

Homework 1 • Due on Sept 3 2020 @ 9 am Per Unit Problem: Common MVA Base should be specified. You can use either 30 MVA Base or 100 MVA Base.

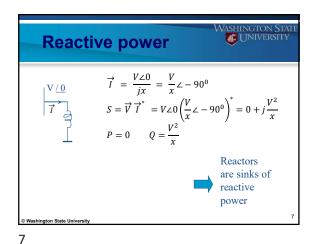
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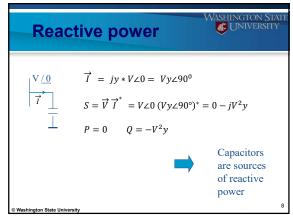
Basics $v(t) = \sqrt{2}V\cos(\omega t)$ $\vec{V} = V \angle 0$ $i(t) = \sqrt{2} I \cos(\omega t - \varphi)$ $\vec{I} = I \angle - \varphi$ $p(t) = 2VI\cos(\omega t)\cos(\omega t - \varphi)$ = $2VI\cos(\omega t)(\cos\omega t\cos\varphi + \sin\omega t\sin\varphi)$ = $VI \cos \varphi \left[2 \cos^2 \omega t \right] + VI \sin \varphi \left[2 \cos \omega t \sin \omega t \right]$ $= VI\cos\varphi \left[1 + \cos 2\omega t\right] + VI\sin\varphi \left[\sin 2\omega t\right]$ $= P \left[1 + \cos 2 \omega t \right] + Q \left[\sin 2 \omega t \right]$ $p_1(t)$ + $p_2(t)$

Basics Assume VI=1, φ=600. Then, P=0.5, Q=0.877 Average = 0.5. Average = 0. Real power. Swinging power.

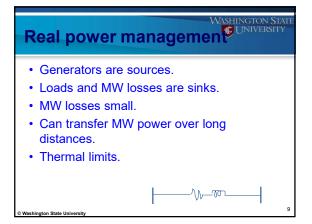
Basics $\vec{V} = V \angle 0$ $\vec{I} = I \angle - \varphi$ $\vec{S} = \vec{V} \vec{I}^* = VI \cos \varphi + j VI \sin \varphi = P + j Q$ • P = VI $\cos \varphi$ and Q = VI $\sin \varphi$ • S = P + j Q · Real power well-understood. · Generators are sources. Loads and Losses are sinks. · Reactive power?

Basic components $\overrightarrow{I} = \frac{V \angle 0}{R} = \frac{V}{R} \angle 0$ $S = \overrightarrow{V} \overrightarrow{I}^* = V \angle 0 \left(\frac{V}{R} \angle 0\right)^* = \frac{V^2}{R} + j \ 0$ $P = \frac{V^2}{R} \qquad Q = 0$ Resistors are sinks of real power





10



Reactive power management

• Generators and capacitors are sources.

• Reactors and loads are sinks.

• Abundance of reactors in the power system.

• Line reactances typically ten times the line resistances. Same for transformers,...

9

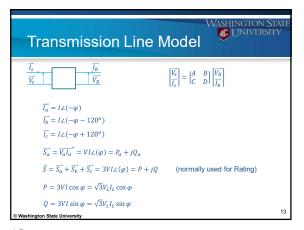
Transmission Line Models

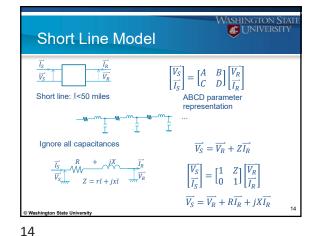
Distributed Parameter Circuit

Line Model

Long

| < 50 miles | 50 miles | 150 miles | 150 miles | 20 miles | 120 miles | 12





Medium Line Model

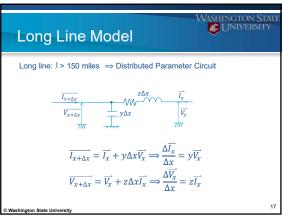
Medium Line Model

Medium line: 50 miles < ξ < 150 miles

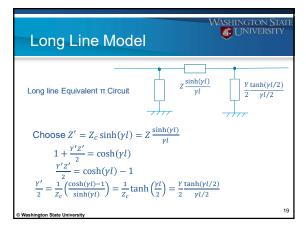
Lump all capacitances \Rightarrow Put one half on each side $\overline{I_S}$ R + $\overline{I_S}$ $\overline{I_R}$ $\overline{I_R}$

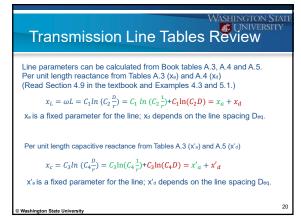
Medium Line Model $\overrightarrow{I_S} = \overrightarrow{I_1} + \overrightarrow{V_S} \frac{Y}{2} = \overrightarrow{I_R} + \overrightarrow{V_R} \frac{Y}{2} + \frac{Y}{2} \left(1 + \frac{ZY}{2}\right) \overrightarrow{V_R} + \frac{Y}{2} Z \overrightarrow{I_R}$ $= \overrightarrow{V_R} \left(\frac{Y}{2} + \frac{Y}{2} + \frac{Y^2 Z}{4}\right) + \overrightarrow{I_R} \left(1 + \frac{YZ}{2}\right)$ $= \overrightarrow{V_R} \left(Y + \frac{Y^2 Z}{4}\right) + \overrightarrow{I_R} \left(1 + \frac{YZ}{2}\right)$ $\left[\overrightarrow{V_S}\right] = \begin{bmatrix} 1 + \frac{YZ}{2} & Z \\ Y \left(1 + \frac{YZ}{4}\right) & 1 + \frac{YZ}{2} \end{bmatrix} \overrightarrow{I_R}$ © Washington State University

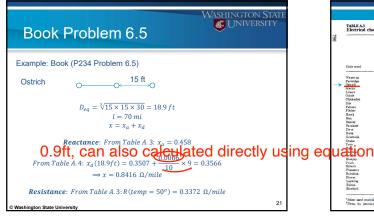
15

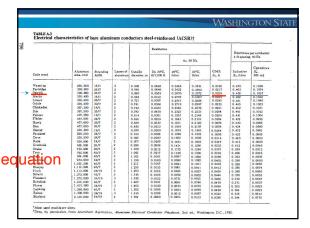


Long Line Model $\frac{d\overline{I_x}}{dx} = y\overline{V_x} \Rightarrow \frac{d^2\overline{V_x}}{dx^2} = yz\overline{V_x} \\
= \frac{d^2\overline{V_x}}{dx} = z\overline{I_x} \qquad \frac{d^2\overline{I_x}}{dx^2} = yz\overline{I_x}$ $Z_c = \sqrt{\frac{z}{y}} & \gamma = \sqrt{zy}$ $Z_c = \sqrt{\frac{z}{y}} & \gamma = \sqrt{zy}$ Washington State University $Z_c = \sqrt{\frac{z}{y}} & \gamma = \sqrt{zy}$ $Z_c = \sqrt{\frac{z}{y}} & \gamma = \sqrt{zy}$ Washington State University









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