

**EE-792**

**TEST-3**

**Summer-19**

**First Name:** \_\_\_\_\_

*Solution.*

**Last Name:** \_\_\_\_\_

- Open text book, and closed notes. One sheet of notes (A4 size, both sides) will be allowed to the exam.
- Time for this Test is one hour thirty minutes.
- Calculators are allowed for this test (any kind)
- All work in this exam must be your own, sharing of calculators, formula sheet or text book will not be allowed.

- (1)  $\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \end{bmatrix} u, \quad y = \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  Find the transformation matrix for the given model to convert into observable canonical form. Now by using the transformation matrix find the state transition matrix of the new model. (25 points)

from the solution  $T = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix} \quad T^{-1} = \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix}$

$$\Phi(s) = [sI - A]^{-1} = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} s-3 & 0 \\ 0 & s-2 \end{bmatrix}^{-1}$$

$$\Phi(s) = \begin{pmatrix} \frac{s-2}{(s-2)(s-3)} & 0 \\ 0 & \frac{s-3}{(s-2)(s-3)} \end{pmatrix} = \begin{pmatrix} \frac{1}{s-3} & 0 \\ 0 & \frac{1}{s-2} \end{pmatrix}$$

$$\Phi(t) = \begin{bmatrix} e^{+3t} & 0 \\ 0 & e^{+2t} \end{bmatrix}$$

$$\hat{\Phi}(t) = T^{-1} \Phi(t) T = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} e^{+3t} & 0 \\ 0 & e^{+2t} \end{bmatrix} \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} 3e^{+3t} & e^{+2t} \\ 2e^{+3t} & e^{+2t} \end{bmatrix} \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 3e^{+3t} - 2e^{+2t} & -3e^{+3t} + 3e^{+2t} \\ 2e^{+3t} - 2e^{+2t} & -2e^{+3t} + 3e^{+2t} \end{bmatrix}$$

$$T^{-1} \Phi(t) T = \begin{bmatrix} e^{3t} & -e^{2t} \\ -2e^{3t} & 3e^{2t} \end{bmatrix} \begin{bmatrix} 3 & +1 \\ +2 & 3 \end{bmatrix}$$

$$T^{-1} \Phi(t) = \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} e^{3t} & 0 \\ 0 & e^{2t} \end{bmatrix} = \begin{bmatrix} e^{3t} & -e^{2t} \\ -2e^{3t} & 3e^{2t} \end{bmatrix}$$

$$= \begin{bmatrix} 3e^{3t} - 2e^{2t} & e^{3t} - e^{2t} \\ -6e^{3t} + 6e^{2t} & -2e^{3t} + 3e^{2t} \end{bmatrix}$$

Please show me your calculations for partial credit

(2) A model has  $A = \begin{bmatrix} 0 & 1 \\ 2 & -3 \end{bmatrix}$   $B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$   $C = [1 \quad -1]$  design an observer with a desired poles at  $-1 \pm j4$ , find the state equation of Observer. (25 points)

$$A = \begin{bmatrix} 0 & 1 \\ 2 & -3 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad C = [1 \quad -1]$$

$$A^o = [A - KC] \Rightarrow \begin{bmatrix} 0 & 1 \\ 2 & -3 \end{bmatrix} - \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} [1 \quad -1]$$

$$= \begin{bmatrix} 0 & 1 \\ 2 & -3 \end{bmatrix} - \begin{bmatrix} k_1 & -k_1 \\ k_2 & -k_2 \end{bmatrix} \quad \begin{matrix} \text{VS} \\ \text{VS} \end{matrix}$$

$$= \begin{bmatrix} -k_1 & (1+k_1) \\ 2-k_2 & (-3+k_2) \end{bmatrix}$$

$$\det [sI - A^o] = \begin{vmatrix} s & 0 \\ 0 & s \end{vmatrix} - \begin{vmatrix} -k_1 & (1+k_1) \\ (2-k_2) & (-3+k_2) \end{vmatrix} = \begin{vmatrix} (s+k_1) & -(1+k_1) \\ -(2-k_2) & (s+3+k_2) \end{vmatrix}$$

$$= s^2 + k_1 s + 3s + 3k_1 + k_2 s + k_1 k_2 - 2 - 2k_1 + k_2 - k_1 k_2 = 0$$

$$= s^2 + (k_1 + 3 + k_2)s + k_2 - 2 + k_1 = 0$$

Desired poles at  $-1 \pm j4$

Then we have:-

$$\Rightarrow (s+1+4j)(s+1-4j) = 0$$

$$\Rightarrow s^2 + s + 4js + s + 1 + 4j - 4js - 4j + 16$$

$$\Rightarrow s^2 + 2s + 17 = 0$$

$$\text{State equation: } \dot{\hat{x}} = (A - KC)\hat{x} + Bu + Ky$$

$$\hat{\dot{x}} = \begin{bmatrix} -9 & 10 \\ -8 & 7 \end{bmatrix} \hat{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u + \begin{bmatrix} 9 \\ +10 \end{bmatrix} y$$

$$k_1 + 3 + k_2 = 2$$

$$k_1 + k_2 = -1$$

$$2k_1 = 18$$

$$k_1 = 9$$

$$k_1 + 3 + k_2 = 17$$

$$k_1 - k_2 = 19$$

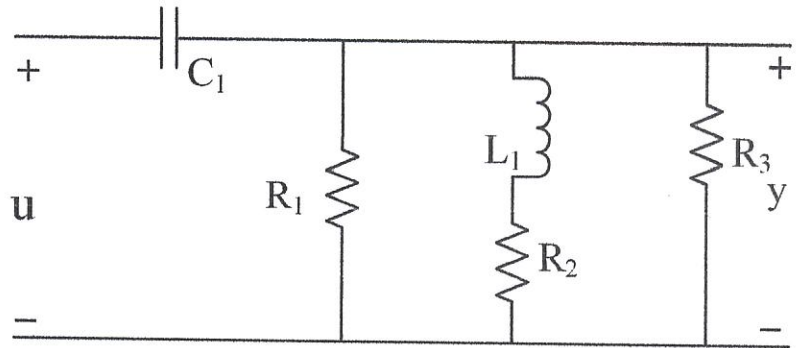
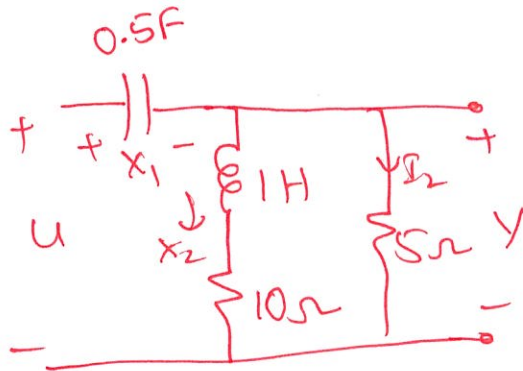
$$k_2 = 10$$

It has Unique Solution

Please show me your calculations for partial credit

(3) Find the controllability, Observability and stability of the state and output equation obtained from the following electrical circuit, take each resistance value as 10 Ohm, capacitance as 0.5F and inductance as 1H.

(25 points)



$$u = x_1 + \dot{x}_2 + 10x_2$$

$$\dot{x}_2 = -x_1 - 10x_2 + u$$

$$y = 5I_2 = \dot{x}_2 + 10x_2 =$$

$$y = u - x_1$$

$$\dot{x}_1 = \frac{1}{0.5}(x_2 + I_2)$$

$$\dot{x}_1 = 2\left(x_2 + \frac{u}{5} - \frac{x_1}{5}\right)$$

$$A = \begin{bmatrix} -\frac{2}{5} & 2 \\ -1 & -10 \end{bmatrix} \quad B = \begin{bmatrix} \frac{2}{5} \\ 1 \end{bmatrix}$$

$$C = [-1, 0] \quad D = 1$$

$$P_c = [B, AD] = \begin{bmatrix} \frac{2}{5} & \frac{46}{25} \\ 1 & -\frac{52}{5} \end{bmatrix}$$

$\det P_c \neq 0$  So Controllable

$$B = \begin{bmatrix} -1 & 0 \\ \frac{2}{5} & -1 \end{bmatrix} \quad \det P_o \neq 0 \text{ So observable}$$

$$[sI - A] = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} -\frac{2}{5} & 2 \\ -1 & -10 \end{bmatrix} = \begin{bmatrix} s + \frac{2}{5} & -2 \\ 1 & s + 10 \end{bmatrix}$$

$$\det [sI - A] = s^2 + \frac{52}{5}s + 4 - 2 = 0$$

$$s^2 + \frac{52}{5}s + 2 = 0$$

Poles must be stable poles

Please show me your calculations for partial credit

(4)  $\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$ ,  $y = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + 3u$ , Transfer the given model into Jordan form by using transformation matrix. (25 points)

$$P_c = \begin{bmatrix} B & AB \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & -3 \end{bmatrix}$$

$$P_c \neq 0.$$

$$AB = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} -\lambda & 1 \\ -2 & -3-\lambda \end{bmatrix}$$

$$= \begin{bmatrix} -\lambda & 1 \\ -2 & -3-\lambda \end{bmatrix}$$

$$|A - \lambda I| = -\lambda(-3-\lambda) + 2$$

$$= \lambda^2 + 3\lambda + 2 = 0$$

$$(\lambda + 2)(\lambda + 1) = 0$$

$$\lambda = -2, \lambda = -1$$

$$\text{If } \lambda = -1$$

$$(A - \lambda I) = \begin{bmatrix} 1 & 1 \\ -2 & -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ -2 & -2 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{21} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$v_{11} \neq v_{21} = 0$$

$$v_{11} = -v_{21}$$

$$v_{11} = 1$$

$$v_{21} = -1$$

$$\text{If } \lambda = -2$$

$$\begin{bmatrix} 2 & 1 \\ -2 & -1 \end{bmatrix} \begin{bmatrix} v_{12} \\ v_{22} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$2v_{12} + v_{22} = 0$$

$$v_{12} = 1, v_{22} = -2$$

$$T = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix} \quad T^{-1} = \frac{1}{-1} \begin{bmatrix} -2 & -1 \\ 1 & 1 \end{bmatrix}$$

$$T^{-1} = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix}$$

$$\hat{A} = T^{-1}AT = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$$

$$= \begin{bmatrix} -2 & -1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix}$$

$$\hat{B} = T^{-1}B = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\hat{C} = CT = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix} = \begin{bmatrix} -1 & -2 \end{bmatrix}$$

Please show me your calculations for partial credit