~\Documents\documents_general\structured_courses\math564\evaluations\projects \p05\solve6.py

```
1 #!/usr/bin/env python3
2
   # -*- coding: utf-8 -*-
3
 4
   script for solving the Minimium Time Path Problem
   Version: November 9, 2023
5
 6
   Author: Tom Asaki
7
8
9
   import numpy as np
10
   import optimize as opt
   import pandas as pd
11
12
   import matplotlib.pyplot as plt
13
14
   from objective import pathtime as obj
15
16
   N=12 # This is the order of the fit (2N decision variables)
17
18
   # read in the velocity data array defined on
19
   \# [0,1]x[0,1] and set the path end points
   v=pd.read csv('SpeedData.csv',header=None).to numpy()
20
   my,mx=v.shape
21
   A=(.05,.05)
22
   B=(.95,.95)
23
24
25
   alg=dict(obj
                      = obj,
26
                     = 0.2*np.random.randn(2*N,1),
            x0
27
                    = (v, A, B),
            params
28
                     = 'BFGS',
            method
29
                     = 999.
            maxiter
30
            progress = 10,
31
            ngtol
                      = 1E-8,
32
                     = 1E-8,
            dftol
33
                     = 1E-8,
            dxtol
34
            Lambda
                      = 1.,
35
            Lambdamax = 100.,
            linesearch = 'StrongWolfe',
36
37
            c1
                      = 0.001,
38
            c2
                      = 0.9,
39
                      = 10,
            m
40
            maxcond
                      = 1000,
41
            )
42
43
   res=opt.minimize(alg)
44
45
   46
   # plot the optimal path superimposed on the velocity image
47
              = 1000
                          # number of points defining the path
   smp
             = 256
                          # figure dpi (effects scale)
48
   FigDPI
             = (8,6)
                          # fiugure size
49
   FigSize
             = 'jet'
                          # velocity colormap
50
   ColorMap
   LineColor = 'white'
                          # path plot color
51
```

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52
   LineWidth
              = 1
                            # path line width
   PointSize
                            # size of path endpoints
53
                = 16
54
55
   r=np.linspace(0,1,smp)
56
   xx=(1-r)*A[0]+r*B[0]
   yy = (1-r)*A[1]+r*B[1]
57
   for k in range(N):
58
59
       s=np.sin((k+1)*np.pi*r)
       xx+=res['x'][k,-1]*s
60
       yy+=res['x'][k+N,-1]*s
61
62
   xxr=xx*(mx-1)
   yyr=yy*(my-1)
63
64
65
   fig = plt.figure(dpi=FigDPI,figsize=FigSize)
   ax=fig.add subplot()
66
   vim=ax.imshow(v,cmap=ColorMap)
67
   plt.colorbar(vim,orientation='vertical')
68
   ax.plot(yyr,xxr,color=LineColor,linewidth=LineWidth)
69
   ax.scatter(A[1]*mx,A[0]*my,PointSize,LineColor)
70
   ax.scatter(B[1]*mx,B[0]*my,PointSize,LineColor)
71
   plt.xticks([])
72
   plt.yticks([])
73
   plt.show()
74
75
76
77
78
```

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