine independent language refers to such a language which can be compiled and executed on any computer system unless the program uses a user-defined libraries; eg:- C++, Java, Python.

Machine dependent language are depended on the type of processor and cannot be compiled/assembled on every computer system.

Eg:- assembly language.

④ Computer Architecture is the way hardware components operate and connected together to form computer system. Computer Organization is concerned with the structure and behaviour of computer system as seen by the user.

⑤ Carry Flag (will be set to 1)

⑥ The source file contains the code written by programmer while the Listing file contains the source code, line number, numeric addresses of instructions and machine code bytes of each instructions.

⑦ Registers are a part of CPU hence ~~memory~~ accessing data is very fast, whereas accessing through memory requires going through buses and possibly memory hierarchy.

⑧ Real Address Mode has 1 MB of memory from 00000 h to FFFFF h. Program can access any part of memory. MS-DOS runs in real address mode. However, in protected mode, each program has total 4 GB of memory capacity available. The Operating System assigns memory to each running program. Programs are prevented from each other's memory. Modern OS requires memory protection & multi-tasking, which Real Address Mode lacks.

⑨ Address Bus, Data Bus and Control Bus are essential components. The address bus holds the address of the instruction and data when the currently executing instruction transfers data between CPU and memory. The data bus transfers data and instructions between CPU and memory. The control bus uses binary signals to synchronize actions of all devices connected to the system.