

# Aidan Reilly

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## EXPERIENCE

### Robotics Software Engineer Intern

*Komatsu Mining*

05/2024 - current

*Warrendale, PA*

- Developing autonomous vehicles for underground mining using **Unreal Engine 5** and **ROS2**

### Robotics Software Engineer Intern

*Komatsu Mining*

05/2023 - 08/2023

*Warrendale, PA*

- Developed autonomous mining vehicles, increasing efficiency by 25% and driving \$1.1 billion in annual revenue
- Streamlined development with **Docker** and **Azure DevOps** in a **Linux** environment
- Increased performance by 20x using **CUDA**, improving the quality of simulations and pointcloud processing
- Utilized the latest technologies of **C++**, **Python**, **3D Lidar**, **Radar**, **IMU**, **ROS2**, **SLAM**, **NAV2**
- Presented work to Vice Presidents, resulting in increased funding and more projects

### Undergraduate Teaching Assistant - Discrete Mathematics

*University of Pittsburgh*

08/2022 - 05/2023

*Pittsburgh, PA*

- Supported students through weekly recitation, tutoring and office hours; managed grading and provided tutoring

## EDUCATION

### University of Pittsburgh

*B.S. in Computer Science, Minor in Mathematics, GPA: 3.6*

08/2021 - 05/2024

### Delaware County Community College

*A.S. in Computer Science, GPA: 3.9*

08/2019 - 05/2021

**Coursework:** Deep Learning, Computer Vision, AI, Data Structures & Algorithms, C++, Python

## PROJECTS

### ANA - Autonomous Navigation Assembly | [https://github.com/Razzi86/ana\\_bot](https://github.com/Razzi86/ana_bot)

08/2023 - current

- Engineered an autonomous robot car, integrating state of the art tools like **C++**, **Python**, **ROS2**, **SLAM**, **NAV2**, **Lidar**, **Depth**, **Jetson Orin**, **Arduino**, and **Encoder Motors**
- Performs sensor fusion to achieve robust localization, control, and path planning

### MIT-PITT-RW Perception Team | <https://driverless.mit.edu/mitpitttw>

01/2024 - current

- Contributed to an autonomous racecar by developing ML models for real-time vehicle and obstacle recognition
- Modified docker to work on **ARM64 computer architecture**, enabling development on the NVIDIA Jetson Orin

### Clothing Segmentation Extension | <https://github.com/DW-Han/fashion-segmentation-repo>

02/2022 - 04/2023

- Led the development of an AI-based Chrome extension for live clothing segmentation, achieving %86 accuracy
- Utilized **Pytorch**, **TensorFlow** for model, **JavaScript**, **CSS**, **HTML** for front and back end

### Box Game | [https://github.com/Razzi86/Box\\_Game](https://github.com/Razzi86/Box_Game)

05/2019 - 07/2019

- Engineered a two-player handheld game using Raspberry Pi and electrical engineering

## SKILLS

**Languages:** C/C++, Python, JavaScript, Java, MATLAB, CUDA

**Tools:** Docker, Azure Devops, Git/GitHub, NVIDIA Jetson, Unreal Engine 5, Gazebo, ROS2

**Technologies:** PyTorch, TensorFlow, OpenCV, CUDA, Ubuntu, PyQt5, SLAM, Nav2, PCL, ICP, YOLO, CAD