

1 DataStructure

1.1 treap

```

1 struct Treap
2 {
3     int pri, sz;
4     int rev;
5     ll data, sum;    // tag: make-same
6     Treap *lchild, *rchild;
7     Treap(ll d):pri(rand()), sz(1), rev(0), data(d), sum(d),
8         lchild(NULL), rchild(NULL)
9     {
10     }
11     inline void up();
12     inline void down();
13 };
14 inline int size(Treap *t) { return t? t->sz:0; }
15 inline ll get_data(Treap *t) { return t? t->data:0; }
16 inline ll get_sum(Treap *t) { return t? t->sum:0; }
17
18 inline void Treap::up()
19 {
20     if(lchild) lchild->down();
21     if(rchild) rchild->down();
22     sz = 1+size(lchild)+size(rchild);
23     sum = get_sum(lchild) + data + get_sum(rchild);
24 }
25
26 inline void Treap::down()
27 {
28     if(rev)
29     {
30         swap(mxpre, mxpost);
31         swap(lchild, rchild);
32         if(lchild) lchild->rev ^= 1;
33         if(rchild) rchild->rev ^= 1;
34         rev ^= 1;
35     }
36 }
37
38 Treap *merge(Treap *a, Treap *b)
39 {
40     if(!a || !b) return (a? a:b);
41     if(a->pri < b->pri)
42     {
43         a->down();
44         a->rchild = merge(a->rchild, b);
45         a->up();
46         return a;
47     }
48     else
49     {
50         b->down();
51         b->lchild = merge(a, b->lchild);
52         b->up();
53         return b;
54     }
55 }
56
57 void split(Treap *o, Treap *&a, Treap *&b, int k)
58 {

```

```

59     if(!o) a = b = NULL;
60     else
61     {
62         o->down();
63         if(k >= size(o->lchild)+1)
64         {
65             a = o;
66             split(o->rchild, a->rchild, b, k-size(o->lchild)-1);
67         }
68         else
69         {
70             b = o;
71             split(o->lchild, a, b->lchild, k);
72         }
73         o->up();
74     }
75 }

```

1.2 disjoint_set

```

1 // path compression
2 int f[N];
3
4 int findrt(int x)
5 {
6     if(f[x] == x) return x;
7     else return f[x] = findrt(f[x]);
8 }
9
10 int same(int x, int y)
11 {
12     return findrt(x) == findrt(y);
13 }
14
15 void uni(int x, int y)
16 {
17     f[findrt(y)] = findrt(x);
18 }
19
20 void init()
21 {
22     for(int i = 0; i < N; i++) f[i] = i;
23 }
24
25 //union by rank
26 int f[N]; //disjoint set
27 int rk[N]; //union by rank
28
29 int findrt(int x)
30 {
31     if(f[x] == x) return x;
32     else return f[x] = findrt(f[x]);
33 }
34
35 bool same(int x, int y)
36 {
37     return findrt(x) == findrt(y);
38 }
39
40 void uni(int x, int y)
41 {
42     x = findrt(x), y = findrt(y);

```

```

43     if(x == y) return;
44     if(rk[x] < rk[y]) f[x] = y;
45     else if(rk[x] == rk[y]) f[x] = y, rk[y]++;
46     else f[y] = x;
47 }
48
49 void init()
50 {
51     for(int i = 0; i < N; i++) f[i] = i, rk[i] = 0;
52 }

```

1.3 2d_st_tag

```

1 //二維陣列單點查詢區間加值
2 class St1d
3 {
4 private:
5     ll st[4*N];
6
7 public:
8     void build();
9     void modify(int l, int r, int idx, int L, int R, ll v);
10    ll query(int l, int r, int idx, int x);
11    void down(int idx);
12 };
13
14 void St1d::build()
15 {
16     memset(st, 0, sizeof(st));
17 }
18
19 void St1d::modify(int l, int r, int idx, int L, int R, ll v)
20 {
21     if(r < L || R < l) return;
22     if(L <= l && r <= R)
23     {
24         st[idx] += v;
25         return;
26     }
27     assert(l != r);
28     down(idx);
29     int mid = (l+r)/2;
30     modify(l, mid, idx*2, L, R, v);
31     modify(mid+1, r, idx*2+1, L, R, v);
32 }
33
34 ll St1d::query(int l, int r, int idx, int x)
35 {
36     if(x < l || r < x) return 0;
37     if(l == x && r == x) return st[idx];
38     down(idx);
39     int mid = (l+r)/2;
40     ll left = query(l, mid, idx*2, x);
41     ll right = query(mid+1, r, idx*2+1, x);
42     return left+right;
43 }
44
45 void St1d::down(int idx)
46 {
47     st[idx*2] += st[idx], st[idx*2+1] += st[idx];
48     st[idx] = 0;
49 }
50

```

```

51 //////////////////////////////////////////////////
52
53 class St2d
54 {
55 private:
56     St1d st[4*N];
57
58 public:
59     void build(int il, int ir, int idx);
60     void modify(int il, int ir, int jl, int jr, int idx, int
        iL, int iR, int jL, int jR, ll v);
61     ll query(int il, int ir, int jl, int jr, int idx, int i,
        int j);
62 };
63
64 void St2d::build(int il, int ir, int idx)
65 {
66     st[idx].build();
67     if(il == ir) return;
68     int mid = (il+ir)/2;
69     build(il, mid, idx*2);
70     build(mid+1, ir, idx*2+1);
71 }
72
73 void St2d::modify(int il, int ir, int jl, int jr, int idx,
        int iL, int iR, int jL, int jR, ll v)
74 {
75     if(ir < iL || iR < iL) return;
76     if(iL <= iL && iR <= iR)
77     {
78         st[idx].modify(jl, jr, 1, jL, jR, v); return;
79     }
80     int mid = (il+ir)/2;
81     modify(il, mid, jl, jr, idx*2, iL, iR, jL, jR, v);
82     modify(mid+1, ir, jl, jr, idx*2+1, iL, iR, jL, jR, v);
83 }
84
85 ll St2d::query(int il, int ir, int jl, int jr, int idx, int i
        , int j)
86 {
87     ll tot = 0;
88     if(i < iL || iR < i) return 0;
89     if(iL <= i && i <= iR) tot += st[idx].query(jl, jr, 1, j)
        ;
90     if(il == i && ir == i) return tot;
91     int mid = (il+ir)/2;
92     tot += query(il, mid, jl, jr, idx*2, i, j);
93     tot += query(mid+1, ir, jl, jr, idx*2+1, i, j);
94     return tot;
95 }

```

1.4 BIT

```

1 #define lowbit(x) x&-x
2
3 int arr[N]; //紀錄前綴和
4 int bit[N];
5
6 void conv(int a[], int n) //離散化
7 {
8     vector<int> tmp;
9     for(int i = 1; i <= n; i++) tmp.push_back(a[i]);

```

```

10     sort(tmp.begin(), tmp.end());
11     for(int i = 1; i <= n; i++) a[i] = lower_bound(tmp.begin
        (), tmp.end(), a[i]) - tmp.begin() + 1;
12 }
13
14 void buildbit() //每個bit[x]紀錄[x-lowbit(x)+1, x]的總和
15 {
16     for(int i = 0; i < n; i++) bit[i] = arr[i]-arr[i-lowbit(i
        )];
17 }
18
19 int sum(int x) //查詢[1,x]的總和
20 {
21     int rtn = 0;
22     for(;x;x-=lowbit(x)) rtn += bit[x];
23     return rtn;
24 }
25
26 void modify(int x, int d) //把位置x的東西加上d
27 {
28     for(;x<=n;x+=lowbit(x)) bit[x] += d;
29 }

```

1.5 1d_segTree_tag

```

1 //線段樹懶人標記：一維陣列區間加值區間乘值區間查詢總和
2 struct Node //data = data*mul+add;
3 {
4     ll data, mul, add;
5 };
6
7 ll getval(int l, int r, int idx)
8 {
9     return (st[idx].data*st[idx].mul%MD+(r-l+1)*st[idx].add%
        MD)%MD;
10 }
11
12 void up(int l, int r, int idx)
13 {
14     int mid = 1+(r-1)/2;
15     st[idx].data = (getval(l, mid, idx*2)+getval(mid+1, r,
        idx*2+1))%MD;
16 }
17
18 void down(int l, int r, int idx)
19 {
20     st[idx].data = getval(l, r, idx);
21     int lson = idx*2, rson = idx*2+1;
22     if(l != r)
23     {
24         st[lson].mul = st[lson].mul*st[idx].mul%MD;
25         st[lson].add = (st[lson].add*st[idx].mul+st[idx].add)
            %MD;
26         st[rson].mul = st[rson].mul*st[idx].mul%MD;
27         st[rson].add = (st[rson].add*st[idx].mul+st[idx].add)
            %MD;
28     }
29     st[idx].mul = 1, st[idx].add = 0;
30 }
31
32 void buildst(int l, int r, int idx)
33 {

```

```

34     st[idx].mul = 1, st[idx].add = 0;
35     if(l == r)
36     {
37         st[idx].data = arr[l];
38         return;
39     }
40     int mid = 1+(r-1)/2;
41     buildst(l, mid, idx*2);
42     buildst(mid+1, r, idx*2+1);
43     up(l, r, idx);
44 }
45
46 void add(int l, int r, int idx, int L, int R, int v) //操作L,
        R
47 {
48     if(r < L || R < l) return;
49     if(L <= l && r <= R)
50     {
51         st[idx].add = (st[idx].add+v)%MD;
52         return;
53     }
54     down(l, r, idx);
55     int mid = 1+(r-1)/2;
56     add(l, mid, idx*2, L, R, v);
57     add(mid+1, r, idx*2+1, L, R, v);
58     up(l, r, idx);
59 }
60
61 void mul(int l, int r, int idx, int L, int R, int v)
62 {
63     if(r < L || R < l) return;
64     if(L <= l && r <= R)
65     {
66         st[idx].add = st[idx].add*v%MD;
67         st[idx].mul = st[idx].mul*v%MD;
68         return;
69     }
70     down(l, r, idx);
71     int mid = 1+(r-1)/2;
72     mul(l, mid, idx*2, L, R, v);
73     mul(mid+1, r, idx*2+1, L, R, v);
74     up(l, r, idx);
75 }
76
77 ll query(int l, int r, int idx, int L, int R)
78 {
79     if(r < L || R < l) return 0;
80     if(L <= l && r <= R)
81     {
82         return getval(l, r, idx);
83     }
84     down(l, r, idx);
85     int mid = 1+(r-1)/2;
86     return (query(l, mid, idx*2, L, R)+query(mid+1, r, idx
        *2+1, L, R))%MD;
87 }

```

1.6 1d_segTree

```

1 void buildst(int l, int r, int idx) //1, r是st的區間
2 {
3     if(l == r)

```

```

4   {
5       st[idx] = arr[l];
6       return;
7   }
8   int mid = (l+r)/2;
9   buildst(l, mid, idx*2);
10  buildst(mid+1, r, idx*2+1);
11  st[idx] = max(st[idx*2], st[idx*2+1]);
12 }
13
14 ll query(int l, int r, int idx, int L, int R) //L,R是操作的
   區間
15 {
16     if(r < L || R < l) return -INF;
17     if(L <= l && r <= R) return st[idx];
18     int mid = (l+r)/2;
19     return max(query(l, mid, idx*2, L, R), query(mid+1, r,
20         idx*2+1, L, R));
21 }
22 void modify(int l, int r, int idx, int x, int v)
23 {
24     if(r < x || x < l) return;
25     if(l == r)
26     {
27         st[idx] += v; return;
28     }
29     int mid = (l+r)/2;
30     modify(l, mid, idx*2, x, v);
31     modify(mid+1, r, idx*2+1, x, v);
32     st[idx] = max(st[idx*2], st[idx*2+1]);
33 }

```

1.7 Matrix

```

1 ll SZ,MOD;
2 const int MAXSZ=105;
3
4 struct Mat
5 {
6     ll m[MAXSZ][MAXSZ];
7     Mat(){memset(m, 0, sizeof(m));}
8 };
9
10 Mat matMul(const Mat &A, const Mat &B)
11 {
12     Mat rtn;
13     for(int i = 0; i < SZ; i++)
14         for(int k = 0; k < SZ; k++)
15             if(A.m[i][k])for(int j = 0; j < SZ; j++)
16             {
17                 rtn.m[i][j] += (A.m[i][k]*B.m[k][j]);
18             }
19     return rtn;
20 }
21 //B is of size SZ
22 vector<ll> matMul(const Mat &A, const vector<ll> &B)
23 {
24     vector<ll> rtn(SZ,0);
25     for(int i = 0; i < SZ; i++)
26         for(int j = 0; j < SZ; j++)
27             rtn[i] = (rtn[i]+A.m[i][j]*B[j]);

```

```

28     return rtn;
29 }
30 }
31
32 Mat matPow(Mat& M, ll p)
33 {
34     if(p == 0)
35     {
36         Mat iden;
37         for(int i=0;i<SZ;i++)iden.m[i][i]=1;
38         return iden;
39     }
40     if(p == 1)return M;
41     Mat rtn = matPow(M, p/2);
42     if(p&1)return matMul(matMul(rtn, rtn), M);
43     else return matMul(rtn, rtn);
44 }

```

1.8 undo_disjoint_set

```

1 struct DisjointSet {
2     // save() is like recursive
3     // undo() is like return
4     int n, fa[MXN], sz[MXN];
5     vector<pair<int*,int>> h;
6     vector<int> sp;
7     void init(int tn) {
8         n=tn;
9         for (int i=0; i<n; i++) sz[fa[i]=i]=1;
10        sp.clear(); h.clear();
11    }
12    void assign(int *k, int v) {
13        h.PB({k, *k});
14        *k=v;
15    }
16    void save() { sp.PB(SZ(h)); }
17    void undo() {
18        assert(!sp.empty());
19        int last=sp.back(); sp.pop_back();
20        while (SZ(h)!=last) {
21            auto x=h.back(); h.pop_back();
22            *x.F=x.S;
23        }
24    }
25    int f(int x) {
26        while (fa[x]!=x) x=fa[x];
27        return x;
28    }
29    void uni(int x, int y) {
30        x=f(x); y=f(y);
31        if (x==y) return ;
32        if (sz[x]<sz[y]) swap(x, y);
33        assign(&sz[x], sz[x]+sz[y]);
34        assign(&fa[y], x);
35    }
36 }djs;

```

2 Flow

2.1 dinic

```

1 template<typename T>
2 struct DINIC{
3     static const int MAXN=105;
4     static const T INF=INT_MAX;
5     int n, level[MAXN], cur[MAXN];
6     struct edge{
7         int v,pre;
8         T cap,flow,r;
9         edge(int v,int pre,T cap):v(v),pre(pre),cap(cap),flow(0),
10             r(cap){}
11     };
12     int g[MAXN];
13     vector<edge> e;
14     void init(int _n){
15         memset(g,-1,sizeof(int)*(n=_n)+1));
16         e.clear();
17     }
18     void add_edge(int u,int v,T cap,bool directed=false){
19         e.push_back(edge(v,g[u],cap));
20         g[u]=e.size()-1;
21         e.push_back(edge(u,g[v],directed?0:cap));
22         g[v]=e.size()-1;
23     }
24     int bfs(int s,int t){
25         memset(level,0,sizeof(int)*(n+1));
26         memcpy(cur,g,sizeof(int)*(n+1));
27         queue<int> q;
28         q.push(s);
29         level[s]=1;
30         while(q.size()){
31             int u=q.front();q.pop();
32             for(int i=g[u];~i;i=e[i].pre){
33                 if(!level[e[i].v]&&e[i].r){
34                     level[e[i].v]=level[u]+1;
35                     q.push(e[i].v);
36                     if(e[i].v==t)return 1;
37                 }
38             }
39         }
40         return 0;
41     }
42     T dfs(int u,int t,T cur_flow=INF){
43         if(u==t)return cur_flow;
44         T df;
45         for(int &i=cur[u];~i;i=e[i].pre){
46             if(level[e[i].v]==level[u]+1&&e[i].r){
47                 if(df=dfs(e[i].v,t,min(cur_flow,e[i].r)))
48                     e[i].flow+=df;
49                 e[i^1].flow-=df;
50                 e[i].r-=df;
51                 e[i^1].r+=df;
52                 return df;
53             }
54         }
55         return level[u]=0;
56     }
57     T dinic(int s,int t,bool clean=true){
58         if(clean){

```

```

59     for(size_t i=0;i<e.size();++i){
60         e[i].flow=0;
61         e[i].r=e[i].cap;
62     }
63 }
64 T ans=0, mf=0;
65 while(bfs(s,t))while(mf=dfs(s,t))ans+=mf;
66 return ans;
67 }
68 };

```

2.2 MaxDensitySubgraph

```

1  #include<stdio.h>
2  #include<string.h>
3  const int N=1500;
4  const double inf=0x3fffffff;
5  const double eps=1e-8;
6  int gap[N],dis[N],start,end,ans,sum,head[N],num,dep[N],n,m;
7  bool vis[N];
8  struct edge
9  {
10     int st,ed,next;
11     double flow;
12 }e[80*N];
13 struct node
14 {
15     int x,y;
16 }P[1100];
17 void addedge(int x,int y,double w)
18 {
19     e[num].st=x,e[num].ed=y,e[num].flow=w,e[num].next=head[x];
20     head[x]=num++;
21     e[num].st=y,e[num].ed=x,e[num].flow=0,e[num].next=head[y];
22     head[y]=num++;
23 }
24 void makemap(double g)
25 {
26     int i;
27     memset(head,-1,sizeof(head));
28     num=0;
29     for(i=1;i<=n;i++)
30         addedge(i,end,g);
31     for(i=0;i<m;i++)
32     {
33         addedge(n+i+1,P[i].y,inf);
34         addedge(n+i+1,P[i].x,inf);
35         addedge(start,n+i+1,1.0);
36     }
37 }
38 double dfs(int u,double minflow)
39 {
40     if(u==end)return minflow;
41     int i,v;
42     double f,flow=0.0;
43     for(i=head[u];i!=-1;i=e[i].next)
44     {
45         v=e[i].ed;
46         if(e[i].flow>0)
47             if(dis[v]+1==dis[u])

```

```

48         f=dfs(v,e[i].flow>minflow-flow?minflow-flow:e111
49             [i].flow);
50         flow+=f;
51         e[i].flow-=f;
52         e[i^1].flow+=f;
53         if(minflow-flow<=1e-8)return flow;
54         if(dis[start]>=ans)return flow;
55     }
56 }
57 if(--gap[dis[u]]==0)
58     dis[start]=ans;
59     dis[u]++;
60     gap[dis[u]]++;
61     return flow;
62 }
63 double isap()
64 {
65     double maxflow=0.0;
66     memset(gap,0,sizeof(gap));
67     memset(dis,0,sizeof(dis));
68     gap[0]=ans;
69     while(dis[start]<ans)
70         maxflow+=dfs(start,inf);
71     return 1.0*m-maxflow;
72 }
73 void dfs1(int u)
74 {
75     vis[u]=true;
76     if(u>=1&&u<=n)
77         sum++;
78     for(int i=head[u];i!=-1;i=e[i].next)
79     {
80         int v=e[i].ed;
81         if(vis[v]==false&&e[i].flow>0)
82             dfs1(v);
83     }
84 }
85 int main()
86 {
87     int i;
88     double Left,Right,mid,flow;
89     while(scanf("%d%d",&n,&m)!=-1)
90     {
91         if(m==0){printf("1\n1\n");continue;}
92         start=0,end=n+m+1,ans=end+1;
93         for(i=0;i<m;i++)
94         {
95             scanf("%d%d",&P[i].x,&P[i].y);
96         }
97         Left=0;Right=m;
98         while(Right-Left>=1.0/n)//胡伯涛的论文给出了证明,不同解
99             之间误差的精度不超过1/(n*n)
100     {
101         mid=(Left+Right)/2;
102         makemap(mid);
103         flow=isap();
104         if(flow<eps)//求出最大权值闭回路
105             if(flow<eps)//如果小于0·g值太大
106                 Right=mid;
107             else Left=mid;
108     }
109     makemap(Left);
110     isap();
111     memset(vis,false,sizeof(vis));
112     sum=0;

```

```

111     dfs1(start);
112     printf("%d\n",sum);
113     for(i=1;i<=n;i++)
114         if(vis[i]==true)//残留网络中源点能到达的点
115             printf("%d\n",i);
116 }
117 return 0;
118 }

```

2.3 MinCostMaxFlow

```

1  template<typename TP>
2  struct MCMF{
3      static const int MAXN=440;
4      static const TP INF=999999999;
5      struct edge{
6          int v,pre;
7          TP r,cost;
8          edge(int v,int pre,TP r,TP cost):v(v),pre(pre),r(r),cost(cost){}
9      };
10     int n,S,T;
11     TP dis[MAXN],PIS,ans;
12     bool vis[MAXN];
13     vector<edge> e;
14     int g[MAXN];
15     void init(int _n){
16         memset(g,-1,sizeof(int)*(n=_n+1));
17         e.clear();
18     }
19     void add_edge(int u,int v,TP r,TP cost,bool directed=false)
20     {
21         e.push_back(edge(v,g[u],r,cost));
22         g[u]=e.size()-1;
23         e.push_back(
24             edge(u,g[v],directed?0:r,-cost));
25         g[v]=e.size()-1;
26     }
27     TP augment(int u,TP CF){
28         if(u==T||!CF)return ans+=PIS*CF,CF;
29         vis[u]=1;
30         TP r=CF,d;
31         for(int i=g[u];~i;i=e[i].pre){
32             if(e[i].r&&e[i].cost&&!vis[e[i].v]){
33                 d=augment(e[i].v,min(r,e[i].r));
34                 e[i].r-=d;
35                 e[i^1].r+=d;
36                 if(!(r=d))break;
37             }
38         }
39         return CF-r;
40     }
41     bool modlabel(){
42         for(int u=0;u<=n;u++)dis[u]=INF;
43         static deque<int>q;
44         dis[T]=0,q.push_back(T);
45         while(q.size()){
46             int u=q.front();q.pop_front();
47             TP dt;
48             for(int i=g[u];~i;i=e[i].pre){
49                 if(e[i^1].r&&(dt=dis[u]-e[i].cost)<dis[e[i].v]){
50                     if((dis[e[i].v]=dt)<=dis[q.size()?q.front():S]){
51                         q.push_front(e[i].v);
52                     }
53                 }
54             }
55         }
56     }
57 }

```

```

51         }else q.push_back(e[i].v);
52     }
53 }
54 }
55 for(int u=0;u<=n;++u)
56     for(int i=g[u];~i;i=e[i].pre)
57         e[i].cost+=dis[e[i].v]-dis[u];
58 return PIS+=dis[S], dis[S]<INF;
59 }
60 TP mincost(int s,int t){
61     S=s,T=t;
62     PIS=ans=0;
63     while(modlabel()){
64         do memset(vis,0,sizeof(bool)*(n+1));
65         while(augment(S,INF));
66     }return ans;
67 }
68 };

```

3 Geometry

3.1 nearestDist

```

1 bool cmp_y(P a, P b)
2 {
3     return a.y < b.y;
4 }
5
6 bool cmp_x(P a, P b)
7 {
8     return a.x < b.x;
9 }
10
11 double dc(P *arr, int n)
12 {
13     if(n == 1) return INF;
14     int mid = n/2;
15     double cx = arr[mid].x;
16     double dist = min( dc(arr, mid), dc(arr+mid, n-mid) );
17     inplace_merge(arr, arr+mid, arr+n, cmp_y);
18     static vector<P> brr; brr.clear();
19     for(int i = 0; i < n; i++)
20     {
21         if(fabs(arr[i].x)-cx >= dist) continue;
22         for(int j = brr.size()-1; j >= 0; j--)
23         {
24             double dx = brr[j].x-arr[i].x;
25             double dy = brr[j].y-arr[i].y;
26             if(fabs(dy) >= dist) break;
27             dist = min(dist, sqrt(dx*dx+dy*dy));
28         }
29         brr.push_back(arr[i]);
30     }
31     return dist;
32 }
33
34 double nearestDist(P *arr, int n)
35 {
36     sort(arr, arr+n, cmp_x);
37     return dc(arr, n);
38 }

```

3.2 SegmentGeometry

```

1 double EPS = 1e-10;
2
3 double add(double a, double b)
4 {
5     if(fabs(a+b)<EPS*(fabs(a)+fabs(b))) return 0;
6     else return a+b;
7 }
8
9 struct P//struct for 2d vector/point
10 {
11     double x,y;
12     P() {}
13     P(double x, double y):x(x),y(y) {}
14     P operator+(P p){return P(add(x,p.x), add(y,p.y));}
15     P operator-(P p){return P(add(x,-p.x), add(y,-p.y));}
16     P operator*(double d){return P(x*d,y*d);}
17     double dot(P p){return add( x*p.x, y*p.y );}
18     double det(P p){return add( x*p.y, -y*p.x );}
19 };
20
21 //is point q on p1p2
22 bool on_seg(P p1, P p2, P q){return (p1-q).det(p2-q)==0&&(p1-q).dot(p2-q)<=0;}
23
24 P intersection(P p1, P p2, P q1, P q2)//p and q Must not be parallel
25 {return p1 + (p2-p1)*((q2-q1).det(q1-p1)/(q2-q1).det(p2-p1));}
26
27 bool par(P p1, P p2, P p3, P p4){return (p2-p1).det(p4-p3)==0;}
28
29 bool operator<(const P& lhs, const P& rhs)
30 {return (lhs.x==rhs.x)?lhs.y<rhs.y:lhs.x<rhs.x;}
31
32 bool operator==(const P& lhs, const P& rhs)
33 {return lhs.x==rhs.x&&lhs.y==rhs.y;}
34
35 double len(P vec)
36 {return sqrt(add(vec.x*vec.x, vec.y*vec.y));}
37
38 double dis(P p1, P p2)
39 {return len(p2-p1);}
40
41 struct seg
42 {
43     seg() {}
44     seg(P _p1, P _p2)
45     {
46         p[0]=_p1;
47         p[1]=_p2;
48         if(p[1]<p[0])swap(p[0],p[1]);
49     }
50     P p[2];
51 };
52
53 bool par(seg& lhs, seg& rhs)
54 {return par(lhs.p[0],lhs.p[1],rhs.p[0],rhs.p[1]);}
55
56 P intersection(seg& lhs, seg& rhs)//p and q Must not be parallel
57 {return intersection(lhs.p[0],lhs.p[1],rhs.p[0],rhs.p[1]);}
58

```

```

59 bool on_seg(seg& sg, P q)
60 {return on_seg(sg.p[0],sg.p[1],q);}
61
62 bool overlap(seg s1, seg s2)
63 {
64     return par(s1,s2)&&
65     ( on_seg(s1,s2.p[0])||on_seg(s1,s2.p[1])||
66     on_seg(s2,s1.p[0])||on_seg(s2,s1.p[1]) );
67 }
68
69 bool is_intersect(seg s1, seg s2)
70 {
71     if(par(s1,s2))return false;
72     P p0 = intersection(s1,s2);
73     return on_seg(s1,p0)&&on_seg(s2,p0);
74 }
75
76 //make sure the vec is not vertical
77 double interpolate(seg& vec, double X)
78 {
79     double y0=vec.p[0].y,y1=vec.p[1].y,
80     x0=vec.p[0].x,x1=vec.p[1].x;
81     return y0+(y1-y0)*(X-x0)/(x1-x0);
82 }
83
84 //pts in clockwise order, p[N]=p[0]
85 bool in_poly(P* pol,int N,P pt)
86 {
87     double X = pt.x,Y=pt.y;
88     int pas=0;
89     for(int i=0;i<N;i++)
90     {
91         if(pol[i].x==pol[i+1].x)continue;
92         seg s0(pol[i],pol[i+1]);
93         //up or down?
94         double Y1 = interpolate(s0,X);
95         if(Y1<Y-EPS)continue;
96         double x1=min(pol[i].x,pol[i+1].x),xr=max(pol[i].x,
97             pol[i+1].x);
98         if(x1<X-EPS&&xr>X-EPS)pas++;
99     }
100     return pas&1;
101 }
102
103 double dpseg(P p, P p1, P p2)//p to p1p2, p1!=p2
104 {
105     P v=p2-p1, v1=p-p1, v2=p-p2;
106     if( v.dot(v1) < EPS )return dis(p,p1);
107     if( v.dot(v2) > EPS )return dis(p,p2);
108     return fabs((p-p1).det(v))/len(v);
109 }
110
111 double dpseg(P p, seg s1)
112 {
113     return dpseg(p,s1.p[0],s1.p[1]);
114 }
115
116 double dsegseg(P p1, P p2, P p3, P p4)
117 {
118     if( is_intersect( seg(p1,p2), seg(p3,p4) ) )return 0;
119     return min( min( dpseg(p1,p3,p4),dpseg(p2,p3,p4) ), min(
120         dpseg(p3,p1,p2),dpseg(p4,p1,p2) ) );
121 }
122
123 double dsegseg(seg s1, seg s2)
124 {

```

```

123     return dsegseg( s1.p[0],s1.p[1],s2.p[0],s2.p[1] );
124 }

```

4 Graph

4.1 floyd_warshall

```

1 int d[N][N];
2
3 void init()
4 {
5     for(int i = 0; i < v; i++)
6         for(int j = 0; j < v; j++)
7             if(i == j) d[i][j] = 0;
8             else d[i][j] = INF;
9 }
10
11 void floyd_warshall()
12 {
13     for(int k = 0; k < v; k++)
14         for(int i = 0; i < v; i++)
15             for(int j = 0; j < v; j++)
16                 if(d[i][k] != INF && d[k][j] != INF)
17                     d[i][j] = min(d[i][j], d[i][k] + d[k][j]);
18 }

```

4.2 mst_prim

```

1 int cost[100][100];
2 bool used[100];
3 int mincost[100];
4 int v, e;
5 #define INF 2147483647
6
7 int prim()
8 {
9     for(int i = 0; i < v; i++)
10     {
11         mincost[i] = INF;
12         used[i] = false;
13     }
14     mincost[0] = 0;
15     int res = 0;
16
17     while(true)
18     {
19         int x = -1;
20         for(int u = 0; u < v; u++)
21             if(!used[u] && (x == -1 || mincost[u] < mincost[x])) x = u;
22
23         if(x == -1) break;
24         used[x] = true;
25         res += mincost[x];
26
27         for(int u = 0; u < v; u++)
28             mincost[u] = min(mincost[u], cost[x][u]);

```

```

29     }
30     return res;
31 }
32
33 void init()
34 {
35     for(int i = 0; i < v; i++)
36         for(int j = 0; j < v; j++)
37             if(i == j) cost[i][j] = 0;
38             else cost[i][j] = INF;
39 }

```

4.3 HeavyLightDecomposition

```

1 const int MAX_N;
2 vector<int> link[MAX_N]; //edge
3
4 void dfs_build(int now, int fa, int *weight, int *depth, int *pa, int *son)
5 {
6     weight[now]=1;
7     son[now]=-1;
8     pa[now]=fa;
9     for(auto i:link[now])
10     {
11         if(i==fa) continue;
12         depth[i]=depth[now]+1;
13         dfs_build(i,now,weight,depth,pa,son);
14         if(son[now]==-1 || weight[son[now]] < weight[i]) son[now]=i;
15         weight[now]+=weight[i];
16     }
17 }
18 void build_top(int now, int top, int *pa, int *son, int *link_top)
19 {
20     link_top[now]=top;
21     if(son[now]==-1) return;
22     build_top(son[now],top,pa,son,link_top);
23     for(auto i:link[now])
24     {
25         if(i==son[now] || i==pa[now]) continue;
26         build_top(i,i,pa,son,link_top);
27     }
28 }
29 inline void HLD(int *weight, int *depth, int *pa, int *son, int *link_top)
30 {
31     memset(son,-1,sizeof(int)*MAX_N);
32     depth[1]=1; //set node(1) as root
33     dfs_build(1,0,weight,depth,pa,son);
34     build_top(1,1,pa,son,link_top);
35 }
36 inline int find_lca(int x, int y, int *depth, int *pa, int *link_top)
37 {
38     int tx=link_top[x], ty=link_top[y];
39     while(tx!=ty)
40     {
41         if(depth[tx]<depth[ty])
42         {
43             swap(tx,ty);
44             swap(x,y);
45         }

```

```

46     tx=link_top[x=pa[x]];
47 }
48 return depth[x]<depth[y]?x:y;
49 }
50 //usage:
51 //build HeavyLightDecomposition: HLD
52 //find LCA(x,y): find_lca

```

4.4 匹配問題轉換

4.4.1 一般圖匹配問題轉換

1. 最大匹配邊數 $|+|$ 最小邊涵蓋 $=|V|$ (無孤立點)
2. 最大獨立集 $|+|$ 最小點涵蓋 $=|V|$
3. 最大權匹配-> 最大權完美匹配: 用 0 邊補成完全圖
4. 最大權最大匹配-> 最大權匹配: 先把所有邊加上 | 最負邊權重 $+1$, 得到新的圖 G' 上沒有任何負邊, 然後所有邊再加上 G' 上所有邊權重和, 這樣最大權匹配就會 = 最大權最大匹配.

4.5 TarjanBridge

```

1 void tarjan(int u, int p) { // p -> u
2     dfn[u] = low[u] = ++tim;
3
4     for(auto v: G[u]) { //u->v
5         if(!dfn[v]) {
6             tarjan(v, u);
7             low[u] = min(low[u], low[v]);
8             if(low[v] > dfn[u]) {
9                 ans++;
10                E.push_back(edge(u, v));
11            }
12        }
13        else if(v != p)
14            low[u] = min(low[u], dfn[v]);
15    }
16 }
17
18 struct edge {
19     int from, to;
20     edge(int u, int v): from(u), to(v) {}
21 };
22
23 for(int i=0; i<n; i++)
24     if(!dnf[i])
25         tarjan(i, -1);

```

4.6 BridgeConnected

```

1 struct edge {
2     int from, to;
3     edge(int u, int v): from(u), to(v) {}
4 };
5 vector<edge> bridge;
6 vector<int> G[MAXN];
7 int dfn[MAXN], low[MAXN], tim;
8 int bccID[MAXN], bccCNT;
9 int st[MAXN], top;

```

```

10 void tarjan(int u, int p){ // p->u
11     dfn[u]= low[u]= ++tim;
12     st[top++]=u;
13     for(auto v:G[u]){ // u->v
14         if(!dfn[v]){
15             tarjan(v, u);
16             low[u]= min(low[u], low[v]);
17             if(low[v] > dfn[u])
18                 bridge.push_back(edge(u, v));
19         }
20     }
21     else if(v != p)
22         low[u]= min(low[u], dfn[v]);
23 }
24
25 if(dfn[u] == low[u]){
26     int w;
27     do{
28         w= st[--top];
29         bccID[w]= bccCNT;
30     }while(w != u);
31     bccCNT++;
32 }
33 }

```

4.7 mst_kruskal

```

1 struct edge { int u, v, cost; };
2
3 bool comp(const edge& e1, const edge& e2)
4 {
5     return e1.cost < e2.cost;
6 }
7
8 int kruskal()
9 {
10     sort(es, es + e, comp);
11     dset s(v);
12     int res = 0;
13     for(int i = 0; i < e; i++)
14     {
15         edge E = es[i];
16         if(s.Find(E.u) != s.Find(E.v))
17         {
18             s.Union(E.u, E.v);
19             res += E.cost;
20         }
21     }
22     return res;
23 }

```

4.8 bellman_Ford

```

1 struct edge{ int from, to, cost; };
2 #define INF 2147483647
3
4 edge es[100];
5
6 int d[100]; //min distance
7 int V, E, s, f;

```

```

8
9 bool bellman_ford() // return true if there is negative loop
10 {
11     for(int i = 0; i < V; i++) d[i] = INF;
12     d[s] = 0;
13
14     for(int i = 0; i < V; i++)
15     {
16         for(int j = 0; j < E; j++)
17         {
18             edge e = es[j];
19             if(d[e.from] != INF && d[e.to] > d[e.from] + e.
20                 cost)
21             {
22                 d[e.to] = d[e.from] + e.cost;
23                 if(i == V - 1) return true; //got neg loop
24             }
25             if(d[e.to] != INF && d[e.from] > d[e.to] + e.cost
26                 )
27             {
28                 d[e.from] = d[e.to] + e.cost;
29                 if(i == V - 1) return true; //got neg loop
30             }
31         }
32     }
33     return false;
34 }

```

4.9 MaxWeightPerfectMatch

```

1 struct Graph {
2     // Minimum General Weighted Matching (Perfect Match) 0-base
3     static const int MXN = 105;
4     int n, edge[MXN][MXN];
5     int match[MXN], dis[MXN], onstk[MXN];
6     vector<int> stk;
7     void init(int _n) {
8         n = _n;
9         for (int i=0; i<n; i++)
10             for (int j=0; j<n; j++)
11                 edge[i][j] = 0;
12     }
13     void add_edge(int u, int v, int w) {
14         edge[u][v] = edge[v][u] = w;
15     }
16     bool SPFA(int u) {
17         if (onstk[u]) return true;
18         stk.push_back(u);
19         onstk[u] = 1;
20         for (int v=0; v<n; v++){
21             if (u != v && match[u] != v && !onstk[v]){
22                 int m = match[v];
23                 if (dis[m] > dis[u] - edge[v][m] + edge[u][v]){
24                     dis[m] = dis[u] - edge[v][m] + edge[u][v];
25                     onstk[v] = 1;
26                     stk.push_back(v);
27                     if (SPFA(m)) return true;
28                     stk.pop_back();
29                     onstk[v] = 0;
30                 }
31             }
32         }
33         onstk[u] = 0;
34     }
35 }

```

```

34     stk.pop_back();
35     return false;
36 }
37
38 int solve() {
39     // find a match
40     for (int i=0; i<n; i+=2){
41         match[i] = i+1, match[i+1] = i;
42     }
43     for(;;){
44         int found = 0;
45         for (int i=0; i<n; i++) dis[i] = onstk[i] = 0;
46         for (int i=0; i<n; i++){
47             stk.clear();
48             if (!onstk[i] && SPFA(i)){
49                 found = 1;
50                 while (stk.size()>=2){
51                     int u = stk.back(); stk.pop_back();
52                     int v = stk.back(); stk.pop_back();
53                     match[u] = v;
54                     match[v] = u;
55                 }
56             }
57             if (!found) break;
58         }
59         int ret = 0;
60         for (int i=0; i<n; i++)
61             ret += edge[i][match[i]];
62         ret /= 2;
63         return ret;
64     }
65 }graph;

```

4.10 StronglyConnectedComponent

```

1 int V, E;
2 vector<int> G[MAXV];
3 vector<int> rG[MAXV];
4 vector<int> vs; //postorder
5 bool used[MAXV];
6 int comp[MAXV]; //scc id, topologically ordered
7
8 void add_edge(int from, int to)
9 {
10     G[from].pb(to);
11     rG[to].pb(from);
12 }
13
14 void dfs(int u) //get postorder
15 {
16     used[u] = true;
17     for (int i=0; i<G[u].size(); i++)
18         if (!used[G[u][i]]) dfs(G[u][i]);
19     vs.pb(u);
20 }
21
22 void rdfs(int u, int k)
23 {
24     used[u]=true;
25     comp[u]=k;
26     for (int i=0; i<rG[u].size(); i++)
27         if (!used[rG[u][i]]) rdfs(rG[u][i], k);
28 }

```



```

29 int scc()//return scc cnt
30 {
31     memset(used,0,sizeof(used));
32     vs.clear();
33     FOR(v,1,V) if(!used[v]) dfs(v);
34     memset(used,0,sizeof(used));
35     int k = 0;//sccID
36     FORD(i,V-1,0)
37         if(!used[ vs[i] ])
38             {
39                 rdfs(vs[i],k);
40                 k++;
41             }
42     return k;
43 }
44 }

```

4.11 MaxBiMatching

```

1 //注意：變數v
2 #define MAXV 505
3 int V;//# of vertex
4 vector<int> G[MAXV];
5 int match[MAXV];
6 int used[MAXV];
7
8 void add_edge(int u, int v)
9 {
10     G[u].pb(v);
11     G[v].pb(u);
12 }
13
14 bool dfs(int u)
15 {
16     used[u]=true;
17     for(int i = 0; i < G[u].size(); i++)
18     {
19         int v = G[u][i], w = match[v];
20         if(w<0 || !used[w] && dfs(w))
21         {
22             match[u]=v;
23             match[v]=u;
24             return true;
25         }
26     }
27     return false;
28 }
29
30 int bip_match()
31 {
32     int res=0;
33     memset(match,-1,sizeof(match));
34     for(int v=0; v<V; v++)
35     {
36         if(match[v]<0)
37         {
38             memset(used,0,sizeof(used));
39             if(dfs(v)) res++;
40         }
41     }
42     return res;
43 }

```

4.12 dijkstra

```

1
2 struct edge{int to, cost;};
3 typedef pair<int, int> P; //first = min distance, second = v
4     id
5 #define f first
6 #define s second
7 #define INF 2147483647
8
9 int V, E, S, F;
10 vector<edge> G[100];
11 int d[100];
12
13 void dijkstra()
14 {
15     priority_queue<P, vector<P>, greater<P>> q;
16     fill(d, d + V, INF);
17     d[S] = 0;
18     q.push(P(0, S));
19
20     while(!q.empty())
21     {
22         P p = q.top(); q.pop();
23         int v = p.s;
24         if(d[v] < p.f) continue;
25         for(int i = 0; i < G[v].size(); i++)
26         {
27             edge e = G[v][i];
28             if(d[e.to] > d[v] + e.cost)
29             {
30                 d[e.to] = d[v] + e.cost;
31                 q.push(P(d[e.to], e.to));
32             }
33         }
34     }
35 }

```

4.13 TwoConnected

```

1 vector<int> G[MAXN];
2 vector<int> bcc[MAXN]; // bcc內的點
3
4 int dfn[MAXN], low[MAXN], tim, ans;
5 int st[MAXN], top;
6 int bccID[MAXN], bcc_cnt;// 每個點的bcc編號
7 bool is_cut[MAXN]; // 是否為割點，割點的ID會被覆蓋
8
9 void tarjan(int u, int p){ // p->u
10     int child= 0, w;
11     dfn[u] = low[u] = ++tim;
12     st[top++] = u;
13     for(auto v:G[u]){ // u->v
14         if(!dfn[v]){
15             tarjan(v, u); child++;
16             low[u] = min(low[u], low[v]);
17             if(low[v] >= dfn[u]){
18                 is_cut[u]= true;
19             }
20             do{
21                 w = st[--top];
22                 bccID[w]= bcc_cnt;

```

```

22         bcc[bcc_cnt].push_back(w);
23     }while(dfn[w] > dfn[v]);
24     bccID[u]= bcc_cnt;
25     bcc[bcc_cnt++].push_back(u);
26 }
27 }
28 else if(v != p)
29     low[u]= min(low[u], dfn[v]);
30 }
31
32 if(p == -1 && child<2)
33     is_cut[u]= false;
34 }

```

4.14 ArticulationPoint

```

1 vector<int> G[MAXN];
2 int dfn[MAXN], low[MAXN], tim, ans;
3 void tarjan(int u, int p){ // p -> u
4     int child=0, cut_node=0;
5     dfn[u] = low[u] = ++tim;
6     for(auto v:G[u]){ // u -> v
7         if(!dfn[v]){ // tree edge
8             tarjan(v, u); child++;
9             low[u]= min(low[u], low[v]);
10            if(low[v] >= dfn[u]) cut_node=1;
11        }
12        else if(v!=p) //back edge
13            low[u]= min(low[u], dfn[v]);
14    }
15
16    if(p!=-1 && cut_node) ans++;
17    if(p==-1 && child>=2) ans++;
18 }
19 //how to call
20 for(int i=0; i<n; i++)
21     if(!dnf[i])
22         tarjan(i, -1);

```

4.15 MaxWeightPerfectBiMatch

```

1 const int maxn = 500 + 3, INF = 0x3f3f3f3f;
2 int n, W[maxn][maxn];
3 int mat[maxn];
4 int Lx[maxn], Ly[maxn], slack[maxn];
5 bool S[maxn], T[maxn];
6
7 inline void tension(int &a, const int b) {
8     if(b < a) a = b;
9 }
10
11 inline bool match(int u) {
12     S[u] = true;
13     for(int v = 0; v < n; ++v) {
14         if(T[v]) continue;
15         int t = Lx[u] + Ly[v] - W[u][v];
16         if(!t) {
17             T[v] = true;
18             if(mat[v] == -1 || match(mat[v])) {
19                 mat[v] = u;

```



```

20         return true;
21     }
22     }else tension(slack[v], t);
23 }
24 return false;
25 }
26
27 inline void update() {
28     int d = INF;
29     for(int i = 0; i < n; ++i)
30         if(!T[i]) tension(d, slack[i]);
31     for(int i = 0; i < n; ++i) {
32         if(S[i]) Lx[i] -= d;
33         if(T[i]) Ly[i] += d;
34     }
35 }
36
37 inline void KM() {
38     for(int i = 0; i < n; ++i) {
39         Lx[i] = Ly[i] = 0; mat[i] = -1;
40         for(int j = 0; j < n; ++j) Lx[i] = max(Lx[i], W[i][j]);
41     }
42     for(int i = 0; i < n; ++i) {
43         fill(slack, slack + n, INF);
44         while(true) {
45             for(int j = 0; j < n; ++j) S[j] = T[j] = false;
46             if(match(i)) break;
47             else update();
48         }
49     }
50 }

```

4.16 MaximalClique

```

1 #define MAXN 32
2 int n, m, Max;
3 ll v[MAXN], deg[MAXN]; //neighbors
4
5 void update_maximum(ll R)
6 {
7     int Size = 0;
8     while(R)
9     {
10         if(R&1)Size++;
11         R>>=1;
12     }
13     Max = max(Size, Max);
14 }
15
16 int pickPivot(ll P)
17 {
18     int pivot = -1, Max = -1;
19     memset(deg, 0, sizeof(deg));
20     for(int i = 0; i < n; i++)
21     {
22         if(P&(1LL<<i)) //i is in P
23         {
24             if(pivot == -1) //i = default pivot
25             {
26                 pivot = i;
27                 Max = deg[i];
28             }

```

```

29         for(int j = 0; j < i; j++)
30         {
31             if((P&(1LL<<j))&&(v[i]&(1LL<<j)))
32             {
33                 deg[i]++;
34                 if(deg[i] > Max)
35                 {
36                     Max = deg[i];
37                     pivot = i;
38                 }
39             }
40             deg[j]++;
41             if(deg[j] > Max)
42             {
43                 Max = deg[j];
44                 pivot = j;
45             }
46         }
47     }
48     return pivot;
49 }
50
51 void BronKerbosch(ll R, ll P, ll X)
52 {
53     if(!P) //P is empty, no candidates left
54     {
55         if(!X)
56         {
57             //clique
58             update_maximum(R);
59         }
60         return;
61     }
62     int u = pickPivot(P|X);
63     for(int i = 0; i <= n-1; i++)
64     {
65         if(P&(~v[u]&(1LL<<i)) //vi is in P
66         {
67             BronKerbosch( R|(1LL<<i), P&v[i], X&v[i] );
68             P&=~(1LL<<i);
69             X|=(1LL<<i);
70         }
71     }
72 }
73
74 int main()
75 {
76     ios::sync_with_stdio(false);
77     cin.tie(0);
78     while(cin >> n)
79     {
80         cin >> m;
81
82         Max = 0;
83         FOR(i,0,n-1)v[i] = 0;
84
85         int a, b;
86         FOR(i,1,m)
87         {
88             cin >> a >> b;
89             v[a]|=(1LL<<b);
90             v[b]|=(1LL<<a);
91         }
92         BronKerbosch(0, (1LL<<n)-1, 0);
93         cout << Max << '\n';
94     }

```

```

95     }
96     return 0;
97 }

```

4.17 MaxMatching

```

1 #define FZ(x) memset(x,0,sizeof(x))
2 struct GenMatch // 1-base
3 {
4     static const int MAXN = 250;
5     int V;
6     bool el[MAXN][MAXN];
7     int pr[MAXN];
8     bool inq[MAXN], inp[MAXN], inb[MAXN];
9     queue<int> qe;
10    int st,ed;
11    int nb;
12    int bk[MAXN], djs[MAXN];
13    int ans;
14    void init(int _V)
15    {
16        V = _V;
17        FZ(el);
18        FZ(pr);
19        FZ(inq);
20        FZ(inp);
21        FZ(inb);
22        FZ(bk);
23        FZ(djs);
24        ans = 0;
25    }
26    void add_edge(int u, int v)
27    {
28        el[u][v] = el[v][u] = 1;
29    }
30    int lca(int u,int v)
31    {
32        memset(inp,0,sizeof(inp));
33        while(1)
34        {
35            u = djs[u];
36            inp[u] = true;
37            if(u == st) break;
38            u = bk[pr[u]];
39        }
40        while(1)
41        {
42            v = djs[v];
43            if(inp[v]) return v;
44            v = bk[pr[v]];
45        }
46        return v;
47    }
48    void upd(int u)
49    {
50        int v;
51        while(djs[u] != nb)
52        {
53            v = pr[u];
54            inb[djs[u]] = inb[djs[v]] = true;
55            u = bk[v];
56            if(djs[u] != nb) bk[u] = v;
57        }

```

```

58 }
59 void blo(int u,int v)
60 {
61     nb = lca(u,v);
62     memset(inb,0,sizeof(inb));
63     upd(u);
64     upd(v);
65     if(djs[u] != nb) bk[u] = v;
66     if(djs[v] != nb) bk[v] = u;
67     for(int tu = 1; tu <= V; tu++)
68         if(inb[djs[tu]])
69         {
70             djs[tu] = nb;
71             if(!inq[tu])
72             {
73                 qe.push(tu);
74                 inq[tu] = 1;
75             }
76         }
77 }
78 void flow()
79 {
80     memset(inq,false,sizeof(inq));
81     memset(bk,0,sizeof(bk));
82     for(int i = 1; i <= V; i++)
83         djs[i] = i;
84
85     while(qe.size()) qe.pop();
86     qe.push(st);
87     inq[st] = 1;
88     ed = 0;
89     while(qe.size())
90     {
91         int u = qe.front();
92         qe.pop();
93         for(int v = 1; v <= V; v++)
94             if(el[u][v] && (djs[u] != djs[v]) && (pr[u]
95                 != v))
96             {
97                 if((v == st) || ((pr[v] > 0) && bk[pr[v]]
98                     > 0))
99                     blo(u,v);
100                 else if(bk[v] == 0)
101                 {
102                     bk[v] = u;
103                     if(pr[v] > 0)
104                     {
105                         if(!inq[pr[v]]) qe.push(pr[v]);
106                     }
107                     else
108                     {
109                         ed = v;
110                         return;
111                     }
112                 }
113             }
114 }
115 void aug()
116 {
117     int u,v,w;
118     u = ed;
119     while(u > 0)
120     {
121         v = bk[u];
122         w = pr[v];

```

```

122     pr[v] = u;
123     pr[u] = v;
124     u = w;
125 }
126 }
127 int solve()
128 {
129     memset(pr,0,sizeof(pr));
130     for(int u = 1; u <= V; u++)
131         if(pr[u] == 0)
132         {
133             st = u;
134             flow();
135             if(ed > 0)
136             {
137                 aug();
138                 ans ++;
139             }
140         }
141     return ans;
142 }
143 } gm;

```

4.18 spfa

```

1 typedef pair<int, ll> P;
2 #define idx first
3 #define w second
4 int vn, en;
5 vector<P> graph[N];
6 ll dist[N];
7
8 bool spfa() // return true if neg cycle
9 {
10     for(int i = 0; i < vn; i++) dist[i] = INF; dist[0] = 0;
11     int cnt[N] = {0};
12     bool inq[N] = {false};
13     queue<int> q; q.push(0); inq[0] = true;
14     while(!q.empty())
15     {
16         int s = q.front(); q.pop();
17         inq[s] = false;
18         for(auto e:graph[s])
19         {
20             if(dist[e.idx] > dist[s]+e.w)
21             {
22                 dist[e.idx] = dist[s]+e.w;
23                 if(++cnt[e.idx] >= vn) return true;
24                 if(!inq[e.idx])
25                 {
26                     inq[e.idx] = true;
27                     q.push(e.idx);
28                 }
29             }
30         }
31     }
32     return false;
33 }

```

4.19 MinimumMeanCycle

```

1 #include<cstdio> //for DBL_MAX
2 int dp[MAXN][MAXN]; // 1-base,O(NM)
3 vector<tuple<int,int,int>> edge;
4 double mmc(int n){//allow negative weight
5     const int INF=0x3f3f3f3f;
6     for(int t=0;t<n;++t){
7         memset(dp[t+1],0x3f,sizeof(dp[t+1]));
8         for(const auto &e:edge){
9             int u,v,w;
10             tie(u,v,w) = e;
11             dp[t+1][v]=min(dp[t+1][v],dp[t][u]+w);
12         }
13     }
14     double res = DBL_MAX;
15     for(int u=1;u<=n;++u){
16         if(dp[n][u]==INF) continue;
17         double val = -DBL_MAX;
18         for(int t=0;t<n;++t)
19             val=max(val, (dp[n][u]-dp[t][u])*1.0/(n-t));
20         res=min(res,val);
21     }
22     return res;
23 }

```

5 Math

5.1 EulerPhi

```

1 //find in O(sqrt(N))
2
3 int euler_phi(int N)
4 {
5     int res=N;
6     for(int i=2;i*i<=N;i++)
7     {
8         if(N%i==0)
9         {
10             res=res/i*(i-1);
11             for(;N%i==0;N/=i);
12         }
13     }
14     if(N!=1)res=res/N*(N-1);//self=prime
15     return res;
16 }
17
18 //tabulate in O(MAXN)
19
20 int euler[MAXN];
21
22 void euler_phi2()
23 {
24     for(int i=0;i<MAXN;i++)euler[i]=i;
25     for(int i=2;i<MAXN;i++)
26     {
27         if(euler[i]==i)
28         {
29             for(int j=i;j<MAXN;j+=i)
30             {
31                 euler[j]=euler[j]/i*(i-1);
32             }
33         }
34     }
35 }

```

```

34 }
35 }

```

5.2 exgcd

```

1 ll exgcd(ll a, ll &ar, ll b) //維護a*ar+b*as=gcd(a, b)
2 {
3     ll as = 0, br = 0, bs = 1;
4     while(a && b)
5     {
6         ar -= br*(a/b);
7         as -= bs*(a/b);
8         a %= b;
9         if(a == 0) break;
10        br -= ar*(b/a);
11        bs -= as*(b/a);
12        b %= a;
13    }
14    if(a == 0) a = b, ar = br; //維護a*ar+b*as=gcd(a, b)
15    return a; //return gcd(a, b)
16 }

```

5.3 NTT

```

1 typedef long long ll;
2
3 const ll P = (479<<21)+1;
4 const ll G = 3;
5 inline ll fpw(ll x, ll y, ll m)
6 {
7     ll rtn = 1;
8     for(x=(x>=m?x%m:x); y>=1)
9     {
10        if(y&1) rtn = rtn*x%m;
11        x = x*x%m;
12    }
13    return rtn;
14 }
15 inline vector<ll> ntt(vector<ll> rtn, int Rev = 1)
16 {
17     int ntt_n = rtn.size();
18     for(int i=0, j=0; i<ntt_n; i++)
19     {
20         if(i>j) swap(rtn[i], rtn[j]);
21         for(int k=(ntt_n>>1); (j^=k)<k; k>>=1);
22     }
23     for(int i=2, m=1; i<=ntt_n; i<=1, m++)
24     {
25         ll w = 1, wn = fpw(G, (P-1)>>m, P), u, t;
26         int mh = i>>1;
27         for(int j=0; j<mh; j++)
28         {
29             for(int k=j; k<ntt_n; k+=i)
30             {
31                 u = rtn[k], t = w*rtn[k+mh]%P;
32                 rtn[k] = (u+t)%P;
33                 rtn[k+mh] = (u-t)%P;
34             }
35             w = w*wn%P;

```

```

36     }
37 }
38 if(!~Rev)
39 {
40     for(int i=1; i<ntt_n/2; i++) swap(rtn[i], rtn[ntt_n-i]);
41     ll Revn = fpw(ntt_n, P-2, P);
42     for(int i=0; i<ntt_n; i++) rtn[i] = rtn[i]*Revn%P;
43 }
44 return rtn;
45 }

```

5.4 BigInteger

```

1 class BigInt
2 {
3 public:
4     // constructors
5     BigInt();
6     BigInt(ll);
7     BigInt(const char*);
8     BigInt(string);
9     BigInt(bool, vector<int>);
10    // functions
11    inline void print();
12    // operators
13    bool operator== (const BigInt &a) const;
14    bool operator!= (const BigInt &a) const;
15    bool operator< (const BigInt &a) const;
16    bool operator> (const BigInt &a) const;
17    bool operator<= (const BigInt &a) const;
18    bool operator>= (const BigInt &a) const;
19    BigInt operator- () const;
20    BigInt operator+ (const BigInt &a) const;
21    BigInt operator- (const BigInt &a) const;
22    BigInt operator* (const BigInt &a) const;
23    BigInt operator/ (const BigInt &a) const;
24    BigInt operator% (const BigInt &a) const;
25    // variables
26    const static int MAX = 1000000;
27    bool Neg = false;
28    vector<int> seq;
29 };
30
31 // constructors
32 BigInt::BigInt() {}
33 BigInt::BigInt(ll in)
34 {
35     if(in<0) Neg=true, in=-in;
36     while(in!=0)
37     {
38         seq.emplace_back(in%MAX);
39         in/=MAX;
40     }
41     if(seq.empty()) seq.emplace_back(0);
42 }
43 BigInt::BigInt(const char *s)
44 {
45     int i, j, tmp, end=0;
46     if(s[0]=='-') Neg=true, end=1;
47     for(i=strlen(s)-1, j=1, tmp=0; i>=end; i--, j*=10)
48     {
49         if(j==MAX)
50         {

```

```

51             seq.emplace_back(tmp);
52             j=1, tmp=0;
53         }
54         tmp += (s[i]-'0')*j;
55     } seq.emplace_back(tmp);
56 }
57 BigInt::BigInt(string s):BigInt(s.c_str()) {}
58 BigInt::BigInt(bool b, vector<int> v):Neg(b), seq(v) {}
59 // functions
60 void BigInt::print()
61 {
62     if(Neg) putchar('-');
63     printf("%d", seq.back());
64     for(int i=(int)(seq.size()-2); i>=0; i--)
65         printf("%06d", seq[i]);
66     puts("");
67 }
68 // operators
69 bool BigInt::operator== (const BigInt &a) const
70 {
71     return Neg==a.Neg&&seq==a.seq;
72 }
73 bool BigInt::operator!= (const BigInt &a) const
74 {
75     return !((*this)==a);
76 }
77 bool BigInt::operator< (const BigInt &a) const
78 {
79     if(Neg^a.Neg) return Neg;
80     if(seq.size()!=a.seq.size()) return Neg^(seq.size()<a.seq.size());
81     for(int i=seq.size()-1; i>=0; i--)
82         if(seq[i]!=a.seq[i]) return Neg^(seq[i]<a.seq[i]);
83     return false;
84 }
85 bool BigInt::operator> (const BigInt &a) const
86 {
87     if(Neg^a.Neg) return a.Neg;
88     if(seq.size()!=a.seq.size()) return a.Neg^(seq.size()>a.seq.size());
89     for(int i=seq.size()-1; i>=0; i--)
90         if(seq[i]!=a.seq[i]) return a.Neg^(seq[i]>a.seq[i]);
91     return false;
92 }
93 bool BigInt::operator<= (const BigInt &a) const
94 {
95     return !((*this)>a);
96 }
97 bool BigInt::operator>= (const BigInt &a) const
98 {
99     return !((*this)<a);
100 }
101 BigInt BigInt::operator- () const
102 {
103     return BigInt(Neg^1, seq);
104 }
105 BigInt BigInt::operator+ (const BigInt &a) const
106 {
107     if(Neg^a.Neg)
108         return Neg?a-(-(*this)):(*this)-(-a);
109     BigInt rtn(Neg, vector<int>(max(seq.size(), a.seq.size())));
110     for(int i=0; i<(int)(seq.size()); i++) rtn.seq[i]+=seq[i];
111     for(int i=0; i<(int)(a.seq.size()); i++) rtn.seq[i]+=a.seq[i];
112     for(int i=0; i<(int)(rtn.seq.size()-1; i++)
113         if(rtn.seq[i]>=MAX)

```

```

114     rtn.seq[i+1]+=rtn.seq[i]/MAX, rtn.seq[i]%=MAX;
115     if (rtn.seq.back()>=MAX)
116     {
117         rtn.seq.emplace_back(rtn.seq.back()/MAX);
118         rtn.seq[rtn.seq.size()-2]%=MAX;
119     }
120     return rtn;
121 }
122 BigInt BigInt::operator- (const BigInt &a) const
123 {
124     if (Neg^a.Neg) return (*this)+(-a);
125     if (Neg^((!this)<a)) return (-a)-(!this);
126     BigInt rtn(Neg, vector<int>(max(seq.size(),a.seq.size())));
127     for(int i=0; i<(int)(seq.size()); i++) rtn.seq[i]+=seq[i];
128     for(int i=0; i<(int)(a.seq.size()); i++) rtn.seq[i]-=a.seq[i];
129     for(int i=0; i<(int)(rtn.seq.size())-1; i++)
130         if (rtn.seq[i]<0)
131             rtn.seq[i+1]--, rtn.seq[i]+=MAX;
132     while(!rtn.seq.empty() && !rtn.seq.back()) rtn.seq.pop_back();
133     if (rtn.seq.empty()) rtn = BigInt(0ll);
134     return rtn;
135 }
136 BigInt BigInt::operator* (const BigInt &a) const
137 {
138     BigInt rtn(Neg^a.Neg, vector<int>(0));
139     vector<Complex> x, y;
140     for(auto i:seq) x.emplace_back(i);
141     for(auto i:a.seq) y.emplace_back(i);
142     int N=1;
143     while(N<(int)(x.size()+y.size())) N<= 1;
144     while(N!=(int)(x.size())) x.emplace_back(0);
145     while(N!=(int)(y.size())) y.emplace_back(0);
146     x = fft(x), y = fft(y);
147     for(int i=0; i<N; i++) x[i] = x[i]*y[i];
148     x = fft(x,-1);
149     ll tmp = 0;
150     for(int i=0; i<N; i++)
151     {
152         tmp += (ll)(x[i].x+0.1);
153         rtn.seq.emplace_back(tmp%MAX);
154         tmp /= MAX;
155     }
156     rtn.seq.emplace_back(tmp);
157     while(!rtn.seq.empty() && !rtn.seq.back()) rtn.seq.pop_back();
158     if (rtn.seq.empty()) rtn = BigInt(0ll);
159     return rtn;
160 }
161 BigInt BigInt::operator/ (const BigInt &a) const
162 {
163     if (a==BigInt(0ll)) return a;
164     BigInt rtn, check, BITmp, posiA, posiB;
165     posiA = (*this), posiA.Neg = false;
166     posiB = a, posiB.Neg = false;
167     int PRECISION = max(seq.size(),a.seq.size()+6, N = 1;
168     ll tmp = 0;
169     while(N<PRECISION+6) N<= 1;
170     N<= 1;
171     vector<Complex> B, c1(N,0), c2(N,0), c3(N,0);
172     vector<Complex> *x = (&c1), *xp = (&c2), *calc = (&c3);
173     for(int i=a.seq.size()-1; i>=0; i--)
174         B.emplace_back(a.seq[i]);
175     B.resize(N,0);
176     B = fft(B);
177     (*x)[a.seq.size()] = MAX/a.seq.back();

```

```

177 bool found = false;
178 while(!found)
179 {
180     (*x) = fft(*x);
181     for(int i=0; i<N; i++) (*calc)[i] = (*x)[i]*B[i];
182     (*calc) = fft(*calc,-1);
183     for(int i=a.seq.size()-1; i<N; i++)
184         (*calc)[i-a.seq.size()+1] = (*calc)[i];
185     for(int i=N-a.seq.size()+1; i<N; i++)
186         (*calc)[i] = 0;
187     for(int i=N-1; i>=1; i--)
188     {
189         tmp = (ll)((*calc)[i].x+0.1);
190         (*calc)[i-1] = (ll)((*calc)[i-1].x+0.1)+tmp/MAX;
191         (*calc)[i] = tmp % MAX;
192         if (tmp)
193         {
194             (*calc)[i-1] = (ll)((*calc)[i-1].x+0.1)+1;
195             (*calc)[i] = MAX-tmp;
196         }
197     }
198     (*calc)[0] = 2-(ll)((*calc)[0].x+0.1);
199     for(int i=PRECISION+6; i<N; i++) (*calc)[i] = 0;
200     (*calc) = fft(*calc);
201     for(int i=0; i<N; i++) (*xp)[i] = (*calc)[i]*(*x)[i];
202     (*xp) = fft(*xp,-1);
203     (*x) = fft(*x,-1);
204     for(int i=N-1; i>=1; i--)
205     {
206         tmp = (ll)((*xp)[i].x+0.1);
207         (*xp)[i] = tmp%MAX;
208         (*xp)[i-1] = (ll)((*xp)[i-1].x+0.1)+tmp/MAX;
209     }
210     for(int i=PRECISION+6; i<N; i++) (*xp)[i] = 0;
211     found = true;
212     for(int i=0; i<=PRECISION&&found; i++)
213         if ((ll)((*xp)[i].x+0.1) != (ll)((*x)[i].x+0.1))
214             found = false;
215     calc = x, x = xp, xp = calc, calc = (&c3);
216 }
217 for(int i=N-1; i>=1; i--)
218     rtn.seq.emplace_back((ll)((*x)[i].x+0.1));
219 while(!rtn.seq.back()) rtn.seq.pop_back();
220 rtn = rtn*posiA;
221 for(int i=N-1; i<(int)(rtn.seq.size()); i++)
222     rtn.seq[i-N+1] = rtn.seq[i];
223 for(int i=max((int)(rtn.seq.size()-N+1),0); i<(int)(rtn.seq.size()); i++)
224     rtn.seq[i] = 0;
225 while(!rtn.seq.empty() && !rtn.seq.back()) rtn.seq.pop_back();
226 if (rtn.seq.empty()) rtn = BigInt(0ll);
227 check = rtn*posiB;
228 BITmp = check+posiB;
229 while(posiA>BITmp)
230     rtn = rtn+BigInt(1), check = BITmp, BITmp = check+posiB;
231 BITmp = check-posiB;
232 while(posiA<=BITmp)
233     rtn = rtn-BigInt(1), check = BITmp, BITmp = check-posiB;
234 rtn.Neg = Neg^a.Neg;
235 return rtn;
236 }
237 BigInt BigInt::operator% (const BigInt &a) const
238 {
239     return (*this)-(!this)/a*a;
240 }

```

5.5 prime_detect

```

1 const int N = 10000000;
2 bool isprime[N] = {true};
3 void prime_detect()
4 {
5     for(int i = 2; i < sq; i++)
6         if (isprime[i])
7             for(int j = i*i; j < N; j+=i) isprime[j] = false;
8 }

```

5.6 GaussianJordan

```

1 const double EPS = 1e-8;
2 typedef vector<double> vec;
3 typedef vector<vec> mat;
4
5 //solve Ax=b
6 //if no sol/inf sol, return vec of size 0
7 vec gauss_jordan(const mat& A, const vec& b)
8 {
9     int n = A.size();
10    mat B(n, vec(n+1));
11    for(int i=0; i<n; i++) for(int j=0; j<n; j++) B[i][j] = A[i][j];
12
13    for(int i=0; i<n; i++) B[i][n] = b[i];
14
15    for(int i=0; i<n; i++)
16    {
17        int pivot=i;
18        for(int j=i; j<n; j++)
19        {
20            if (abs(B[j][i])>abs(B[pivot][i])) pivot=j;
21        }
22        swap(B[i], B[pivot]);
23        if (abs(B[i][i])<EPS) return vec(); //no/inf sol
24
25        for(int j=i+1; j<n; j++) B[i][j] /= B[i][i];
26        for(int j=0; j<n; j++)
27        {
28            if (i!=j)
29            {
30                for(int k=i+1; k<n; k++)
31                    B[j][k] -= B[j][i]*B[i][k];
32            }
33        }
34    }
35    vec x(n);
36    for(int i=0; i<n; i++) x[i] = B[i][n];
37    return x;
38 }

```

5.7 modeq

```

1 // 解線性模方程組 (最小非負整數解)
2 const int N; //N個方程
3 ll A[N], B[N], M[N]; // A * X = B (%M)
4 ll solve() //解X, return INF if no solution
5 {

```

```

6  ll k = 0, h = 1;
7  for(ll i = 0; i < N; i++)
8  {
9      ll a = A[i]*h, b = B[i]-A[i]*k, m = M[i], ar;
10     ll d = exgcd(a, ar=1, m);
11     if(b%d != 0) return INF;
12     ll n = abs(m/d);
13     ll t = ar*b/d; t%=n; t+=n; t%=n;
14
15     k += h*t, h *= n; k%=h; //維護解是正的
16 }
17 int ret = (k*h+h)%h;
18 return ret;
19 }

```

5.8 FFT

```

1  const double PI = acos(-1.0);
2  struct Complex
3  {
4      double x,y;
5      Complex() {}
6      Complex(double a):x(a),y(0) {}
7      Complex(double a, double b):x(a),y(b) {}
8      Complex operator+ (const Complex &a){ return Complex(x+a.x,
9          y+a.y); }
10     Complex operator- (const Complex &a){ return Complex(x-a.x,
11         y-a.y); }
12     Complex operator* (const Complex &a){ return Complex(x*a.x-
13         y*a.y,x*a.y+y*a.x); }
14 };
15 inline vector<Complex> fft(vector<Complex> rtn, int Rev = 1)
16 {
17     int fft_n = rtn.size();
18     for(int i=0,j=0;i<fft_n;i++)
19     {
20         if(i>j) swap(rtn[i],rtn[j]);
21         for(int k=(fft_n>>1);(j^=k)<k;k>>=1);
22     }
23     for(int i=2,m;i<=fft_n;i<=1)
24     {
25         m = i>>1;
26         for(int j=0;j<fft_n;j+=i)
27         {
28             for(int k=0;k<m;k++)
29             {
30                 Complex y = rtn[j+k*m]*Complex(cos(2*PI/i*k), Rev*sin
31                     (2*PI/i*k));
32                 rtn[j+k+m] = rtn[j+k]-y;
33                 rtn[j+k] = rtn[j+k]+y;
34             }
35         }
36     }
37     for(int i=0;!--Rev&&i<fft_n;i++)
38         rtn[i].x = rtn[i].x/fft_n;
39     return rtn;
40 }

```

6 String

6.1 hash

```

1  #define MAXN 1000000
2  #define mod 1073676287
3  /*mod 必須要是質數*/
4  typedef long long T;
5  char s[MAXN+5];
6  T h[MAXN+5]; /*hash陣列*/
7  T h_base[MAXN+5]; /*h_base[n]=(prime^n)%mod*/
8  void hash_init(int len,T prime){
9      h_base[0]=1;
10     for(int i=1;i<=len;i++){
11         h[i]=(h[i-1]*prime+s[i-1])%mod;
12         h_base[i]=(h_base[i-1]*prime)%mod;
13     }
14 }
15 T get_hash(int l,int r){/*閉區間寫法·設編號為0~len-1*/
16     return (h[r+1]-(h[l]*h_base[r-l+1])%mod+mod)%mod;
17 }

```

6.2 SuffixArray-STL

```

1  struct CMP
2  {
3      int len,k,*Rank,a,b;
4      inline bool operator()(int i, int j)
5      {
6          if(Rank[i]!=Rank[j])return Rank[i]<Rank[j];
7          a=(i+k)<len?Rank[i]:-1;
8          b=(j+k)<len?Rank[j]:-1;
9          return a<b;
10     }
11 };
12 void SA_build(int *SA, int *Rank, char *S){
13     int tmp[MAX_N], len=strlen(S);
14     for(int i=0;i<len;i++) SA[i]=i, Rank[i]=S[i];
15     CMP cmp={len,1};
16     while(cmp.k*=2)
17     {
18         cmp.Rank=Rank;
19         sort(SA,SA+len,cmp);
20         tmp[SA[0]]=0;
21         for(int i=1;i<len;i++)
22             tmp[SA[i]]=tmp[SA[i-1]]+cmp(SA[i-1],SA[i]);
23         if(tmp[SA[len-1]]==len-1) break;
24         for(int i=0;i<len;i++) Rank[i]=tmp[i];
25     }
26 }

```

6.3 Z-value

```

1  void Z_build(const char *S, int *Z)
2  {
3      Z[0]=0;
4      int b=0;

```

```

5  for(int i=1;S[i];i++)
6  {
7      if(Z[b]+b<i) Z[i]=0;
8      else Z[i]=min(Z[b]+b-i,Z[i-b]);
9      while(S[i+Z[i]]&&S[Z[i]]==S[i+Z[i]]) Z[i]++;
10     if(Z[i]+i>Z[b]+b) b=i;
11 }
12 }

```

6.4 BWT

```

1  // use with suffix array
2  int pivot;
3  // BWT array size must be double of the data size
4  inline void BWT(char *tmp, char *in, char *out, int *SA, int
5      *Rank)
6  {
7      int len=strlen(in);
8      for(int i=0;i<len;i++) tmp[i]=tmp[i+len]=in[i];
9      tmp[len*2]='\0';
10     SA_build(SA,Rank,tmp);
11     for(int i=0,j=0;i<2*len;i++)
12     {
13         if(SA[i]==len) pivot=j;
14         if(SA[i]<len)
15             out[j++]=in[(SA[i]+len-1)%len];
16     }
17     out[len]='\0';
18 }
19 inline void IBWT(char *in, char *out, int *tmp)
20 {
21     int len=strlen(in);
22     vector<int> idx[256];
23     for(int i=0;i<len;i++)
24         idx[in[i]].emplace_back(i);
25     for(int i=0,k=0;i<256;i++)
26         for(int j=0;j<(int)(idx[i].size());j++)
27             tmp[k++]=idx[i][j];
28     int p=pivot;
29     for(int i=0;i<len;i++)
30         out[i]=in[p=tmp[p]];
31     out[len]='\0';
32 }

```

6.5 LCP

```

1  //build query in O(nlogn), query LCP(i,j) in O(1)
2  int dp_height[MAX_N][20];
3  void height_build(int *SA, int *Rank, char *S, int *Height)
4  {
5      int len=strlen(S), k=0;
6      for(int i=0;i<len;i++)
7      {
8          if(Rank[i]==0) continue;
9          while(S[i+k] == S[SA[Rank[i]-1]+k]) k++;
10         Height[Rank[i]]=k;
11         if(k) k--;
12     } Height[0]=0;
13     for(int i=0;i<len;i++) dp_height[i][0]=Height[i];

```

```

14 for(int i=0;i<len;i++) for(int j=1;i+(1<<j)<len;j++)
15     dp_height[i][j]=min(dp_height[i][j-1], dp_height[i+(1<<j)-1][j-1]);
16 }
17 int height_query(int x, int y)
18 {
19     int k=0;
20     while((1<<(k+1))<=y-x) k++;
21     return min(dp_height[x+1][k], dp_height[y-(1<<k)+1][k]);
22 }

```

6.6 SuffixArray

```

1 void SA_radix_sort(int *s, int *e, int *Rank, int rankcnt)
2 {
3     int box[MAX_N], tmp[MAX_N], len=e-s;
4     memset(box,0,sizeof(int)*rankcnt);
5     for(int i=0;i<len;i++) box[Rank[i]]++;
6     for(int i=1;i<rankcnt;i++) box[i]=box[i]+box[i-1];
7     for(int i=len-1;i>=0;i--) tmp[--box[Rank[s[i]]]]=s[i];
8     for(int i=0;i<len;i++) s[i]=tmp[i];
9 }
10 #define equal(a,b,c) c[a]!=c[b]||a+k>=len||c[a+k]!=c[b+k]
11 void SA_build(int *SA, int *Rank, char *S)
12 {
13     int ranktmp[MAX_N], len=strlen(S), rankcnt='z'+1;
14     for(int i=0;i<len;i++) Rank[i]=S[i];
15     for(int k=1;rankcnt!=len;k*=2)
16     {
17         for(int i=0;i<len;i++) SA[i]=(i+len-k)%len;
18         SA_radix_sort(SA+k, SA+len, Rank+k, rankcnt);
19         SA_radix_sort(SA, SA+len, Rank, rankcnt);
20         ranktmp[SA[0]]=0, rankcnt=0;
21         for(int i=1;i<len;i++)
22             ranktmp[SA[i]]=rankcnt+equal(SA[i-1], SA[i], Rank);
23         rankcnt++;
24         for(int i=0;i<len;i++) Rank[i]=ranktmp[i];
25     }
26 }
27 #undef equal

```

6.7 AC-Automation

```

1 #define SZ 25000
2 int nx[SZ][26], spt;
3 int fl[SZ], efl[SZ], ed[SZ];
4 int newnode()
5 {
6     for(int i=0;i<26;i++) nx[spt][i]=0;
7     ed[spt]=0;
8     return spt++;
9 }
10 int add(char *s, int sptnow)
11 {
12     for(int i=0;s[i];i++)
13     {
14         int tmp=s[i]-'a';
15         if(nx[sptnow][tmp]==0) nx[sptnow][tmp]=newnode();
16         sptnow=nx[sptnow][tmp];
17     }

```

```

18     ed[sptnow]=1;
19     return sptnow;
20 }
21 int bfsq[SZ], qs, qe;
22 void make_fl(int root)
23 {
24     fl[root]=efl[root]=qs=qe=0;
25     bfsq[qe++]=root;
26     while(qs!=qe)
27     {
28         int p=bfsq[qs++];
29         for(int i=0;i<26;i++)
30         {
31             int t=nx[p][i];
32             if(t==0) continue;
33             int tmp=fl[p];
34             for(;tmp&&nx[tmp][i]==0;tmp=fl[tmp]);
35             fl[t]=tmp?nx[tmp][i]:root;
36             efl[t]=ed[fl[t]]?fl[t]:efl[fl[t]];
37             bfsq[qe++]=t;
38         }
39     }
40 }

```

6.8 KMP

```

1 void failure_build(const char *p, int *fail)
2 {
3     for(int i=1, j=fail[0]=-1; p[i]; i++)
4     {
5         while(j>=0&&p[j+1]!=p[i]) j=fail[j];
6         if(p[j+1]==p[i]) j++;
7         fail[i]=j;
8     }
9 }
10 int KMP(const char *T, const char *P, int *fail)
11 {
12     failure_build(P, fail);
13     for(int i=0, j=-1; T[i]; i++)
14     {
15         while(j>=0&&P[j+1]!=T[i]) j=fail[j];
16         if(P[j+1]==T[i]) j++;
17         if(!P[j+1]) return i-j;
18     }
19     return -1;
20 }
21 //使用方法：KMP(主字串, 待匹配字串, failure array)
22 //回傳：第一個完全匹配的位置

```

7 other

7.1 2sat

```

1 const int N = 10; // 變數數量
2 bool adj[20][20]; // adjacency matrix
3 int visit[20]; // DFS visit record

```

```

4 int sat[20]; // 解
5
6 int not(int a) {return a<N ? a+N : a-N;}
7
8 // 另外一種方式
9 /*
10 int not(int a) {return a&1 ? a : a+1;}
11 int not(int a) {return a^1;}
12 */
13
14 bool dfs_try(int i)
15 {
16     if (visit[i] == 1 || sat[i] == 1) return true;
17     if (visit[i] == 2 || sat[i] == 2) return false;
18     visit[i] = 1;
19     visit[not(i)] = 2;
20     for (int j=0; j<N+N; ++j)
21         if (adj[i][j] && !dfs_try(j))
22             return false;
23     return true;
24 }
25
26 void dfs_mark(int i)
27 {
28     if (sat[i] == 1) return;
29     sat[i] = 1;
30     sat[not(i)] = 2;
31     for (int j=0; j<N+N; ++j)
32         if (adj[i][j])
33             dfs_mark(j);
34 }
35
36 void two_satisfiability()
37 {
38     // 一次輸入一個括號
39     memset(adj, false, sizeof(adj));
40     int a, b;
41     while (cin >> a >> b)
42     {
43         map[not(a)][b] = true;
44         map[not(b)][a] = true;
45     }
46
47     // 找出一組解
48     for (int i=0; i<N; ++i)
49     {
50         memset(visit, 0, sizeof(visit));
51         if (dfs_try(i)) {dfs_mark(i); continue;}
52
53         memset(visit, 0, sizeof(visit));
54         if (dfs_try(not(i))) {dfs_mark(not(i)); continue;}
55
56         // 無解則立即結束。
57         return;
58     }
59
60     // 印出一組解。
61     for (int i=1; i<N; ++i)
62         if (sat[i] == 1)
63             cout << i;
64         else /*if (sat[i] == 2)*/
65             cout << "not" << i;
66 }

```

7.2 PojTree

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4 typedef long long int ll;
5 typedef pair<int, ll> P;
6 #define idx first
7 #define w second
8
9 const int N = 10004;
10 const ll INF = (1ll << 60);
11
12 int vn;
13 ll k;
14 vector<P> graph[N];
15 vector<int> dist;
16 ll subtreeSz[N];
17 bool isCentroid[N];
18
19 void init()
20 {
21     for(int i = 1; i <= vn; i++)
22         graph[i].clear(), isCentroid[i] = false;
23 }
24
25 void buildTree()
26 {
27     for(int i = 1; i < vn; i++)
28     {
29         int u, v, l; scanf("%d %d %d", &u, &v, &l);
30         graph[u].push_back(P(v, l));
31         graph[v].push_back(P(u, l));
32     }
33 }
34
35 ll calSubsz(int v, int p)
36 {
37     subtreeSz[v] = 1;
38     for(auto c:graph[v])
39     {
40         if(isCentroid[c.idx] || c.idx == p) continue;
41         subtreeSz[v] += calSubsz(c.idx, v);
42     }
43     return subtreeSz[v];
44 }
45
46 P getCentroid(int v, int p, ll subsz)
47 {
48     P cen(-1, INF);
49     ll mxsonSz = -1;
50     for(auto c:graph[v])
51     {
52         if(c.idx == p || isCentroid[c.idx]) continue;
53         P res = getCentroid(c.idx, v, subsz);
54         if(res.w < cen.w) cen = res;
55         mxsonSz = max(mxsonSz, subtreeSz[c.idx]);
56     }
57     mxsonSz = max(mxsonSz, subsz-subtreeSz[v]);
58     if(mxsonSz < cen.w) cen = P(v, mxsonSz);
59     return cen;
60 }
61
62 void getDist(int v, int p, ll w)

```

```

64 {
65     if(w > k) return;
66     dist.push_back(w);
67     for(auto c:graph[v])
68     {
69         if(c.idx == p || isCentroid[c.idx]) continue;
70         getDist(c.idx, v, w+c.w);
71     }
72 }
73
74 ll calValidPair(int idx, ll w)
75 {
76     dist.clear();
77     getDist(idx, -1, w);
78     sort(dist.begin(), dist.end());
79     ll sum = 0;
80     for(int l = 0, r = dist.size()-1; l < r; )
81     {
82         if(dist[r]+dist[l] <= k) sum += r-l, l++;
83         else r--;
84     }
85     return sum;
86 }
87
88 ll treedc(int v)
89 {
90     ll sum = 0;
91     // find centroid
92     calSubsz(v, v);
93     int cen = getCentroid(v, v, subtreeSz[v]).idx;
94     isCentroid[cen] = true;
95
96     sum += calValidPair(cen, 0);
97     for(auto c:graph[cen])
98     {
99         if(isCentroid[c.idx]) continue;
100         sum += calValidPair(c.idx, c.w);
101         sum += treedc(c.idx);
102     }
103     return sum;
104 }
105
106 int main()
107 {
108     while(scanf("%d %lld", &vn, &k) && vn && k)
109     {
110         init();
111         buildTree();
112         printf("%lld\n", treedc(1));
113     }
114     return 0;
115 }

```

7.3 definss

```

1 #include <bits/stdc++.h>
2 using namespace std;
3 #define pb push_back
4 #define pii pair<int,int>
5 #define pll pair<ll, ll>
6 #define pil pair<int,ll>
7 #define pli pair<ll,int>
8 #define ppi pair<pii,int>

```

```

9 #define pip pair<int,pii>
10 #define pdd pair<double, double>
11 #define f first
12 #define s second
13 #define MOD 1000000007
14 #define mkp make_pair
15 #define M_PI 3.14159265358979323846
16 #define FOR(i,l,r) for (int i=l;i<=r;i++)
17 #define LOR(i,l,r) for (ll i=l;i<=r;i++)
18 #define FORD(i,r,l) for (int i=r;i>=l;i--)
19 #define LORD(i,r,l) for (ll i=r;i>=l;i--)
20 #define INF 1000000000
21 #define CL(x) memset(x,0,sizeof(x))
22 typedef long long ll;
23
24 int main()
25 {
26     ios::sync_with_stdio(false);
27     cin.tie(0);
28
29     return 0;
30 }

```


ACM ICPC TEAM

REFERENCE -

NTHU_FURRYFORCE

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