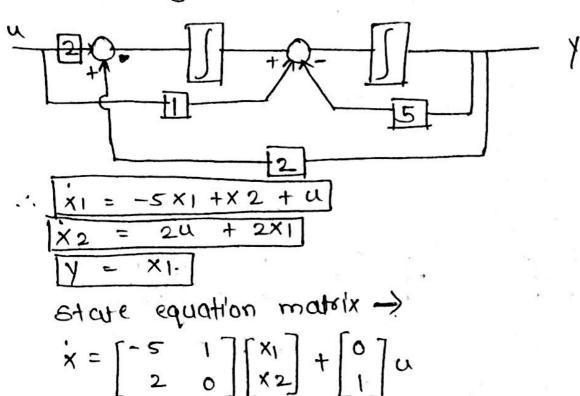
CHINMAY V MALWADE WINEAR SYSTEMS D889V695 HOMEWORK #3) y-39 -69 -99 = 24 +-4 +54 [controllable cononical = y = 20 - 0 + 50 + 34 + 64 + 94 and system concept => 24 - 4 + 54 - system - 2 We have, · Z = u + 32 + 62 + 92 Y = 22 - 2 + 52 Order of system = 3 No. of integrators = 3 = u + 6x2 + 9x1 + 3x3 = 9x1 +6x2 + 3x3 + u $y = 5x_1 + 2x_3 - x_2$ state Equation Matrix output Equation Matrix ->

2) $i_1 + si_2 - 2y = i_1 + 2u$ [observable (anonical Form). $\Rightarrow i_2 = i_1 + 2u - si_2 + 2y$ $\therefore y = \int u + 2 \int u - s \int y + 2 \int y$ order of system = 2 $\therefore \# \text{ of Integrators} = 2$.



output equation matrix
$$\rightarrow$$

 $Y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

Steel equation matrix
$$\rightarrow$$
 $\dot{x} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ 1/5 \end{bmatrix} + \begin{bmatrix} -2/9 \\ 1/5 \\ 1/5 \end{bmatrix} u$

Output equation matrix \rightarrow
 $\dot{y} = \begin{bmatrix} 1 & 0 \\ -6 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$
 $\dot{y} = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$
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 $\dot{y} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

$$\begin{array}{l} \left\{ \begin{array}{l} x_{1} \\ x_{2} \\ x_{3} \end{array} \right\} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -18 & -27 & -10 \end{array} \right] \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 \\ 0 \\ -18 & -27 & -10 \end{array} \right] \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{3} \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 \\ 0 \\ -18 & -27 & -10 \end{array} \right] \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \\ x_{3} \\ x_{4} \\ x_{5} \\ x_{$$