ADDITIONAL THOUGHTS ON THE EXISTENCE OF GLOBAL MINIMIZERS We discussed in class that none of the six properties below is sufficient for guaranteeing the existence of a global minimizer of f: R">R. Continuous 2. Bounded Below 3. Convex 4. Quasi-convex 5 Coercive 6. existence of a local minimizer However, some combinations of two properties are sufficent. Theorem; let f: R">R be convex. If x" is a local minimizer of f, then x is a global minimizer of f. Theorem: Let f: RM = R be coercive. If f is either continuous or bounded below or quasi-convex, then some (note that the grasi convex X'EIR exists which is a global minimizer of f. Condition allows convex as well) Another way to think about coercive functions: Fact: A function f: Rh > R is operate if and only if every subserver set of f to bounded All other combinations of two properties from the list above do not guarantee the existence of a global minimizer. See the chart on the next page. Some Cautions: Convexity or quasiconvexity is not necessary for the existence of a global minimizer. Convexity => quasiconvex not the other way We will see examples of discontinuous convex finctions (normally this cannot happen!)

This table shows	Counterex	amples where	2 two propert	ies hold and no	glòbal min exists
Bounded Below	convex	quasiconvex	coercive	local min exists	
e-×	e-x	e ^{-x}	Malks,	$(x^2 + \frac{1}{2})e^{-x}$	Continuous
	e ^{-x}	·e×	warks)	$(x^2 + \frac{1}{2})e^{-x}$	Bounded Below
		e ^{-x}	maries.	morks)	Convex
			Markey.	Slat /	quasiconvex
					coercive