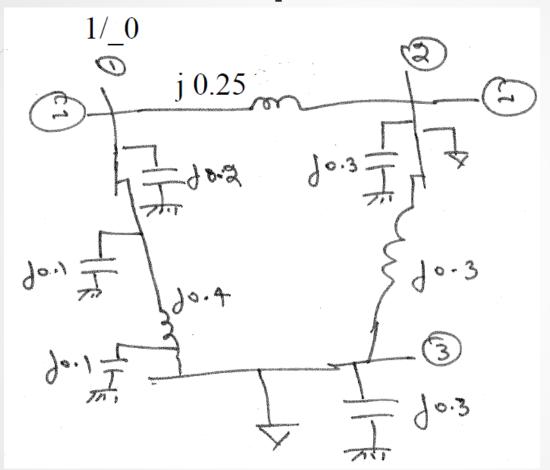


E_E 491 Review Session #7

Ali Shakeri Kahnamouei Fall 2020



Fast Decoupled Ex.



$$P_{G_2} = 1.0, V_2 = 1.04, P_{L_2} = 0.25, Q_{L_2} = 0.1, P_{L_3} = 0.5, Q_{L_3} = 0.3$$



Fast Decoupled Ex.



Fast Decoupled Ex.

$$\begin{bmatrix}
R_{1}^{1} \\
R_{1}^{1} \\
Q_{1}^{1}
\end{bmatrix} = \begin{bmatrix}
0.769 \\
-0.512
\end{bmatrix}
\quad and \quad \begin{cases}
\Delta R_{1}^{1} \\
\Delta R_{3}^{1}
\end{bmatrix} = \begin{bmatrix}
R_{1}^{1} - 0.75 \\
0.01245
\end{bmatrix}$$

$$\begin{bmatrix}
\Delta \delta_{1}^{1} \\
\delta_{3}^{1}
\end{bmatrix} = \begin{bmatrix}
0.769 \\
-0.315
\end{bmatrix}
\quad and \quad \begin{cases}
\Delta R_{1}^{1} \\
\Delta R_{3}^{1}
\end{bmatrix} = \begin{bmatrix}
R_{1}^{1} + 0.5 \\
R_{1}^{1} + 0.3
\end{bmatrix}$$

$$\begin{bmatrix}
\Delta \delta_{1}^{1} \\
\delta_{3}^{1}
\end{bmatrix} = \begin{bmatrix}
0.01222 \\
0.000923
\end{bmatrix}$$

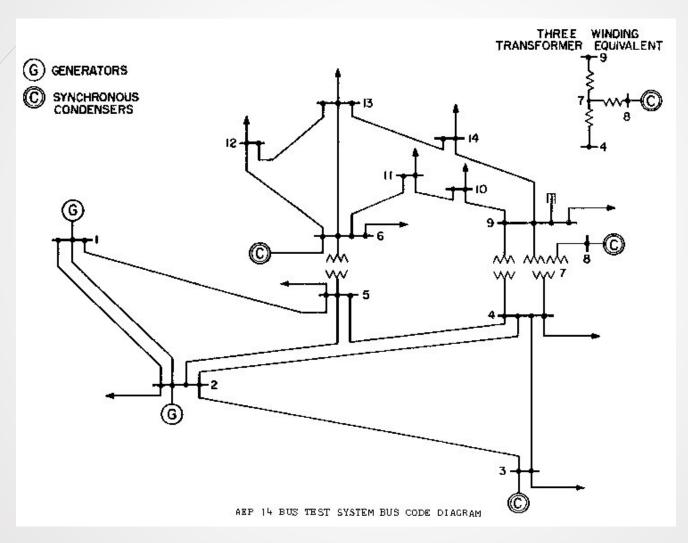
$$\Delta V_{3}^{1} = B_{V}^{1} \begin{pmatrix}
\Delta P_{3}^{1} \\
N_{3}^{1}
\end{pmatrix} = 0.00284$$

$$X^{(1)} = X^{(1)} + \Delta X^{(1)} = \begin{bmatrix}
\delta_{1}^{(1)} + \Delta \delta_{3}^{(1)} \\
\delta_{3}^{(1)} + \Delta \delta_{3}^{(1)}
\end{bmatrix} = \begin{bmatrix}
0.0796 \\
-0.0353 \\
1.0403
\end{bmatrix}$$
Therefore,
$$S^{(1)} = \begin{bmatrix}
0.0796 \\
-0.0353
\end{bmatrix}$$

$$Y^{(2)} = \begin{bmatrix}
1.04 \\
1.040375
\end{bmatrix}$$



Q-limits (IEEE 14-Bus System)





Questions?