

Linear Systems

Exam - 3

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①

$$1) \quad A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & -2 & -1 \end{bmatrix} \quad B = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad C = [1 \ 0 \ 1] \quad D = 3$$

$$H(s) = C [sI - A]^{-1} B + D$$

$$sI - A = \begin{bmatrix} s & 0 & 0 \\ 0 & s & 0 \\ 0 & 0 & s \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & -2 & -1 \end{bmatrix} = \begin{bmatrix} s-1 & 0 & 0 \\ 0 & s-4 & 0 \\ 0 & 2 & s+1 \end{bmatrix}$$

$$[sI - A]^{-1} = \frac{1}{(s-1)(s-4)(s+1)} \begin{bmatrix} (s-4)(s+1) & 0 & 0 \\ 0 & (s-1)(s+1) & 0 \\ 0 & 0 & (s-1)2 \end{bmatrix}^T$$

$$= \begin{bmatrix} \frac{1}{s-1} & 0 & 0 \\ 0 & \frac{1}{s-4} & \frac{2}{(s-1)(s+1)} \\ 0 & \frac{2}{(s-4)(s+1)} & \frac{1}{s+1} \end{bmatrix}$$

$$[sI - A]^{-1} B = \begin{bmatrix} \frac{1}{s-1} & 0 & 0 \\ 0 & \frac{1}{s-4} & \frac{2}{(s-1)(s+1)} \\ 0 & \frac{2}{(s-4)(s+1)} & \frac{1}{s+1} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{s-1} \\ 0 \\ \frac{1}{s+1} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{s-1} \\ \frac{2}{s-3s-4} \\ \frac{1}{s+1} \end{bmatrix} \quad \text{Now } C [sI - A]^{-1} B = [1 \ 0 \ 1] \begin{bmatrix} \frac{1}{s-1} \\ \frac{2}{s-3s-4} \\ \frac{1}{s+1} \end{bmatrix}$$

$$\Rightarrow \frac{1}{s-1} + \frac{1}{s+1} \quad \text{Now } C [sI - A]^{-1} B + D$$

$$= \frac{1}{s-1} + \frac{1}{s+1} + 3$$

(2)

$$\therefore H(s) = \frac{1}{s-1} + \frac{1}{s+1} + 3$$

$$H(s) = \frac{y(s)}{u(s)} = \frac{(s+1) + (s-1) + 3(s-1)(s+1)}{(s-1)(s+1)} = \frac{s+1+s-1+3(s^2-1)}{s^2-1}$$

$$\frac{y(s)}{u(s)} = \frac{3s^2 + 2s - 3}{s^2 - 1}$$

$$\boxed{\ddot{y} - y = 3\ddot{u} + 2\dot{u} - 3u}$$

$$2) \quad A = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 4 & 0 \\ 1 & -2 & 3 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 4 & 0 \\ 1 & -2 & 3 \end{bmatrix} - \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix} = \begin{bmatrix} 1-\lambda & 0 & -1 \\ 0 & 4-\lambda & 0 \\ 1 & -2 & 3-\lambda \end{bmatrix}$$

$$\det |A - \lambda I| = (1-\lambda)(4-\lambda)(3-\lambda) - 0 - 1(-(4-\lambda))$$

$$= (1-\lambda)(4-\lambda)(3-\lambda) + (4-\lambda)$$

$$= (4-\lambda) \left[(1-\lambda)(3-\lambda) + 1 \right]$$

$$= (4-\lambda) \left[3 - 3\lambda - \lambda + \lambda^2 + 1 \right]$$

$$\Rightarrow (4-\lambda) \left[\lambda^2 - 4\lambda + 4 \right] = 0$$

$$(4-\lambda) \left[\lambda^2 - 2\lambda - 2\lambda + 4 \right] = 0$$

$$(4-\lambda) \left[\lambda(\lambda-2) - 2(\lambda-2) \right] = 0$$

$$(4-\lambda) \left[\lambda-2 \right]^2 = 0$$

$$\boxed{(4-\lambda)(\lambda-2)(\lambda-2) = 0}$$

(3)

\therefore Eigen values are 2, 2, 4 //

when $\lambda = 2$

$$[A - \lambda I] = \begin{bmatrix} 1-\lambda & 0 & -1 \\ 0 & 4-\lambda & 0 \\ 1 & -2 & 3-\lambda \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{21} \\ v_{31} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -1 & 0 & -1 \\ 0 & 2 & 0 \\ 1 & -2 & 1 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{21} \\ v_{31} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{aligned} -v_{11} - v_{31} &= 0 \\ 2v_{21} &= 0 \\ +v_{11} - 2v_{21} + v_{31} &= 0 \end{aligned}$$

Let $\boxed{v_{11} = 1}$ then $-v_{11} - v_{31} = 0$

$$-1 - v_{31} = 0$$

$$-v_{31} = 1$$

$$\Rightarrow \boxed{v_{31} = -1}$$

$$v_{11} - 2v_{21} + v_{31} = 0$$

$$1 - 2v_{21} - 1 = 0$$

$$\boxed{v_{21} = 0}$$

$$= \begin{bmatrix} v_{11} \\ v_{21} \\ v_{31} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} v_{12} \\ v_{22} \\ v_{32} \end{bmatrix}$$

when $\lambda = 4$

$$[A - \lambda I] = \begin{bmatrix} -3 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & -2 & -1 \end{bmatrix} \begin{bmatrix} v_{13} \\ v_{23} \\ v_{33} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{aligned} -3v_{13} - v_{33} &= 0 \\ v_{13} - 2v_{23} - v_{33} &= 0 \end{aligned}$$

$$\boxed{v_{33} = 3}$$

now

$$-3v_{13} - 3 = 0$$

$$\boxed{v_{13} = -1}$$

$$v_{13} - 2v_{23} - v_{33} = 0$$

$$-1 - 2v_{23} - 3 = 0$$

$$-2v_{23} = 4$$

$$\boxed{v_{23} = -2}$$

$$\begin{bmatrix} v_{13} \\ v_{23} \\ v_{33} \end{bmatrix} = \begin{bmatrix} -1 \\ -2 \\ 3 \end{bmatrix}$$

$$\therefore \text{Eigen vector} = \begin{bmatrix} v_{11} & v_{12} & v_{13} \\ v_{21} & v_{22} & v_{23} \\ v_{31} & v_{32} & v_{33} \end{bmatrix} = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & -2 \\ -1 & -1 & 3 \end{bmatrix} // = T \quad (4)$$

$$(3) \quad A = \begin{bmatrix} -8 & 1 \\ 6 & 0 \end{bmatrix} \quad B = \begin{bmatrix} -5 \\ -6 \end{bmatrix} \quad C = \begin{bmatrix} -1 & 0 \end{bmatrix} \quad D = 3$$

to Jordan form

$$AB = \begin{bmatrix} -8 & 1 \\ 6 & 0 \end{bmatrix} \begin{bmatrix} -5 \\ -6 \end{bmatrix} = \begin{bmatrix} 40 & -6 \end{bmatrix}$$

$$A - \lambda I \Rightarrow \begin{bmatrix} -8 & 1 \\ 6 & 0 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} -8-\lambda & 1 \\ 6 & -\lambda \end{bmatrix}$$

$$\det |A - \lambda I| = \begin{aligned} & (-8-\lambda)(-\lambda) - 6 \\ & = 8\lambda + \lambda^2 - 6 = 0 \\ & \lambda^2 + 8\lambda - 6 = 0 \end{aligned}$$

$$\lambda = -4 \pm \sqrt{22}$$

$$\boxed{\lambda = -8.69, 0.69}$$

when $\lambda = 0.69$

$$A - \lambda I = \begin{bmatrix} -8-0.69 & 1 \\ 6 & -0.69 \end{bmatrix} = \begin{bmatrix} -8.69 & 1 \\ 6 & -0.69 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{21} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow -8.69 v_{11} + v_{21} = 0 \quad \text{--- (1)} \quad \text{(1) } \times 0.69 + \text{(2)}$$

$$6 v_{11} - 0.69 v_{21} = 0 \quad \text{--- (2)} \quad -5.99 v_{11} + 0.69 v_{21} + 6 v_{11} - 0.69 v_{21} = 0$$

$$\text{let } v_{11} = 1 \quad \therefore \quad v_{21} = 8.69 \quad (69)$$

$$\begin{bmatrix} v_{11} \\ v_{21} \end{bmatrix} = \begin{bmatrix} 1 \\ 8.69 \end{bmatrix}$$

when $\lambda = -8.69$

(5)

$$A - \lambda I = \begin{bmatrix} -8+8.69 & 1 \\ 6 & +8.69 \end{bmatrix} \begin{bmatrix} v_{12} \\ v_{22} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow +0.69 v_{12} + v_{22} = 0 \quad v_{12} = 1$$
$$6 v_{12} + v_{22} = 0 \quad \therefore v_{22} = -6 - 0.69$$

$$\begin{bmatrix} v_{12} \\ v_{22} \end{bmatrix} = \begin{bmatrix} 1 \\ -0.69 \end{bmatrix}$$

$$\therefore \text{Eigen vector} = \begin{bmatrix} 1 & 1 \\ 8.69 & -0.69 \end{bmatrix} = T$$

$$T^{-1} = \frac{1}{-0.69 - 8.69} \begin{bmatrix} -0.69 & -1 \\ -8.69 & 1 \end{bmatrix} = \frac{1}{-9.38} \begin{bmatrix} -0.69 & -1 \\ -8.69 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 0.07 & 0.10 \\ 0.92 & -0.10 \end{bmatrix}$$

Now $\hat{A} = T^{-1} A T$

$$= \begin{bmatrix} 0.07 & 0.1 \\ 0.92 & -0.1 \end{bmatrix} \begin{bmatrix} -8 & 1 \\ 6 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 8.69 & -0.69 \end{bmatrix}$$
$$= \begin{bmatrix} 0.04 & 0.07 \\ -7.96 & 0.92 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 8.69 & -0.69 \end{bmatrix} = \begin{bmatrix} 0.65 & -0.008 \\ 0.034 & -8.594 \end{bmatrix}$$

$$\hat{B} = T^{-1} B = \begin{bmatrix} 0.07 & 0.1 \\ 0.92 & -0.1 \end{bmatrix} \begin{bmatrix} -5 \\ -6 \end{bmatrix} = \begin{bmatrix} -0.35 & -0.6 \\ -4 \end{bmatrix} = \begin{bmatrix} -0.95 \\ -4 \end{bmatrix}$$

$$\hat{C} = C^T = [-1 \ 0] \begin{bmatrix} 1 & 1 \\ 8.69 & -0.69 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & -1 \end{bmatrix}$$

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$$\therefore \hat{\dot{x}} = \begin{bmatrix} 0.65 & -0.008 \\ 0.034 & -8.594 \end{bmatrix} x + \begin{bmatrix} -0.95 \\ -4 \end{bmatrix} u //$$

$$\hat{y} = [-1 \ -1] x + 3u //$$

④ $A = \begin{bmatrix} 3 & 1 \\ 0 & 2 \end{bmatrix} \quad B = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \quad C = [-1 \ 1]$

$$sI - A = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 3 & 1 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} s-3 & -1 \\ 0 & s-2 \end{bmatrix}$$

$$\det |sI - A| \Rightarrow (s-3)(s-2) = 0$$

$$s^2 - 3s - 2s + 6 = 0$$

$$s^2 - 5s + 6$$

$$\hat{A} = \begin{bmatrix} 5 & 1 \\ -6 & 0 \end{bmatrix} \quad \hat{C} = [1 \ 0]$$

$$P_0 = \begin{bmatrix} C \\ CA \end{bmatrix} \quad \text{Now } CA = [-1 \ 1] \begin{bmatrix} 3 & 1 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} -3 & 1 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} -3 & 1 \end{bmatrix}$$

$$P_0 = \begin{bmatrix} -1 & 1 \\ -3 & 1 \end{bmatrix}$$

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$$\hat{P}_0 = \begin{bmatrix} \hat{C} \\ \hat{C}\hat{A} \end{bmatrix} \quad \hat{C}\hat{A} = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 5 & 1 \\ -6 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 5 & 1 \end{bmatrix}$$

$$\hat{P}_0 = \begin{bmatrix} 1 & 0 \\ 5 & 1 \end{bmatrix}$$

$$P_0^{-1} = \begin{bmatrix} -1 & 1 \\ -3 & 1 \end{bmatrix}^{-1} = \frac{1}{-1 - (-3)} \begin{bmatrix} 1 & -1 \\ 3 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 3 & -1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.5 & -0.5 \\ 1.5 & -0.5 \end{bmatrix}$$

$$T = P_0^{-1} \hat{P}_0 = \begin{bmatrix} 0.5 & -0.5 \\ 1.5 & -0.5 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 5 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -2 & -0.5 \\ -1 & -0.5 \end{bmatrix}$$

$\hat{B} \neq \star$ Now $T^{-1} = \begin{bmatrix} -2 & -0.5 \\ -1 & -0.5 \end{bmatrix}^{-1} = \frac{1}{-1 - \frac{1}{2}} \begin{bmatrix} -0.5 & +0.5 \\ 1 & -2 \end{bmatrix}$

$$= \begin{bmatrix} -1 & 1 \\ 2 & -4 \end{bmatrix}$$

$$\hat{B} = T^{-1} B = \begin{bmatrix} -1 & 1 \\ 2 & -4 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -2 + 1 \\ 4 - 4 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} //$$

⑧

⑤ $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & -2 & -1 \end{bmatrix} \quad B = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad C = [1 \quad 1 \quad 1] \quad D = 3$

stability

$$sI - A = \begin{bmatrix} s & 0 & 0 \\ 0 & s & 0 \\ 0 & 0 & s \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & -2 & -1 \end{bmatrix} = \begin{bmatrix} s-1 & 0 & 0 \\ 0 & s-4 & 0 \\ 0 & 2 & s+1 \end{bmatrix}$$

$$\det |sI - A| = (s-1)(s+4)(s+1) - 0 + 0$$

$\Rightarrow s = 1, -4, -1 \quad \therefore s = 1$ lies right side of y axis
 \therefore It is unstable.

Controllability

$$P_c = [B \quad AB \quad A^2B] \quad AB = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & -2 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$3 \times 3 \quad \quad \quad 3 \times 1$

$$= \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

$$P_c = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 1 & -1 & 1 \end{bmatrix}$$

$$A^2B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & -2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & -2 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\det(P_c) = 1(0) - 1(0) + 1(0) = 0$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 16 & 0 \\ 0 & -6 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

\therefore It is uncontrollable.

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observability

$$P_0 = \begin{bmatrix} C \\ CA \\ CA^2 \end{bmatrix}$$

$$CA = [1 \ 1 \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & -2 & -1 \end{bmatrix}$$

$$= [1 \ 2 \ -1]$$

$$CA^2 = [1 \ 1 \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 16 & 0 \\ 0 & -6 & 1 \end{bmatrix}$$

$$= [1 \ 10 \ 1]$$

$$P_0 = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & -1 \\ 1 & 10 & 1 \end{bmatrix}$$

$$\det(P_0) = 1(2+10) - 1(1+1) + 1(10-2)$$

$$= \cancel{-2} \cancel{+8} \quad 12 - 2 + 8 \neq 0$$

$$\cancel{-2} \neq 0$$

\therefore It is observable