## Invatarea prin recompensa

## **Value Iteration**

## **Algoritmul Value Iteration**

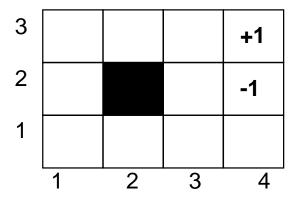
Calculeaza utilitatea starilor (recompensa pe termen lung):

$$\mathbf{U}_{t+1}(\mathbf{S}_i) = \mathbf{R}(\mathbf{S}_i) + \delta \max_{a} \sum_{j} \mathbf{T}(\mathbf{S}_i, \mathbf{a}, \mathbf{S}_j) * \mathbf{U}_t(\mathbf{S}_j)$$

distanta(U, U') = 
$$\frac{1}{S} \sqrt{\sum_{i=1}^{S} (U(S_i) - U'(S_i))^2}$$
, S = numarul de stari

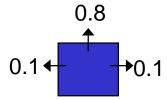
Politica optima 
$$\pi * (S_i) = \arg \max_{a} \sum_{j} (R(S_i) + T(S_i, a, S_j) * U(S_j))$$

Exemplu: grid 3 x 4



- Doua stari terminale cu recompensele +1 si -1
- Toate celelalte stari au recompensele -0.04
- Deplasarea se poate face in directiile Nord/Sud/Est/Vest

Exemplu: Modelul mediului T - deplasare in directia N



Exemplu de calcul a utilitatii pentru starea  $S(\delta = 1)$ 

