

React*Race

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1 Syntax and Semantics of Core React

Syntax

$\text{Prog} \ni P ::= e$	top-level exp
$\quad \mid c.\lambda x.e P$	component def
$\text{Expr} \ni e ::= x$	identifier
$\quad \mid () \mid \text{true} \mid \text{false} \mid n$	constant
$\quad \mid \text{view}[e, \dots, e]$	view
$\quad \mid \text{if } e \text{ } e \text{ } e$	conditional
$\quad \mid \lambda x.e$	function def
$\quad \mid e e$	application
$\quad \mid \text{let } x = e \text{ in } e$	let binding
$\quad \mid \text{let } (x, x'_{\text{set}}) = \text{useState}^{\ell} e \text{ in } e$	useState hook
$\quad \mid \text{let } x = \text{useRef}^{\ell} e \text{ in } e$	useRef hook
$\quad \mid \text{useEffect } e$	useEffect hook
$\quad \mid e; e$	sequence
$\quad \mid e \oplus e$	binary op

Semantics

$\text{Val} \ni v ::= \langle \rangle \mid b \mid n$	primitive values
$\quad \mid \overline{[s]}$	view spec list
$\quad \mid \langle \lambda x.e, \sigma \rangle$	closure
$\quad \mid \langle \text{set}_{\ell}, p \rangle$	setter closure
$\quad \mid \langle c.\lambda x.e, \sigma \rangle$	component closure
$\quad \mid \langle c.\lambda x.e, \sigma, v \rangle$	component spec
$\text{Bool} \ni b ::= \text{tt} \mid \text{ff}$	
$\text{ViewSpec} \ni s ::= \langle \rangle \mid n$	primitive spec
$\quad \mid \langle c.\lambda x.e, \sigma, v \rangle$	component spec
$\text{Env} \ni \sigma ::= \{x \mapsto v\}$	environment
$\text{Phase} \ni \phi ::= \text{PInit} \mid \text{PUpdate}$	
$\quad \mid \text{PRetry} \mid \text{PEffect}$	phase
$\text{Decision} \ni d ::= \text{Idle} \mid \text{Retry} \mid \text{Update}$	decision
$\text{PartView} \ni \pi ::= \bullet$	root
$\quad \mid \langle \langle c.\lambda x.e, \sigma, v \rangle, d, \rho_s, \rho_r, q \rangle$	node
$\text{SttStore} \ni \rho_s ::= \{ \ell \mapsto \langle v, q \rangle \}$	state store
$\text{RefStore} \ni \rho_r ::= \{ \ell \mapsto v \}$	ref store
$\text{JobQ} \ni q ::= \left[\overline{\langle \lambda x.e, \sigma \rangle} \right]$	job queue
$\text{Tree} \ni t ::= \ulcorner \mid \lceil n \rceil \mid p$	tree
$\text{TreeMem} \ni m ::= \{ p \mapsto \langle \pi, l \rangle \}$	tree memory

$p \in \text{Path}$ tree path
 $l ::= [t]$ children

$$\boxed{m, \sigma \vdash e \Downarrow_p^\phi v, m'}$$

VAR	UNIT	TRUE	FALSE	INT
$m, \sigma \vdash x \Downarrow_p^\phi \sigma(x), m$	$m, \sigma \vdash () \Downarrow_p^\phi \langle \rangle, m$	$m, \sigma \vdash \text{true} \Downarrow_p^\phi \mathbb{T}, m$	$m, \sigma \vdash \text{false} \Downarrow_p^\phi \mathbb{F}, m$	$m, \sigma \vdash n \Downarrow_p^\phi n, m$
$\frac{\text{VIEWSPEC} \quad (m_i, \sigma \vdash e_i \Downarrow_p^\phi s_i, m_{i+1})_{i=1}^n \quad \text{COND} \quad m, \sigma \vdash e_1 \Downarrow_p^\phi b, m' \quad m', \sigma \vdash (b ? e_2 : e_3) \Downarrow_p^\phi v, m''}{m_1, \sigma \vdash \text{view } [e_i]_{i=1}^n \Downarrow_p^\phi [s_i]_{i=1}^n, m_{n+1} \quad m, \sigma \vdash \text{if } e_1 e_2 e_3 \Downarrow_p^\phi v, m''}$				
$\frac{\text{FUNC} \quad m, \sigma \vdash \lambda x. e \Downarrow_p^\phi \langle \lambda x. e, \sigma \rangle, m}{m, \sigma \vdash \lambda x. e \Downarrow_p^\phi \langle \lambda x. e, \sigma \rangle, m}$				
$\frac{\text{APPFUNC} \quad m, \sigma \vdash e_1 \Downarrow_p^\phi \langle \lambda x. e, \sigma' \rangle, m_1 \quad m_1, \sigma \vdash e_2 \Downarrow_p^\phi v_2, m_2 \quad m_2, \sigma' \{x \mapsto v_2\} \vdash e \Downarrow_p^\phi v', m'}{m, \sigma \vdash e_1 e_2 \Downarrow_p^\phi v', m'}$				
$\frac{\text{APPCOMP} \quad m, \sigma \vdash e_1 \Downarrow_p^\phi \langle c. \lambda x. e, \sigma' \rangle, m_1 \quad m_1, \sigma \vdash e_2 \Downarrow_p^\phi v_2, m_2}{m, \sigma \vdash e_1 e_2 \Downarrow_p^\phi \langle c. \lambda x. e, \sigma' \rangle, m_2}$				
$\frac{\text{APPSETSTT} \quad m, \sigma \vdash e_1 \Downarrow_p^\phi \langle \text{set}_\ell, p' \rangle, m_1 \quad m_1, \sigma \vdash e_2 \Downarrow_p^\phi \langle \lambda x. e, \sigma' \rangle, m_2}{m, \sigma \vdash e_1 e_2 \Downarrow_p^\phi \langle \rangle, m_2 \left\{ (p') . \pi \left\langle d \mapsto (p = p' \wedge \phi \neq \text{PEffect}) ? \text{Retry} : \text{Update} \right\rangle \right\}}$				
$\frac{\text{LETBIND} \quad m, \sigma \vdash e_1 \Downarrow_p^\phi v_1, m_1 \quad m_1, \sigma \{x \mapsto v_1\} \vdash e_2 \Downarrow_p^\phi v_2, m_2}{m, \sigma \vdash \text{let } x = e_1 \text{ in } e_2 \Downarrow_p^\phi v_2, m_2}$				
$\frac{\text{STTBIND} \quad m, \sigma \vdash e_1 \Downarrow_p^{\text{PInit}} v_1, m_1 \quad m_1 \{ (p) . \pi . \rho_s . (\ell) \mapsto \langle v_1, [] \rangle \}, \sigma \{x \mapsto v_1, x'_{\text{set}} \mapsto \langle \text{set}_\ell, p \rangle \} \vdash e_2 \Downarrow_p^{\text{PInit}} v_2, m_2}{m, \sigma \vdash \text{let } (x, x'_{\text{set}}) = \text{useState}^\ell e_1 \text{ in } e_2 \Downarrow_p^{\text{PInit}} v_2, m_2}$				
$\frac{\text{STTREBIND} \quad \phi \in \{\text{PUpdate}, \text{PRetry}\} \quad m_1(p) . \pi . \rho_s(\ell) = \left\langle v_1, \left[\overline{\langle \lambda x_i . e'_i, \sigma_i \rangle} \right]_{i=1}^n \right\rangle \quad (m_i, \sigma_i \{x_i \mapsto v_i\} \vdash e'_i \Downarrow_p^\phi v_{i+1}, m_{i+1})_{i=1}^n}{m_{n+1} \left\{ (p) . \pi . \left\langle d \mapsto (v_{n+1} \neq v_1 ? \text{Update} : d) \right\rangle \right\}, \sigma \left\{ x \mapsto v_{n+1}, x'_{\text{set}} \mapsto \langle \text{set}_\ell, p \rangle \right\} \vdash e_2 \Downarrow_p^\phi v, m'}$				
$\frac{m_1, \sigma \vdash \text{let } (x, x'_{\text{set}}) = \text{useState}^\ell e_1 \text{ in } e_2 \Downarrow_p^\phi v, m'}{m, \sigma \vdash \text{let } (x, x'_{\text{set}}) = \text{useState}^\ell e_1 \text{ in } e_2 \Downarrow_p^\phi v, m'}$				
$\frac{\text{REFBIND} \quad m, \sigma \vdash e_1 \Downarrow_p^{\text{PInit}} v_1, m_1 \quad m_1 \{ (p) . \pi . \rho_r . (\ell) \mapsto v_1 \}, \sigma \{x \mapsto v_1\} \vdash e_2 \Downarrow_p^{\text{PInit}} v_2, m_2}{m, \sigma \vdash \text{let } x = \text{useRef}^\ell e_1 \text{ in } e_2 \Downarrow_p^{\text{PInit}} v_2, m_2}$				
$\frac{\text{REFREBIND} \quad \phi \in \{\text{PUpdate}, \text{PRetry}\} \quad m(p) . \pi . \rho_r(\ell) = v_1 \quad m, \sigma \{x \mapsto v_1\} \vdash e_2 \Downarrow_p^\phi v_2, m_2}{m, \sigma \vdash \text{let } x = \text{useRef}^\ell e_1 \text{ in } e_2 \Downarrow_p^\phi v_2, m_2}$				
$\frac{\text{EFF} \quad \phi \in \{\text{PInit}, \text{PUpdate}, \text{PRetry}\}}{m, \sigma \vdash \text{useEffect } e \Downarrow_p^\phi \langle \rangle, m \{ (p) . \pi . \langle q \mapsto q \triangleright \langle \lambda _ . e, \sigma \rangle \rangle \}}$				
$\boxed{m, \sigma \vdash e \Downarrow_p^\phi v, m'}$				
$\frac{\text{EVALONCE} \quad m, \sigma \vdash e \Downarrow_p^\phi v, m' \quad m'(p) . \pi . d \in \{\text{Idle}, \text{Update}\}}{m, \sigma \vdash e \Downarrow_p^\phi v, m'}$				
$\frac{\text{EVALMULT} \quad m, \sigma \vdash e \Downarrow_p^\phi v, m' \quad m'(p) . \pi . d = \text{Retry} \quad m', \sigma \vdash e \Downarrow_p^\phi v', m''}{m, \sigma \vdash e \Downarrow_p^\phi v', m''}$				

$$\boxed{m \vdash \text{render1}(s) = \langle t, m' \rangle}$$

$$\begin{array}{c}
\text{RENDER1NULL} \quad \text{RENDER1INT} \\
\hline
m \vdash \text{render1}(\langle \rangle) = \langle \ulcorner, m \rangle \quad m \vdash \text{render1}(n) = \langle \ulcorner n, m \rangle \\
\text{RENDER1COMP} \\
m \vdash p \text{ fresh} \quad m\{p\} \mapsto \langle \langle c.\lambda x.e, \sigma, v \rangle, \text{Idle}, \{\}, [], [] \rangle, \sigma\{x \mapsto v\} \vdash e \mathbb{I}_p^{\text{PInit}} [\bar{s}], m' \\
\quad m' \vdash \text{render}(p, [\bar{s}]) = m'' \\
\hline
m \vdash \text{render1}(\langle c.\lambda x.e, \sigma, v \rangle) = \langle p, m'' \rangle
\end{array}$$

$$m \vdash \text{render}(p, [\bar{s}]) = m'$$

$$\begin{array}{c}
\text{RENDER} \\
(m_i \vdash \text{render1}(s_i) = \langle t_i, m'_i \rangle)_{i=1}^n \quad (m_{i+1} = m'_i\{(p).l \mapsto l \triangleright t_i\})_{i=1}^n \\
\hline
m_1 \vdash \text{render}(p, [\bar{s}_i]_{i=1}^n) = m'
\end{array}$$

$$m \vdash \text{update1}(t, v_\varepsilon) = \langle b, m' \rangle$$

$$\begin{array}{c}
\text{UPDATE1NULL} \quad \text{UPDATE1INT} \quad \text{UPDATE1PATH} \\
\hline
m \vdash \text{update1}(\ulcorner, \varepsilon) = \langle \text{ff}, m \rangle \quad m \vdash \text{update1}(\ulcorner n, \varepsilon) = \langle \text{ff}, m \rangle \quad m \vdash \text{update}(p, v_\varepsilon) = \langle b, m' \rangle \\
m \vdash \text{update1}(p, v_\varepsilon) = \langle b, m' \rangle
\end{array}$$

$$m \vdash \text{update}(p, v_\varepsilon) = \langle b, m' \rangle$$

$$\begin{array}{c}
\text{UPDATEROOT} \\
m_1(p) = \langle \bullet, [\bar{t}_i]_{i=1}^n \rangle \quad (m_i \vdash \text{update1}(t_i, \varepsilon) = \langle b_i, m_{i+1} \rangle)_{i=1}^n \\
\hline
m_1 \vdash \text{update}(p, \varepsilon) = \langle \bigvee_{i=1}^n b_i, m_{n+1} \rangle \\
\text{UPDATENODEIDLE} \\
m_1(p) = \langle \pi, [\bar{t}_i]_{i=1}^n \rangle \quad \pi.d = \text{Idle} \quad (m_i \vdash \text{update1}(t_i, \varepsilon) = \langle b_i, m_{i+1} \rangle)_{i=1}^n \\
\hline
m_1 \vdash \text{update}(p, \varepsilon) = \langle \bigvee_{i=1}^n b_i, m_{n+1} \rangle \\
\text{UPDATENODERECONCILE} \\
m(p) = \langle \langle c.\lambda x.e, \sigma, v' \rangle, d, \rho_s, q \rangle, [\bar{t}_i]_{i=1}^n \rangle \quad (d = \text{Update}) \vee (d = \text{Idle} \wedge v_\varepsilon \neq \varepsilon) \\
v = (v_\varepsilon \neq \varepsilon \text{ ? } v_\varepsilon : v') \quad m\{p\}.\pi \langle d \mapsto \text{Idle} \rangle, \sigma\{x \mapsto v\} \vdash e \mathbb{I}_p^{\text{PUpdate}} [\bar{s}_i]_{i=1}^{n'}, m' \\
\quad m'\{p\}.\pi \langle l \mapsto [] \rangle \vdash \text{reconcile}([\bar{t}_i]_{i=1}^{\min\{n, n'\}}, [\bar{s}_i]_{i=1}^{n'}) = \langle b, m'' \rangle \\
\hline
m \vdash \text{update}(p, v_\varepsilon) = \langle b \vee (m'(p).\pi.d \neq \text{Idle}), m'' \rangle
\end{array}$$

$$m \vdash \text{reconcile1}(t, s) = \langle b, t, m' \rangle$$

$$m \vdash \text{reconcile1}(t, s) = \begin{cases} \langle \text{ff}, \ulcorner, m \rangle & \text{if } \langle t, s \rangle = \langle \ulcorner, \langle \rangle \rangle \\ \langle \text{ff}, \ulcorner n, m \rangle & \text{if } \langle t, s \rangle = \langle \ulcorner n, \langle n \rangle \rangle \\ \langle b, p, m' \rangle & \text{if } \langle t, s \rangle = \langle p, \langle c.\lambda x.e, \sigma, v \rangle \rangle \wedge m(p).\pi.s = \langle c.\lambda x.e, \sigma, v' \rangle, \\ & \text{where } (m \vdash \text{update1}(p, (v \neq v' \text{ ? } v : \varepsilon))) = \langle b, m' \rangle \\ \langle \text{tt}, t', m' \rangle & \text{otherwise, where } (m \vdash \text{render1}(s)) = \langle t', m' \rangle \end{cases}$$

$$m \vdash \text{reconcile}(p, [\bar{t}], [\bar{s}]) = \langle b, m' \rangle$$

$$\begin{array}{c}
\text{RECONCILE} \\
\left\{ \begin{array}{l} m_i \vdash \text{reconcile1}(t_i, s_i) = \langle b_i, t_i, m'_i \rangle \quad \text{if } i \leq n' \\ m_i \vdash \text{render1}(s_i) = \langle t_i, m'_i \rangle, \quad b_i = \text{tt} \text{ otherwise} \\ \text{where } m_{i+1} = m'_i\{(p).l \mapsto l \triangleright t_i\} \end{array} \right\}_{i=1}^n \\
\hline
m_1 \vdash \text{reconcile}(p, [\bar{t}]_{i=1}^{n'}, [\bar{s}_i]_{i=1}^n) = \langle \bigvee_{i=1}^n b_i, m_{n+1} \rangle
\end{array}$$

$$\boxed{m \vdash \text{commitEffs1}(t) = m'}$$

$$\frac{\text{COMMITEFFS1UNIT}}{m \vdash \text{commitEffs1}(\langle \rangle) = m} \quad \frac{\text{COMMITEFFS1INT}}{m \vdash \text{commitEffs1}(n) = m} \quad \frac{\text{COMMITEFFS1PATH}}{m \vdash \text{commitEffs1}(p) = m'}$$

$$\boxed{m \vdash \text{commitEffs}(p) = m'}$$

$$\frac{\text{COMMITEFFSROOT} \quad m_1(p) = \langle \bullet, [\bar{t}_i]_{i=1}^n \rangle \quad (m_i \vdash \text{commitEffs1}(t_i) = m_{i+1})_{i=1}^n}{m_1 \vdash \text{commitEffs}(p) = m_{n+1}}$$

$$\frac{\text{COMMITEFFSNODE} \quad m_1(p) = \langle \pi, [\bar{t}_i]_{i=1}^n \rangle \quad \pi \neq \bullet \quad \pi.q = [\langle \lambda _ . e_i, \sigma_i \rangle]_{i=1}^k \quad (m_i, \sigma_i \vdash e_i \Downarrow_p^{\text{pEffect}} v_i, m_{i+1})_{i=1}^k \quad m'_1 = m_{k+1}\{ \langle p \rangle . \pi \langle q \mapsto [] \rangle \} \quad (m'_i \vdash \text{commitEffs1}(t_i) = m'_{i+1})_{i=1}^n}{m_1 \vdash \text{commitEffs}(p) = m'_{n+1}}$$

$$\boxed{\sigma \vdash P \Downarrow [\bar{s}]}$$

$$\frac{\text{GATHERCOMP} \quad \sigma \{ c \mapsto \langle c.\lambda x.e, \sigma \rangle \} \vdash P \Downarrow [\bar{s}]}{\sigma \vdash c.\lambda x.e P \Downarrow [\bar{s}]} \quad \frac{\text{TOPEXP} \quad \{\}, \sigma \vdash e \Downarrow [\bar{s}], \{\}}{\sigma \vdash e \Downarrow [\bar{s}]}$$

$$\boxed{P \text{ or } \langle p, m \rangle \hookrightarrow \langle p, m' \rangle}$$

$$\frac{\text{STEPPROG} \quad \{\} \vdash P \Downarrow [\bar{s}] \quad \{\} \vdash p \text{ fresh} \quad \{p \mapsto \langle \bullet, [] \rangle\} \vdash \text{render}(p, [\bar{s}]) = m \quad m \vdash \text{commitEffs}(p) = m'}{P \hookrightarrow \langle p, m' \rangle}$$

$$\frac{\text{STEPPATHUPDATE} \quad m \vdash \text{update}(p, \varepsilon) = \langle \mathbb{t}, m' \rangle \quad m' \vdash \text{commitEffs}(q) = m''}{\langle p, m \rangle \hookrightarrow \langle p, m'' \rangle} \quad \frac{\text{STEPPATHDONE} \quad m \vdash \text{update}(p, \varepsilon) = \langle \mathbb{f}, m' \rangle}{\langle p, m \rangle \hookrightarrow \langle p, m' \rangle}$$

2 Language extension

We extend the core React with objects and the heap.

Syntax

$$\begin{array}{ll} \text{Expr} \ni e ::= \overline{\{x : e\}} & \text{object} \\ & | e.x \quad \text{field access} \\ & | e.x := e \quad \text{assignment} \end{array}$$

Semantics

$$\begin{array}{ll} \text{Prim} \ni \epsilon ::= \langle \rangle \mid b \mid n & \text{primitive values} \\ \text{Object} \ni o ::= [\bar{s}] & \text{view spec list} \\ & | \langle \lambda x.e, \sigma \rangle \quad \text{closure} \\ & | \langle \text{set}_\ell, p \rangle \quad \text{setter closure} \\ & | \langle c.\lambda x.e, \sigma \rangle \quad \text{component closure} \\ & | \langle c.\lambda x.e, \sigma, v \rangle \quad \text{component spec} \\ \text{Bool} \ni b ::= \mathbb{t} \mid \mathbb{f} & \\ \text{ViewSpec} \ni s ::= \langle \rangle \mid n & \text{primitive spec} \end{array}$$

	$ \langle c.\lambda x.e, \sigma, v \rangle$	component spec
Env $\ni \sigma$	$::= \overline{\{x \mapsto v\}}$	environment
Phase $\ni \phi$	$::= \text{PInit} \mid \text{PUpdate}$ $ \text{PRetry} \mid \text{PEffect}$	phase
Decision $\ni d$	$::= \text{Idle} \mid \text{Retry} \mid \text{Update}$	decision
PartView $\ni \pi$	$::= \bullet$	root
	$ \langle \langle c.\lambda x.e, \sigma, v \rangle, d, \rho_s, \rho_r, q \rangle$	node
SttStore $\ni \rho_s$	$::= \overline{\{\ell \mapsto \langle v, q \rangle\}}$	state store
RefStore $\ni \rho_r$	$::= \overline{\{\ell \mapsto v\}}$	ref store
JobQ $\ni q$	$::= \overline{[\langle \lambda x.e, \sigma \rangle]}$	job queue
Tree $\ni t$	$::= \ulcorner _ \urcorner \mid \ulcorner n \urcorner \mid p$	tree
TreeMem $\ni m$	$::= \overline{\{p \mapsto \langle \pi, l \rangle\}}$	tree memory
	$p \in \text{Path}$	tree path
	$l ::= [\bar{t}]$	children