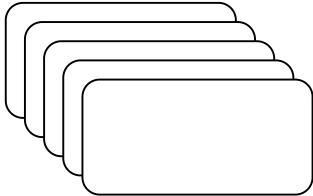


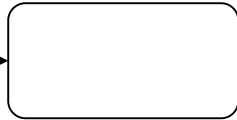
$t = 0$



Frame 0, 1, 2, 3, 4



L-VLN



Predicted Frame 0