

# Lecture 9

## 3.2 PUSHDOWN AUTOMATA (PA)

3.2.1 PA Model

3.2.2 PA Definition

3.2.3 PA and Context-Free Grammar

# Lecture 9

## 3.2 PUSHDOWN AUTOMATA (PA)

3.2.1 PA Model

3.2.2 PA Definition

3.2.3 PA and Context-Free Grammar

# Pushdown Automata (PA)

# Pushdown Automata (PA)

Finite Automata

# Pushdown Automata (PA)

Finite Automata

*Control unit*

# Pushdown Automata (PA)

Finite Automata

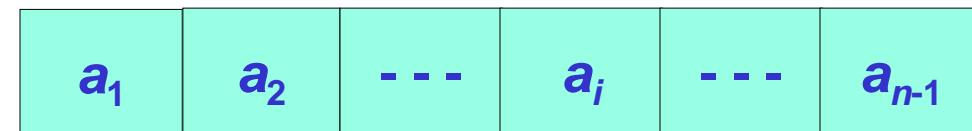
*Control unit*

***State  $q$***

# Pushdown Automata (PA)

## Finite Automata

*Input Tape*

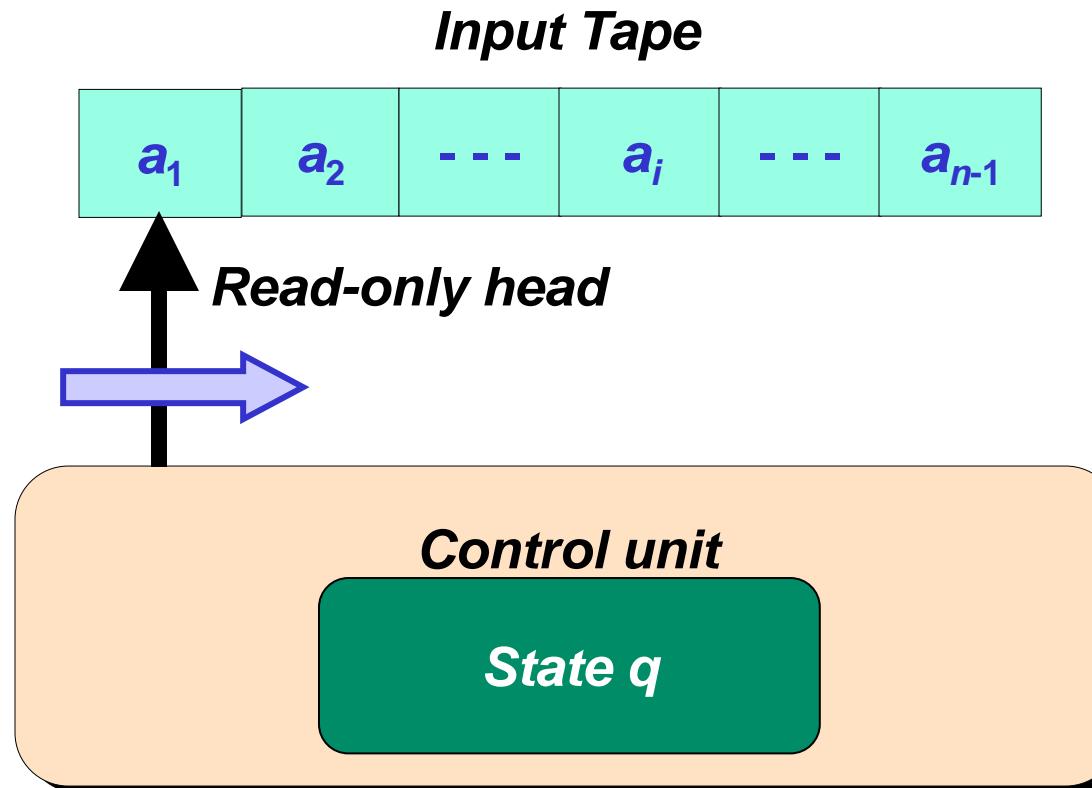


*Control unit*

*State q*

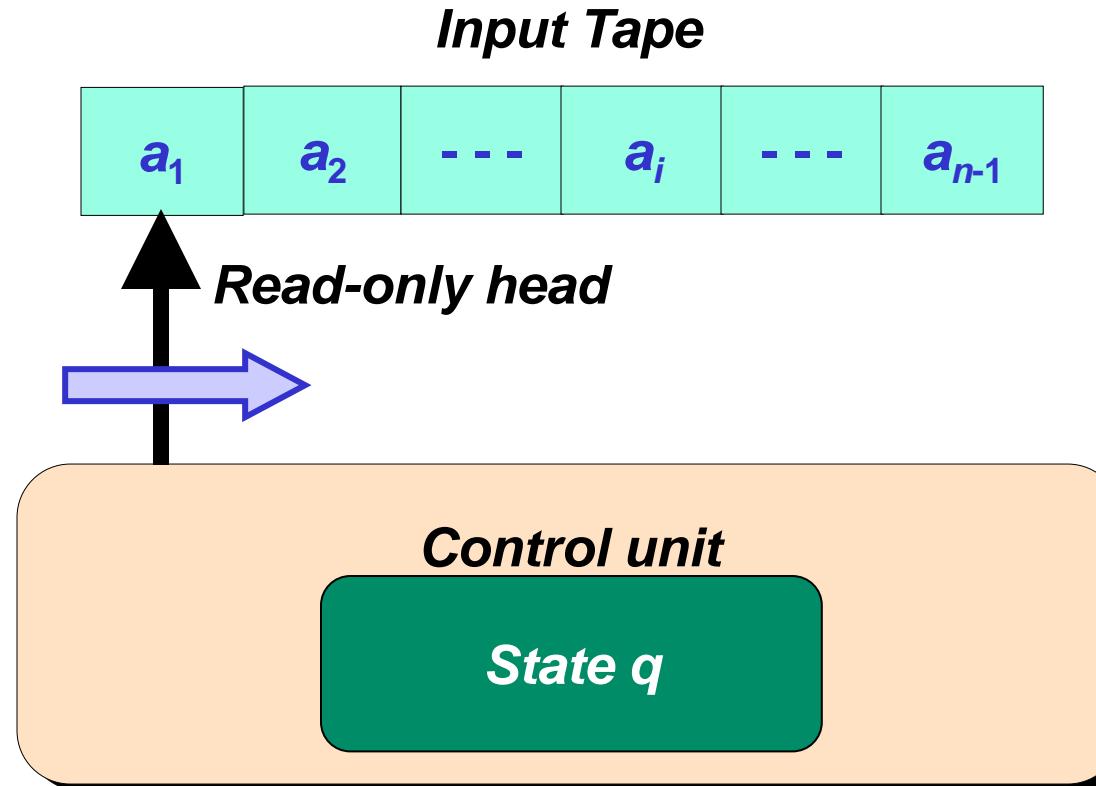
# Pushdown Automata (PA)

## Finite Automata



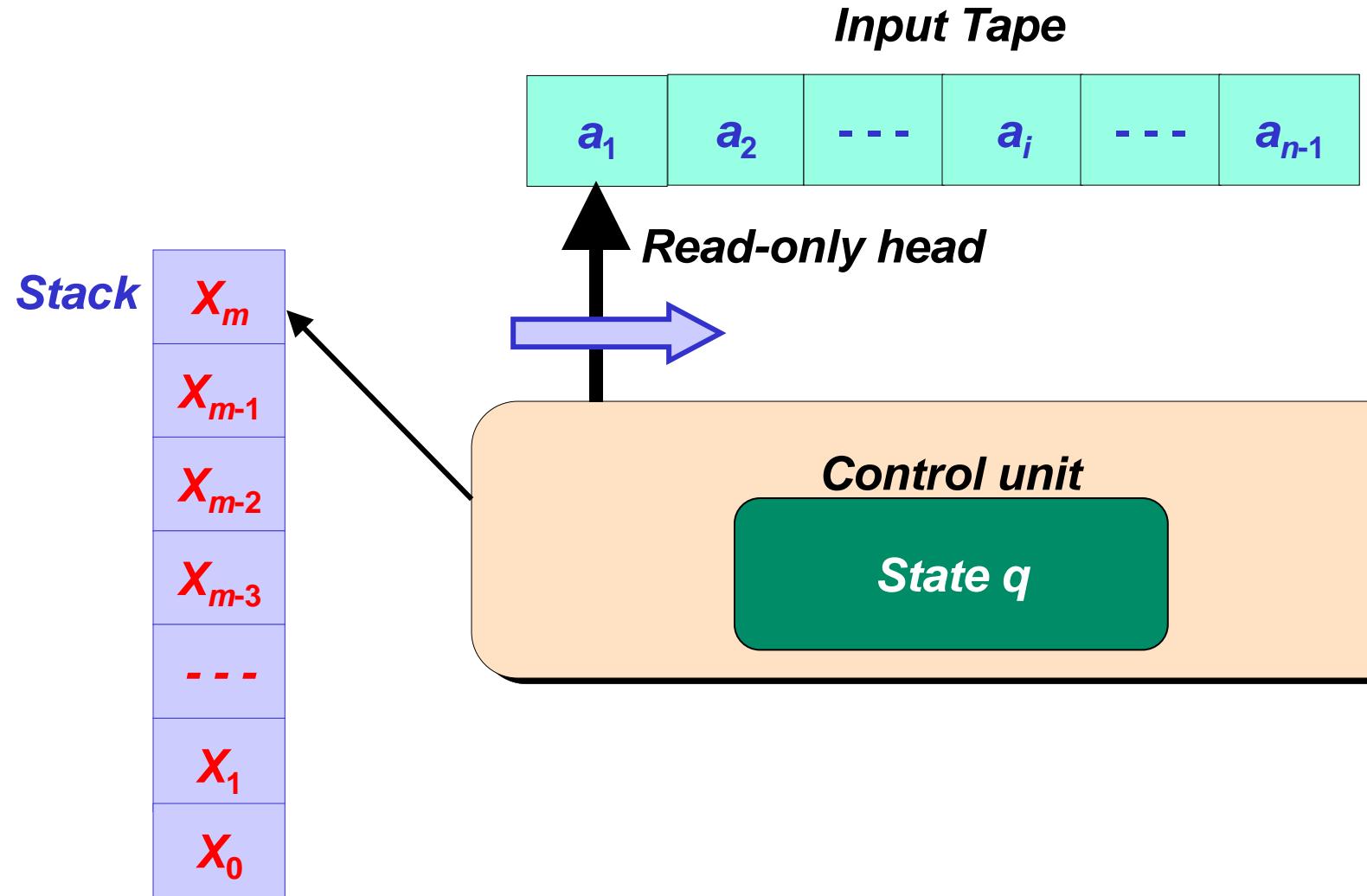
# Pushdown Automata (PA)

## Pushdown automata



# Pushdown Automata (PA)

## Pushdown automata



# Pushdown Automata

# Pushdown Automata

- **Decision**

# Pushdown Automata

- **Decision**
  - Input

# Pushdown Automata

- **Decision**
  - **Input**
    1. **State of control unit**

# Pushdown Automata

- **Decision**
  - **Input**
    1. **State of control unit**
    2. **Symbol read on the input track – *not necessarily***

# Pushdown Automata

- **Decision**
  - **Input**
    1. **State of control unit**
    2. **Symbol read on the input track – *not necessarily***
    3. **Symbol read on the top of the stack**

# Pushdown Automata

- **Decision**
  - **Input**
    1. **State of control unit**
    2. **Symbol read on the input track – *not necessarily***
    3. **Symbol read on the top of the stack**
  - **Output**

# Pushdown Automata

- **Decision**
  - **Input**
    1. **State of control unit**
    2. **Symbol read on the input track – *not necessarily***
    3. **Symbol read on the top of the stack**
  - **Output**
    1. **New state**

# Pushdown Automata

- **Decision**
  - **Input**
    1. State of control unit
    2. Symbol read on the input track – *not necessarily*
    3. Symbol read on the top of the stack
  - **Output**
    1. New state
    2. If symbol is read from the input track – *head moves to the right*

# Pushdown Automata

- **Decision**
  - **Input**
    1. State of control unit
    2. Symbol read on the input track – *not necessarily*
    3. Symbol read on the top of the stack
  - **Output**
    1. New state
    2. If symbol is read from the input track – *head moves to the right*
    3. Writing a new symbol at the top of the stack

# Pushdown Automata

- **Decision**
  - **Input**
    1. State of control unit
    2. Symbol read on the input track – *not necessarily*
    3. Symbol read on the top of the stack
  - **Output**
    1. New state
    2. If symbol is read from the input track – *head moves to the right*
    3. Writing a new symbol at the top of the stack
      - Empty string  $\epsilon$

# Pushdown Automata

- **Decision**
  - **Input**
    1. State of control unit
    2. Symbol read on the input track – *not necessarily*
    3. Symbol read on the top of the stack
  - **Output**
    1. New state
    2. If symbol is read from the input track – *head moves to the right*
    3. Writing a new symbol at the top of the stack
      - Empty string  $\epsilon$
      - String of length 1

# Pushdown Automata

- **Decision**
  - **Input**
    1. State of control unit
    2. Symbol read on the input track – *not necessarily*
    3. Symbol read on the top of the stack
  - **Output**
    1. New state
    2. If symbol is read from the input track – *head moves to the right*
    3. Writing a new symbol at the top of the stack
      - Empty string  $\epsilon$
      - String of length 1
      - String containing multiple symbols

# Pushdown Automata

# Pushdown Automata

- **Two transition types**

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$

# Pushdown Automata

- **Two transition types**
  - **State of the control unit** -  $q$
  - **Input symbol** -  $a$

# Pushdown Automata

- **Two transition types**
  - **State of the control unit** -  $q$
  - **Input symbol** -  $a$
  - **Symbol at the top of the stack** -  $Z$

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$
  - Input symbol -  $a$
  - Symbol at the top of the stack -  $Z$
  - $(q, a, Z) = (p, \gamma)$

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$
  - Input symbol -  $a$
  - Symbol at the top of the stack -  $Z$
- $(q, a, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$
  - Input symbol -  $a$
  - Symbol at the top of the stack -  $Z$
- $(q, a, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$
  - read-only head moves one position to the right

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$
  - Input symbol -  $a$
  - Symbol at the top of the stack -  $Z$
- $(q, a, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$
  - read-only head moves one position to the right
  - top stack symbol is replaced by the string  $\gamma$

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$
  - Input symbol -  $a$
  - Symbol at the top of the stack -  $Z$
- $(q, a, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$
  - read-only head moves one position to the right
  - top stack symbol is replaced by the string  $\gamma$
- $(q, \varepsilon, Z) = (p, \gamma)$

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$
  - Input symbol -  $a$
  - Symbol at the top of the stack -  $Z$
- $(q, a, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$
  - read-only head moves one position to the right
  - top stack symbol is replaced by the string  $\gamma$
- $(q, \varepsilon, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$
  - Input symbol -  $a$
  - Symbol at the top of the stack -  $Z$
- $(q, a, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$
  - read-only head moves one position to the right
  - top stack symbol is replaced by the string  $\gamma$
- $(q, \varepsilon, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$
  - read-only remains at the same position

# Pushdown Automata

- Two transition types
  - State of the control unit -  $q$
  - Input symbol -  $a$
  - Symbol at the top of the stack -  $Z$
- $(q, a, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$
  - read-only head moves one position to the right
  - top stack symbol is replaced by the string  $\gamma$
- $(q, \varepsilon, Z) = (p, \gamma)$ 
  - control unit changes state to new state  $p$
  - read-only remains at the same position
  - top stack symbol is replaced by the string  $\gamma$

# Pushdown Automata

# Pushdown Automata

- **Input string acceptance decision**

# Pushdown Automata

- **Input string acceptance decision**
  - **made in two possible ways**

# Pushdown Automata

- **Input string acceptance decision**
  - **made in two possible ways**
  - **PA  $M$  that accepts by final (accepting) state:**

# Pushdown Automata

- **Input string acceptance decision**
  - **made in two possible ways**
  - **PA  $M$  that accepts by final (accepting) state:**
    - String is accepted if the control unit is in **accepting state** after it reads **all symbols** from the input type.

# Pushdown Automata

- **Input string acceptance decision**
  - **made in two possible ways**
  - **PA  $M$  that accepts by final (accepting) state:**
    - String is accepted if the control unit is in **accepting state** after it reads **all symbols** from the input type.
    - $L(M)$

# Pushdown Automata

- **Input string acceptance decision**
  - **made in two possible ways**
  - **PA  $M$  that accepts by final (accepting) state:**
    - String is accepted if the control unit is in **accepting state** after it reads **all symbols** from the input type.
    - $L(M)$
  - **PA  $M$  that accepts by empty stack:**

# Pushdown Automata

- **Input string acceptance decision**
  - **made in two possible ways**
  - **PA  $M$  that accepts by final (accepting) state:**
    - String is accepted if the control unit is in **accepting state** after it reads **all symbols** from the input type.
    - $L(M)$
  - **PA  $M$  that accepts by empty stack:**
    - String is accepted if the stack remains **empty** after **all symbols** from the input type are read.

# Pushdown Automata

- **Input string acceptance decision**
  - **made in two possible ways**
  - **PA  $M$  that accepts by final (accepting) state:**
    - String is accepted if the control unit is in **accepting state** after it reads **all symbols** from the input type.
    - $L(M)$
  - **PA  $M$  that accepts by empty stack:**
    - String is accepted if the stack remains **empty** after **all symbols** from the input type are read.
    - $N(M)$



$$N(M) = \{ \text{ } (^n a )^n \mid n \geq 1 \}$$

$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
-------------------	--------------	--------------------	------------------	----------------------	-----------------------

$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>	<i>Move to right</i>
1)	$q_0$	( $K$	$q_0$	$A K$		

$$N(M) = \{ (n \text{ } a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>

$$N(M) = \{ (n \text{ } a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>

$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>
4)	$q_1$	) $A$	$q_1$	$\epsilon$	<i>Move to right</i>

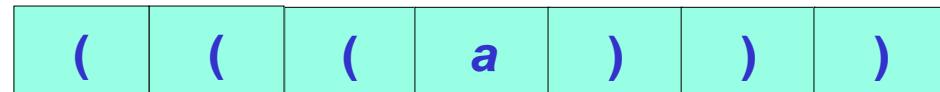
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>
4)	$q_1$	) $A$	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ $K$	$q_1$	$\epsilon$	<i>Remain at position</i>

$$N(M) = \{ (n \text{ } a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>

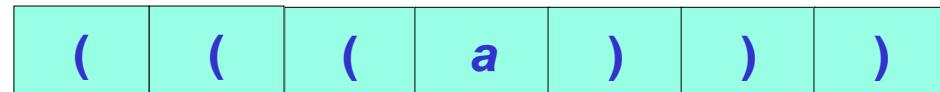
*Input tape*



$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>

*Input tape*



*Stack*



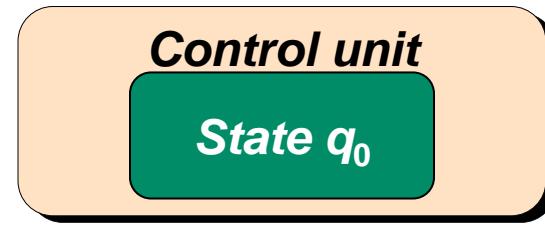
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>

*Input tape*



*Stack* K



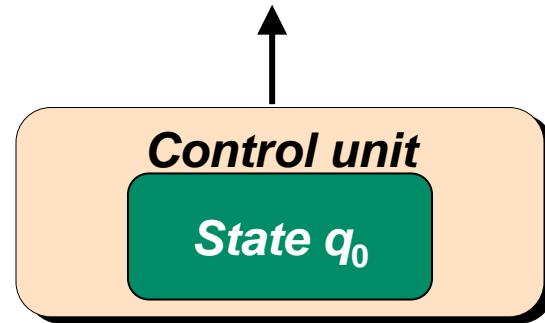
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>

*Input tape*



*Stack* K



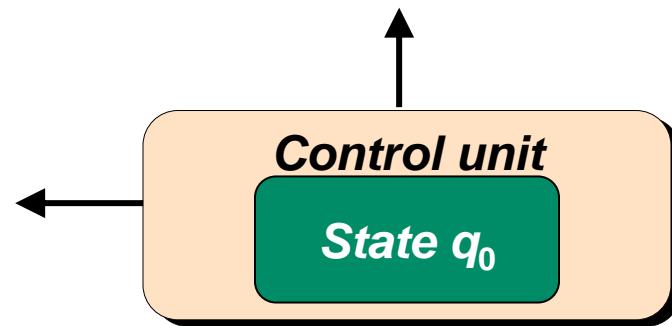
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>

*Input tape*



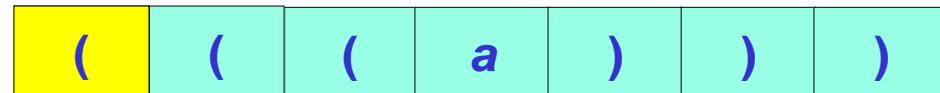
*Stack* K



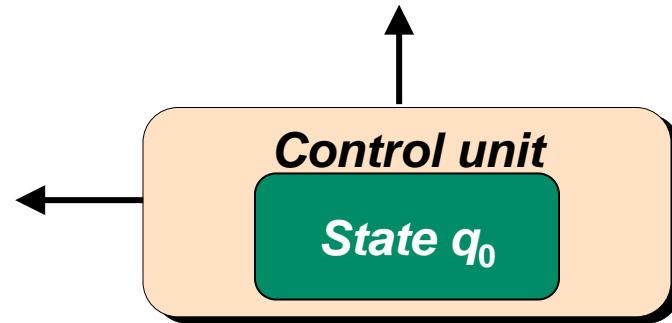
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>

*Input tape*

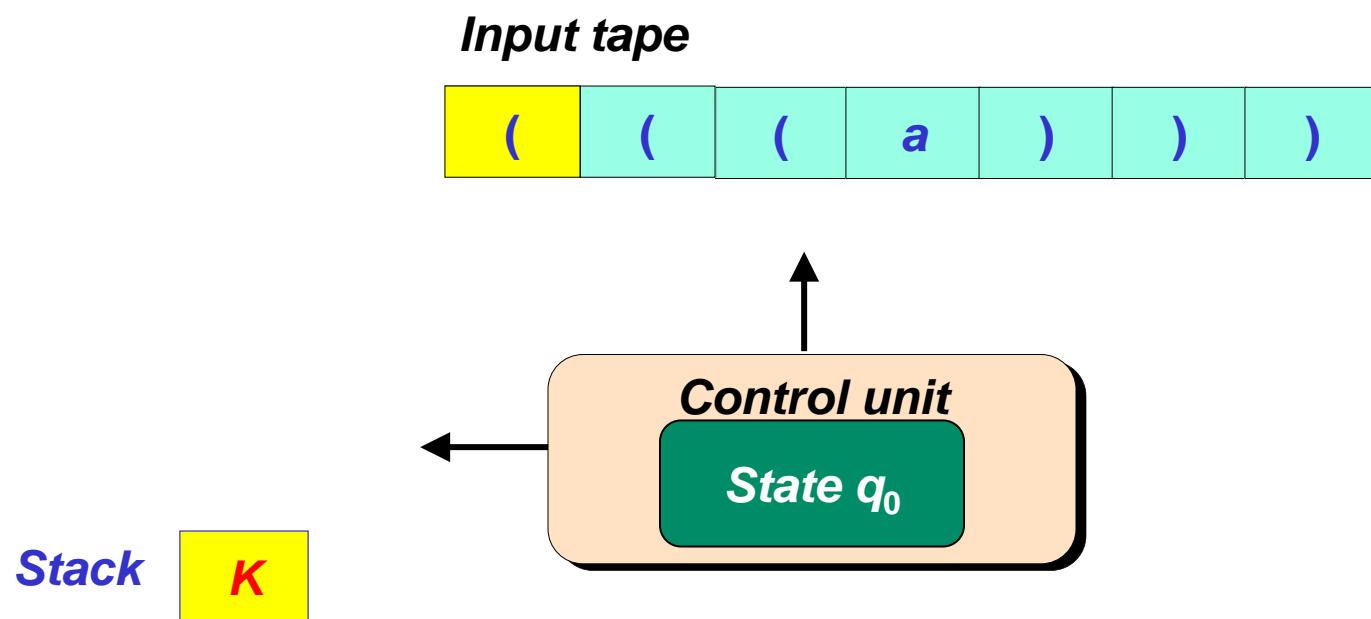


*Stack* K



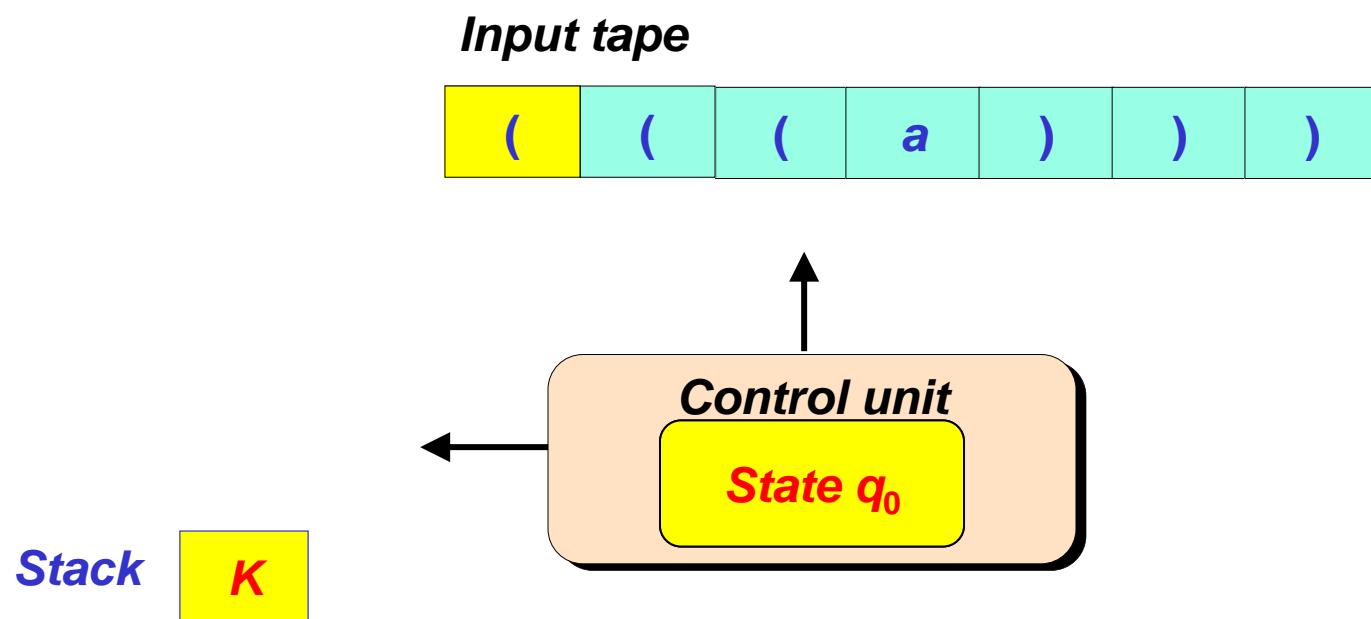
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



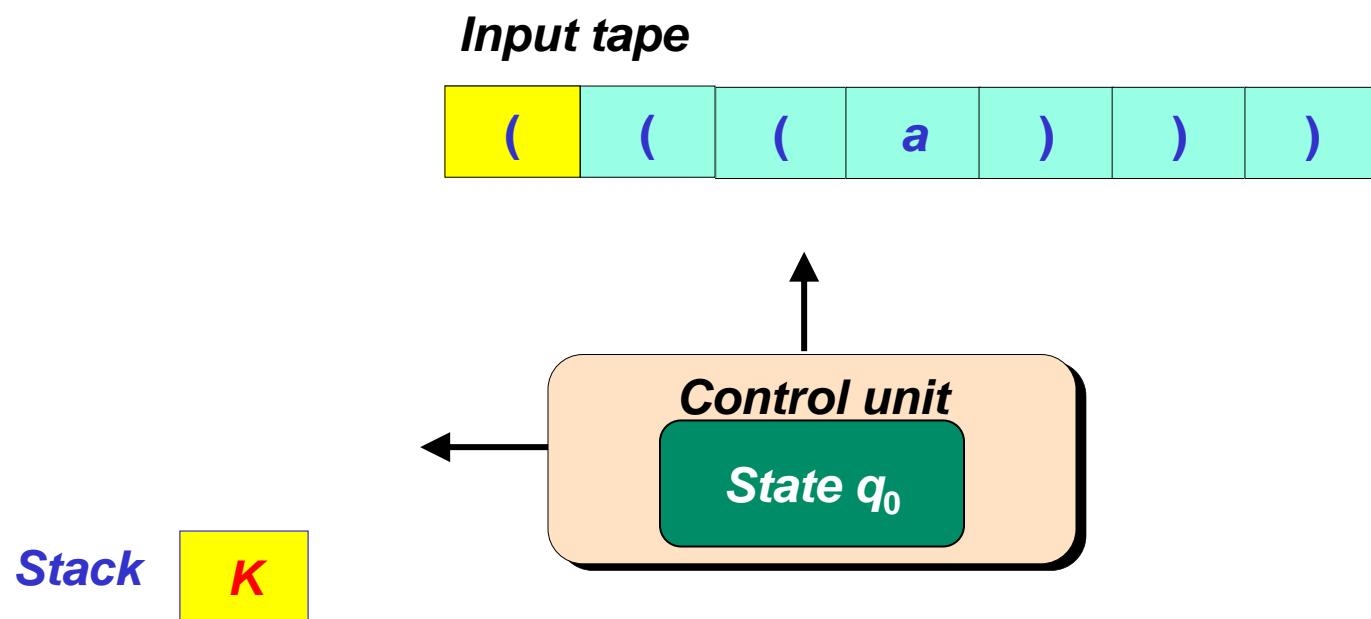
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>
4)	$q_1$	) $A$	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ $K$	$q_1$	$\epsilon$	<i>Remain at position</i>



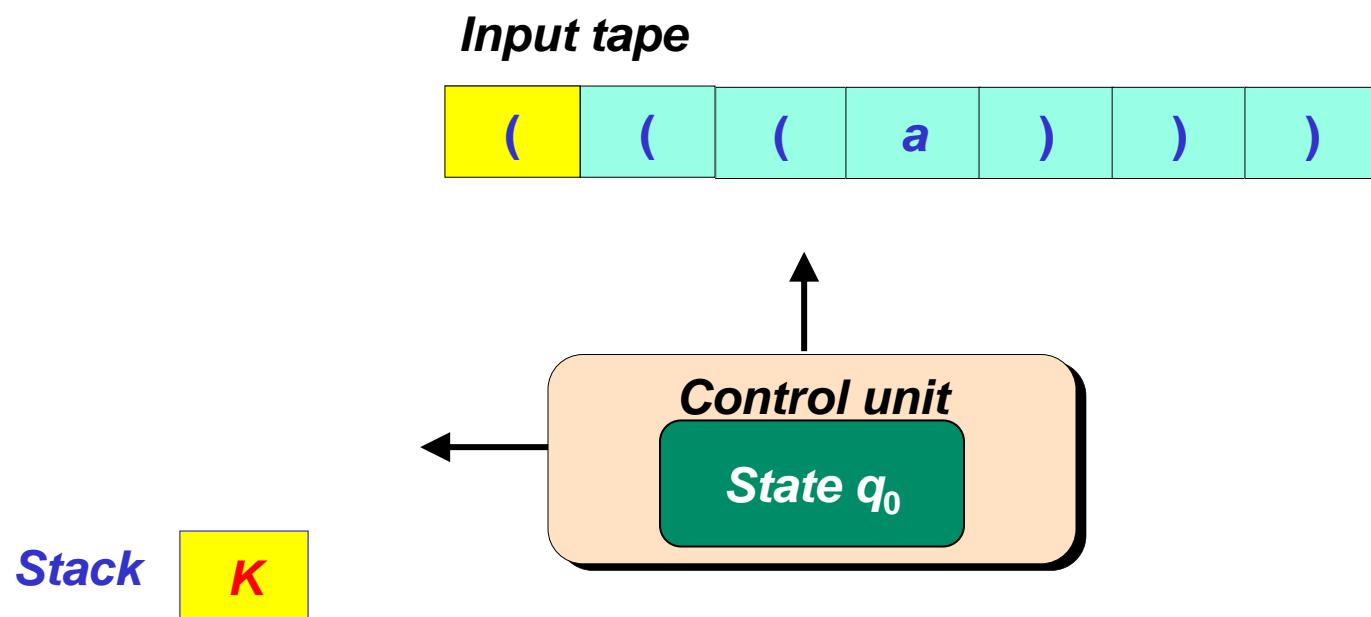
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>
4)	$q_1$	) $A$	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ $K$	$q_1$	$\epsilon$	<i>Remain at position</i>



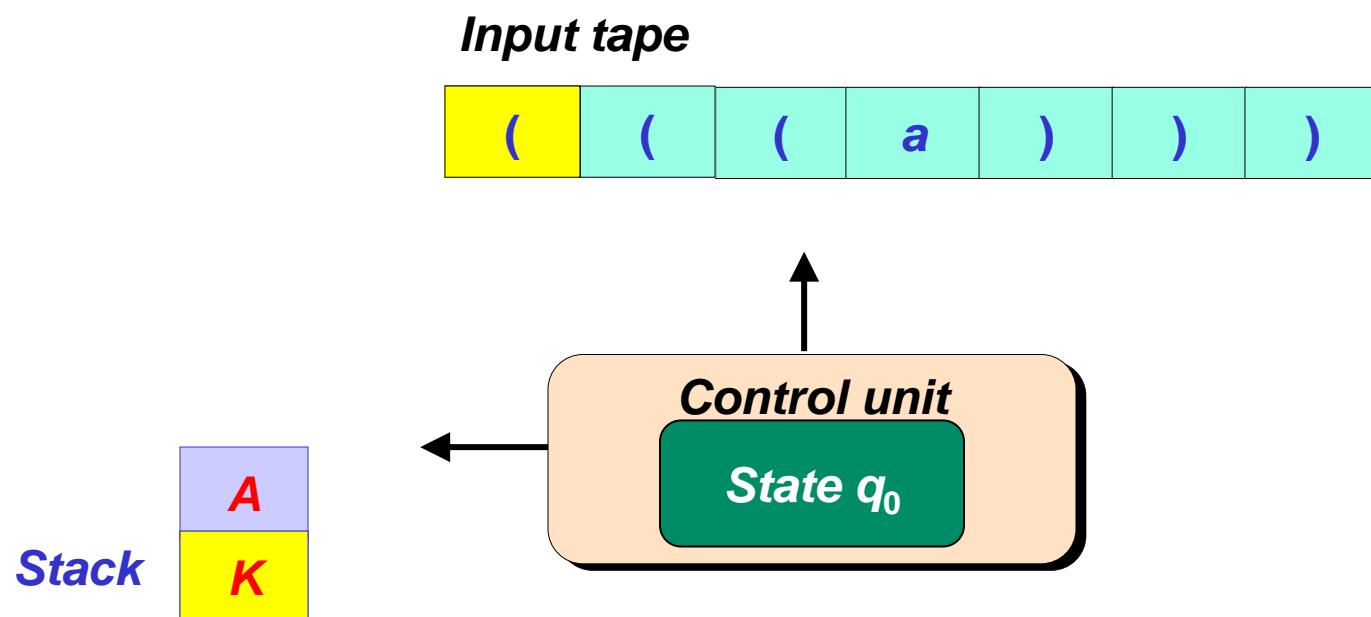
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>
4)	$q_1$	) $A$	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ $K$	$q_1$	$\epsilon$	<i>Remain at position</i>



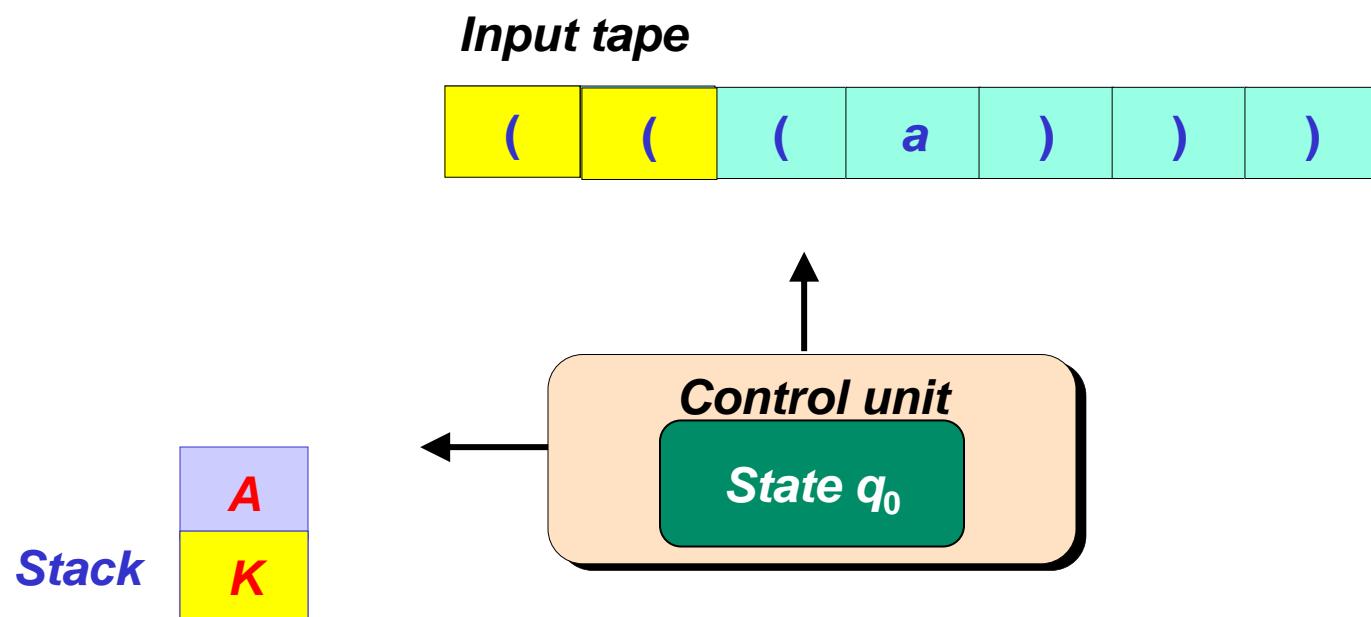
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



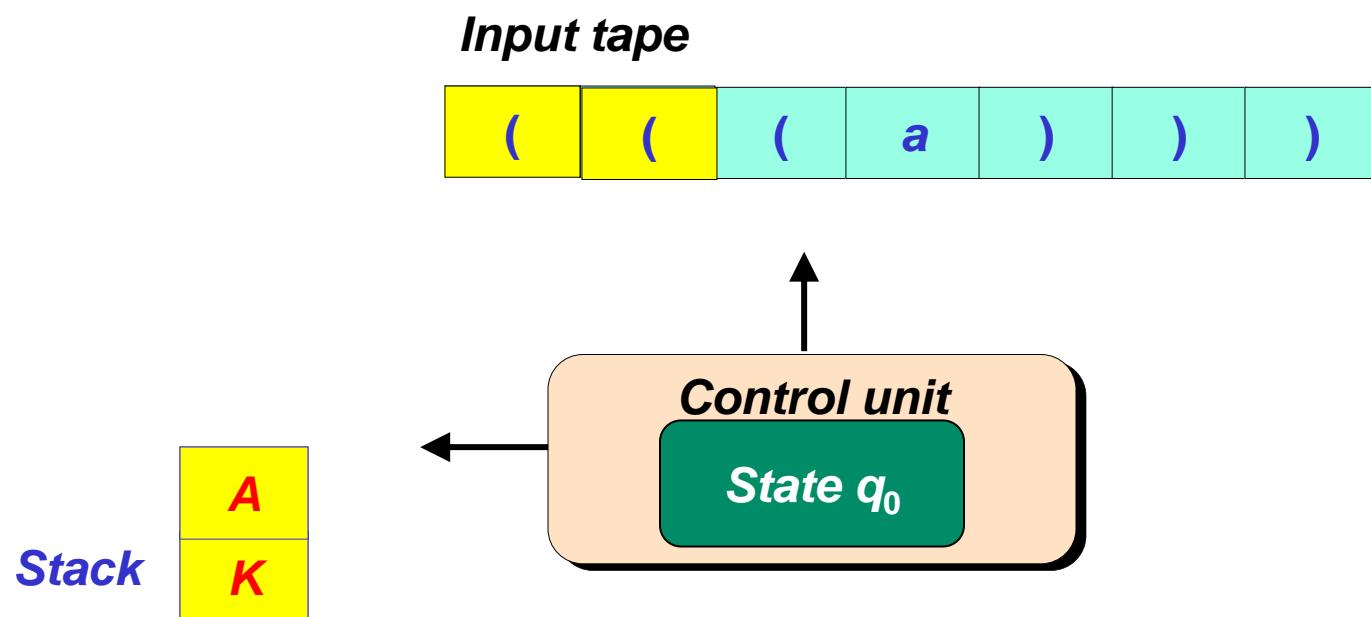
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



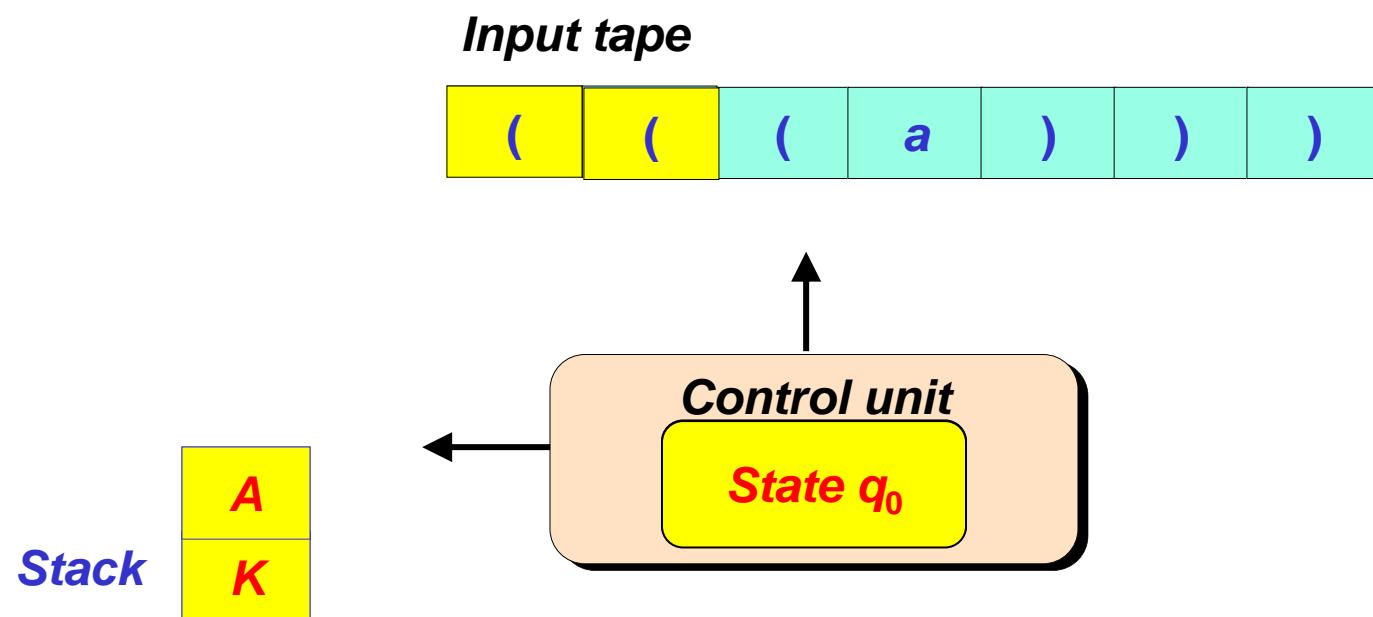
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



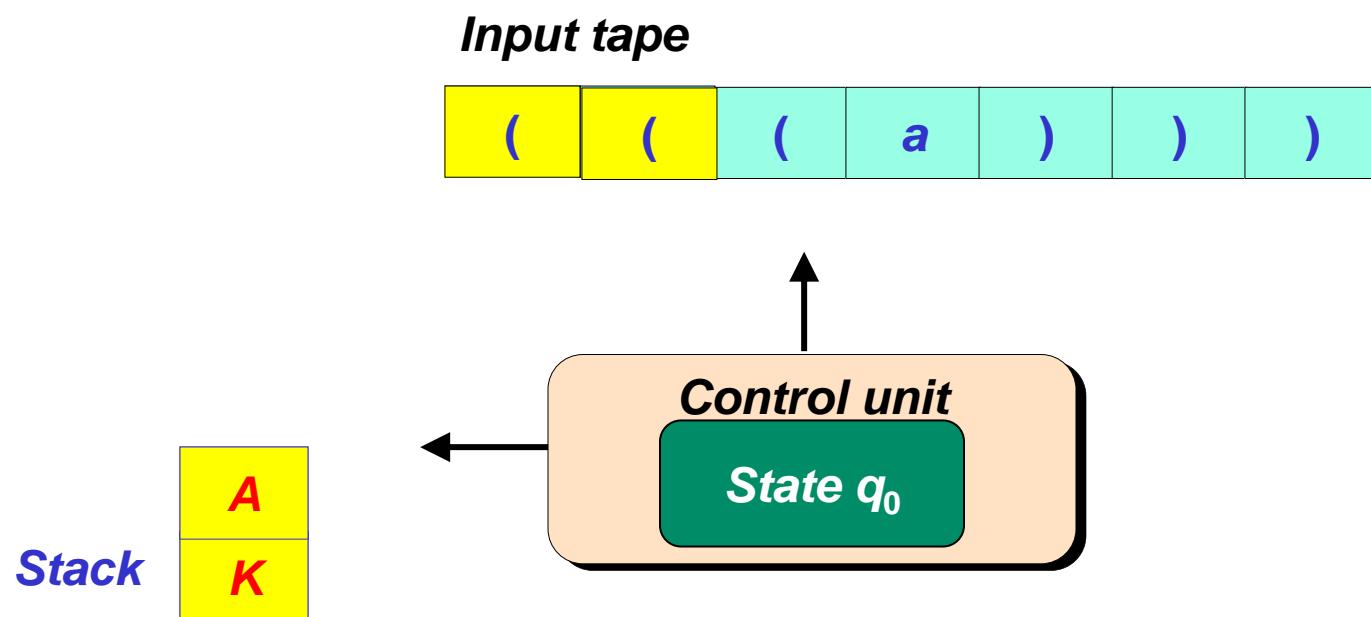
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



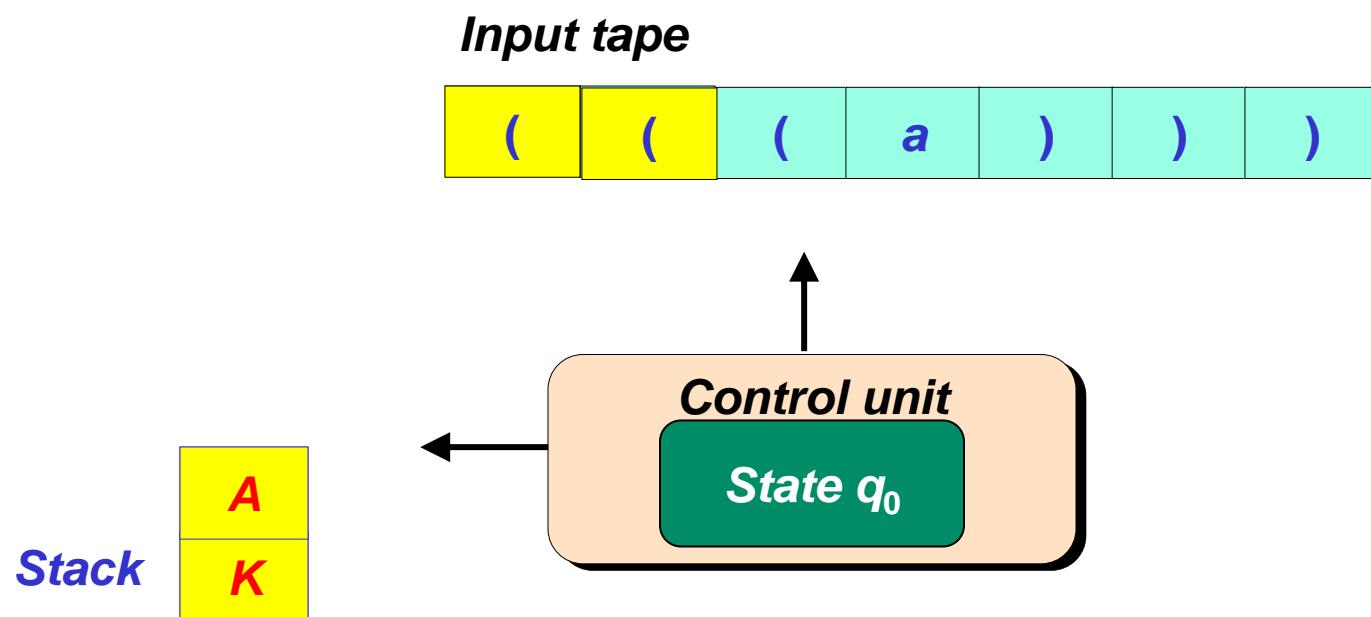
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>
4)	$q_1$	) $A$	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ $K$	$q_1$	$\epsilon$	<i>Remain at position</i>



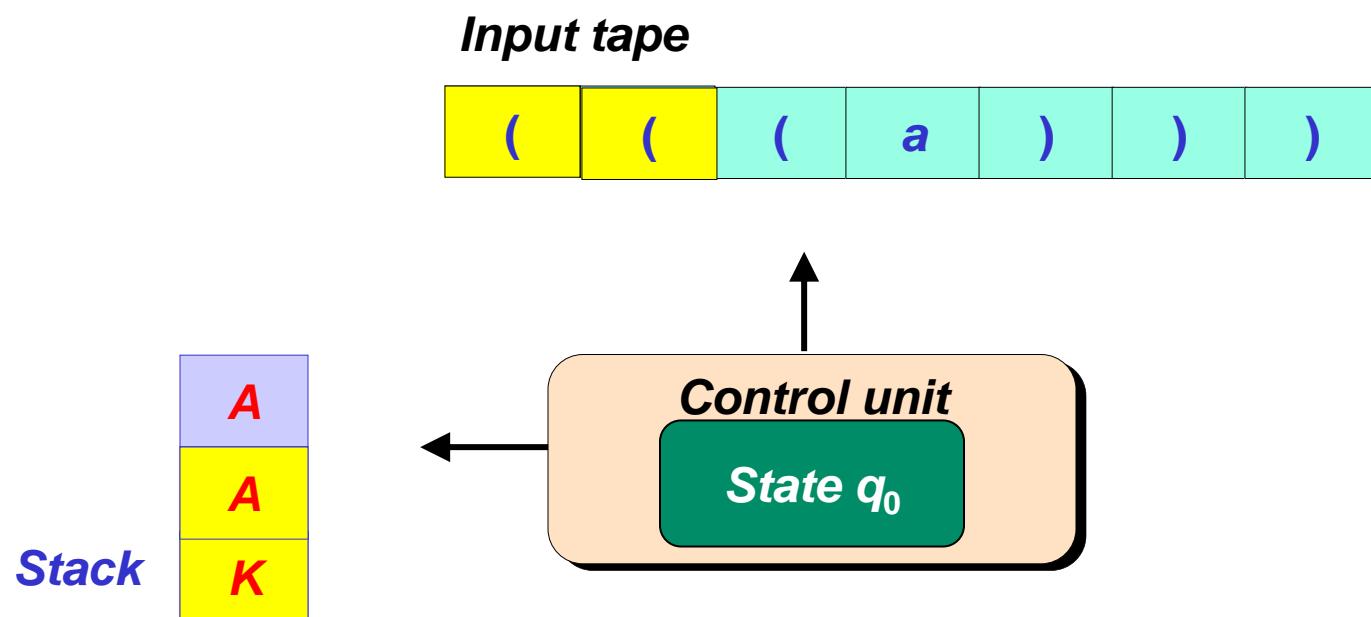
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



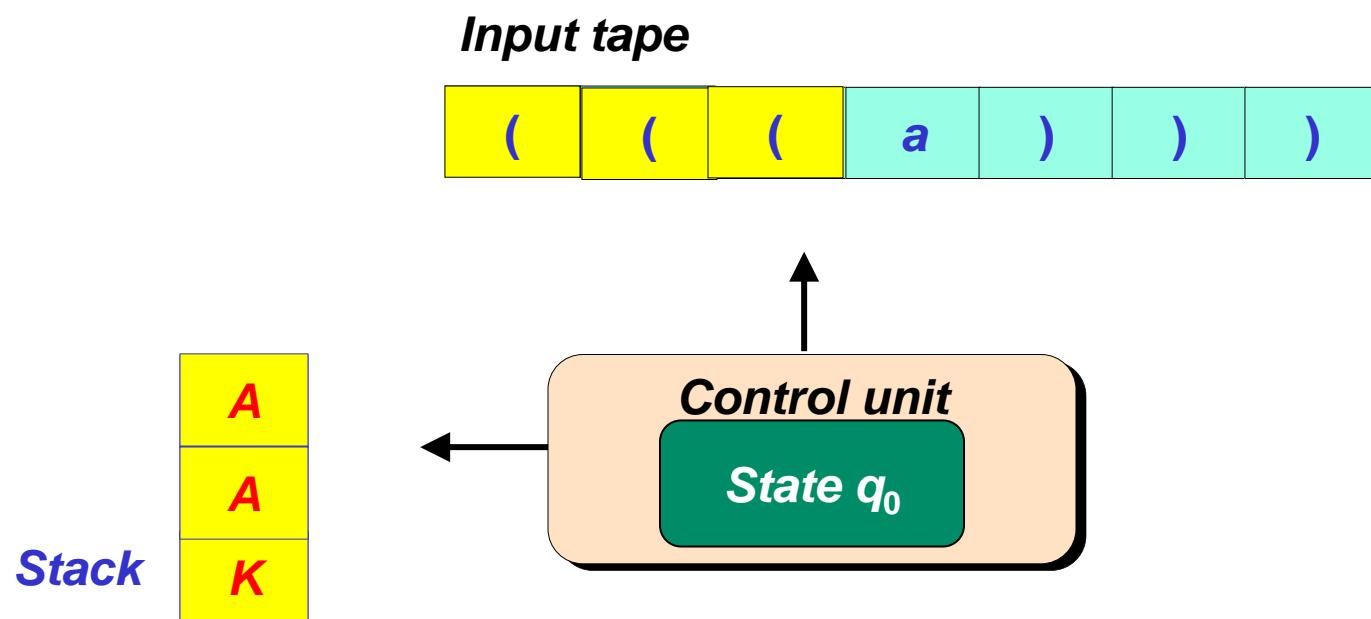
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



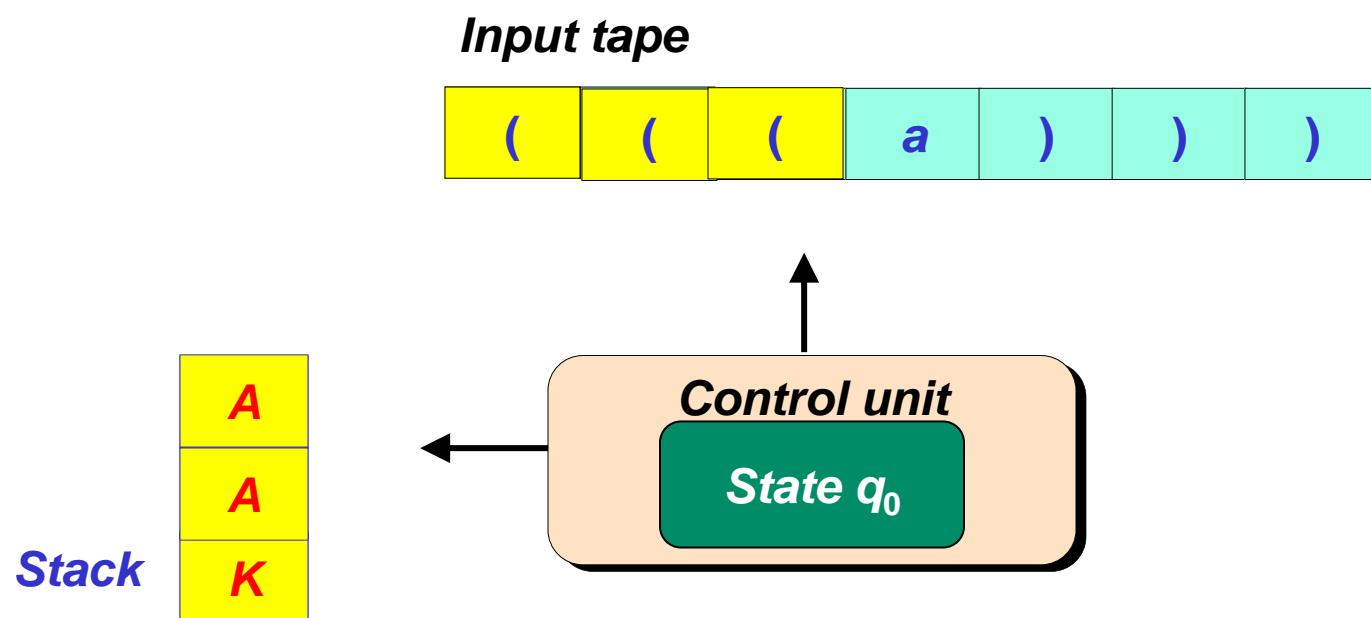
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



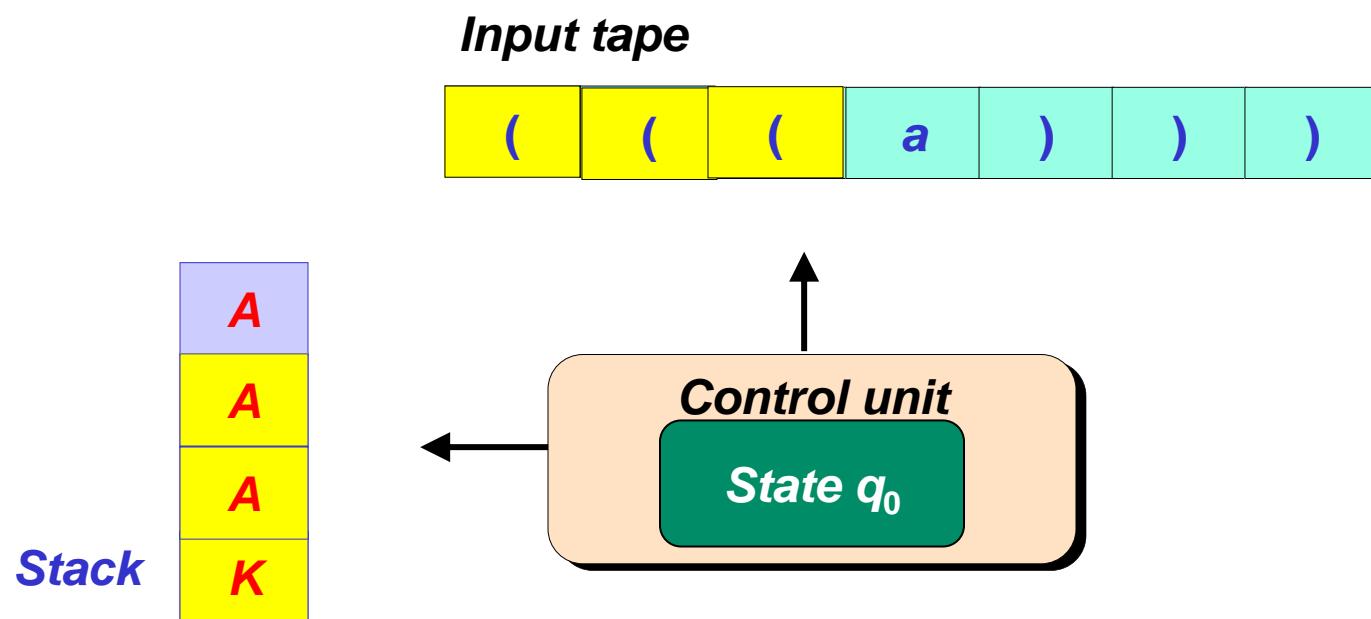
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>
4)	$q_1$	) $A$	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ $K$	$q_1$	$\epsilon$	<i>Remain at position</i>



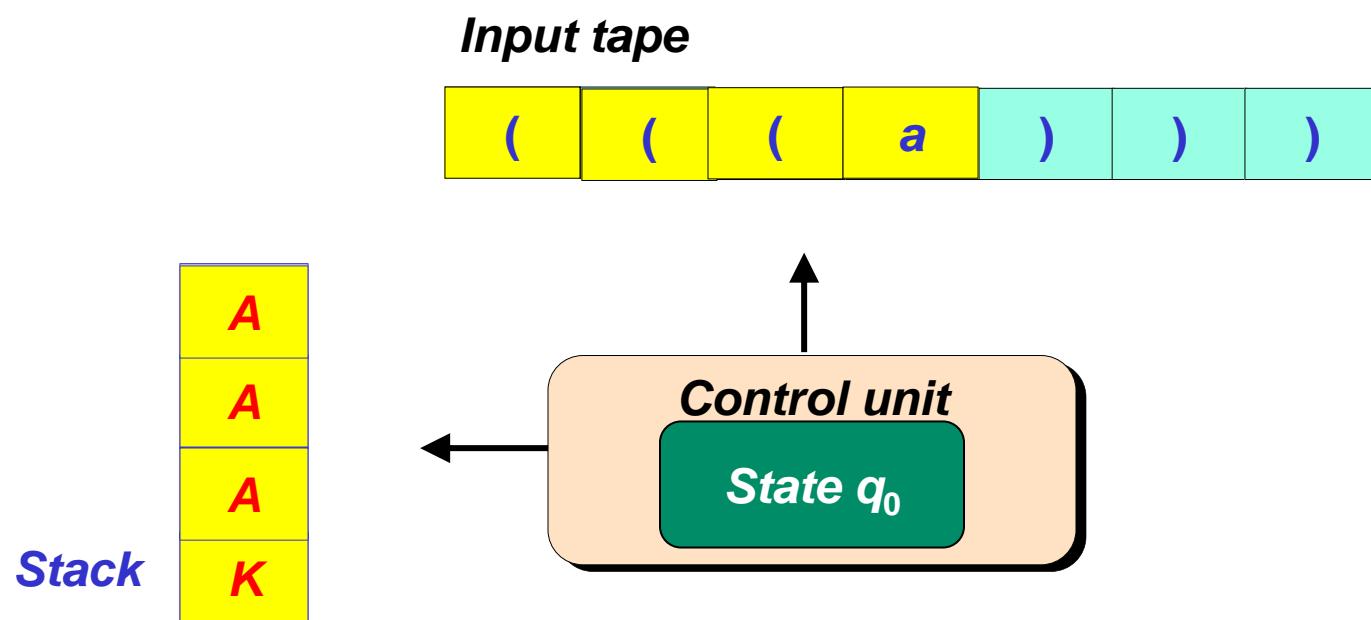
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



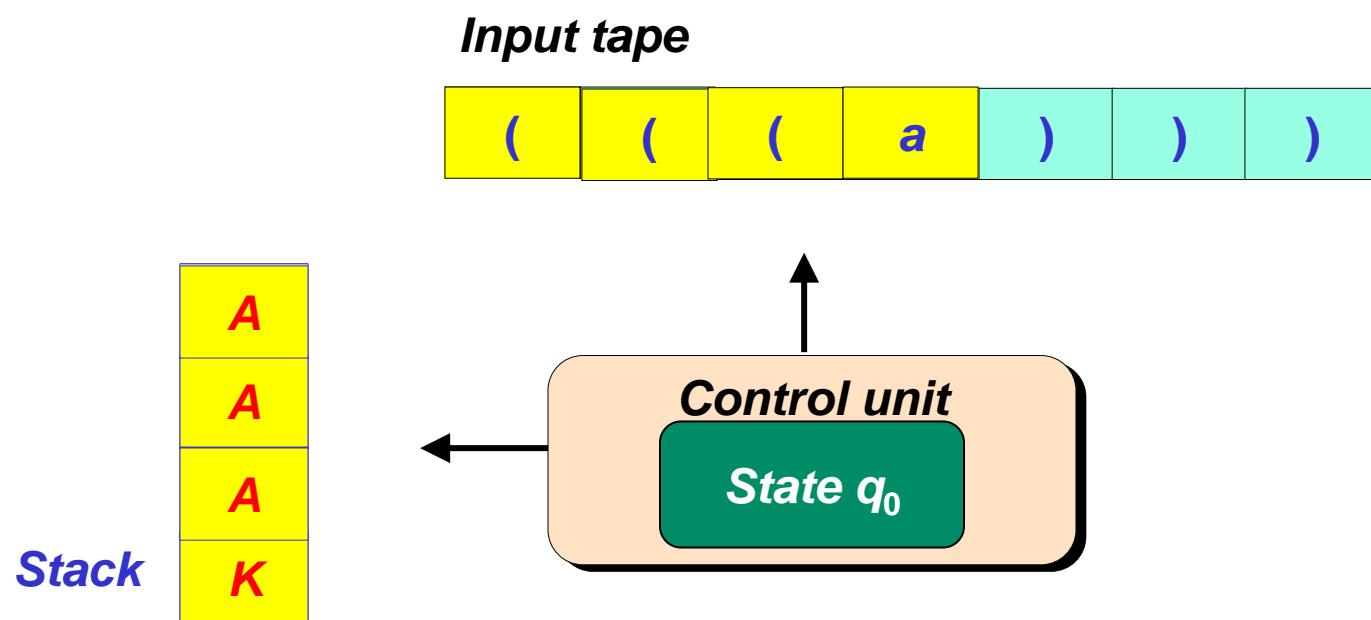
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



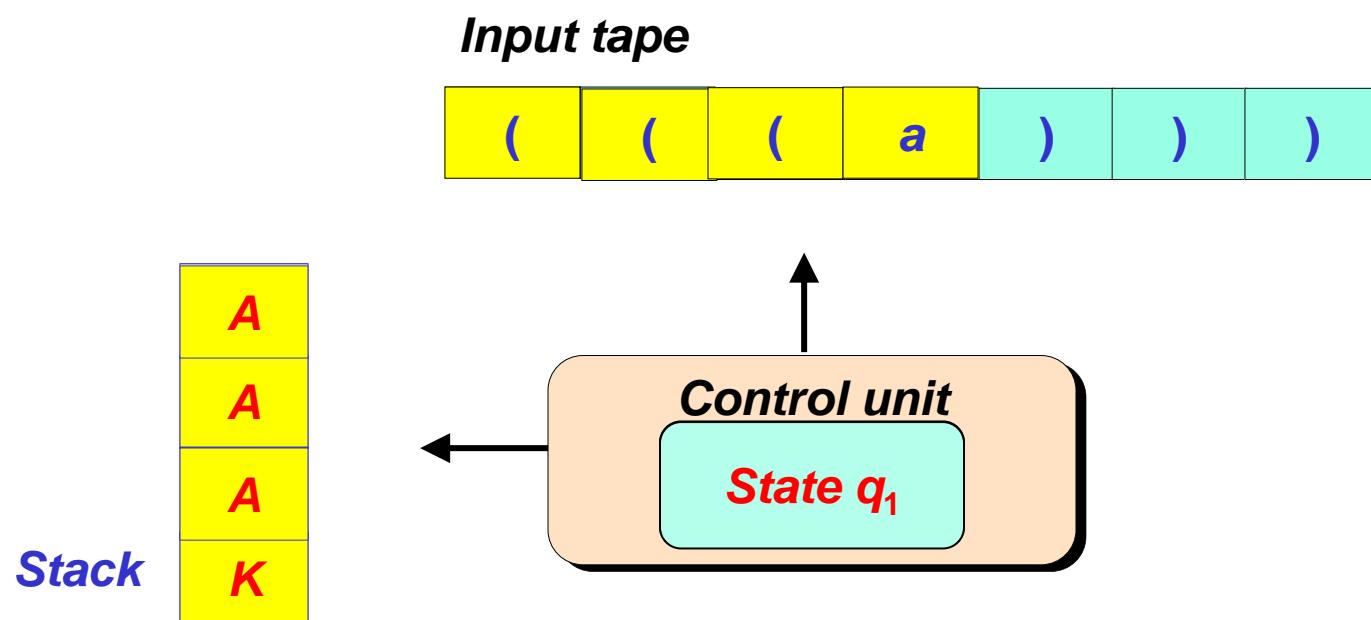
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	<span style="color:red">a</span> <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



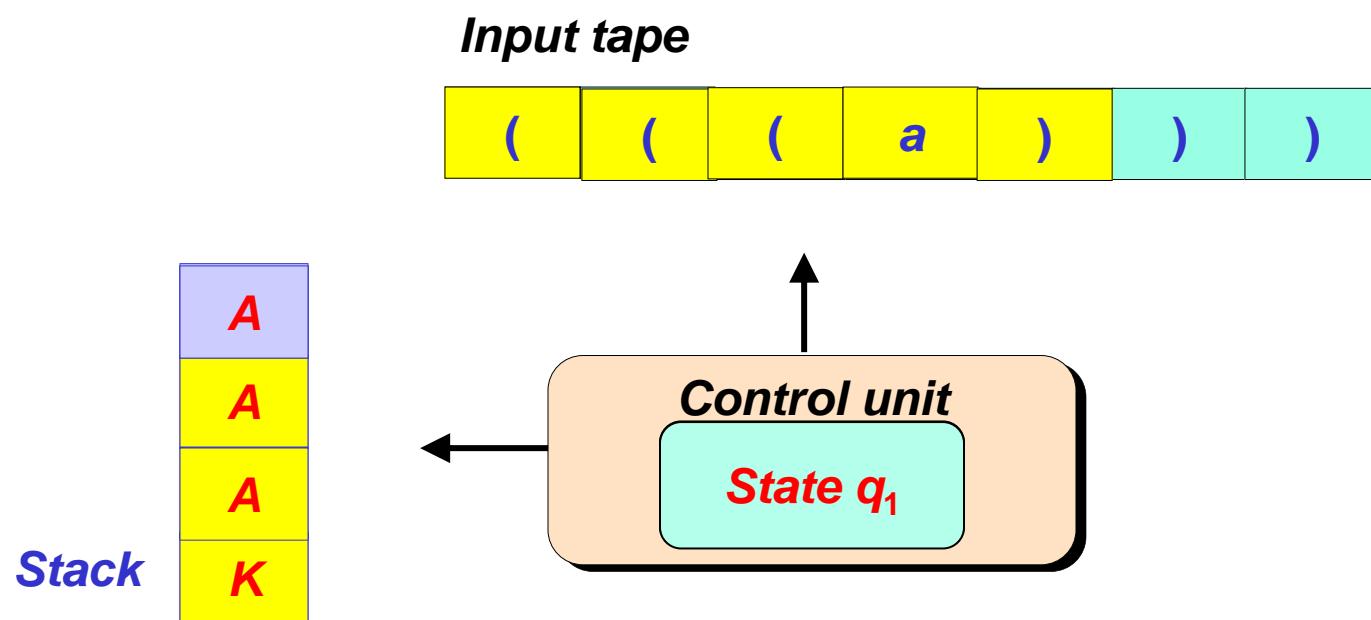
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

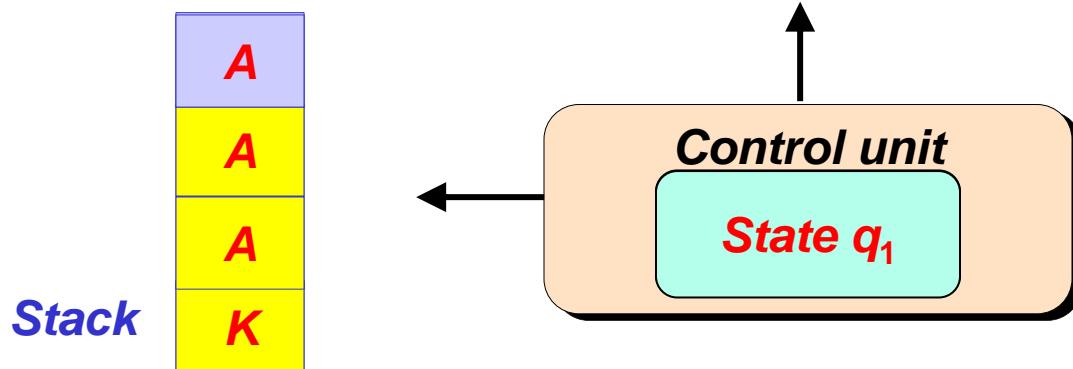
<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

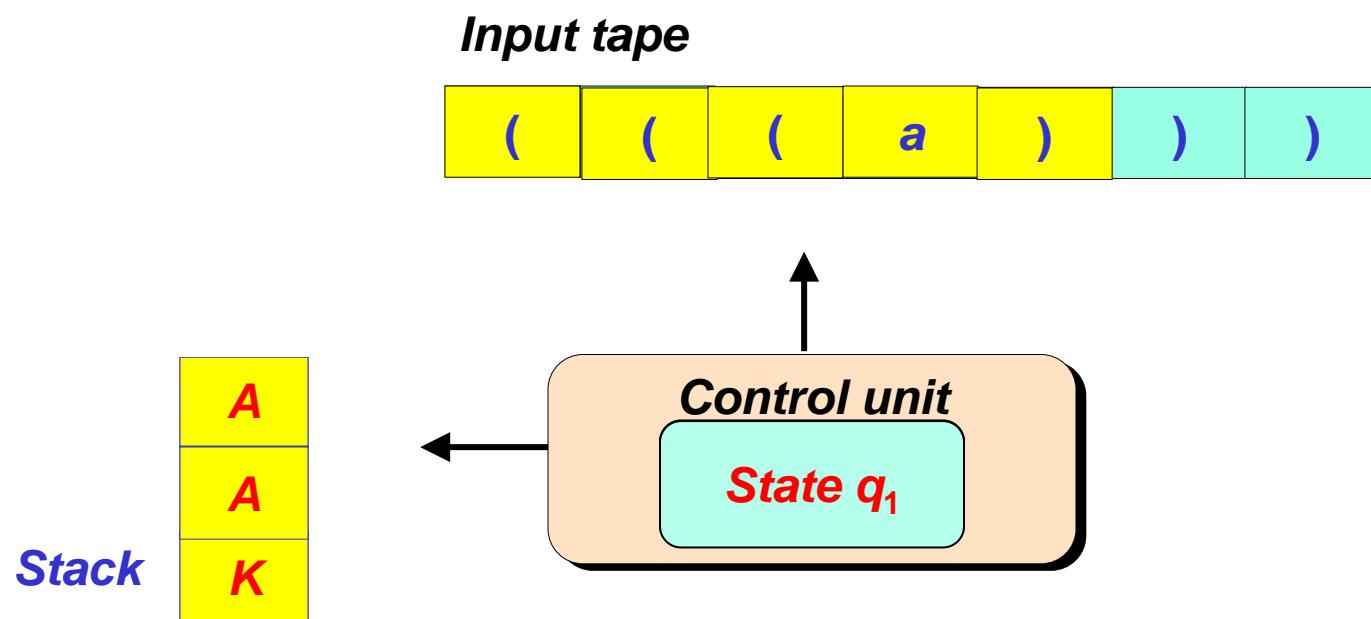
<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( $K$	$q_0$	$AK$	<i>Move to right</i>
2)	$q_0$	( $A$	$q_0$	$AA$	<i>Move to right</i>
3)	$q_0$	$a$ $A$	$q_1$	$A$	<i>Move to right</i>
4)	$q_1$	) $A$	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ $K$	$q_1$	$\epsilon$	<i>Remain at position</i>

*Input tape*



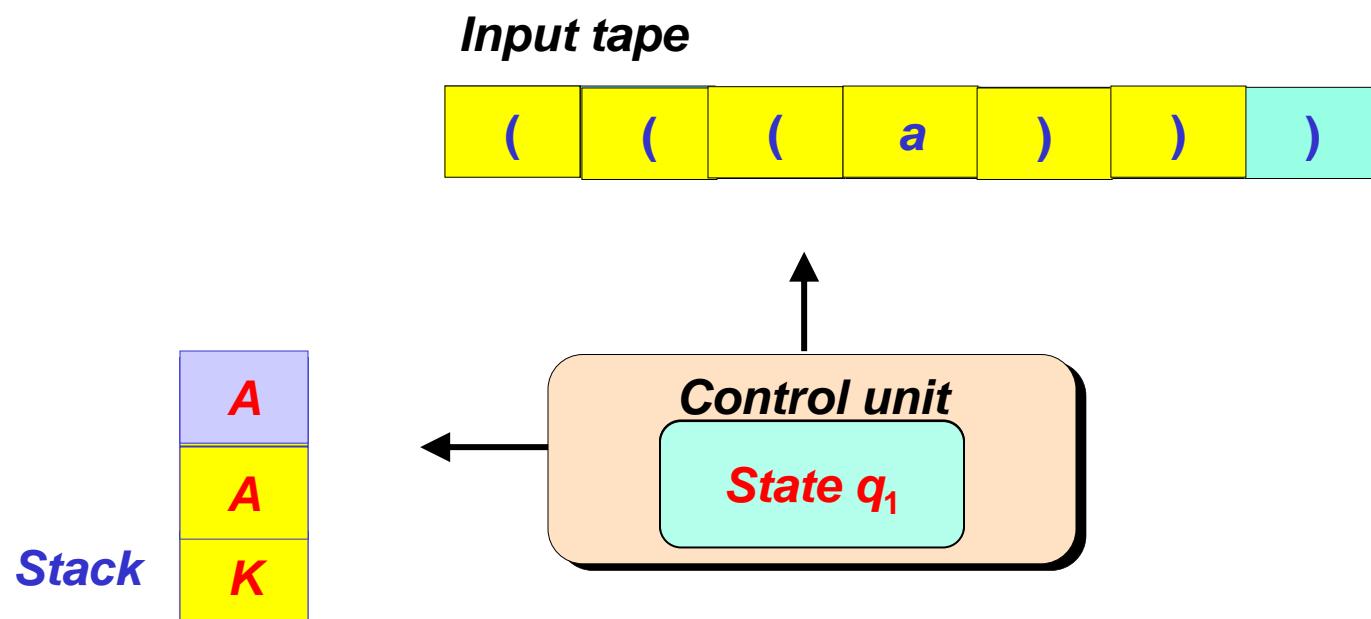
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

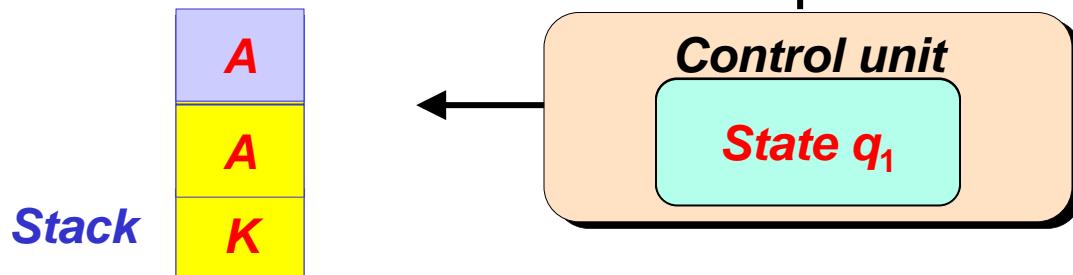
<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

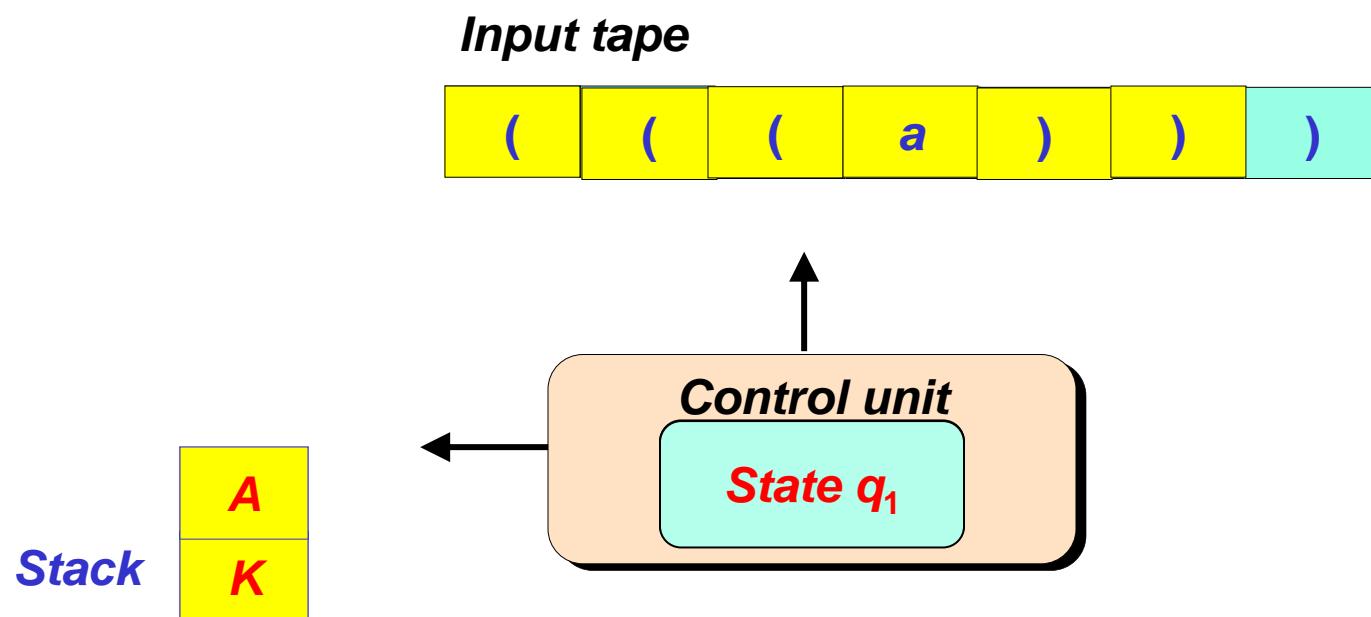
<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>

*Input tape*



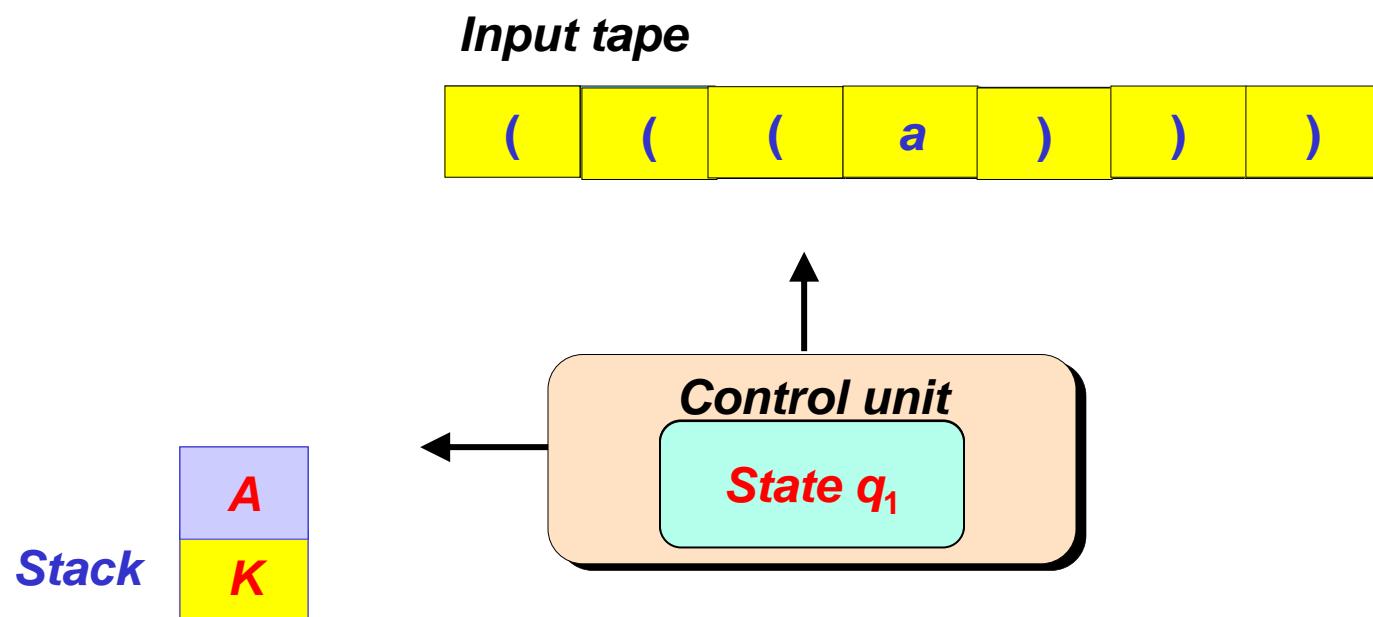
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



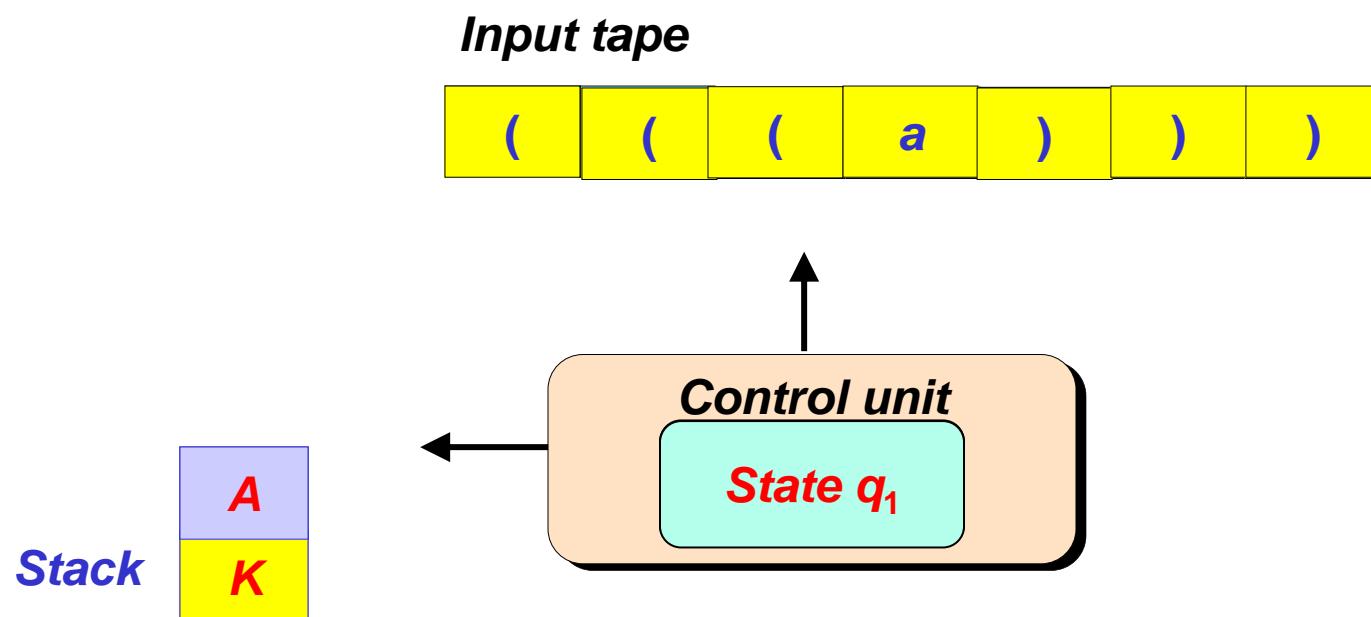
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



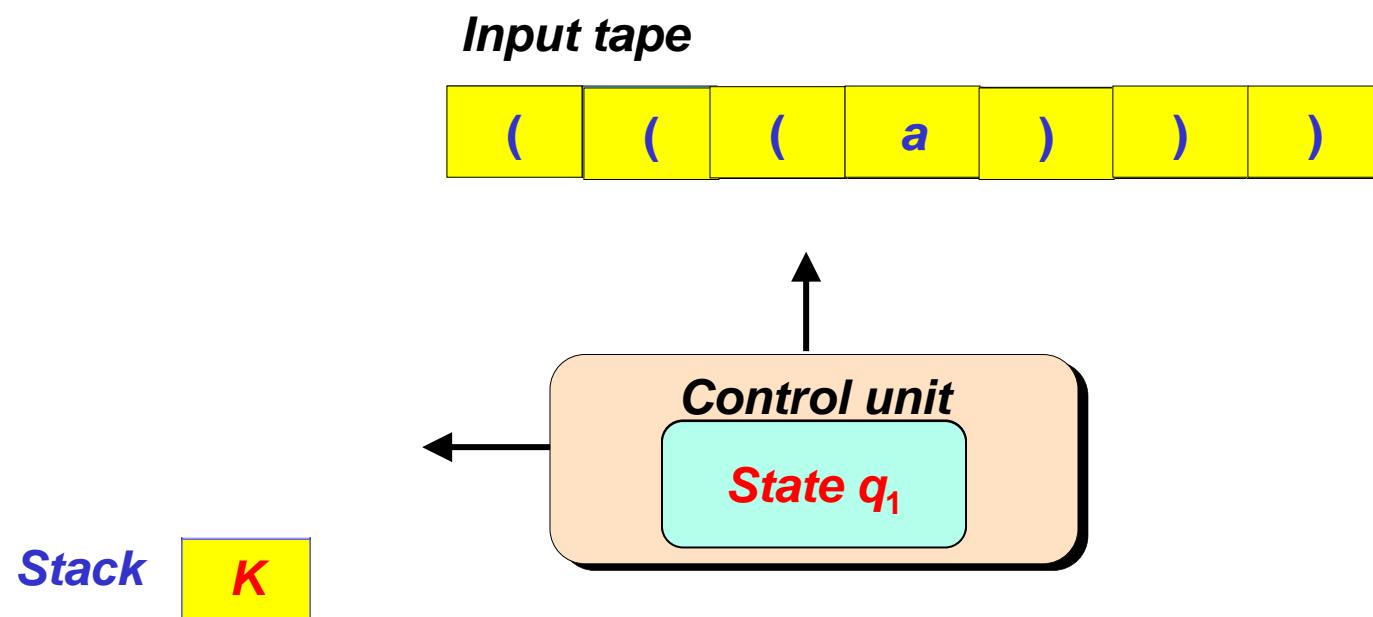
$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

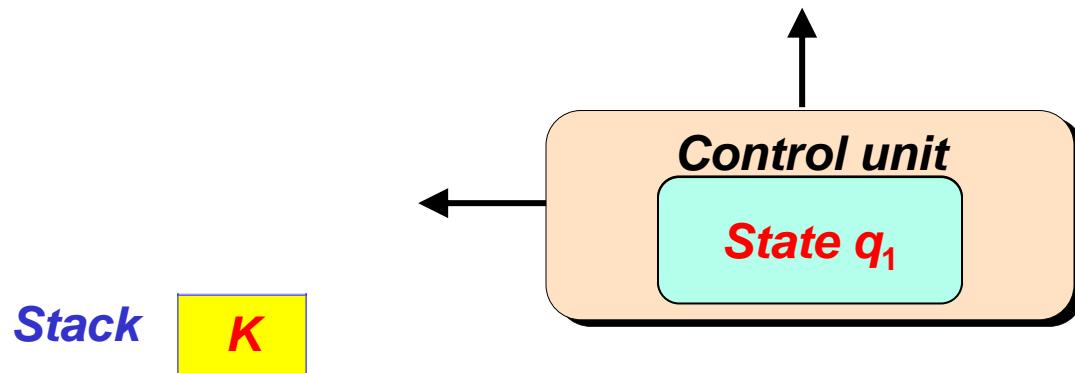
<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

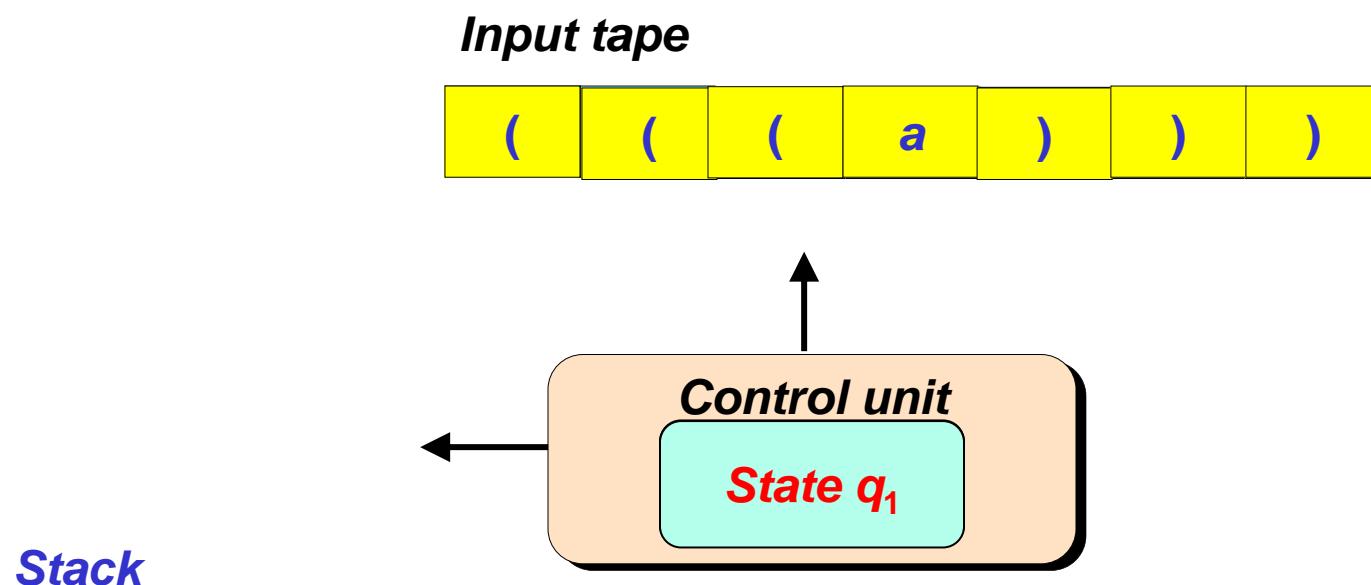
<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>

*Input tape*



$$N(M) = \{ (n a)^n \mid n \geq 1\}$$

<i>Transition</i>	<i>State</i>	<i>Input Stack</i>	<i>New state</i>	<i>New stack top</i>	<i>Read-only head</i>
1)	$q_0$	( <span style="color:red">K</span>	$q_0$	<span style="color:red">AK</span>	<i>Move to right</i>
2)	$q_0$	( <span style="color:red">A</span>	$q_0$	<span style="color:red">AA</span>	<i>Move to right</i>
3)	$q_0$	a <span style="color:red">A</span>	$q_1$	<span style="color:red">A</span>	<i>Move to right</i>
4)	$q_1$	) <span style="color:red">A</span>	$q_1$	$\epsilon$	<i>Move to right</i>
5)	$q_1$	$\epsilon$ <span style="color:red">K</span>	$q_1$	$\epsilon$	<i>Remain at position</i>



# Lecture 9

## 3.2 PUSHDOWN AUTOMATA (PA)

3.2.1 PA Model

3.2.2 PA Definition

3.2.3 PA and Context-Free Grammar

# PA Definition

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

**Q**

- finite set of states

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

**Q**  
**Σ**

- finite set of states
- finite set of input symbols

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

**Q**

**Σ**

**Γ**

- finite set of states
- finite set of input symbols
- finite state of stack symbols

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

**Q**  
**Σ**  
**Γ**  
**δ**

- finite set of states
- finite set of input symbols
- finite state of stack symbols
- transition function

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

Q  
Σ  
Γ  
δ

- finite set of states
- finite set of input symbols
- finite state of stack symbols
- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

- finite set of states
- finite set of input symbols
- finite state of stack symbols
- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

- finite set of states
- finite set of input symbols
- finite state of stack symbols
- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state
- start stack symbol

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

$q \in Q$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

$$a \in \Sigma$$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

$Z \in \Gamma$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

$$p_1 \in Q$$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

$$\gamma_1 \in \Gamma^*$$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

# PA Definition

$$pa = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$Q$

$\Sigma$

$\Gamma$

$\delta$

$q_0 \in Q$

$Z_0 \in \Gamma$

$F \subseteq Q$

- finite set of states

- finite set of input symbols

- finite state of stack symbols

- transition function

$$\delta : Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

- start state

- start stack symbol

- set of accepting states

$$\delta(q, a, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

$$\delta(q, \varepsilon, Z) = \{ (p_1, \gamma_1), (p_2, \gamma_2), \dots, (p_m, \gamma_m) \}$$

# PA Definition

# PA Definition

$$L(M_1) = \{ w^2 w^R \mid w \in (0+1)^* \}$$

# PA Definition

$$L(M_1) = \{ w^2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

# PA Definition

$$L(M_1) = \{ w^2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

*Input tape*

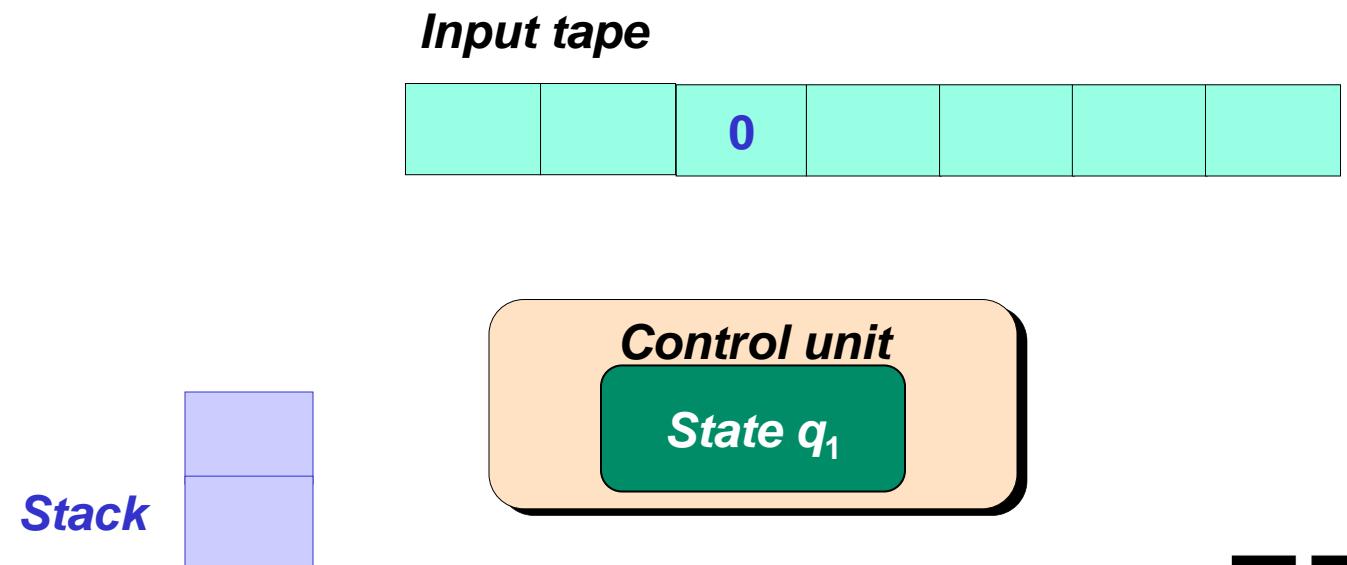


*Control unit*  
State  $q_1$

# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

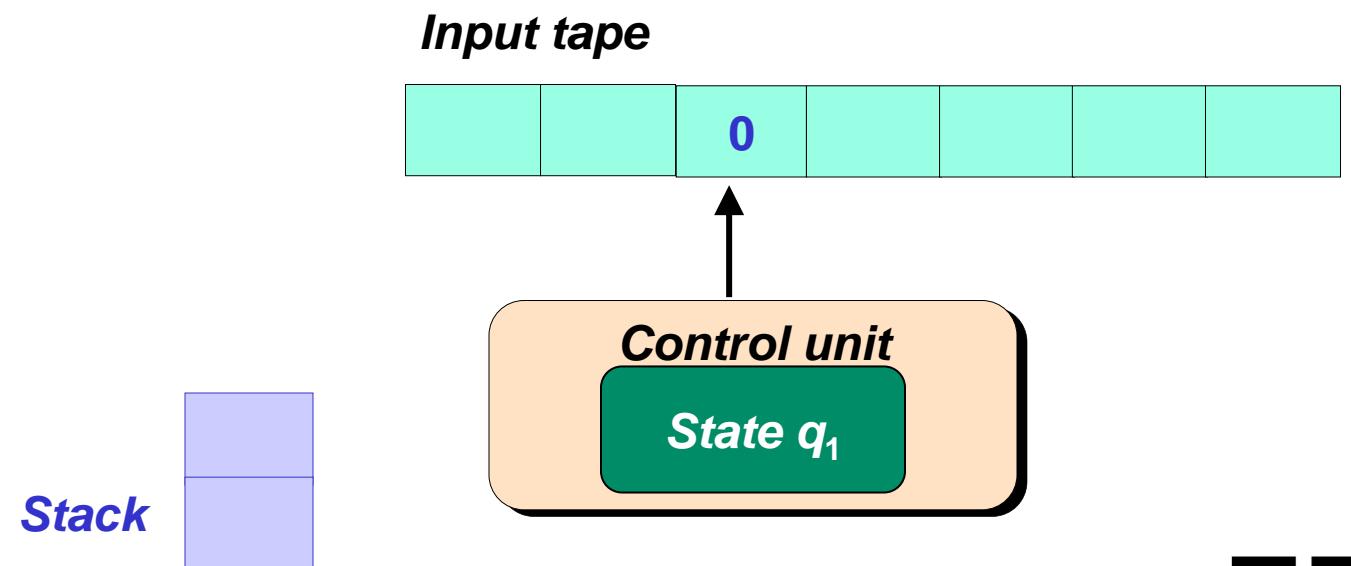
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

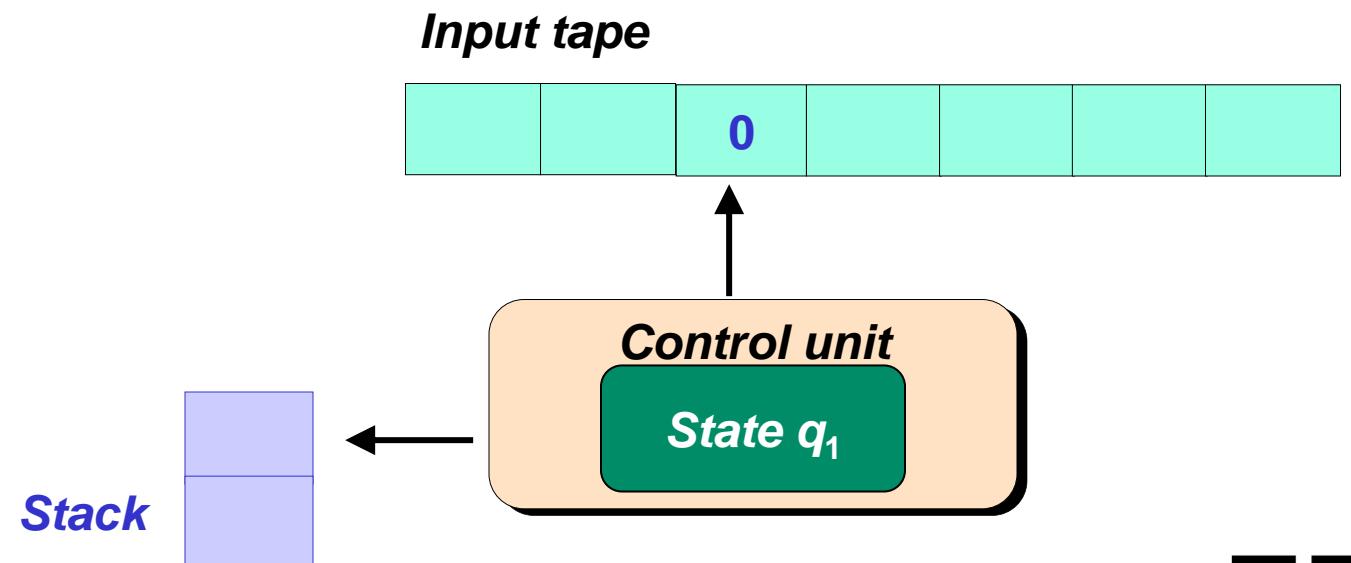
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

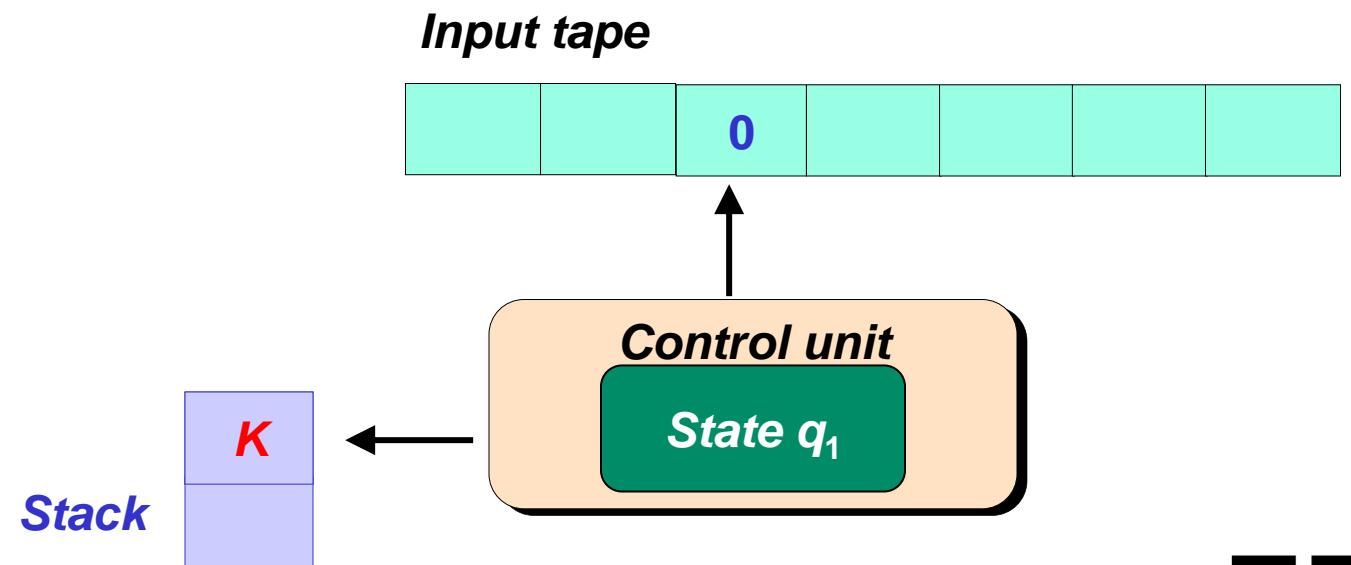
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

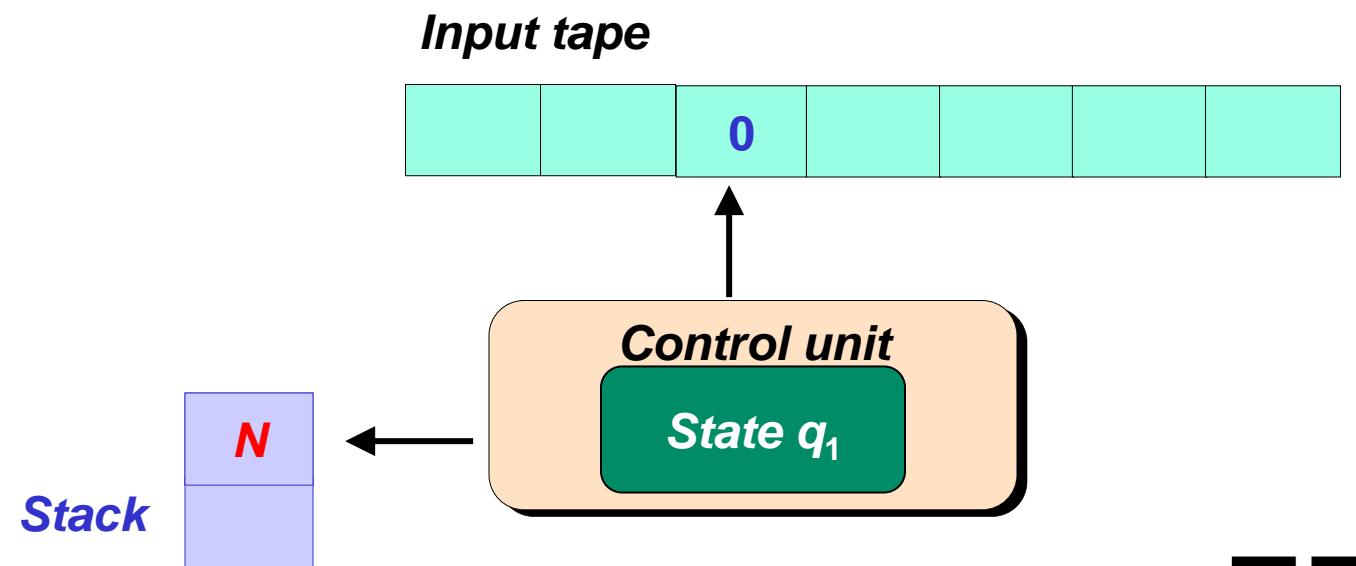
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

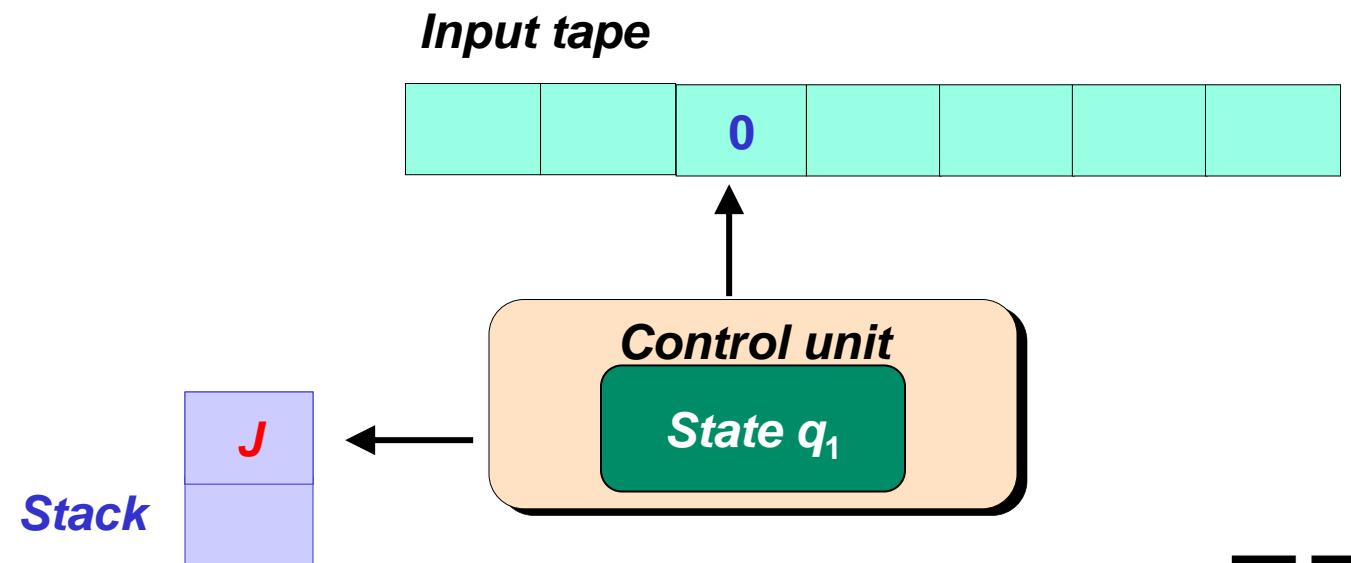
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

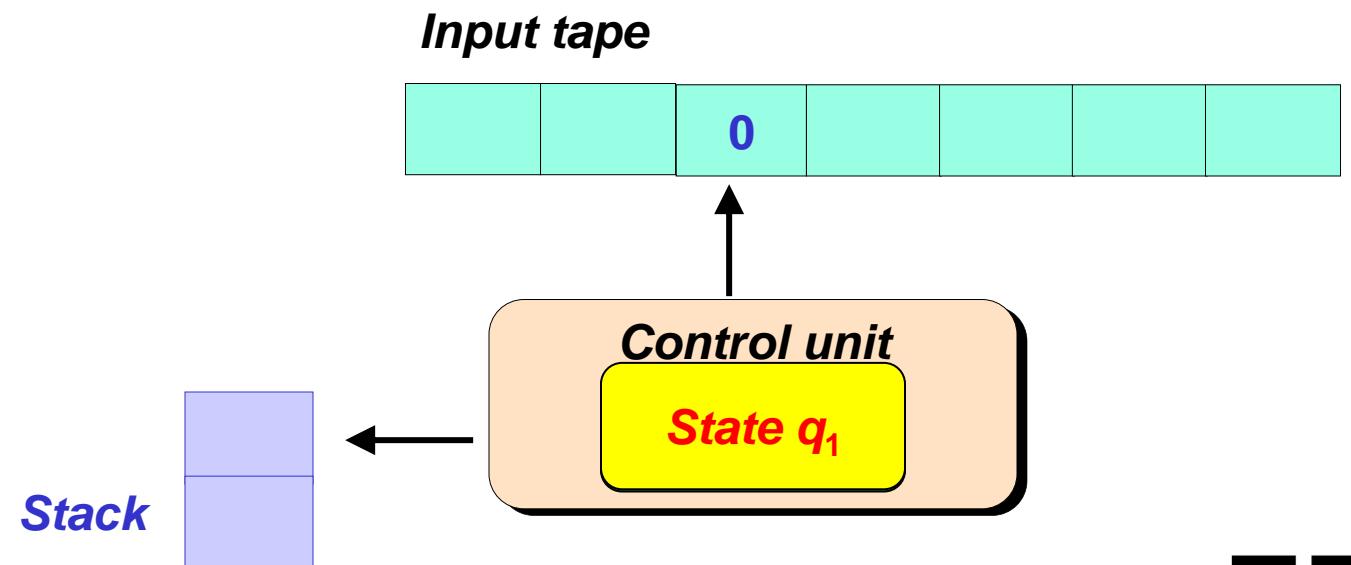
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

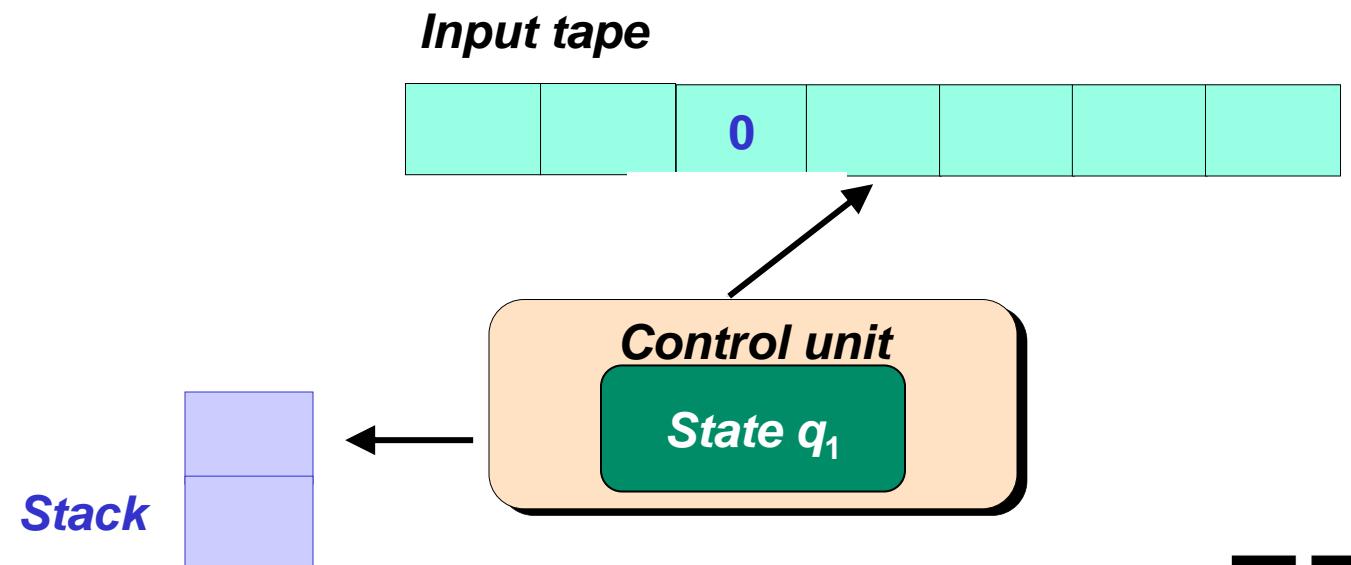
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

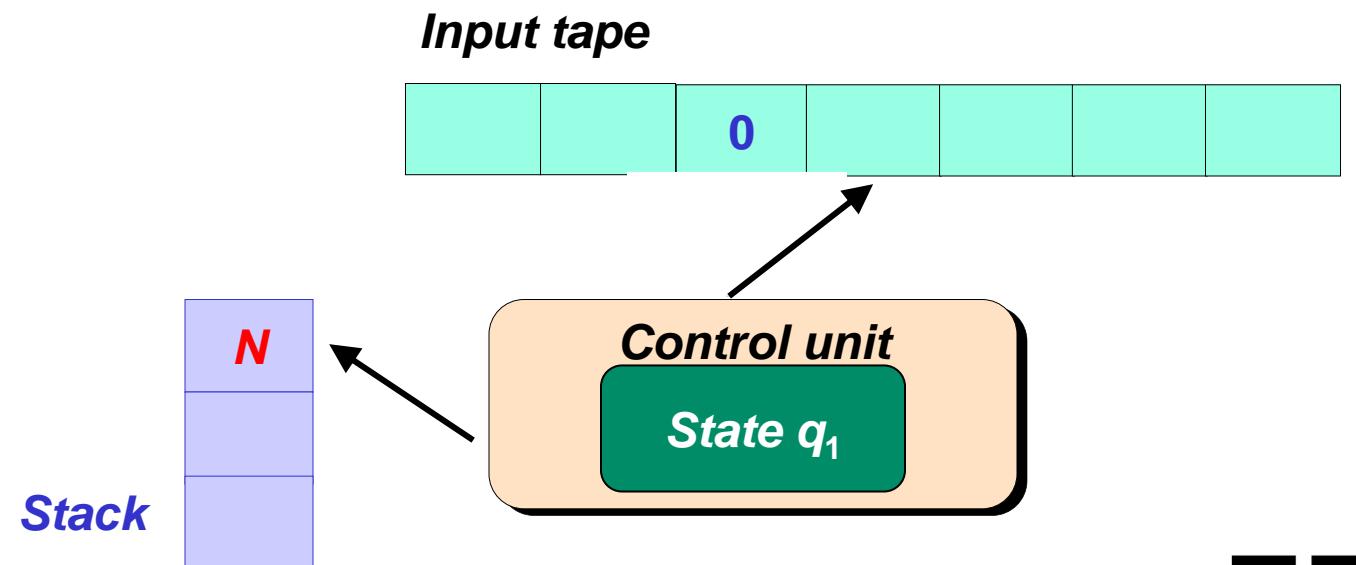
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

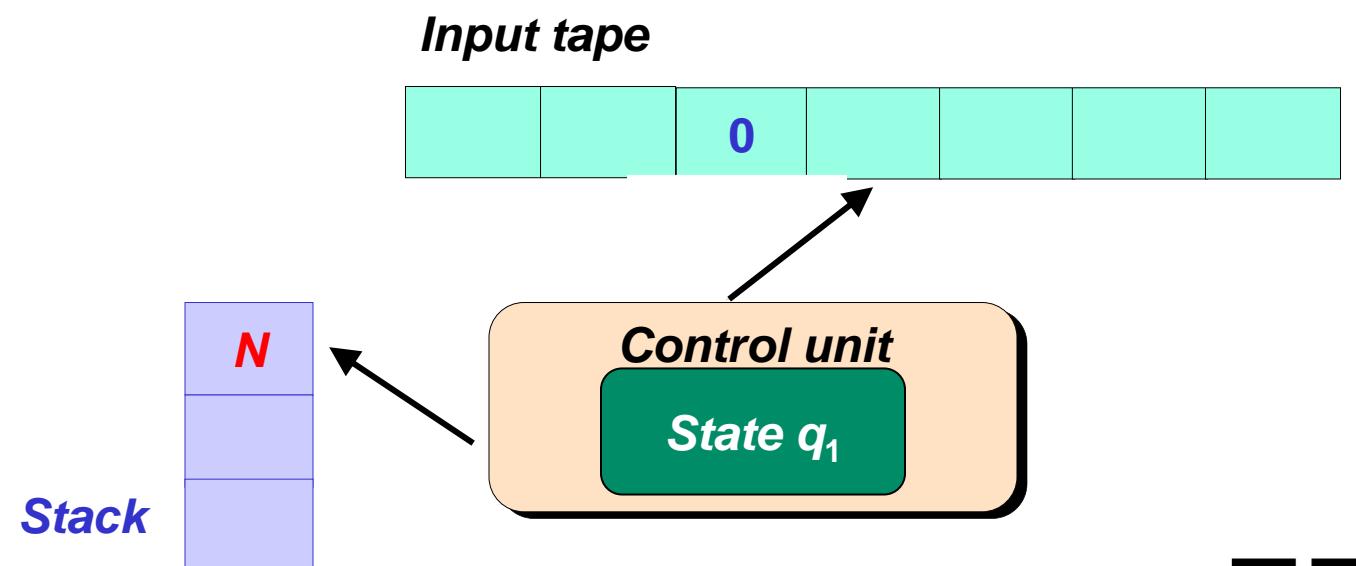


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

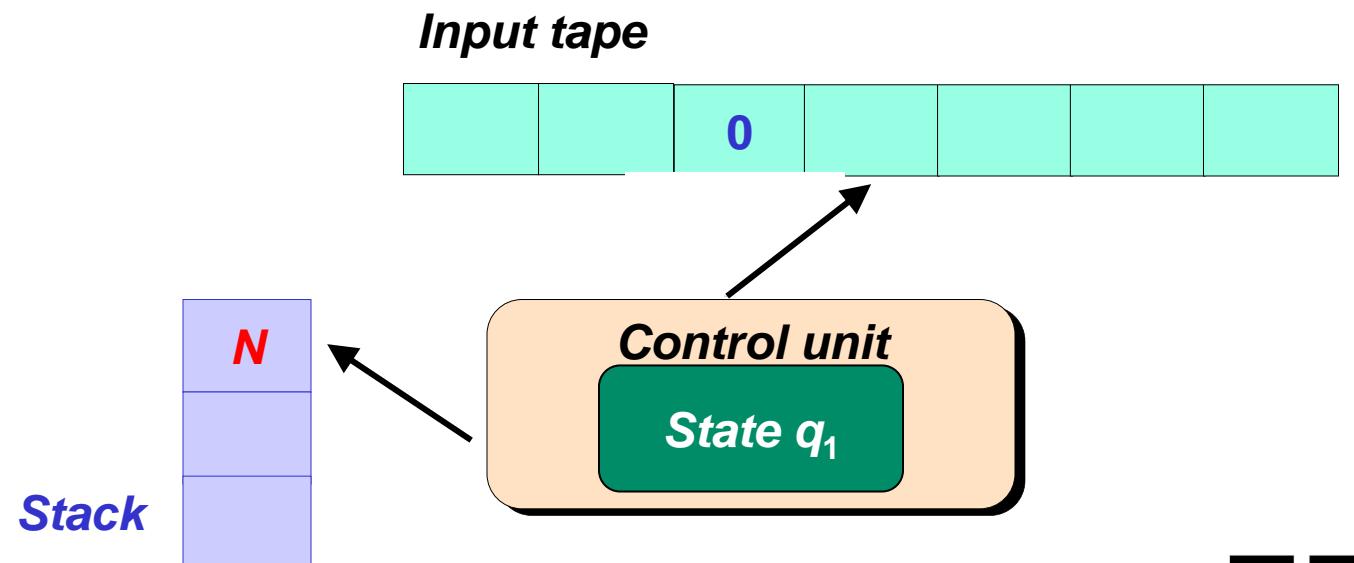


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$

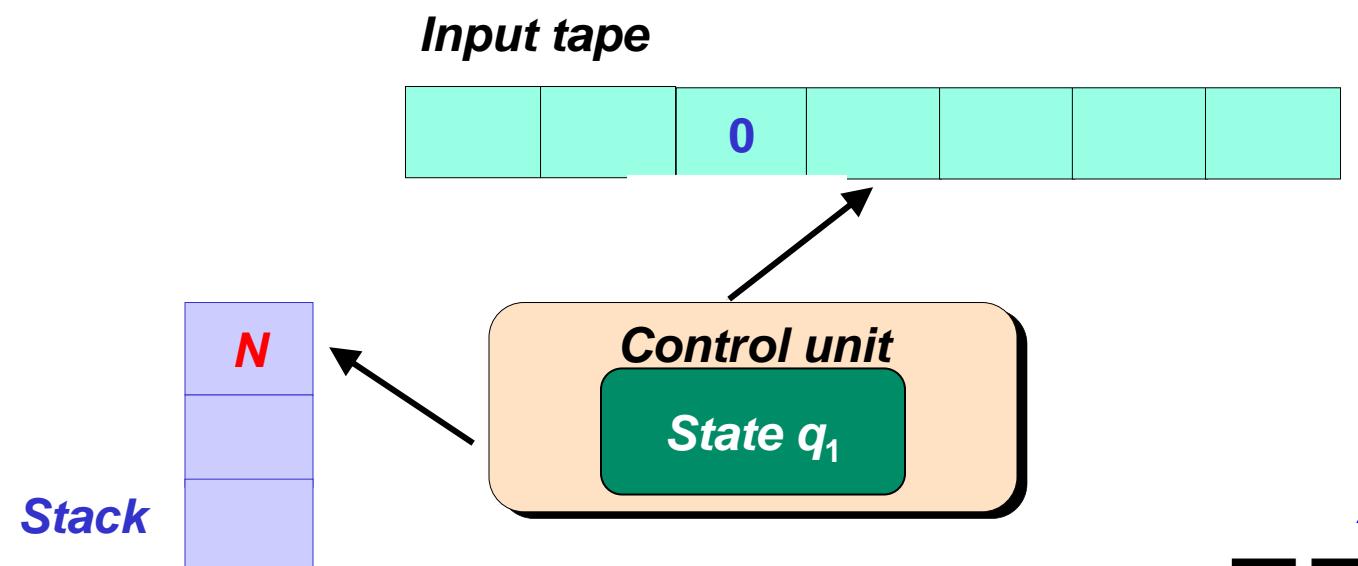


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

PA  $M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

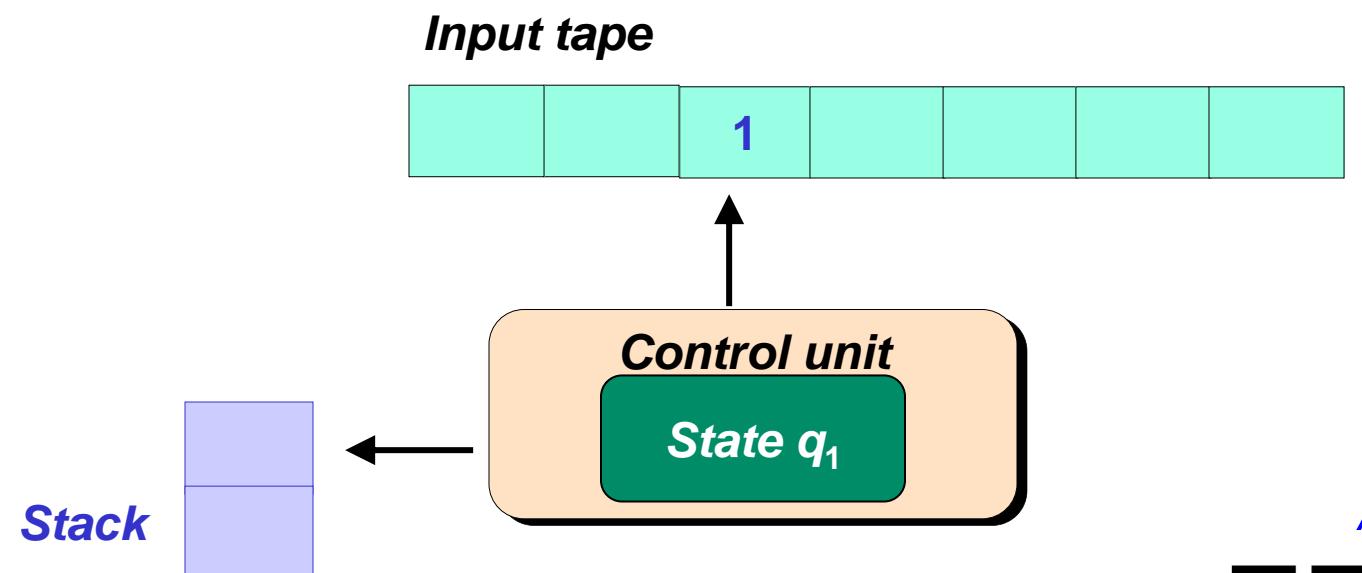


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

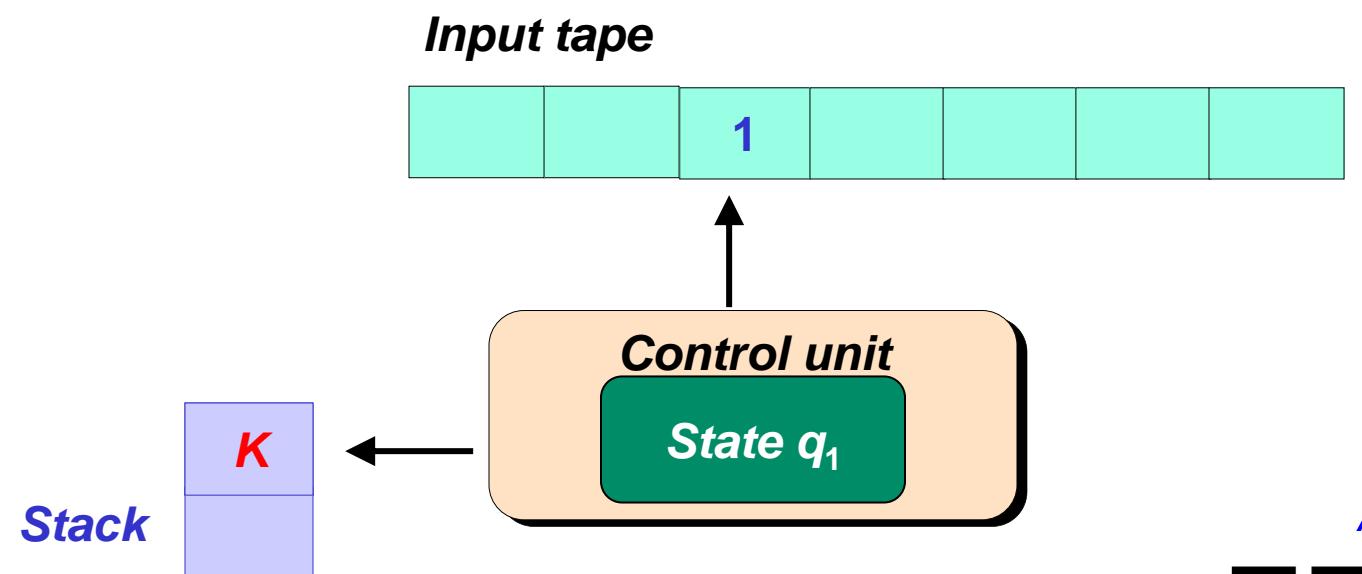


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

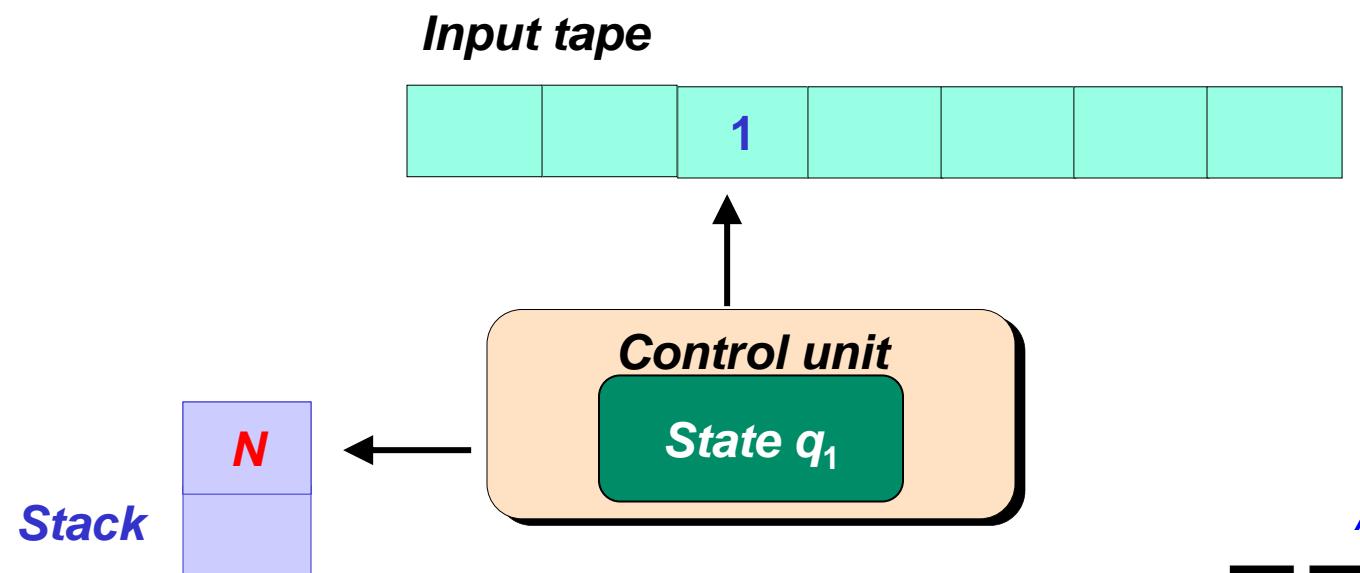


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

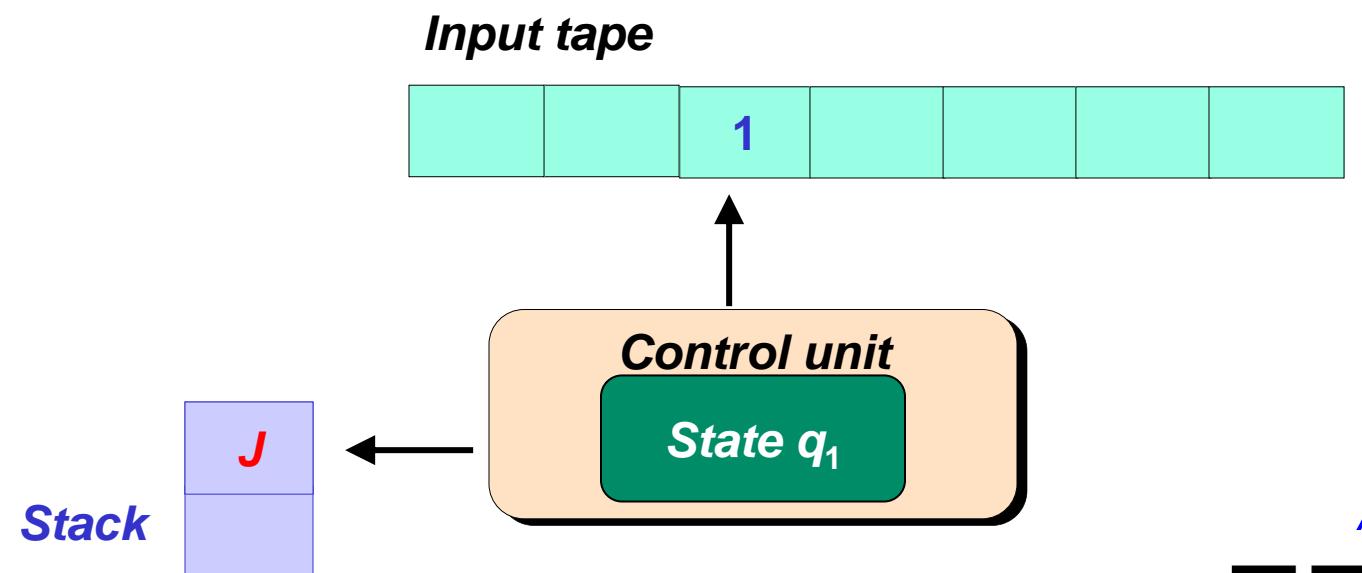


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

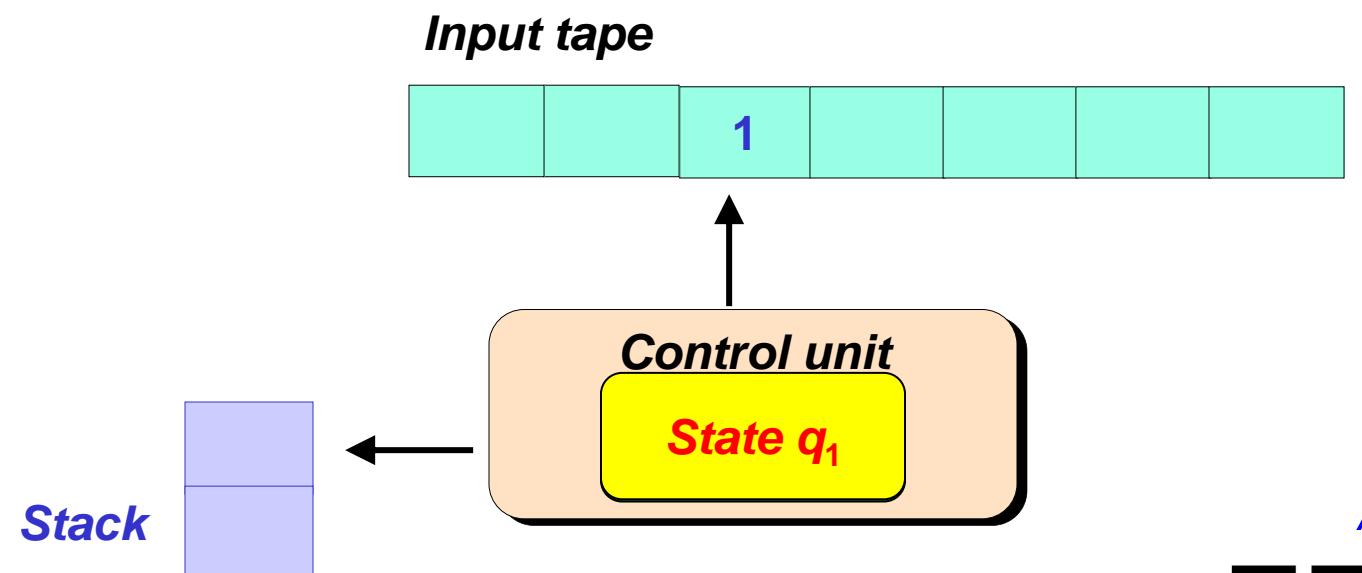


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

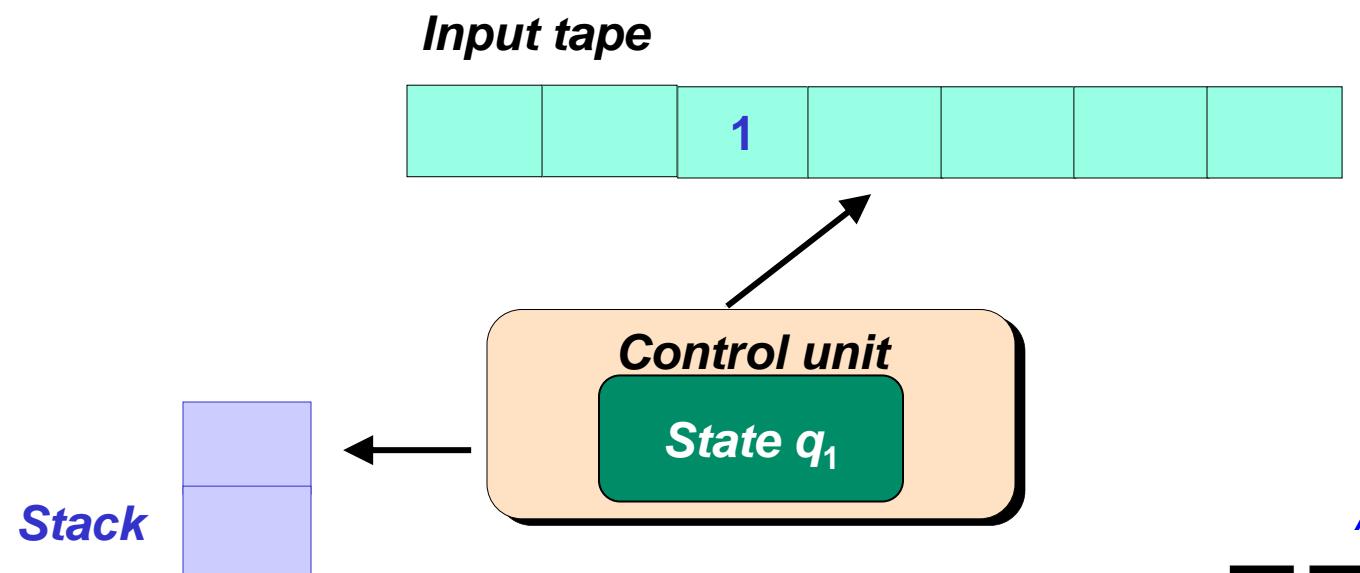


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

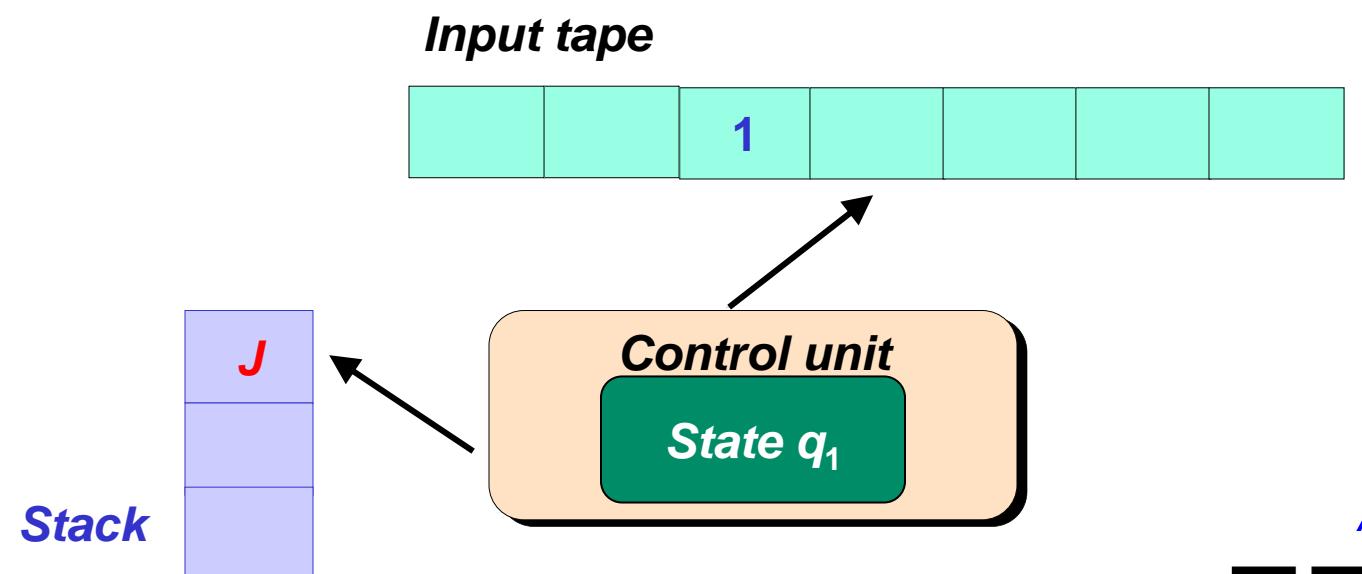


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

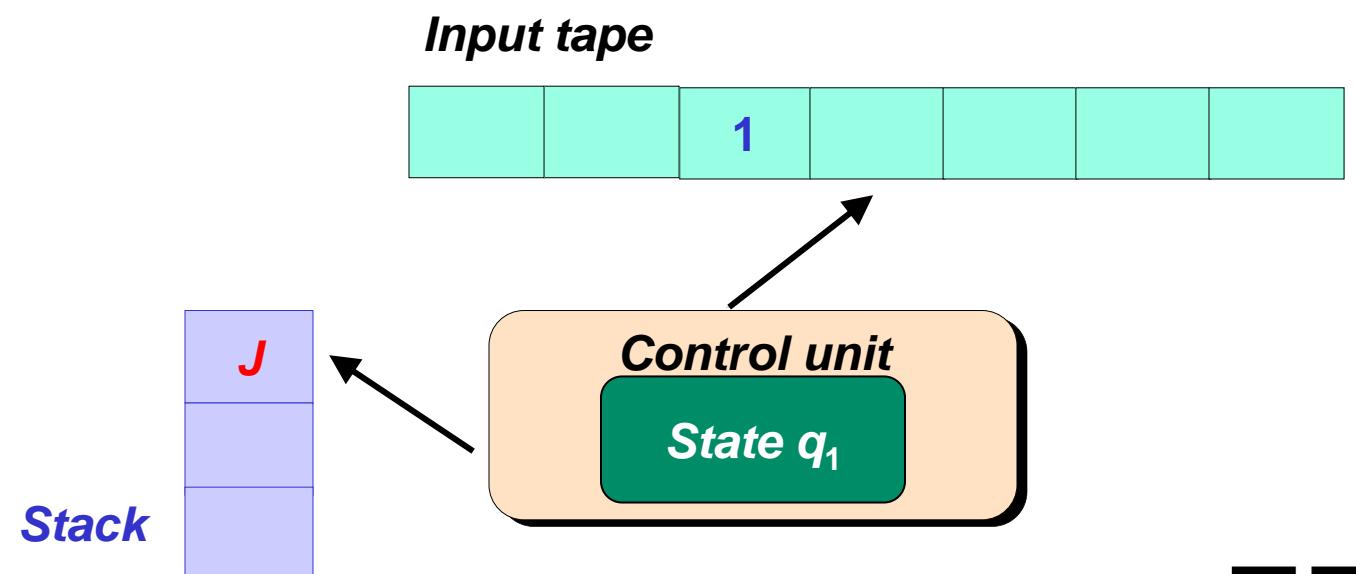
$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

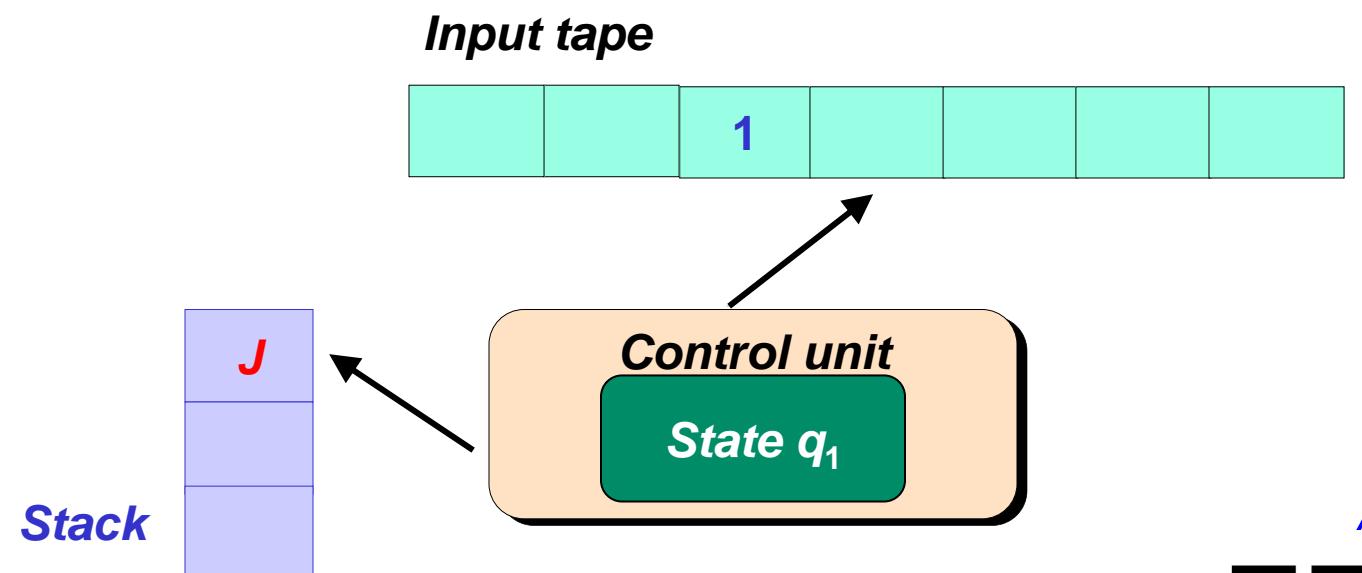
$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

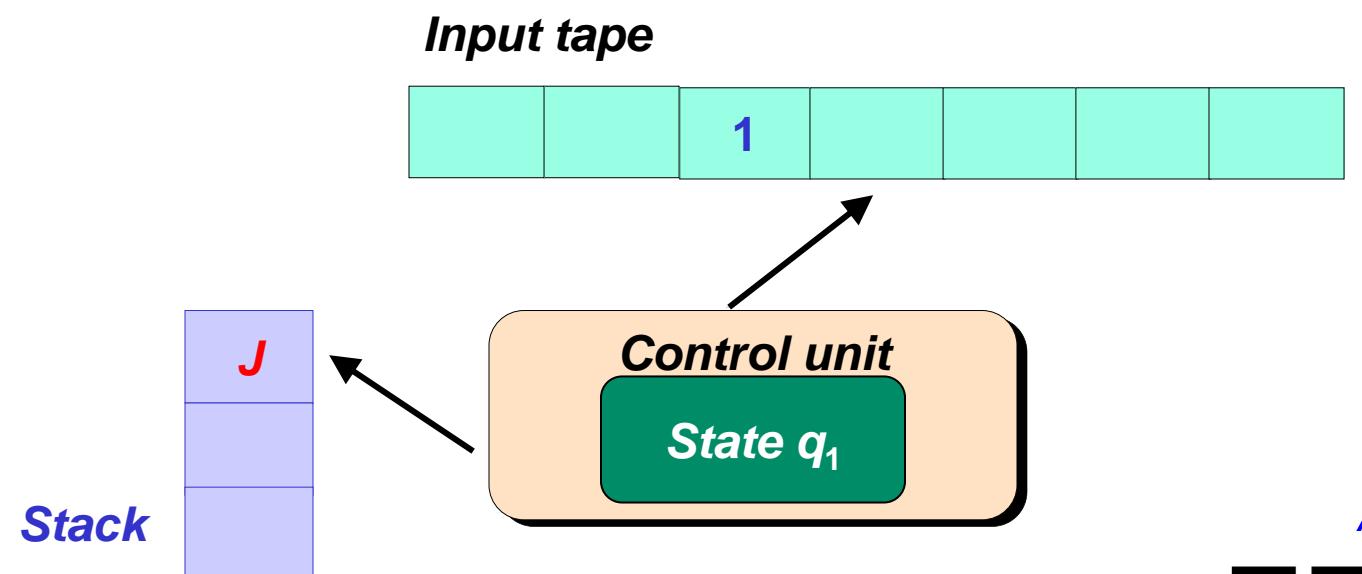


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$ |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$ |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$ |

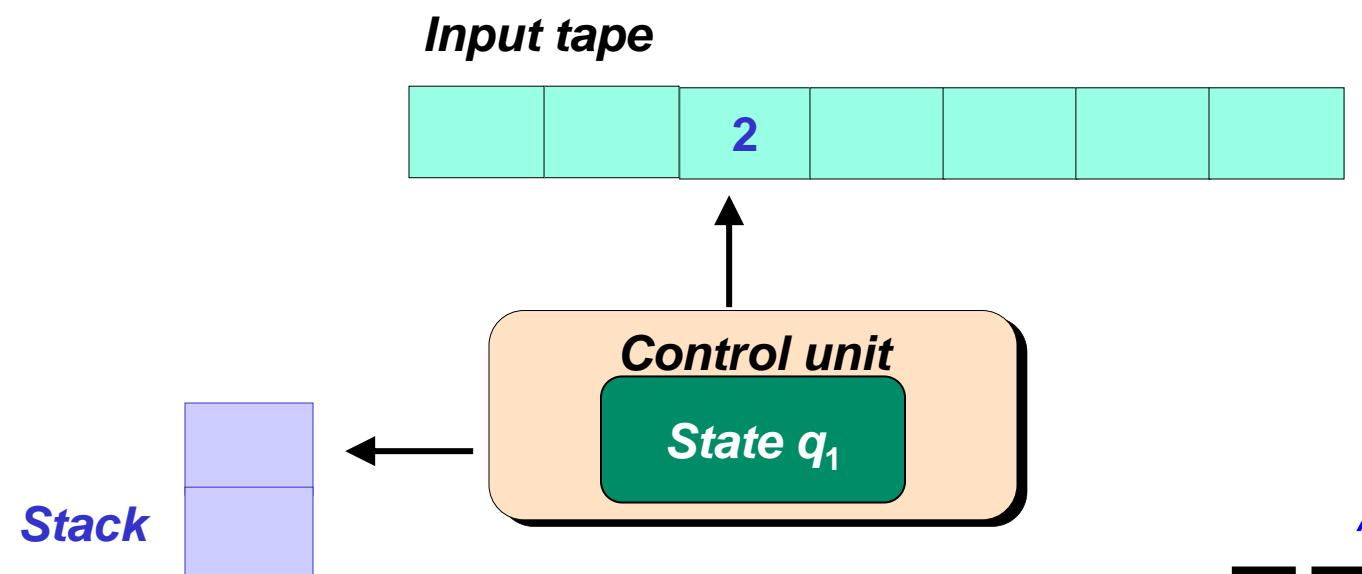


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$ |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$ |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$ |

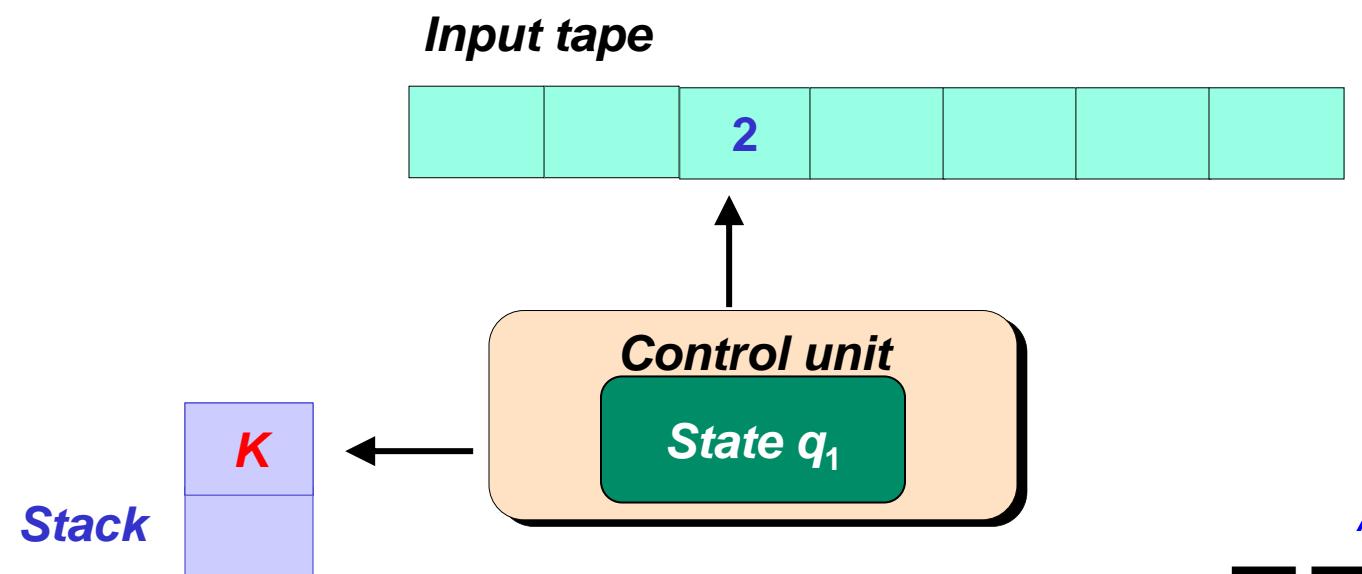


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$ |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$ |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$ |

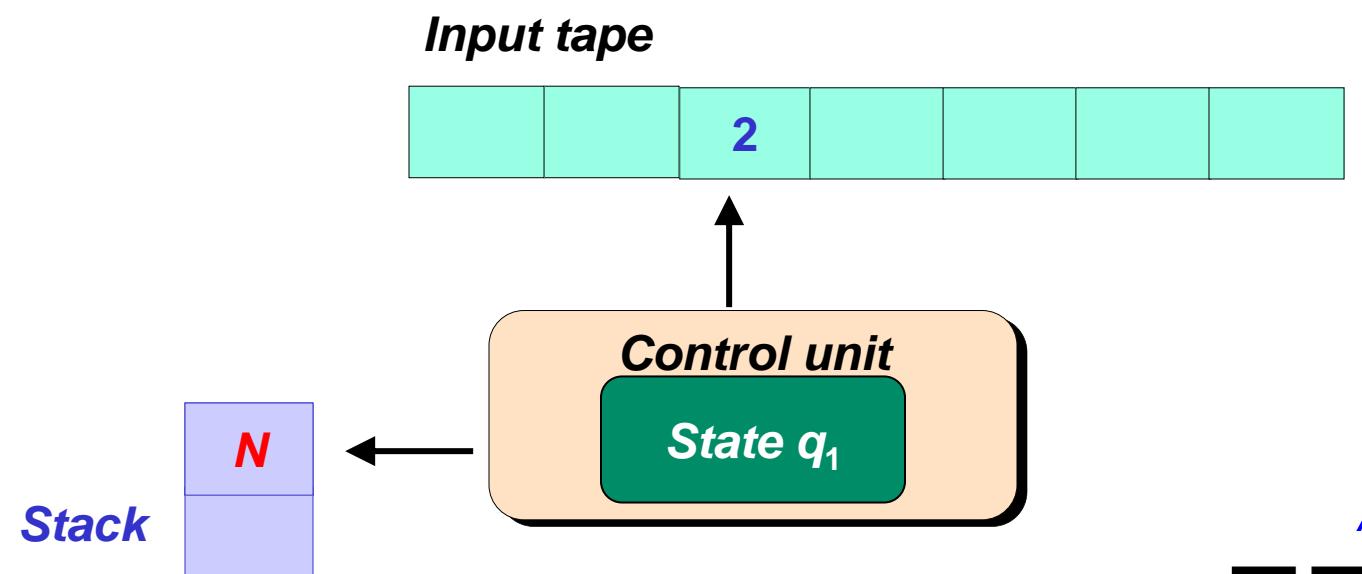


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$ |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$ |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$ |

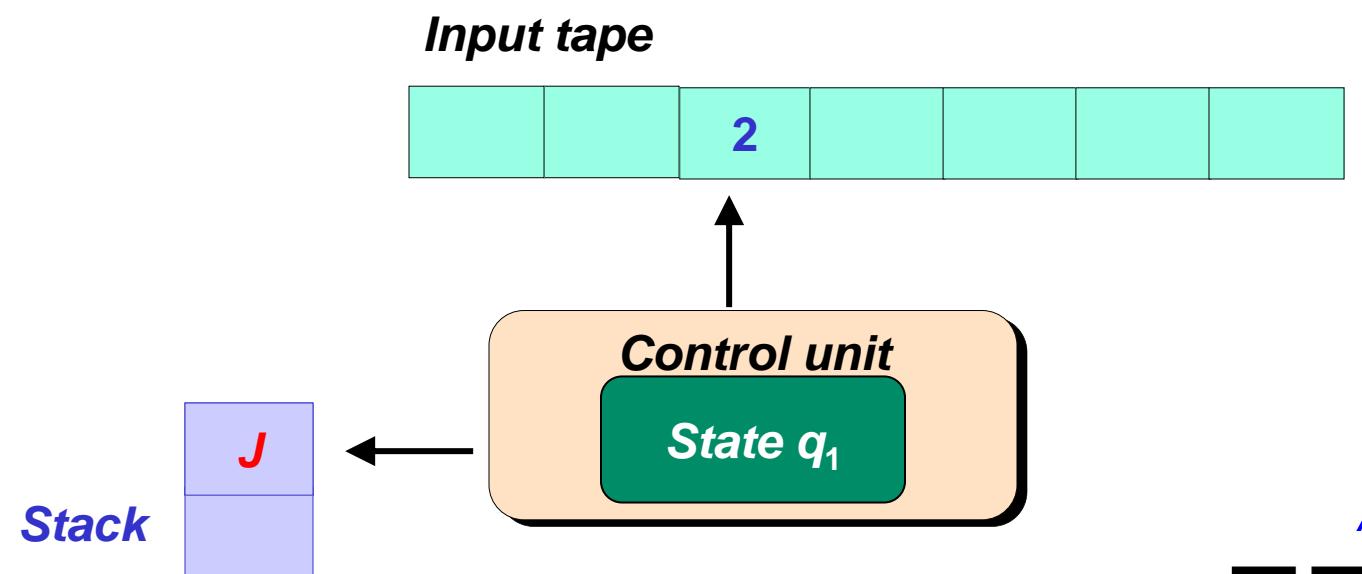


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$ |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$ |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$ |

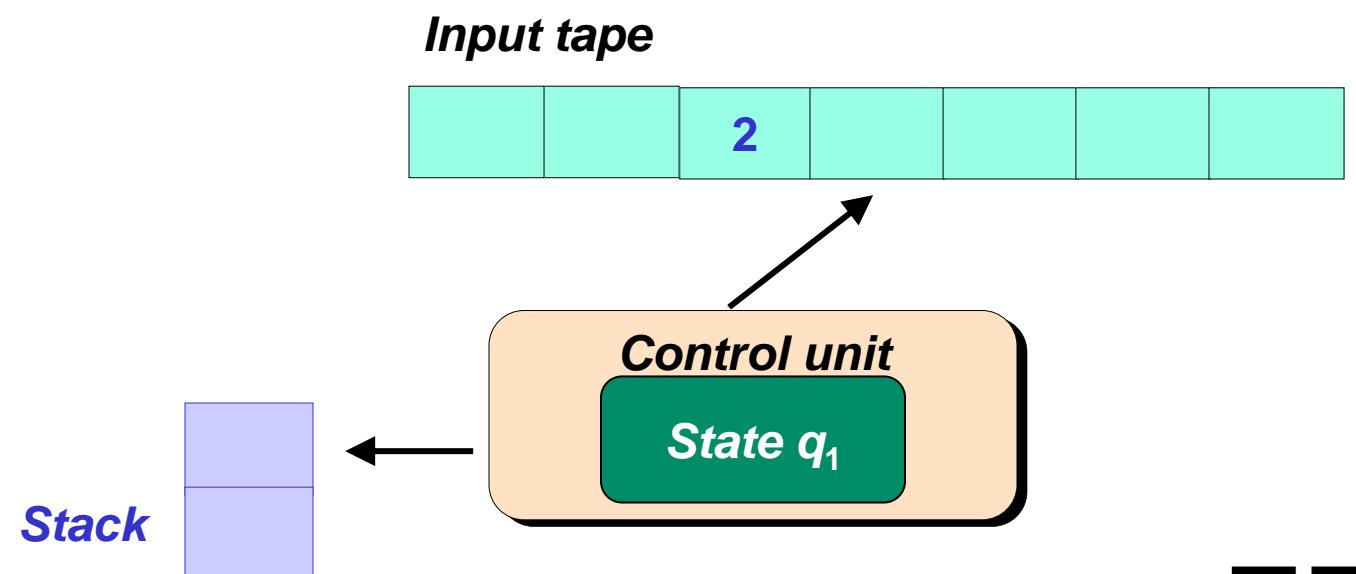


# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$ |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$ |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$ |



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

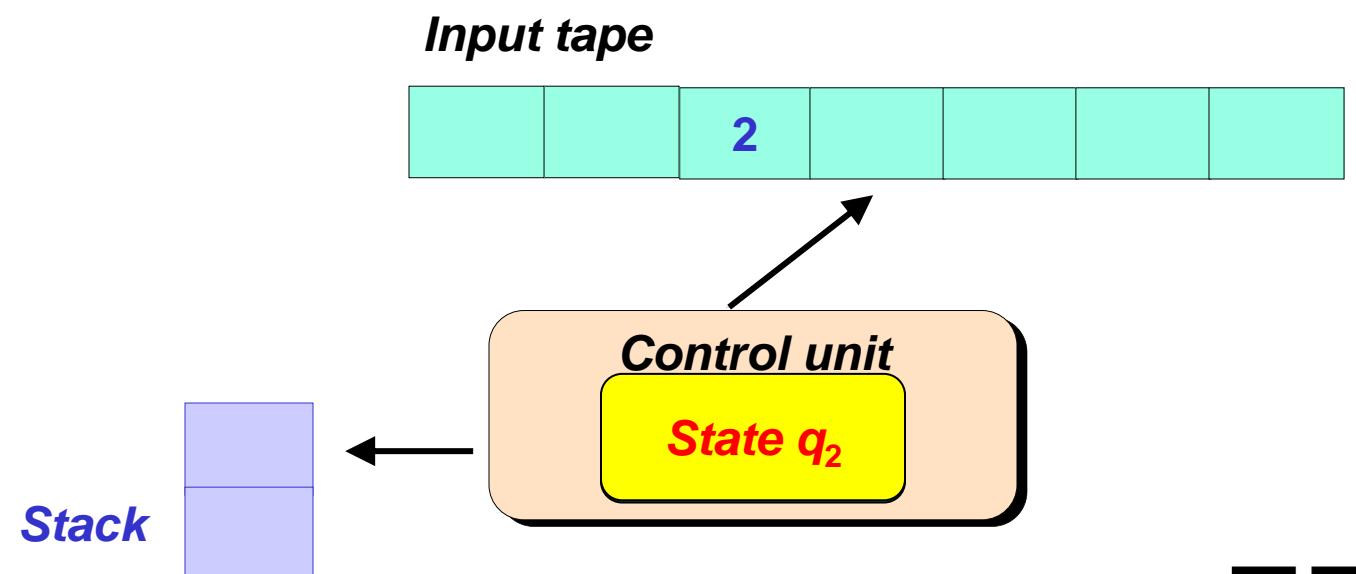
$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

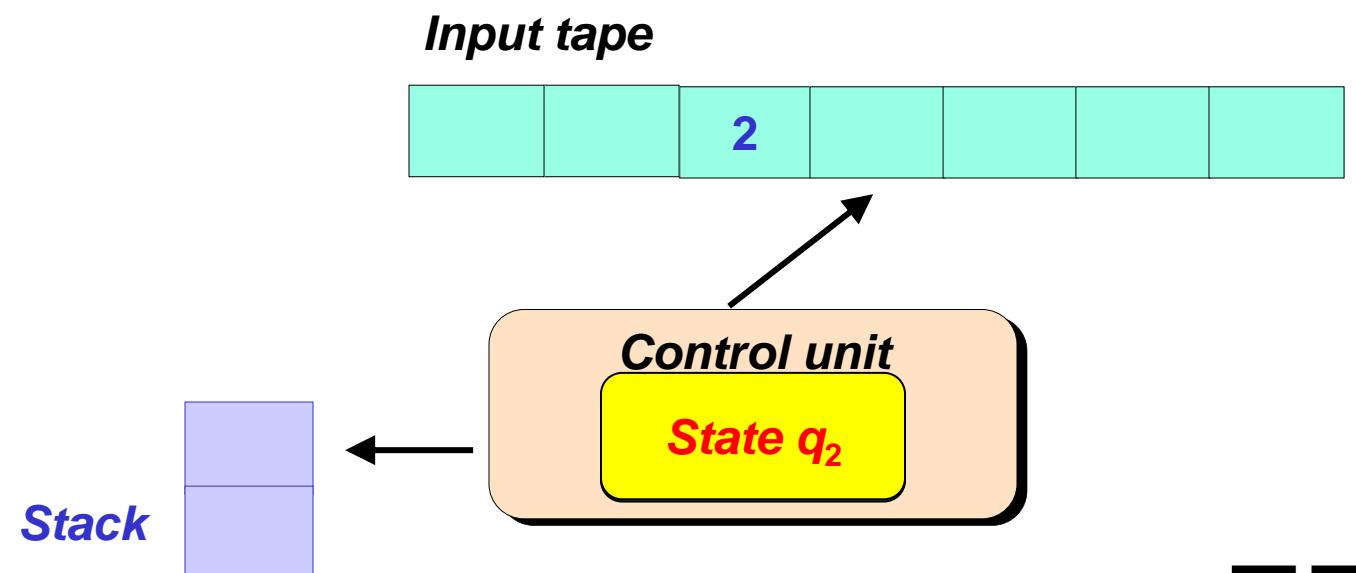
$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

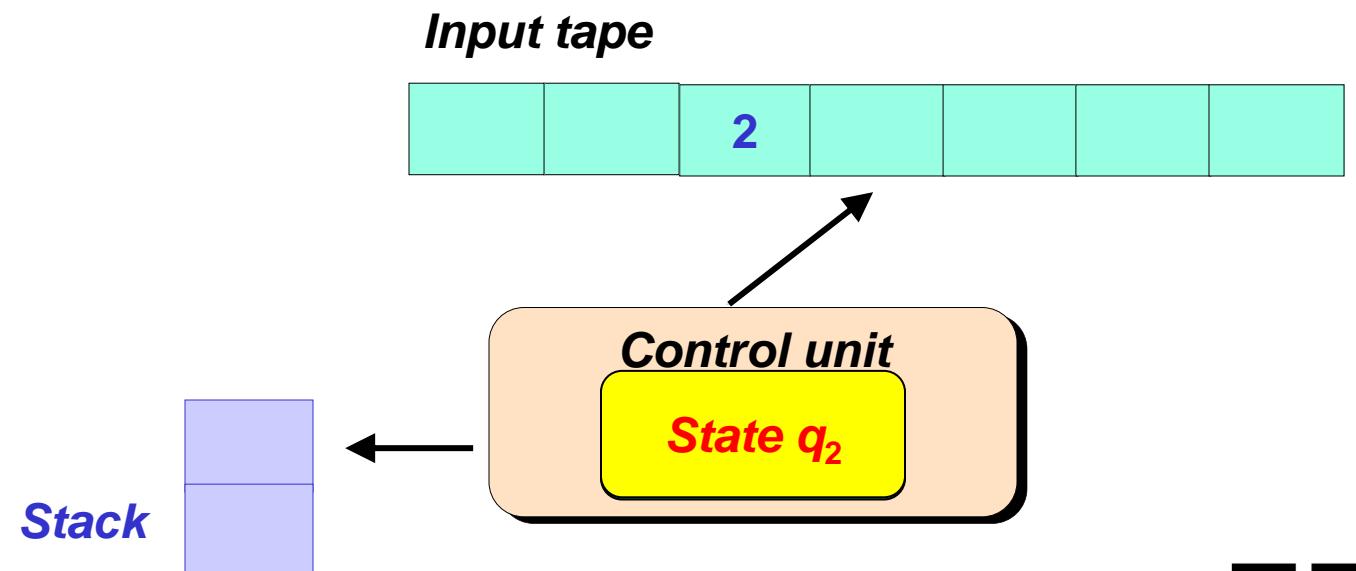
$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

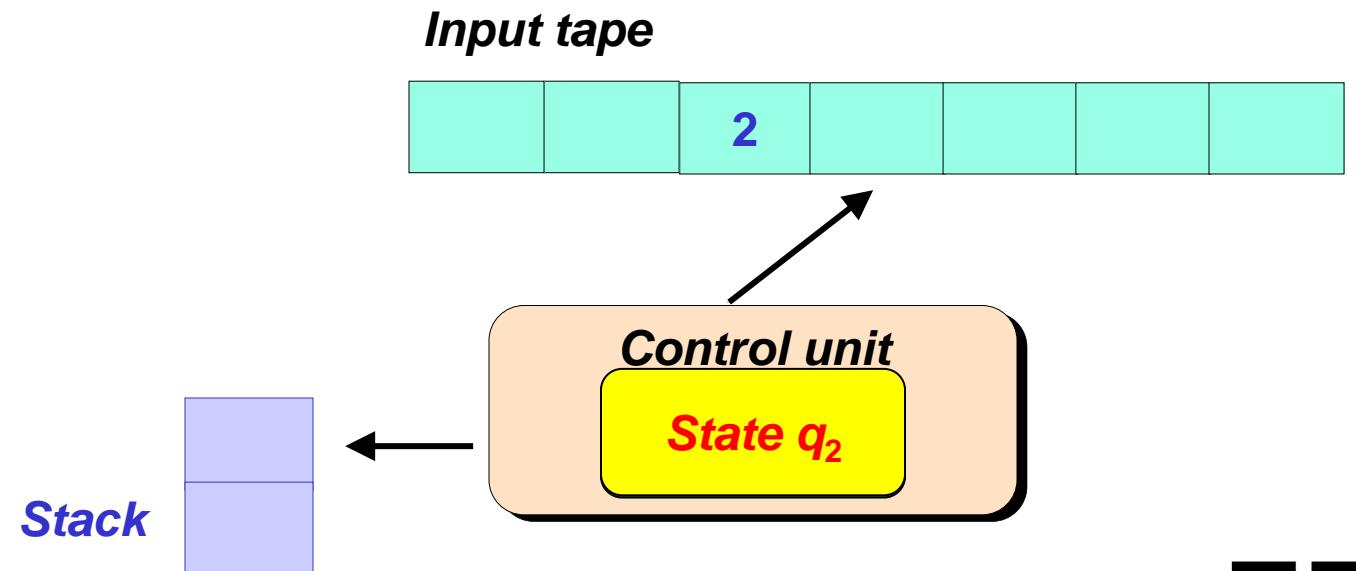
$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

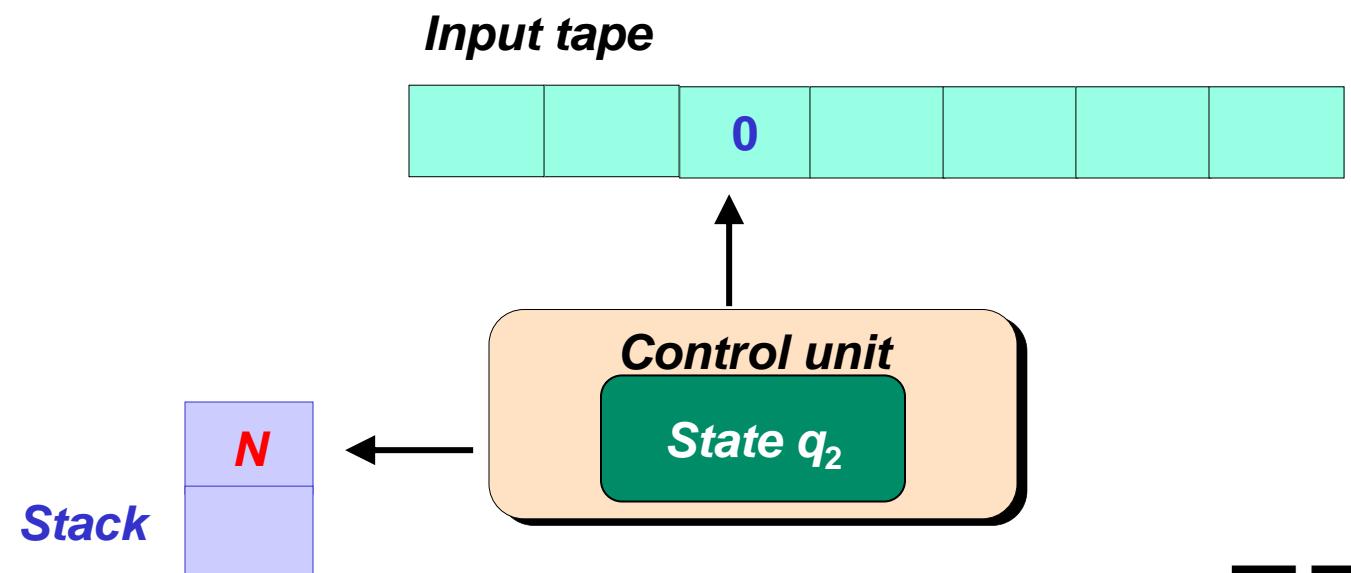
$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

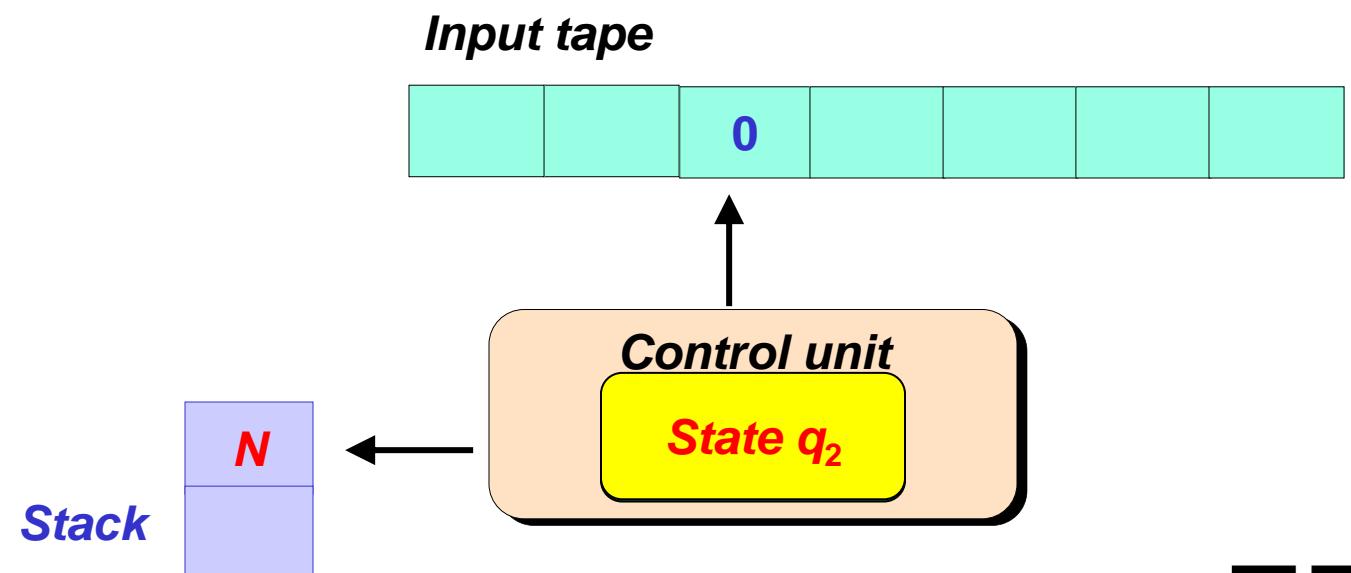
$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

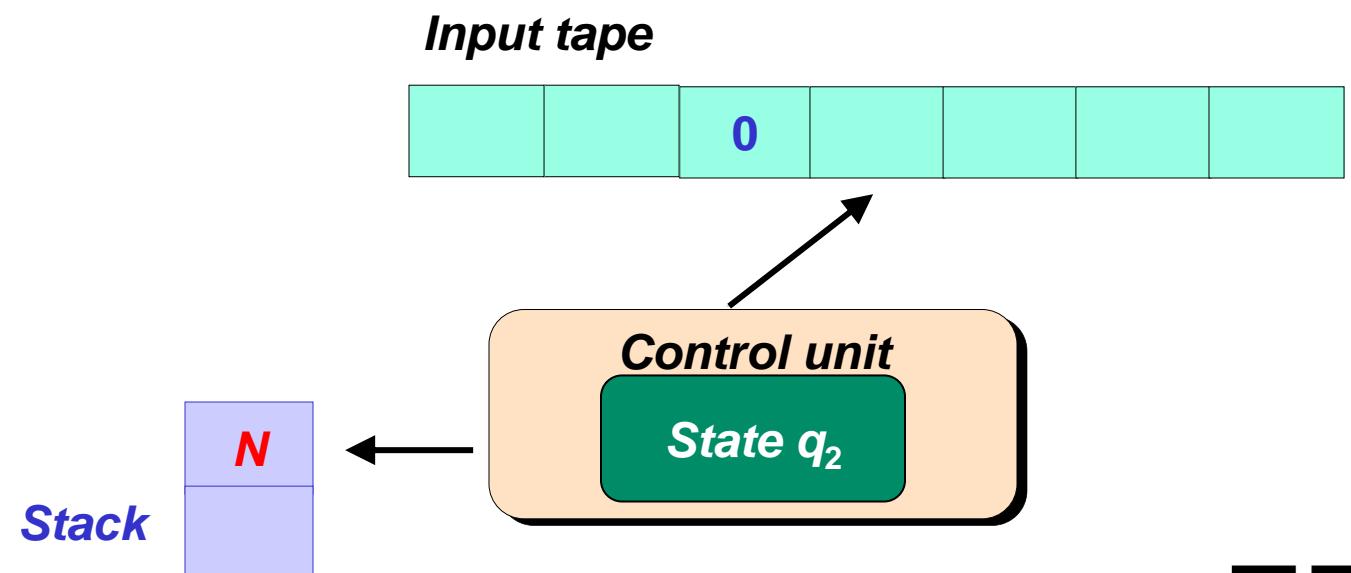
$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

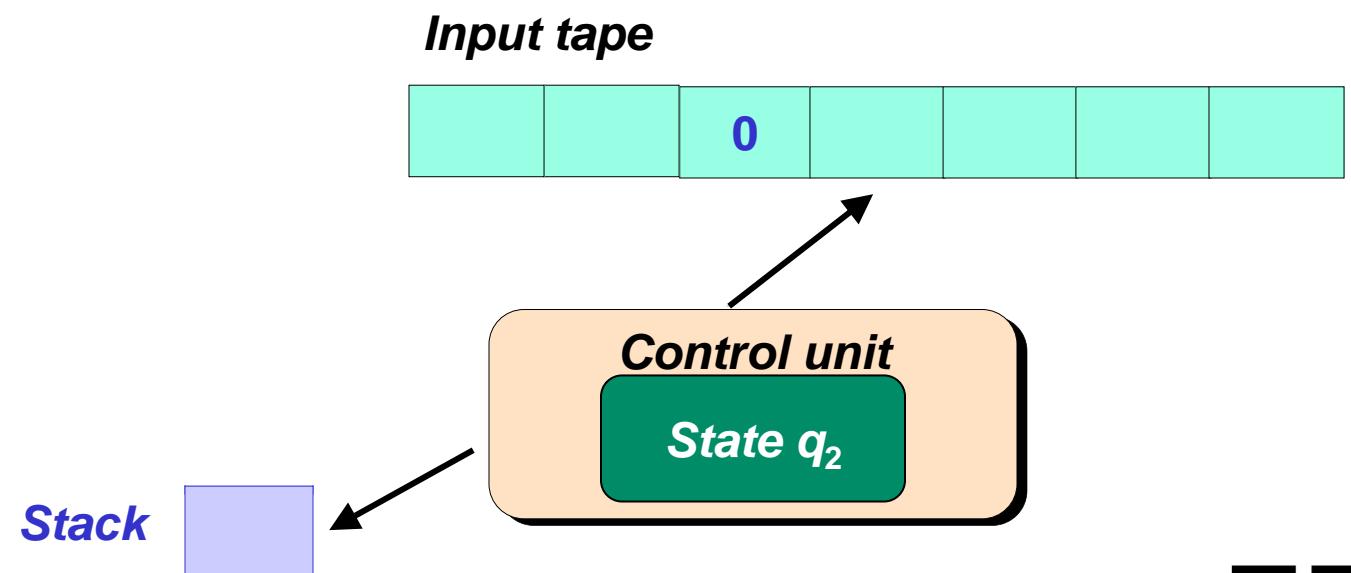
$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

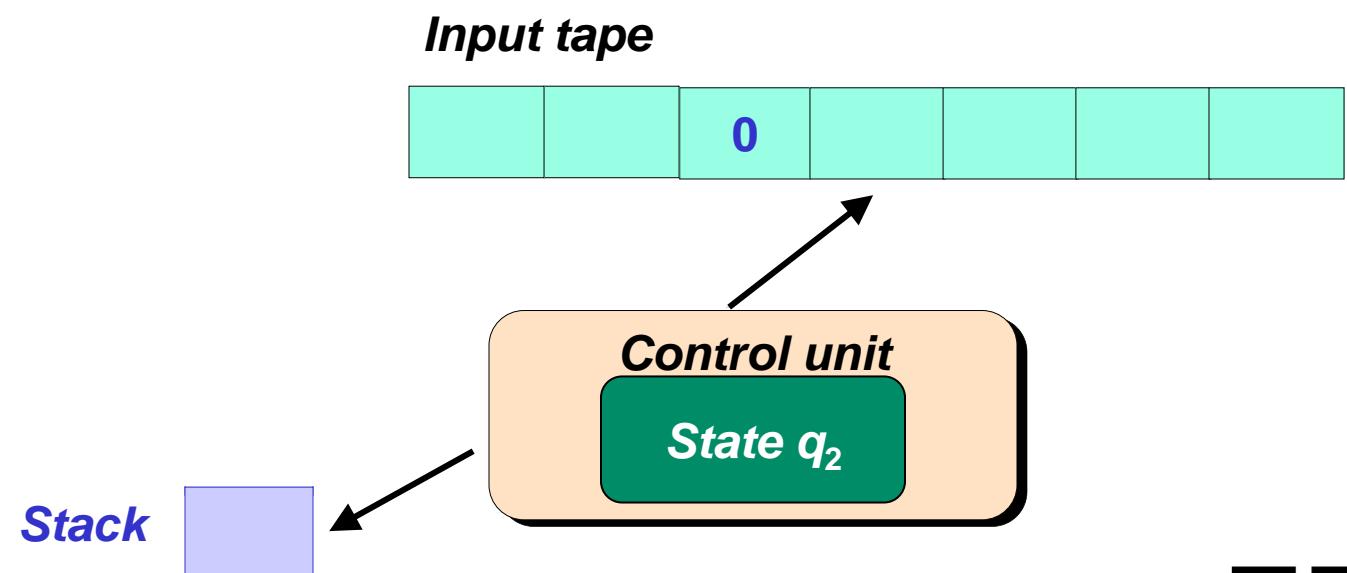
$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

PA  $M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$

1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$

2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$

3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$

4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$

5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

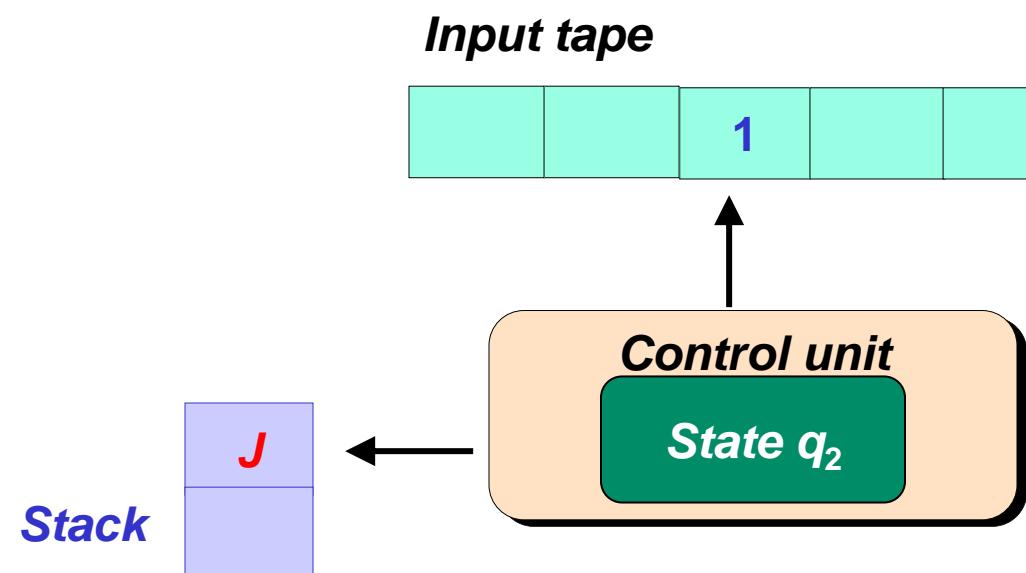
6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$

7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$

10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$

8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$

9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

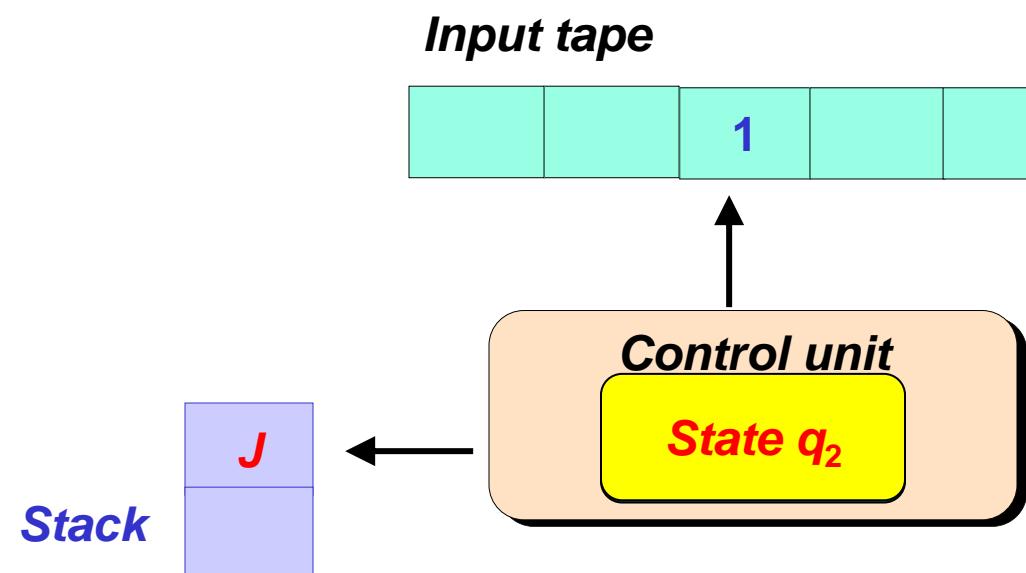
$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

PA  $M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$

1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$

2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$

3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$

4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$

5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

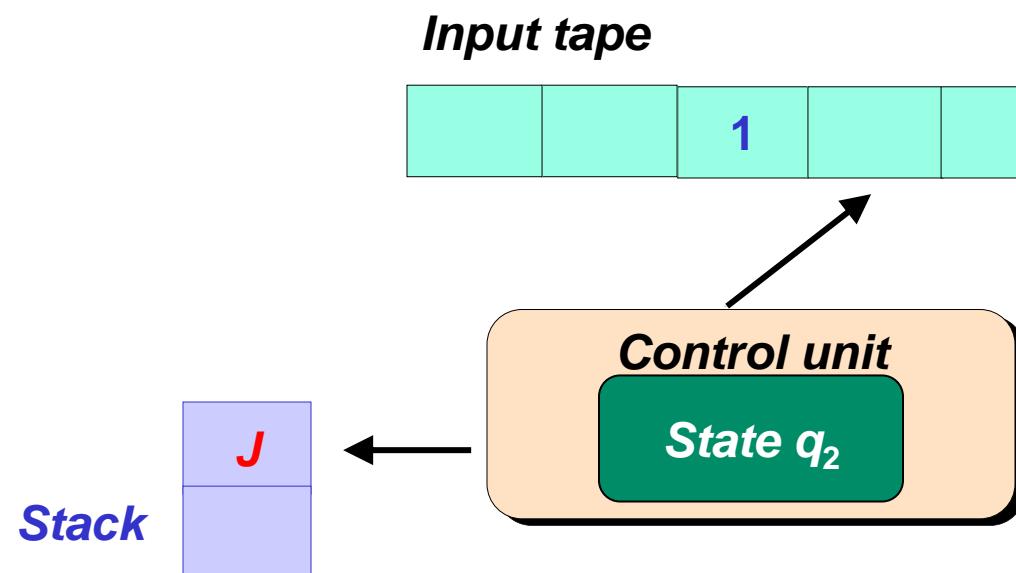
6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$

7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$

10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$

8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$

9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

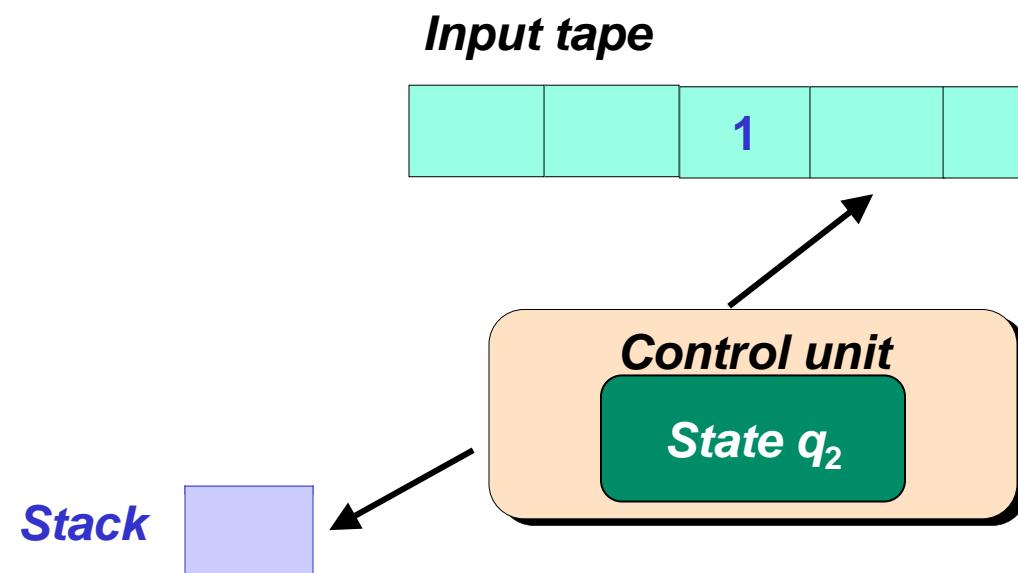
$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

PA  $M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$

1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$

2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$

3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$

4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$

5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$

6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$

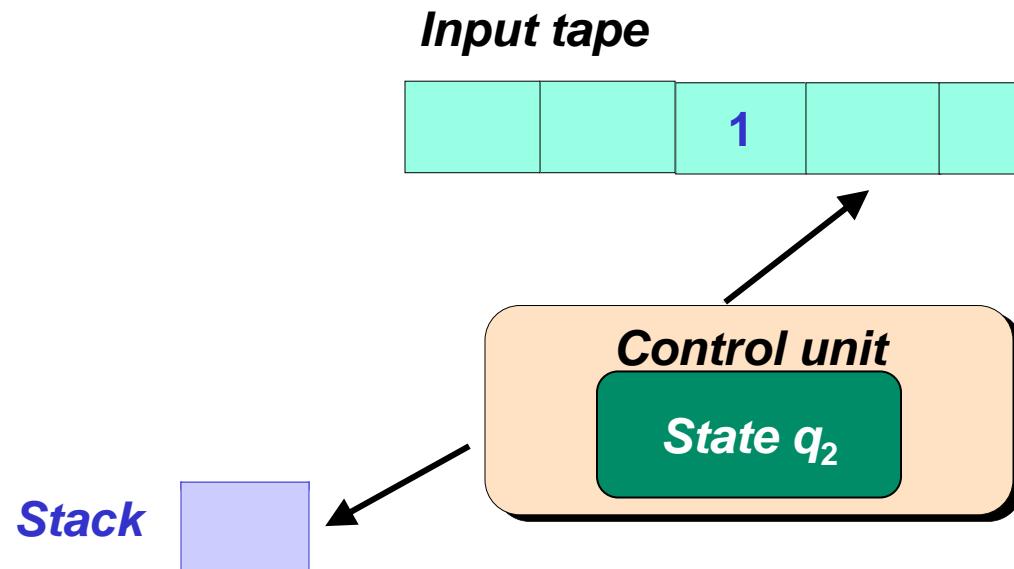
7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$

10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$

8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$

11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$

9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

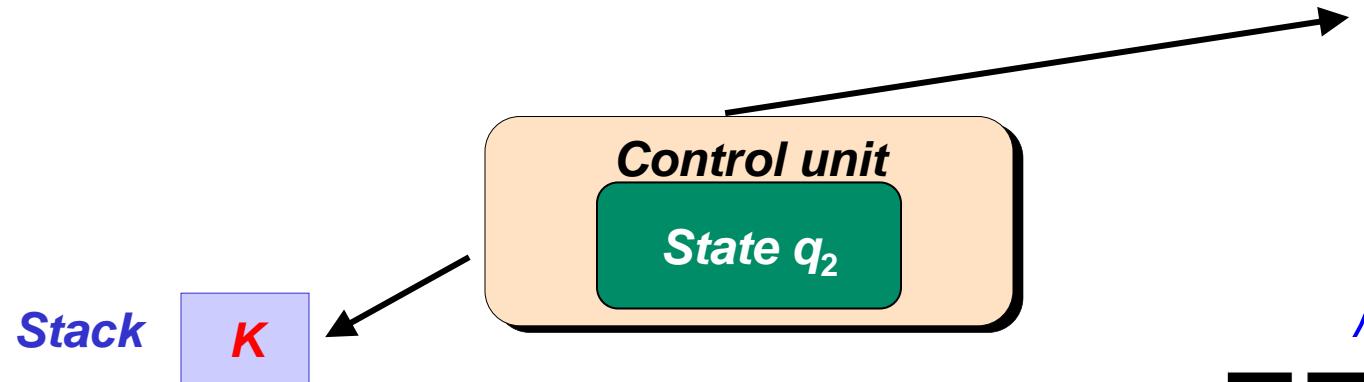
$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

*Input tape*



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

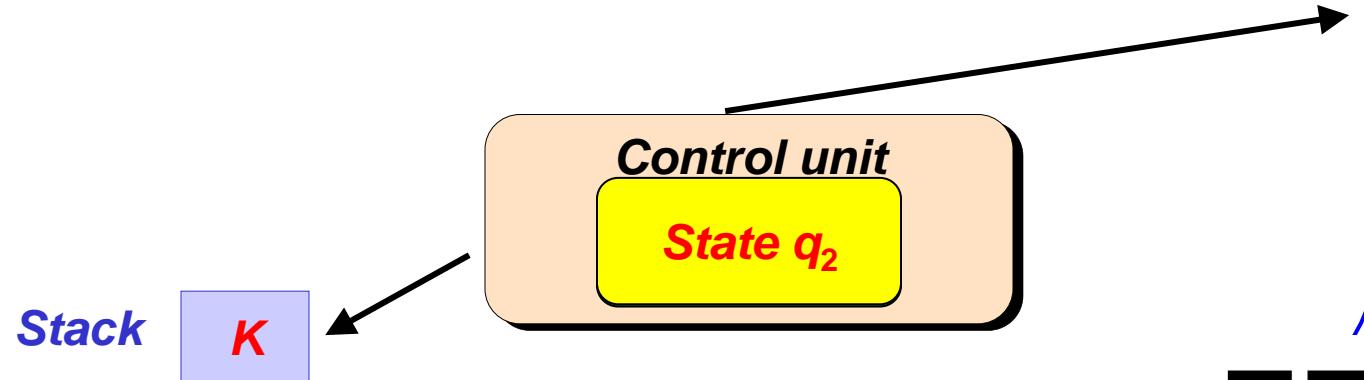
$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

*Input tape*



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

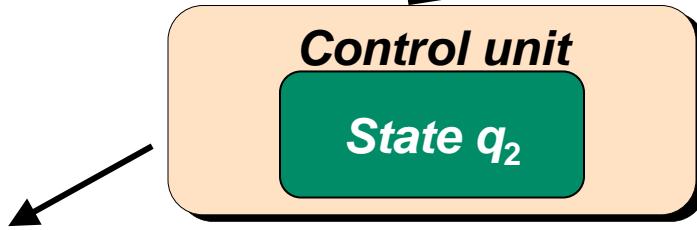
$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

*Input tape*



*Stack*



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

*Input tape*



*Stack*



# PA Definition

$$L(M_1) = \{ w 2 w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

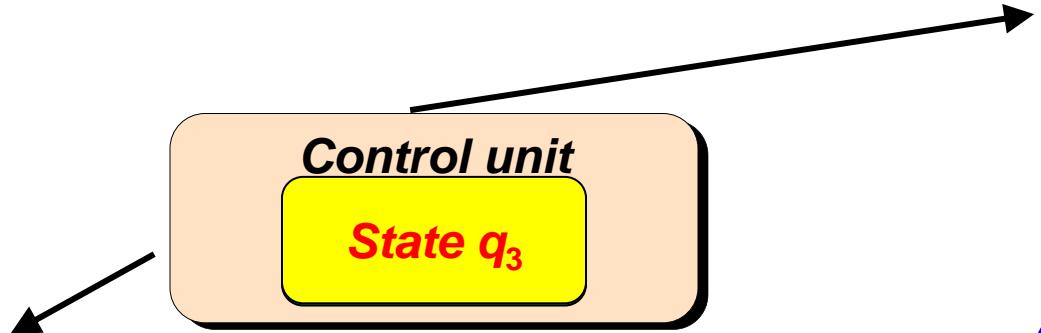
$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$$

*Input tape*



*Stack*





- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
-

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 

<b>State</b>	<i>Remaining input</i>	<b>Stack</b>	<i>Transition</i>
--------------	----------------------------	--------------	-------------------

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 

<b>State</b>	<i>Remaining input</i>	<b>Stack</b>	<i>Transition</i>
$q_1$	0012100	K	

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 

<i>State</i>	<i>Remaining input</i>	<i>Stack</i>	<i>Transition</i>
$q_1$	0012100	K	

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 

<b>State</b>	<i>Remaining input</i>	<b>Stack</b>	<i>Transition</i>
$q_1$	0012100	K	

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 

<i>State</i>	<i>Remaining input</i>	<i>Stack</i>	<i>Transition</i>
$q_1$	0012100	K	

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 

<b>State</b>	<i>Remaining input</i>	<b>Stack</b>	<i>Transition</i>
$q_1$	0012100	K	

- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |

<i>State</i>	<i>Remaining input</i>	<i>Stack</i>	<i>Transition</i>
$q_1$	0012100	K	$\delta(q_1, 0, K) = \{(q_1, NK)\}$

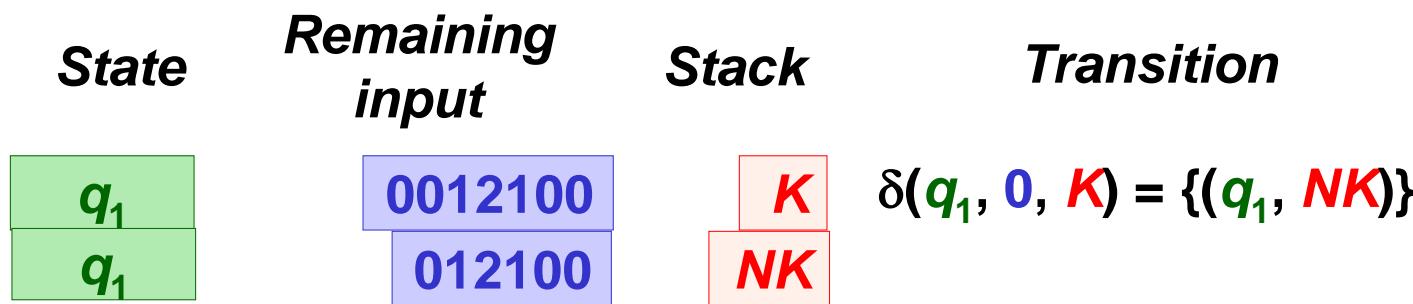
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 

<i>State</i>	<i>Remaining input</i>	<i>Stack</i>	<i>Transition</i>
			$\delta(q_1, 0, K) = \{(q_1, NK)\}$

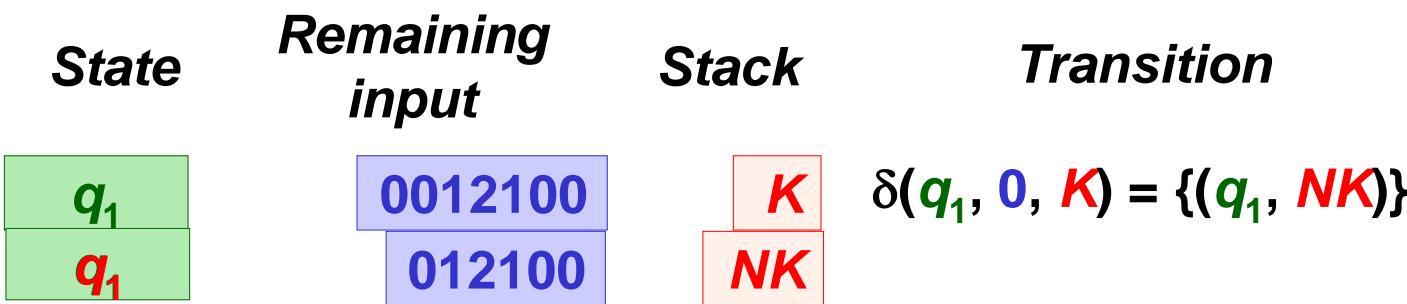
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |

<i>State</i>	<i>Remaining input</i>	<i>Stack</i>	<i>Transition</i>
$q_1$ $q_1$	0012100 012100	K	$\delta(q_1, 0, K) = \{(q_1, NK)\}$

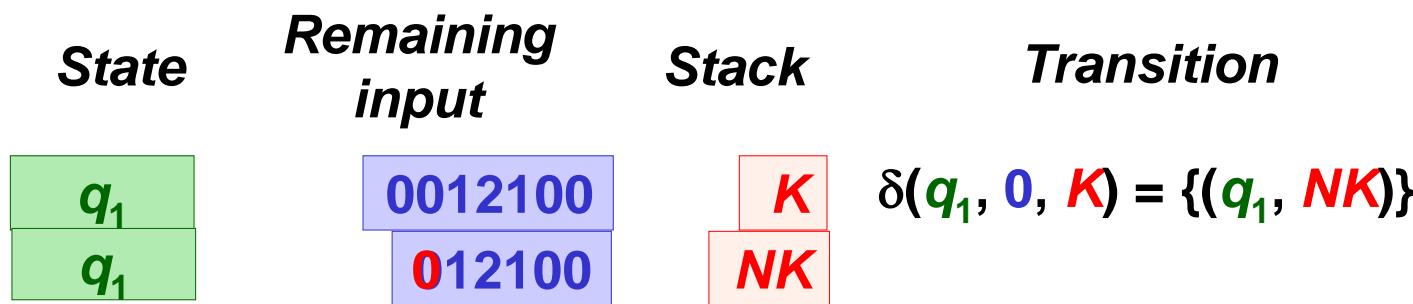
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 



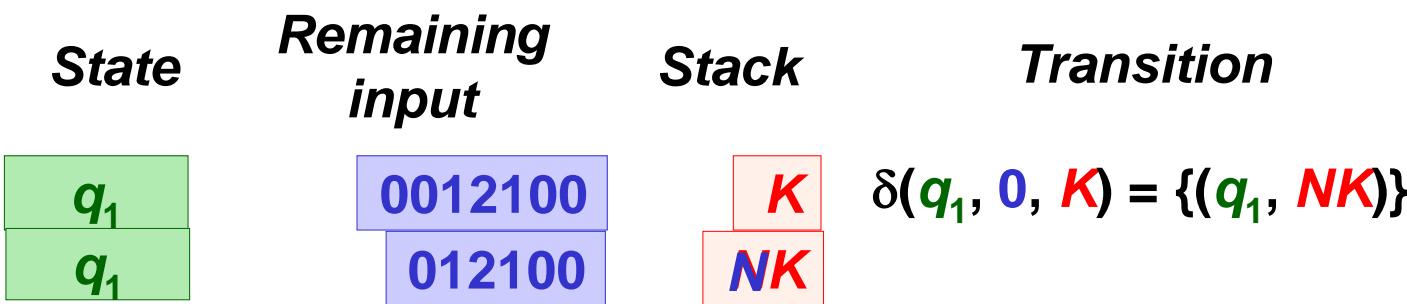
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



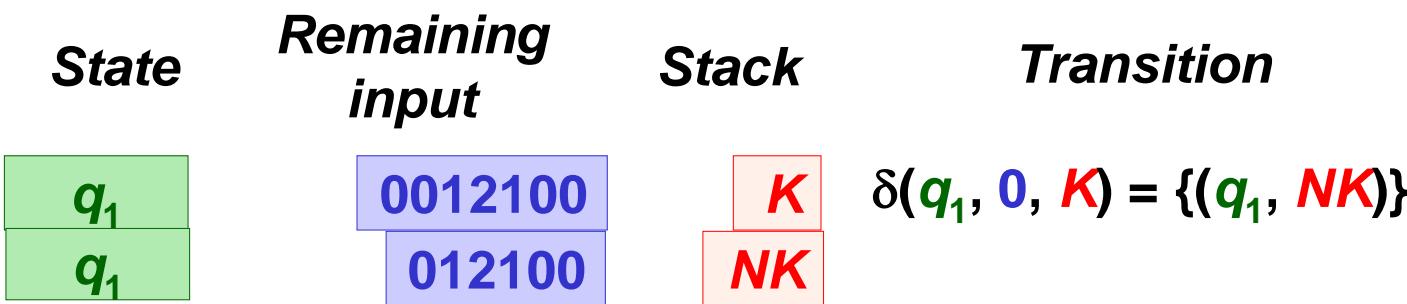
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 



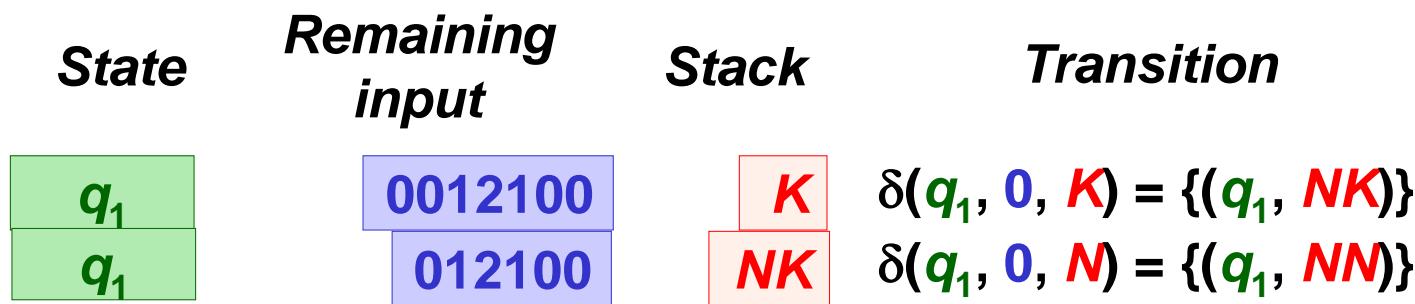
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



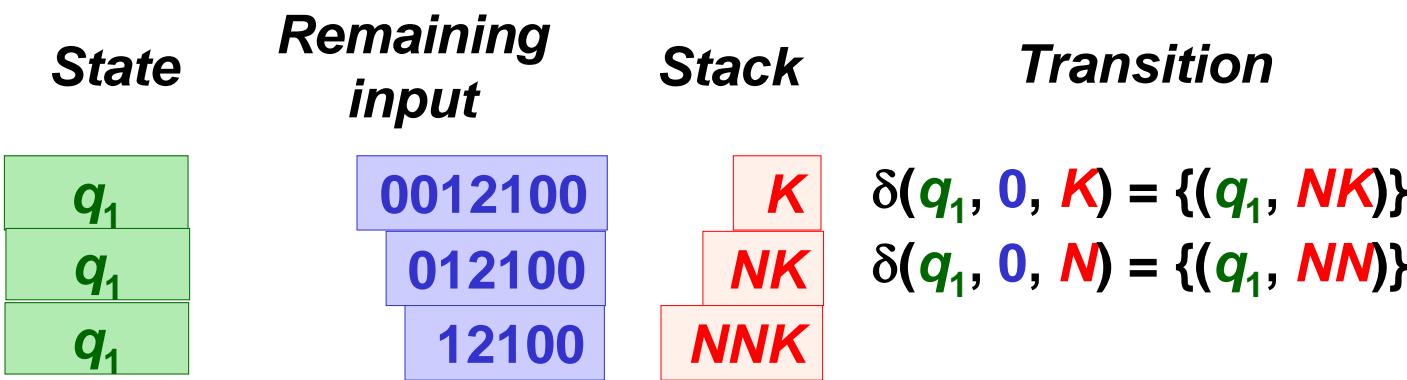
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



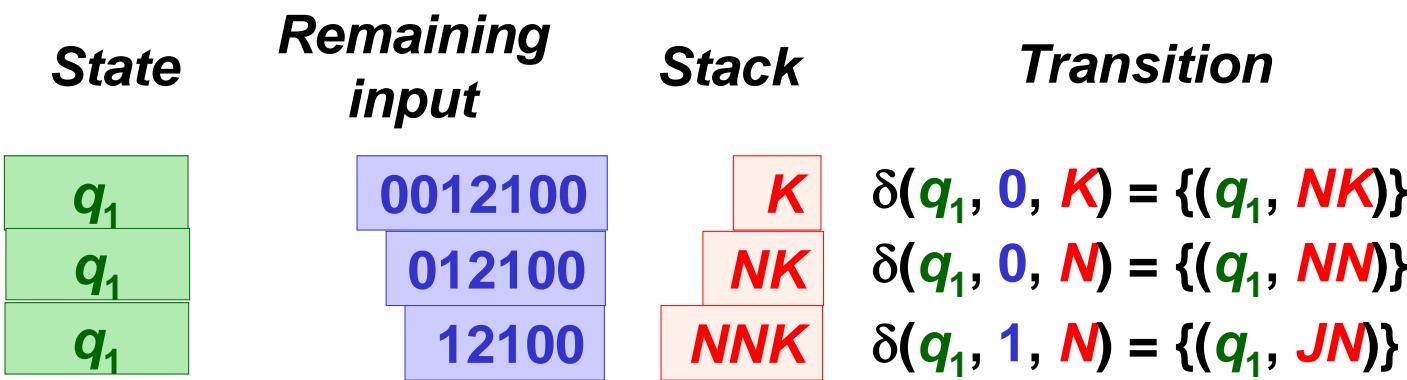
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 



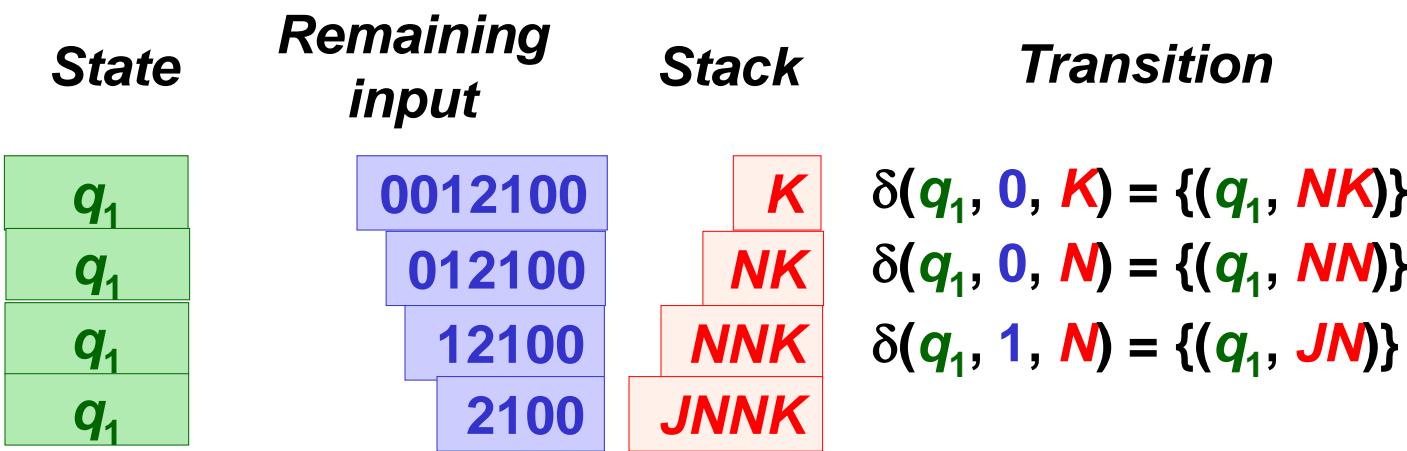
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 



- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 



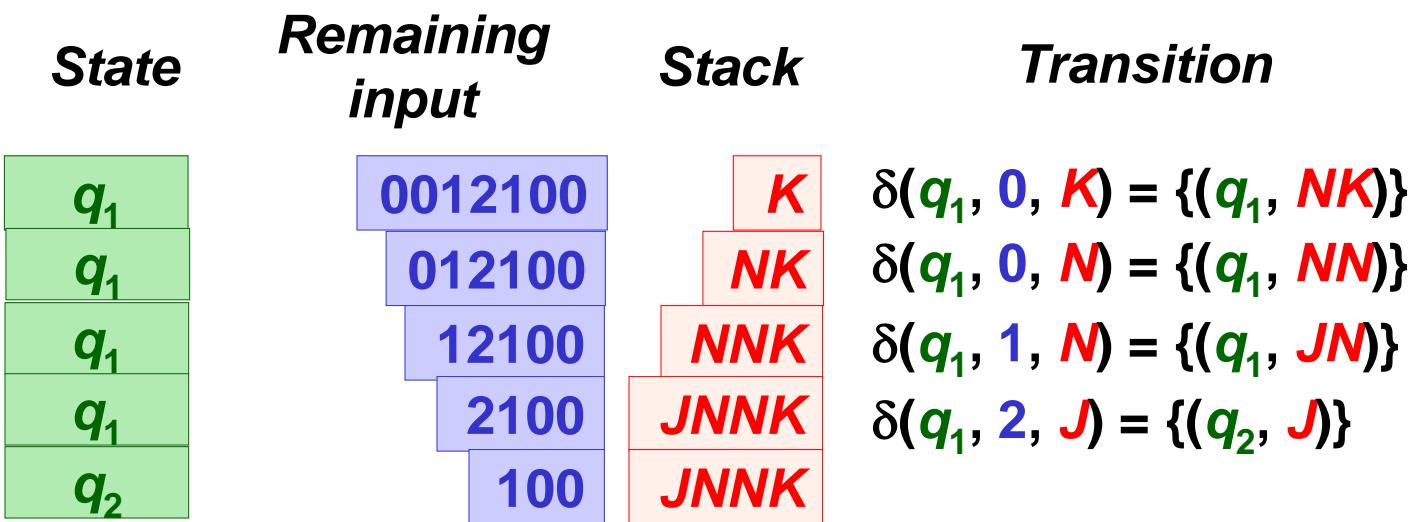
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |
- 



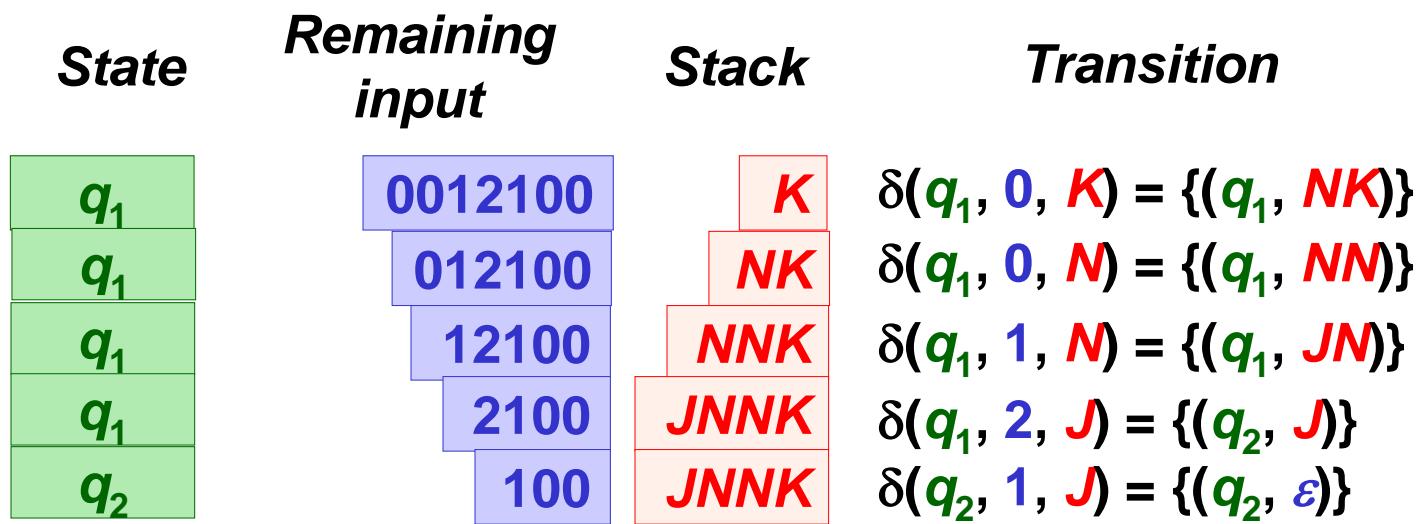
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |

<i>State</i>	<i>Remaining input</i>	<i>Stack</i>	<i>Transition</i>
$q_1$	0012100	$K$	$\delta(q_1, 0, K) = \{(q_1, NK)\}$
$q_1$	012100	$NK$	$\delta(q_1, 0, N) = \{(q_1, NN)\}$
$q_1$	12100	$NNK$	$\delta(q_1, 1, N) = \{(q_1, JN)\}$
$q_1$	2100	$JNNK$	$\delta(q_1, 2, J) = \{(q_2, J)\}$

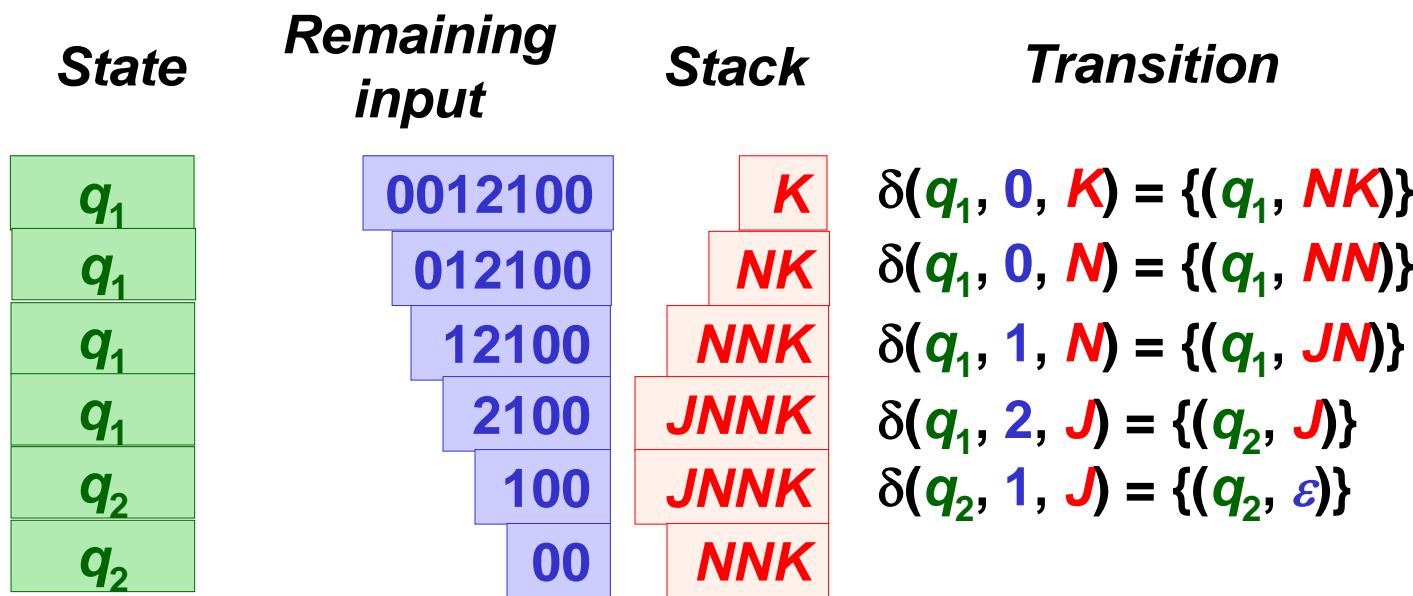
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



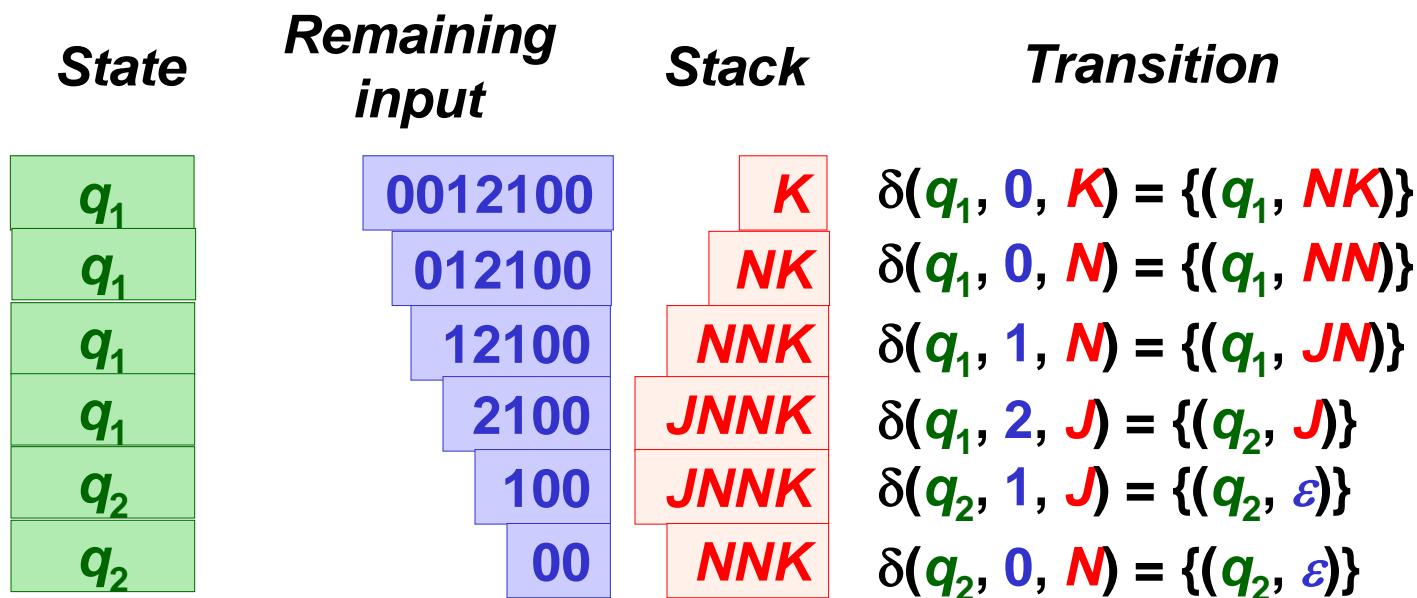
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



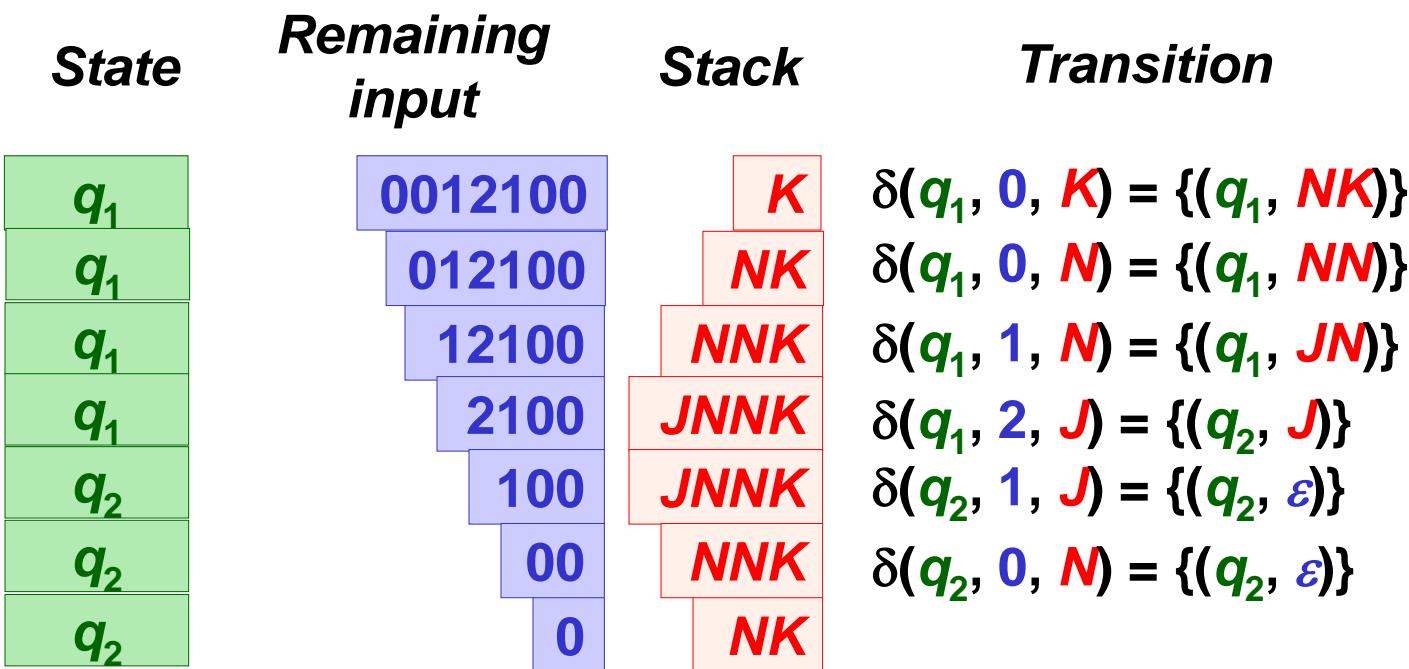
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



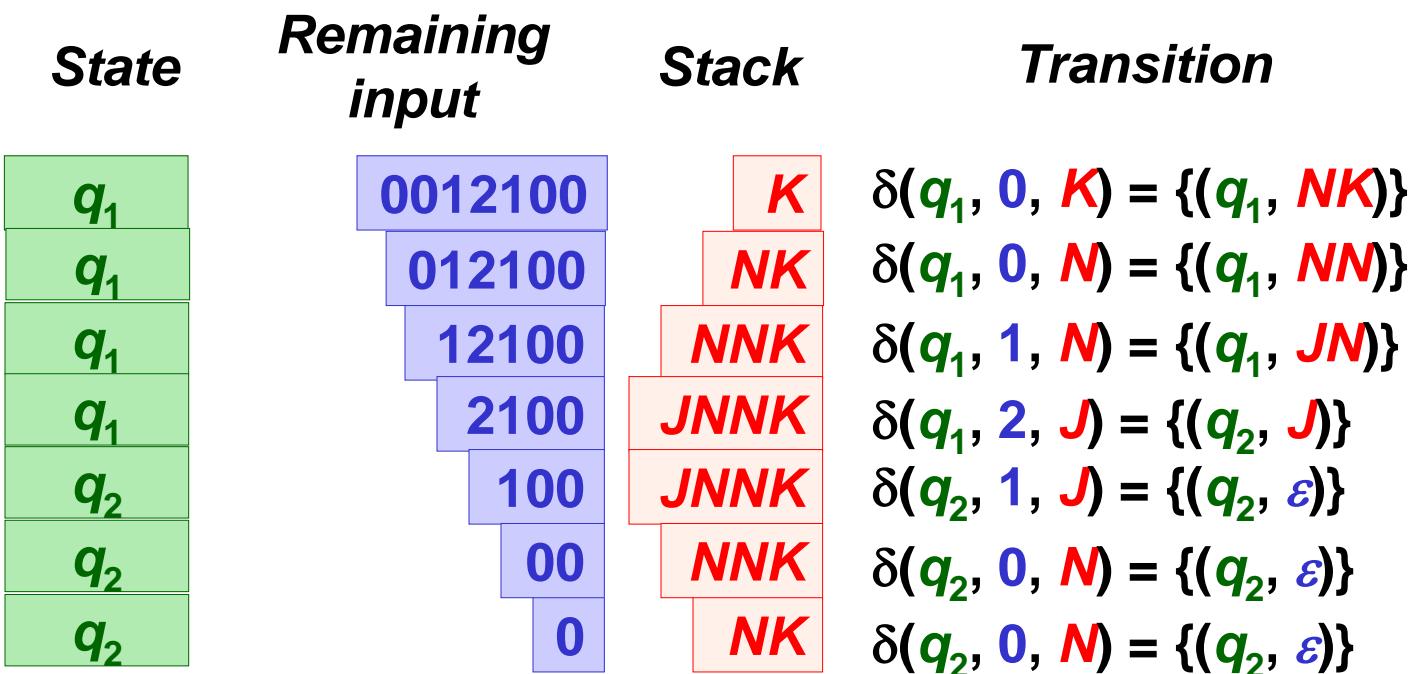
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



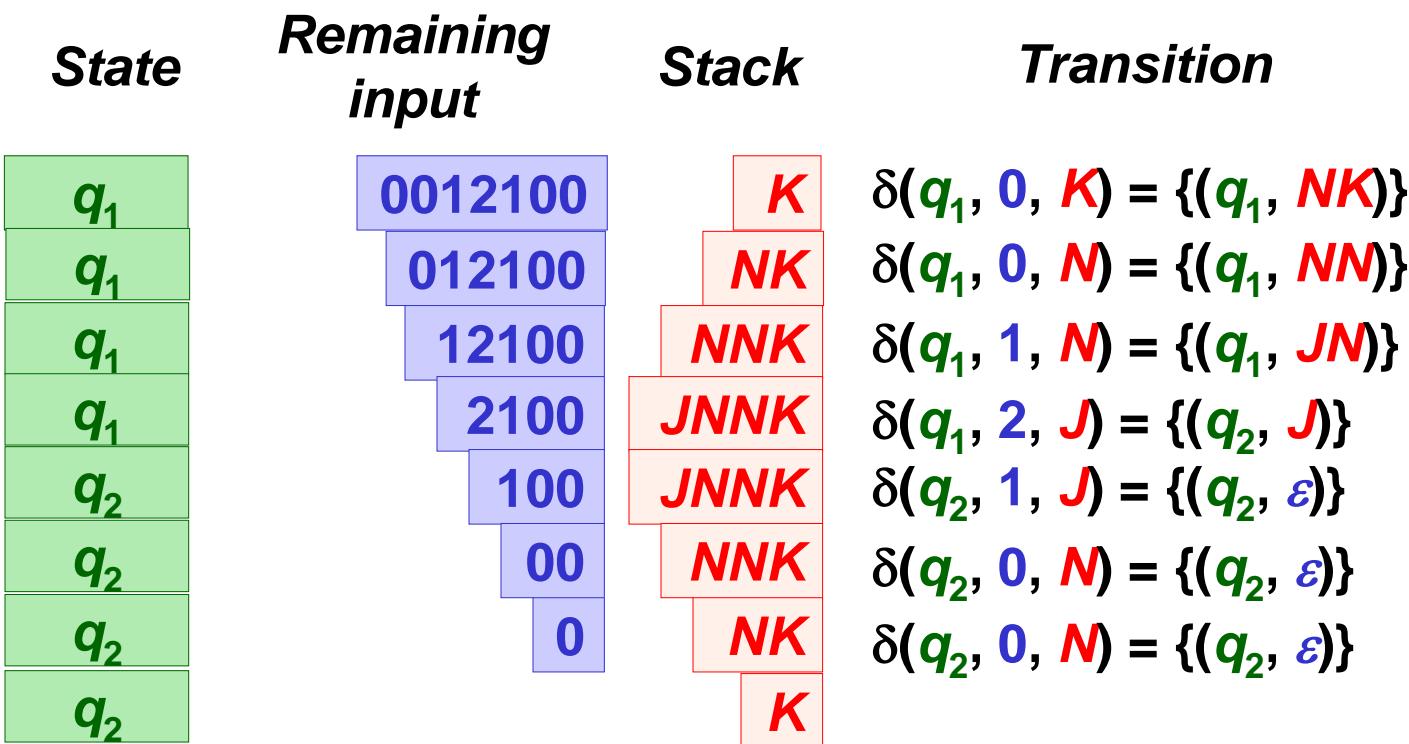
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



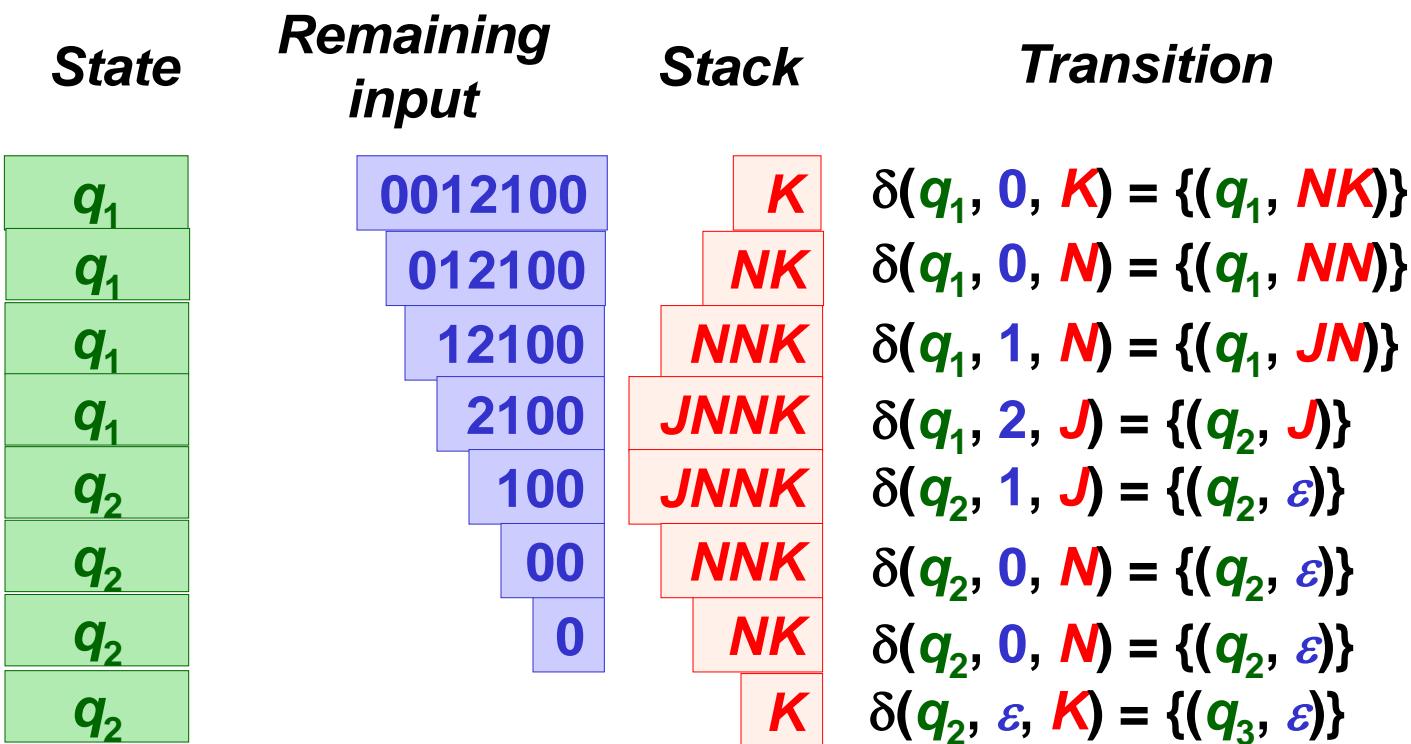
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



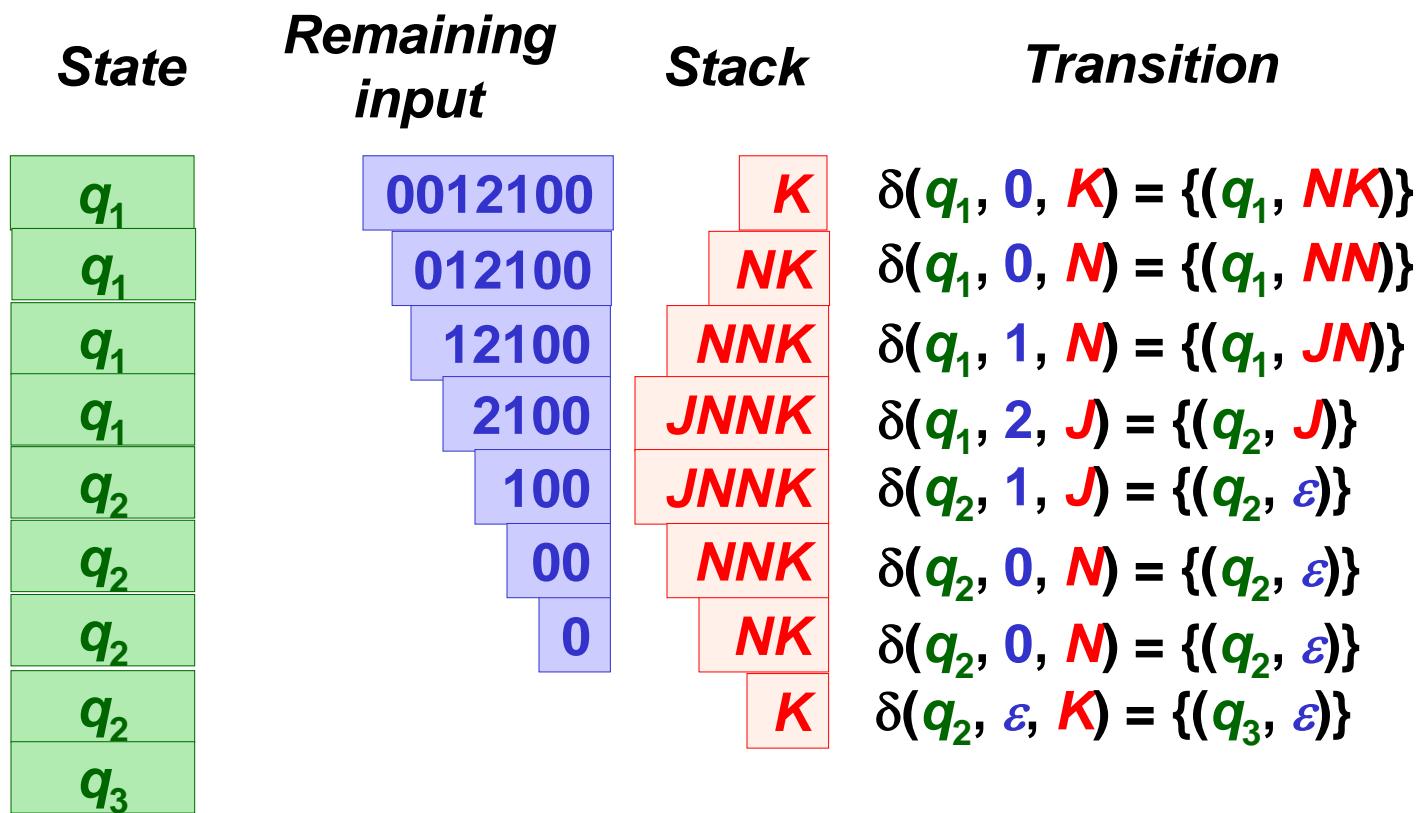
- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |



- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |

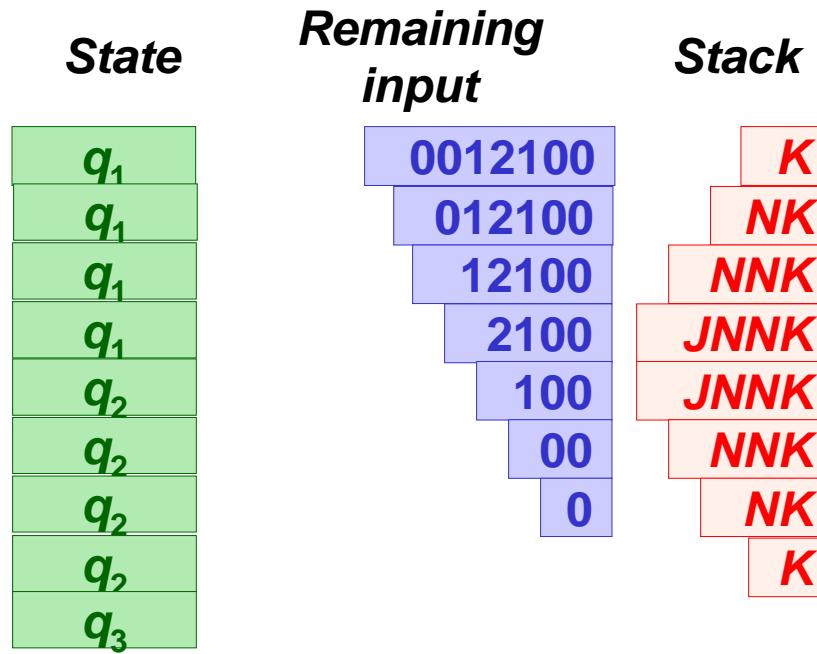


- |  |  |
|--|--|
| 1) $\delta(q_1, 0, K) = \{(q_1, NK)\}$ | 2) $\delta(q_1, 1, K) = \{(q_1, JK)\}$                     |
| 3) $\delta(q_1, 0, N) = \{(q_1, NN)\}$ | 4) $\delta(q_1, 1, N) = \{(q_1, JN)\}$                     |
| 5) $\delta(q_1, 0, J) = \{(q_1, NJ)\}$ | 6) $\delta(q_1, 1, J) = \{(q_1, JJ)\}$                     |
| 7) $\delta(q_1, 2, K) = \{(q_2, K)\}$  | 10) $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$           |
| 8) $\delta(q_1, 2, N) = \{(q_2, N)\}$  | 11) $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$           |
| 9) $\delta(q_1, 2, J) = \{(q_2, J)\}$  | 12) $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$ |

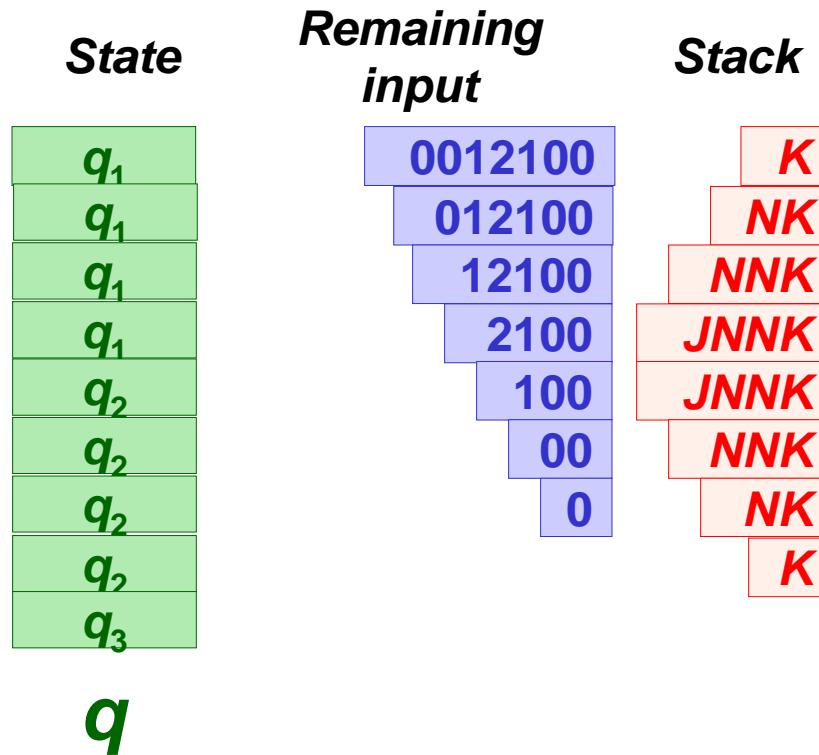
<i>State</i>	<i>Remaining input</i>	<i>Stack</i>	<i>Transition</i>
$q_1$	0012100	K	$\delta(q_1, 0, K) = \{(q_1, NK)\}$
$q_1$	012100	NK	$\delta(q_1, 0, N) = \{(q_1, NN)\}$
$q_1$	12100	NNK	$\delta(q_1, 1, N) = \{(q_1, JN)\}$
$q_1$	2100	JNNK	$\delta(q_1, 2, J) = \{(q_2, J)\}$
$q_2$	100	JNNK	$\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
$q_2$	00	NNK	$\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
$q_2$	0	NK	$\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
$q_2$		K	$\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$
$q_3$			$q_3 \in F$ and string is not accepted

# Instantaneous Descriptions of PA

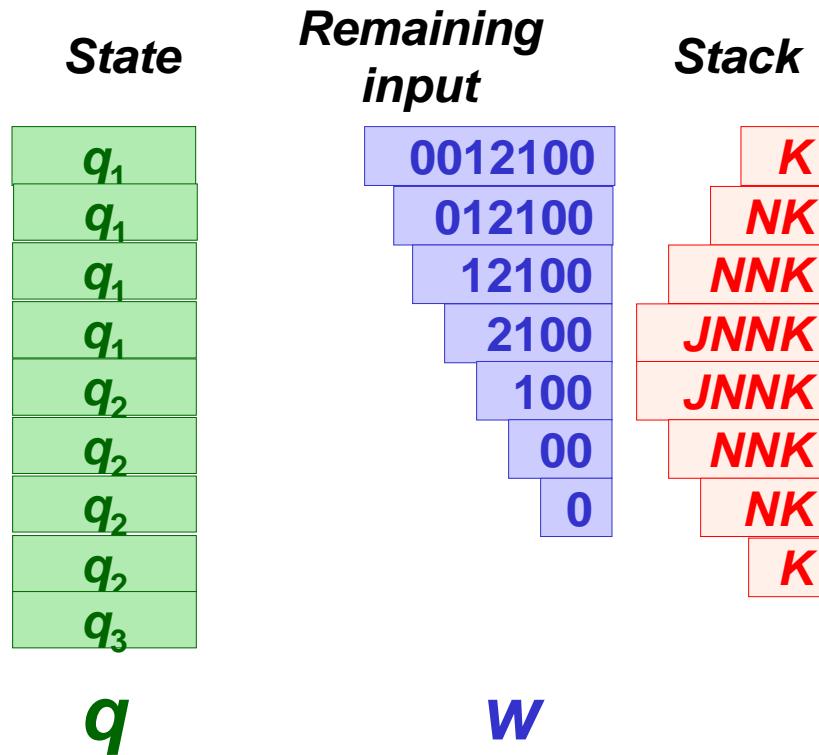
# Instantaneous Descriptions of PA



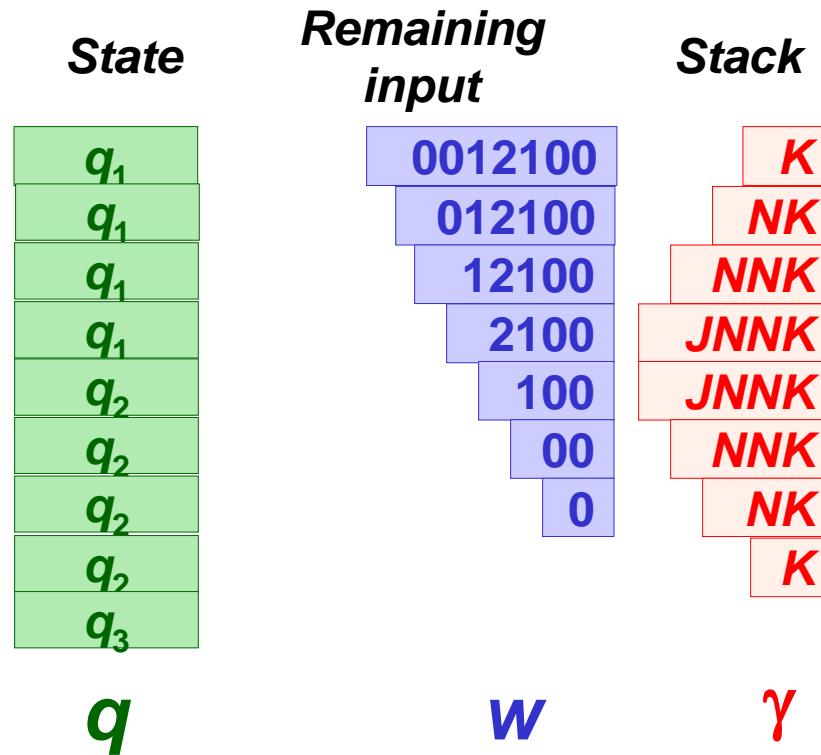
# Instantaneous Descriptions of PA



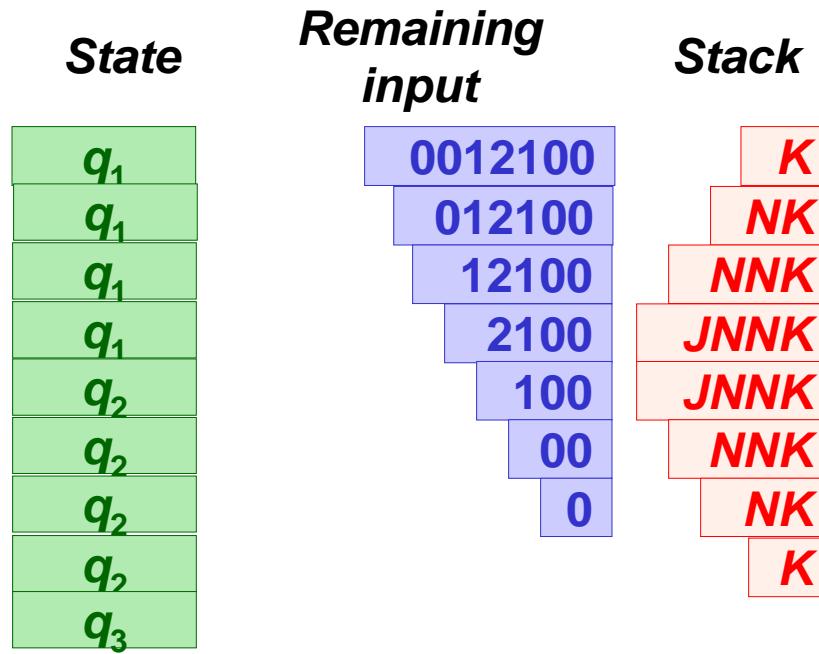
# Instantaneous Descriptions of PA



# Instantaneous Descriptions of PA

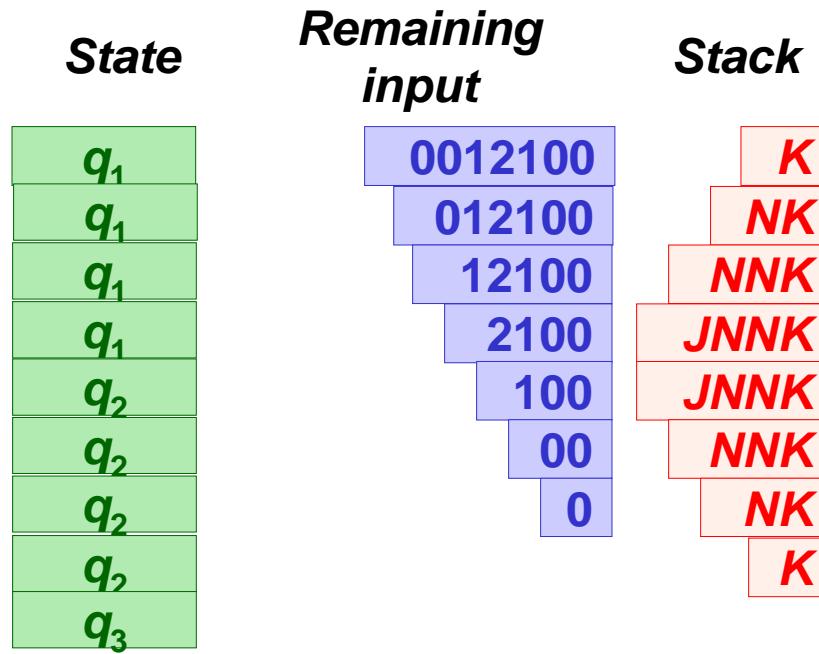


# Instantaneous Descriptions of PA



$(q, w, \gamma)$

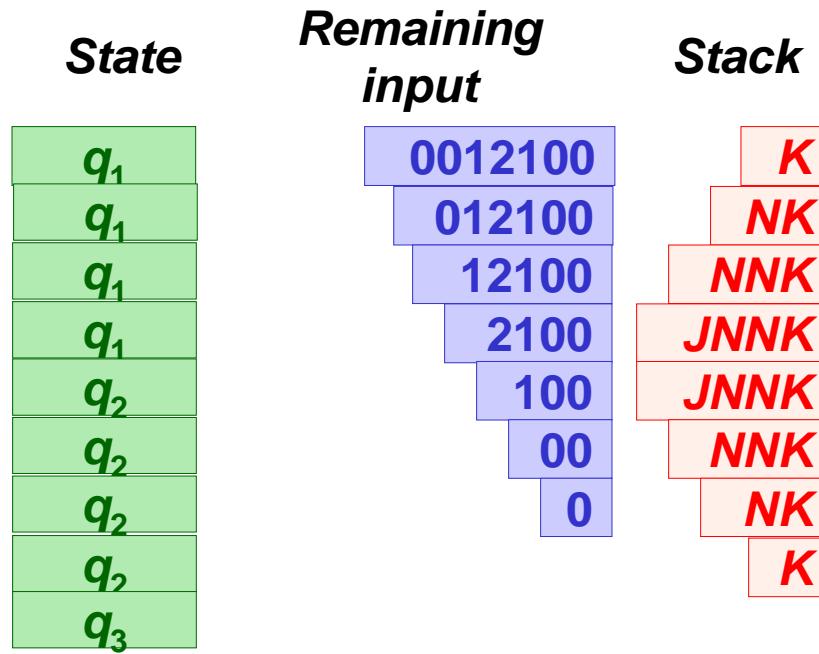
# Instantaneous Descriptions of PA



$(q, w, \gamma)$

$(q, aw, Z\alpha)$

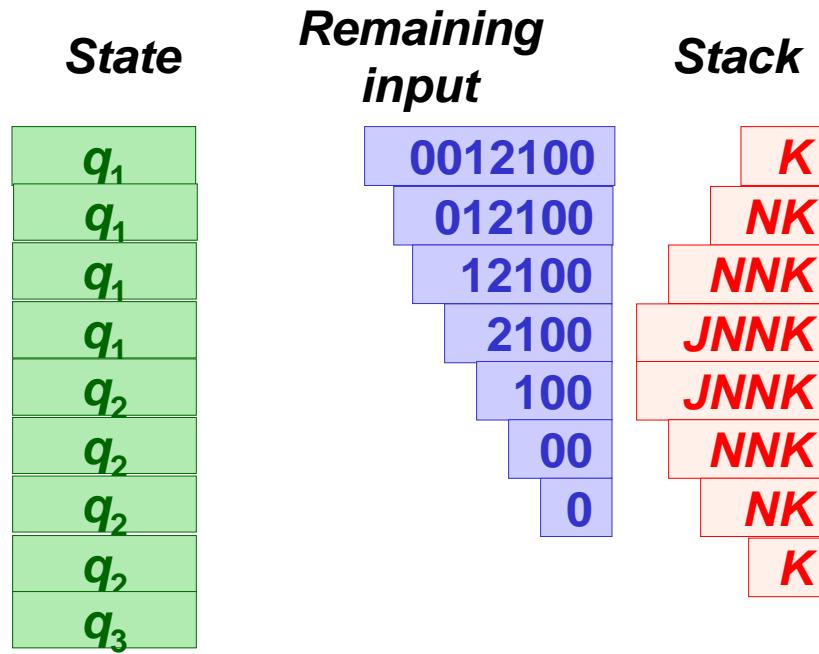
# Instantaneous Descriptions of PA



$(q, w, \gamma)$

$(q, aw, z\alpha) \succ_M$

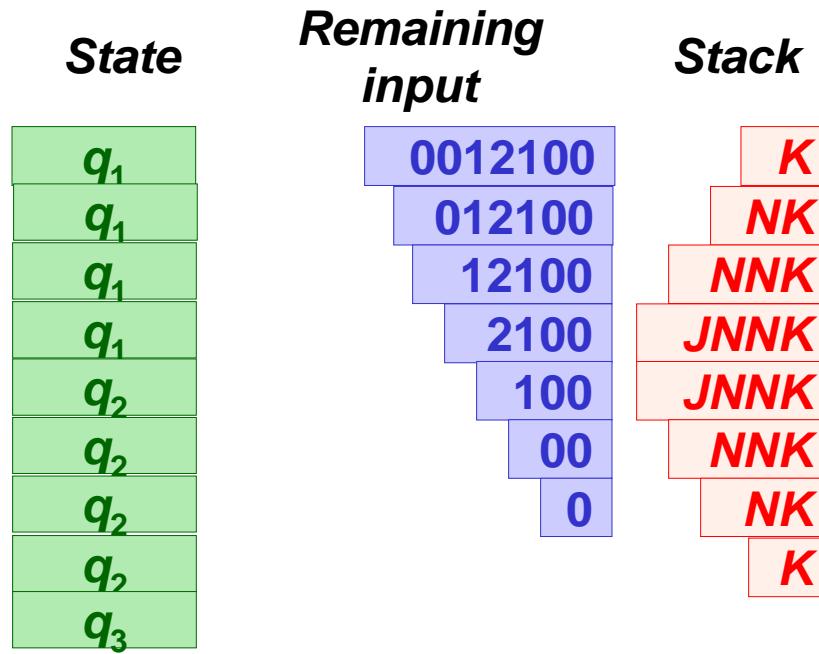
# Instantaneous Descriptions of PA



$(q, w, \gamma)$

$(q, aw, Z\alpha) \xrightarrow[M]{} (p, w, \beta\alpha)$

# Instantaneous Descriptions of PA

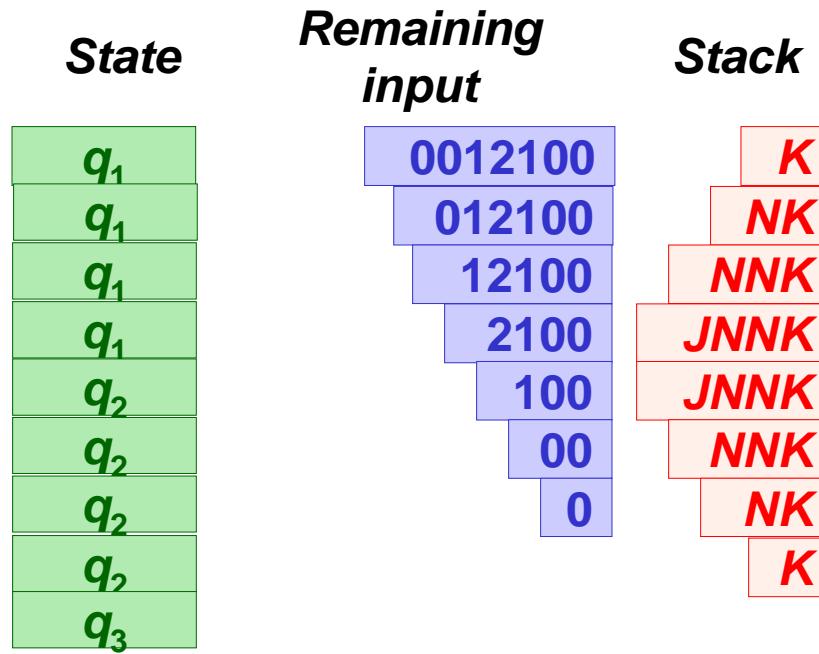


$(q, w, \gamma)$

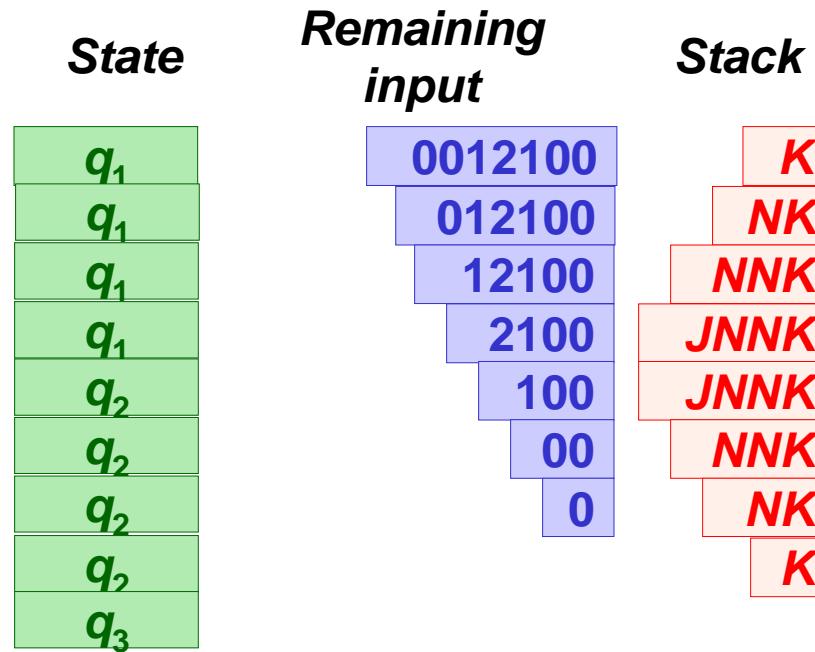
$$(q, aw, Z\alpha) \underset{M}{\succ} (p, w, \beta\alpha)$$

if and only if  $(p, \beta) \in \delta(q, a, Z)$

# Instantaneous Descriptions of PA

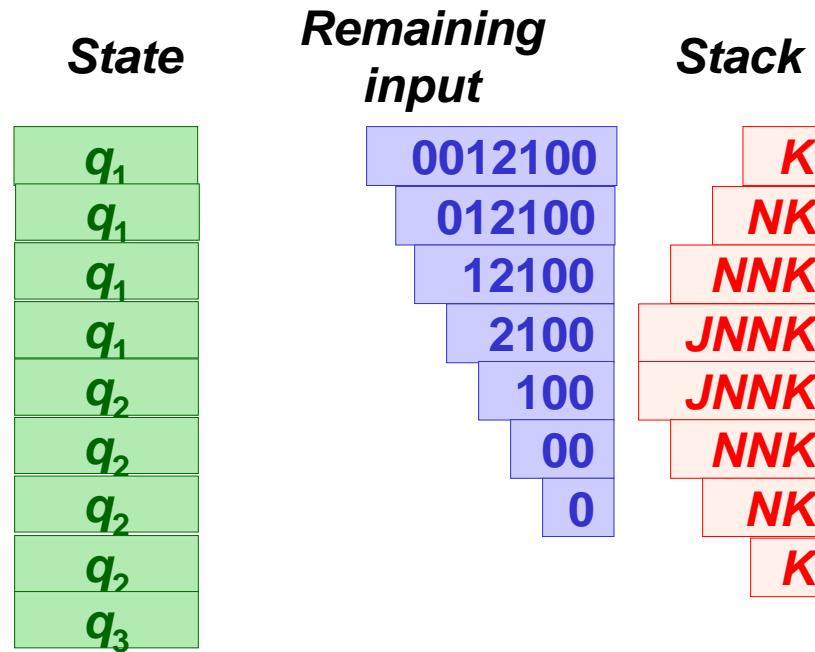


# Instantaneous Descriptions of PA



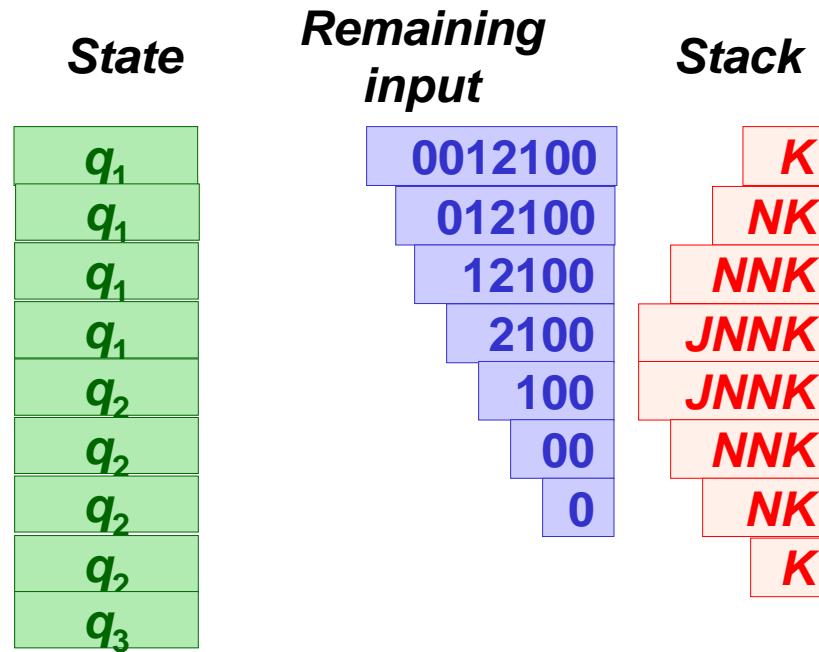
$(q_1, 0012100, K) \succ (q_1, 012100, NK) \succ (q_1, 12100, NNK) \succ (q_1, 2100, JNNK) \succ$

# Instantaneous Descriptions of PA



$(q_1, 0012100, K) \succ (q_1, 012100, NK) \succ (q_1, 12100, NNK) \succ (q_1, 2100, JNNK) \succ (q_2, 100, JNNK) \succ (q_2, 00, NNK) \succ (q_2, 0, NK) \succ (q_2, \varepsilon, K) \succ (q_3, \varepsilon, \varepsilon)$

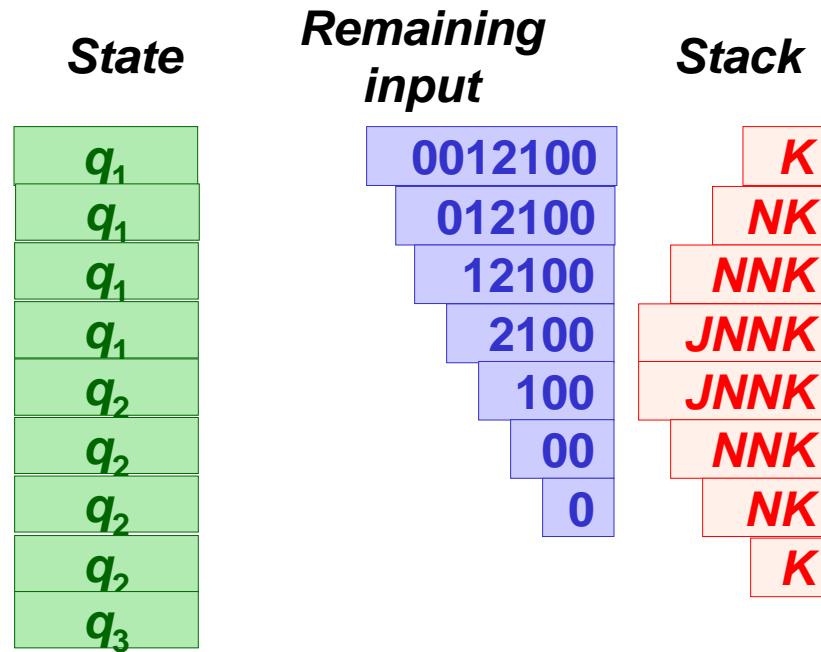
# Instantaneous Descriptions of PA



$(q_1, 0012100, K) \succ (q_1, 012100, NK) \succ (q_1, 12100, NNK) \succ (q_1, 2100, JNNK) \succ (q_2, 100, JNNK) \succ (q_2, 00, NNK) \succ (q_2, 0, NK) \succ (q_2, \varepsilon, K) \succ (q_3, \varepsilon, \varepsilon)$

$(q_1, 0012100, K)$

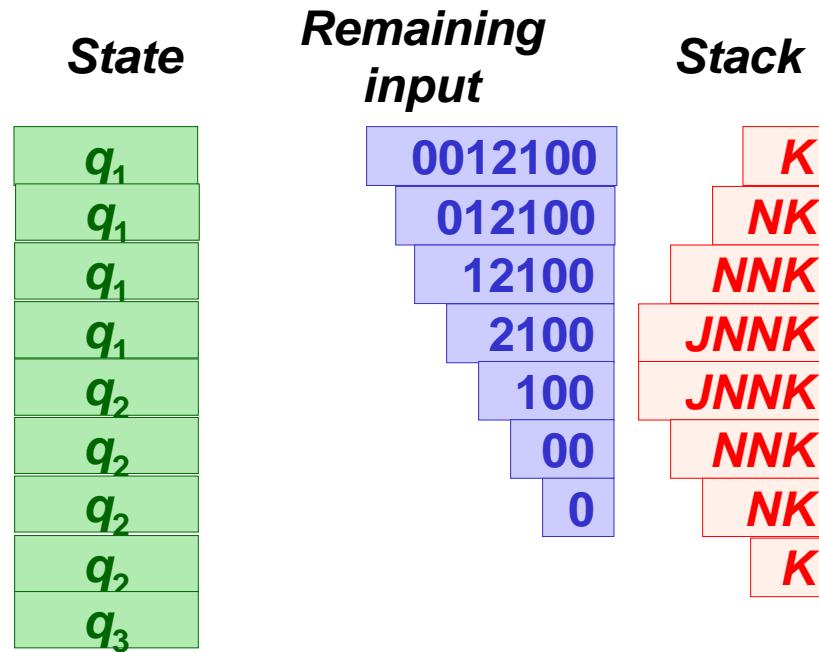
# Instantaneous Descriptions of PA



$(q_1, 0012100, K) \succ (q_1, 012100, NK) \succ (q_1, 12100, NNK) \succ (q_1, 2100, JNNK) \succ$   
 $(q_2, 100, JNNK) \succ (q_2, 00, NNK) \succ (q_2, 0, NK) \succ (q_2, \varepsilon, K) \succ (q_3, \varepsilon, \varepsilon)$

$$(q_1, 0012100, K) \xrightarrow[M]{*}$$

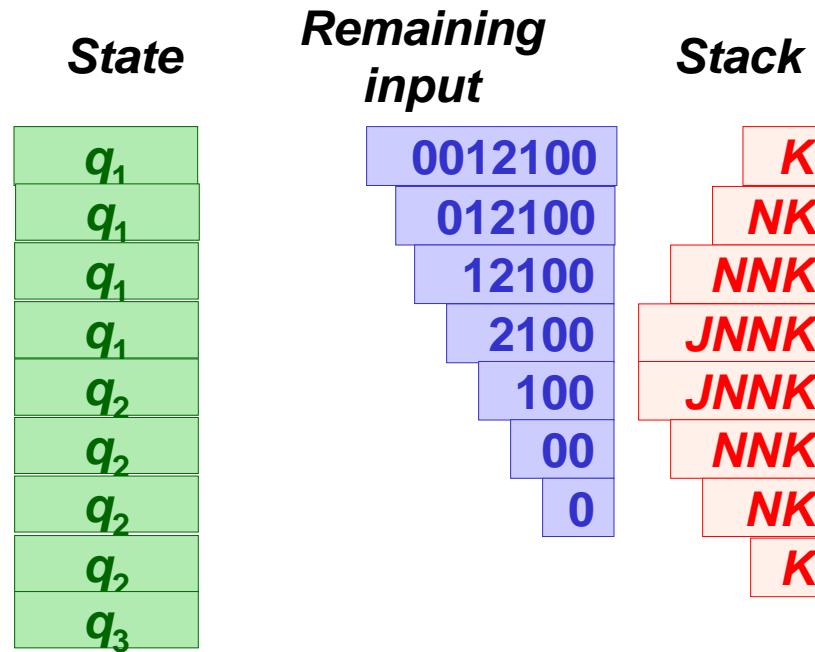
# Instantaneous Descriptions of PA



$(q_1, 0012100, K) \succ (q_1, 012100, NK) \succ (q_1, 12100, NNK) \succ (q_1, 2100, JNNK) \succ$   
 $(q_2, 100, JNNK) \succ (q_2, 00, NNK) \succ (q_2, 0, NK) \succ (q_2, \varepsilon, K) \succ (q_3, \varepsilon, \varepsilon)$

$$(q_1, 0012100, K) \xrightarrow[M]{*} (q_3, \varepsilon, \varepsilon)$$

# Instantaneous Descriptions of PA



$(q_1, 0012100, K) \succ (q_1, 012100, NK) \succ (q_1, 12100, NNK) \succ (q_1, 2100, JNNK) \succ$   
 $(q_2, 100, JNNK) \succ (q_2, 00, NNK) \succ (q_2, 0, NK) \succ (q_2, \varepsilon, K) \succ (q_3, \varepsilon, \varepsilon)$

$$(q_1, 0012100, K) \xrightarrow[M]{*} (q_3, \varepsilon, \varepsilon)$$

$$(q_1, 0012100, K) \xrightarrow[M]{8} (q_3, \varepsilon, \varepsilon)$$

# Language Acceptance By PA

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by final state:**

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by final state:**

$L(M) = \{ w \mid (q_0, w, Z_0)$

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by final state:**

$L(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*}$

# Language Acceptance By PA

PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

acceptance by final state:

$L(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*} (p, \varepsilon, \gamma) \text{ for some state } p \in F \text{ i } \gamma \in \Gamma^* \}$

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by final state:**

$L(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*} (p, \varepsilon, \gamma) \text{ for some state } p \in F \text{ i } \gamma \in \Gamma^* \}$

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by final state:**

$L(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*} (p, \varepsilon, \gamma) \text{ for some state } p \in F \text{ i } \gamma \in \Gamma^* \}$

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by empty stack:**

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by final state:**

$L(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*} (p, \varepsilon, \gamma) \text{ for some state } p \in F \text{ i } \gamma \in \Gamma^* \}$

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by empty stack:**

$N(M) = \{ w \mid (q_0, w, Z_0)$

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by final state:**

$L(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*} (p, \varepsilon, \gamma) \text{ for some state } p \in F \text{ i } \gamma \in \Gamma^* \}$

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

**acceptance by empty stack:**

$N(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*} (\text{empty stack}) \}$

# Language Acceptance By PA

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

acceptance by final state:

$L(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*} (p, \varepsilon, \gamma) \text{ for some state } p \in F \text{ i } \gamma \in \Gamma^* \}$

**PA  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$**

acceptance by empty stack:

$N(M) = \{ w \mid (q_0, w, Z_0) \xrightarrow[M]{*} (p, \varepsilon, \varepsilon) \text{ for some state } p \in Q \}$



$$L(M_1) = \{ \quad w \quad 2 \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$
- 7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$
- 8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$
- 9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$
- 7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$
- 8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$
- 9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$
- 7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$
- 8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$
- 9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, \boxed{q_3}\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$
- 7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$
- 8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$
- 9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, \boxed{q_3}\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, \boxed{q_3}\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, \boxed{q_3}\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$
- 7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$
- 8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$
- 9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, \boxed{q_3}\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ)\}$
- 7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$
- 8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$
- 9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, \boxed{q_3}\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 7)  $\delta(q_1, 2, K) = \{(q_2, K)\}$
- 8)  $\delta(q_1, 2, N) = \{(q_2, N)\}$
- 9)  $\delta(q_1, 2, J) = \{(q_2, J)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, \boxed{q_3}\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$$

$$13) \quad \delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_3, \varepsilon)\}$$

$$L(M_1) = \{ \quad w \boxed{2} \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, \boxed{q_3}\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{ \boxed{q_3} \} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$$

$$13) \quad \delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$$

$$7) \quad \delta(q_1, 2, K) = \{(q_2, K)\}$$

$$8) \quad \delta(q_1, 2, N) = \{(q_2, N)\}$$

$$9) \quad \delta(q_1, 2, J) = \{(q_2, J)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{ \boxed{q_2} \varepsilon \})$$

# Nondeterminism

$$L(M_1) = \{ \quad w \quad \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$$

$$13) \quad \delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

# Nondeterminism

$$L(M_1) = \{ \quad w \quad \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$$

$$13) \quad \delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

# Nondeterminism

$$L(M_1) = \{ \quad w \quad \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$$

$$13) \quad \delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

# Nondeterminism

$$L(M_1) = \{ \quad w \quad \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$$

$$13) \quad \delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

# Nondeterminism

$$L(M_1) = \{ \quad w \quad \quad w^R \mid w \in (0+1)^* \}$$

$$\text{PA } M_1 = ( \{q_1, q_2, q_3\}, \{0, 1, 2\}, \{N, J, K\}, \delta, q_1, K, \{q_3\} )$$

$$1) \quad \delta(q_1, 0, K) = \{(q_1, NK)\}$$

$$3) \quad \delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$$

$$13) \quad \delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

$$5) \quad \delta(q_1, 0, J) = \{(q_1, NJ)\}$$

$$2) \quad \delta(q_1, 1, K) = \{(q_1, JK)\}$$

$$4) \quad \delta(q_1, 1, N) = \{(q_1, JN)\}$$

$$6) \quad \delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$$

$$10) \quad \delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$$

$$11) \quad \delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$$

$$12) \quad \delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$$

# Nondeterminism

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
  
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
  
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
  
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

$(q_1, 001100, K)$

## Nondeterminism

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
  
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
  
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
  
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism

$(q_1, 001100, K)$



- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
  
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
  
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
  
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism

$(q_1, 001100, K)$   
↓  
 $(q_1, 01100, NK)$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism

$(q_1, 001100, K)$

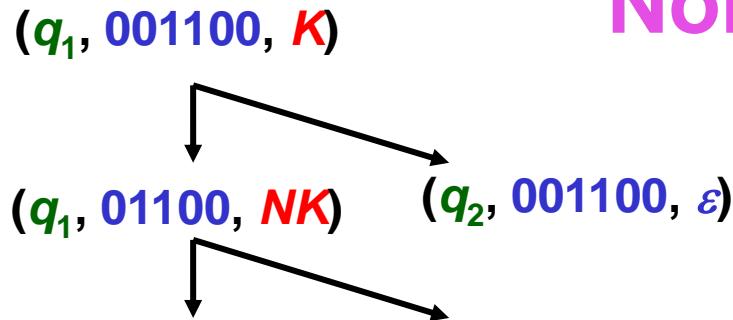
$(q_1, 01100, NK)$



$(q_2, 001100, \varepsilon)$

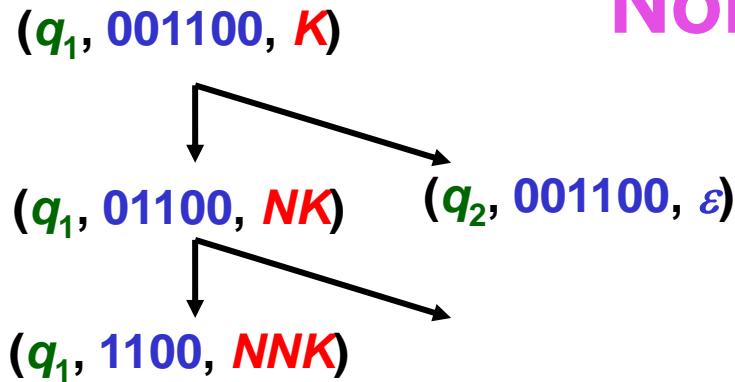
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism



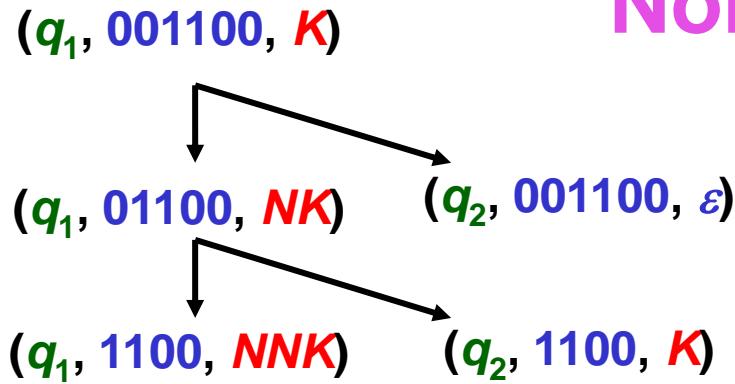
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism



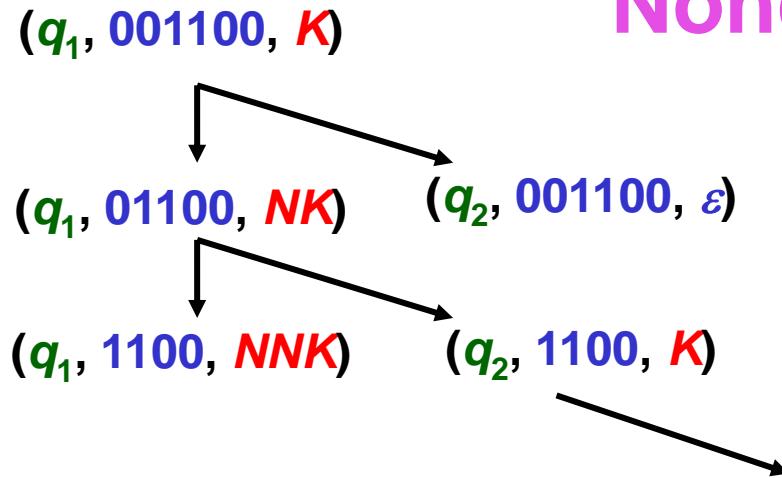
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism



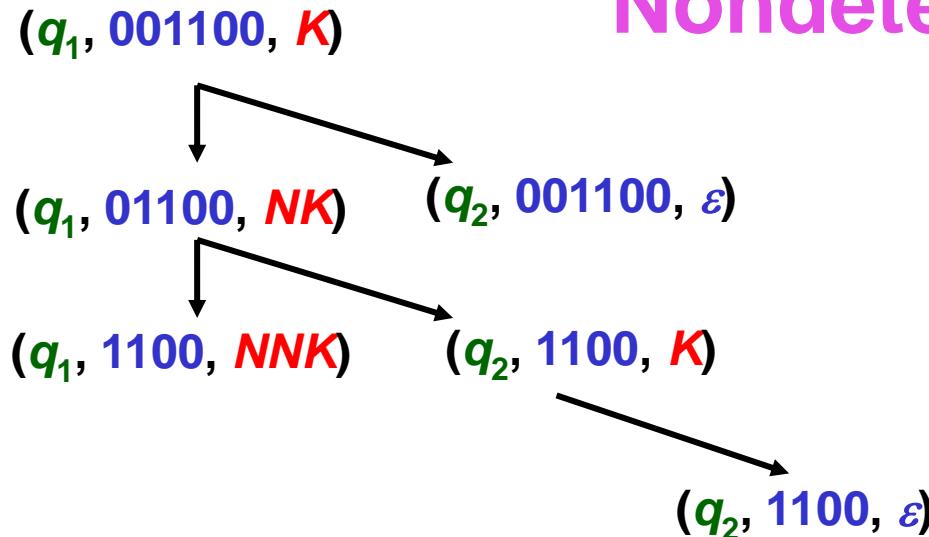
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism



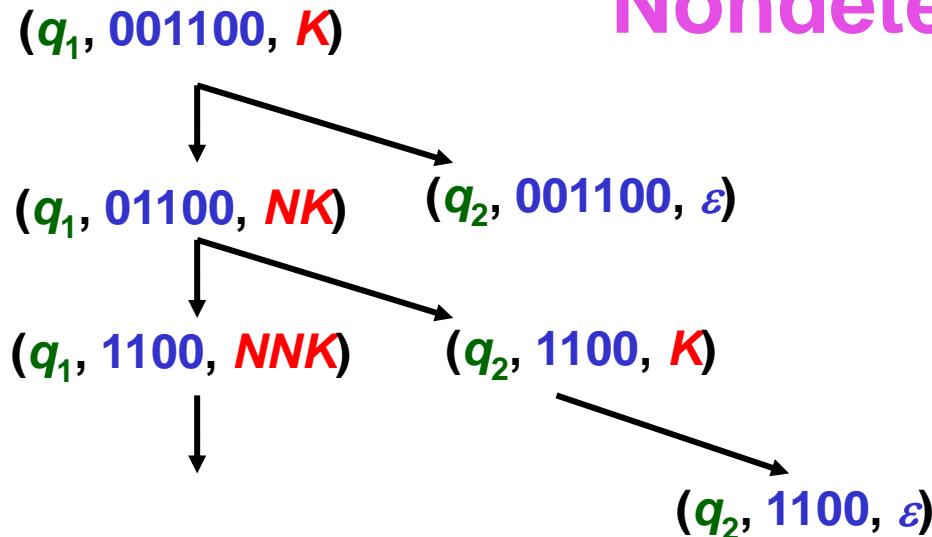
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

# Nondeterminism



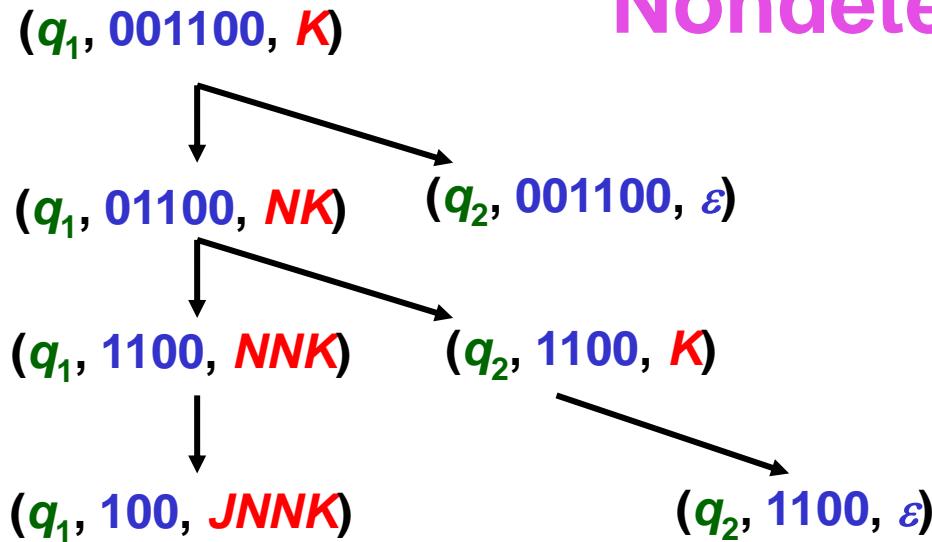
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism



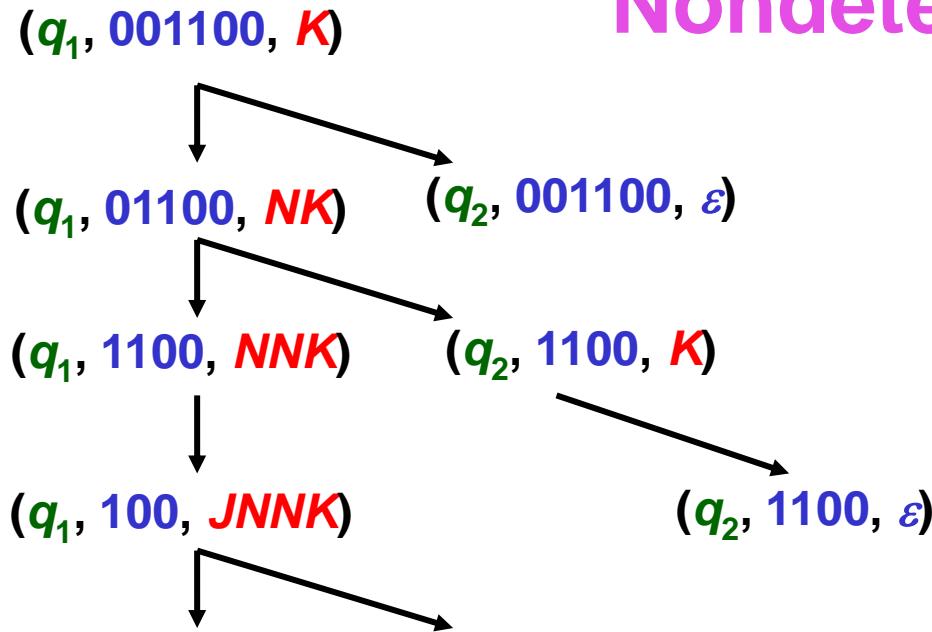
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 12)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 13)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$

# Nondeterminism



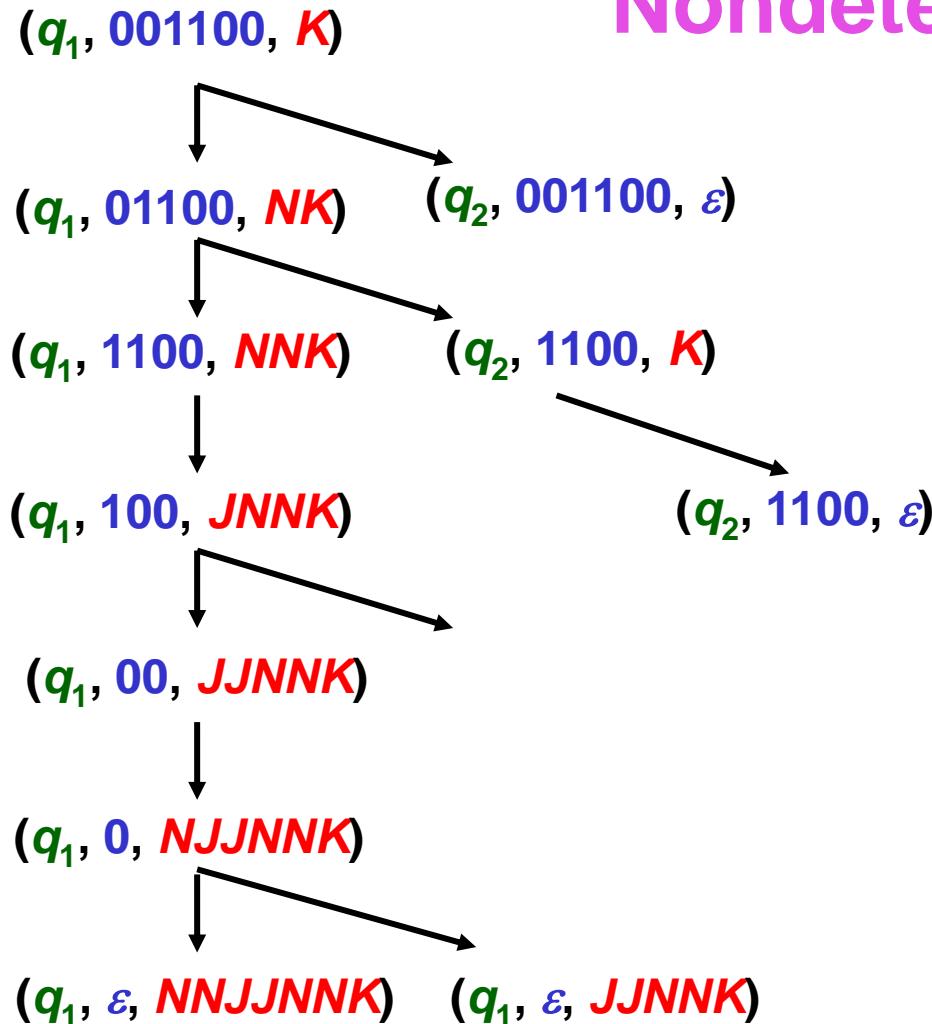
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

# Nondeterminism



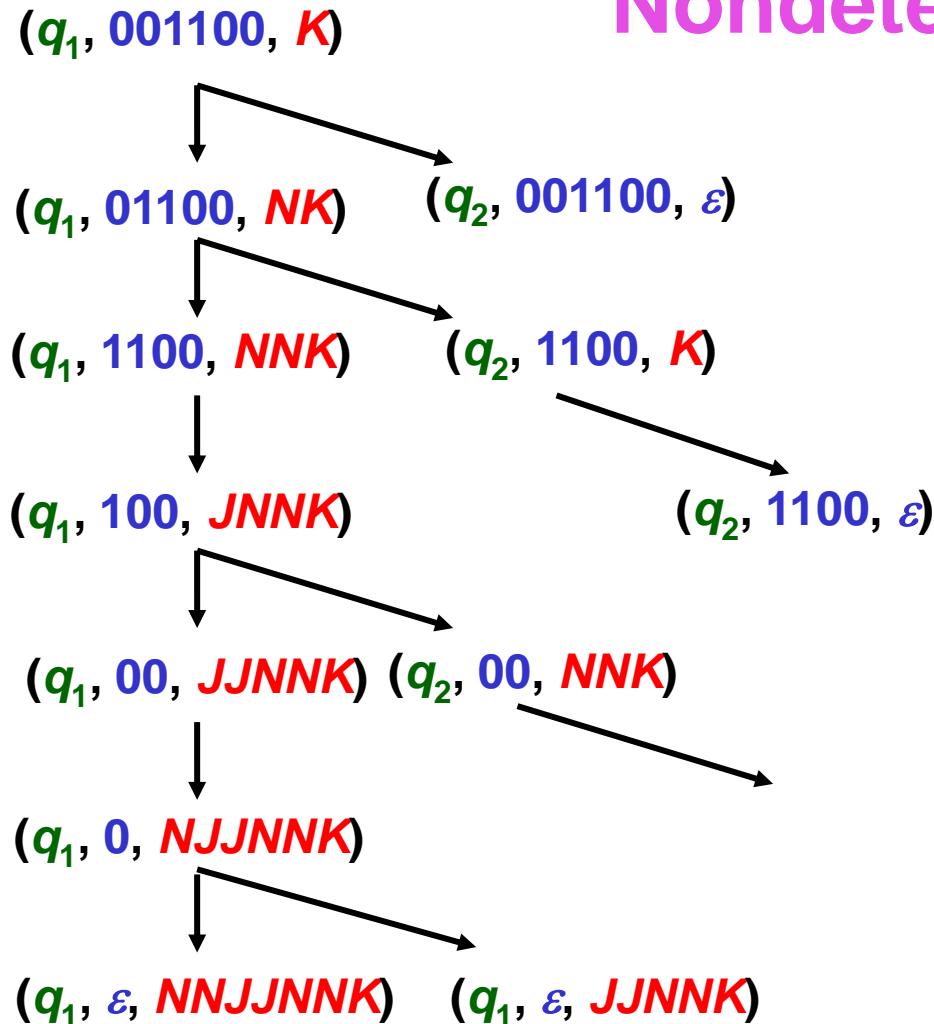
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

# Nondeterminism



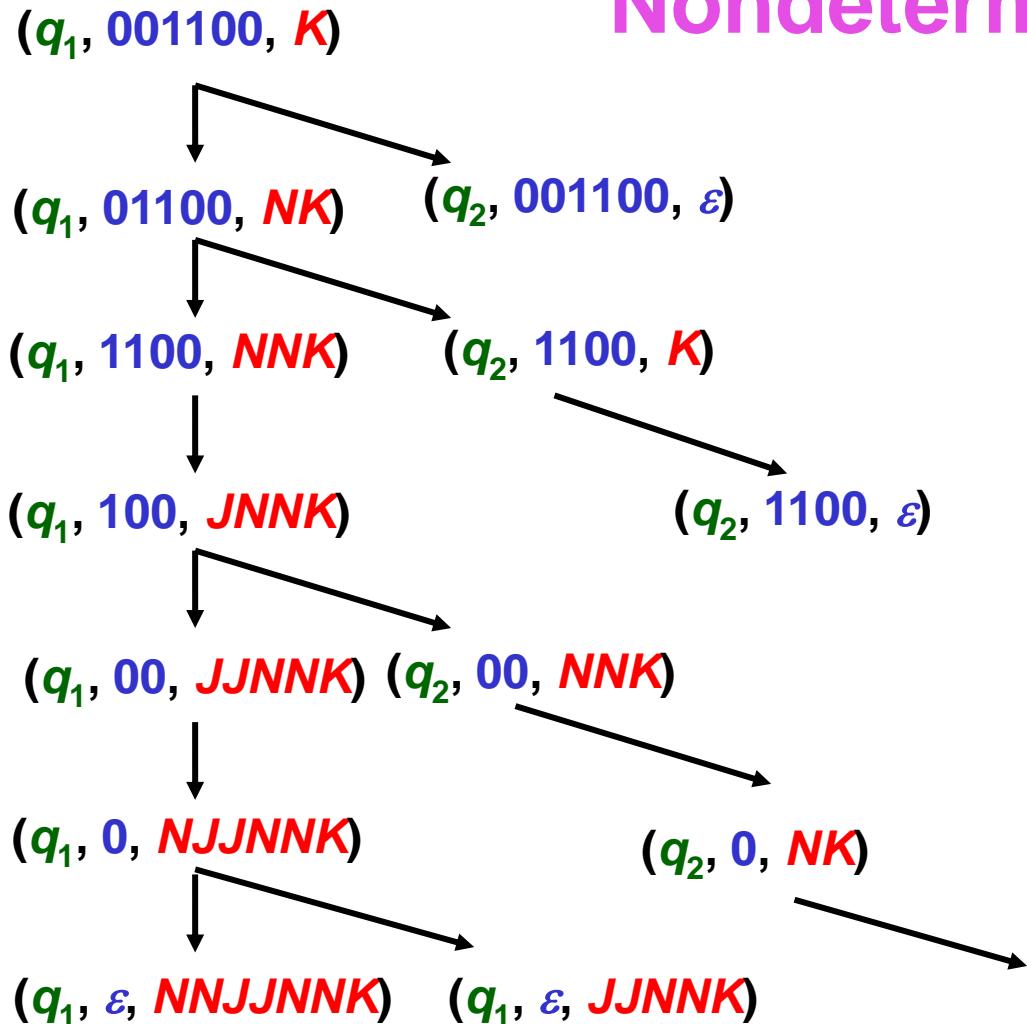
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

# Nondeterminism



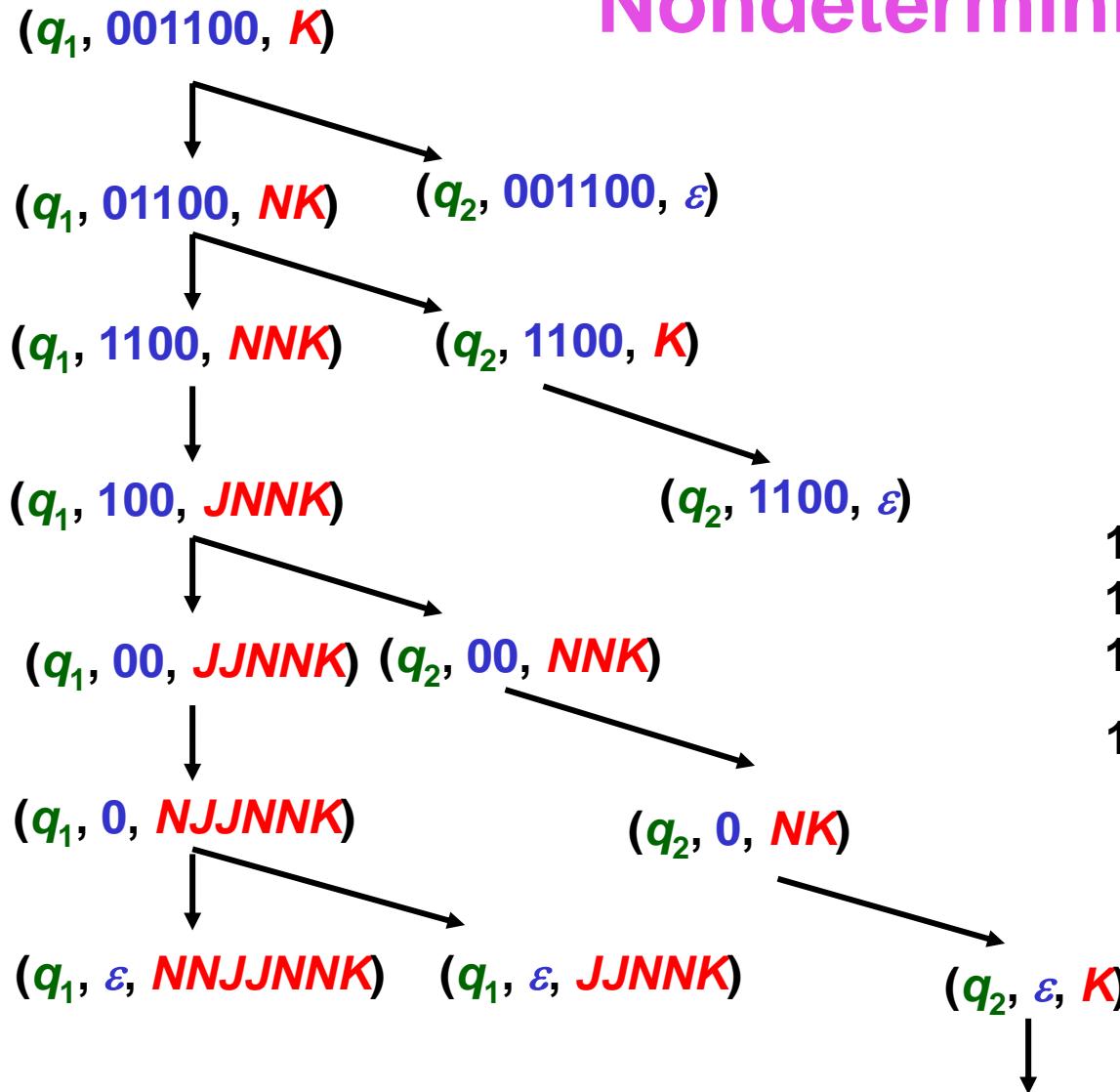
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

# Nondeterminism



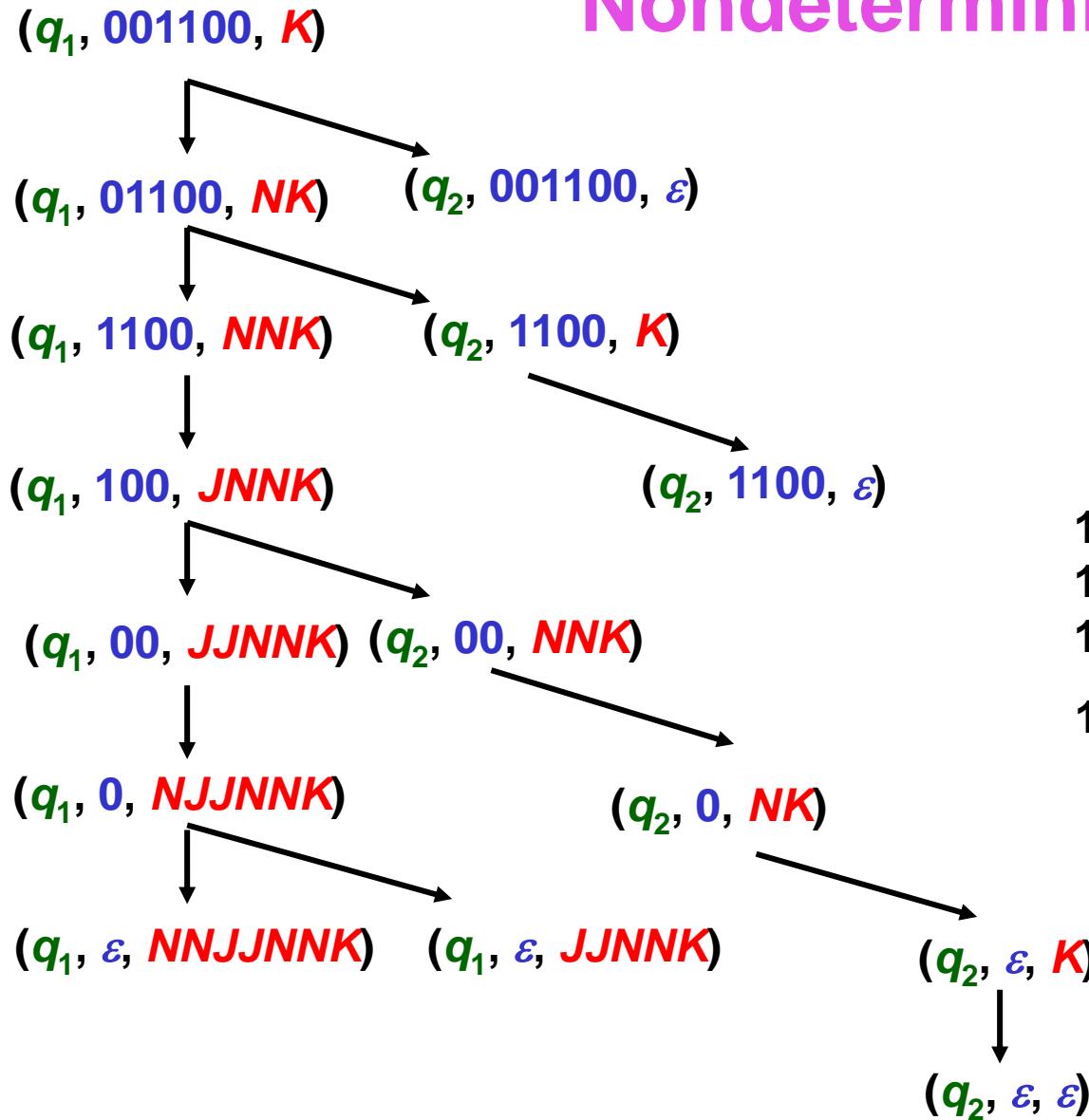
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

# Nondeterminism



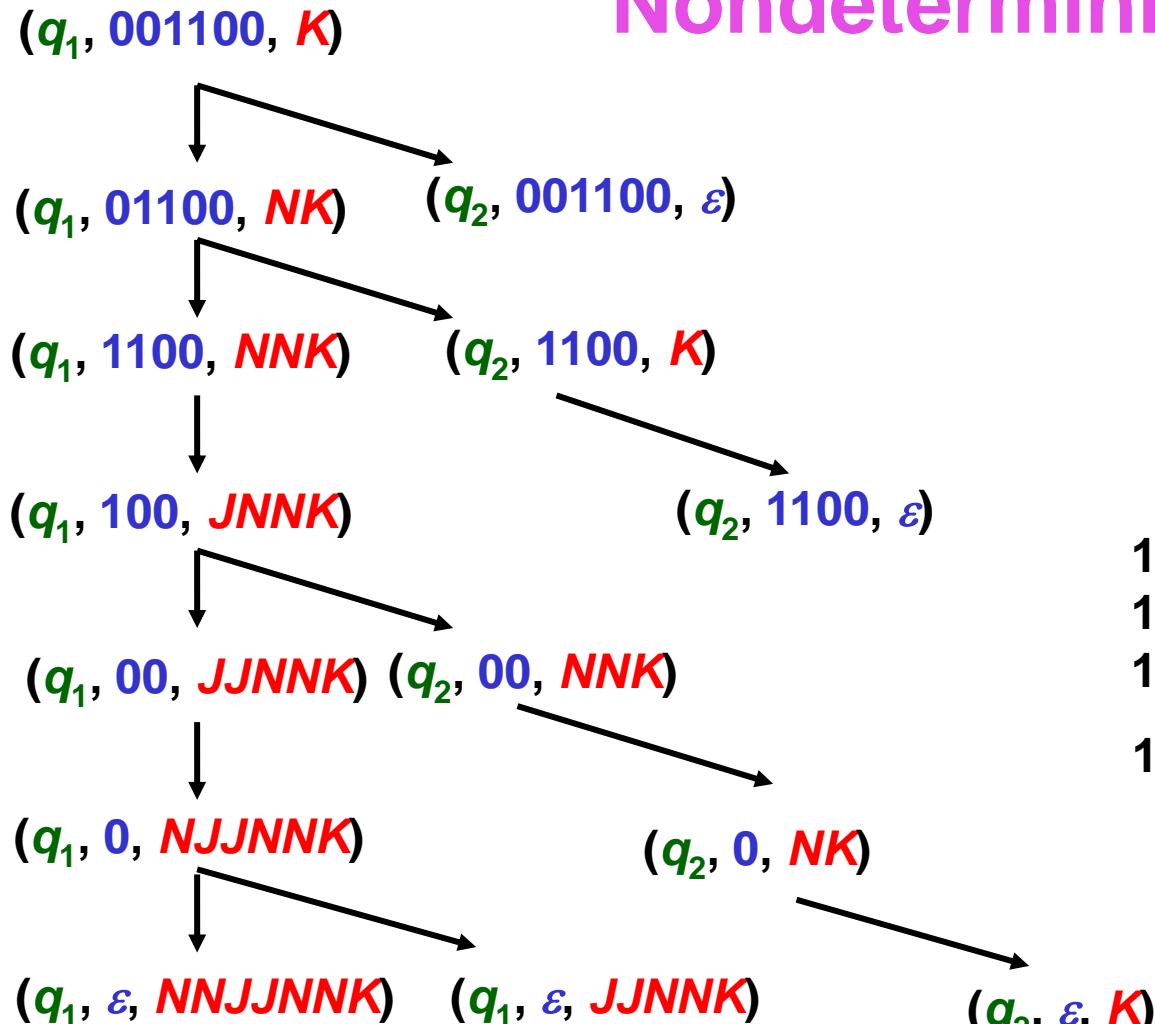
- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

# Nondeterminism



- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

# Nondeterminism



- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \epsilon)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \epsilon)\}$
- 10)  $\delta(q_2, 0, N) = \{(q_2, \epsilon)\}$
- 11)  $\delta(q_2, 1, J) = \{(q_2, \epsilon)\}$
- 12)  $\delta(q_2, \epsilon, K) = \{(q_2, \epsilon)\}$
- 13)  $\delta(q_1, \epsilon, K) = \{(q_2, \epsilon)\}$

**Accept string**

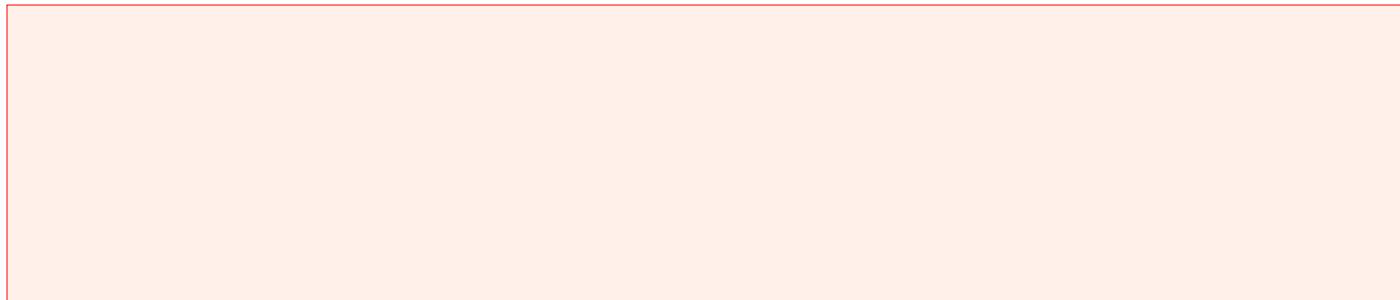
# Deterministic PA (DPA)

# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**

# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**



# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**

If  $(\delta(q, \varepsilon, Z) \neq \emptyset)$

# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**

If  $(\delta(q, \varepsilon, Z) \neq \emptyset)$

then

# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**

If  $(\delta(q, \varepsilon, Z) \neq \emptyset)$

then

$\delta(q, a, Z) = \emptyset, \forall a \in \Sigma$

# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**

If  $(\delta(q, \varepsilon, Z) \neq \emptyset)$

then

$\delta(q, a, Z) = \emptyset, \forall a \in \Sigma$

# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**

If  $(\delta(q, \varepsilon, Z) \neq \emptyset)$

then

$$\delta(q, a, Z) = \emptyset, \forall a \in \Sigma$$

There is at most one element in set  $\delta(q, a, Z)$   
 $\forall q \in Q$

# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**

If  $(\delta(q, \varepsilon, Z) \neq \emptyset)$

then

$$\delta(q, a, Z) = \emptyset, \forall a \in \Sigma$$

There is at most one element in set  $\delta(q, a, Z)$

$$\forall q \in Q$$

$$\forall Z \in \Gamma$$

# Deterministic PA (DPA)

**Deterministic DPA  $M=(Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ :**

If  $(\delta(q, \varepsilon, Z) \neq \emptyset)$

then

$$\delta(q, a, Z) = \emptyset, \forall a \in \Sigma$$

**There is at most one element in set  $\delta(q, a, Z)$**

$$\forall q \in Q$$

$$\forall Z \in \Gamma$$

$$\forall a \in (\Sigma \cup \{\varepsilon\})$$

# Lecture 9

## 3.2 PUSHDOWN AUTOMATA (PA)

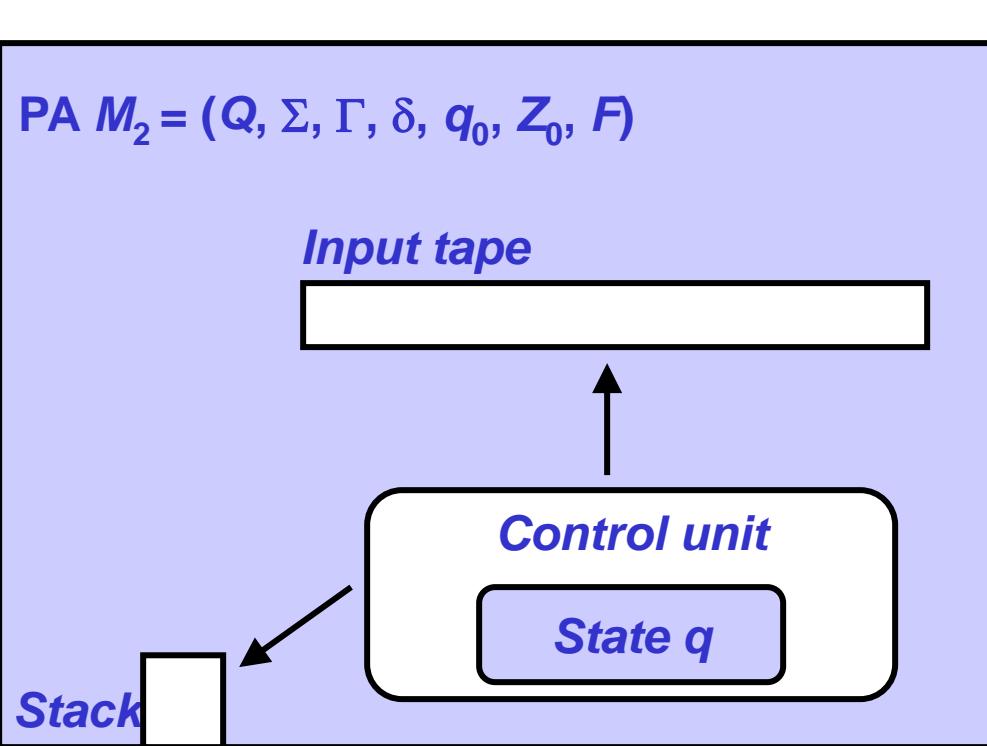
3.2.1 PA Model

3.2.2 PA Definition

3.2.3 PA and Context-Free Grammar

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

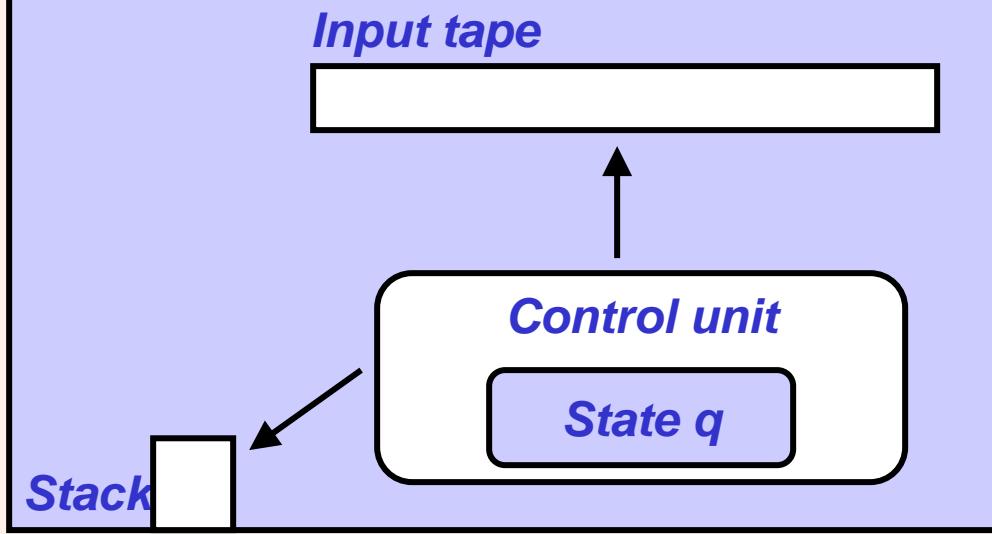
## Constructing a PA that accepts by empty stack from a PA that accepts by final state



## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

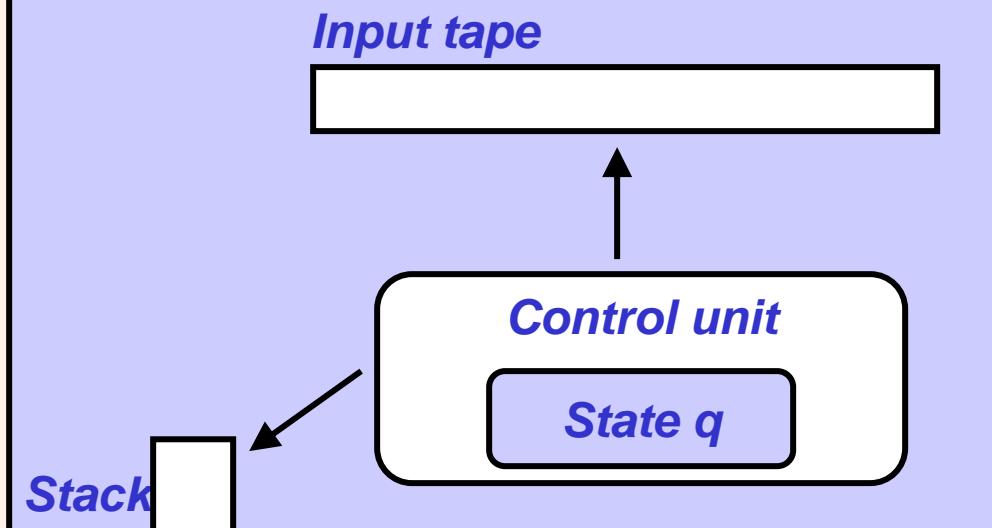


## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

1) set  $\delta'(q, a, Z) = \delta(q, a, Z)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

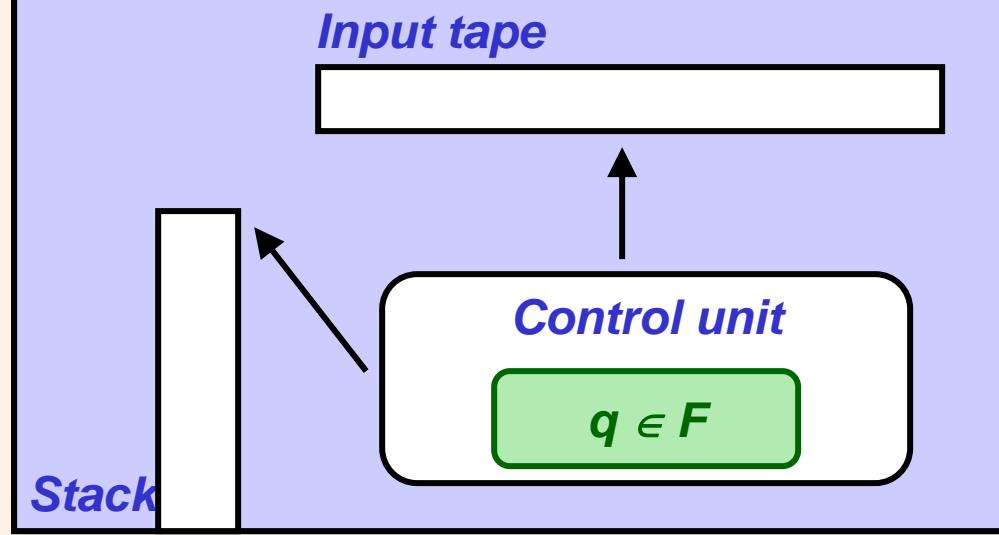


## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

1) set  $\delta'(q, a, Z) = \delta(q, a, Z)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

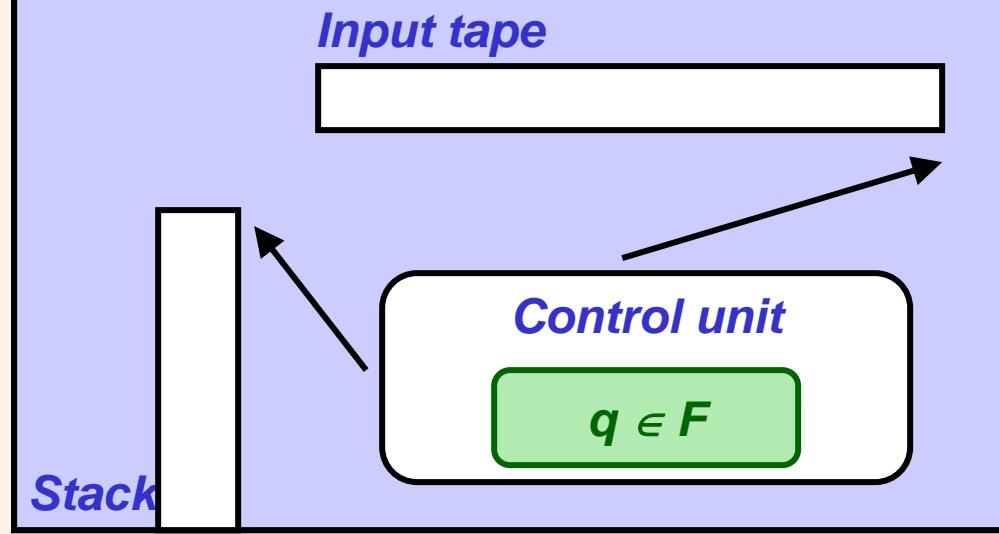


## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

1) set  $\delta'(q, a, Z) = \delta(q, a, Z)$

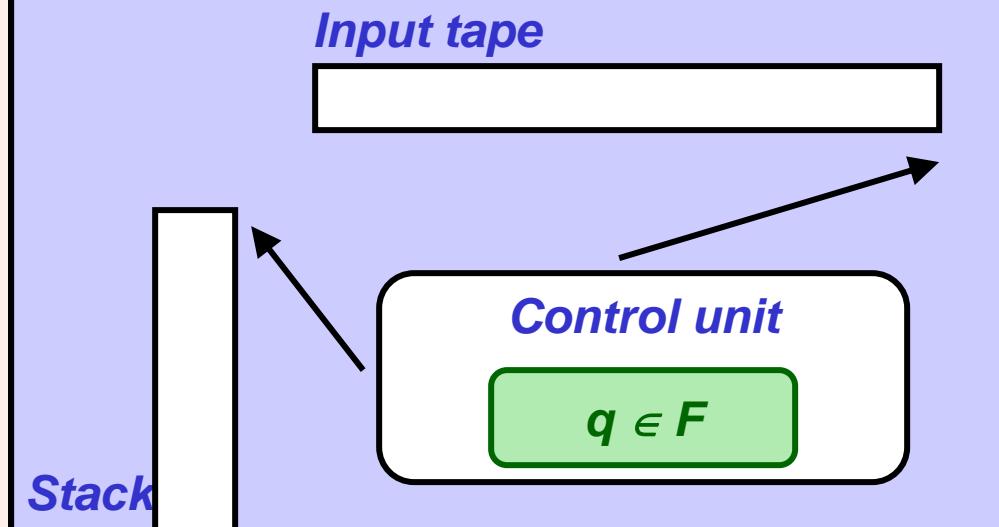
PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$



## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$



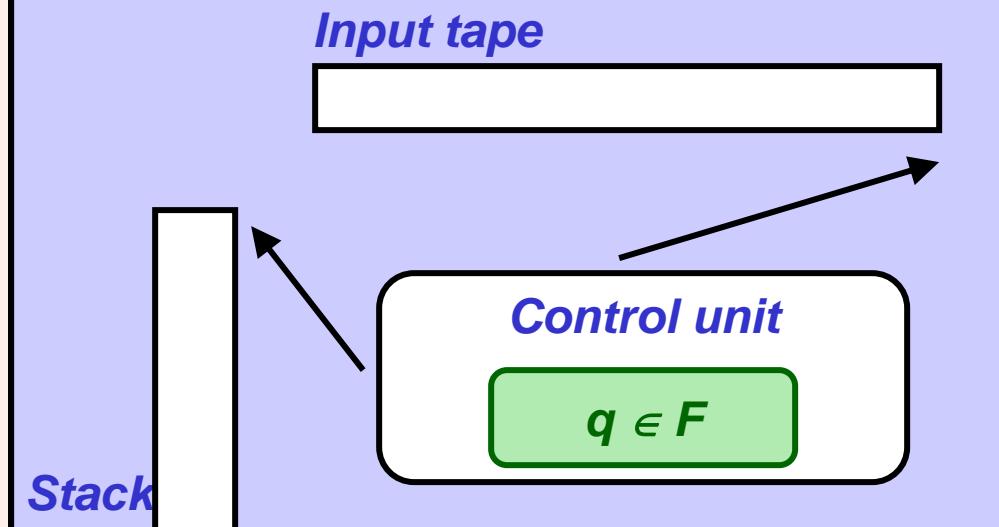
1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

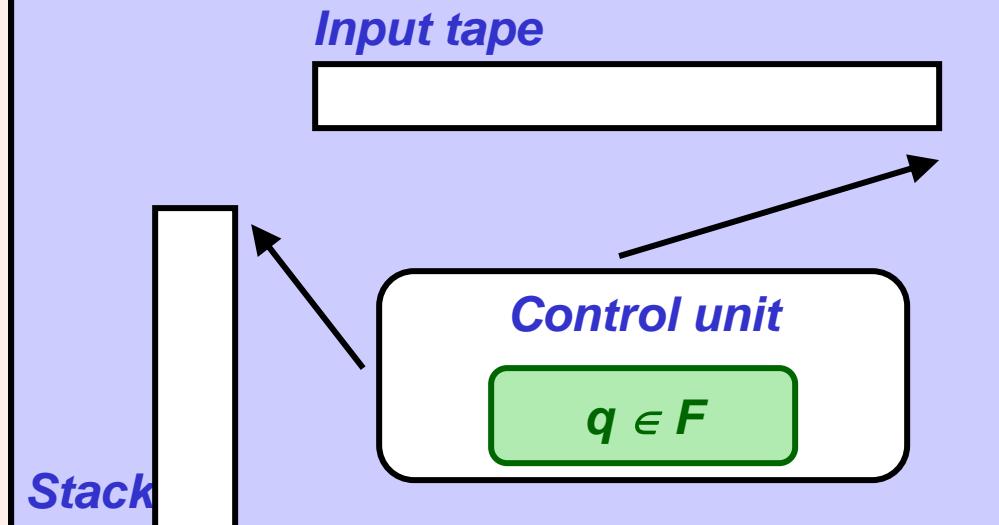
2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

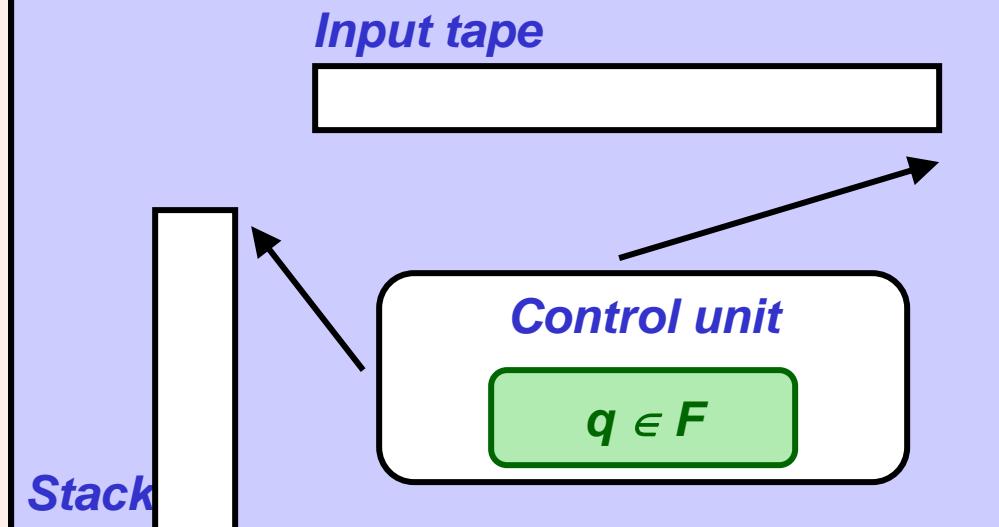
$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$



1) set  $\delta'(q, a, Z) = \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

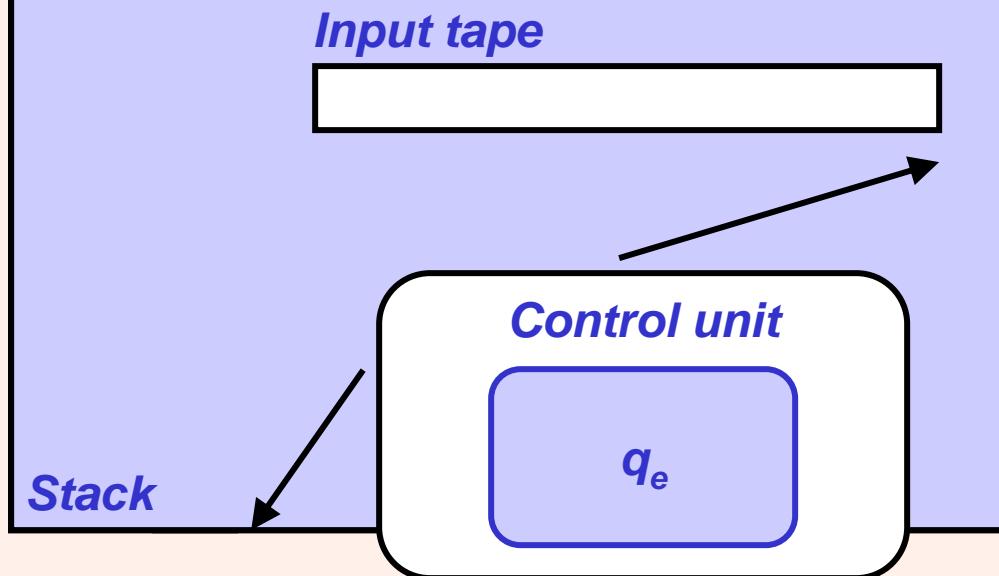
$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

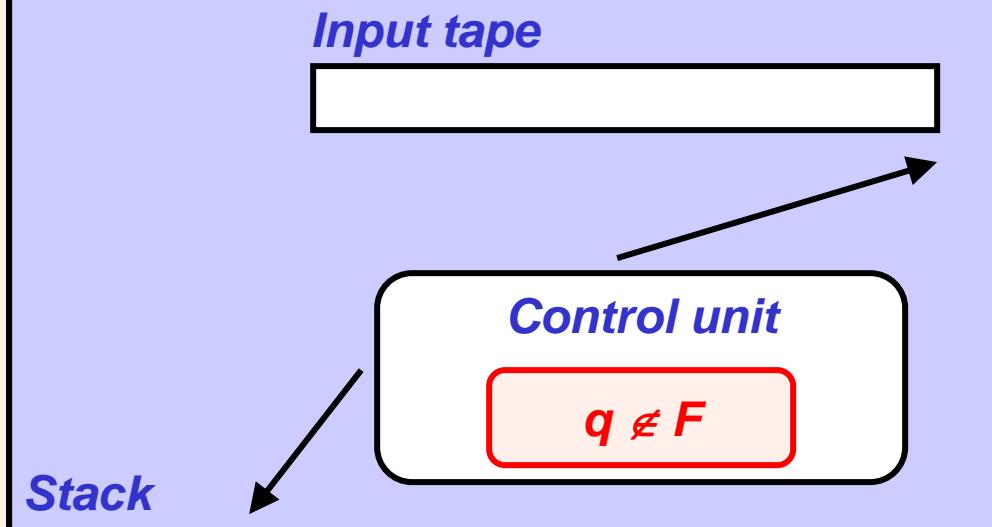
$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$



1) set  $\delta'(q, a, Z) = \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



1) set  $\delta'(q, a, Z) = \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

3)  $Z_0' = X_0$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \sqcup \{ X_0 \}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{ X_0 \}$$

$$Q' = Q' \cup \{ q_0' \}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Stack*

$X_0$

$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) q \in F$$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{ X_0 \}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Stack*

$X_0$

$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) q \in F$$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



Stack

$X_0$

$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) q \in F$$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$(q_0, x, Z_0)$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



Stack

$X_0$

$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) q \in F$$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



Stack

$X_0$

$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) q \in F$$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$(q_0', x, X_0)$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



Stack

$X_0$

$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) q \in F$$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$$(q_0', x, X_0) \succ_{M_1}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$$(q_0', x, X_0) \succ_{M_1} (q_0, x, Z_0 X_0)$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$$(q_0', x, X_0) \succ_{M_1} (q_0, x, Z_0 X_0) \succ_{M_1}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$$(q_0', x, X_0) \succ_{M_1} (q_0, x, Z_0 X_0) \succ_{M_1} (q, \varepsilon, A\gamma X_0)$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$$(q_0', x, X_0) \succ_{M_1} (q_0, x, Z_0 X_0) \succ_{M_1} (q, \varepsilon, A\gamma X_0) \succ_{M_1}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$$(q_0', x, X_0) \succ_{M_1} (q_0, x, Z_0 X_0) \succ_{M_1} (q, \varepsilon, A\gamma X_0) \succ_{M_1} (q_e, \varepsilon, \gamma X_0)$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$$(q_0', x, X_0) \succ_{M_1} (q_0, x, Z_0 X_0) \succ_{M_1} (q, \varepsilon, A\gamma X_0) \succ_{M_1} (q_e, \varepsilon, \gamma X_0) \succ_{M_1}$$

## Constructing a PA that accepts by empty stack from a PA that accepts by final state

PA  $M_1 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', \emptyset)$

PA  $M_2 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

*Input tape*



*Control unit*

$q \notin F$

*Stack*

$X_0$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $q \in F$

$$Q' = Q \cup \{ q_e \}$$

$$\delta'(q, \varepsilon, Z) = \delta'(q, \varepsilon, Z) \cup (q_e, \varepsilon)$$

$$(q_e, \varepsilon) \in \delta'(q_e, \varepsilon, Z)$$

$$Z \in (\Gamma \cup \{X_0\})$$

3)  $Z_0' = X_0$

$$\Gamma' = \Gamma \cup \{X_0\}$$

$$Q' = Q' \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$$

$$(q_0, x, Z_0) \succ_{M_2} (q, \varepsilon, A\gamma), q \in F$$

$$(q_0', x, X_0) \succ_{M_1} (q_0, x, Z_0 X_0) \succ_{M_1} (q, \varepsilon, A\gamma X_0) \succ_{M_1} (q_e, \varepsilon, \gamma X_0) \succ_{M_1} (q_e, \varepsilon, \varepsilon)$$



**PA**  $M_2 = (\{q_1, q_2\}, \{0, 1\}, \{N, K\}, \delta, q_1, K, \{q_2\})$

PA  $M_2 = (\{q_1, q_2\}, \{0, 1\}, \{N, K\}, \delta, q_1, K, \{q_2\})$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 3)  $\delta(q_1, 1, N) = \{(q_2, \varepsilon)\}$
- 4)  $\delta(q_2, 1, N) = \{(q_2, \varepsilon)\}$

**PA**  $M_1 = (\{q_1, q_2, q_0', q_e\}, \{0, 1\}, \{N, K, X_0\}, \delta', q_0', X_0, \emptyset)$

**PA**  $M_2 = (\{q_1, q_2\}, \{0, 1\}, \{N, K\}, \delta, q_1, K, \{q_2\})$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 3)  $\delta(q_1, 1, N) = \{(q_2, \varepsilon)\}$
- 4)  $\delta(q_2, 1, N) = \{(q_2, \varepsilon)\}$

PA  $M_1 = (\{q_1, q_2, q_0', q_e\}, \{0, 1\}, \{N, K, X_0\}, \delta', q_0', X_0, \emptyset)$

PA  $M_2 = (\{q_1, q_2\}, \{0, 1\}, \{N, K\}, \delta, q_1, K, \{q_2\})$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 3)  $\delta(q_1, 1, N) = \{(q_2, \varepsilon)\}$
- 4)  $\delta(q_2, 1, N) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

**PA  $M_1 = (\{q_1, q_2, q_0', q_e\}, \{0, 1\}, \{N, K, X_0\}, \delta', q_0', X_0, \emptyset)$**

**PA  $M_2 = (\{q_1, q_2\}, \{0, 1\}, \{N, K\}, \delta, q_1, K, \{q_2\})$**

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 3)  $\delta(q_1, 1, N) = \{(q_2, \varepsilon)\}$
- 4)  $\delta(q_2, 1, N) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

- 5)  $\delta'(q_2, \varepsilon, N) = \{(q_e, \varepsilon)\}$
- 6)  $\delta'(q_2, \varepsilon, K) = \{(q_e, \varepsilon)\}$
- 7)  $\delta'(q_2, \varepsilon, X_0) = \{(q_e, \varepsilon)\}$

PA  $M_1 = (\{q_1, q_2, q_0', q_e\}, \{0, 1\}, \{N, K, X_0\}, \delta', q_0', X_0, \emptyset)$

PA  $M_2 = (\{q_1, q_2\}, \{0, 1\}, \{N, K\}, \delta, q_1, K, \{q_2\})$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 3)  $\delta(q_1, 1, N) = \{(q_2, \varepsilon)\}$
- 4)  $\delta(q_2, 1, N) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

- 5)  $\delta'(q_2, \varepsilon, N) = \{(q_e, \varepsilon)\}$
- 6)  $\delta'(q_2, \varepsilon, K) = \{(q_e, \varepsilon)\}$
- 7)  $\delta'(q_2, \varepsilon, X_0) = \{(q_e, \varepsilon)\}$

- 8)  $\delta'(q_e, \varepsilon, N) = \{(q_e, \varepsilon)\}$
- 9)  $\delta'(q_e, \varepsilon, K) = \{(q_e, \varepsilon)\}$
- 10)  $\delta'(q_e, \varepsilon, X_0) = \{(q_e, \varepsilon)\}$

PA  $M_1 = (\{q_1, q_2, q_0', q_e\}, \{0, 1\}, \{N, K, X_0\}, \delta', q_0', X_0, \emptyset)$

PA  $M_2 = (\{q_1, q_2\}, \{0, 1\}, \{N, K\}, \delta, q_1, K, \{q_2\})$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 3)  $\delta(q_1, 1, N) = \{(q_2, \varepsilon)\}$
- 4)  $\delta(q_2, 1, N) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

- 5)  $\delta'(q_2, \varepsilon, N) = \{(q_e, \varepsilon)\}$
- 6)  $\delta'(q_2, \varepsilon, K) = \{(q_e, \varepsilon)\}$
- 7)  $\delta'(q_2, \varepsilon, X_0) = \{(q_e, \varepsilon)\}$

- 8)  $\delta'(q_e, \varepsilon, N) = \{(q_e, \varepsilon)\}$
- 9)  $\delta'(q_e, \varepsilon, K) = \{(q_e, \varepsilon)\}$
- 10)  $\delta'(q_e, \varepsilon, X_0) = \{(q_e, \varepsilon)\}$

$(q_1, 00011, K) \succ (q_1, 0011, NK) \succ (q_1, 011, NNK)$   
 $\succ (q_1, 11, NNNK) \succ (q_2, 1, NNK) \quad (q_2, \varepsilon, NK)$

**PA  $M_1 = (\{q_1, q_2, q_0', q_e\}, \{0, 1\}, \{N, K, X_0\}, \delta', q_0', X_0, \emptyset)$**

**PA  $M_2 = (\{q_1, q_2\}, \{0, 1\}, \{N, K\}, \delta, q_1, K, \{q_2\})$**

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 0, N) = \{(q_1, NN)\}$
- 3)  $\delta(q_1, 1, N) = \{(q_2, \varepsilon)\}$
- 4)  $\delta(q_2, 1, N) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

- 5)  $\delta'(q_2, \varepsilon, N) = \{(q_e, \varepsilon)\}$
- 6)  $\delta'(q_2, \varepsilon, K) = \{(q_e, \varepsilon)\}$
- 7)  $\delta'(q_2, \varepsilon, X_0) = \{(q_e, \varepsilon)\}$

- 8)  $\delta'(q_e, \varepsilon, N) = \{(q_e, \varepsilon)\}$
- 9)  $\delta'(q_e, \varepsilon, K) = \{(q_e, \varepsilon)\}$
- 10)  $\delta'(q_e, \varepsilon, X_0) = \{(q_e, \varepsilon)\}$

$(q_1, 00011, K) \succ (q_1, 0011, NK) \succ (q_1, 011, NNK)$   
 $\succ (q_1, 11, NNNK) \succ (q_2, 1, NNK) (q_2, \varepsilon, NK)$

$(q_0', 00011, X_0) \succ (q_1, 00011, KX_0) \succ (q_1, 0011, NKX_0) \succ (q_1, 011, NNKX_0) \succ$   
 $(q_1, 11, NNNKX_0) \succ (q_2, 1, NNKX_0) \succ (q_2, \varepsilon, NKX_0) \succ$   
 $(q_e, \varepsilon, KX_0) \succ (q_e, \varepsilon, X_0) \succ (q_e, \varepsilon, \varepsilon)$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$

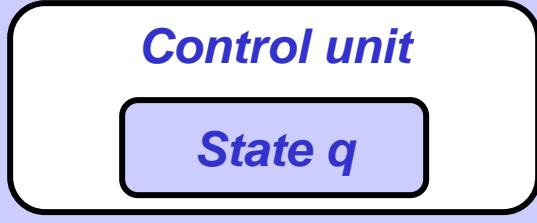
*Input tape*



*Control unit*

*State  $q$*

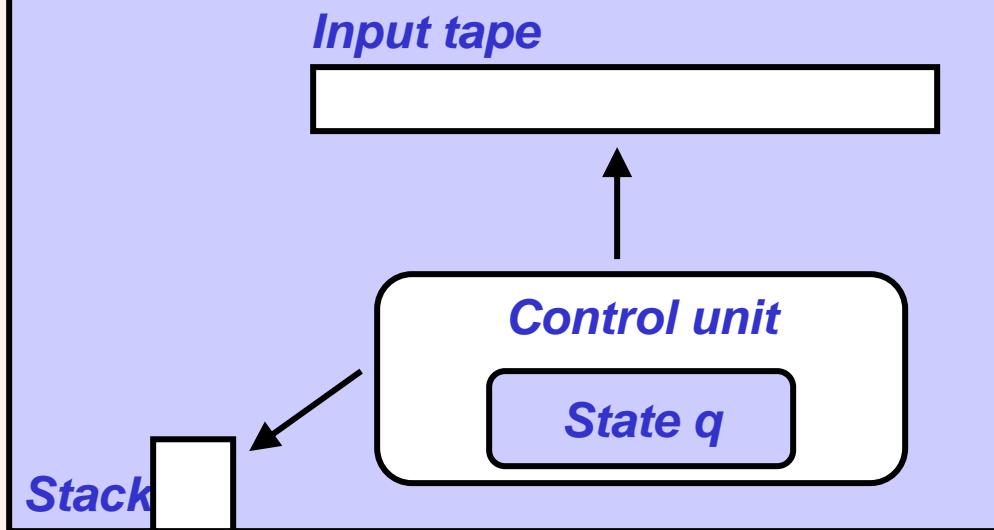
*Stack*



## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$

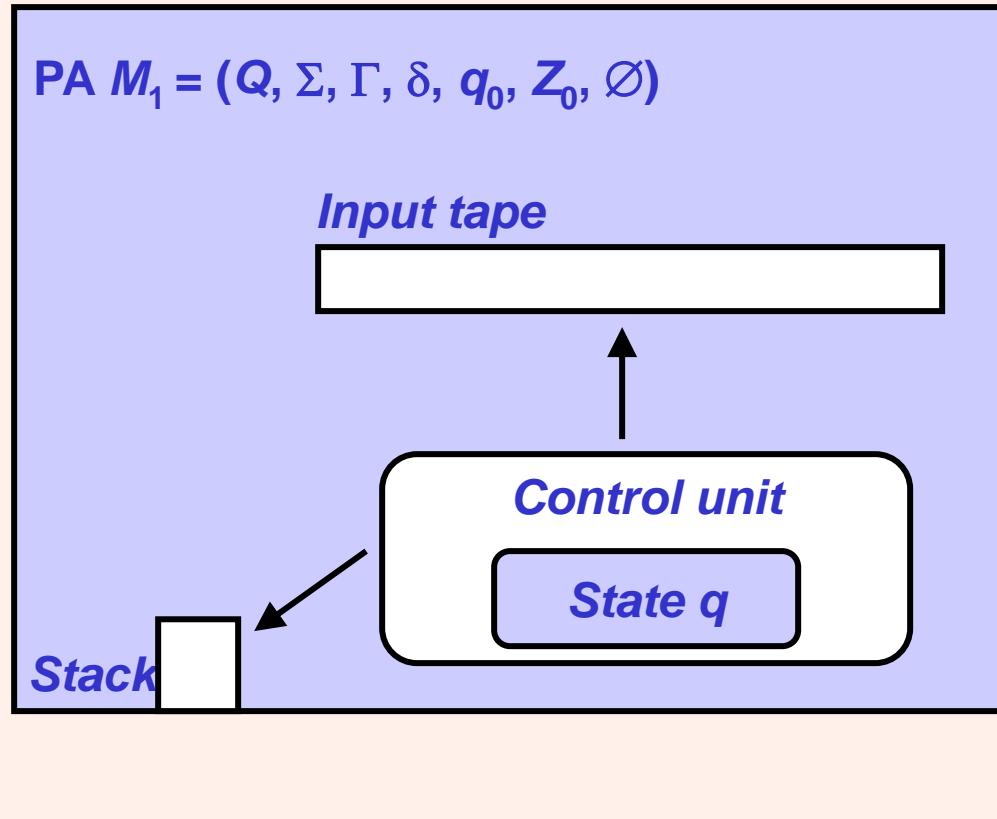


## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$



## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$

*Input tape*



*Stack*

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$

*Input tape*



*Control unit*

$q$

*Stack*

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$

*Input tape*



*Control unit*

$q$

*Stack*



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

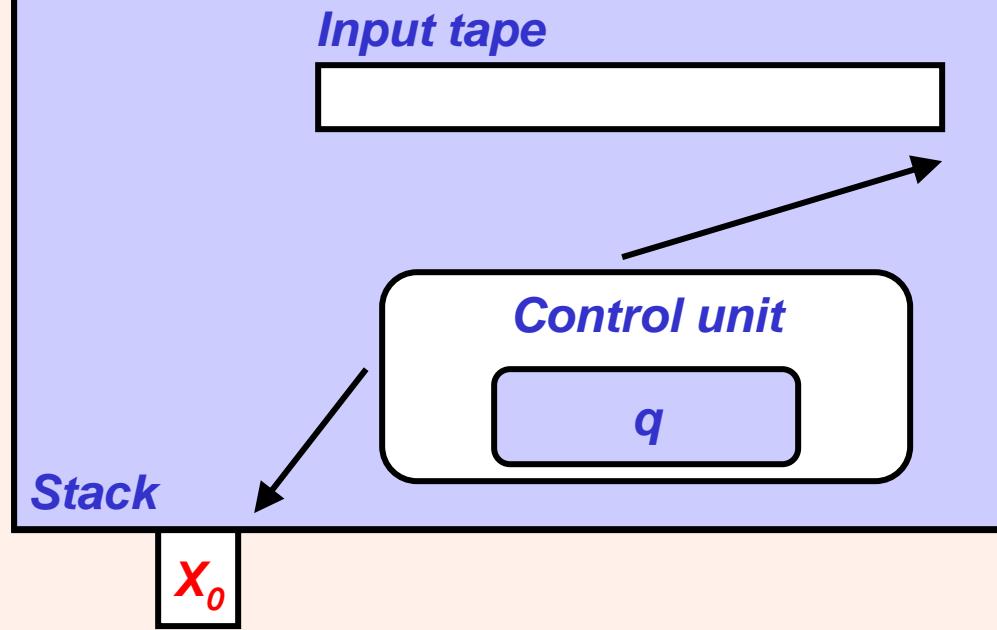
2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



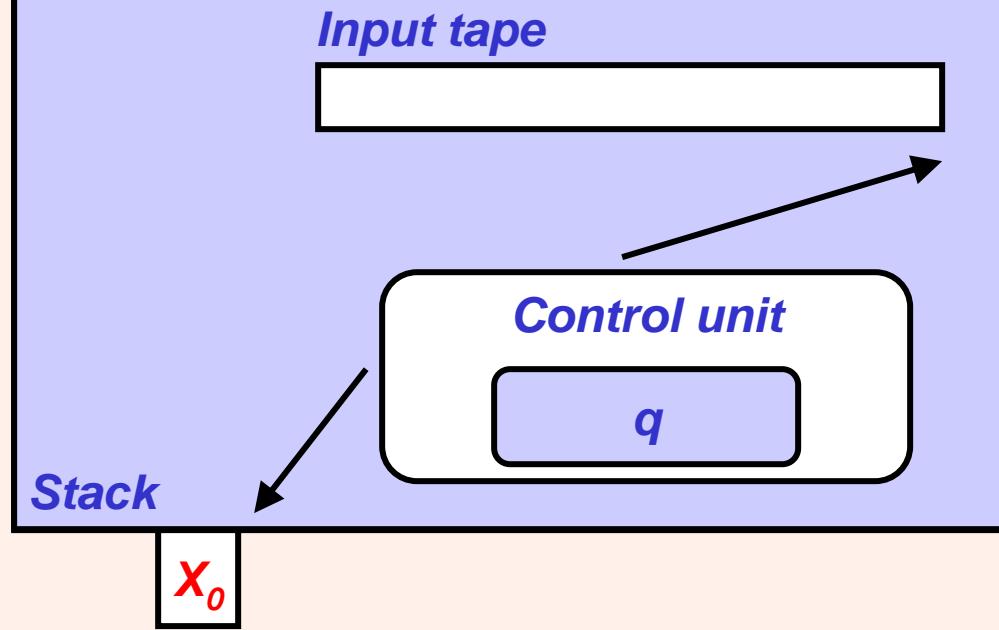
1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$   
 $F' = \{ q_f \}$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

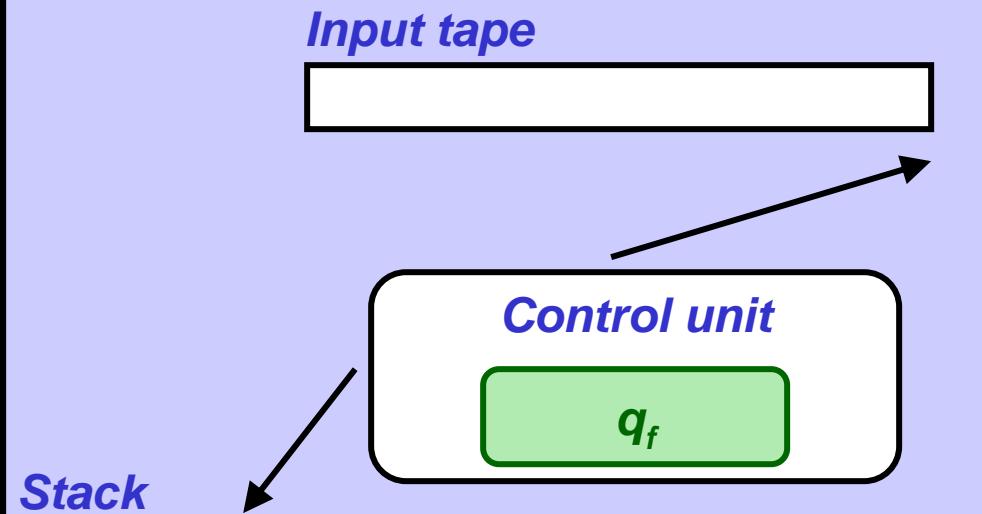
$F' = \{ q_f \}$

$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

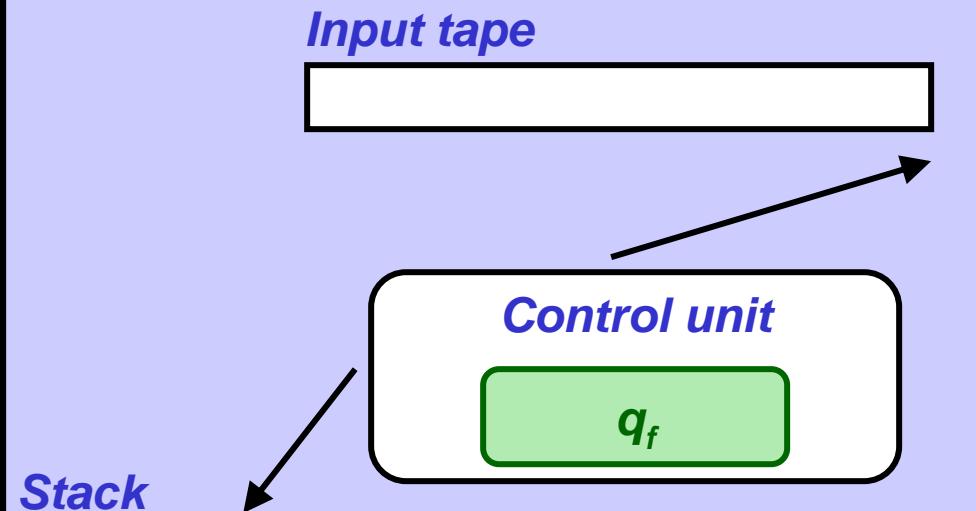
$F' = \{ q_f \}$

$(q_f, \epsilon) \in \delta'(q, \epsilon, X_0)$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

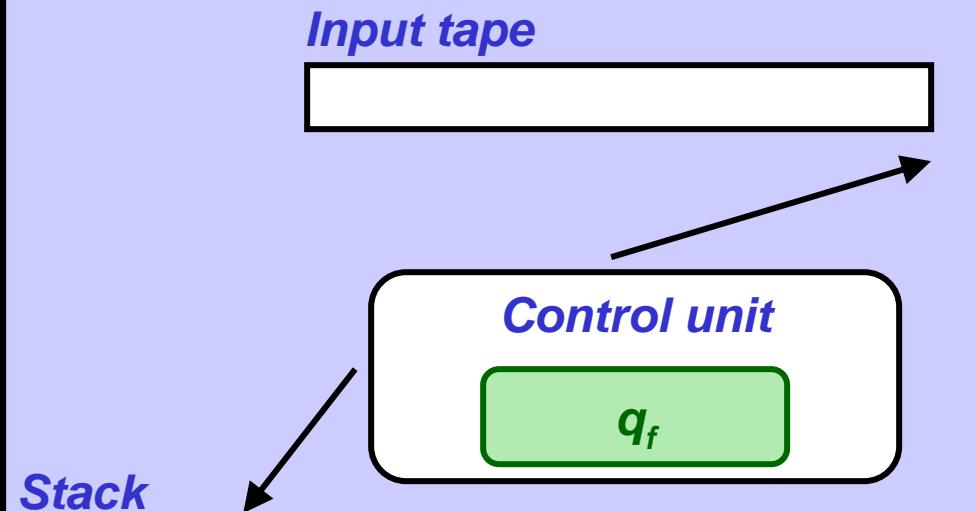
$(q_f, \epsilon) \in \delta'(q, \epsilon, X_0)$

3)  $Z_0' = X_0$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

$(q_f, \epsilon) \in \delta'(q, \epsilon, X_0)$

3)  $Z_0' = X_0$

$\Gamma' = \Gamma \cup \{ X_0 \}$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

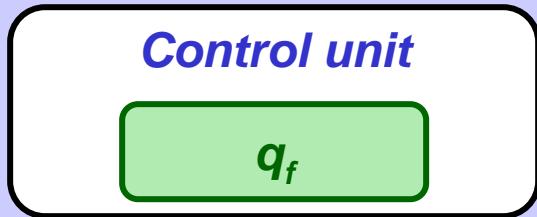
PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$

*Input tape*



*Stack*



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

$(q_f, \epsilon) \in \delta'(q, \epsilon, X_0)$

3)  $Z_0' = X_0$

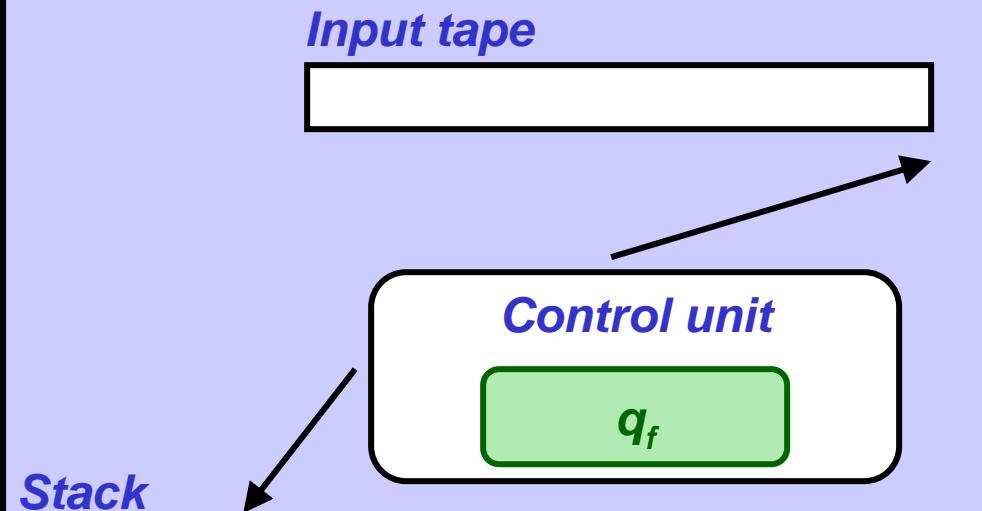
$\Gamma' = \Gamma \cup \{ X_0 \}$

$Q' = Q \cup \{ q_0' \}$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$

3)  $Z_0' = X_0$

$\Gamma' = \Gamma \cup \{ X_0 \}$

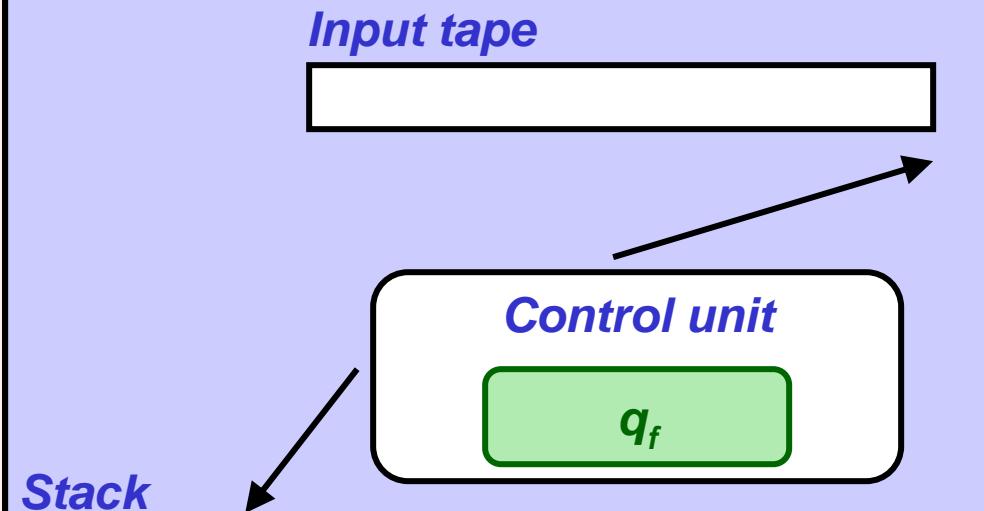
$Q' = Q \cup \{ q_0' \}$

$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



$(q_0, x, Z_0)$

1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

$(q_f, \epsilon) \in \delta'(q, \epsilon, X_0)$

3)  $Z_0' = X_0$

$\Gamma' = \Gamma \cup \{ X_0 \}$

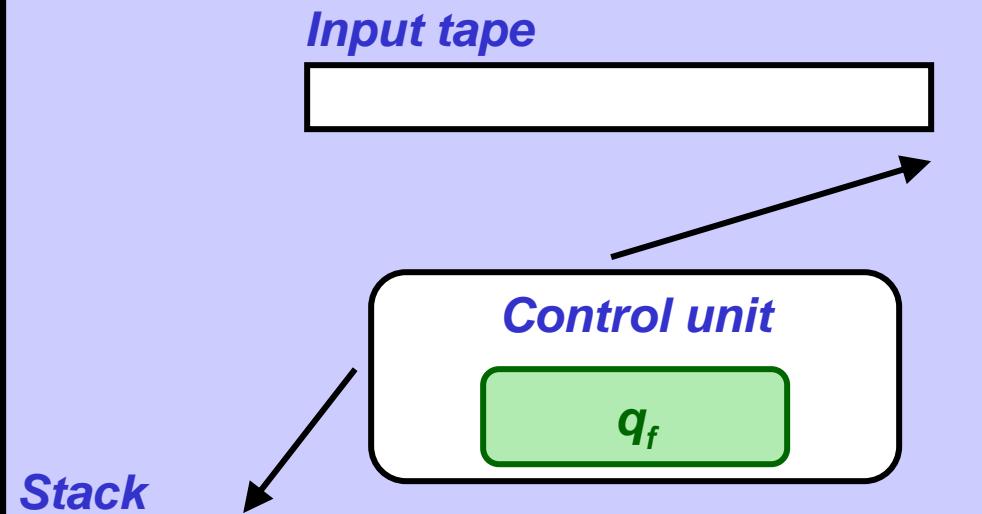
$Q' = Q \cup \{ q_0' \}$

$\delta'(q_0', \epsilon, X_0) = \{(q_0, Z_0 X_0)\}$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$

3)  $Z_0' = X_0$

$\Gamma' = \Gamma \cup \{ X_0 \}$

$Q' = Q \cup \{ q_0' \}$

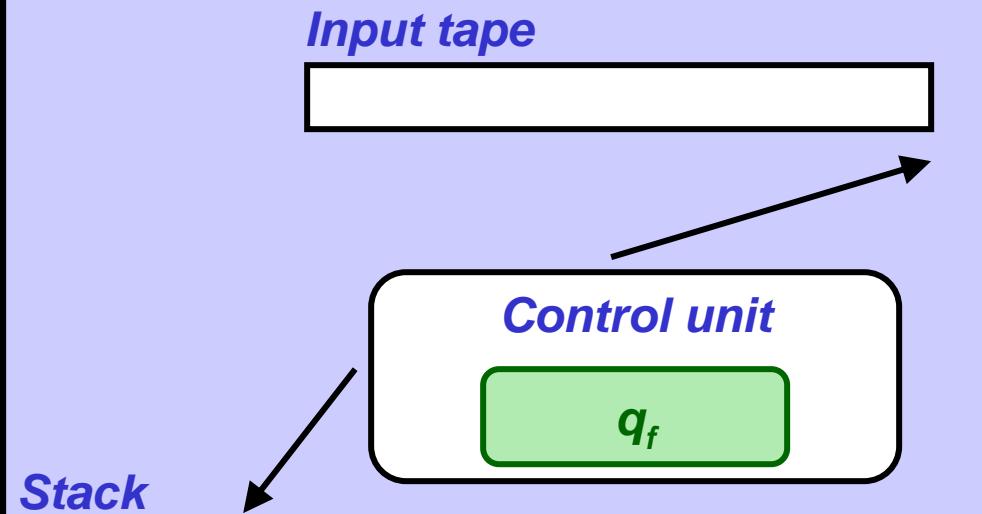
$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$

$$(q_0, x, Z_0) \xrightarrow{M_1}$$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$

3)  $Z_0' = X_0$

$\Gamma' = \Gamma \cup \{ X_0 \}$

$Q' = Q \cup \{ q_0' \}$

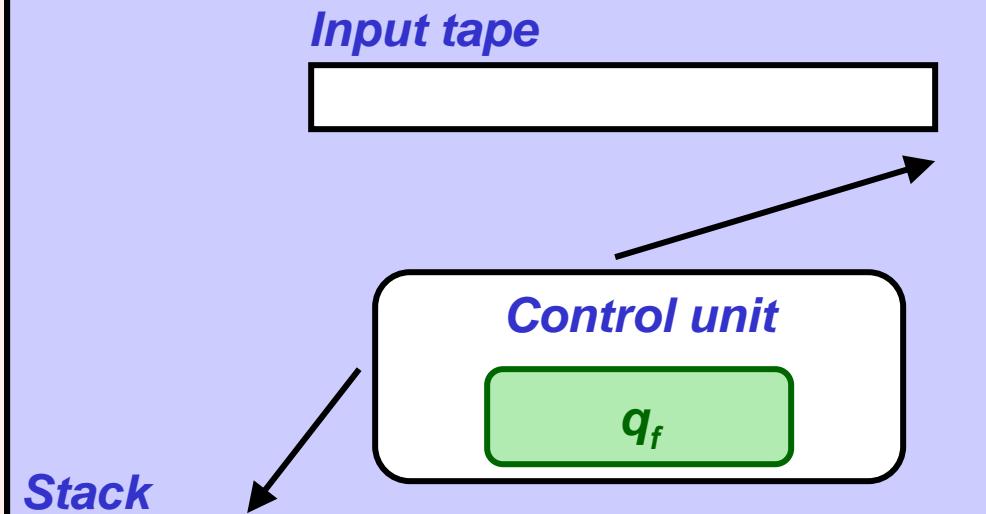
$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$

$$(q_0, x, Z_0) \xrightarrow[M_1]{} (q, \varepsilon, \varepsilon)$$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$

3)  $Z_0' = X_0$

$\Gamma' = \Gamma \cup \{ X_0 \}$

$Q' = Q \cup \{ q_0' \}$

$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$

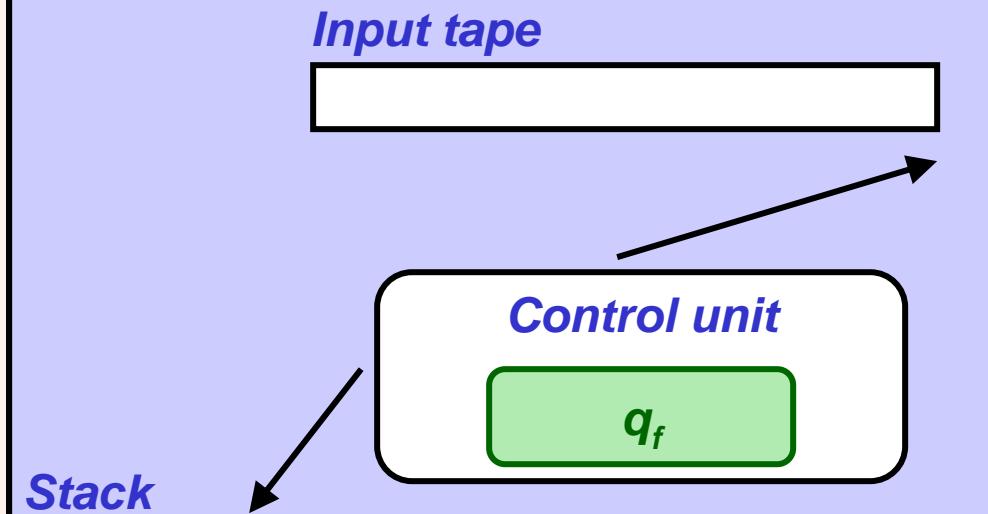
$$(q_0, x, Z_0) \xrightarrow[M_1]{} (q, \varepsilon, \varepsilon)$$

$$(q_0', x, X_0)$$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



1) set  $\delta'(q, a, Z) = \text{set } \delta(q, a, Z)$

2)  $Q' = Q' \cup \{ q_f \}$

$F' = \{ q_f \}$

$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$

3)  $Z_0' = X_0$

$\Gamma' = \Gamma \cup \{ X_0 \}$

$Q' = Q \cup \{ q_0' \}$

$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$

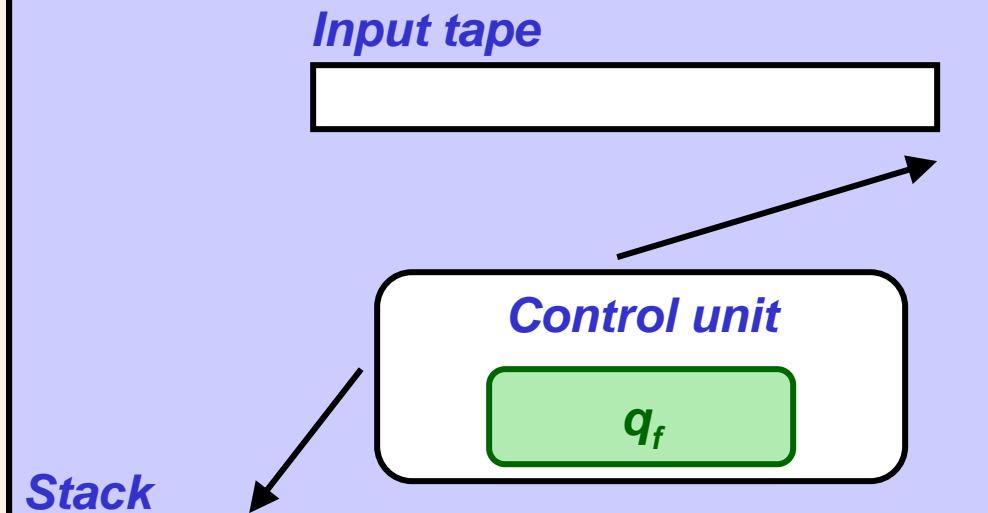
$$(q_0, x, Z_0) \succ_{M_1} (q, \varepsilon, \varepsilon)$$

$$(q_0', x, X_0) \succ_{M_2}$$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) Q' = Q' \cup \{ q_f \}$$

$$F' = \{ q_f \}$$

$$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{ X_0 \}$$

$$Q' = Q \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$$

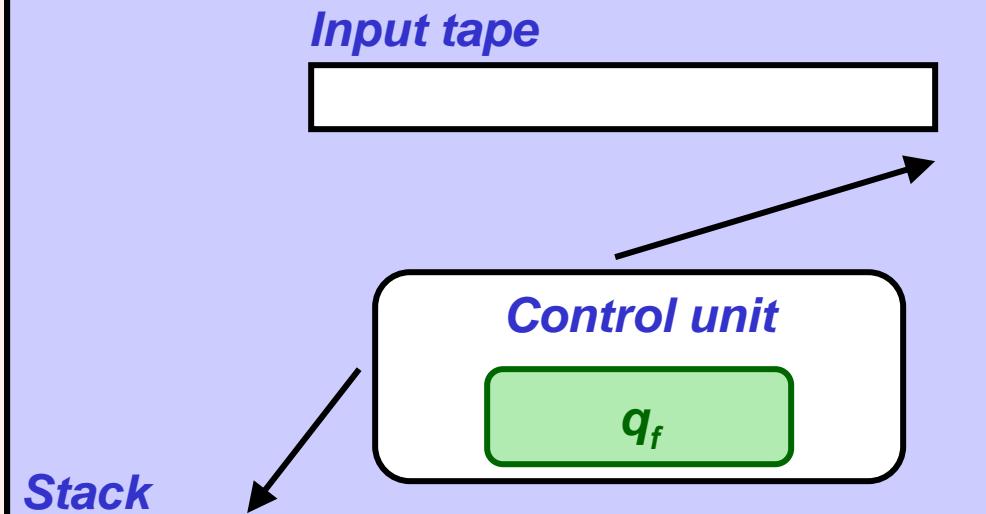
$$(q_0, x, Z_0) \xrightarrow[M_1]{} (q, \varepsilon, \varepsilon)$$

$$(q_0', x, X_0) \xrightarrow[M_2]{} (q_0, x, Z_0 X_0)$$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) Q' = Q' \cup \{ q_f \}$$

$$F' = \{ q_f \}$$

$$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{ X_0 \}$$

$$Q' = Q \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$$

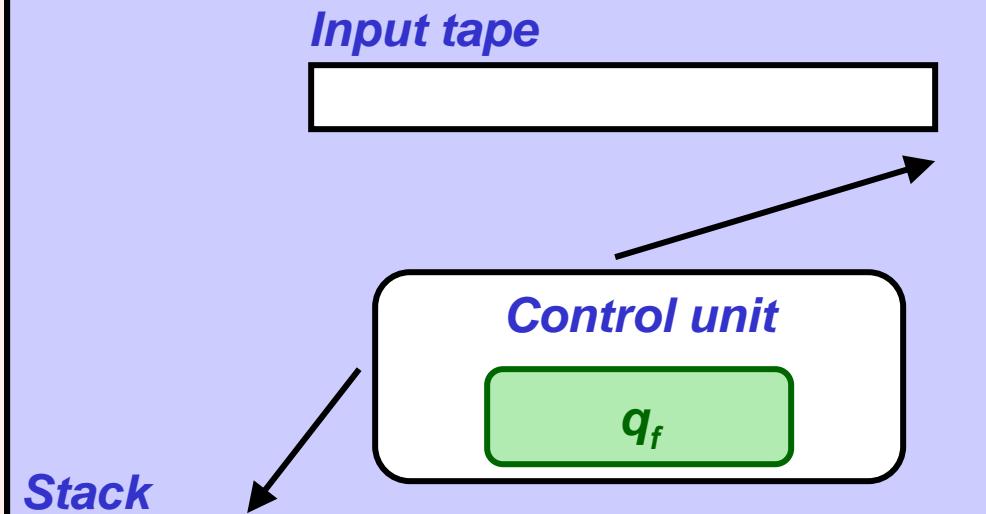
$$(q_0, x, Z_0) \succ_{M_1} (q, \varepsilon, \varepsilon)$$

$$(q_0', x, X_0) \succ_{M_2} (q_0, x, Z_0 X_0) \succ_{M_2}$$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) Q' = Q' \cup \{ q_f \}$$

$$F' = \{ q_f \}$$

$$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{ X_0 \}$$

$$Q' = Q \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$$

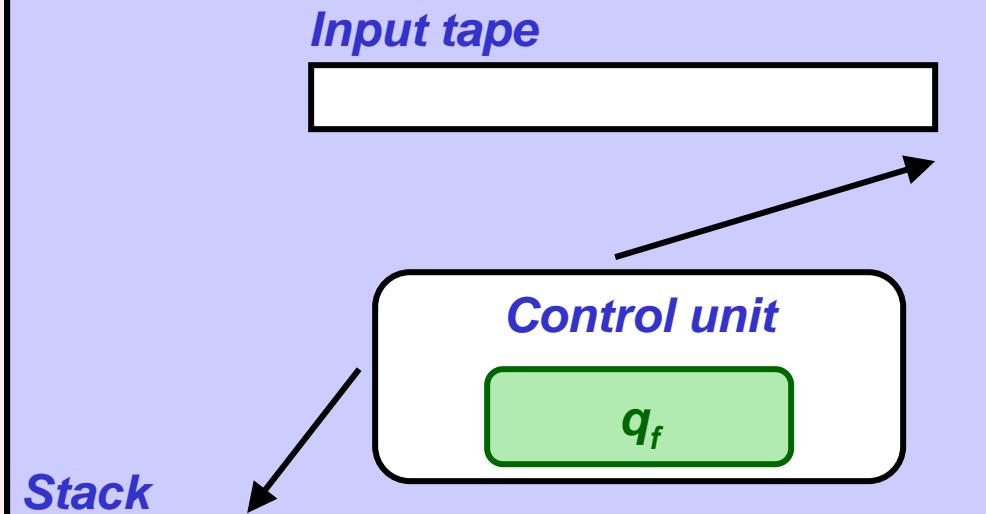
$$(q_0, x, Z_0) \succ_{M_1} (q, \varepsilon, \varepsilon)$$

$$(q_0', x, X_0) \succ_{M_2} (q_0, x, Z_0 X_0) \succ_{M_2} (q, \varepsilon, \varepsilon X_0)$$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) Q' = Q' \cup \{ q_f \}$$

$$F' = \{ q_f \}$$

$$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{ X_0 \}$$

$$Q' = Q \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$$

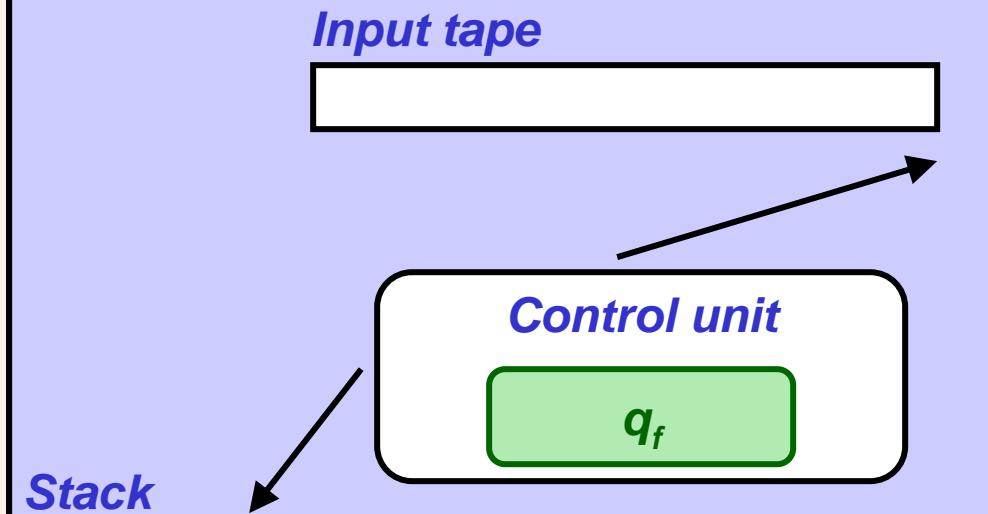
$$(q_0, x, Z_0) \succ_{M_1} (q, \varepsilon, \varepsilon)$$

$$(q_0', x, X_0) \succ_{M_2} (q_0, x, Z_0 X_0) \succ_{M_2} (q, \varepsilon, \varepsilon X_0) \succ_{M_2}$$

## Constructing a PA that accepts by final state from a PA that accepts by empty stack

PA  $M_2 = (Q', \Sigma, \Gamma', \delta', q_0', Z_0', F')$

PA  $M_1 = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$



$$1) \text{ set } \delta'(q, a, Z) = \text{set } \delta(q, a, Z)$$

$$2) Q' = Q' \cup \{ q_f \}$$

$$F' = \{ q_f \}$$

$$(q_f, \varepsilon) \in \delta'(q, \varepsilon, X_0)$$

$$3) Z_0' = X_0$$

$$\Gamma' = \Gamma \cup \{ X_0 \}$$

$$Q' = Q \cup \{ q_0' \}$$

$$\delta'(q_0', \varepsilon, X_0) = \{ (q_0, Z_0 X_0) \}$$

$$(q_0, x, Z_0) \succ_{M_1} (q, \varepsilon, \varepsilon)$$

$$(q_0', x, X_0) \succ_{M_2} (q_0, x, Z_0 X_0) \succ_{M_2} (q, \varepsilon, \varepsilon X_0) \succ_{M_2} (q_f, \varepsilon, \varepsilon)$$



**PA  $M_1 = (\{q_1, q_2\}, \{0, 1\}, \{N, J, K\}, \delta, q_1, K, \emptyset)$**

PA  $M_1 = (\{q_1, q_2\}, \{0, 1\}, \{N, J, K\}, \delta, q_1, K, \emptyset)$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 7)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 8)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 9)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 10)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$

**PA  $M_2 = (\{q_1, q_2, q_0', q_f\}, \{0, 1\}, \{N, J, K, X_0\}, \delta', q_0', X_0, \{q_f\})$**

**PA  $M_1 = (\{q_1, q_2\}, \{0, 1\}, \{N, J, K\}, \delta, q_1, K, \emptyset)$**

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 7)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 8)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 9)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 10)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$

PA  $M_2 = (\{q_1, q_2, q_0', q_f\}, \{0, 1\}, \{N, J, K, X_0\}, \delta', q_0', X_0, \{q_f\})$

PA  $M_1 = (\{q_1, q_2\}, \{0, 1\}, \{N, J, K\}, \delta, q_1, K, \emptyset)$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 7)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 8)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 9)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 10)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

PA  $M_2 = (\{q_1, q_2, q_0', q_f\}, \{0, 1\}, \{N, J, K, X_0\}, \delta', q_0', X_0, \{q_f\})$

PA  $M_1 = (\{q_1, q_2\}, \{0, 1\}, \{N, J, K\}, \delta, q_1, K, \emptyset)$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 7)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 8)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 9)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 10)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

11)  $\delta'(q_1, \varepsilon, X_0) = \{(q_f, \varepsilon)\}$   
12)  $\delta'(q_2, \varepsilon, X_0) = \{(q_f, \varepsilon)\}$

PA  $M_2 = (\{q_1, q_2, q_0', q_f\}, \{0, 1\}, \{N, J, K, X_0\}, \delta', q_0', X_0, \{q_f\})$

PA  $M_1 = (\{q_1, q_2\}, \{0, 1\}, \{N, J, K\}, \delta, q_1, K, \emptyset)$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 7)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 8)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 9)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 10)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

11)  $\delta'(q_1, \varepsilon, X_0) = \{(q_f, \varepsilon)\}$   
12)  $\delta'(q_2, \varepsilon, X_0) = \{(q_f, \varepsilon)\}$

$(q_1, 001100, K) \succ (q_1, 01100, NK) \succ (q_1, 1100, NNK) \succ$   
 $(q_1, 100, JNNK) \succ (q_2, 00, NNK) \succ (q_2, 0, NK) \succ (q_2, \varepsilon, K) \succ (q_2, \varepsilon, \varepsilon)$

PA  $M_2 = (\{q_1, q_2, q_0', q_f\}, \{0, 1\}, \{N, J, K, X_0\}, \delta', q_0', X_0, \{q_f\})$

PA  $M_1 = (\{q_1, q_2\}, \{0, 1\}, \{N, J, K\}, \delta, q_1, K, \emptyset)$

- 1)  $\delta(q_1, 0, K) = \{(q_1, NK)\}$
- 2)  $\delta(q_1, 1, K) = \{(q_1, JK)\}$
- 3)  $\delta(q_1, 0, N) = \{(q_1, NN), (q_2, \varepsilon)\}$
- 4)  $\delta(q_1, 1, N) = \{(q_1, JN)\}$
- 5)  $\delta(q_1, 0, J) = \{(q_1, NJ)\}$
- 6)  $\delta(q_1, 1, J) = \{(q_1, JJ), (q_2, \varepsilon)\}$
- 7)  $\delta(q_2, 0, N) = \{(q_2, \varepsilon)\}$
- 8)  $\delta(q_2, 1, J) = \{(q_2, \varepsilon)\}$
- 9)  $\delta(q_1, \varepsilon, K) = \{(q_2, \varepsilon)\}$
- 10)  $\delta(q_2, \varepsilon, K) = \{(q_2, \varepsilon)\}$

0)  $\delta'(q_0', \varepsilon, X_0) = \{(q_1, KX_0)\}$

11)  $\delta'(q_1, \varepsilon, X_0) = \{(q_f, \varepsilon)\}$   
12)  $\delta'(q_2, \varepsilon, X_0) = \{(q_f, \varepsilon)\}$

$(q_1, 001100, K) \succ (q_1, 01100, NK) \succ (q_1, 1100, NNK) \succ$   
 $(q_1, 100, JNNK) \succ (q_2, 00, NNK) \succ (q_2, 0, NK) \succ (q_2, \varepsilon, K) \succ (q_2, \varepsilon, \varepsilon)$

$(q_0', 001100, X_0) \succ (q_1, 001100, KX_0) \succ (q_1, 01100, NKX_0) \succ (q_1, 1100, NNKX_0) \succ$   
 $(q_1, 100, JNNKX_0) \succ (q_2, 00, NNKX_0) \succ (q_2, 0, NKX_0) \succ (q_2, \varepsilon, KX_0) \succ (q_2, \varepsilon, \varepsilon X_0)$   
 $\succ (q_f, \varepsilon, \varepsilon)$