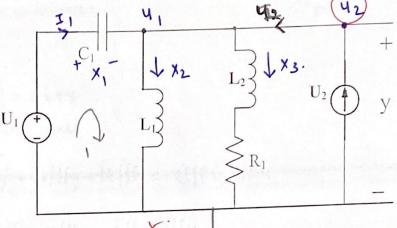


(1) Write the state equation and output equations

(25 points)



output function. Y= 42. Un= corrent

State equations.

we have XIX = 1 STIdt

$$\dot{X}_1 = \frac{1}{c_1} \mathbf{I}_1$$

$$\frac{4_2-R_1X_3}{L_2}=\dot{X}_3$$

$$\dot{\lambda}_2 = \frac{u_1}{L_1} - \frac{\lambda_1}{L_1}$$

$$\frac{1}{x_3} = \frac{42}{12} - \frac{R_1 x_3}{12}$$

$$\dot{x}_1 = \frac{1}{c_1} u_1^{\lambda}$$

$$\dot{x}_2 = \frac{u_1}{c_1} - \frac{x_1}{c_1}$$

$$\dot{x}_3 = \frac{1}{c_1} u_1^{\lambda}$$

$$\dot{x}_4 = \frac{1}{c_1} u_1^{\lambda}$$

$$\dot{x}_5 = \frac{1}{c_1} u_1^{\lambda}$$

$$\dot{x}_7 = \frac{1}{c_1} u_1^{\lambda}$$

$$\dot{x}_7 = \frac{1}{c_1} u_1^{\lambda}$$

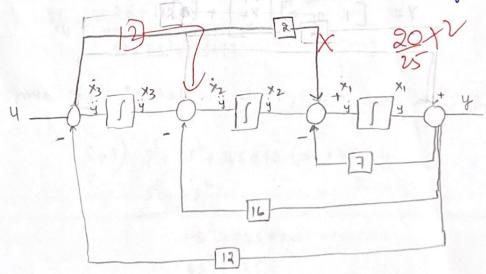
$$\dot{x}_8 = \frac{1}{c_1} u_1^{\lambda}$$

Please show me your calculations for partial credit

(2)  $\ddot{y} + 7\ddot{y} + 16\dot{y} + 12y = 2\dot{u} + u$ , find the state and output equation by using the observer canonical form of the given model. (25 points)

Sol: Given

The simulation diagram for the above can be drawn as follows:



from above we get

of equation:

y = x, 4/19 - 1)

Please show me your calculations for partial credit

(3)  $\ddot{y} + 7\ddot{y} + 16\dot{y} + 12y = 2\dot{u} + u$ , find the state and output equation by using the Jordan form. This methamatical modal has pole at '-3' (25 points)

Sol: Given

The above eq 10 can be converted into s-domain as follows

We have  $H_s = \frac{4}{4} = \frac$ 

$$\frac{4}{4} = \frac{2s+1}{s^3+7s^2+16s+12}$$
;

given that 9t has pole at -3, So one proof is S+3.

$$S+3) S^{3}+75^{2}+165+12 (s^{2}+45+4)$$

$$-\frac{S^{3}+3S^{2}}{4S^{2}+165+12}$$

$$-\frac{4S^{2}+12S}{4S+12}$$

$$-\frac{4S+12}{4S+12}$$

$$(4) \begin{bmatrix} \dot{x_1} \\ \dot{x_2} \\ \dot{x_3} \end{bmatrix} = \begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} u, \quad y = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \text{ write the transfer }$$

function for the above state equation and output equation (25 points)

Transfer function 
$$H_S = ((SI-A)^{-1}B+0.$$

$$A = \begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -4 \end{bmatrix} \quad B = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad C = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}.$$

$$SI = \begin{bmatrix} S & O & O \\ O & S & O \\ O & O & S \end{bmatrix}$$

$$SI-A = \begin{bmatrix} S & 0 & 0 \\ 0 & S & 0 \\ 0 & 0 & S \end{bmatrix} - \begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -4 \end{bmatrix}$$

$$= \begin{bmatrix} S+2 & 0 & 0 \\ 0 & S+1 & 0 \\ 0 & 0 & S+4 \end{bmatrix}$$

$$(SI-A)^{-1} = \frac{1}{|SI-A|}$$
 (Adjoint of  $SI-A$ )

$$|SI-A| = |S+2| |S+1| 0 = |S+2| (S+1)(S+4).$$

(0-factor of 
$$0 = (-1)^{1+2} \begin{vmatrix} 0 & 0 \\ 0 & 5+4 \end{vmatrix} = 0$$
  
(0-factor of  $0 = (-1)^{1+2} \begin{vmatrix} 0 & 0 \\ 0 & 5+4 \end{vmatrix} = 0$   
(0-factor of  $0 = (-1)^{1+3} \begin{vmatrix} 0 & 5+1 \\ 0 & 0 \end{vmatrix} = 0$ 

Please show me your calculations for partial credit

Among 2 and 3, we observe as follows

In 2, the Imput is dependent on only one of the state variable and not dependent on output. where all

m3, the Input is depends on both the state variables and state functions are particularly depends on diagonal elements i.e each state function in the given querion dependents on particular state variable.

4th

3

$$\frac{4}{4} = \frac{5^{3} + 55 + 4 + 25^{2} + 125 + 16 + 35^{2} + 95 + 6}{(5^{2} + 35 + 2)(5 + 4)}$$

$$\frac{4}{4} = \frac{5^{3} + 55 + 4 + 25^{2} + 125 + 16 + 35^{2} + 95 + 6}{(5^{2} + 265 + 26)(5 + 4)}$$

$$S^{3}+3S^{2}+2S+4S^{2}+12S+8$$

$$\Rightarrow y(S^{3}+3S^{2}+2S+4S^{2}+12S+8) = u(6S^{2}+26S+26)$$