

例 1.1 $\therefore K = \begin{bmatrix} f_x & 0 & c_x \\ 0 & f_y & c_y \\ 0 & 0 & 1 \end{bmatrix}$

$\therefore \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} = K \cdot \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}$

$\therefore X =$

例 1.1 $K = \begin{bmatrix} f_x & 0 & c_x \\ 0 & f_y & c_y \\ 0 & 0 & 1 \end{bmatrix}$

$\therefore \begin{cases} x = \frac{X \cdot f_x}{Z} + c_x \\ y = \frac{Y \cdot f_y}{Z} + c_y \end{cases}$

2. 齐次坐标下 $\lambda \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} = \begin{bmatrix} f_x & 0 & c_x & 0 \\ 0 & f_y & c_y & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \\ 1 \end{bmatrix}$

$\therefore \begin{cases} x = \frac{f_x \cdot X + c_x \cdot Z}{\lambda} \\ y = \frac{f_y \cdot Y + c_y \cdot Z}{\lambda} \end{cases} \quad \lambda = Z$

例 2.1 $H = \begin{bmatrix} 1.207 & 0.586 & 1.0 \\ 2.207 & 3.242 & 2.0 \\ 1.0 & 2.0 & 1.0 \end{bmatrix}$

$|K| = 1$

$$H_c = \begin{bmatrix} s \cdot R & t \\ 0^T & 1 \end{bmatrix} \quad \text{tr} R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$H_A = \begin{bmatrix} K & 0 \\ 0^T & 1 \end{bmatrix} \quad K = \begin{bmatrix} k_{11} & k_{12} \\ 0 & k_{22} \end{bmatrix}, \quad k_{11} \cdot k_{22} = 1$$

$k_{11} > 0, k_{12} > 0, k_{22} > 0$

$$H_p = \begin{bmatrix} I & 0 \\ v^T & v \end{bmatrix}$$

$$H = \begin{bmatrix} A & t \\ v^T & v \end{bmatrix}$$

$$H_c \cdot H_A \cdot H_p = \begin{bmatrix} sR \cdot K & t \\ 0^T & 1 \end{bmatrix} \cdot \begin{bmatrix} I & 0 \\ v^T & v \end{bmatrix}$$

$$= \begin{bmatrix} sRK + t \cdot v^T & vt \\ v^T & v \end{bmatrix} = \begin{bmatrix} 1.707 & 0.586 & 1.0 \\ 2.707 & 3.242 & 2.0 \\ 1.0 & 2.0 & 1.0 \end{bmatrix}$$

$$\therefore sRK + t \cdot v^T = \begin{bmatrix} 1.707 & 0.586 \\ 2.707 & 3.242 \end{bmatrix} \quad vt = \begin{bmatrix} 1.0 \\ 2.0 \end{bmatrix} \quad v = 1.0, v^T = [1.0 \ 2.0]$$

$$\therefore t = \begin{bmatrix} 1.0 \\ 2.0 \end{bmatrix} \Rightarrow s \cdot R \cdot K = \begin{bmatrix} 0.707 & -1.414 \\ 0.707 & 4.242 \end{bmatrix}$$

$$\therefore s \cdot |R| \cdot |K| = 4$$

$$\therefore s^2 = 4 \Rightarrow s = 2$$

$$\therefore R \cdot K = \frac{1}{2} \begin{bmatrix} 0.707 & -1.414 \\ 0.707 & 4.242 \end{bmatrix} = \begin{bmatrix} 1 & -2 \\ 1 & 4 \end{bmatrix}$$

$$s \cdot \begin{bmatrix} k_{11} \cos \theta & k_{12} \cos \theta - k_{22} \sin \theta \\ k_{11} \sin \theta & k_{12} \sin \theta + k_{22} \cos \theta \end{bmatrix} = \begin{bmatrix} 0.707 & -1.414 \\ 0.707 & 4.242 \end{bmatrix}$$

$$\therefore k_{11} = \frac{1}{2}, \theta = \frac{\pi}{4}, k_{22} = \frac{1}{2}, k_{12} = 1$$

$$\therefore H_3 = \begin{bmatrix} \sqrt{2} & -\sqrt{2} & 1 \\ \sqrt{2} & \sqrt{2} & 2 \\ 0 & 0 & 1 \end{bmatrix} \quad H_A = \begin{bmatrix} \frac{1}{2} & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad H_P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$

$$\text{例 3.1.} \quad \begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{bmatrix} a_{11} & a_{12} & t_x \\ a_{21} & a_{22} & t_y \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{pmatrix} x \\ y \\ 1 \end{pmatrix} \Rightarrow Z' = H_A Z$$

设有 $AB \parallel CD$.

$$A: (x_1, y_1), B: (x_2, y_2), C: (x_3, y_3), D: (x_4, y_4)$$

$$\therefore \frac{|AB|^2}{|CD|^2} = \frac{(x_2 - x_1)^2 + (y_2 - y_1)^2}{(x_3 - x_4)^2 + (y_3 - y_4)^2}$$

$$\therefore \frac{|AB|}{|CD|} = \sqrt{\frac{(x_1 - x_2)^2 + (y_1 - y_2)^2}{(x_3 - x_4)^2 + (y_3 - y_4)^2}} = \sqrt{\frac{(Z_A - Z_B)^T \cdot (Z_A - Z_B)}{(Z_C - Z_D)^T \cdot (Z_C - Z_D)}}$$

$$\therefore \frac{Z'_A - Z'_B}{Z'_C - Z'_D} = \frac{H_A \cdot Z_A - H_A \cdot Z_B}{H_A \cdot Z_C - H_A \cdot Z_D} = \frac{H_A \cdot (Z_A - Z_B)}{H_A \cdot (Z_C - Z_D)}$$

$$\therefore |A'B'|^2 = (Z'_A - Z'_B)^T \cdot (Z'_A - Z'_B) = (H_A \cdot (Z_A - Z_B))^T \cdot (H_A \cdot (Z_A - Z_B))$$

$$= (Z_A - Z_B)^T \cdot H_A^T \cdot H_A \cdot (Z_A - Z_B)$$

$$= (Z_A - Z_B)^T \cdot \begin{pmatrix} A^2 & A^t \\ t_A & 1 \end{pmatrix} \cdot (Z_A - Z_B)$$

$$\text{同理 } |C'D'|^2 = (Z_C - Z_D)^T \cdot \begin{pmatrix} A^2 & A^t \\ t_A & 1 \end{pmatrix} \cdot (Z_C - Z_D)$$

$$\text{设 } (\bar{x}_A - \bar{x}_B)^T = (\bar{x}_{AB}^T, 0)^T, (\bar{x}_C - \bar{x}_D)^T = (\bar{x}_{CD}^T, 0)^T$$

$$\therefore \frac{|AB|}{|CD|} = \frac{\bar{x}_{AB}^T \cdot \bar{x}_{AB}}{\bar{x}_{CD}^T \cdot \bar{x}_{CD}}$$

$$\begin{aligned} \left| \frac{A'B'}{C'D'} \right|^2 &= \frac{(\bar{x}_{AB}^T \ 0) \begin{pmatrix} A^2 & At \\ -tA & 1 \end{pmatrix} \begin{pmatrix} \bar{x}_{AB} \\ 0 \end{pmatrix}}{(\bar{x}_{CD}^T \ 0) \begin{pmatrix} A^2 & At \\ -tA & 1 \end{pmatrix} \begin{pmatrix} \bar{x}_{CD} \\ 0 \end{pmatrix}} \\ &= \frac{(\bar{x}_{AB}^T A^2 \bar{x}_{AB} \ \bar{x}_{AB}^T A t) \cdot \begin{pmatrix} \bar{x}_{AB} \\ 0 \end{pmatrix}}{(\bar{x}_{CD}^T A^2 \bar{x}_{CD} \ \bar{x}_{CD}^T A t) \cdot \begin{pmatrix} \bar{x}_{CD} \\ 0 \end{pmatrix}} \\ &= \frac{\bar{x}_{AB}^T A^2 \bar{x}_{AB}}{\bar{x}_{CD}^T A^2 \bar{x}_{CD}} \\ &= \frac{(x_1 - x_2, y_1 - y_2) \cdot A^2 \begin{pmatrix} x_1 - x_2 \\ y_1 - y_2 \end{pmatrix}}{(x_3 - x_4, y_3 - y_4) \cdot A^2 \begin{pmatrix} x_3 - x_4 \\ y_3 - y_4 \end{pmatrix}} \end{aligned}$$

$$\therefore \varphi_{AB} // \varphi_{CD}$$

$$\therefore \frac{|AB|}{|CD|} = k \Rightarrow \bar{x}_{AB} = k \cdot \bar{x}_{CD}$$

$$\therefore \left| \frac{A'B'}{C'D'} \right|^2 = \frac{k \cdot \bar{x}_{CD}^T A^2 \bar{x}_{CD} - k \cdot \bar{x}_{CD}}{\bar{x}_{CD}^T A^2 \bar{x}_{CD}} = k^2$$

$$\therefore \left| \frac{A'B'}{C'D'} \right| = k \text{ 不变.}$$