

# CCCN221 – Computer Architecture

## Lab 8 – Floating points in MIPS

In this lab, we will go through Floating-Point Number Representation (IEEE 754 Standard), have the basic understanding of MIPS Floating-Point Unit. Will write down programs using the MIPS Floating-Point Instructions that will have the input and output as the floating point numbers.

### Floating-Point Number Representation

Floating-point numbers have been defined as follows

<b>S</b>	<b>E = Exponent</b>	<b>F = Fraction</b>
----------	---------------------	---------------------

The Sign bit **S** is zero (positive) or one (negative).

For single-precision the Exponent field **E** has 8 bits and for double-precision, 11 bits. The exponent field is biased. The Bias is 127 for single-precision and 1023 for double-precision.

The Fraction field **F** is 23 bits for single-precision and 52 bits for double-precision. Floating-point numbers are normalized (except when **E** is zero). There is an implicit **1.** (not stored) before the fraction **F**. Therefore, the value of a normalized floating-point number is:

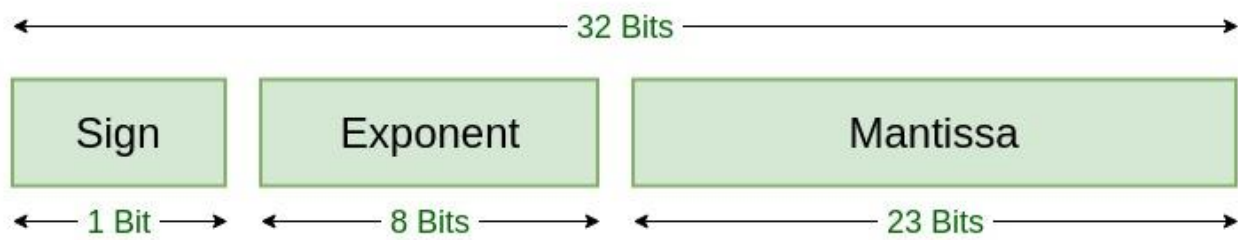
$$\text{Value} = \square (1.F)_2 \times 2^{E - \text{Bias}}$$

The QTSPIM simulator has a floating-point representation tool that illustrates single-precision floating-point numbers. The figure 1 shows the floating point representation.

Now use the tool to check the binary format and the decimal value of floating-point numbers.

For example, the decimal value of: **0 10000001 101101000000000000000000** is **6.75**.

Similarly, the 32-bit representation of: **-2.7531** is **1 10000000 01100000011001011001010**.



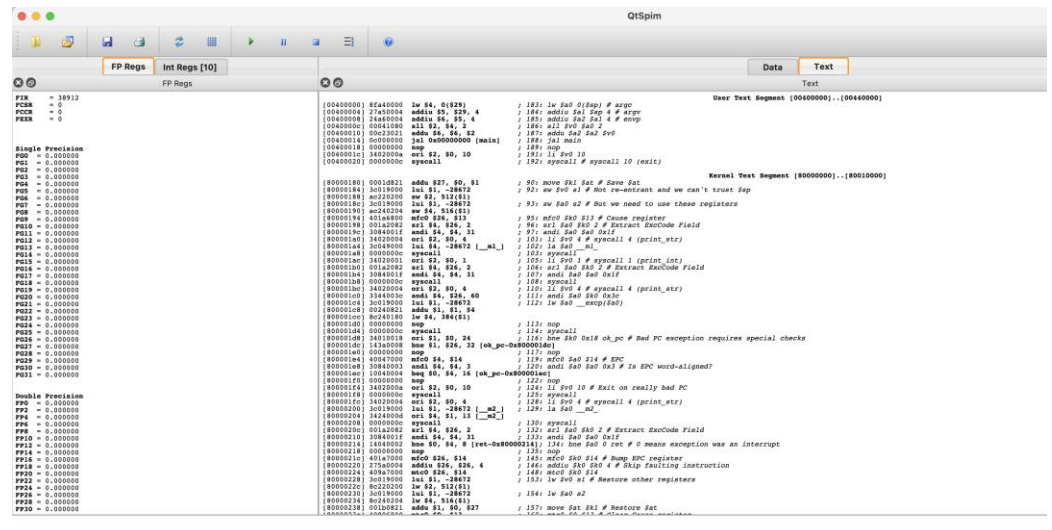
## Single Precision IEEE 754 Floating-Point Standard

Figure 9.1: Floating-Point Representation

### MIPS Floating-Point Registers

The floating-point unit (called coprocessor 1) has 32 floating-point registers. These registers are numbered as **\$f0**, **\$f1**, ..., **\$f31**. Each register is 32 bits wide. Thus, each register can hold one single-precision floating-point number. How can we use these registers to store 64-bit double-precision floating-point numbers? The answer is that the 32 single-precision registers are grouped into 16 double-precision registers. The double-precision number is stored in an even-odd pair of registers, but we only refer to the even-numbered register. For example, when we store a double-precision number in **\$f0**, it is actually stored in registers **\$f0** and **\$f1**.

In addition, there are 8 condition flags, numbered from 0 to 7. These condition flags are used by floating-point compare and branch instructions. These are shown in Figure 9.2.



## MIPS Floating-Point Instructions

Instruction	Example	Meaning
lwc1    or   l.s	lwc1    \$f1,0(\$sp)	Load a word from memory to a single-precision floating-point register: \$f1 = MEM[\$sp]
ldc1    or   l.d	ldc1    \$f2,8(\$t1)	Load a double word from memory to a double-precision register: \$f2 = MEM[\$t1+8]

Instruction	Example	Meaning
swc1 or s.s	swc1 \$f5,4(\$t2)	Store a single-precision floating-point register in memory: $\text{MEM}[\$t2+4] = \$f5$
sdcl or s.d	sdcl \$f6,16(\$t3)	Store a double-precision floating-point register in memory: $\text{MEM}[\$t3+16] = \$f6$

The floating-point arithmetic instructions are listed next. The **.s** extension is used for single-precision arithmetic instructions, while the **.d** is used for double-precision instructions.

Instruction	Example	Meaning
add.s	add.s \$f0,\$f2,\$f4	$\$f0 = \$f2 + \$f4$ (single-precision)
add.d	add.d \$f0,\$f2,\$f4	$\$f0 = \$f2 + \$f4$ (double-precision)
sub.s	sub.s \$f0,\$f2,\$f4	$\$f0 = \$f2 - \$f4$ (single-precision)
sub.d	sub.d \$f0,\$f2,\$f4	$\$f0 = \$f2 - \$f4$ (double-precision)
mul.s	mul.s \$f0,\$f2,\$f4	$\$f0 = \$f2 \times \$f4$ (single-precision)
mul.d	mul.d \$f0,\$f2,\$f4	$\$f0 = \$f2 \times \$f4$ (double-precision)
div.s	div.s \$f0,\$f2,\$f4	$\$f0 = \$f2 / \$f4$ (single-precision)
div.d	div.d \$f0,\$f2,\$f4	$\$f0 = \$f2 / \$f4$ (double-precision)
sqrt.s	sqrt.s \$f0, \$f2	Square root (single-precision)
sqrt.d	sqrt.d \$f0, \$f2	Square root (double-precision)
abs.s	abs.s \$f0, \$f2	Absolute value (single-precision)
abs.d	abs.d \$f0, \$f2	Absolute value (double-precision)
neg.s	neg.s \$f0, \$f2	Negative value (single-precision)
neg.d	neg.d \$f0, \$f2	Negative value (double-precision)

The data movement instructions move data between general-purpose and floating-point registers, or between floating-point registers.

Instruction	Example	Meaning
mfc1	mfc1 \$t0, \$f2	Move data from a floating-point register to a general-purpose register.
mtc1	mtc1 \$t0, \$f2	Move data from a general-purpose register to a floating-point register.
mov.s	mov.s \$f0, \$f1	Move single-precision data between two floating-point registers.
mov.d	mov.d \$f0, \$f2	Move double-precision data between two floating-point registers (move even-odd pair of registers).

The convert instructions convert the format of data in floating-point registers. Three data formats are supported: **.s** = single-precision float, **.d** = double-precision, and **.w** = integer word.

Instruction	Example	Meaning
cvt.s.w	cvt.s.w \$f0,\$f2	<b>\$f0</b> = convert <b>\$f2</b> from word to single-precision
cvt.s.d	cvt.s.d \$f0,\$f2	<b>\$f0</b> = convert <b>\$f2</b> from double to single-precision
cvt.d.w	cvt.d.w \$f0,\$f2	<b>\$f0</b> = convert <b>\$f2</b> from word to double-precision
cvt.d.s	cvt.d.s \$f0,\$f2	<b>\$f0</b> = convert <b>\$f2</b> from single to double-precision
cvt.w.s	cvt.w.s \$f0,\$f2	<b>\$f0</b> = convert <b>\$f2</b> from single-precision to word
cvt.w.d	cvt.w.d \$f0,\$f2	<b>\$f0</b> = convert <b>\$f2</b> from double-precision to word
ceil.w.s	ceil.w.s \$f0,\$f2	<b>\$f0</b> = Integer ceiling of single-precision float in <b>\$f2</b>
ceil.w.d	ceil.w.d \$f0,\$f2	<b>\$f0</b> = Integer ceiling of double-precision float in <b>\$f2</b>
floor.w.s	floor.w.s \$f0,\$f2	<b>\$f0</b> = Integer floor of single-precision float in <b>\$f2</b>
floor.w.d	floor.w.d \$f0,\$f2	<b>\$f0</b> = Integer floor of double-precision float in <b>\$f2</b>
trunc.w.s	trunc.w.s \$f0,\$f2	<b>\$f0</b> = Truncate single-precision float in <b>\$f2</b>
trunc.w.d	trunc.w.d \$f0,\$f2	<b>\$f0</b> = Truncate double-precision float in <b>\$f2</b>

The floating-point compare instructions compare floating-point registers for equality, less than, and less than or equal. The FP compare instructions set the condition flags **0** to **7** to true (1) or false(0).

Instruction	Example	Meaning
c.eq.s	c.eq.s \$f2,\$f3	if ( <b>\$f2 == \$f3</b> ) set flag <b>0</b> to true else false
c.eq.d	c.eq.s 3,\$f4,\$f6	Compare equal double-precision. Result in flag <b>3</b>
c.lt.s	c.eq.s 4,\$f5,\$f8	if ( <b>\$f5 &lt; \$f8</b> ) set flag <b>4</b> to true else false
c.lt.d	c.lt.d 7,\$f4,\$f6	Compare less-than double. Result in flag <b>7</b>
c.le.s	c.le.s \$f10,\$f11	if ( <b>\$f10 &lt;= \$f11</b> ) set flag <b>0</b> to true else false
c.le.d	c.le.d \$f14,\$f16	Compare less or equal double. Result in flag <b>0</b>

The floating-point branch instructions (**bc1t** and **bc1f**) branch to the target address based on the value of the specified condition flag (true or false).

Instruction	Example	Meaning
bc1t	bc1t label	Branch to label if condition flag <b>0</b> is true
bc1t	bc1t 1, label	Branch to label if condition flag <b>1</b> is true
bc1f	bc1f label	Branch to label if condition flag <b>0</b> is false
bc1f	bc1f 4, label	Branch to label if condition flag <b>4</b> is false

## System Call Services for Floating-Point Numbers

The MARS tool provides the following **Syscall** service numbers (passed in **\$v0**) to print and read single-precision and double-precision floating-point numbers:

Service	\$v0	Arguments	Result
Print Float	<b>2</b>	<b>\$f12</b> = float to print	
Print Double	<b>3</b>	<b>\$f12</b> = double to print	
Read Float	<b>6</b>		Float is returned in <b>\$f0</b>
Read Double	<b>7</b>		Double is returned in <b>\$f0</b>

## MIPS Floating-Point Register Usage Convention

Compilers follow the MIPS register usage convention when translating functions and procedures into MIPS assembly-language code. The following table shows the MIPS software convention for floating-point registers. Not following the MIPS software usage convention can result in serious bugs when passing parameters, getting results, or using registers across function calls.

Registers	Usage
\$f0 - \$f3	Floating-point procedure results
\$f4 - \$f11	Temporary floating-point registers, NOT preserved across procedure calls
\$f12 - \$f15	Floating-point parameters, NOT preserved across procedure calls. Additional floating-point parameters should be pushed on the stack.
\$f16 - \$f19	More temporary registers, NOT preserved across procedure calls.
\$f20 - \$f31	Saved floating-point registers. Should be preserved across procedure calls.

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## Lab Tasks

### Task 1

1. Convert by hand the number **-123456789** into its 32-bit single-precision binary representation, and Show your work for a full mark.

First. We start with the positive version of the number  $|-123456789| = 123456789$

Second. We divide the number repeatedly by 2

division = quotient + remainder;

$$123\,456\,789 \div 2 = 61\,728\,394 + 1;$$

$$61\,728\,394 \div 2 = 30\,864\,197 + 0;$$

$$30\,864\,197 \div 2 = 15\,432\,098 + 1;$$

$$15\,432\,098 \div 2 = 7\,716\,049 + 0;$$

$$7\,716\,049 \div 2 = 3\,858\,024 + 1;$$

$$3\,858\,024 \div 2 = 1\,929\,012 + 0;$$

$$1\,929\,012 \div 2 = 964\,506 + 0;$$

$$964\,506 \div 2 = 482\,253 + 0;$$

$$482\,253 \div 2 = 241\,126 + 1;$$

$$241\,126 \div 2 = 120\,563 + 0;$$

$$120\,563 \div 2 = 60\,281 + 1;$$

$$60\,281 \div 2 = 30\,140 + 1;$$

$$30\,140 \div 2 = 15\,070 + 0;$$

$15\,070 \div 2 = 7\,535 + 0;$   
 $7\,535 \div 2 = 3\,767 + 1;$   
 $3\,767 \div 2 = 1\,883 + 1;$   
 $1\,883 \div 2 = 941 + 1;$   
 $941 \div 2 = 470 + 1;$   
 $470 \div 2 = 235 + 0;$   
 $235 \div 2 = 117 + 1;$   
 $117 \div 2 = 58 + 1;$   
 $58 \div 2 = 29 + 0;$   
 $29 \div 2 = 14 + 1;$   
 $14 \div 2 = 7 + 0;$   
 $7 \div 2 = 3 + 1;$   
 $3 \div 2 = 1 + 1;$   
 $1 \div 2 = 0 + 1;$

Then we Construct the base 2 representation of the positive number.

123 456 789 (decimal) = 111 0101 1011 1100 1101 0001 0101 (binary)

After that. We Normalize the binary representation of the number.

111 0101 1011 1100 1101 0001 0101 (binary) =  $1.1101\,0110\,1111\,0011\,0100\,0101\,01$  (binary)  $\times 2^{26}$

Now. We adjust the exponent. Exponent (unadjusted) = 26

Exponent (adjusted) = Exponent (unadjusted) +  $2(8-1) - 1 = 26 + 2(8-1) - 1 = (26 + 127)(10)$   
 = 153(10)

Then we use the same technique by dividing the number repeatedly by 2

division = quotient + remainder;

$153 \div 2 = 76 + 1;$   
 $76 \div 2 = 38 + 0;$   
 $38 \div 2 = 19 + 0;$   
 $19 \div 2 = 9 + 1;$   
 $9 \div 2 = 4 + 1;$   
 $4 \div 2 = 2 + 0;$   
 $2 \div 2 = 1 + 0;$   
 $1 \div 2 = 0 + 1;$

Exponent (adjusted) = 153 (decimal) = 1001 1001 (binary)

After that. We normalized the mantissa by:

- A- Remove the leading bit
- B- Adjust its length to 23 by removing the excess bits

1.1101 0110 1111 0011 0100 0101 01 (binary) = 110 1011 0111 1001 1010 0010

Finally. The three elements that make up 32 bit single precision IEEE 754 binary floating point are  
 Sign (1 bit) = 1



Exponent (8 bits) = 1001 1001 (binary)  
Mantissa (23 bits) = 110 1011 0111 1001 1010 0010  
= 1 10011001 11010110111100110100010

## Task 2

2. Convert by hand the floating-point number **1 10010100 100110000011000000000000** (shown in binary) into its corresponding decimal value. Show your work for a full mark.

Sign bit: 1 (negative)

Exponent: 10010100 (binary) = 148 (decimal)

Mantissa: 100110000011000000000000 (binary)

First, we subtract 127 from the exponent to get the true exponent:  $148 - 127 = 21$

Second, we convert the mantissa to decimal, by multiplying by  $2^{\text{N of number}}$ :

$$1 \times 2^{-1} + 0 \times 2^{-2} + 0 \times 2^{-3} + 1 \times 2^{-4} + 1 \times 2^{-5} + 0 \times 2^{-6} + 0 \times 2^{-7} + 0 \times 2^{-8} + 0 \times 2^{-9} + 0 \times 2^{-10} + 1 \times 2^{-11} + 1 \times 2^{-12} + 0 \times 2^{-13} + 0 \times 2^{-14} + 0 \times 2^{-15} + 0 \times 2^{-16} + 0 \times 2^{-17} + 0 \times 2^{-18} + 0 \times 2^{-19} + 0 \times 2^{-20} + 0 \times 2^{-21} + 0 \times 2^{-22} + 0 \times 2^{-23} = 0.594482421875 \text{ (decimal)}$$

Then we will add 1 to the mantissa:  $0.594482421875 \text{ (decimal)} + 1 = 1.594482421875 \text{ (decimal)}$

Finally, the floating-point value is then equal to  $-1 \times 2^{21} \times 1.594482421875 = -3343872$

## Task 3

3. Trace the following program by hand to determine the values of registers **\$f0** thru **\$f9**. Notice that **array1** and **array2** have the same elements, but in a different order. Comment on the sums of **array1** and **array2** elements computed in registers **\$f4** and **\$f9**, respectively. Now use the QTSPIM tool to trace the execution of the program and verify your results. What conclusion can be made from this exercise?

```
.data
array1: .float 5.6e+20, -5.6e+20, 1.2
array2: .float 1.2, 5.6e+20, -5.6e+20
.text
.globl main

main:
```

```

la      $t0, array1
lwc1    $f0, 0($t0)
lwc1    $f1, 4($t0)
lwc1    $f2, 8($t0)
add.s   $f3, $f0, $f1
add.s   $f4, $f2, $f3
la      $t1, array2
lwc1    $f5, 0($t1)
lwc1    $f6, 4($t1)
lwc1    $f7, 8($t1)
add.s   $f8, $f5, $f6
add.s   $f9, $f7, $f8

```

```

li $v0, 10      # To terminate the program
syscall

```

```

.end main

```

```

$f0 = 5.6e+20
$f1 = -5.6e+20
$f2 = 1.2
$f3 = $f0 + $f1 = 0
$f4 = $f2 + $f3 = 1.2
$f5 = 1.2
$f6 = 5.6e+20
$f7 = -5.6e+20
$f8 = $f5 + $f6 = 5.6e+20
$f9 = $f7 + $f8 = 0

```

The sum of elements of "array1" is 1.2 and the sum of elements of "array2" is 0. This shows that the order of elements in a floating-point addition operation can affect the result due to the limited precision of floating-point numbers.

## Task 4

- Write an interactive program that inputs an integer **sum** and an integer **count**, computes, and displays the **average** = **(float)** **sum** / **(float)** **count** as a single-precision floating-point number. Hint: use the proper convert instruction to convert **sum** and **count** from integer word into single-precision float.

### PICTURES OF THE CODE:

The screenshot shows the MARS MIPS simulator interface. The main window displays the assembly code for LAB08.asm, which implements the program described in Task 4. The code includes prompts for 'sum' and 'count', reads these values, converts them to floats, computes the average, and prints the result.

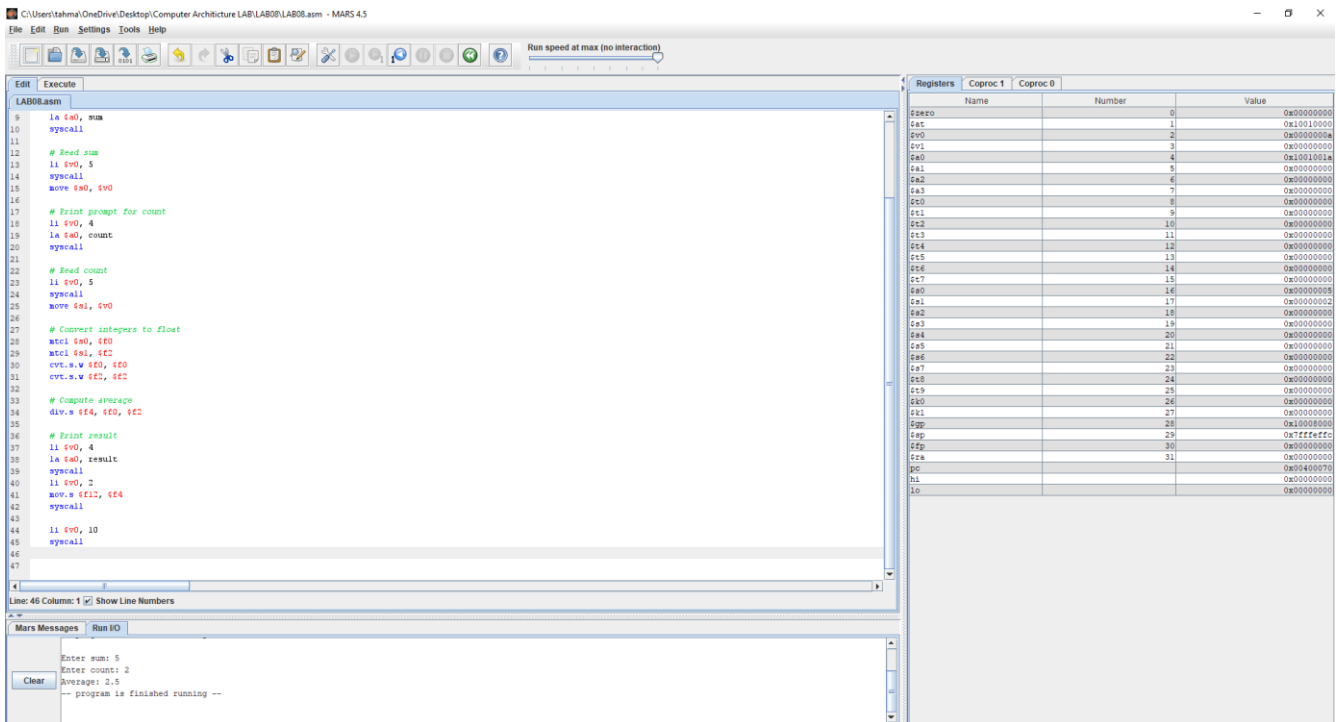
```
1 .data
2 sum: .asciiz "Enter sum: "
3 count: .asciiz "Enter count: "
4 result: .asciiz "Average: "
5
6 .text
7 # Print prompt for sum
8 li $v0, 4
9 la $a0, sum
10 syscall
11
12 # Read sum
13 li $v0, 5
14 syscall
15 move $t0, $v0
16
17 # Print prompt for count
18 li $v0, 4
19 la $a0, count
20 syscall
21
22 # Read count
23 li $v0, 5
24 syscall
25 move $t1, $v0
26
27 # Convert integers to float
28 mtcl $t0, $t0
29 mtcl $t1, $t1
30 cvt.s.w $t0, $t0
31 cvt.s.w $t1, $t1
32
33 # Compute average
34 div.s $t2, $t0, $t1
35
36 # Print result
37 li $v0, 4
38 la $a0, result
39 syscall
40 li $v0, 2
```

The right panel shows the registers, with \$t0, \$t1, and \$t2 containing the sum, count, and average respectively. The bottom panel shows the program's output, which matches the expected result of 1.666666.

Registers	Coproc 1	Coproc 0
Name	Number	Value
\$zero	0	0x00000000
\$at	1	0x00000000
\$v0	2	0x00000000
\$v1	3	0x00000000
\$a0	4	0x00000000
\$a1	5	0x00000000
\$a2	6	0x00000000
\$a3	7	0x00000000
\$t0	8	0x00000000
\$t1	9	0x00000000
\$t2	10	0x00000000
\$t3	11	0x00000000
\$t4	12	0x00000000
\$t5	13	0x00000000
\$t6	14	0x00000000
\$t7	15	0x00000000
\$s0	16	0x00000000
\$s1	17	0x00000000
\$s2	18	0x00000000
\$s3	19	0x00000000
\$s4	20	0x00000000
\$s5	21	0x00000000
\$s6	22	0x00000000
\$s7	23	0x00000000
\$t8	24	0x00000000
\$t9	25	0x00000000
\$d0	26	0x00000000
\$d1	27	0x00000000
\$fp	28	0x10000000
\$sp	29	0xffffffff
\$gp	30	0x00000000
\$ra	31	0x00000000
\$pc		0x00400000
\$hi		0x00000000
\$lo		0x00000000

Mars Messages Run XO

```
Enter sum: 10
Enter count: 6
Average: 1.666666
-- program is finished running --
```



CODE:

.data

sum: .asciiz "Enter sum: "

count: .asciiz "Enter count: "

result: .asciiz "Average: "

.text

# Print prompt for sum

li \$v0, 4

la \$a0, sum

syscall

# Read sum

li \$v0, 5

syscall

move \$s0, \$v0

# Print prompt for count

li \$v0, 4

la \$a0, count

syscall

# Read count

li \$v0, 5

syscall

move \$s1, \$v0

```
# Convert integers to float
```

```
mtc1 $s0, $f0
```

```
mtc1 $s1, $f2
```

```
cvt.s.w $f0, $f0
```

```
cvt.s.w $f2, $f2
```

```
# Compute average
```

```
div.s $f4, $f0, $f2
```

```
# Print result
```

```
li $v0, 4
```

```
la $a0, result
```

```
syscall
```

```
li $v0, 2
```

```
mov.s $f12, $f4
```

```
syscall
```

```
li $v0, 10
```

```
syscall
```

## Task 5

5. Write an interactive program that inputs the coefficient of a quadratic equation, computes, and displays the roots of the quadratic equation. All input, computation, and output should be done using double-precision floating-point instructions and registers. The program should handle the case of complex roots and displays the results properly.

$$x = -b \pm \frac{\sqrt{b^2 - 4ac}}{2a}$$

The screenshot displays the Visual Studio Code editor with the assembly file LAB08\_2.asm open. The code is written in x86-64 assembly and implements a program to solve a quadratic equation. It prompts the user for coefficients a, b, and c, calculates the discriminant, and then uses the `sqrt` instruction to find the square root of the discriminant. The roots are calculated using the quadratic formula and displayed to the user.

The assembly code is as follows:

```

1  .data
2  promptA: .ascii "Enter coefficient a: "
3  promptB: .ascii "Enter coefficient b: "
4  promptC: .ascii "Enter coefficient c: "
5  result: .ascii "\nThe roots are: "
6  msg: .ascii "Info: "
7  complexRoot: .ascii "Complex Roots."
8  four: .double 4.0
9  two: .double 2.0
10 zero: .double 0.0
11 negOne: .double -1.0
12 open: .ascii "("
13 close: .ascii ")"
14 imaginaryPart: .ascii "i "
15 plus: .ascii " + "
16 minus: .ascii " - "
17 sqrt: .ascii " \sqrt{"
18 dividi: .ascii " / "
19
20
21 .text
22 # Print prompt message to enter coefficient a
23 li %v0, 4
24 la %a0, promptA
25 syscall
26
27 # Read coefficient a
28 li %v0, 7
29 syscall
30 mov.d %f20, %f0
31
32
33 # Print prompt message to enter coefficient b
34 li %v0, 4
35 la %a0, promptB
36 syscall
37
38 # Read coefficient b
39 li %v0, 7
40 syscall
41 mov.d %f21, %f0
42
43 # Print prompt message to enter coefficient c
44 li %v0, 4
45 la %a0, promptC
46 syscall
47
48 # Read coefficient c
49 li %v0, 7
50 syscall
51 mov.d %f22, %f0
52
53 # Calculate discriminant
54 mul.d %f23, %f21, %f21
55 mul.d %f23, %f23, %f22
56 neg.d %f23, %f23
57 sqrt.d %f23, %f23
58
59 # Calculate roots
60 div.d %f24, %f23, %f20
61 div.d %f25, %f23, %f20
62
63 # Print result
64 li %v0, 1
65 la %a0, result
66 syscall
67
68 # Print imaginary part
69 li %v0, 1
70 la %a0, imaginaryPart
71 syscall
72
73 # Print plus/minus sign
74 li %v0, 1
75 la %a0, plus
76 syscall
77
78 # Print root 1
79 li %v0, 1
80 la %a0, %f24
81 syscall
82
83 # Print root 2
84 li %v0, 1
85 la %a0, %f25
86 syscall
87
88 # Print complex root message
89 li %v0, 1
90 la %a0, complexRoot
91 syscall
92
93 # Print info message
94 li %v0, 1
95 la %a0, msg
96 syscall
97
98 # Print program finished message
99 li %v0, 1
100 la %a0, "Program finished running\n"
101 syscall

```

The assembly output window shows the execution of the program, including the prompts for coefficients and the calculated roots.

The registers window shows the state of the registers after the program has finished running.

The screenshot shows the x86-64 assembly editor and debugger interface. The assembly code defines a program that calculates the roots of a quadratic equation. The registers window shows the state of various registers, including EAX, ECX, EDI, and ESI. The console window displays the program's output, including the coefficients and the calculated roots.

**Assembly Code:**

```

LAB00_2.asm
34  li %v0, 4
35  la %a0, promptl
36  syscall
37
38  # Read coefficient b
39  li %v0, 7
40  syscall
41  mov.d %f14, %f0
42
43
44  # Print prompt message to enter coefficient c
45  li %v0, 4
46  la %a0, promptc
47  syscall
48
49  # Read coefficient c
50  li %v0, 7
51  syscall
52  mov.d %f16, %f0
53
54  # Calculate the discriminant: fff = f14^2 - 4 * f12 * f16
55  mul.d %f0, %f14, %f14 # fff = f14 * f14
56  ldbl %f10, four # load four into f10
57  mul.d %f10, %f10, %f20 # 4 * f10
58  mul.d %f10, %f10, %f10 # f10 = f10 * f16
59  sub.d %f0, %f0, %f10 # fff = fff - f10
60
61  # Check if the roots are complex
62  ldbl %f10, zero
63  e.lt.d %f0, %f10
64  bc1t complex
65
66  # Compute the roots
67  sqtt.d %f0, %f0 # square root fff and store it in fff
68  ldbl %f10, two
69  mul.d %f10, %f10, %f20

```

**Registers:**

Register	Value
\$zero	0x00000000
\$at	0x10000000
\$v0	0x00000004
\$v1	0x00000007
\$a0	0x10010094
\$a1	0x00000000
\$a2	0x00000000
\$a3	0x00000000
\$a4	0x00000000
\$t0	0x00000000
\$t1	0x00000000
\$t2	0x00000000
\$t3	0x00000000
\$t4	0x00000000
\$t5	0x00000000
\$t6	0x00000000
\$t7	0x00000000
\$t8	0x00000000
\$t9	0x00000000
\$s0	0x00000000
\$s1	0x00000000
\$s2	0x00000000
\$s3	0x00000000
\$s4	0x00000000
\$s5	0x00000000
\$s6	0x00000000
\$s7	0x00000000
\$s8	0x00000000
\$s9	0x00000000
\$t0	0x00000000
\$t1	0x00000000
\$t2	0x00000000
\$t3	0x00000000
\$t4	0x00000000
\$t5	0x00000000
\$t6	0x00000000
\$t7	0x00000000
\$t8	0x00000000
\$t9	0x00000000
\$s0	0x00000000
\$s1	0x00000000
\$s2	0x00000000
\$s3	0x00000000
\$s4	0x00000000
\$s5	0x00000000
\$s6	0x00000000
\$s7	0x00000000
\$s8	0x00000000
\$s9	0x00000000
\$t0	0x00000000
\$t1	0x00000000
\$t2	0x00000000
\$t3	0x00000000
\$t4	0x00000000
\$t5	0x00000000
\$t6	0x00000000
\$t7	0x00000000
\$t8	0x00000000
\$t9	0x00000000
\$s0	0x00000000
\$s1	0x00000000
\$s2	0x00000000
\$s3	0x00000000
\$s4	0x00000000
\$s5	0x00000000
\$s6	0x00000000
\$s7	0x00000000
\$s8	0x00000000
\$s9	0x00000000
\$t0	0x00000000
\$t1	0x00000000
\$t2	0x00000000
\$t3	0x00000000
\$t4	0x00000000
\$t5	0x00000000
\$t6	0x00000000
\$t7	0x00000000
\$t8	0x00000000
\$t9	0x00000000
\$s0	0x00000000
\$s1	0x00000000
\$s2	0x00000000
\$s3	0x00000000
\$s4	0x00000000
\$s5	0x00000000
\$s6	0x00000000
\$s7	0x00000000
\$s8	0x00000000
\$s9	0x00000000
\$t0	0x00000000
\$t1	0x00000000
\$t2	0x00000000
\$t3	0x00000000
\$t4	0x00000000
\$t5	0x00000000
\$t6	0x00000000
\$t7	0x00000000
\$t8	0x00000000
\$t9	0x00000000
\$s0	0x00000000
\$s1	0x00000000
\$s2	0x00000000
\$s3	0x00000000
\$s4	0x00000000
\$s5	0x00000000
\$s6	0x00000000
\$s7	0x00000000
\$s8	0x00000000
\$s9	0x00000000
\$t0	0x00000000
\$t1	0x00000000
\$t2	0x00000000
\$t3	0x00000000
\$t4	0x00000000
\$t5	0x00000000
\$t6	0x00000000
\$t7	0x00000000
\$t8	0x00000000
\$t9	0x00000000
\$s0	0x00000000
\$s1	0x00000000
\$s2	0x00000000
\$s3	0x00000000
\$s4	0x00000000
\$s5	0x00000000
\$s6	0x00000000
\$s7	0x00000000
\$	

LAB08\_2.asm

```

67 sqt.d f10, f10 # square root of f10 and store it in f10
68 ldi f10, two
69 mul.d f10, f10, f10
70 sub.d f14, f10, f14
71 add.d f14, f14, f10
72 div.d f10, f14, f10 # f10 = f10 / f14
73
74 # Print the roots
75 li f10, 4
76 la f10, result
77 syscall
78
79 li f10, 3
80 mov.d f10, f10
81 syscall
82
83 li f10, 4
84 la f10, oza
85 syscall
86
87 mul.d f14, f10, f10
88 div.d f10, f14, f10
89 syscall
90
91 # Handle complex roots
92
93 # compiler
94 ldi f10, negine
95 mul.d f14, f10, f10
96 sqt.d f14, f14
97 mul.d f14, f10, f14 # converting b to -b
98 ldi f10, two
99 mul.d f10, f10, f10
100 ldi f10, two
101 mul.d f10, f10, f10

```

Line: 141 Column: 26 Show Line Numbers

Mars Messages Run IO

Enter coefficient a: 1  
Enter coefficient b: 5  
Enter coefficient c: 10

The roots are: (-5.0 + 3.8729833462074171 ) / 2.0  
Or:  
The roots are: (-5.0 - 3.8729833462074171 ) / 2.0  
-- program is finished running --

Registers Coproc 1 Coproc 0

Name	Number	Value
\$zero	0	0x00000000
\$at	1	0x10100000
\$v0	2	0x0000000a
\$v1	3	0x00000000
\$a0	4	0x1001000a
\$a1	5	0x00000000
\$a2	6	0x00000000
\$a3	7	0x00000000
\$t0	8	0x00000000
\$t1	9	0x00000000
\$t2	10	0x00000000
\$t3	11	0x00000000
\$t4	12	0x00000000
\$t5	13	0x00000000
\$t6	14	0x00000000
\$t7	15	0x00000000
\$s0	16	0x00000000
\$s1	17	0x00000000
\$s2	18	0x00000000
\$s3	19	0x00000000
\$s4	20	0x00000000
\$s5	21	0x00000000
\$s6	22	0x00000000
\$s7	23	0x00000000
\$t8	24	0x00000000
\$t9	25	0x00000000
\$s0	26	0x00000000
\$s1	27	0x00000000
\$s2	28	0x10000000
\$s3	29	0x7ffffeff
\$s4	30	0x10000000
\$s5	31	0x00000000
\$pc		0x00400218
\$hi		0x00000000
\$lo		0x00000000

LAB08\_2.asm

```

100 ldi f10, two
101 mul.d f10, f10, f10
102
103 # Print the roots (part real, part imaginary)
104 li f10, 4
105 la f10, result
106 syscall
107
108 li f10, 4
109 la f10, open
110 syscall
111
112 li f10, 3
113 mov.d f10, f10
114
115 li f10, 4
116 la f10, plus
117 syscall
118
119 li f10, 3
120 mov.d f10, f10
121
122 li f10, 4
123 la f10, imaginaryPart
124 syscall
125
126 li f10, 4
127 la f10, close
128 syscall
129
130 li f10, 4
131 la f10, divid
132 syscall
133
134

```

Line: 141 Column: 26 Show Line Numbers

Mars Messages Run IO

Enter coefficient a: 1  
Enter coefficient b: 5  
Enter coefficient c: 10

The roots are: (-5.0 + 3.8729833462074171 ) / 2.0  
Or:  
The roots are: (-5.0 - 3.8729833462074171 ) / 2.0  
-- program is finished running --

Registers Coproc 1 Coproc 0

Name	Number	Value
\$zero	0	0x00000000
\$at	1	0x10100000
\$v0	2	0x0000000a
\$v1	3	0x00000000
\$a0	4	0x1001000a
\$a1	5	0x00000000
\$a2	6	0x00000000
\$a3	7	0x00000000
\$t0	8	0x00000000
\$t1	9	0x00000000
\$t2	10	0x00000000
\$t3	11	0x00000000
\$t4	12	0x00000000
\$t5	13	0x00000000
\$t6	14	0x00000000
\$t7	15	0x00000000
\$s0	16	0x00000000
\$s1	17	0x00000000
\$s2	18	0x00000000
\$s3	19	0x00000000
\$s4	20	0x00000000
\$s5	21	0x00000000
\$s6	22	0x00000000
\$s7	23	0x00000000
\$s8	24	0x00000000
\$s9	25	0x00000000
\$s0	26	0x00000000
\$s1	27	0x00000000
\$s2	28	0x10000000
\$s3	29	0x7ffffeff
\$s4	30	0x00000000
\$s5	31	0x00000000
\$pc		0x00400218
\$hi		0x00000000
\$lo		0x00000000

C:\Users\tahma\OneDrive\Desktop\Computer Architecture LAB\LAB08\LAB08\_2.asm - MARS 4.5

File Edit Run Settings Tools Help

Run speed at max (no interaction)

LAB08\_2.asm

```

133 mysyscall
134
135 li $v0, 3
136 mov.d $f12, $f0
137 mysyscall
138
139 # printing the minus case
140 li $v0, 4
141 la $a0, ora
142 mysyscall
143 li $v0, 4
144 la $a0, result
145 mysyscall
146 li $v0, 4
147 la $a0, open
148 mysyscall
149 li $v0, 3
150 mov.d $f12, $f14
151 mysyscall
152 li $v0, 4
153 la $a0, minus
154 mysyscall
155 li $v0, 3
156 mov.d $f12, $f6
157 mysyscall
158 li $v0, 4
159 la $a0, imaginaryPart
160 mysyscall
161 li $v0, 4
162 la $a0, close
163 mysyscall
164 li $v0, 4
165 la $a0, divid
166 mysyscall
167 li $v0, 3
168 mov.d $f12, $f0

```

Line: 166 Column: 8 | Show Line Numbers

Mars Messages Run IO

Enter coefficient a: 1  
Enter coefficient b: 5  
Enter coefficient c: 10

The roots are:  $(-5.0 + 3.8729833462074171) / 2.0$   
Or:  
The roots are:  $(-5.0 - 3.8729833462074171) / 2.0$   
-- program is finished running --

Clear

Registers Coproc 1 Coproc 0

Name	Number	Value
\$zero	0	0x00000000
\$at	1	0x00000000
\$v0	2	0x00000000
\$v1	3	0x00000000
\$a0	4	0x00000000
\$a1	5	0x00000000
\$a2	6	0x00000000
\$a3	7	0x00000000
\$t0	8	0x00000000
\$t1	9	0x00000000
\$t2	10	0x00000000
\$t3	11	0x00000000
\$t4	12	0x00000000
\$t5	13	0x00000000
\$t6	14	0x00000000
\$t7	15	0x00000000
\$s0	16	0x00000000
\$s1	17	0x00000000
\$s2	18	0x00000000
\$s3	19	0x00000000
\$s4	20	0x00000000
\$s5	21	0x00000000
\$s6	22	0x00000000
\$s7	23	0x00000000
\$t8	24	0x00000000
\$t9	25	0x00000000
\$d0	26	0x00000000
\$d1	27	0x00000000
\$fp	28	0x10000000
\$gp	29	0x7ffffeff
\$tp	30	0x00000000
\$ra	31	0x00000000
\$pc		0x00400000
\$hi		0x00000000
\$lo		0x00000000

C:\Users\tahma\OneDrive\Desktop\Computer Architecture LAB\LAB08\LAB08\_2.asm - MARS 4.5

File Edit Run Settings Tools Help

Run speed at max (no interaction)

LAB08\_2.asm

```

141 la $a0, ora
142 mysyscall
143 li $v0, 4
144 la $a0, result
145 mysyscall
146 li $v0, 4
147 la $a0, open
148 mysyscall
149 li $v0, 3
150 mov.d $f12, $f14
151 mysyscall
152 li $v0, 4
153 la $a0, minus
154 mysyscall
155 li $v0, 3
156 mov.d $f12, $f6
157 mysyscall
158 li $v0, 4
159 la $a0, imaginaryPart
160 mysyscall
161 li $v0, 4
162 la $a0, close
163 mysyscall
164 li $v0, 4
165 la $a0, divid
166 mysyscall
167 li $v0, 3
168 mov.d $f12, $f0
169 mysyscall
170
171 end:
172 li $v0, 10
173 mysyscall
174
175

```

Line: 175 Column: 1 | Show Line Numbers

Mars Messages Run IO

Enter coefficient a: 10  
Enter coefficient b: 5  
Enter coefficient c: 3

The roots are:  $(-5.0 + 9.746794344089631) / 20.0$   
Or:  
The roots are:  $(-5.0 - 9.746794344089631) / 20.0$   
-- program is finished running --

Clear

Registers Coproc 1 Coproc 0

Name	Number	Value
\$zero	0	0x00000000
\$at	1	0x10100000
\$v0	2	0x0000000a
\$v1	3	0x00000000
\$a0	4	0x10010000
\$a1	5	0x00000000
\$a2	6	0x00000000
\$a3	7	0x00000000
\$t0	8	0x00000000
\$t1	9	0x00000000
\$t2	10	0x00000000
\$t3	11	0x00000000
\$t4	12	0x00000000
\$t5	13	0x00000000
\$t6	14	0x00000000
\$t7	15	0x00000000
\$s0	16	0x00000000
\$s1	17	0x00000000
\$s2	18	0x00000000
\$s3	19	0x00000000
\$s4	20	0x00000000
\$s5	21	0x00000000
\$s6	22	0x00000000
\$s7	23	0x00000000
\$s8	24	0x00000000
\$t9	25	0x00000000
\$d0	26	0x00000000
\$d1	27	0x00000000
\$fp	28	0x10000000
\$gp	29	0x7ffffeff
\$tp	30	0x00000000
\$ra	31	0x00000000
\$pc		0x00400218
\$hi		0x00000000
\$lo		0x00000000

## OUTPUTS

Reset: reset completed.

Enter coefficient a: 25  
Enter coefficient b: -30  
Enter coefficient c: 9

The roots are: 0.6  
Or: 0.6  
-- program is finished running --

Reset: reset completed.

Enter coefficient a: 1  
Enter coefficient b: 5  
Enter coefficient c: 1

The roots are: -0.20871215252208009  
Or: -4.7912878474779195  
-- program is finished running --



```
Reset: reset completed.

Enter coefficient a: 10
Enter coefficient b: 200
Enter coefficient c: 50

The roots are: -0.2532056551910358
Or: -19.746794344808965
-- program is finished running --
```

```
Reset: reset completed.

Enter coefficient a: 10
Enter coefficient b: 20
Enter coefficient c: 30

The roots are: (-20.0 + 28.284271247461902i ) / 20.0
Or:
The roots are: (-20.0 - 28.284271247461902i ) / 20.0
-- program is finished running --
```

```
Reset: reset completed.

Enter coefficient a: 321.13
Enter coefficient b: 1.23
Enter coefficient c: 54.2

The roots are: (-1.23 + 263.8550190919248i ) / 642.26
Or:
The roots are: (-1.23 - 263.8550190919248i ) / 642.26
-- program is finished running --
```

## CODE:

```
.data
promptA: .asciiz "Enter coefficient a: "
promptB: .asciiz "Enter coefficient b: "
promptC: .asciiz "Enter coefficient c: "
result: .asciiz "\nThe roots are: "
ors: .asciiz "\nOr: "
complexRoot: .asciiz "Complex Roots."
four: .double 4.0
two: .double 2.0
zero: .double 0.0
negOne: .double -1.0
open: .asciiz "("
close: .asciiz ")"
imaginaryPart: .asciiz "i "
plus: .asciiz " + "
minus: .asciiz " - "
sqr: .asciiz " √"
divid: .asciiz " / "

.text
# Print prompt message to enter coefficient a
li $v0, 4
la $a0, promptA
syscall

# Read coefficient a
li $v0, 7
syscall
mov.d $f20, $f0

# Print prompt message to enter coefficient b
li $v0, 4
la $a0, promptB
syscall
```

```

# Read coefficient b
li $v0, 7
syscall
mov.d $f14, $f0

# Print prompt message to enter coefficient c
li $v0, 4
la $a0, promptC
syscall

# Read coefficient c
li $v0, 7
syscall
mov.d $f16, $f0

# Calculate the discriminant:  $\$f8 = \$f14^2 - 4 * \$f12 * \$f16$ 
mul.d $f8, $f14, $f14 #  $\$f8 = \$f14 * \$f14$ 
ldc1 $f10, four # load four into $f10
mul.d $f10, $f10, $f20 #  $4 * \$f20$ 
mul.d $f10, $f10, $f16 #  $\$f10 = \$f10 * \$f16$ 
sub.d $f8, $f8, $f10 #  $\$f8 = \$f8 - \$f10$ 

# Check if the roots are complex
ldc1 $f18, zero
c.lt.d $f8, $f18
bc 1t complex

# Compute the roots
sqrt.d $f8, $f8 # square root $f8 and store it in $f8
ldc1 $f10, two
mul.d $f6, $f10, $f20
sub.d $f14, $f18, $f14
add.d $f4, $f14, $f8
div.d $f22, $f4, $f6 #  $\$f10 = \$f8 / \$f6$ 

# Print the roots
li $v0, 4
la $a0, result
syscall
li $v0, 3
mov.d $f12, $f22
syscall
li $v0, 4
la $a0, ors
syscall
li $v0, 3
sub.d $f4, $f14, $f8
div.d $f12, $f4, $f6
syscall
j end

# Handle complex roots

```

```
complex:
ldc1 $f6 negOne
mul.d $f4, $f8 $f6
sqrt.d $f6, $f4
sub.d $f14, $f18, $f14 # converting b to -b
ldc1 $f12, two
mul.d $f8, $f12, $f20
```

```
# Print the roots (part real, part imaginary)
li $v0, 4
la $a0, result
syscall
li $v0, 4
la $a0, open
syscall
li $v0, 3
mov.d $f12, $f14
syscall
```

```
li $v0, 4
la $a0, plus
syscall
```

```
li $v0, 3
mov.d $f12, $f6
syscall
```

```
li $v0, 4
la $a0, imaginaryPart
syscall
```

```
li $v0, 4
la $a0, close
syscall
```

```
li $v0, 4
la $a0, divid
syscall
```

```
li $v0, 3
mov.d $f12, $f8
syscall
```

```
# printing the minus case
li $v0, 4
la $a0, ors
syscall
li $v0, 4
la $a0, result
syscall
li $v0, 4
la $a0, open
syscall
li $v0, 3
mov.d $f12, $f14
syscall
li $v0, 4
```

```

la $a0, minus
syscall
li $v0, 3
mov.d $f12, $f6
syscall
li $v0, 4
la $a0, imaginaryPart
syscall
li $v0, 4
la $a0, close
syscall
li $v0, 4
la $a0, divid
syscall
li $v0, 3
mov.d $f12, $f8
syscall

end:
li $v0, 10
syscall

```

## Task 6

6. Square Root Calculation: Newton's iterative method can be used to approximate the square root of a number **x**. Let the initial **guess** be **1**. Then each new **guess** can be computed as follows:

$$\text{guess} = ((x/\text{guess}) + \text{guess}) / 2;$$

Write a function called **square\_root** that receives a double-precision parameter **x**, computes, and returns the approximated value of the square root of **x**. Write a loop that repeats 20 times and computes 20 **guess** values, then returns the final **guess** after 20 iterations. Use the MIPS floating-point register convention to pass the parameter **x** and to return the function result. All computation should be done using double-precision floating-point instructions and registers. Compare the result of the **sqrtd** instruction against the result of your **square\_root** function. What is the error in absolute value?

## PICTURES OF THE CODE:

```

LAB08_3.asm
1 .data
2 $num: .asciiz "The number we are going to take the square root is: "
3 $guessnum: .asciiz "The guess number is: "
4 $sqrt_answer: .asciiz "The sqrt.d answer is: "
5 $num: .double 59843.32154
6 $guess: .double 1.0
7 $half: .double 0.5
8 $twenty: .word 20
9
10 .text
11 main:
12     # Print message
13     li $v0, 4
14     la $a0, $num
15     syscall
16
17     # Print number
18     li $v0, 3
19     l.d $f12, $num
20     syscall
21
22     # Print guess message
23     li $v0, 4
24     la $a0, $guessnum
25     syscall
26
27     # Call square_root function
28     j square_root
29
30 square_root:
31     # Load initial guess
32     l.d $f0, $guess
33
34     # Load loop counter
35     lw $t0, $twenty
36
37     # Loop 20 times
38     loop:
39         # Calculate new guess
40         l.d $t4, $num
41         div.d $f6, $f0, $t4
42         add.d $f6, $f6, $f0
43         l.d $f2, $half
44         mul.d $f6, $f6, $f2
45
46         # Store new guess in $f0
47         mov.d $f0, $f6
48
49         # Decrement loop counter
50         addi $t0, $t0, -1
51         bne $t0, $zero, loop
52
53     # Print result
54     li $v0, 3
55     mov.d $f12, $f0
56     syscall
57
58     # Compare with sqrt.d
59     li $v0, 4
60     la $a0, $sqrt_answer
61     syscall
62
63     li $v0, 3
64     l.d $f12, $f0
65     syscall
66
67     # Exit program
68     li $v0, 10
69     syscall
70

```

MARS Messages | Run I/O

```

The number we are going to take the square root is: 59843.32154
The guess number is: 244.629466516292
The sqrt.d answer is: 244.629466516292
-- program is finished running --

```

Clear

```

LAB08_3.asm
34     lw $t0, $twenty
35
36     # Repeat 20 times
37     loop:
38         # Calculate new guess
39         l.d $t4, $num
40         div.d $f6, $f0, $t4
41         add.d $f6, $f6, $f0
42         l.d $f2, $half
43         mul.d $f6, $f6, $f2
44
45         # Store new guess in $f0
46         mov.d $f0, $f6
47
48         # Decrement loop counter
49         addi $t0, $t0, -1
50         bne $t0, $zero, loop
51
52     # Print result
53     li $v0, 3
54     mov.d $f12, $f0
55     syscall
56
57     # Compare with sqrt.d
58     li $v0, 4
59     la $a0, $sqrt_answer
60     syscall
61
62     li $v0, 3
63     l.d $f12, $f0
64     syscall
65
66     # Exit program
67     li $v0, 10
68     syscall
69
70

```

MARS Messages | Run I/O

```

The number we are going to take the square root is: 59843.32154
The guess number is: 244.629466516292
The sqrt.d answer is: 244.629466516292
-- program is finished running --

```

Clear

## COMPARING RESULTS:

```

The number we are going to take the square root is: 9.984988675761652E15
The guess number is: 9.5227767724486E9
The sqrt.d answer is: 9.992491519016492E7
-- program is finished running --

```

$$\text{Error} = 9.5227767724486E9 - 9.992491519016492E7 = 852929148061692$$

```
The number we are going to take the square root is: 9.0
The guess number is: 3.0
The sqrt.d answer is: 3.0
-- program is finished running --
```

$\text{Error} = 3.0 - 3.0 = 0.0$

```
The number we are going to take the square root is: 5.43987564387543E14
The guess number is: 5.1913644684564495E8
The sqrt.d answer is: 2.3323540991614953E7
-- program is finished running --
```

$\text{Error} = 2.3323540991614953E7 - 5.1913644684564495E8 = 4.85801037029501E8$

The difference gets bigger when the number is big. We can fix that by increasing the loops from 20 to something bigger.

CODE:

```
.data
sqnum: .asciiz "The number we are going to take the square root is: "
guessnum: .asciiz "\nThe guess number is: "
sqr: .asciiz "\nThe sqrt.d answer is: "
num: .double 5.43987564387543E14
guess: .double 1.0
half: .double 0.5
twenty: .word 20
```

```
.text
```

```
main:
```

```
    # Print message
    li $v0, 4
    la $a0, sqnum
    syscall
```

```
    # Print number
    li $v0, 3
    l.d $f12, num
    syscall
```

```
    # Print guess message
    li $v0, 4
    la $a0, guessnum
    syscall
```

```
    # Call square_root function
    j square_root
```

```

square_root:
    # Load initial guess
    l.d $f0, guess

    # Load loop counter
    lw $t0, twenty

    # Repeat 20 times
loop:
    # Calculate new guess
    l.d $f4, num
    div.d $f6, $f4, $f0
    add.d $f6, $f6, $f0
    l.d $f2, half
    mul.d $f6, $f6, $f2

    # Store new guess in $f0
    mov.d $f0, $f6

    # Decrement loop counter
    addi $t0, $t0, -1
    bne $t0, $zero, loop

    # Print result
    li $v0, 3
    mov.d $f12, $f0
    syscall

    # Compare with sqrt.d
    li $v0, 4
    la $a0, sqr
    syscall
    li $v0, 3
    sqrt.d $f12, $f4
    syscall

    # Exit program
    li $v0, 10
    syscall

```