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# REPORT 2

## Minimizing Dockerfiles

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Bucharest, 2025

I want first and foremost to thank my advisor, Prof. Răzvan Deaconescu, for his guidance and support throughout this project. His expertise and insights have been invaluable in shaping my understanding of the subject matter and in helping me navigate the challenges I faced during this endeavor.

I also want to thank my friends and family without whom these 4 years would have been so much harder.

# Contents

<b>Acknowledgements</b>	<b>i</b>
<b>1 Introduction</b>	<b>1</b>
<b>2 Background</b>	<b>2</b>
2.1 A brief history of containers . . . . .	2
2.2 The anatomy of a container . . . . .	2
2.3 Related work . . . . .	4
<b>3 Motivation and Objectives</b>	<b>5</b>
<b>4 Use Cases</b>	<b>6</b>
<b>5 Building Blocks</b>	<b>8</b>
<b>6 Architecture Overview</b>	<b>10</b>
6.1 Static Analysis . . . . .	10
6.2 Dynamic Analysis . . . . .	10
6.3 Brute Force . . . . .	11
<b>7 Implementation Details</b>	<b>12</b>
7.1 Overview . . . . .	12
7.2 Project Structure . . . . .	12
7.3 Preprocessing . . . . .	13
7.4 Static Analysis . . . . .	14
7.5 Dynamic Analysis . . . . .	16
<b>8 Status and Planned Work</b>	<b>19</b>
8.1 Status . . . . .	19
8.2 Planned Work . . . . .	19

# List of Figures

2.1	Containers vs VMs . . . . .	2
2.2	Container layers . . . . .	3
4.1	High-level comparison of the software components of traditional VMs (a), containers (b), containers in VMs (c) with unikernels (d). . . . .	6
5.1	High-level architecture of the application . . . . .	8
6.1	Brute force approach to finding the minimal Dockerfile . . . . .	11
7.1	Language execution speed comparison [6] . . . . .	12

# List of Listings

2.1	Sample Dockerfile . . . . .	3
2.2	Sample Multi-stage Dockerfile . . . . .	3
4.1	Sample Kraftfile . . . . .	6
6.1	ldd command . . . . .	10
6.2	strace command . . . . .	10
7.1	Project Structure . . . . .	12
7.2	Go DockerConfig structure . . . . .	13
7.3	Dockerfile.minimal.template . . . . .	14
7.4	ldd parser function . . . . .	14
7.5	File util functions . . . . .	15
7.6	File util functions . . . . .	16
7.7	File util functions . . . . .	17

# Chapter 1

## Introduction

*“But ... it works on my machine...”* is a phrase no developer wants to hear. It is a phrase that highlights both the frustration of software engineers and the complexity of the software development life cycle. The most common cause for this issue arising lies in the mismatch between the developer’s local environment and the production environment where the code is run [15]. On traditional deployments on a physical server or virtual machine, it is up to the developer to ensure that all the necessary configurations are met for the application to run, which can be a tedious process, especially when the the number of dependencies is high or when we want to upgrade to a newer version.

The solution? ... Using containers. Containers are software that package up code, runtime, libraries, config files, everything needed for an application to run [13] which can then be executed across different machines without additional setup. This, alongside faster boot times, lower resource usage and ease of scale, especially when coupled with orchestration tools like Kubernetes, made containers grow in popularity, even surpassing virtual machines in some cases [20].

However, the comparison with virtual machines, where containers are usually much better, often paints the picture that these metrics are irrelevant when it pertains to them, one such metric being size of the container itself. This is not true. The size of the container is directly proportional to the number of binaries and packages that are installed and as such reducing the size has the following benefits [8]:

- **Security** - smaller the size, smaller the attack surface a hacker has to work with
- **Performance and Efficiency** - smaller images are faster to deploy and, in general, use fewer system resources
- **Maintainability** - smaller images have fewer dependencies, making it easier to maintain and update them

As such, the goal of my project is to create a tool that can strip a container of all its unnecessary files and packages, leaving only the files needed for the application to run properly and export it as a *Dockerfile*, the recipe used to create the container.

## Chapter 2

# Background

### 2.1 A brief history of containers

The idea of containerization is not a new one. The concept has its roots since the late 70s, with *chroot*, a Unix command that allows a process to change its root directory, effectively isolating it from the rest of the system [3], creating so called *chroot jails*. Over the decades, this concept grew and evolved, with the introduction of *FreeBSD jails* and *Solaris Zones* around the turn of the millennium adding support for multiple isolated environments within the same OS instance [3].

The next major milestone happened in 2008 with the introduction of *LXC* (Linux Containers), adding kernel-level support for containers, by leveraging two Linux kernel components: *cgroups*, which provides ways to group processes in order to better manage resources and *namespaces*, which provide isolation.[3]

In 2013, the launch of *Docker* radically changed the landscape of containerization by providing a developer-friendly way to create, manage and deploy containers. Docker introduced the concept of container images, files which store the data needed for the container to run, *Docker Hub*, a public repository for sharing container images, and a powerful command-line interface for managing containers [3]. In the years that followed, multiple platforms sprung up such as *Apptainer* and *Podman*, which are both open-source alternatives to Docker, but none of them managed to gain the same level of popularity. As such, Docker became synonymous with containerization, holding an overwhelming market share of 87.85%[1] thus cementing themselves as the de facto standard in the industry.

### 2.2 The anatomy of a container

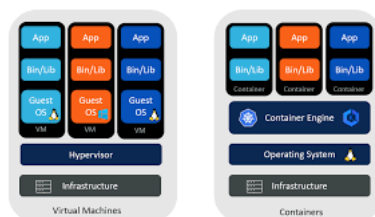


Figure 2.1: Containers vs VMs

As opposed to virtual machines, which run a full operating system on top of a hypervisor,

containers share the host operating system and run as isolated processes making them much more lightweight and efficient by only having to package the application and its dependencies into a so-called container image. Currently, there are over 10000 container images available on Docker Hub, ranging from simple *hello-world* apps, to *databases* and even full-blown Linux distributions like *Ubuntu*.

Now, how do we create our own container image? By creating a *Dockerfile*, a simple text file that contains all the necessary steps to build the image.

---

```
1 FROM python:3.10.0-slim
2 COPY requirements.txt .
3 RUN pip install -r requirements.txt
4 COPY . .
5 CMD ["python", "adapter.py"]
```

---

Listing 2.1: Sample Dockerfile

The format of a Dockerfile is quite simple, with each line representing a command that will be executed in order, the specifications for what each command does can be found in the official documentation<sup>1</sup> As each command is executed, a new layer is applied on top of the previous one, the container image being represented as a stack of these layers. A layer represents a change to the base image layer such as adding or removing files, installing packages or changing environment variables.

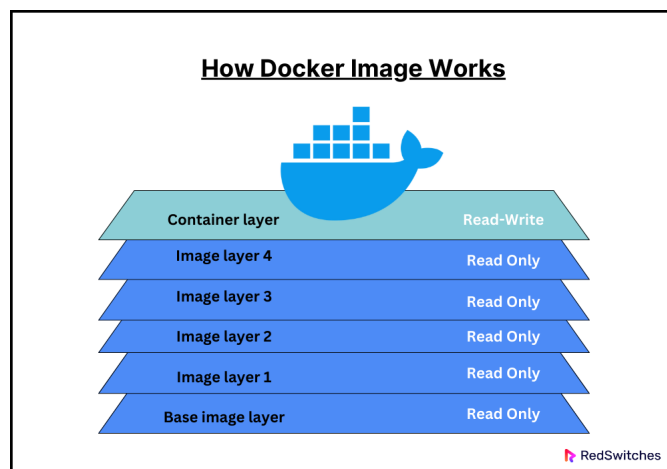


Figure 2.2: Container layers

All Dockerfiles require a base image, which is specified by the keyword *FROM*. The base image can be represented by either an existing image, or if you want to create your own, you can use *FROM scratch* to start from an empty filesystem. Additionally, Docker supports building the container image in multiple stages, by using the *FROM* command multiple times in the same Dockerfile.

---

```
1 FROM alpine:latest AS builder
2 RUN apk --no-cache add build-base
3
4 FROM builder AS build1
```

---

<sup>1</sup><https://docs.docker.com/reference/dockerfile/>



```
5      COPY source1.cpp source.cpp
6      RUN g++ -o /binary source.cpp
7
8      FROM builder AS build2
9      COPY source2.cpp source.cpp
10     RUN g++ -o /binary source.cpp
```

---

Listing 2.2: Sample Multi-stage Dockerfile

This coupled with the *scratch* base image serves as the mechanism that allows for the creation of minimal container images, by defining first a builder image and then copying the required files to the empty image.

## 2.3 Related work

Before proceeding further, it is important to acknowledge the work done by my peers in the field of container image minimization.

The earliest mention of building minimal container images is in a blog post dated 4th of July 2014 by Adriaan de Jonge on the site Xebia [5] and is corroborated by a 2015-02-03<sup>1</sup> München talk by Brian Harrington [11] which describe using *tar* to create the *scratch* image and then copying the required files to it, or by using tools like *buildroot*<sup>2</sup> or *debootstrap*<sup>3</sup> to create a minimal Linux distribution and then copying the required files to it.

In 2016, the first Alpine Linux image was published, which had a compressed size of 1.86MB<sup>4</sup> as it was built using *musl* and *busybox*, two lightweight alternatives to the standard C library and coreutils respectively. Around the same time, the *Distroless* philosophy i.e images containing only the application and its dependencies, was introduced by Google, with the first of these images being build using the open source tool *Bazel* for languages such as Java, Go and Python. Recently, Canonical, the company behind Ubuntu, has embraced distroless with their *Chiseled*<sup>5</sup> ubuntu images.

However, none of these tackle the fundamental issue of using minimal container images, being that the developer has to manually determine the dependencies of the application, which can be a arduous task, especially for large applications. The only project that I could find that is tangentially related to this is *dockershrink* by developer Raghav Dua [7]. This tool utilizes Artificial Intelligence in order reduce the size of the container image by generating a new Dockerfile updated to use slimmer base images and removing unnecessary files. [7] However, this tool is still in beta and it only works for NodeJS applications, as well as having to provide it with a OpenAI API key in order to access the full functionality of the tool. Additionally, it does not utilize the *scratch* image, which means that the final container image generated by the shrunk Dockerfile is not the most minimal possible.

---

<sup>1</sup>not sure if it's the 2nd of March or 3rd of February as I could not find this presentation and the only mention of this is in his GitHub repository [11]

<sup>2</sup>Buildroot

<sup>3</sup>debootstrap

<sup>4</sup>Oldest Alpine Linux image on Docker Hub

<sup>5</sup>Chiseled

## Chapter 3

# Motivation and Objectives

The main advantages of minimal containers are their enhanced security and small image size. Their improved security comes from the inherent properties of being minimal, meaning:

- **minimized attack surface** - by having only the required dependencies for the application to run, the only attack vector a hacker has is the application itself and not other components
- **clear dependency tree** - with only the required dependencies, it is easier to identify and audit them in case of a vulnerability being discovered, [2]

Additionally, their small size means that they are faster to deploy and use fewer system resources like *CPU* and *memory*, which is especially important in a cloud environment where the cost is directly proportional to the resources used and shaving a couple of seconds off the deployment time can lead to hours, even days given the size of the cluster. [14].

By creating a tool that can automatically detect an application's dependencies and create the Dockerfile which produces the minimal container for that app, we can save developers the time and effort of having to do it themselves, which can be tiresome and frustrating process.

# Chapter 4

## Use Cases

A real world example for the need to generate these minimal Dockerfiles and the reason that spawned this project is *Unikraft*<sup>1</sup>.

Unikraft was envisioned as a faster and more secure alternative to running applications in containers or virtual machines, by leveraging the power of ultra-lightweight virtual machines known as unikernels [19].

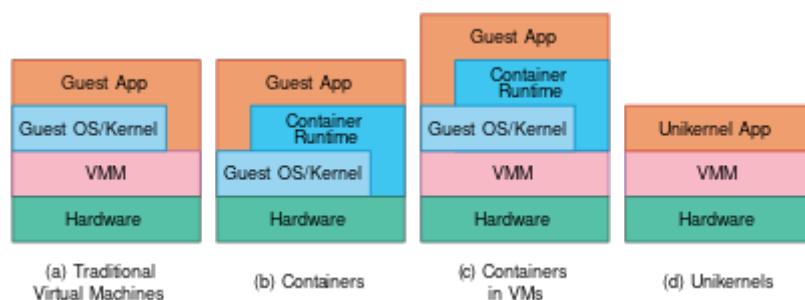


Figure 4.1: High-level comparison of the software components of traditional VMs (a), containers (b), containers in VMs (c) with unikernels (d).

Unikernels are specialized operating systems that are built as single-address space binary objects, meaning that they don't have user space-kernel space separation. They combine both the complete execution isolation and hardware access typical of VMs with the size of containers, which makes them ideal for cloud deployments [19].

Unikraft provides the tools needed to build, run and manage unikernels, in the form of a command-line program called *kraft*<sup>2</sup>. It features an interface similar to that of Docker's, with it being able to run pre-build unikernels or create new ones from a file called *Kraftfile*<sup>3</sup>.

---

```
1 spec: v0.6
2 runtime: base:latest
3 rootfs: ./Dockerfile
4 cmd: ["/helloworld"]
```

---

Listing 4.1: Sample Kraftfile

---

<sup>1</sup><https://unikraft.org/>

<sup>2</sup><https://unikraft.org/docs/cli>

<sup>3</sup>also *kraft.yaml* or *kraft.yml* for legacy support

Kraftfiles are written in YAML<sup>1</sup>, which follows an attribute-value structure. For my thesis, the only relevant attribute is *rootfs*, which describes the source from which the unikernel's root filesystem is built. Although optional [18], since most applications do require one, it is usually specified. As unikernels operate in resource-constrained specialized environments where efficiency is crucial, so do their filesystems need to strike the balance between providing the necessary storage requirements and also adhering to their lightweight philosophy.

There are many ways to define a root filesystem, one of which being highlighted in the Kraftfile example above, where a Dockerfile is used to build a container whose filesystem is later extracted to be used by the resulting unikernel. Thus, the Dockerfile should be as minimal as possible. So far, this process was done manually<sup>2</sup>, which explains the rather low number of applications that have been ported to Unikraft<sup>3</sup>, which need constant maintaining as different versions of the same app may require different Dockerfiles.

---

<sup>1</sup><https://yaml.org/>

<sup>2</sup><https://unikraft.org/docs/contributing/adding-to-the-app-catalog>

<sup>3</sup><https://github.com/unikraft/catalog>

# Building Blocks



For finding the runtime dependencies, I will be following the steps outlined here [17] and here [16] and will be a three-pronged approach, consisting of:

- **Static analysis** - inspecting the executable file for any linked libraries.
- **Dynamic analysis** - running the application and tracing its system calls <sup>1</sup>.
- **Brute force** - a fail-safe incase the other two fail to yield any results.

*Go* is a statically-typed, compiled language known for its simplicity and efficiency. It was built by Google in 2007 for use in networking and infrastructure services, being designed to be efficient, readable and high-performing. [4]

*Python* is a high-level, interpreted language known for its simplicity and readability. It was created by Guido van Rossum in the late 1980s and has since become one of the most popular programming languages in the world. [9]

---

<sup>1</sup>system calls, *syscalls*, are the mechanism used by applications to request services from the kernel, like I/O, spawning processes, etc.

<sup>2</sup><https://docs.docker.com/reference/api/engine/sdk/>

Although both languages are capable of achieving the same results, Go's performance superiority over Python, coupled with its concurrency and low-level capabilities, make it the clear choice for this project. The choice of using Go is also motivated by the fact that Docker itself is written in Go [12], which means that the SDK is better integrated with the rest of the Docker ecosystem and has better performance than the Python SDK.

## Chapter 6

# Architecture Overview

### 6.1 Static Analysis

Static analysis is the process of analyzing a program's code without executing it. In our context, we will be using it to identify the libraries that the application is dynamically linked using the *ldd* command.

---

```
1 ~ > ldd /usr/bin/man
2     linux-vdso.so.1 (0x00007ffe831f5000)
3     libmandb-2.9.1.so => /usr/lib/man-db/libmandb-2.9.1.so (0
4         x00007f068b572000)
5     libman-2.9.1.so => /usr/lib/man-db/libman-2.9.1.so (0
6         x00007f068b52f000)
7     libc.so.6 => /lib/x86_64-linux-gnu/libc.so.6 (0x00007f068b502000)
8     libpipeline.so.1 => /lib/x86_64-linux-gnu/libpipeline.so.1 (0
9         x00007f068b4f1000)
10    libz.so.1 => /lib/x86_64-linux-gnu/libz.so.1 (0x00007f068b2ff000)
11    libgdbm.so.6 => /lib/x86_64-linux-gnu/libgdbm.so.6 (0
12        x00007f068b2ef000)
13    libseccomp.so.2 => /lib/x86_64-linux-gnu/libseccomp.so.2 (0
14        x00007f068b2cb000)
15    /lib64/ld-linux-x86-64.so.2 (0x00007f068b59b000)
```

---

Listing 6.1: ldd command

The output of the command is a list of shared libraries that the application depends on, along with their paths. This approach works well for simple applications but it quickly becomes insufficient for most production applications.

### 6.2 Dynamic Analysis

Dynamic analysis is the process of analyzing a program's behavior during its execution. Our use case is to identify the other files that the application accesses during its execution, as well as any spawned processes and their dependencies. This is done using the *strace* command, which uses the *ptrace* system call to trace the system calls made by a process.

---

```
1 ~ > strace -fe execve,openat echo "Hello, World\!"
2     execve("/usr/bin/echo", ["echo", "Hello, World!"], 0x7fff43b04ce8 /* 36
3         vars */) = 0
4     openat(AT_FDCWD, "/etc/ld.so.cache", O_RDONLY|O_CLOEXEC) = 3
```

---

```

4      openat(AT_FDCWD, "/lib/x86_64-linux-gnu/libc.so.6", O_RDONLY|O_CLOEXEC)
      = 3
5      Hello, World!
6      +++ exited with 0 +++

```

Listing 6.2: strace command

For our scenario, we are interested in the *openat*, which means that the application is trying to open a file, and *execve*, which means that the application is trying to execute another program. The *-f* flag is used to allow strace to also trace the child processes spawned by the application, thus ensuring that we do not omit any dependencies. Additionally, it can trace processes that are already running using the *-p* flag, which will be used to trace the process running inside the container, this however needing root privilege since the process inside the container is in another namespace.

### 6.3 Brute Force

The brute force approach is a last resort method that is used should both the static and dynamic analysis fail in generating the minimal Dockerfile. Using the Docker SDK, we can extract the filesystem from the container and use it for this step. Given that in the containerized environment, the application is running normally and in a *FROM scratch* environment it is not (which does not contain any files), therefore there exists a point where removing a file from the filesystem causes the application to fail. Since removing files one at a time and building a new container each time is not feasible, we have to attempt a more efficient approach, that being a *binary search*.

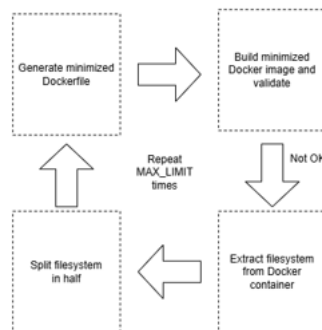


Figure 6.1: Brute force approach to finding the minimal Dockerfile

We start by splitting in half the filesystem into two buckets - *used* and *unused*. The decision of which files land in what bucket will be left to a coin toss in order to ensure fairness. We then build the Dockerfile with the files in the *used* bucket and run the application. If it fails, then we split the *unused* bucket in half and repeat the process. If the app succeeds, we repeat the cycle by splitting the shrunken filesystem in half again and follow the same steps. This will repeat at max *MAX\_LIMIT* times, a predefined limit we impose on the number of iterations. This sifting process is a greedy one and thus will not always generate the minimal Dockerfile, but it will offer a good approximation of it, especially if the limit is set to a high value.



## Chapter 7

# Implementation Details

### 7.1 Overview

As stated previously, the implementation is written in Go, a statically typed, compiled language designed for simplicity and efficiency. The choice of Go was influenced by its support for both low-level systems programming and high-level programming paradigms, making it suitable for building robust and efficient applications. Additionally, Go is one of the faster languages in terms of execution speed and features a rich ecosystem of community-built modules [10], which can be leveraged to speed up development.

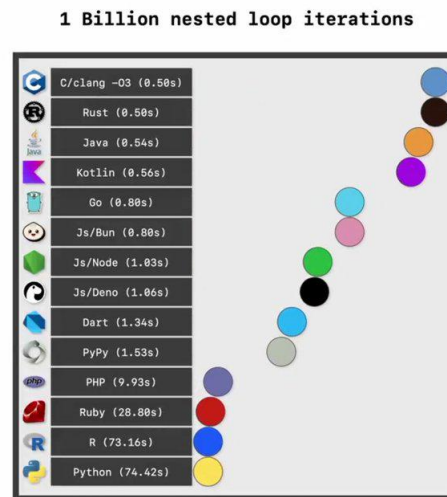


Figure 7.1: Language execution speed comparison [6]

### 7.2 Project Structure

The project is organized into multiple packages, each serving a specific purpose, as outlined in the architectural section.

```
1 .
2 |-- cmd
3 |-- main.go
```

---

```

4      |-- dockerminimizer
5      |-- dockerminimizer.go
6      |-- go.mod
7      |-- go.sum
8      |-- install.sh
9      |-- ldd
10     |-- ldd.go
11     |-- logger
12     |-- logger.go
13     |-- preprocess
14     |-- preprocess.go
15     |-- README.md
16     |-- strace
17     |-- strace.go
18     |-- types
19     |-- types.go
20     |-- utils
21     |-- utils.go

```

---

Listing 7.1: Project Structure

The executable created is *dockerminimizer*, which takes the following arguments:

- **-file**: The path to the Dockerfile to be minimized.
- **-image**: The name of an images from a Docker registry to be minimized
- **-max\_limit**: How many times should the binary search procedure be run for
- **-debug**: Enable logging of actions
- **-timeout**: How long should the minimal Docker container run before being declared as successful
- **-strace\_path**: The path to a statically-linked strace binary
- **-binary\_search**: Decide whether to continue the minimization process with a binary search if dynamic analysis failed

### 7.3 Preprocessing

After the arguments are parsed, the program will create a temporary directory where the necessary files for the minimal Dockerfile will be stored under *./dockerminimizer/<unique\_id>*. The unique ID is generated using a *MD5* hash of the current timestamp in order to ensure the uniqueness of the directory name should multiple instances of the program be run at the same time. The following steps are the building of the Docker image and the extraction of its filesystem to the directory. There are multiple ways of extracting a Docker container's filesystem [21], but the one we want to use is the one that preserves the original filesystem, without adding any additional files. This can be achieved by passing the *-o* flag to the build command, which will extract the unmodified filesystem to a desired location and type (the one we are interested in is tarball). The docker image is then parsed for its metadata, which is stored in a JSON file, which contains information about the image's environment variables, entrypoint, command, exposed ports and user. This metadata is stored as a custom type defined in the *types*.

---

```

1      type DockerConfig struct {
2          User          string           `json:"User"`
3          ExposedPorts map[string]map[string]any `json:"ExposedPorts"`
4          Env            []string        `json:"Env"`
5          Cmd           []string        `json:"Cmd"`

```

---

```

6         WorkingDir    string                `json:"WorkingDir"`
7         Entrypoint    []string              `json:"Entrypoint"`
8     }

```

---

Listing 7.2: Go DockerConfig structure

This is then used to create a template Dockerfile, which serves as a base for all the other Dockerfiles that will be generated.

---

```

1  FROM node:20.9.0 as builder
2
3  WORKDIR /app
4
5  COPY app.js /app/app.js
6  COPY package.json /app/package.json
7  COPY package-lock.json /app/package-lock.json
8
9  RUN npm install
10 EXPOSE 3000
11 CMD ["node", "app.js"]
12
13
14 FROM scratch
15
16 ENV PATH=/usr/local/sbin:/usr/local/bin:/usr/sbin:/usr/bin:/sbin:/bin
17 ENV NODE_VERSION=20.9.0
18 ENV YARN_VERSION=1.22.19
19 WORKDIR /app
20 EXPOSE 3000/tcp
21 ENTRYPOINT ["docker-entrypoint.sh"]
22 CMD ["node", "app.js"]

```

---

Listing 7.3: Dockerfile.minimal.template

This is then used to create the Dockerfile containing only the entrypoint/command files in order to check if it is already a minimal Dockerfile. Should it not be the case, the program will proceed to the static analysis phase.

## 7.4 Static Analysis

In the static analysis phase, the base Dockerfile default running command (i.e first entrypoint/-command in the image configuration) is run through *ldd* in order to determine the libraries that are required for the program to run. In order to ensure that *ldd* finds the correct libraries, the command is run utilizing *chroot* in the context of the extracted filesystem. The output of the command is then parsed and stored into two dictionaries, one for the normal files and one for the symbolic links, which need to be resolved to the actual files in order to be copied accurately into the Dockerfile.

---

```

1  func ParseOutput(output []byte, rootfsPath string) (map[string][]string,
2      map[string]string) {
3      files := make(map[string][]string)
4      symLinks := make(map[string]string)
5      scanner := bufio.NewScanner(bytes.NewReader(output))
6      for scanner.Scan() {
7          line := scanner.Text()
8          if strings.Contains(line, "=>") {
9              parts := strings.Split(line, "=>")

```

---

```

9         lib := strings.Split(strings.TrimSpace(parts[1]), " ")[0]
10
11         if strings.Contains(lib, "not found") {
12             continue
13         }
14         utils.AddFilesToDockerfile(lib, files, symLinks, rootfsPath)
15
16     } else if strings.Contains(line, "not found") {
17         continue
18     } else {
19         lib := strings.Split(strings.TrimSpace(line), " ")[0]
20         utils.AddFilesToDockerfile(lib, files, symLinks, rootfsPath)
21     }
22 }
23 return files, symLinks
24 }
```

Listing 7.4: ldd parser function

The reason why we are storing the files in a dictionary where the key is the directory name is due to the Docker's limit of 127 build stages, meaning that there can be at most 127 *COPY* commands in the minimal Dockerfile. Fortunately, we can circumvent this by putting all the files that belong to the same directory in the same *COPY* command.

The way this is achieved is by utilizing Go's *filepath* package, which allows for easy manipulation of file paths.

```

1 func RealPath(path string) string {
2     realPath, _ := filepath.Abs(path)
3     return filepath.Clean(realPath)
4 }
5
6 func CheckIfFileExists(file string, envPath string) bool {
7     info, err := os.Stat(envPath + "/" + file)
8     return !os.IsNotExist(err) && !info.IsDir()
9 }
10
11 func CheckIfSymbolicLink(file string, envPath string) bool {
12     info, err := os.Lstat(envPath + "/" + file)
13     if err != nil {
14         return false
15     }
16     return info.Mode() & os.ModeSymlink != 0
17 }
18
19 func ReadSymbolicLink(file string, envPath string) string {
20     link, _ := os.Readlink(envPath + "/" + file)
21     resolved := link
22     if !filepath.IsAbs(link) {
23         resolved = filepath.Join(filepath.Dir(envPath+"/"+file),
24                                 link)
25     }
26     return strings.TrimPrefix(resolved, envPath)
27 }
28
29 func AddFilesToDockerfile(file string, files map[string][]string, symLinks
30     map[string]string, rootfsPath string) {
31     file = RealPath(file)
32     if CheckIfFileExists(file, rootfsPath) {
```

```

31         if CheckIfSymbolicLink(file, rootfsPath) {
32             symLinks[file] = ReadSymbolicLink(file, rootfsPath)
33         } else {
34             files[filepath.Dir(file)] = AppendIfMissing(files[
35                 filepath.Dir(file)], file)
36         }
37     }

```

Listing 7.5: File util functions

With the two dictionaries populated, they are used to create the Dockerfile for this stage, by adding the *COPY* commands for each directory to the template Dockerfile, which is then tested to see if it can build and run the container successfully. If it is not, the next step is the dynamic analysis of the command.

## 7.5 Dynamic Analysis

For this stage, we attach a *strace* probe to the docker running command, in order to determine the files used and processes that are spawned by the command. In order to do this, we utilize Docker's volumes to mount a statically-linked *strace* binary into the container, as well as a logfile to save the output of the command. The reason for using a statically-linked binary is so that the libraries used by *strace* don't interfere with the libraries used by the command. To determine the runtime dependencies of the command, we will trace the *open* and *exec* family of syscalls [16] as well as passing the *-f* flag to trace the child processes as well.

```

1  func parseOutput(output string, syscalls []string, files map[string][]
2      string, symLinks map[string]string, envPath string) {
3      regexes := make(map[string]*regexp.Regexp)
4      for _, syscall := range syscalls {
5          regexes[syscall] = regexp.MustCompile(syscall + `
6              \([^\)]*?"([^\"]+)"`)
7      }
8      for line := range strings.SplitSeq(output, "\n") {
9          for _, syscall := range syscalls {
10             if regexes[syscall].MatchString(line) {
11                 match := regexes[syscall].FindStringSubmatch(line)
12                 if len(match) > 1 {
13                     utils.AddFilesToDockerfile(match[1], files, symLinks
14                         , envPath+"/rootfs")
15                 }
16                 break
17             }
18         }
19     }
20 }

```

Listing 7.6: File util functions

Parsing the output is made trivial by using regexes to match the syscalls and extract the first text between `" "`.

A problem that was quickly encountered was that in dealing with commands that are run via shebangs. A shebang is a special comment that is used to indicate the interpreter that should be used to run the script, and are always put at the top of the file, starting with the characters `#!/`. When stracing the command, only the command itself is being shown as executed, and not the shebang. This is due to how the operating system handles the shebang. Finding the

interpreter is done internally by the kernel in the `load_script` function, which is not visible to the `strace` command [?]. To fix this and make this step more robust, we firstly determine if a shebang is present in the base command, and afterwards we follow the minimization steps of static and dynamic analysis on the interpreter as well.

---

```

1  func getSheBang(command string, rootfsPath string) string {
2      file, err := os.Open(rootfsPath + "/" + command)
3      if err != nil {
4          log.Error("Failed to open file:", command)
5          return ""
6      }
7      defer file.Close()
8      var firstLine []byte
9      buf := make([]byte, 1)
10     for {
11         n, err := file.Read(buf)
12         if n > 0 {
13             if buf[0] == '\n' {
14                 break
15             }
16             firstLine = append(firstLine, buf[0])
17         }
18         if err != nil {
19             break
20         }
21     }
22     return string(firstLine)
23 }
24
25 func parseShebang(imageName string, containerName string, syscalls []string,
26     files map[string][]string, symLinks map[string]string, envPath
27     string, metadata types.DockerConfig, timeout int) (map[string][]
28     string, map[string]string) {
29     command := utils.GetContainerCommand(imageName, envPath, metadata)
30     hasSudo := utils.HasSudo()
31     shebang := getSheBang(command, envPath+"/rootfs")
32     regex := regexp.MustCompile(`^#!\s*([^\s]+)`)
33     if !regex.MatchString(shebang) {
34         log.Error("Failed to find shebang in file:", command)
35         return files, symLinks
36     }
37     match := regex.FindStringSubmatch(shebang)
38     if len(match) < 2 {
39         log.Error("Failed to find interpreter in shebang:", command)
40         return files, symLinks
41     }
42     interpreter := match[1]
43     lddCommand := hasSudo + " chroot " + envPath + "/rootfs ldd " +
44         interpreter
45     log.Info("Running command:", lddCommand)
46     lddOutput, err := exec.Command("sh", "-c", lddCommand).
47         CombinedOutput()
48     if err != nil {
49         log.Error("Failed to run ldd command\n" + err.Error())
50     }
51     files, symLinks = ldd.ParseOutput(lddOutput, envPath+"/rootfs")
52
53     output := getStraceOutput(imageName, envPath+"/strace", envPath+"/
54         log.txt", syscalls,

```

---

```
50         containerName, interpreter, envPath, metadata, timeout)
51     parseOutput(output, syscalls, files, symLinks, envPath)
52     return files, symLinks
53 }
```

---

Listing 7.7: File util functions

Finally, we create the Dockerfile for this stage and validate it like in the static analysis phase.

## Chapter 8

# Status and Planned Work

### 8.1 Status

The application is implemented up to the binary search analysis stage. There are a few issues with the dynamic analysis, but they are not critical. The application is able to minimize quite a few Dockerfiles, but not as many as I would have expected, possibly related to the issues with the dynamic analysis.

### 8.2 Planned Work

The next steps are doing more research on the issues with the dynamic analysis part and then implementing the binary search algorithm. With that, all Dockerfiles should be minimized with a huge penalty in the resource usage and execution time.



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