



E_E 491

Review Session #4

A decorative graphic on the left side of the slide, consisting of several thin, curved lines in shades of blue and grey, and a solid blue arrow pointing to the right.

Ali Shakeri Kahnarmouei

Fall 2020



Power Flow Equations

Bus Type	Given Parameters	Unknown Parameters
Slack Bus	V, δ	P, Q
Generator Bus	$P, V $	Q, δ
Load Bus	P, Q	V, δ

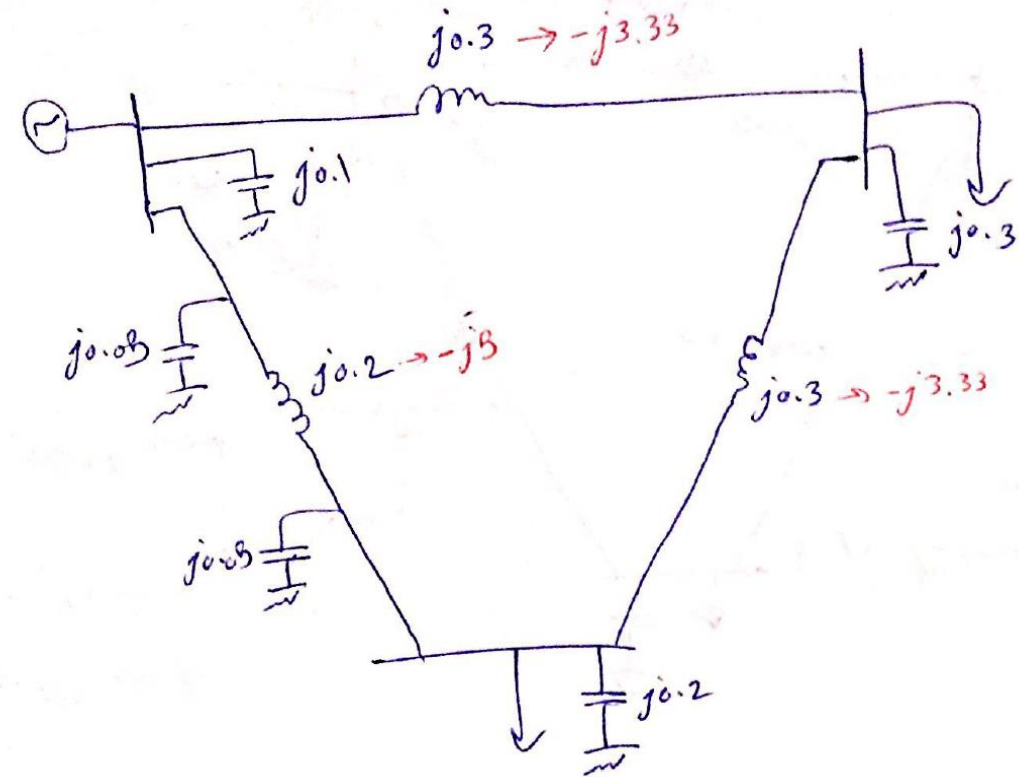
$$P_i = \sum_{j=1}^n |Y_{ij} V_i V_j| \cos(\delta_i - \delta_j - \theta_{ij})$$

$$Q_i = \sum_{j=1}^n |Y_{ij} V_i V_j| \sin(\delta_i - \delta_j - \theta_{ij})$$

Power Flow Equations (Ex. 1)

$V_1 = 1, \delta_1 = 0, PL_2 = 0.2, QL_2 = 0.1, PL_3 = 0.5, QL_3 = 0.3$

- (1) Slack Bus: $V_1 = 1, \delta_1 = 0, P_1 = ?, Q_1 = ?$
- (2) PQ Bus: $P_2 = PG_2 - PL_2 = 0 - 0.2 = -0.2, Q_2 = -0.1, V_2 = ?, \delta_2 = ?$
- (3) PQ Bus: $P_3 = -0.5, Q_3 = -0.3, V_3 = ?, \delta_3 = ?$





Power Flow Equations (Ex. 1)

$$\overline{Y}_{BUS} = \begin{bmatrix} 8.18 \angle -90^\circ & 3.33 \angle 90^\circ & 5 \angle 90^\circ \\ 3.33 \angle 90^\circ & 6.36 \angle -90^\circ & 3.33 \angle 90^\circ \\ 5 \angle 90^\circ & 3.33 \angle 90^\circ & 8.08 \angle -90^\circ \end{bmatrix}$$

$$P1 = 3.33 * V1 * V2 * \cos(-\delta2 - 90) + 5 * V1 * V3 * \cos(-\delta3 - 90)$$

$$Q1 = 8.18 * V1^2 * \sin(90) + 3.33 * V1 * V2 * \sin(\delta1 - \delta2 - 90) + 5 * V1 * V3 * \sin(\delta1 - \delta3 - 90)$$

Bus 2:

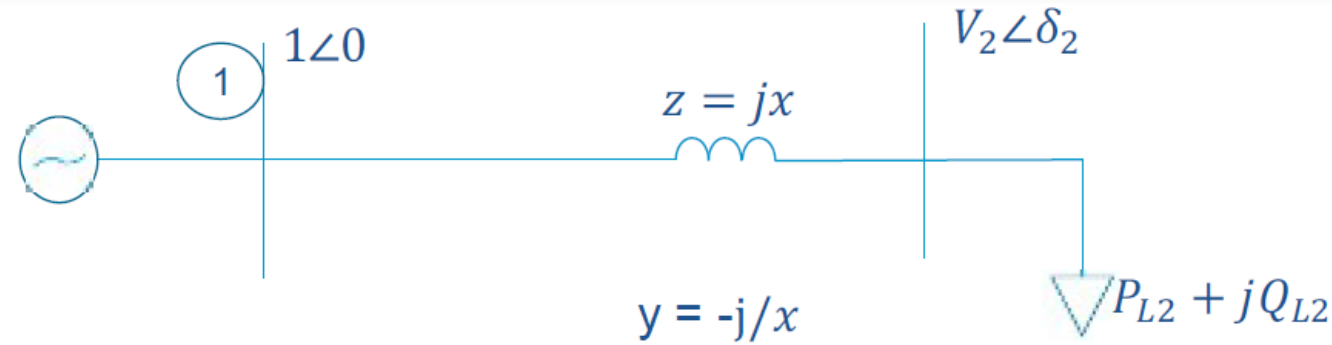
$$P2 = 3.33 * V2 * V1 * \cos(\delta2 - \delta1 - 90) + 6.36 * V2^2 * \cos(90) + 3.33 * V2 * V3 * \cos(\delta2 - \delta3 - 90)$$

$$Q2 = 3.33 * V2 * V1 * \sin(\delta2 - \delta1 - 90) + 6.36 * V2^2 * \sin(90) + 3.33 * V2 * V3 * \sin(\delta2 - \delta3 - 90)$$

Bus 3:

$$P3 = 5 * V3 * V1 * \cos(\delta3 - \delta1 - 90) + 3.33 * V3 * V2 * \cos(\delta3 - \delta2 - 90) + 8.08 * V3^2 * \cos(90)$$

$$Q3 = 5 * V3 * V1 * \sin(\delta3 - \delta1 - 90) + 3.33 * V3 * V2 * \sin(\delta3 - \delta2 - 90) + 8.08 * V3^2 * \sin(90)$$



$$\overrightarrow{Y_{Bus}} = \begin{bmatrix} \frac{1}{x} \angle -90^\circ & \frac{1}{x} \angle 90^\circ \\ \frac{1}{x} \angle 90^\circ & \frac{1}{x} \angle -90^\circ \end{bmatrix}$$

5

PV Diagram



PV Diagram

$$P_2 = V_2 V_1 y_{21} \cos(\delta_2 - \delta_1 - \theta_{21}) + V_2^2 y_{22} \cos(\theta_{22}) \quad (1)$$

$$P_2 = V_2 \frac{1}{x} \cos(\delta_2 - 90) + V_2^2 \frac{1}{x} \cos(-90) \quad (2)$$

$$P_2 = V_2 \frac{1}{x} \sin(\delta_2) = -P_{L_2} \quad (3)$$

$$Q_2 = V_2 V_1 y_{21} \sin(\delta_2 - \delta_1 - \theta_{21}) - V_2^2 y_{22} \sin(\theta_{22}) \quad (4)$$

$$Q_2 = V_2 \frac{1}{x} \sin(\delta_2 - 90) - V_2^2 \frac{1}{x} \sin(-90) \quad (5)$$

$$Q_2 = -V_2 \frac{1}{x} \cos(\delta_2) + V_2^2 \frac{1}{x} = -Q_{L_2} \quad (6)$$

$$V_2 \sin(\delta_2) = -x P_{L_2} \quad (7)$$

$$V_2^2 (\sin(\delta_2))^2 = (x P_{L_2})^2 \quad (8)$$

$$V_2^2 (\cos(\delta_2))^2 = (x Q_{L_2} + V_2^2)^2 \quad (9)$$

$$V_2^2 = (x P_{L_2})^2 + (x Q_{L_2})^2 + 2x Q_{L_2} V_2^2 + V_2^4 \quad (10)$$

$$V_2^4 + V_2^2 (2x Q_{L_2} - 1) + x^2 (P_{L_2}^2 + Q_{L_2}^2) = 0 \quad (11)$$

PV Diagram (x=0.4, Unity PF)

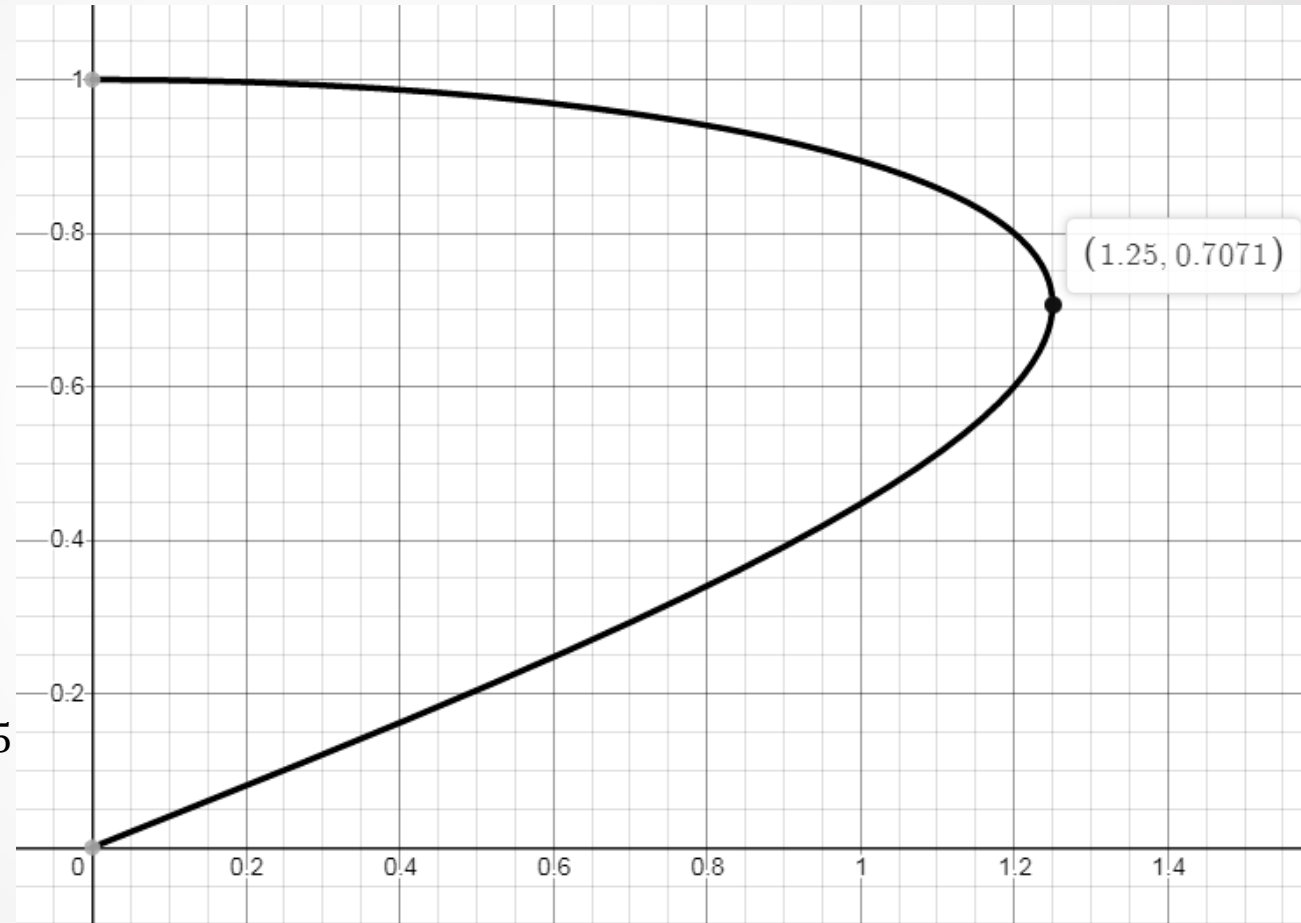
$$\cos(\delta_2) = 1 \Rightarrow \delta_2 = 0$$

$$Q_{L_2} = P_{L_2} \tan(\delta_2) = 0$$

$$V_2^4 - V_2^2 + 0.16P_{L_2}^2 = 0$$

$$V_2^2 = \frac{1 \pm \sqrt{1 - 0.64P_{L_2}^2}}{2}$$

$$V_2 = \begin{cases} 1, 0 & , P_{L_2} = 0 \\ \sqrt{\frac{1 \pm \sqrt{1 - 0.64P_{L_2}^2}}{2}} & , 0 < P_{L_2} < 1.25 \\ \frac{1}{\sqrt{2}} & , P_{L_2} = 1.25 \\ Undefined & , P_{L_2} > 1.25 \end{cases}$$





8

PV Diagram ($x=0.4$, 0.8 PF Lagging)

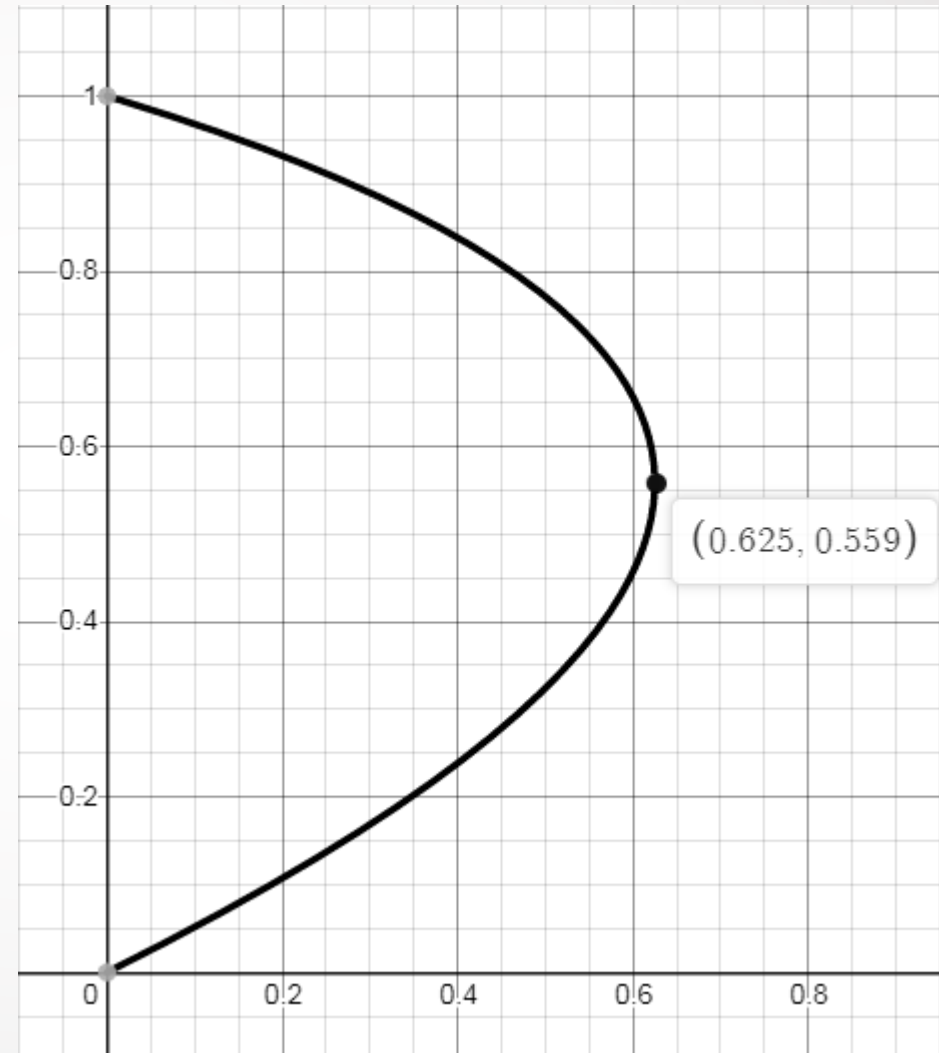
$$\cos(\delta_2) = 0.8 \Rightarrow \delta_2 = \arccos(0.8)$$

$$Q_{L_2} = P_{L_2} \tan(\delta_2) = P_{L_2} \tan(\arccos(0.8)) = 0.75P_{L_2}$$

$$V_2^4 + V_2^2(0.6P_{L_2} - 1) + 0.25P_{L_2}^2 = 0$$

$$V_2^2 = \frac{(1 - 0.6P_{L_2}) \pm \sqrt{1 - 1.2P_{L_2} - 0.64P_{L_2}^2}}{2}$$

$$V_2 = \begin{cases} 1, 0 & , P_{L_2} = 0 \\ \frac{(1 - 0.6P_{L_2}) \pm \sqrt{1 - 1.2P_{L_2} - 0.64P_{L_2}^2}}{2} & , 0 < P_{L_2} < 0.625 \\ 0.559 & , P_{L_2} = 0.625 \\ \text{Undefined} & , P_{L_2} > 0.625 \end{cases}$$





9

PV Diagram ($x=0.4$, 0.8 PF Leading)

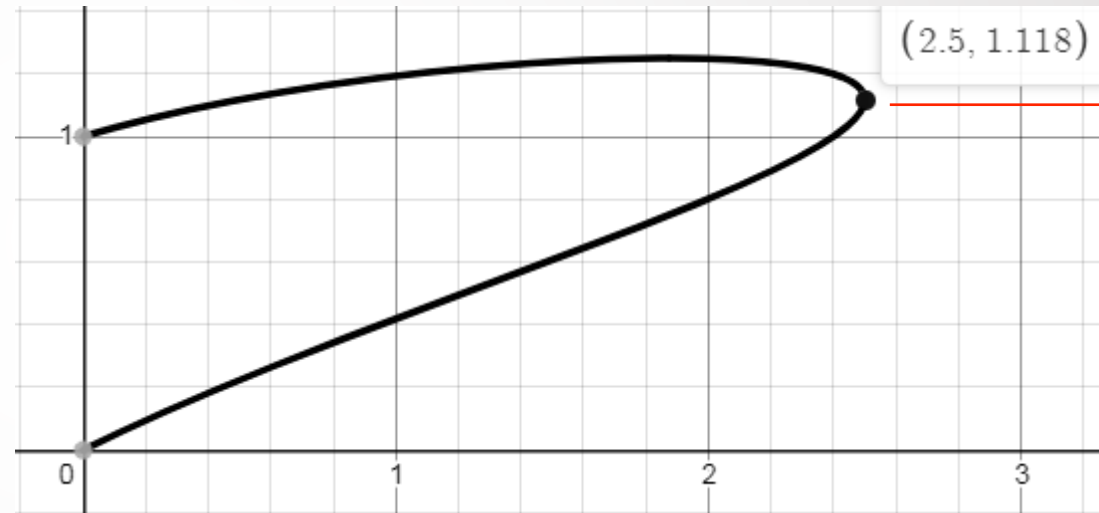
$$\cos(\delta_2) = 0.8 \Rightarrow \delta_2 = \arccos(0.8)$$

$$Q_{L_2} = -P_{L_2} \tan(\delta_2) = -P_{L_2} \tan(\arccos(0.8)) = -0.75P_{L_2}$$

$$V_2^4 - V_2^2(0.6P_{L_2} + 1) + 0.25P_{L_2}^2 = 0$$

$$V_2^2 = \frac{(1 + 0.6P_{L_2}) \pm \sqrt{1 + 1.2P_{L_2} - 0.64P_{L_2}^2}}{2}$$

$$V_2 = \begin{cases} 1, 0 & , P_{L_2} = 0 \\ \sqrt{\frac{(1 + 0.6P_{L_2}) \pm \sqrt{1 + 1.2P_{L_2} - 0.64P_{L_2}^2}}{2}} & , 0 < P_{L_2} < 2.5 \\ 1.118 & , P_{L_2} = 2.5 \\ \text{Undefined} & , P_{L_2} > 2.5 \end{cases}$$



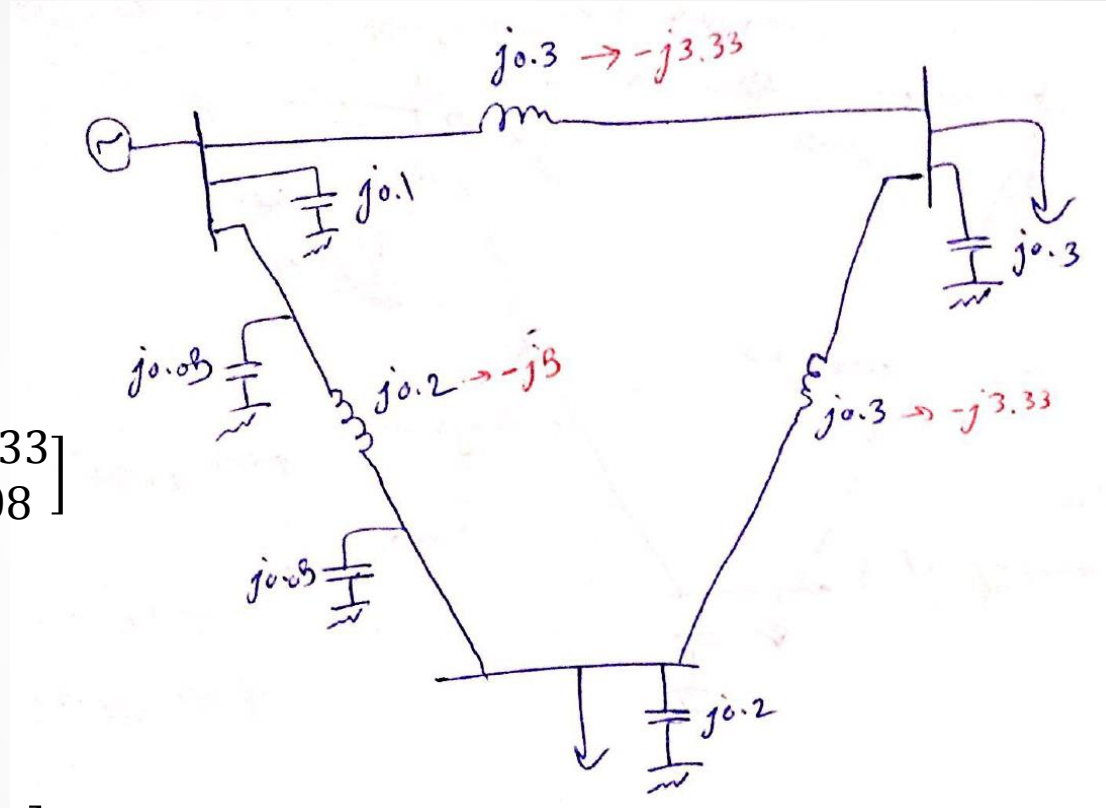
DC Power Flow

$$\overrightarrow{Y}_{BUS} = \begin{bmatrix} -j8.18 & j3.33 & j5 \\ j3.33 & -j6.36 & j3.33 \\ j5 & j3.33 & -j8.08 \end{bmatrix}$$

$$B_{DC} = -\text{Imag}[Y_{BUS}]_{2:3}^{2:3} = \begin{bmatrix} 6.36 & -3.33 \\ -3.33 & 8.08 \end{bmatrix}$$

$$P_{L_2} = 0.2, Q_{L_2} = 0.1$$

$$P_{L_3} = 0.5, Q_{L_3} = 0.3$$



$$\begin{bmatrix} P_2 \\ P_3 \end{bmatrix} = B_{DC} \begin{bmatrix} \delta_2 \\ \delta_3 \end{bmatrix} \Rightarrow \begin{bmatrix} \delta_2 \\ \delta_3 \end{bmatrix} = B_{DC}^{-1} \begin{bmatrix} -P_{L_2} \\ -P_{L_3} \end{bmatrix} \Rightarrow \begin{bmatrix} \delta_2 \\ \delta_3 \end{bmatrix} = \begin{bmatrix} 0.2005 & 0.0826 \\ 0.0826 & 0.1578 \end{bmatrix} \begin{bmatrix} -0.2 \\ -0.5 \end{bmatrix} = \begin{bmatrix} -0.0814 \\ -0.0954 \end{bmatrix}$$

$$\begin{bmatrix} \overrightarrow{V_1} \\ \overrightarrow{V_2} \\ \overrightarrow{V_3} \end{bmatrix} = \begin{bmatrix} 1 \angle 0 \\ 1 \angle -0.0814 \\ 1 \angle -0.0954 \end{bmatrix}$$



Questions?