EECE 8395 - Medical Image Segmentation

Project 3

Tahsin Reasat

ID: 000614908

All local functions are attached at the end of the script.

```
clear all
close all
clc
```

Task 1

1a) First we load in our ground truth mandible and mandible segmentations from 3 raters

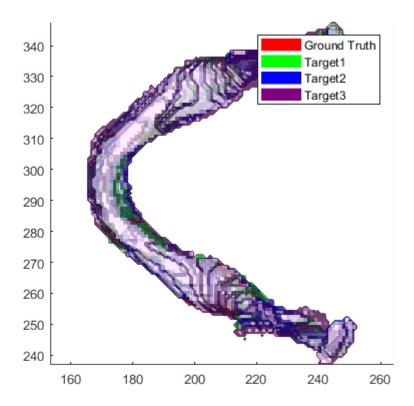
```
data_dir='C:\Users\reasatt\Data\EECE_395\';
gt = ReadNrrd([data_dir '0522c0001\structures\mandible.nrrd']);
t1 = ReadNrrd([data_dir '\0522c0001\structures\target1.nrrd']);
t2 = ReadNrrd([data_dir '\0522c0001\structures\target2.nrrd']);
t3 = ReadNrrd([data_dir '\0522c0001\structures\target3.nrrd']);
```

1b) Now we create surfaces for all of the volumetric segmentations.

```
gts = isosurface(gt.data,0.5);
gts.vertices = gts.vertices.*repmat(gt.voxsz,[length(gts.vertices),1]);
t1s = isosurface(t1.data,0.5);
t1s.vertices = t1s.vertices.*repmat(t1.voxsz,[length(t1s.vertices),1]);
t2s = isosurface(t2.data,0.5);
t2s.vertices = t2s.vertices.*repmat(t2.voxsz,[length(t2s.vertices),1]);
t3s = isosurface(t3.data,0.5);
t3s.vertices = t3s.vertices.*repmat(t3.voxsz,[length(t3s.vertices),1]);
```

1c) Display the surfaces in one figure

```
figure(1);clf
DisplayMesh(gts,[1,0,0],0.5);...
DisplayMesh(t1s,[0,1,0],0.5);...
DisplayMesh(t2s,[0,0,1],0.5);...
DisplayMesh(t3s,[0.5,0,0.5],0.5);...
legend('Ground Truth', 'Target1','Target2','Target3')
```



1d) Calculate volume

```
volume_gts=VolumeofMesh(gts);
volume_t1s=VolumeofMesh(t1s);
volume_t2s=VolumeofMesh(t2s);
volume_t3s=VolumeofMesh(t3s);
```

1e) Measure Dice similarity, mean symmetric absolute surface, Hausdorff distance between the ground truth and each of the three raters

Dice

```
dice_t1=dice(t1.data,gt.data);
dice_t2=dice(t2.data,gt.data);
dice_t3=dice(t3.data,gt.data);
```

Mean symmetric absolute surface, and Hausdorff distance

```
[mn1,mn2,mx1,mx2]=SurfaceDistance(gts,t1s);
meandist1=mean([mn1,mn2])

meandist1 = 0.1150
```

```
hausdorff1=max([mx1,mx2])
```

```
hausdorff1 = 1.1200
```

```
[mn1,mn2,mx1,mx2]=SurfaceDistance(gts,t2s);
meandist2=mean([mn1,mn2])

meandist2 = 0.1267

hausdorff2=max([mx1,mx2])

hausdorff2 = 2.3787

[mn1,mn2,mx1,mx2]=SurfaceDistance(gts,t3s);
meandist3=mean([mn1,mn2])

meandist3 = 0.8586

hausdorff3=max([mx1,mx2])

hausdorff3 = 5.2463
```

1g) Create a majority vote segmentation from the three rater segmentations, measure its volume, and measure Dice similarity, Mean surface, and Hausdorff distances to the ground truth

```
mv = t1;
mv.data = t1.data + t2.data + t3.data > 1.5;
mvs = isosurface(mv.data,0.5);
mvs.vertices = mvs.vertices.*repmat(mv.voxsz,[length(mvs.vertices),1]);
[mn1,mn2,mx1,mx2]=SurfaceDistance(gts,mvs);
meandistmv=mean([mn1,mn2])

meandistmv = 0.0860

hausdorffmv=max([mx1,mx2])
```

Task 2

Define filepaths

```
data_dir='C:\Users\reasatt\Data\EECE_395';
filepaths_gt=glob([data_dir '\*\structures\mandible.nrrd']);
% glob performs pattern matching of file and directory names based on
% wildcard characters. Downloaded from mathworks file exchange section.
filepaths_t1=glob([data_dir '\*\structures\target1.nrrd']);
filepaths_t2=glob([data_dir '\*\structures\target2.nrrd']);
filepaths_t3=glob([data_dir '\*\structures\target3.nrrd']);
```

Initialize variables to store data

```
n sample=10;
volume gts vec=zeros(1,n sample);
volume t1s vec=zeros(1,n sample);
volume t2s vec=zeros(1,n sample);
volume t3s vec=zeros(1,n sample);
tp1 vec=zeros(1,n sample);
tn1 vec=zeros(1,n sample);
fp1 vec=zeros(1,n sample);
fn1 vec=zeros(1,n sample);
tp2 vec=zeros(1,n sample);
tn2 vec=zeros(1,n sample);
fp2 vec=zeros(1,n sample);
fn2 vec=zeros(1,n sample);
tp3 vec=zeros(1,n sample);
tn3 vec=zeros(1,n sample);
fp3 vec=zeros(1,n sample);
fn3 vec=zeros(1,n sample);
dice t1 vec=zeros(1,n sample);
dice t2 vec=zeros(1,n sample);
dice t3 vec=zeros(1,n sample);
dice mv vec=zeros(1,n sample);
hausdorff1 vec=zeros(1,n sample);
hausdorff2 vec=zeros(1,n sample);
hausdorff3 vec=zeros(1,n sample);
hausdorffmv vec=zeros(1,n sample);
meandist1 vec=zeros(1,n sample);
meandist2 vec=zeros(1,n sample);
meandist3 vec=zeros(1,n sample);
meandistmv vec=zeros(1,n sample);
```

Compute data for the first 10 samples

```
for i= 1:n sample
    tic
    gt = ReadNrrd(filepaths gt{i});
    t1 = ReadNrrd(filepaths t1{i});
    t2 = ReadNrrd(filepaths t2{i});
    t3 = ReadNrrd(filepaths t3{i});
    qts = isosurface(gt.data,0.5);
   qts.vertices = qts.vertices.*repmat(qt.voxsz,[length(qts.vertices),1]);
    t1s = isosurface(t1.data, 0.5);
    tls.vertices = tls.vertices.*repmat(tl.voxsz,[length(tls.vertices),1]);
    t2s = isosurface(t2.data,0.5);
    t2s.vertices = t2s.vertices.*repmat(t2.voxsz,[length(t2s.vertices),1]);
    t3s = isosurface(t3.data,0.5);
    t3s.vertices = t3s.vertices.*repmat(t3.voxsz,[length(t3s.vertices),1]);
   mv = t1;
   mv.data =double(t1.data + t2.data + t3.data > 1.5);
   mvs = isosurface(mv.data,0.5);
   mvs.vertices = mvs.vertices.*repmat(mv.voxsz,[length(mvs.vertices),1]);
   %% Calculate volume
```

```
volume gts=VolumeofMesh(gts);
volume t1s=VolumeofMesh(t1s);
volume t2s=VolumeofMesh(t2s);
volume t3s=VolumeofMesh(t3s);
%% Calculate tp,tn,fp,fn
[tp1,fp1,tn1,fn1]=class perf(gt.data,t1.data);
[tp2,fp2,tn2,fn2]=class perf(gt.data,t2.data);
[tp3,fp3,tn3,fn3]=class perf(gt.data,t3.data);
%% Dice coefficient
dice t1=dice(t1.data,gt.data);
dice t2=dice(t2.data,gt.data);
dice t3=dice(t3.data,gt.data);
dice mv=dice(mv.data,gt.data);
% Mean symmetric absolute surface, and Hausdorff distance
[mn1,mn2,mx1,mx2]=SurfaceDistance(gts,t1s);
meandist1=mean([mn1,mn2]);
hausdorff1=max([mx1,mx2]);
[mn1,mn2,mx1,mx2]=SurfaceDistance(gts,t2s);
meandist2=mean([mn1,mn2]);
hausdorff2=max([mx1,mx2]);
[mn1,mn2,mx1,mx2]=SurfaceDistance(gts,t3s);
meandist3=mean([mn1,mn2]);
hausdorff3=max([mx1,mx2]);
[mn1,mn2,mx1,mx2]=SurfaceDistance(gts,mvs);
meandistmv=mean([mn1,mn2]);
hausdorffmv=max([mx1,mx2]);
%% Store all data
volume gts vec(i)=volume gts;
volume t1s vec(i)=volume t1s;
volume t2s vec(i)=volume t2s;
volume t3s vec(i)=volume t3s;
tpl vec(i)=tpl; tnl vec(i)=tnl;fpl vec(i)=fpl;fnl vec(i)=fnl;
tp2 vec(i)=tp2; tn2 vec(i)=tn2; fp2 vec(i)=fp2; fn2 vec(i)=fn2;
tp3 \text{vec}(i) = \text{tp3}; tn3 \text{vec}(i) = \text{tn3}; fp3 \text{vec}(i) = \text{fp3}; fn3 \text{vec}(i) = \text{fn3};
dice t1 vec(i)=dice t1;
dice t2 vec(i)=dice t2;
dice t3 vec(i)=dice t3;
dice mv vec(i)=dice mv;
hausdorff1 vec(i)=hausdorff1;
hausdorff2 vec(i)=hausdorff2;
hausdorff3 vec(i)=hausdorff3;
hausdorffmv vec(i)=hausdorffmv;
meandist1 vec(i)=meandist1;
meandist2_vec(i)=meandist2;
meandist3 vec(i)=meandist3;
meandistmv vec(i)=meandistmv;
time elapsed=toc;
split path=strsplit(filepaths gt{i},'\');
fprintf('%d. computation done for patient %s, time taken: %.2f minutes\n',...
```

```
i,split path{6}, time elapsed/60)
end
1. computation done for patient 0522c0001, time taken: 6.87 minutes
2. computation done for patient 0522c0002, time taken: 14.19 minutes
3. computation done for patient 0522c0003, time taken: 8.23 minutes
4. computation done for patient 0522c0009, time taken: 13.49 minutes
5. computation done for patient 0522c0013, time taken: 9.86 minutes
6. computation done for patient 0522c0014, time taken: 20.48 minutes
7. computation done for patient 0522c0017, time taken: 11.66 minutes
8. computation done for patient 0522c0057, time taken: 19.55 minutes
9. computation done for patient 0522c0070, time taken: 11.86 minutes
10. computation done for patient 0522c0077, time taken: 14.93 minutes
%save('project 3.mat')
%load('project 3.mat')
tp1 all=sum(tp1 vec);
tn1 all=sum(tn1 vec);
```

2a) Overall confusion matrix

```
fp1 all=sum(fp1 vec);
fn1 all=sum(fn1 vec);
T cf1=table([tp1 all; fn1 all],[fp1 all; tn1 all],...
'VariableNames',{'gt_negative','gt_positive'},...
'RowNames', { 't1 negative'; 't1 positive'});
fprintf('Confusion matrix between ground truth and target1\n\n'); disp(T cf1)
```

Confusion matrix between ground truth and target1

```
gt negative
                              gt_positive
               1.6507e+05
                                    4190
t1 negative
                              3.5923e+08
tl positive
                     3817
```

```
tp2 all=sum(tp2 vec);
tn2 all=sum(tn2 vec);
fp2 all=sum(fp2 vec);
fn2 all=sum(fn2 vec);
T cf2=table([tp2 all; fn2 all],[fp2 all; tn2 all],...
'VariableNames',{'gt_negative','gt_positive'},...
'RowNames', { 't2 negative'; 't2 positive'});
fprintf('Confusion matrix between ground truth and target2\n\n'); disp(T cf2)
```

Confusion matrix between ground truth and target2

```
gt negative
                               gt positive
t2 negative
               1.6597e+05
                                     3654
                               3.5923e+08
t2 positive
                     2913
```

```
tp3_all=sum(tp3_vec);
tn3_all=sum(tn3_vec);
fp3_all=sum(fp3_vec);
fn3_all=sum(fn3_vec);
T_cf3=table([tp3_all; fn3_all],[fp3_all; tn3_all],...
'VariableNames',{'gt_negative','gt_positive'},...
'RowNames',{'t3_negative';'t3_positive'});
fprintf('Confusion matrix between ground truth and target3\n\n'); disp(T_cf3)
```

Confusion matrix between ground truth and target3

```
gt_negative gt_positive ______
t3_negative 1.4798e+05 35285 t3_positive 20903 3.592e+08
```

2b) Sensitivity and Specificity of the targets

```
Sel=tp1_all/(tp1_all+fn1_all);
Sp1=tn1_all/(tn1_all+fp1_all);
Se2=tp2_all/(tp2_all+fn2_all);
Sp2=tn2_all/(tn2_all+fp2_all);
Se3=tp3_all/(tp3_all+fn3_all);
Sp3=tn3_all/(tn3_all+fp3_all);
T_sen_sp=table([Se1;Se2;Se3],[Sp1; Sp2; Sp3],...
'VariableNames',{'Sensitivity','Specificity'},...
'RowNames',{'t1';'t2';'t3'});
disp(T_sen_sp)
```

	Sensitivity	Specificity	
t1	0.9774	0.99999	
t2	0.98275	0.99999	
t3	0.87623	0.9999	

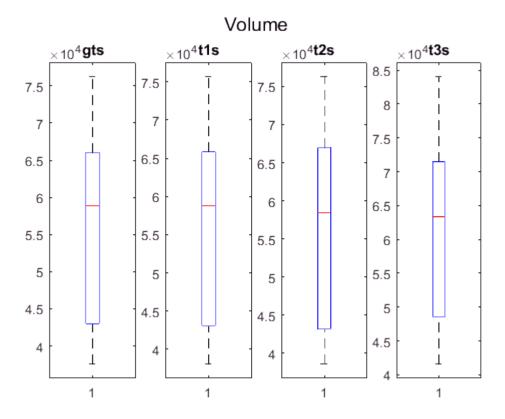
Task 3

- 3a) Code is in the livescript.
- 3b) The segmentations are shown in Task 1c
- 3c) Boxplot of overall results of Task 1d to 1g

Volume

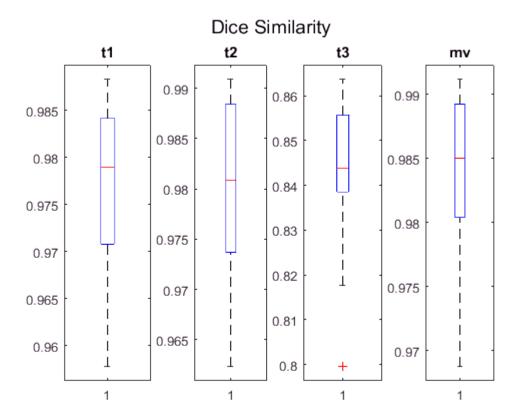
```
subplot(1,4,1); boxplot(volume_gts_vec);title('gts');...
```

```
subplot(1,4,2); boxplot(volume_t1s_vec);title('t1s');...
subplot(1,4,3); boxplot(volume_t2s_vec);title('t2s');...
subplot(1,4,4);boxplot(volume_t3s_vec);title('t3s');...
suptitle('Volume')
```



Dice

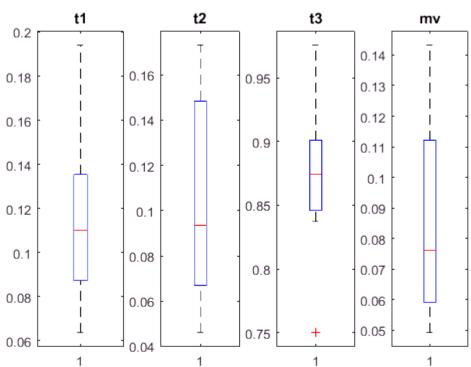
```
subplot(1,4,1);boxplot(dice_t1_vec); title('t1');...
subplot(1,4,2);boxplot(dice_t2_vec);title('t2');...
subplot(1,4,3); boxplot(dice_t3_vec);title('t3');...
subplot(1,4,4);boxplot(dice_mv_vec);title('mv');
suptitle('Dice_Similarity')
```



Mean surface distance

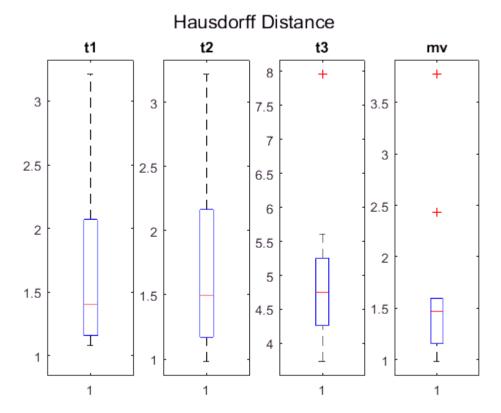
```
subplot(1,4,1);boxplot(meandist1_vec);title('t1');...
subplot(1,4,2);boxplot(meandist2_vec);title('t2');...
subplot(1,4,3);boxplot(meandist3_vec);title('t3');...
subplot(1,4,4);boxplot(meandistmv_vec);title('mv');...
suptitle('Mean Surface Distance')
```





Hausdorff distance

```
subplot(1,4,1);boxplot(hausdorff1_vec);title('t1');...
subplot(1,4,2);boxplot(hausdorff2_vec);title('t2');...
subplot(1,4,3);boxplot(hausdorff3_vec);title('t3');...
subplot(1,4,4);boxplot(hausdorffmv_vec);title('mv');...
suptitle('Hausdorff Distance')
```



3d) Wilcoxon signed-rank test

```
[p volume 1,h volume 1] = signrank(volume gts vec,volume t1s vec);
[p volume 2,h volume 2] = signrank(volume gts vec,volume t2s vec);
[p volume 3,h volume 3] = signrank(volume gts vec,volume t3s vec);
[p volume 12,h volume 12] = signrank(volume t1s vec,volume t2s vec);
[p volume 23,h volume 23] = signrank(volume t2s vec,volume t3s vec);
[p volume 13,h volume 13] = signrank(volume t1s vec,volume t3s vec);
[p dice 12,h dice 12] = signrank(dice t1 vec,dice t2 vec);
[p dice 23,h dice 23] = signrank(dice t2 vec,dice t3 vec);
[p dice 13,h dice 13] = signrank(dice t1 vec,dice t3 vec);
[p meandist 12,h meandist 12] = signrank(meandist1 vec,meandist2 vec);
[p meandist 23,h meandist 23] = signrank(meandist2 vec,meandist3 vec);
[p meandist 13,h meandist 13] = signrank(meandist1 vec,meandist3 vec);
[p hausdorff 12,h hausdorff 12] = signrank(hausdorff1 vec,hausdorff2 vec);
[p hausdorff 23,h hausdorff 23] = signrank(hausdorff2 vec,hausdorff3 vec);
[p hausdorff 13,h hausdorff 13] = signrank(hausdorff1 vec,hausdorff3 vec);
T wil volume=table([p volume 1;p volume 2;p volume 3;p volume 12;p volume 23;p volume 13],...
    [h_volume_1;h_volume_2;h_volume 3;h volume 12;h volume 23;h volume 13],...
    'VariableNames',{'p_value','test_decision'},...
    'RowNames',{'gt and t1';'gt and t2';'gt and t3';'t1 and t2';'t2 and t3';'t1 and t3';});
T wil dice=table([p dice 12;p dice 23;p dice 13],...
    [h_dice_12;h_dice_23;h_dice_13],...
    'VariableNames', {'p_value', 'test_decision'},...
    'RowNames', { 't1 and t2'; 't2 and t3'; 't1 and t3'; });
```

```
T_wil_meandist=table([p_meandist_12;p_meandist_23;p_meandist_13],...
    [h_meandist_12;h_meandist_23;h_meandist_13],...
    'VariableNames',{'p_value','test_decision'},...
    'RowNames',{'t1 and t2';'t2 and t3';'t1 and t3';});

T_wil_hausdorff=table([p_hausdorff_12;p_hausdorff_23;p_hausdorff_13],...
    [h_hausdorff_12;h_hausdorff_23;h_hausdorff_13],...
    'VariableNames',{'p_value','test_decision'},...
    'RowNames',{'t1 and t2';'t2 and t3';'t1 and t3';});

fprintf('Wilcoxon signed-rank test for volume\n\n');disp(T_wil_volume)
```

Wilcoxon signed-rank test for volume

		p_value	${\tt test_decision}$
gt and gt and gt and t1 and t2 and	t2 t3 t2 t3	0.8457 0.69531 0.0019531 0.76953 0.0019531	false false true false true
t1 and	t3	0.0019531	true

fprintf('Wilcoxon signed-rank test for dice similarity\n\n'); disp(T_wil_dice)

Wilcoxon signed-rank test for dice similarity

fprintf('Wilcoxon signed-rank test for mean surface distance\n\n'); disp(T_wil_meandist)

Wilcoxon signed-rank test for mean surface distance

```
p_value test_decision
------

t1 and t2 0.32227 false
t2 and t3 0.0019531 true
t1 and t3 0.0019531 true
```

fprintf('Wilcoxon signed-rank test for Hausdorff distance\n\n'); disp(T wil hausdorff)

Wilcoxon signed-rank test for Hausdorff distance

	p_value	test_decision
t1 and t2 t2 and t3 t1 and t3	1 0.0019531 0.0019531	false true true

In the cases that involve target 3, null hypothesis is rejected. Which means that the distribution of the target 3 segmentation is not similar to ground truth, target 1 and target 2 segmentations.

3e) The confusion matrix, sensitivity and specificity is shown in Task 2a and 2b

Used Functions

```
function dc=dice(data1,data2)
% calculate dice
tp=sum(sum(sum((data1 & data2))));
fp=sum(sum(sum((~data1 & data2))));
%tn=sum(sum((~data1 & ~data2))));
fn=sum(sum(sum((data1 & ~data2))));
dc=2*tp/(2*tp+fp+fn);
end
function [mn1,mn2,mx1,mx2]=SurfaceDistance(qts,t1s)
% calculates mean surface distance
points=qts.vertices;
dist gt2t1 min=1000*ones(1,length(points));
for i=1:length(t1s.faces)
    dist=Points2TriangleDistance(tls.vertices,tls.faces(i,:),points);
    dist gt2t1 min(dist gt2t1 min>dist)=dist(dist gt2t1 min>dist);
%
      if mod(i,500) == 0
          disp(['forward pass eta: ',num2str(elapsed/i*(length(t1s.faces)-i)/60) ' minutes'])
%
%
      end
end
points=t1s.vertices;
dist t12gt min=1000*ones(1,length(points));
% tic
for i=1:length(gts.faces)
    dist=Points2TriangleDistance(gts.vertices,gts.faces(i,:),points);
%
      elapsed=toc;
    dist t12gt min(dist t12gt min>dist)=dist(dist t12gt min>dist);
%
      if mod(i,500) == 0
          disp(['backward pass eta: ',num2str(elapsed/i*(length(gts.faces)-i)/60) ' minutes'])
%
%
      end
mn1=mean(dist gt2t1 min);
mn2=mean(dist t12gt min);
mx1=max(dist gt2t1 min);
mx2=max(dist t12gt min);
end
function dist=Points2TriangleDistance(vertices, face,points)
% calculates minimum distance of all points from a single triangular surface
q1=vertices(face(1),:)';
q2=vertices(face(2),:)';
q3=vertices(face(3),:)';
v1=q2-q1; v2=q3-q1;
V=[v1 \ v2];
coeff=V\(points'-q1);
dist vect=points'-(q1+V*coeff);
```

```
dist=vecnorm(dist vect);
ind rem=\sim(coeff(1,:)>=0 & coeff(2,:)>=0 & sum(coeff)<=1);
points rem=points(ind rem,:);
v3=q3-q2;
d=v1'*(points rem'-q1)/vecnorm(v1)^2;
d(d>1)=1; d(d<0)=0;
e=v2'*(points rem'-q1)/vecnorm(v2)^2;
e(e>1)=1; e(e<0)=0;
f=v3'*(points rem'-q2)/vecnorm(v3)^2;
f(f>1)=1; f(f<0)=0;
d1=vecnorm(points rem'-(q1+v1*d));
d2=vecnorm(points rem'-(q1+v2*e));
d3=vecnorm(points rem'-(q2+v3*f));
d vect=[d1;d2;d3];
dist(ind rem)=min(d vect);
end
function d=vecnorm(v)
% calculates euclidean norm
d=sqrt(sum(v.^2));
end
function [tp,fp,tn,fn]=class perf(data1,data2)
% calculates tp, fp, tn, fn from ground truth and target
tp=sum(sum(sum((data1 & data2))));
fp=sum(sum(sum((~data1 & data2))));
tn=sum(sum((~data1 & ~data2))));
fn=sum(sum((data1 & ~data2))));
end
function V=VolumeofMesh(0)
% calculates volume of a mesh
V=0;
for i=1:length(0.faces)
    v1=0.vertices(0.faces(i,1),:);
    v2=0.vertices(0.faces(i,2),:);
    v3=0.vertices(0.faces(i,3),:);
    V=V+...
    (-v3(1)*v2(2)*v1(3)...
    +v2(1)*v3(2)*v1(3)...
    +v3(1)*v1(2)*v2(3)...
    -v1(1)*v3(2)*v2(3)...
    -v2(1)*v1(2)*v3(3)...
    +v1(1)*v2(2)*v3(3))/6;
end
V=abs(V);
end
```