```
(D@D)(x)(t)
                                         D^{(2)}(x)(t)
                                                                                             (1)
1.
> ec:=diff(x(t),t$2)+w0*w0*x(t)=0
                               ec := \frac{d^2}{At^2} x(t) + w0^2 x(t) = 0
                                                                                             (2)
> dsolve(ec,x(t))
                         x(t) and x cannot both appear in the given ODE.
> dsolve(ec,x(t))
     or, (in dsolve) x(t) and x cannot both appear in the given ODE.
> dsolve(x)
Error, (in dsolve) expecting an ODE or a set or list of ODEs.
> dsolve(ec)
     or, (in dsolve) x(t) and x cannot both appear in the given ODE.
> with (DETools)
[AreSimilar, Closure, DEnormal, DEplot, DEplot3d, DEplot polygon, DFactor, DFactorLCLM,
                                                                                             (3)
   DFactorsols, Dchangevar, Desingularize, FindODE, FunctionDecomposition, GCRD, Gosper,
    Heunsols, Homomorphisms, IVPsol, IsHyperexponential, LCLM, MeijerGsols,
    MultiplicativeDecomposition, ODEInvariants, PDEchangecoords, PolynomialNormalForm,
    RationalCanonicalForm, ReduceHyperexp, RiemannPsols, Xchange, Xcommutator, Xgauge,
    Zeilberger, abelsol, adjoint, autonomous, bernoullisol, buildsol, buildsym, canoni, caseplot,
    casesplit, checkrank, chinisol, clairautsol, constcoeffsols, convertAlg, convertsys, dalembertsol,
    dcoeffs, de2diffop, dfieldplot, diff table, diffop2de, dperiodic sols, dpolyform, dsubs, eigenring,
    endomorphism charpoly, equinv, eta k, eulersols, exactsol, expsols, exterior power, firint,
   firtest, formal sol, gen exp, generate ic, genhomosol, gensys, hamilton eqs,
    hypergeometricsols, hypergeomsols, hyperode, indicialeq, infgen, initialdata, integrate sols,
    intfactor, invariants, kovacicsols, leftdivision, liesol, line int, linearsol, matrixDE,
    matrix riccati, maxdimsystems, moser reduce, muchange, mult, mutest, newton polygon,
    normalG2, ode int y, ode y1, odeadvisor, odepde, parametricsol, particularsol, phaseportrait,
   poincare, polysols, power equivalent, rational equivalent, ratsols, redode, reduceOrder,
    reduce order, regular parts, regularsp, remove RootOf, riccati system, riccatisol, rifread,
    rifsimp, rightdivision, rtaylor, separablesol, singularities, solve group, super reduce, symgen,
    symmetric power, symmetric product, symtest, transinv, translate, untranslate, varparam,
   zoom]
> dsolve(ec,x(t))
                              x(t) = c_1 \sin(w\theta t) + c_2 \cos(w\theta t)
                                                                                             (4)
> dsolve(ec,x(t))
                              x(t) = c_1 \sin(w\theta t) + c_2 \cos(w\theta t)
                                                                                             (5)
```

(6)

rez:=dsolve(ec,x(t))

```
rez := x(t) = c_1 \sin(w\theta t) + c_2 \cos(w\theta t)
                                                                                                                                      (6)
 > ysol:=unapply(rhs(rez), t, w0, _C1, _C2)
                               ysol := (t, w\theta, c_1, c_2) \mapsto c_1 \cdot \sin(t \cdot w\theta) + c_2 \cdot \cos(t \cdot w\theta)
                                                                                                                                      (7)
 > subs(_C1=R*cos(d),_C2=R*sin(d),rez)
                                   x(t) = R\cos(d)\sin(w\theta t) + R\sin(d)\cos(w\theta t)
                                                                                                                                      (8)
> combine(ysol(t,w0,R*cos(d),R*sin(d)))
                                                         R\sin(w0\ t+d)
                                                                                                                                      (9)
 c) > ecsol:=dsolve({ec, x(0)=x0, D(x)(0)=v0}, x(t))
                                    ecsol := x(t) = \frac{v\theta \sin(w\theta t)}{w\theta} + x\theta \cos(w\theta t)
                                                                                                                                    (10)
 \stackrel{=}{>} ec2:=R*cos(d)=v0/w0
                                                  ec2 := R\cos(d) = \frac{v\theta}{w\theta}
                                                                                                                                    (11)
 > ec3:=R*sin(d)=x0
                                                    ec3 := R \sin(d) = x0
                                                                                                                                    (12)
 > solve({ec2,ec3},{R,d})

\begin{cases}
R = \frac{RootOf(-x0^2 w0^2 + Z^2 - v0^2)}{w0}, d = \arctan\left(\frac{x0 w0}{RootOf(-x0^2 w0^2 + Z^2 - v0^2)}\right),
\end{cases}

                                                                                                                                    (13)
      \frac{v\theta}{RootOf(-x\theta^2 w\theta^2 + Z^2 - v\theta^2)}
 > allvalues(%)
 \left\{ R = \frac{\sqrt{x0^2 w0^2 + v0^2}}{w0}, d = \arctan\left(\frac{x0 w0}{\sqrt{x0^2 w0^2 + v0^2}}, \frac{v0}{\sqrt{x0^2 w0^2 + v0^2}}\right) \right\}, \left\{ R = \frac{\sqrt{x0^2 w0^2 + v0^2}}{\sqrt{x0^2 w0^2 + v0^2}} \right\}
                                                                                                                                    (14)
     -\frac{\sqrt{x0^{2} w0^{2} + v0^{2}}}{w0}, d = \arctan\left(-\frac{x0 w0}{\sqrt{x0^{2} w0^{2} + v0^{2}}}, -\frac{v0}{\sqrt{x0^{2} w0^{2} + v0^{2}}}\right)\right\}
> ysol((2*pi)/w0, w0,
 d) > expr:=sqrt(w0^2*39.24^2 + 0^2)/w0=15
                                           expr := \frac{39.24000000 \sqrt{w0^2}}{w0} = 15
                                                                                                                                    (15)
> solve(expr,w0)
> w0:=sqrt(9.81/0.3924)
                                                   w0 := 5.000000000
                                                                                                                                    (16)
> x0:=0.15
                                                           x0 := 0.15
                                                                                                                                    (17)
```

```
v\theta := 0 
d := \arctan(x0*w0/\operatorname{sqrt}(w0^2*x0^2 + v0^2), \ v0/\operatorname{sqrt}(w0^2*x0^2 + v0^2))
d := \arctan\left(\frac{1.000000000 \ w\theta}{\sqrt{w\theta^2}}, 0\right) 
d := \arctan(x0*w0/\operatorname{sqrt}(w0^2*x0^2 + v0^2), \ v0/\operatorname{sqrt}(w0^2*x0^2 + v0^2))
d := 1.570796327 
(20)
```