

Aidan Reilly

610-608-8166 | arr160@pitt.edu | [linkedin.com/in/aidan-r-reilly](https://www.linkedin.com/in/aidan-r-reilly) | github.com/Razzi86 | [portfolio](#)

EXPERIENCE

Komatsu Mining

05/2024 - present

Robotics Software Engineer Intern

Pittsburgh, PA

- Developed software for autonomous mining vehicles in various underground GPS-denied environments.
- Performed and iteratively optimized sensor fusion for robust mapping, path planning, control, and autonomy.
- Increased efficiency by 30%, potentially driving \$800m in annual revenue; drastically improved safety.
- Focus in Mapping and Perception; Used ROS2, LiDAR, Radar, Odometry, SLAM, Unreal Engine 5.

Komatsu Mining

05/2023 - 08/2023

Robotics Software Engineer Intern

Pittsburgh, PA

- Designed lidar perception algorithms to segment objects, match features, and estimate volume and velocity.
- Implemented nodes that aligned pointclouds for multi-vehicle localization and sensor calibration.
- Wrote an executable program that procedurally generated simulated environments of underground mines.
- Worked with a diverse group of engineers, wrote and documented clean code, and maintained code databases.

University of Pittsburgh

08/2022 - 05/2023

Teaching Assistant, Discrete Mathematics

Pittsburgh, PA

- Supported students through weekly recitation, tutoring, and office hours.
- Managed grading for homework and quizzes.

PROJECTS — [PORTFOLIO](#)

ANA (Autonomous Navigation Assembly) | github.com/Razzi86/ana_bot

08/2023 - present

- Designed and developed an autonomous car that fuses lidar and camera to perform autonomous navigation
- Researched and designed multiple prototypes, implementing perception, control, and path planning

MIT-PITT-RW, Perception Team | driverless.mit.edu/mitpitttw

01/2024 - present

- Developing software for an autonomous racecar that competes at speeds of over 150mph.
- Trained machine learning models for real-time obstacle recognition and avoidance using lidar, camera, and radar

Professional Tournament Poker

04/2019 - present

- Coached by super pros Chance Kornuth (#1 worldwide, 2020), James Romero (World Poker Tour Champ, 2016)
- Extensive mastery of game theory, statistics, and probability; Developed UBerkely poker course; Private coach

Clothing Segmentation Extension | github.com/DW-Han/fashion-segmentation-rep

08/2023 - 09/2023

- Developed a Chrome extension for live clothing segmentation and classification, achieving 86% accuracy
- Placed 2nd overall in the 2023 SteelHacks hackathon, winning the "User Experience" category

EDUCATION - *Combined Cumulative GPA: 3.72*

University of Pittsburgh

2024

Honors - B.S. in Computer Science, Minor in Mathematics, GPA: 3.6

Delaware County Community College

2021

Honors - A.S. in Computer Science, GPA: 3.9

Coursework: Data Structures, Computer Vision, Deep Learning, Software Quality, Operating Systems

SKILLS

Languages: C++, Python, CUDA, MATLAB, MIPS, x86, Blueprint

Development: OpenCV, PyTorch, TensorFlow, JUnit, Arduino, Docker, Azure DevOps, Git, Jetson, YOLO, CAD

Robotics: ROS2, Perception, Mapping, SLAM, Nav2, ICP, Unreal Engine 5, Gazebo, Linux/Ubuntu