

تثبيت نظام روز على نظام تشغيل أوبنتو

بعد تثبيت نظام تشغيل أوبنتو 20.04 سواء على virtualbox او كنظام أساسي نتوجه لتثبيت آخر إصدار من نظام ROS وهو Noetic المتوافق مع الإصدار الأخير من أوبنتو



```
rayyan@Rayyan: ~$ wget -c https://raw.githubusercontent.com/qboticslabs/ros_install_noetic/master/ros_install_noetic.sh && chmod +x ./ros_install_noetic.sh && ./ros_install_noetic.sh
--2020-06-17 00:55:39-- https://raw.githubusercontent.com/qboticslabs/ros_install_noetic/master/ros_install_noetic.sh
Resolving raw.githubusercontent.com (raw.githubusercontent.com)... 151.101.36.133
Connecting to raw.githubusercontent.com (raw.githubusercontent.com)|151.101.36.133|:443... connected.
HTTP request sent, awaiting response... 200 OK
Length: 5510 (5.4K) [text/plain]
Saving to: 'ros_install_noetic.sh'
ros_install_noetic.sh 100%[=====] 5.39K --
```

1- بعد فتح التيرمينال نقوم بكتابة الكود الموضح في الصورة التالية

2- ننتظر بعض الوقت حتى يصل لهذه مرحلة ونختار 1 و نضغط enter و ننتظر حتى ينتهي تثبيت full-desktop * بكامل الخصائص

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#####
> {Step 5: Install ROS, you pick how much of ROS you would like to install.}
[1. Desktop-Full Install: (Recommended) : Everything in Desktop plus 2D/3D simulators and 2D/3D perception packages ]

[2. Desktop Install: Everything in ROS-Base plus tools like rqt and rviz]

[3. ROS-Base: (Bare Bones) ROS packaging, build, and communication libraries. No GUI tools.]

top your install (default is 1x)
```

3- بعد انتهاء التثبيت نقوم باستعراض نسخة ROS لكي نتأكد من أن التثبيت تم بنجاح عن طريق كتابه الكود -d Rosversion في التيرمينال

```
rayyan@Rayyan: ~
Unpacking libbignition-transport8-log-dev:amd64 (8.0.0-1-focal) ...
Selecting previously unselected package libbignition-transport8-dev:amd64.
Preparing to unpack .../1005-libbignition-transport8-dev_8.0.0-1-focal_amd64.deb ...
Unpacking libbignition-transport8-dev:amd64 (8.0.0-1-focal) ...
Selecting previously unselected package libsimbody-dev:amd64.
Preparing to unpack .../1006-libsimbody-dev_3.6.1+dfsg-7build1_amd64.deb ...
Unpacking libsimbody-dev:amd64 (3.6.1+dfsg-7build1) ...
Selecting previously unselected package libbullet-dev:amd64.
Preparing to unpack .../1007-libbullet-dev_2.88+dfsg-2build2_amd64.deb ...
Unpacking libbullet-dev:amd64 (2.88+dfsg-2build2) ...
Selecting previously unselected package gazebo11-plugin-base.
Preparing to unpack .../1008-gazebo11-plugin-base_11.0.0-2-focal_amd64.deb ...
Unpacking gazebo11-plugin-base (11.0.0-2-focal) ...
Selecting previously unselected package libgazebo11-dev:amd64.
Preparing to unpack .../1009-libgazebo11-dev_11.0.0-2-focal_amd64.deb ...
Unpacking libgazebo11-dev:amd64 (11.0.0-2-focal) ...
dpkg: error processing archive /tmp/apt-dpkg-install-OLhLxc/1009-libgazebo11-dev_11.0.0-2-focal_amd64.deb (--unpack):
 cannot copy extracted data for './usr/include/gazebo-11/gazebo/rendering/Scene.hh' to './usr/include/gazebo-11/gazebo/rendering/Scene.hh.dpkg-new': failed
No apport report written because the error message indicates a disk full error
dpkg-deb: error: paste subprocess was killed by signal (Broken pipe)
Selecting previously unselected package ros-noetic-gazebo-dev.
Preparing to unpack .../1010-ros-noetic-gazebo-dev_2.9.1-1focal.20200529.054115_amd64.deb ...
Unpacking ros-noetic-gazebo-dev (2.9.1-1focal.20200529.054115) ...
Selecting previously unselected package ros-noetic-gazebo-msgs.
Preparing to unpack .../1011-ros-noetic-gazebo-msgs_2.9.1-1focal.20200529.064004_amd64.deb ...
Unpacking ros-noetic-gazebo-msgs (2.9.1-1focal.20200529.064004) ...
dpkg: error processing archive /tmp/apt-dpkg-install-OLhLxc/1011-ros-noetic-gazebo-msgs_2.9.1-1focal.20200529.064004_amd64.deb (--unpack):
 unable to write new file './var/lib/dpkg/info/ros-noetic-gazebo-msgs.list-new': No space left on device
No apport report written because the error message indicates a disk full error
Selecting previously unselected package ros-noetic-gazebo-ros.
Preparing to unpack .../1012-ros-noetic-gazebo-ros_2.9.1-1focal.20200529.070139_amd64.deb ...
Unpacking ros-noetic-gazebo-ros (2.9.1-1focal.20200529.070139) ...
dpkg: error processing archive /tmp/apt-dpkg-install-OLhLxc/1012-ros-noetic-gazebo-ros_2.9.1-1focal.20200529.070139_amd64.deb (--unpack):
 cannot copy extracted data for './opt/ros/noetic/include/gazebo_ros/PhysicsConfig.h' to './opt/ros/noetic/include/gazebo_ros/PhysicsConfig.h.dpkg-new': failed
No apport report written because MaxReports is reached already
dpkg-deb: error: paste subprocess was killed by signal (Broken pipe)
Selecting previously unselected package ros-noetic-gazebo-plugins.
Preparing to unpack .../1013-ros-noetic-gazebo-plugins_2.9.1-1focal.20200529.070922_amd64.deb ...
Unpacking ros-noetic-gazebo-plugins (2.9.1-1focal.20200529.070922) ...
dpkg: error processing archive /tmp/apt-dpkg-install-OLhLxc/1013-ros-noetic-gazebo-plugins_2.9.1-1focal.20200529.070922_amd64.deb (--unpack):
 cannot copy extracted data for './opt/ros/noetic/include/gazebo_plugins/CameraSynchronizerConfig.h' to './opt/ros/noetic/include/gazebo_plugins/CameraSynchronizerConfig.h.dpkg-new': failed
No apport report written because MaxReports is reached already
dpkg-deb: error: paste subprocess was killed by signal (Broken pipe)
dpkg: unrecoverable fatal error, aborting:
 unable to flush /var/lib/dpkg/updates/tmp.l after padding: No space left on device
E: Sub-process /usr/bin/dpkg returned an error code (2)
rayyan@Rayyan:~$
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rayyan@Rayyan:~$ rosversion -d
noetic
rayyan@Rayyan:~$
```