HWI

Q.1) consider set of observations { \$\overline{\pi}_1, \overline{\pi}_2, \overline{\pi}_1, \overline{\pi}_2, \overline{\pi}_2, \overline{\pi}_1, \overline{\pi}_2, \overline{\

Given: Dala is zero mean.

X is the original dataset matrix (NXd). Let Y be a matrix (NXd) related by linear transformation P.

Covariance Matrix

$$C_X = \frac{1}{N} X_1 X_T$$

$$C_{xii} = \frac{1}{N} \bar{x}_i^T \cdot \bar{x}_i$$

- Diagonal elements are the variances of corresponding features.
- Off-Diagonal elements are covariance b/w features.

$$C_{y} = \frac{1}{N} y. y^{T}$$

Cy -> covariance matrix of Y(optimized)

God: All off-diagonal elements should be zero lie y is decorrelated

Each successive dimension in Y should be rank - ordered according to variance.

$$Cy = \frac{1}{N}(PX)(PX)^{T}$$

$$= \frac{1}{N}PXX^{T}P^{T}$$

$$=$$

Q.2) Gaussian MixIure distribution can be written as linear superposition of gaussian P(x) = E Mx N(x; Hx, Ex) The - mixing coefficient Language OK Special States $(C \geq \mathbb{R} | \mathbb{R}_{k} = 1)$ If Z is discrete latent variable and has a joint distribution p(x,z) with x then p(x) is marginal of p(x, Z) p(x) = \(\sup p(x, 2) = $\sum p(z).p(x|z)$ If z is a one hot vector of dimension k 1.e. ZK ∈ {0,1} with P(2k=1) = TK P(=)= TP PkZk Pk+0 Assuming, data points are drawn independently from dishibution, then log likelihood is given by L(O,x) = lup(x/ w) Tk, Mk, Zk) = \frac{N}{\int_{izi}} ln \left[\frac{K}{\int_{zi}}, P_k \N (\int_i), \mu_k, \int_k)

$$\begin{split} & \left\{ \left(\vec{z}_{k}^{(j)} \right) = P\left(\vec{z}_{k=1} | \vec{x}^{(j)} \right) \\ & = P\left(\vec{z}_{k=1}^{(j)}, \vec{z}_{k}^{(j)} \right) \\ & = P\left(\vec{z}^{(j)} | \vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_{k=1}^{(j)} \right) \\ & = P\left(\vec{x}^{(j)} | \vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_{k=1}^{(j)} \right) \\ & = P\left(\vec{x}^{(j)} | \vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_{k=1}^{(j)} \right) \\ & = P\left(\vec{x}^{(j)} | \vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_{k=1}^{(j)} \right) \\ & = P\left(\vec{x}^{(j)} | \vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_{k=1}^{(j)} \right) \\ & = P\left(\vec{x}^{(j)} | \vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_{k=1}^{(j)} \right) \\ & = P\left(\vec{x}^{(j)} | \vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_{k=1}^{(j)} \right) \\ & = P\left(\vec{x}^{(j)} | \vec{z}_{k=1}^{(j)} \right) P\left(\vec{z}_$$

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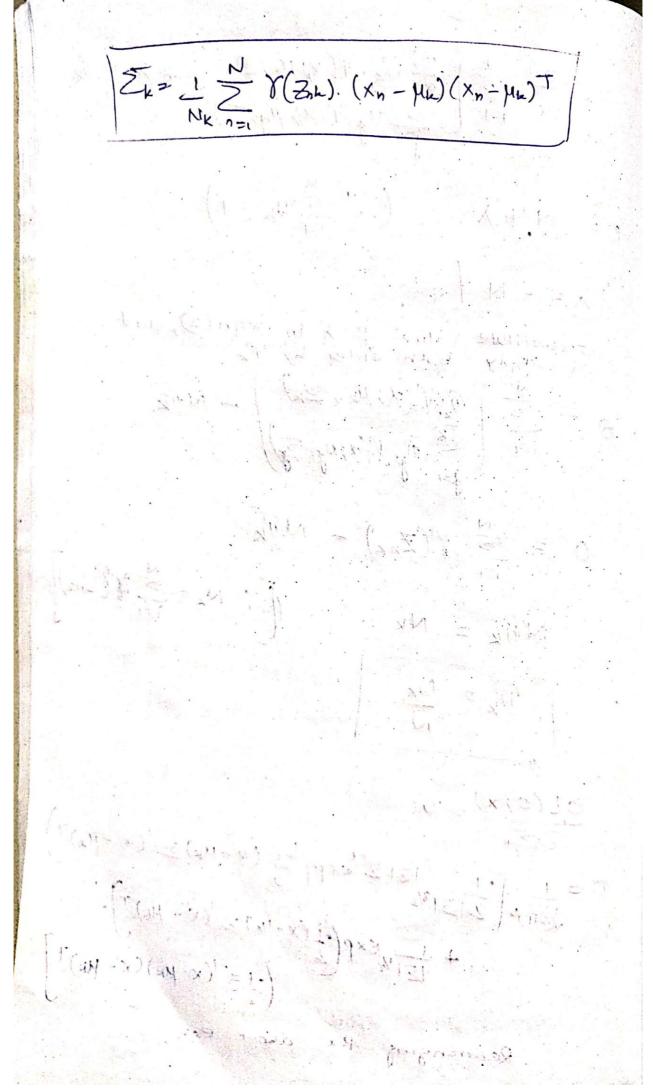
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$$0 = \sum_{i=1}^{N} \left(\sum_{k=1}^{K} \prod_{i} N(x_{i}; \mu_{i}, \Sigma_{k}) \right) + \lambda \sum_{i=1}^{K} \prod_{k} N(x_{i}; \mu_{i}, \Sigma_{k}) + N \prod_{k} N \prod_{k=1}^{K} N(x_{i}; \mu_{i}, \Sigma_{k}) + N \prod_{k=1}^{K} N \prod_{i=1}^{K} N(x_{i}; \mu_{i}, \Sigma_{k}) + N \prod_{i=1}^{K} N \prod_{k=1}^{K} N$$



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