Differential Equations

Ovenview:

1) First Order Equation: dy = ay + q(t)

dy = fly) (Non-linear)

linear eg "

Desond Order Egnation: d'y =- Ky -> Linear cyn

* dy = Slope of the curve; dy = Bending of the curve.

Eq. my'' + by' + ky = f(t)

GOOD EQUATION

Linear Constant Coefficients (If m, b = linear const) => Nice fun' f(t) -> Nice fun' y(t)

(3) System 87 n equation, $\frac{dy}{dt} = \frac{1}{\lambda y}$, $\frac{d^2y}{dt^2} = -3y$

* THE CALCULUS WE NEED

1 Busic derivatives. Eg n', sinn, wen, en, lun.

 \mathbb{E} Rules for f+g, $f(n) \cdot g(n)$, $\frac{f(n)}{g(n)}$, f(g(n))

3 Fundamental. Theorem: dn (y/t) dt = y/n)

* Charls attached.

Derivative Rules

Exponential Functions

$$\frac{d}{dx}(e^x) = e^x$$

$$\frac{d}{dx}(a^x) = a^x \ln a$$

$$\frac{d}{dx}(e^{x(x)}) = e^{x(x)}g'(x)$$

$$\frac{d}{dx}(a^{x(x)}) = \ln(a) a^{x(x)} g'(x)$$

Logarithmic Functions

$$\frac{d}{dx}(\ln x) = \frac{1}{x}, x > 0$$

$$\frac{d}{dx}\ln(g(x)) = \frac{g'(x)}{g(x)}$$

$$\frac{d}{dx}(\log_a x) = \frac{1}{x \ln a}, x > 0$$

$$\frac{d}{dx}(\log_a g(x)) = \frac{g'(x)}{g(x) \ln a}$$

Trigonometric Functions

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\frac{d}{dx}(\tan x) = \sec^2 x$$

$$\frac{d}{dx}(\csc x) = -\csc x \cot x$$

$$\frac{d}{dx}(\sec x) = \sec x \tan x$$

$$\frac{d}{dx}(\cot x) = -\csc^2 x$$

Inverse Trigonometric Functions

$$\frac{d}{dx}(\sin^{-1}x) = \frac{1}{\sqrt{1-x^2}}, x \neq \pm 1$$

$$\frac{d}{dx}(\cos^{-1}x) = \frac{-1}{\sqrt{1-x^2}}, x \neq \pm 1$$

$$\frac{d}{dx}(\tan^{-1}x) = \frac{1}{1+x^2}$$

$$\frac{d}{dx}(\cot^{-1}x) = \frac{-1}{1+x^2}$$

$$\frac{d}{dx}(\sec^{-1}x) = \frac{1}{x\sqrt{x^2-1}}, x \neq \pm 1, 0$$

$$\frac{d}{dx}(\csc^{-1}x) = \frac{-1}{x\sqrt{x^2-1}}, x \neq \pm 1, 0$$

Hyperbolic Functions

$$\frac{d}{dx}(\sinh x) = \cosh x$$

$$\frac{d}{dx}(\cosh x) = \sinh x$$

$$\frac{d}{dx}(\tanh x) = \operatorname{sech}^{2} x$$

$$\frac{d}{dx}(\operatorname{sech} x) = -\operatorname{csch} x \operatorname{coth} x$$

$$\frac{d}{dx}(\operatorname{sech} x) = -\operatorname{sech} x \tanh x$$

$$\frac{d}{dx}(\operatorname{coth} x) = -\operatorname{csch} x$$

Inverse Hyperbolic Functions

$$\frac{d}{dx}(\sinh^{-1}x) = \frac{1}{\sqrt{1+x^2}}$$

$$\frac{d}{dx}(\cosh^{-1}x) = \frac{1}{\sqrt{x^2-1}}, x > 1$$

$$\frac{d}{dx}(\tanh^{-1}x) = \frac{1}{1-x^2}, |x| < 1$$

$$\frac{d}{dx}(\operatorname{csch}^{-1}x) = \frac{-1}{|x|\sqrt{1-x^2}}, x \neq 0$$

$$\frac{d}{dx}(\operatorname{sech}^{-1}x) = \frac{-1}{x\sqrt{1-x^2}}, 0 < x < 1$$

$$\frac{d}{dx}(\coth^{-1}x) = \frac{1}{1-x^2}, |x| > 1$$

Basic Derivatives Rules

Constant Rule: $\frac{d}{dx}(c) = 0$

Constant Multiple Rule: $\frac{d}{dx}[cf(x)] = cf'(x)$

Power Rule: $\frac{d}{dx}(x^n) = nx^{n-1}$

Sum Rule: $\frac{d}{dx}[f(x)+g(x)] = f'(x)+g'(x)$

Difference Rule: $\frac{d}{dx}[f(x) - g(x)] = f'(x) - g'(x)$

Product Rule: $\frac{d}{dx}[f(x)g(x)] = f(x)g'(x) + g(x)f'(x)$

Quotient Rule: $\frac{d}{dx} \left[\frac{f(x)}{g(x)} \right] = \frac{g(x) f'(x) - f(x)g'(x)}{[g(x)]^2}$

Chain Rule: $\frac{d}{dx} f(g(x)) = f'(g(x))g'(x)$

9 $y(t) = \int e^{t-s}q/s ds$ Solves $\frac{dy}{dt} = y + q(t)$ $\Rightarrow y(t) = e^{t} \int e^{-s}q/s ds$ $\frac{dy}{dt} = e^{t} \int e^{-s}q/s ds + e^{t} \cdot [e^{-t}q/t]$ = y + q/t

G) Tangent Line to the graph
$$f(t+\Delta t) \approx f(t) + \Delta t \frac{df(t)}{dt} - 0$$

$$\therefore \Delta f \approx df$$

$$\Delta t \approx df$$
aughor's Series

Taylor's Series \times $f(t+\Delta t) = f(t) + \Delta t \frac{df(t)}{dt} + \frac{1}{2!}(\Delta t)^{2} \frac{d^{2}f}{dt^{2}} \dots$

As we go towards higher derivative: we can recreate the funt.

Parabola.

> Tangent (lin)

t=At

 $+ \frac{1}{n!} (\Delta t)^n \frac{d^n f}{dt^n} + \dots = in eq^n (2) x f$

RESPONSE TO EXPONENTIAL INPUT.

$$\frac{dy}{dt} = ay + e^{st} \quad y(t) = "Exponential Response"$$

$$y = y(0) \text{ at } t = 0.$$

In this case the particular solution y= Yest —

$$\frac{d(Ye^{st})}{dt} = aYe^{st} + e^{st}$$

$$\Rightarrow (S-a) Y = 1$$

$$\Rightarrow Y = \frac{1}{s-a}.$$

$$\Rightarrow \text{from 0} \left(\text{Particular Sol}^{*} \right)$$

$$\text{y(t)} = \frac{e \, s \, t}{s-a} + \text{Null Sol}^{*}.$$

Null soly i.e glt) =
$$e^{st} = 0$$

$$\frac{dy}{dt} = ay$$

$$soly(t) = Ce^{at}$$

$$y(t) = \frac{e^{st}}{s-a} + Ce^{at} - 0$$

$$y(t) = \frac{1}{s-a} + C$$

$$C = y(0) - \frac{1}{(s-a)} - 3$$

$$\therefore \text{ From } 0 \neq 3 \text{ we get,}$$

$$y(t) = \frac{e^{st}}{(s-a)} + [y(0) - \frac{1}{(s-a)}] e^{at}$$

$$\Rightarrow \frac{e^{st}}{(s-a)} = \frac{1}{s} = \frac{1$$

$$y(t) = \frac{e^{st} - e^{at}}{(s-a)} + y(o) e^{at} = y_{vp} + y_{N}$$

another, particular SST h (G.S calls thin a very particular SSTUCION)

$$\frac{\pm L' \text{Mospital Rule (%)}}{\frac{d(s-a)}{ds}} = \frac{d(e^{st}-e^{at})}{\frac{d(s-a)}{ds}} = \frac{te^{st}-0}{1} = te^{at}$$

RESPONSE TO OSCILLATING INPUT

$$\frac{dy}{dt} = ay + coswt, \quad y = y(0) \quad at t = 0$$

$$\Rightarrow$$
 - $\alpha M + \omega N = 1$ $q - \omega M = \alpha N - 0$

From 1 40 we get,

$$M = -a \qquad G N = \frac{\omega}{\omega^2 + a^2}.$$

Here
$$M = G \cos \alpha$$
, $N = G \sin \alpha - 4$

$$\therefore M^{2} + N^{2} = G^{2} \left(\cos^{2} \alpha + \sin^{2} \alpha \right)^{2}$$

$$G = \sqrt{M^{2} + N^{2}}$$

Now, To find a from egh
$$G$$
 $M = \frac{G\cos\alpha}{G\sin\alpha}$

$$\Rightarrow$$
 $tam \alpha = \frac{N}{M}$

SOLUTION FOR ANY INPUT.

SOLUTION FOR ANY INPUT.

$$\frac{dy}{dt} = ay + q(t) . Start at y(0)$$

= cosut or sin cut

= Step fim" } To be covered. = Delta fim"

Checkif he formula is correct;
$$o$$

Now, $y_p(t) = e^{at} \int e^{-as} y(s) ds$

$$\frac{dy_{\beta}(t)}{dt} = \int_{e^{-as}}^{s=t} e^{-as} ds \cdot e^{at} \cdot a - e^{at} \cdot e^{-at} q(t)$$

of By Fundamental Theoram of Calculary

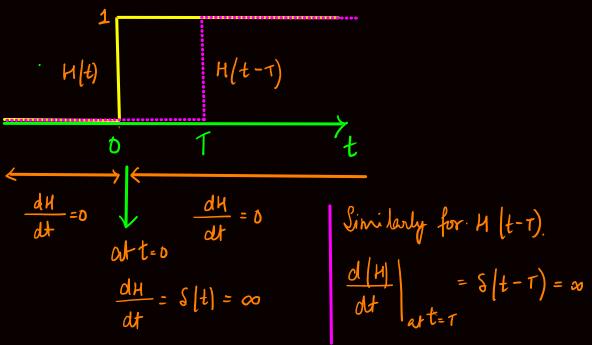
$$= \frac{dy_b}{dt} = ay + q(t)$$

STEP FUNCTION & DELTA FUNCTION

O Step Function (H(t))

Step Fun'

$$f(t) = 0 \quad t < 0$$
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Delta Function
$$\{S\{t\}\}\$$

$$S\{t-T\}$$

$$= 1-0 \quad t=-\infty$$

$$S\{t\} dt = 1$$

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*
$$\int_{-\infty}^{\infty} \delta(t)e^{t}dt = e^{\circ} = 1$$
 * $\int_{-\infty}^{\infty} \delta(t-1)e^{t}dt = e^{T}$

9.
$$\frac{dy}{dt} = ay + \delta(t-1)$$
; $y(0) = 0$

$$y(t) = \int 0 \quad \text{who } t = T$$

$$\begin{cases} e^{a(t-T)} & t \neq T \end{cases}$$

RESPONSE TO COMPLEX EXPONENTIAL

$$\frac{d(ye^{iwt})}{dt} = \alpha ye^{iwt} + e^{iwt}$$

$$\Rightarrow iw ye^{iwt} = \alpha ye^{iwt} + e^{iwt}$$

$$\Rightarrow (iw - \alpha) y = 1$$

$$\Rightarrow y = \frac{1}{(iw - \alpha)}$$

$$i\omega - a = \int a^{2} + \omega^{2} e^{ixt}$$

$$\therefore \psi(t) = \frac{1}{i\omega - a} e^{i\omega t} = \frac{1}{\int a^{2} + \omega^{2}} e^{-ixt} e^{i\omega t}$$

$$= \frac{1}{\int a^{2} + \omega^{2}} e^{i(\omega t - x)}$$

$$= \frac{1}{\int a^{2} + \omega^{2}} cos(\omega t - x) = 6 cos(\omega t - x)$$

$$\int \partial u e^{-ixt} e^{-ixt}$$
Real Part: $\psi(t) = \frac{1}{\int a^{2} + \omega^{2}} cos(\omega t - x) = 6 cos(\omega t - x)$

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INTEGRATING FACTOR FOR A CONSTANT RATE

 \Rightarrow M(t)y(t) = y(0) + $\int M(s)g(s)ds$

$$\frac{dy}{dt} = a(t)y + g(t) . \text{ Solve by integrating factor M}$$

$$\frac{dM}{dt} = -a(t)M \qquad a = const \longrightarrow M = e^{-at}$$

$$a = varying \longrightarrow M = e^{-\int_{a}^{t} a(t)dt}$$

$$\frac{d(M-y)}{dt} = \frac{dy}{dt}M + y\frac{dM}{dt} = \frac{dy}{dt}M - a(t)My = M\left[\frac{dy}{dt} - a(t)y\right]$$

$$= Mg$$
Integraling both sides we get
$$M(t)y(t) - M(0)y(0) = \int_{a}^{t} M(s)g(s)ds$$

$$= \frac{t}{y(t)} = e^{sa(t)}dT$$

$$= \frac{t}{t} = e^{sa(t)}dT$$

$$= \frac{t}{t} = e^{sa(t)}dS$$

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9
$$\frac{dy}{dt} = 2ty + qlt$$
) Solve by integraling factor $I(t)$

Solve by integraling factor $I(t)$

Solve by integraling factor $I(t)$

Solve by integraling factor $I(t)$
 $I(t) = e^{-t^2}$
 $\frac{dI}{dt} = -2t I(t) \quad f(I(0)) = e^{0} = 1$
 $\frac{d(I(y))}{dt} = I(\frac{dy}{dt}) + \frac{dI}{dt} = I(\frac{dy}{dt}) + -2tI(t).y$
 $\frac{d(I(y))}{dt} = I(q(t))$

$$\Rightarrow I(t) \cdot y(t) - y(0) = \int_{0}^{t} e^{-s^{2}} y(s) ds$$
 $\begin{cases} I(t) = e^{-t^{2}} \end{cases}$

$$\frac{1}{7}$$
, $y(t) = y(0).e^{t^2}.+ \int_{0}^{t} e^{t^2-s^2}y(s)ds$

General Rule for choosing Integrating factor is:

$$I(t) = e^{-\int a(t) dT} \{a(T) = const \text{ or Variable}\}$$