

**EE-792**

**TEST-3**

**Summer-18**

**First Name:** Solution

**Last Name:** \_\_\_\_\_

- Open text book, and closed notes. One sheet of notes (A4 size, both sides) will be allowed to the exam.
- Time for this Test is one hour thirty minutes.
- Calculators are allowed for this test (any kind)
- All work in this exam must be your own, sharing of calculators, formula sheet or text book will not be allowed.

- (1)  $\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \end{bmatrix} u, \quad y = \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  Transfer the given model into observable canonical form by using transformation matrix. (25 points)

$$\begin{aligned}
 (sI - A) &= \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} s-3 & 0 \\ 0 & s-2 \end{bmatrix} & \left| \begin{aligned} T &= P_0^{-1} \hat{P}_0 = \begin{bmatrix} -2 & 1 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 5 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix} \\ T^{-1} &= \frac{1}{3-2} \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix} \\ \hat{B} &= T^{-1} B = \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} \\ \hat{B} &= \begin{bmatrix} 1 \\ -1 \end{bmatrix} \\ \hat{C} &= \begin{bmatrix} 1 & 0 \end{bmatrix} \\ \hat{A} &= \begin{bmatrix} 5 & 1 \\ -6 & 0 \end{bmatrix} \end{aligned} \right. \\
 \det(sI - A) &= (s-3)(s-2) \\ &= s^2 - 5s + 6 = 0 \\ \hat{A} &= \begin{bmatrix} 5 & 1 \\ -6 & 0 \end{bmatrix} \quad \hat{C} = \begin{bmatrix} 1 & 0 \end{bmatrix} \\
 CA &= \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 3 & -2 \end{bmatrix} \\
 P_0 &= \begin{bmatrix} C \\ CA \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 3 & -2 \end{bmatrix} \\
 \hat{C} \hat{A} &= \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 5 & 1 \\ -6 & 0 \end{bmatrix} = \begin{bmatrix} 5 & 1 \end{bmatrix} \\
 \hat{P}_0 &= \begin{bmatrix} 1 & 0 \\ 5 & 1 \end{bmatrix} \\
 P_0^{-1} &= \frac{1}{-2+3} \begin{bmatrix} -2 & 1 \\ -3 & 1 \end{bmatrix} \\
 P_0^{-1} &= \begin{bmatrix} -2 & 1 \\ -3 & 1 \end{bmatrix} \\
 \hat{A} &= \begin{bmatrix} 5 & 1 \\ -6 & 0 \end{bmatrix}
 \end{aligned}$$

Please show me your calculations for partial credit

(2) A model has  $A = \begin{bmatrix} 0 & 1 \\ 2 & -3 \end{bmatrix}$   $B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$   $C = [1 \quad -1]$  design an observer with a desired poles at  $-1 \pm j4$  (25 points)

$$A_0 = A - KC = \begin{bmatrix} 0 & 1 \\ 2 & -3 \end{bmatrix} - \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} [1 \quad -1] = \begin{bmatrix} 0 & 1 \\ 2 & -3 \end{bmatrix} - \begin{bmatrix} k_1 & -k_1 \\ k_2 & -k_2 \end{bmatrix}$$

$$A_0 = \begin{bmatrix} -k_1 & 1+k_1 \\ 2-k_2 & k_2-3 \end{bmatrix}$$

$$(sI - A_0) = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} -k_1 & 1+k_1 \\ 2-k_2 & k_2-3 \end{bmatrix} = \begin{bmatrix} s+k_1 & -1-k_1 \\ -2+k_2 & s+3-k_2 \end{bmatrix}$$

$$\begin{aligned} \text{Det } |sI - A_0| &= \begin{bmatrix} (s+k_1)(s+3-k_2) - -(k_1+1)(k_2-2) \end{bmatrix} \\ &= \tilde{s}^2 + 3k_1 - k_1k_2 + 3s - k_2s + (k_1k_2 + k_2 - 2k_1 - 2) \\ &= \tilde{s}^2 + (3 - k_2 + k_1)s + k_1k_2 - 2 = 0 \end{aligned}$$

desired poles

$$(s+1+j4)(s+1-j4) = 0$$

$$\tilde{s}^2 + s - j4/s + s + 1 - j4 + j4/s + j4 - j16 = 0$$

$$\tilde{s}^2 + 2s + 1 + 16 = 0$$

$$\tilde{s}^2 + 2s + 17 = 0$$

$$k_1 = 9 \quad k_2 = 10$$

Please show me your calculations for partial credit

Unique solution

$$3 - k_2 + k_1 = 2$$

$$1 = k_2 - k_1$$

$$k_1 + k_2 - 2 = 17$$

$$k_1 + k_2 = 19$$

$$-k_1 + k_2 = 1$$

$$\begin{array}{r} (+) \\ \hline 2k_2 = 20 \end{array}$$

$$k_2 = 10$$

$$k_1 = 10 - 1 = 9$$

- (3)  $\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \end{bmatrix} u, \quad y = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + 3u$ , convert the given model into jordan form, also find the controllability and observability of the given model before and after transferring the model  
(25 points+ 5 bonus points)

$$P_c = \{B, AB\} = \begin{bmatrix} 2 & 1 \\ 1 & -2 \end{bmatrix}$$

$$AB = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -7 \end{bmatrix}$$

$$\det(P_c) = -14 - 1 = -15$$

it is controllable.

$$P_o = \begin{bmatrix} C \\ CA \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -2 & -2 \end{bmatrix}$$

$$CA = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} = \begin{bmatrix} -2 & -2 \end{bmatrix}$$

it is not observable

$$[A - \lambda I] = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} -\lambda & 1 \\ -2 & -3-\lambda \end{bmatrix}$$

$$\lambda(3+\lambda) + 2 = 0$$

$$\lambda = -1, -2$$

$$\text{for } \lambda = -1$$

$$\begin{bmatrix} 1 & 1 \\ -2 & -2 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$v_{11} + v_{12} = 0 \quad v_{11} = -v_{12}$$

$$v_{11} = 1 \quad v_{12} = -1$$

Please show me your calculations for partial credit

$$\hat{D} = 3$$

$$\lambda = -2$$

$$\begin{bmatrix} 2 & 1 \\ -2 & -1 \end{bmatrix}$$

$$2v_{21} + v_{22} = 0$$

$$v_{22} = -2v_{21}$$

$$v_{21} = 1 \quad v_{22} = -2$$

$$T = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$$

$$T^{-1} = \frac{1}{-1} \begin{bmatrix} -2 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix}$$

$$\hat{A} = T^{-1}AT = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$$

$$= \begin{bmatrix} -2 & -1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix}$$

$$\hat{B} = T^{-1}B = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ -3 \end{bmatrix}$$

$$\hat{C} = CT = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix} = \begin{bmatrix} 0 & -1 \end{bmatrix}$$

$$\hat{P}_c = \{\hat{D} \quad \hat{A}\hat{B}\} = \begin{bmatrix} 5 & -5 \\ -3 & 6 \end{bmatrix} \quad |P_c| \neq 0$$

$$\hat{P}_o = \begin{bmatrix} \hat{C} \\ \hat{C}\hat{A} \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 0 & 2 \end{bmatrix} \quad \hat{P}_o = 0 \quad \text{not observable}$$

controllable



- (4)  $\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$ ,  $y = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + 3u$ , Transfer the given model into Jordan form by using transformation matrix. (25 points)

$$A = \begin{pmatrix} 0 & 1 \\ -2 & -3 \end{pmatrix}$$

$A \rightarrow \lambda I$  for 3rd prob

$$T = \begin{pmatrix} 1 & 1 \\ -1 & -2 \end{pmatrix} \quad T^{-1} = \begin{pmatrix} 2 & 1 \\ -1 & -1 \end{pmatrix}$$

$$\hat{A} = \begin{pmatrix} -1 & 0 \\ 0 & -2 \end{pmatrix}$$

$$\hat{B} = T^{-1}B = \begin{pmatrix} 2 & 1 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\hat{C} = CT = \begin{pmatrix} 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & -2 \end{pmatrix} = \begin{pmatrix} -1 & -2 \end{pmatrix}$$