Aidan Reilly

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EXPERIENCE

Robotics Software Engineer Intern

05/2024 - present

Komatsu Mining

Warrendale, PA

- Developed autonomous vehicle software for underground mining in complex, GPS-denied environments
- Implemented perception and navigation within Unreal Engine 5 using ROS2, LiDAR, RADAR, and Odometry

Robotics Software Engineer Intern

05/2023 - 08/2023

Komatsu Mining

Warrendale, PA

- Developed the core autonomy stack for underground mining vehicles, focusing on perception to localize robots and map out mines, and control for autonomous navigation; used ROS2, PCL, OpenCV, SLAM, NAV2
- Simulation of autonomous vehicles increased operational efficiency by 30%, potentially decreasing labor costs and increasing annual revenue by \$800 million.
- Increased simulation performance by 8x through GPU parallelization, dramatically decreasing development time and expediting real-world testing
- Strong experience in software development, writing clean code, maintaining and organizing code databases, and producing detailed documentation
- Utilized ROS2, C++, Python, Linux, LiDAR, Docker, Azure DevOps, and various other common robotics tools

Undergraduate Teaching Assistant - Discrete Mathematics

08/2022 - 05/2023

University of Pittsburgh

Pittsburgh, PA

• Supported students through weekly recitation, tutoring and office hours; managed grading and provided tutoring

Projects — Portfolio

ANA - Autonomous Navigation Assembly | github.com/Razzi86/ana_bot

08/2023 - present

- Created an autonomous robot car that uses robotics sensors to navigate; uses NVIDIA Jetson, ROS2, and LiDAR
- Researched and implemented optimized methods of perception, control, and navigation

MIT-PITT-RW Autonomous Racecar - Perception Team | driverless.mit.edu/mitpittrw 01/2024 - present

- Developed machine learning models for real-time vehicle and obstacle recognition using LiDAR and Cameras
- Implemented Computer Vision, Machine Learning, and Deep Learning with PyTorch, TensorFLow, and OpenCV

Clothing Segmentation Extension | github.com/DW-Han/fashion-segmentation-rep

08/2023 - 09/2023

- Led the development of an AI-based Chrome extension for live clothing segmentation, achieving %86 accuracy
- 2nd place overall in the 2023 SteelHacks hackathon, winning the "User Experience" judging criteria

Box Game | github.com/Razzi86/Box_Game

08/2023 - 11/2023

• Engineered a two-player handheld game using Raspberry Pi and electrical engineering

EDUCATION

University of Pittsburgh

2024

Honors - B.S. in Computer Science, Minor in Mathematics, GPA: 3.6

Delaware County Community College

2021

Honors - A.S. in Computer Science, GPA: 3.9

Coursework: Deep Learning, Computer Vision, Data Structures & Algorithms, Operating Systems, AI, C++

SKILLS

Languages: C++, Python, MATLAB, Java, URDF, Blueprint, Javascript, CSS, HTML, C#, C,

Tools: Docker, Azure Devops, Git/GitHub, NVIDIA Jetson, Unreal Engine 5, Gazebo, ROS2

Technologies: PyTorch, TensorFlow, OpenCV, CUDA, Ubuntu, PyQt5, SLAM, Nav2, PCL, ICP, YOLO, CAD