

1 Theory

1.1 Notations

1.2 Centralized Multi-Period OPF with Batteries

On similar lines to the branch flow equations in [?], the network is modeled as a function of time, considering the interaction of batteries.

$$p_j^t = \sum_{(j,k) \in \mathcal{L}} P_{jk}^t - \sum_{(i,j) \in \mathcal{L}} \{P_{ij}^t - r_{ij} l_{ij}^t\} - P_{d_j}^t + P_{c_j}^t \quad (1)$$

$$q_j^t = \sum_{(j,k) \in \mathcal{L}} Q_{jk}^t - \sum_{(i,j) \in \mathcal{L}} \{Q_{ij}^t - x_{ij} l_{ij}^t\} - q_{D_j}^t - q_{B_j}^t \quad (2)$$

$$v_j^t = v_i^t + \{r_{ij}^2 + x_{ij}^2\} l_{ij}^t - 2(r_{ij} P_{ij}^t + x_{ij} Q_{ij}^t) \quad (3)$$

$$l_{ij}^t = \frac{(P_{ij}^t)^2 + (Q_{ij}^t)^2}{v_i^t} \quad (4)$$

where $P_{ij}^t, Q_{ij}^t, l_{ij}^t$ denote the sending-end real power, reactive power and the square of the magnitude of the current flowing in the branch (i, j) respectively. v_j^t denotes the square of the magnitude of the voltage at node j . The superscript t specifies the time-period for the corresponding variable. It may be noted that for a radial distribution system, each node j can have only one ‘parent’ node i , and thus the summation for the second term in equations Equation (1) and ?? may be dropped.

(Integer Constraint Relaxed) Naive Brute Force Full Optimization Model - Full Horizon

$$\min_{\substack{P_{ij}^t, Q_{ij}^t, v_j^t, l_{ij}^t, \\ q_{D_j}^t, B_j^t, P_{c_j}^t, P_{d_j}^t, q_{B_j}^t}} \sum_{t=1}^T \sum_{(i,j) \in \mathcal{L}} (r_{ij} l_{ij}^t) \quad (5)$$

$$+ \alpha \sum_{t=1}^T \sum_{j \in \mathcal{B}} \left\{ (1 - \eta_c) P_{c_j}^t + \left(\frac{1}{\eta_d} - 1 \right) P_{d_j}^t \right\} \quad (6)$$

$$+ \gamma \sum_{j \in \mathcal{B}} \left\{ (B_j^T - B_{ref_j})^2 \right\} \quad (7)$$

s.t.

$$p_j^t = \sum_{(j,k) \in \mathcal{L}} P_{jk}^t - \sum_{(i,j) \in \mathcal{L}} \{P_{ij}^t - r_{ij} l_{ij}^t\} - P_{d_j}^t + P_{c_j}^t \quad (8)$$

$$q_j^t = \sum_{(j,k) \in \mathcal{L}} Q_{jk}^t - \sum_{(i,j) \in \mathcal{L}} \{Q_{ij}^t - x_{ij} l_{ij}^t\} - q_{D_j}^t - q_{B_j}^t \quad (9)$$

$$v_j^t = v_i^t + \{r_{ij}^2 + x_{ij}^2\} l_{ij}^t - 2(r_{ij} P_{ij}^t + x_{ij} Q_{ij}^t) \quad (10)$$

$$l_{ij}^t = \frac{(P_{ij}^t)^2 + (Q_{ij}^t)^2}{v_i^t} \quad (11)$$

$$B_j^t = B_j^{t-1} + \Delta t \eta_c P_{c_j}^t - \Delta t \frac{1}{\eta_d} P_{d_j}^t \quad (12)$$

$$B_j^0 = 0.5(soc_{max} + soc_{min}) E_{Rated} = 0.625 E_{Rated} \quad (13)$$

$$where, \quad (14)$$

$$(i, j) : \text{Branch connecting nodes } i \text{ and } j \quad (15)$$

$$p_j^t = p_{D_j}^t - p_{L_j}^t \quad (16)$$

$$q_j^t = -q_{L_j}^t \quad (17)$$

$$t = \{1, 2, \dots, T\} \quad (18)$$

1.3 ENApp based Distributed Multi-Period OPF with Batteries