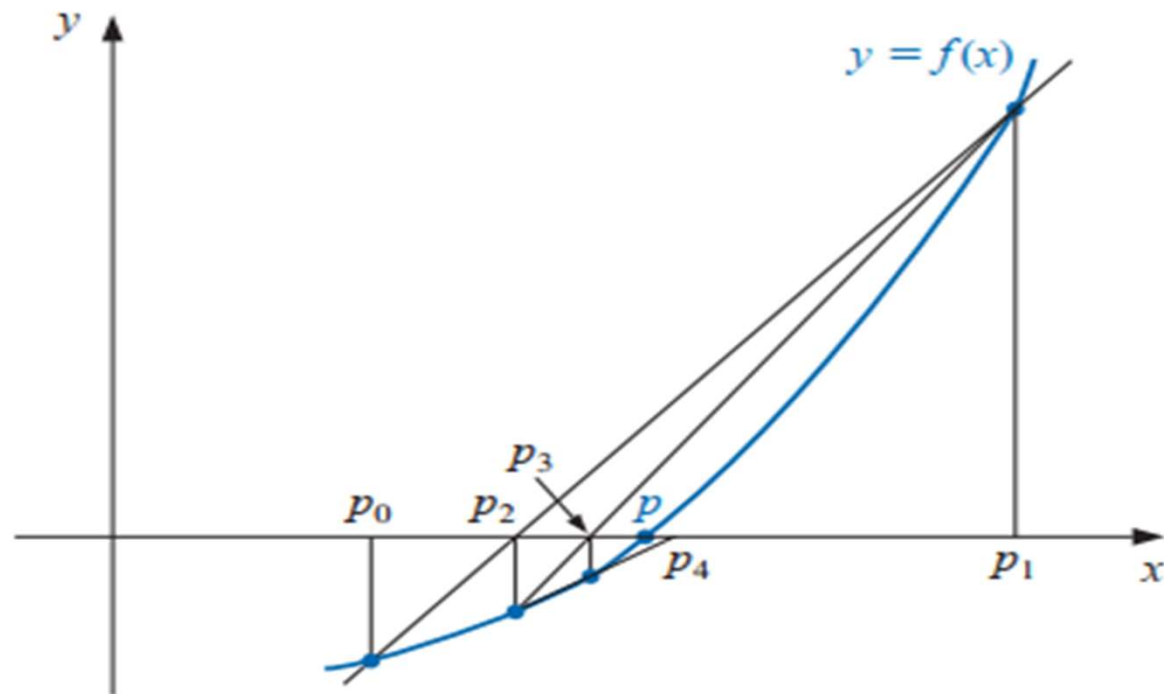


# Lecture # 07 & 08

## Secant & False Position Methods (Regula Falsi or Linear Interpolation Method)

# Secant Method:



# Secant Method:

To find a solution to  $f(x) = 0$  given initial approximations  $p_0$  and  $p_1$ :

INPUT initial approximations  $p_0, p_1$ ; tolerance  $TOL$ ; maximum number of iterations  $N_0$ .

OUTPUT approximate solution  $p$  or message of failure.

Step 1 Set  $i = 2$ ;

$$q_0 = f(p_0);$$

$$q_1 = f(p_1).$$

Step 2 While  $i \leq N_0$  do Steps 3–6.

Step 3 Set  $p = p_1 - q_1(p_1 - p_0)/(q_1 - q_0)$ . (Compute  $p_i$ .)

Step 4 If  $|p - p_1| < TOL$  then

OUTPUT ( $p$ ); (The procedure was successful.)

STOP.

Step 5 Set  $i = i + 1$ .

Step 6 Set  $p_0 = p_1$ ; (Update  $p_0, q_0, p_1, q_1$ .)

$$q_0 = q_1;$$

$$p_1 = p;$$

$$q_1 = f(p).$$

Step 7 OUTPUT ('The method failed after  $N_0$  iterations,  $N_0 =$ ',  $N_0$ );

(The procedure was unsuccessful.)

STOP.

$$p_n = p_{n-1} - \frac{f(p_{n-1})(p_{n-1} - p_{n-2})}{f(p_{n-1}) - f(p_{n-2})}.$$

$$x_{i+1} = x_i - \frac{f(x_i)(x_{i-1} - x_i)}{f(x_{i-1}) - f(x_i)}$$



**Problem Statement.** Use the **secant** method to estimate the root of  $f(x) = e^{-x} - x$ . Start with initial estimates of  $x_{-1} = 0$  and  $x_0 = 1.0$ .

**Solution.** Recall that the true root is 0.56714329. . . .

$$x_{i+1} = x_i - \frac{f(x_i)(x_{i-1} - x_i)}{f(x_{i-1}) - f(x_i)}$$



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$$x_{i+1} = x_i - \frac{f(x_i)(x_{i-1} - x_i)}{f(x_{i-1}) - f(x_i)}$$

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First iteration:

$$x_{-1} = 0 \quad f(x_{-1}) = 1.00000$$

$$x_0 = 1 \quad f(x_0) = -0.63212$$

$$x_1 = 1 - \frac{-0.63212(0 - 1)}{1 - (-0.63212)} = 0.61270 \quad \varepsilon_t = 8.0\%$$

Second iteration:

$$x_0 = 1 \quad f(x_0) = -0.63212$$

$$x_1 = 0.61270 \quad f(x_1) = -0.07081$$

(Note that both estimates are now on the same side of the root.)

$$x_2 = 0.61270 - \frac{-0.07081(1 - 0.61270)}{-0.63212 - (-0.07081)} = 0.56384 \quad \varepsilon_t = 0.58\%$$

Third iteration:

$$x_1 = 0.61270 \quad f(x_1) = -0.07081$$

$$x_2 = 0.56384 \quad f(x_2) = 0.00518$$

$$x_3 = 0.56384 - \frac{0.00518(0.61270 - 0.56384)}{-0.07081 - (-0.00518)} = 0.56717 \quad \varepsilon_t = 0.0048\%$$

Use the Secant method to find a solution to  $x = \cos x$ , and compare the approximations with those given in Example 1 which applied Newton's method.

$n$	$p_n$	<b>Newton</b>	
$n$	$p_n$	$n$	$p_n$
0	0.7853981635	0	0.7853981635
1	0.7071067810	1	0.7395361337
2	0.7602445972	2	0.7390851781
3	0.7246674808	3	0.7390851332
4	0.7487198858	4	0.7390851332
5	0.7325608446		
6	0.7434642113		
7	0.7361282565		

Use the Secant method to find a solution to  $x = \cos x$ , and compare the approximations with those given in Example 1 which applied Newton's method.

$$x_{i+1} = x_i - \frac{f(x_i)(x_{i-1} - x_i)}{f(x_{i-1}) - f(x_i)}$$



Use the Secant method to find a solution to  $x = \cos x$ , and compare the approximations with those given in Example 1 which applied Newton's method.

$n$	$p_n$
0	0.7853981635
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4	0.7487198858
5	0.7325608446
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7	0.7361282565

Newton	
$n$	$p_n$
0	0.7853981635
1	0.7395361337
2	0.7390851781
3	0.7390851332
4	0.7390851332

Secant	
$n$	$p_n$
0	0.5
1	0.7853981635
2	0.7363841388
3	0.7390581392
4	0.7390851493
5	0.7390851332

# Root Finding Methods:

- *Bracketing methods.* As the name implies, these are based on two initial guesses that “bracket” the root—that is, are on either side of the root.
- *Open methods.* These methods can involve one or more initial guesses, but there is no need for them to bracket the root.

## False Position Method:

The **method of False Position** (also called *Regula Falsi*) generates approximations in the same manner as the Secant method, but it includes a test to ensure that the root is always bracketed between successive iterations

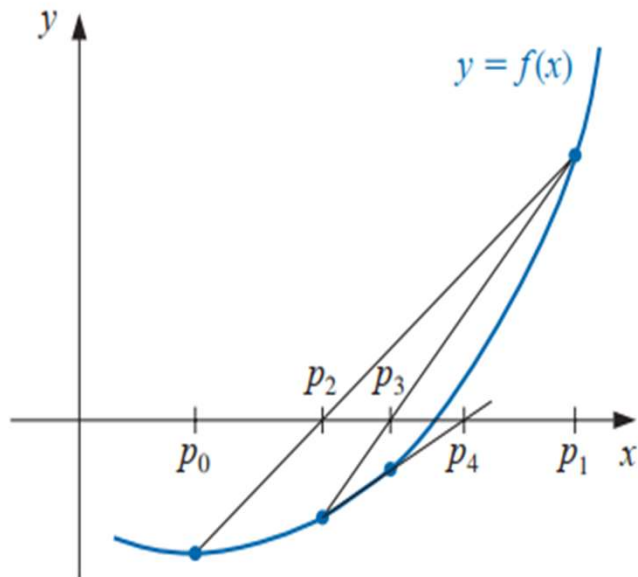
The term *Regula Falsi*, literally a false rule or false position, refers to a technique that uses results that are known to be false, but in some specific manner, to obtain convergence to a true result. False position problems can be found on the Rhind papyrus, which dates from about 1650 B.C.E.

## Working/Iteration Rule:

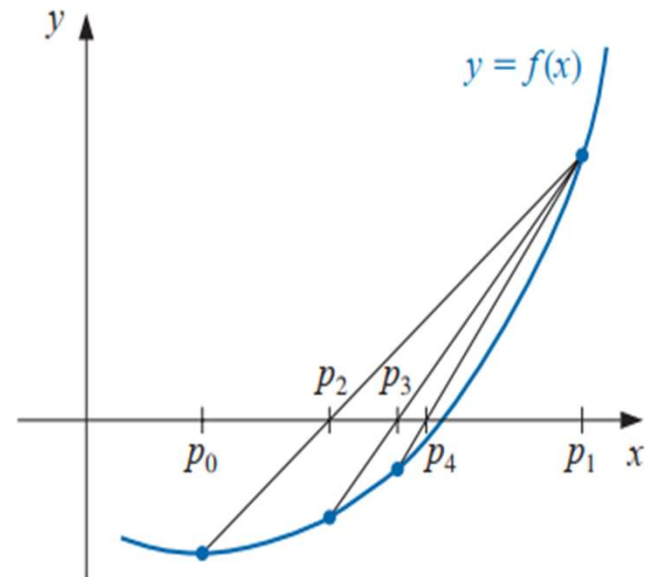
First choose initial approximations  $p_0$  and  $p_1$  with  $f(p_0) \cdot f(p_1) < 0$ . The approximation  $p_2$  is chosen in the same manner as in the Secant method, as the  $x$ -intercept of the line joining  $(p_0, f(p_0))$  and  $(p_1, f(p_1))$ . To decide which secant line to use to compute  $p_3$ , consider  $f(p_2) \cdot f(p_1)$ , or more correctly  $\text{sgn } f(p_2) \cdot \text{sgn } f(p_1)$ .

- If  $\text{sgn } f(p_2) \cdot \text{sgn } f(p_1) < 0$ , then  $p_1$  and  $p_2$  bracket a root. Choose  $p_3$  as the  $x$ -intercept of the line joining  $(p_1, f(p_1))$  and  $(p_2, f(p_2))$ .
- If not, choose  $p_3$  as the  $x$ -intercept of the line joining  $(p_0, f(p_0))$  and  $(p_2, f(p_2))$ , and then interchange the indices on  $p_0$  and  $p_1$ .

Secant Method



Method of False Position





## Algorithm:

To find a solution to  $f(x) = 0$  given the continuous function  $f$  on the interval  $[p_0, p_1]$  where  $f(p_0)$  and  $f(p_1)$  have opposite signs:

**INPUT** initial approximations  $p_0, p_1$ ; tolerance  $TOL$ ; maximum number of iterations  $N_0$ .

**OUTPUT** approximate solution  $p$  or message of failure.

**Step 1** Set  $i = 2$ ;

$$q_0 = f(p_0);$$

$$q_1 = f(p_1).$$

**Step 2** While  $i \leq N_0$  do Steps 3–7.

**Step 3** Set  $p = p_1 - q_1(p_1 - p_0)/(q_1 - q_0)$ . (Compute  $p_i$ .)

**Step 4** If  $|p - p_1| < TOL$  then

OUTPUT ( $p$ ); (The procedure was successful.)

STOP.

**Step 5** Set  $i = i + 1$ ;

$$q = f(p).$$

**Step 6** If  $q \cdot q_1 < 0$  then set  $p_0 = p_1$ ;

$$q_0 = q.$$

**Step 7** Set  $p_1 = p$ ;

$$q_1 = q.$$

**Step 8** OUTPUT ('Method failed after  $N_0$  iterations,  $N_0 =$ ',  $N_0$ );

(The procedure unsuccessful.)

STOP.



## Example: Find the solution $x = \cos x$

**Solution** To make a reasonable comparison we will use the same initial approximations as in the Secant method, that is,  $p_0 = 0.5$  and  $p_1 = \pi/4$ . Table 2.6 shows the results of the method of False Position applied to  $f(x) = \cos x - x$  together with those we obtained using the Secant and Newton's methods. Notice that the False Position and Secant approximations agree through  $p_3$  and that the method of False Position requires an additional iteration to obtain the same accuracy as the Secant method. ■

	False Position	Secant	Newton
$n$	$p_n$	$p_n$	$p_n$
0	0.5	0.5	0.7853981635
1	0.7853981635	0.7853981635	0.7395361337
2	0.7363841388	0.7363841388	0.7390851781
3	0.7390581392	0.7390581392	0.7390851332
4	0.7390848638	0.7390851493	0.7390851332
5	0.7390851305	0.7390851332	
6	0.7390851332		

## Example:

Consider finding the root of  $f(x) = x^2 - 3$ . Let  $\varepsilon = 0.01$ , and start with the interval  $[1, 2]$ .



## Example:

Consider finding the root of  $f(x) = x^2 - 3$ . Let  $\varepsilon = 0.01$ , and start with the interval  $[1, 2]$ .

$a$	$b$	$f(a)$	$f(b)$	$c$	$f(c)$	Update	Step Size
1.0	2.0	-2.00	1.00	1.6667	-0.2221	$a = c$	0.6667
1.6667	2.0	-0.2221	1.0	1.7273	-0.0164	$a = c$	0.0606
1.7273	2.0	-0.0164	1.0	1.7317	0.0012	$a = c$	0.0044

**Solve:**

$x^3 - 2x - 5 = 0$ , by using regula falsi method ( $\varepsilon = 0.0001$ )

Root = 2.094547



**Sol:**

Step	x0	x1	x2	f (x2)
1	2.000000	3.000000	2.058824	-0.390800
2	2.058824	3.000000	2.081264	-0.147204
3	2.081264	3.000000	2.089639	-0.054677
4	2.089639	3.000000	2.092740	-0.020203
5	2.092740	3.000000	2.093884	-0.007451
6	2.093884	3.000000	2.094305	-0.002746
7	2.094305	3.000000	2.094461	-0.001012
8	2.094461	3.000000	2.094518	-0.000373
9	2.094518	3.000000	2.094539	-0.000137
10	2.094539	3.000000	2.094547	-0.000051

**Do Q 1-10 from Ex # 2.3**