

Computer Organization & Assembly Language

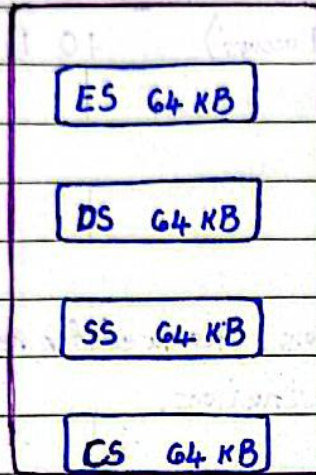
Assignment #01

Date: _____

Q1 :-

FFFFFh (Top Memory) : 1 MB memory space

(a)



Physical Address (Linear):
(Segment $\times 10h$) + Offset

00000h (Bottom Memory)

Physical Address = (Segment $\times 10h$) + Offset

\therefore The segment value is shifted left by 4 bits when multiplied by $10h$ (hex).

8086 uses 20 bits linear address in hex.

(b)

(i) 1234 : 5678

$$\begin{aligned} \text{Physical Address} &= (1234 \times 10h) + 5678h \\ &= 12340h + 5678h \\ &= 179B8h \quad (\text{no wrap-around}) \end{aligned}$$

(ii) FFFF : 000F

$$\begin{aligned} \text{Physical Address} &= (FFFF \times 10h) + 000Fh \\ &= FFFF0h + 000Fh \\ &= FFFFFh \quad (\text{no wrap-around}) \end{aligned}$$

(iii) F000 : FFF0

$$\begin{aligned} \text{Physical Address} &= (F000 \times 10h) + FFF0h \\ &= F0000h + FFF0h \\ &= FFFF0h \quad (\text{no wrap-around}) \end{aligned}$$

(iv) F800 : 9000

$$\begin{aligned}\text{Physical Address} &= (F800 \times 10h) + 9000h \\ &= F8000h + 9000h \\ &= 101000h \quad (\text{wrap-around occurs}) \\ &= 101000h - 100000h \\ &= 01000h\end{aligned}$$

F 8 0 0 0 h
+ 9 0 0 0 h

1 0 1 0 0 0 h

Q2:- General Purpose:

EAX:- Used for arithmetic and logic operations. Also used for return values from functions and used for control instructions.

eg: `MOV EAX, 10`
`ADD EAX, 20`

EBX:- Used as a base pointer for the purpose of memory addressing.

eg: `MOV EBX, OFFSET arr`
`MOV EAX, [EBX]`

ECX:- Used as a counter in loops

eg: `MOV ECX, 4`
loop-example: `ADD EAX, 5`
`LOOP loop-example`

Index/Base/Stack instruction:

EDX:- Used for multiplication, division and input/output operations.

eg: `MOV EDX, 10`
`IMUL EDX, 5`

ESI:- It points the source in string and memory operations.

eg: `MOV ESI, OFFSET src`

EDI :- It points to the destination in string and memory operations.

eg: MOV EDI, OFFSET dest

ESP :- It points to the top of the stack; can be used for push/pop function calls.

eg:- PUSH EAX

POP EBX

EBP :- It is used to reference function parameters and local variables on stack.

eg:- PUSH EBP

MOV EBP, ESP

MOV EAX, [EBP + 8]

EIP :- It holds the address of the next instruction to be executed.

CPU is responsible for updating it automatically after every instruction.

eg:- JMP myLabel

Q3:- 0 x 1234 ABCD

starting address = 4000h

Little Endian:

4000h → CD

4001h → AB

4002h → 34

4003h → 12

Big Endian:

4000h → 12

4001h → 34

4002h → AB

4003h → CD

Q4:-

(i) MOV AX, 8F7AH

∴ 8F7Ah → 1000 1111 0111 1010 b

Hence;

AX = 8F7AH (H means in hex)

CF = 0

SF = 0

(ii) ADD AX, 7A F8 H

 $\therefore \begin{array}{r} 8F7A \text{ h} \\ + 7AF8 \text{ h} \\ \hline 10A72 \text{ h} \end{array}$

Hence;

AX = 0A72 h

CF = 1

SF = 0

(iii) MOV BX, 0FA77 H

 $\therefore \text{FA77 h} \rightarrow 1111 \ 1010 \ 0111 \ 0111 \text{ b}$

Hence;

BX = FA77 H

CF = 1

SF = 0

(iv) INC BX

 $\therefore \text{FA77 H} + 1 = \text{FA88 H}$

Hence;

BX = FA88 H

CF = 1

SF = 1

Q5:- (i), (ii) & (iii)

INCLUDE Irvine32.inc

Seconds EQU 60

Minutes EQU 60

Hours EQU 24

Days EQU 7

.data

finalresult DWORD ?

.code

main PROC

```
mov eax, Seconds
```

```
imul eax, Minutes
```

```
imul eax, Hours
```

```
imul eax, Days
```

```
mov finalresult, eax
```

; saving result into memory

```
mov eax, finalresult
```

```
call Write Dec
```

; printing the result using eax

```
call CRLF
```

```
exit
```

```
main ENDP
```

```
END main
```

Q6:- INCLUDE Irvine32.inc

```
.data
```

```
myArray WORD 1, 2, 3, 4, 5, 6, 7, 8, 9, 10
```

```
size EQU 10
```

```
temp WORD ?
```

```
.code
```

```
main PROC
```

```
mov ebx, [myArray]
```

```
mov esi, OFFSET myArray
```

```
mov ax, myArray
```

```
mov temp, ax
```

```
mov ecx, size - 1
```

```
mov esi, OFFSET myArray
```

```
reverseArr:
```

```
mov ax, [esi + 2]
```

```
mov esi, ax
```

```
add esi, 2
```

```
loop reverseArr
```

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```
mov ax, temp
mov esi, ax
mov ecx, size
mov esi, OFFSET myArray
printArr:
    mov ax, esi
    movzx eax, ax
    call WriteInt
    call CRLF
    add esi, 2
    loop printArr
    exit
```

main ENDP

END main

Q1:-

(a) For Little endian :-

3000h	3001h	3002h	3003h
D4	C3	B2	A1

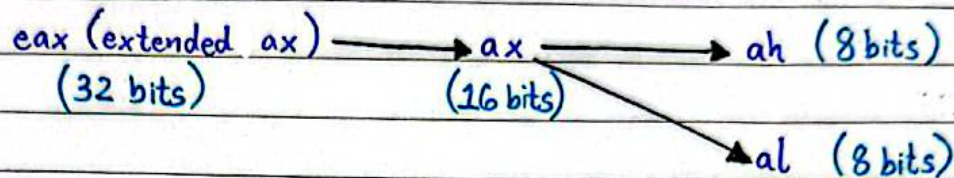
(b) For big endian, at lowest address, the Most Significant Byte will be stored and at the highest address, the Least Significant Byte will be stored. (Opposite of Little Endian)

3000h	3001h	3002h	3003h
A1	B2	C3	D4

(c) `mov eax, [3000h]`

Q8:-

The general purpose registers in x86 are 32-bit by default. They can be accessed in smaller chunks for better efficiency and flexibility when storing 16 bits or 8 bits. The x86 architect is compatible with older 16 bit and 8 bit processor ; hence the registers can be split as shown:



This design allows program written for older CPUs be still executed which enhances flexibility.

For example, when storing a hex character code for 'C' which is 43h. Using eax (32 bits), the processor will allocate 4 bytes for it even though 43h is 1 byte, which makes operations slower when working with strings or characters.

However, using ah or al (both 8-bits), the processor allocates 1 byte which is the same byte size needed to store 43h (1 byte); hence not wasting any memory unnecessarily.

Q9:- INCLUDE Irvine32.inc

.data

var A DWORD 10

var B DWORD 50

var C DWORD 5

var D DWORD 15

.code

main PROC

mov eax, var A

add eax, var B


```
mov ebx, var C
add ebx, var D

sub eax, ebx
mov var A, eax ; moving final result back to var A
call WriteDec
exit

main ENDP
END main
```

Q10:-

- ① One to one relationship is when a single entity is ~~only~~ related to only one other entity.

Eg:- A single assembly language instruction corresponds to only a single machine code instruction.

One to many relationship is when a single entity is related to multiple identities.

Eg:- A single high-level language instruction is equal to multiple lines/instructions in assembly and machine code.

- ② Registers are present inside the CPU, hence instant access. Whereas, for memory access, first address is placed on the address bus then assert the processor's read pin. Then it takes one clock cycle for memory chip to respond. Finally, data is copied from data bus to destination operand.

- ③ Machine independent language refers to such a language which can be compiled and executed on any computer system unless the program uses a user-defined libraries; eg:- C++, Java, Python.

Machine dependent language are depended on the type of processor and cannot be compiled/assembled on every computer system.

eg:- assembly language.

- ④ Computer Architecture is the way hardware components operate and connected together to form computer system. Computer Organization is concerned with the structure and behaviour of computer system as seen by the user.
- ⑤ Carry Flag (will be set to 1)
- ⑥ The source file contains the code written by programmer while the listing file contains the source code, line number, numeric addresses of instructions and machine code bytes of each instructions.
- ⑦ Registers are a part of CPU hence ~~memory~~ accessing data is very fast, whereas accessing through memory requires going through buses and possibly memory hierarchy.
- ⑧ Real Address Mode has 1 MB of memory from 00000 h to FFFFF h. Program can access any part of memory. MS-DOS runs in real address mode. However, in protected mode, each program has total 4 GB of memory capacity available. The Operating System assign memory to each running program. Programs are prevented from each other's memory. Modern OS requires memory protection & multi-tasking, which Real Address Mode lacks.
- ⑨ Address Bus, Data Bus and Control Bus are essential components. The address bus hold the address of the instruction and data when the currently executing instruction transfers data between CPU and memory. The data bus transfers data and instructions between CPU and memory. The control bus uses binary signals to synchronize actions of all devices connected to the system.