## Architectures of Intelligence Assignment 5

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## 1 Part one

- a. A screenshot of the values of ensembles  $\mathbf{a}$ ,  $\mathbf{b}$  and  $\mathbf{c}$  can be found at Figure 1. Note that ensembles  $\mathbf{a}$  and  $\mathbf{b}$  react to changes rather quickly, while ensemble  $\mathbf{c}$  adjusts more slowly. This is due to the fact that the synaptic constant is set to its default value (5ms) for the connections  $stimulus \to a$ ,  $a \to b$  and  $b \to c$ , whereas the connection used to create the simple memory,  $c \to c$ , has a synaptic constant set at 100ms.
- b. A screenshot of the tuning curves of ensemble  $\mathbf{a}$  can be found at Figure 2. The tuning curves represent at which value of x (the input) the neurons respond most frequently. In order to give a good representation of the input value as the output value, many neurons are tuned to different "sections" of the range of the input value, in a way "specializing" in recognizing a specific value and firing most often when their value is the input value. This means that together, the neurons will generate a value that will resemble the input value, as there are 100 neurons which is plenty to represent a range from -1 to 1.
- c. Ensemble **a** has the same value as the stimulus.
  - Ensemble **b** has a value of -0.5, because the connection  $a \to b$  uses the function **centered\_square(a)** which takes the value in **a** and applies the function (a\*a-0.5). 0\*0-0.5=0.5
  - Ensemble  $\mathbf{c}$  has a value of around -1.1. This is because the input to c remains non-zero, causing the integrator (i.e. the simple memory) to saturate quickly, meaning it will tend to its extreme value.

## 2 Part two

A screenshot showing the model running from a tiger can be found at Figure 3.

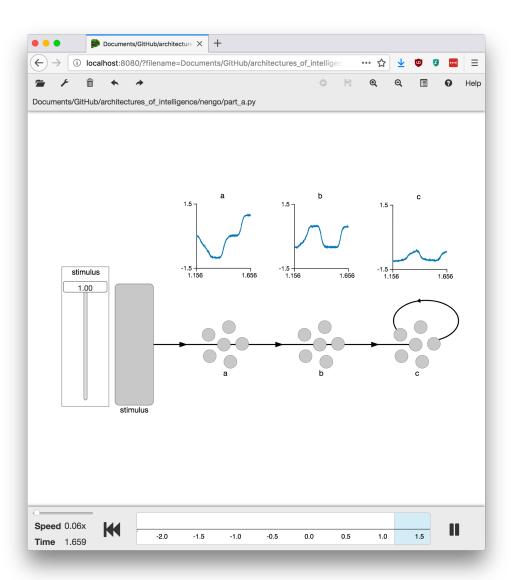


Figure 1: Values for ensembles a, b, and c, while running the model and varying the stimulus, demonstrating the effects of the various connections

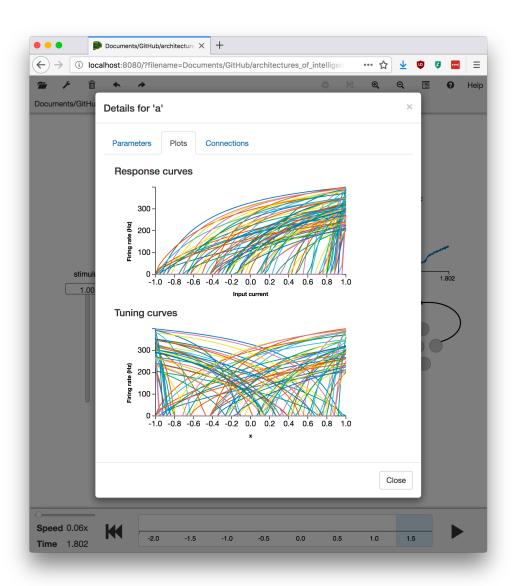


Figure 2: A screenshot of the tuning curves of ensemble a

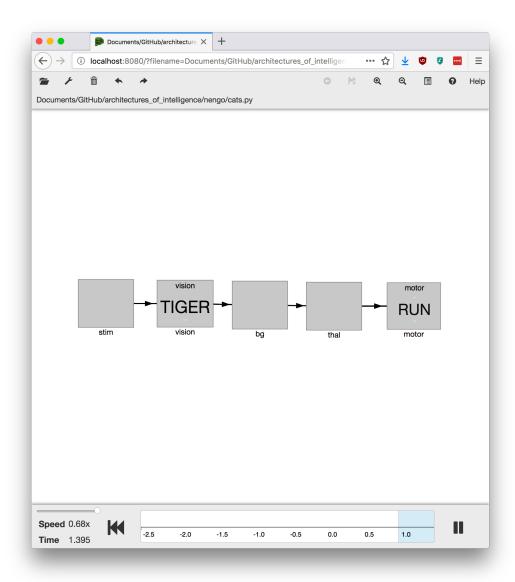


Figure 3: A screenshot showing the model running from a tiger