

Arduinobot

Introduction

Setup

Digital
Twin

ROS 2

Control

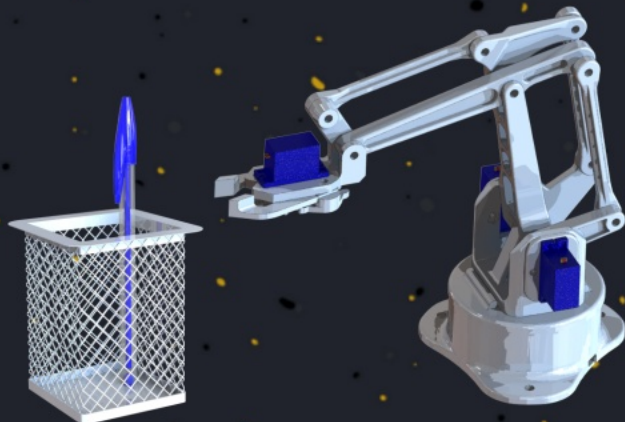
Kinematics

Application

Alexa

Conclusions

Build

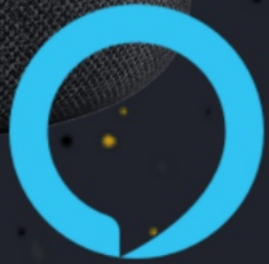




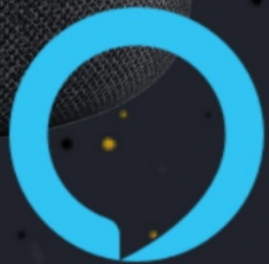






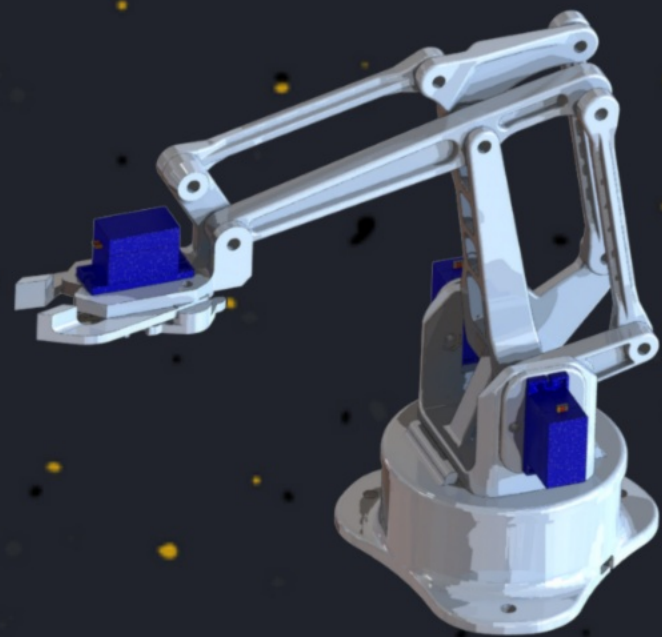


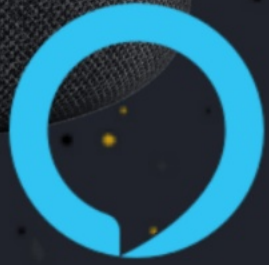
ASK SDK



ASK SDK

ROS 2

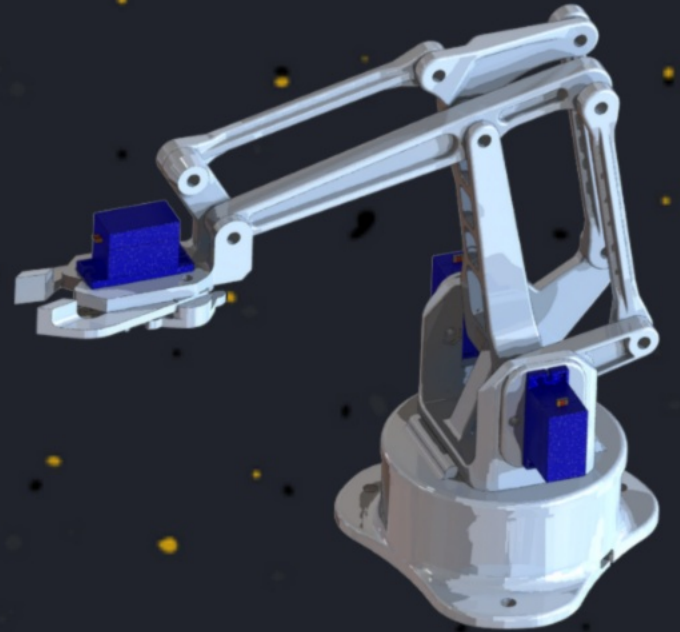


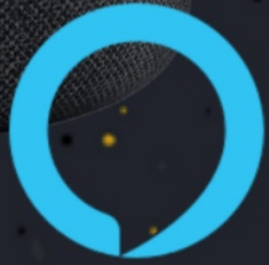


ASK SDK



ROS 2



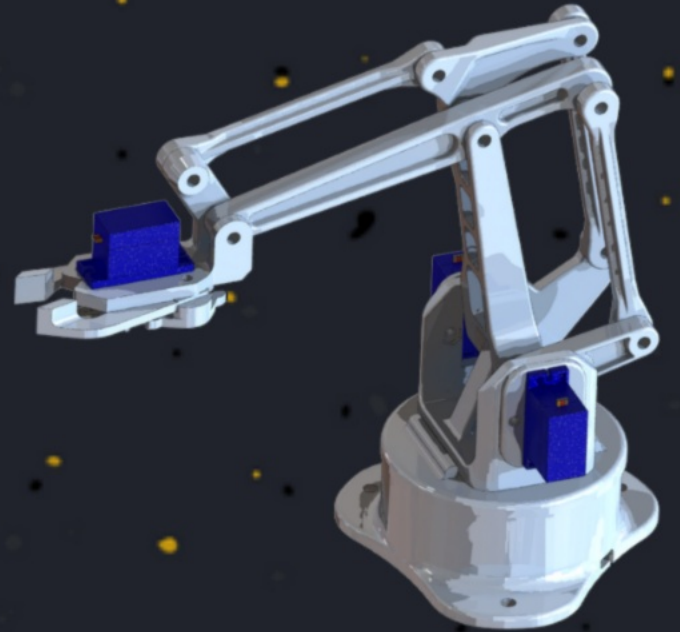


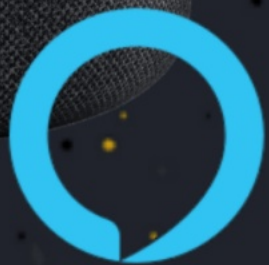
ASK SDK



ngrok

ROS 2



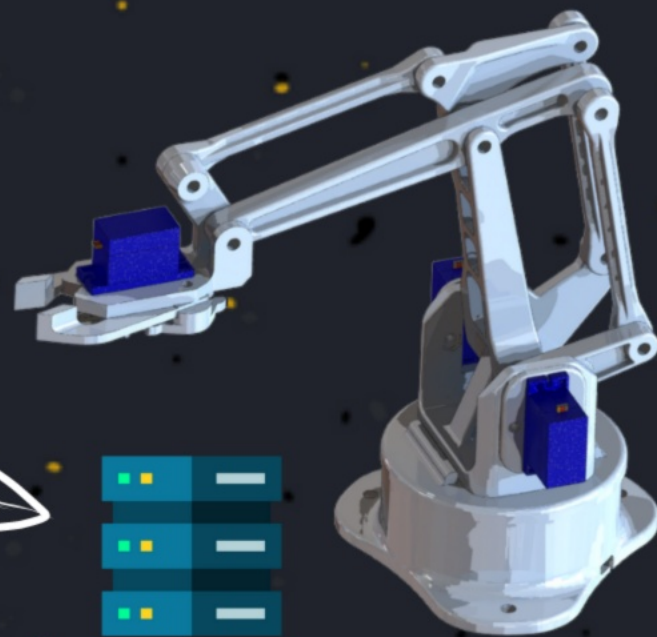


ASK SDK



ngrok

ROS 2



$f(x)$ task_server



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