

Time Series 413, Assignment 4

ARMA Models with Seasonality (TS4)

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MSDS-413-DL
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2022-10-17

The following list defines the data sets and their respective variables.

Global Land and Ocean Temperature Anomalies, November:

https://www.ncdc.noaa.gov/cag/global/time-series/globe/land_ocean/1/11/1880-2020/data.csv

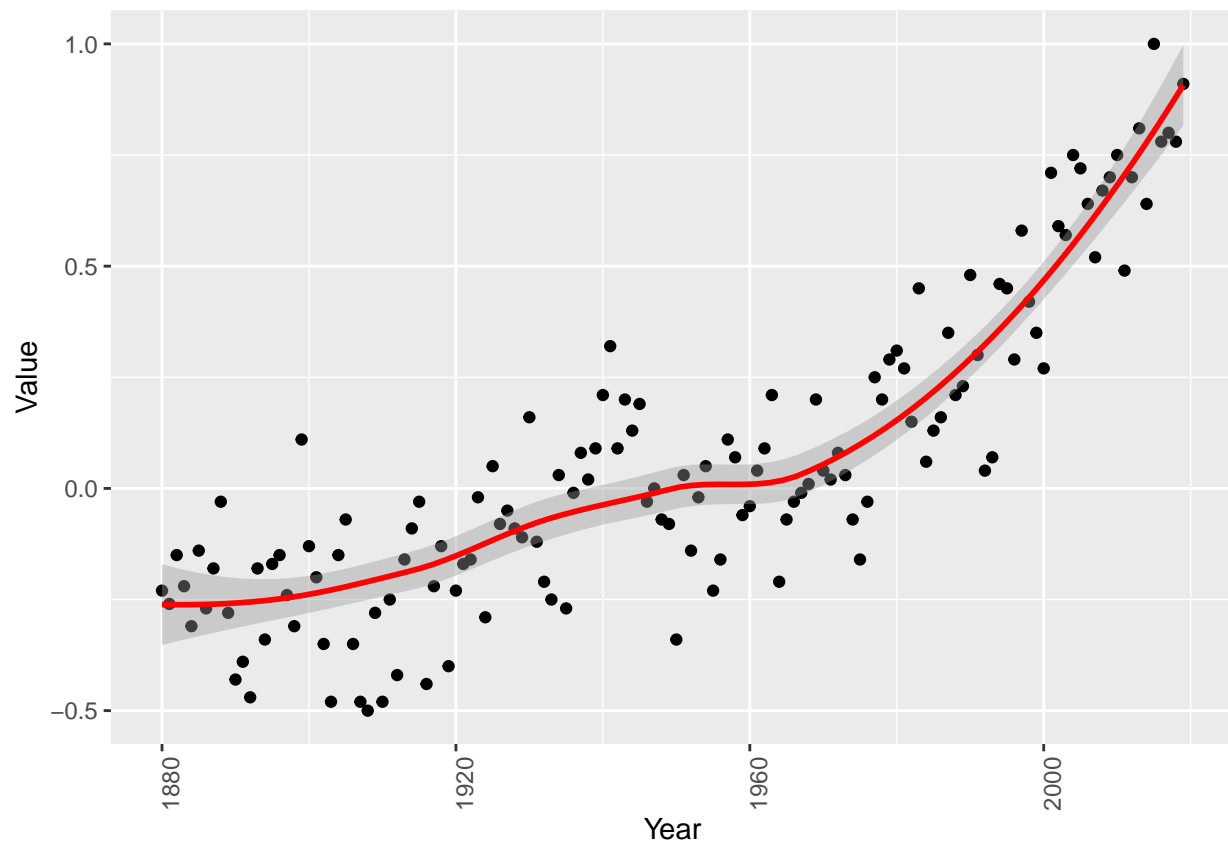
- Units in Degrees Celsius
- Base Period is 1901-2000
- Missing data indicator is -999
- Decades by year of global land and ocean temperature anomalies.
 - Year beginning with 1880 and ending with year 2020
 - Value: Average annual temperatures deviation from base period in degrees Celsius

Your objective is to explore the time series behavior of these data sets including EDA, modeling, model diagnostics, and interpretation.

1. EDA: Global Land and Ocean Temperature Anomalies (20 points)

Conduct a complete EDA on the global land and ocean temperature anomalies.

Let us create a general plot of the data:



We see a general upward trend in the data.

Validate data as a time series:

```
## [1] 140
```

```
## [1] 140
```

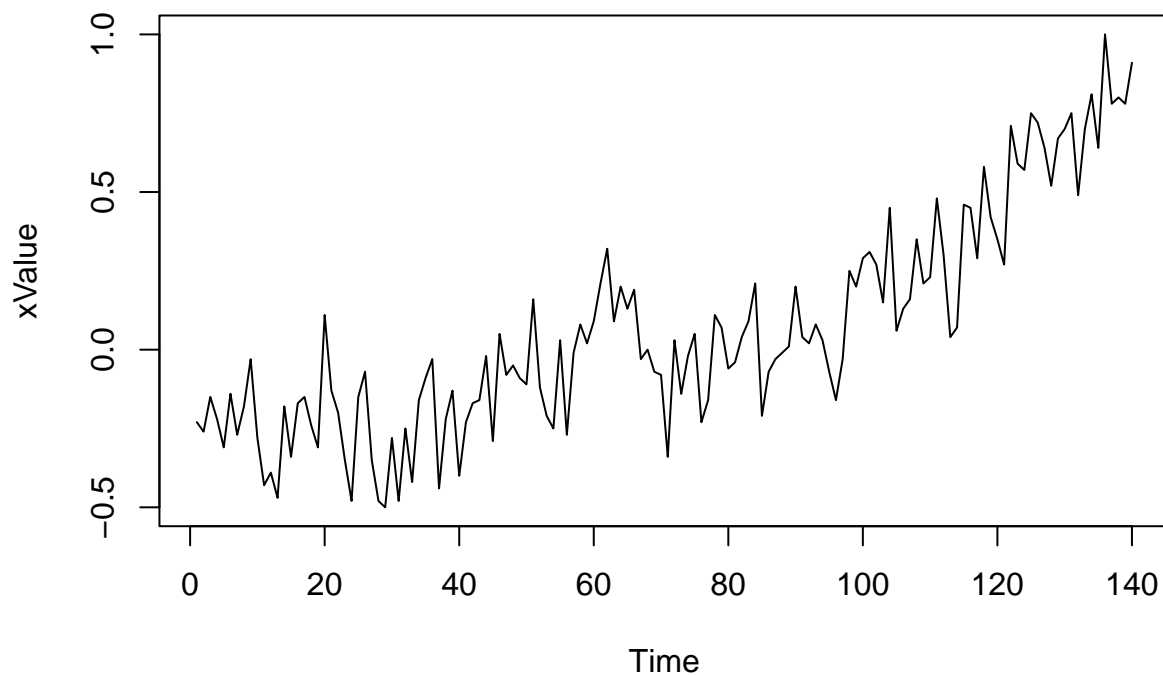
We have 140 unique years in 140 observations, which meets the $H_{10} : x_{it}, i \in \{1, 2\}, t \in \{1, 2, \dots, n\}$ requirement for time series validation.

```
## [1] 140
```

```
## dif
## 1
## 139
```

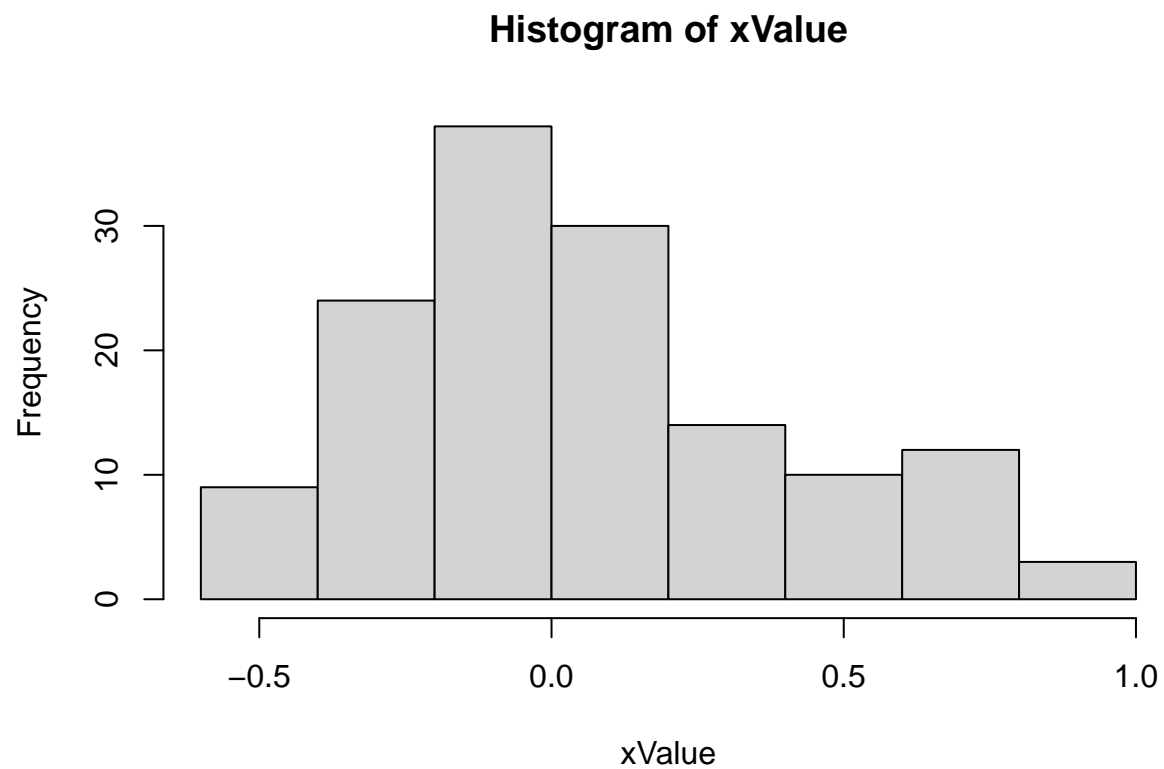
From the test above, we can verify that the constant time span between each date is only one year, denoted by the single value 1. This meets the $H_{20} : (t+1) - t = c, t \in \{1, 2, \dots, n\}$ requirement for time series validation.

Plot:



The plot of the time series data shows non-constant variance with $\text{mean} \neq 0$, especially with how it has an upwards trend.

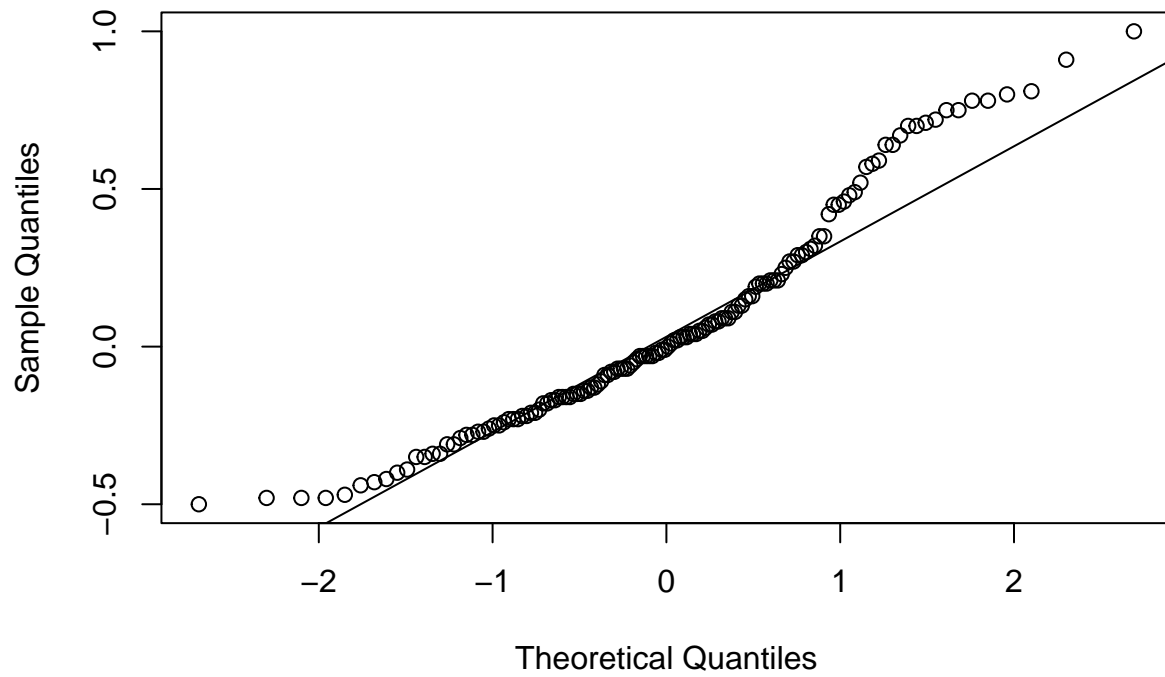
Histogram:



We see the distribution of the data has right-skewed.

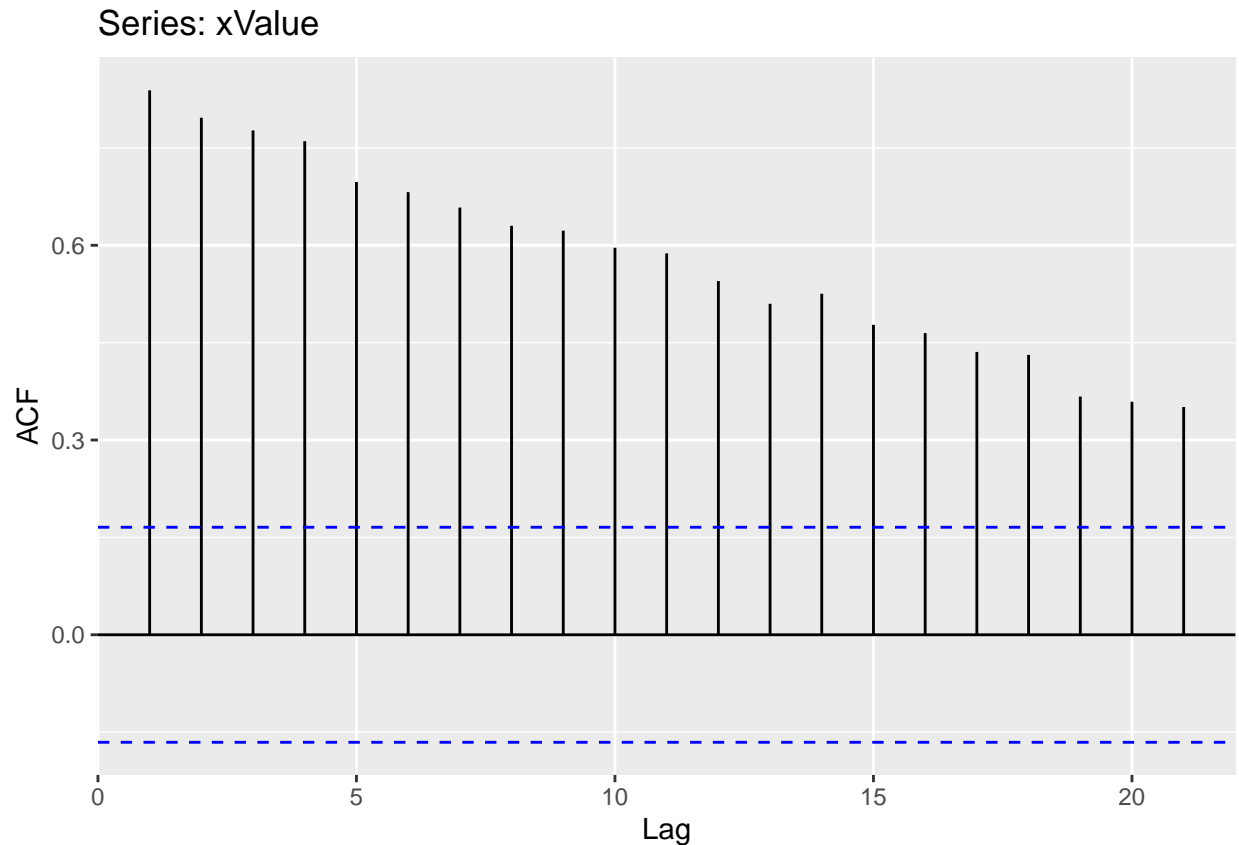
Q-Q Plot:

Normal Q-Q Plot



While most of the data lies on the ideal normal line, a large portion on the right end tends to veer from the line, demonstrating skewness and kurtosis, and not ideally normal in respect to a Gaussian PDF.

Stationarity:



We can see with how the time series data stands, it is not stationary.

EACF:

```
## AR/MA
##  0 1 2 3 4 5 6 7 8 9 10 11 12 13
## 0 x x x x x x x x x x x x x
## 1 x o o o o o o o o o o o x x
## 2 x o o o o o o o o o o o o o
## 3 x o x o o o o o o o o o o o
## 4 o x x x o o o o o o o o o o
## 5 x o x o o o o o o o o o o o
## 6 x x x o o o o o o o o o o o
## 7 x x x o o o x o o o o o o o
```

From the plot above we find it difficult to determine p and q values for $ARMA(p,q)$, as it is not in an ideal shape to easily interpret what is the best p and q values to use for a model.

T-Test for Mean 0:

```
##
## One Sample t-test
##
## data: data
## t = 2.1663, df = 139, p-value = 0.03199
## alternative hypothesis: true mean is not equal to 0
## 95 percent confidence interval:
```

```
## 0.005480935 0.120090494
## sample estimates:
## mean of x
## 0.06278571
##
## T-Test: mean *NOT* statistically zero, linear trend present ->
## reject H0

## [1] FALSE
```

The 95% Confidence Interval (CI) does not include 0 (but just barely!), therefore the mean of Value is not statistically 0, therefore a linear trend is present in the data.

Skewness:

```
##      skew      lwr.ci      upr.ci
## 0.6966006 0.6949931 0.7112777
## Skew: has *RIGHT* skewness,
## property does *NOT* conform to normality and Gaussian PDF

## [1] FALSE
```

Right skewness of the time series data show the time series data is not normal to a Gaussian PDF.

(excess) Kurtosis:

```
##      kurt      lwr.ci      upr.ci
## -0.2008604 -0.2581646 -0.2144355
## Kurt: has *FLAT thin-tailed* (excess) kurtosis,
## property does *NOT* conform to normality and Gaussian PDF

## [1] FALSE
```

Flat Kurtosis of the time series data show the time series data is not normal to a Gaussian PDF.

Constant Variance:

```
##
## studentized Breusch-Pagan test
##
## data:  lm(data ~ seq(1, length(data)))
## BP = 3.6876, df = 1, p-value = 0.05482
##
## Breusch-Pagan: constant variance, homoscedastic ->
## *FAIL* to reject H0

## BP
## TRUE
```

The Breusch-Pagan test show that the time series data has constant variance.

Lag independence:

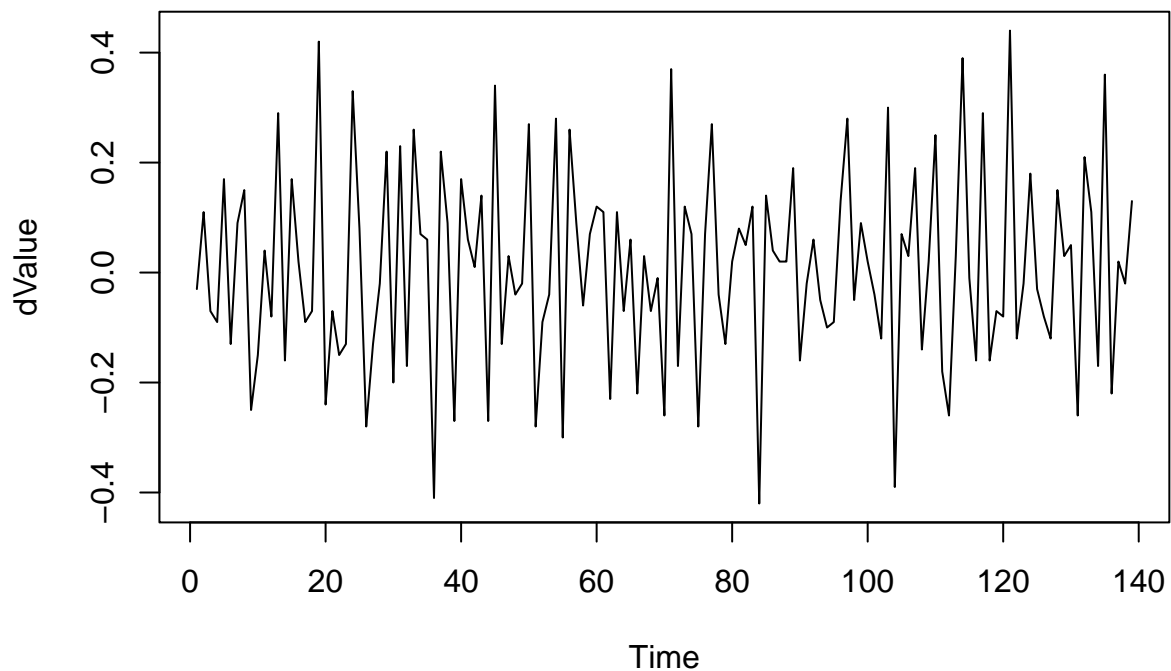
```
##
## Box-Ljung test
##
## data: data
## X-squared = 1101.3, df = 20, p-value < 2.2e-16
##
## Box-Ljung: implies dependency present over 20 lags,
## autocorrelation present -> reject H0

## [1] FALSE
```

he test above show that there is lag dependency within the time series data.

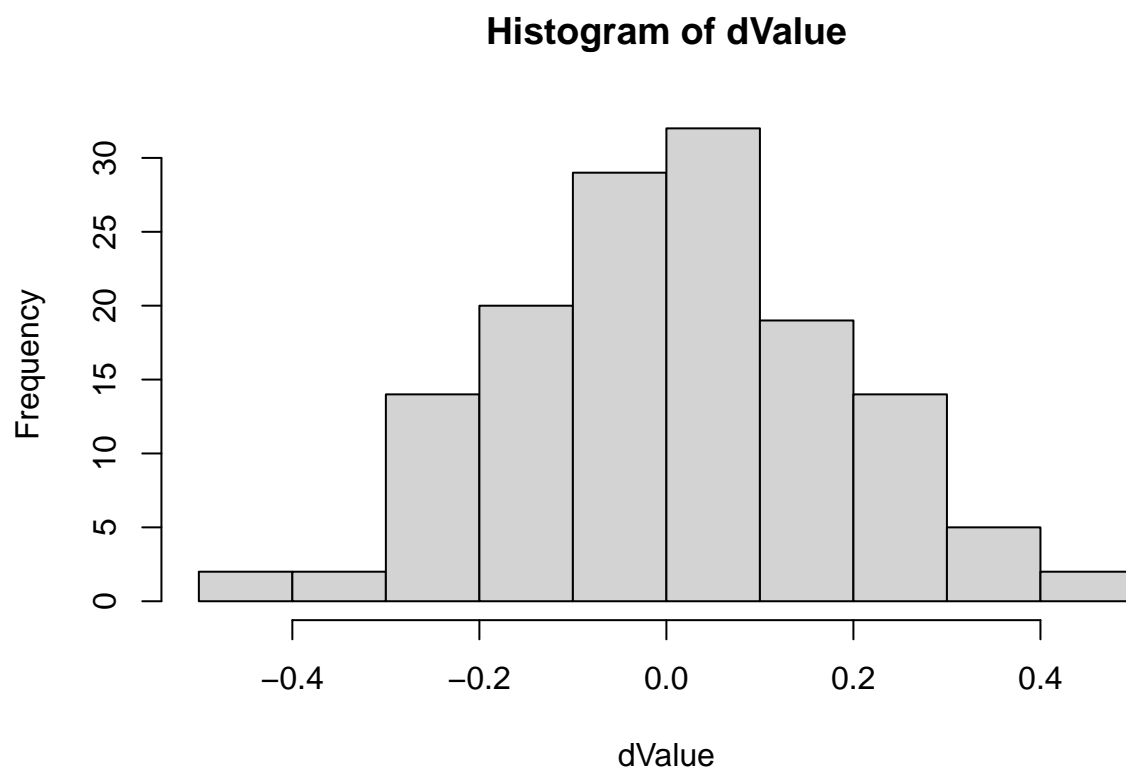
Given the tests results above, especially with the t-test not having mean 0, a linear trend is present. Let us transform the data with the 1st difference (`diff(Value)`) to see if we can remove the linear trend.

`diff(Value)` plot:



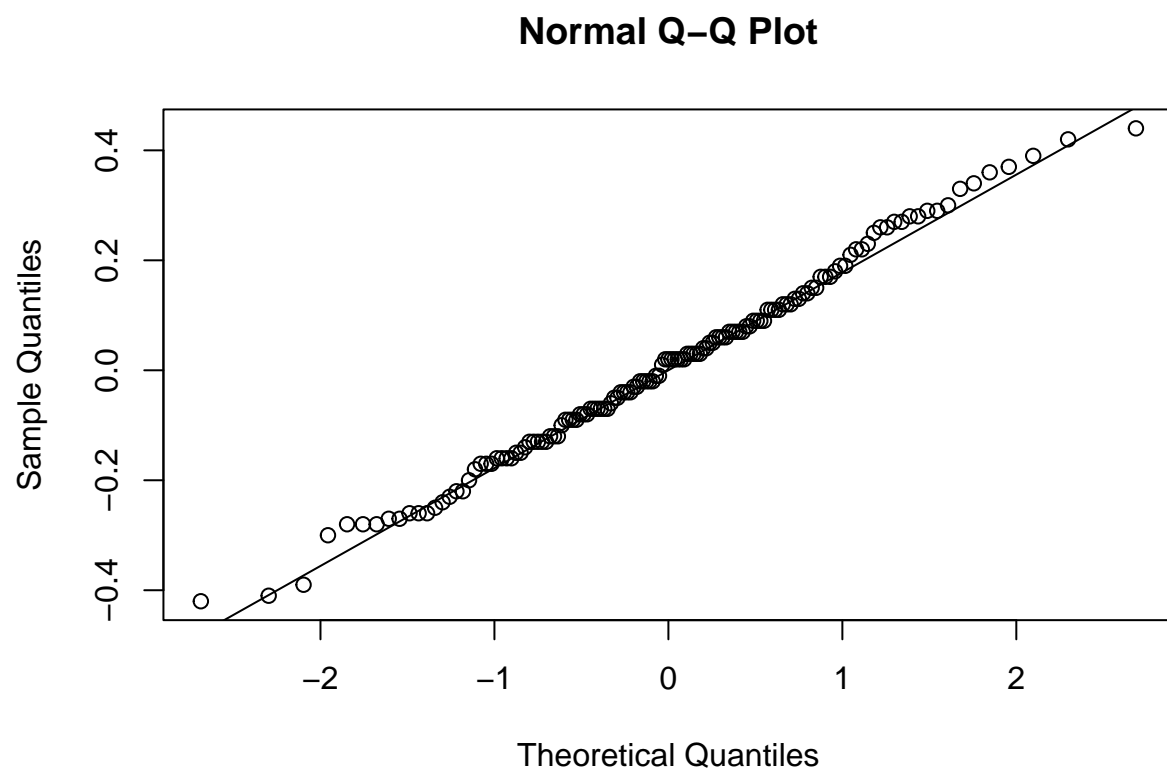
We observe the plot of `diff(Value)` to have constant variance and mean zero, and also mean that the linear slope is removed.

`diff(Value)` normalcy: histogram



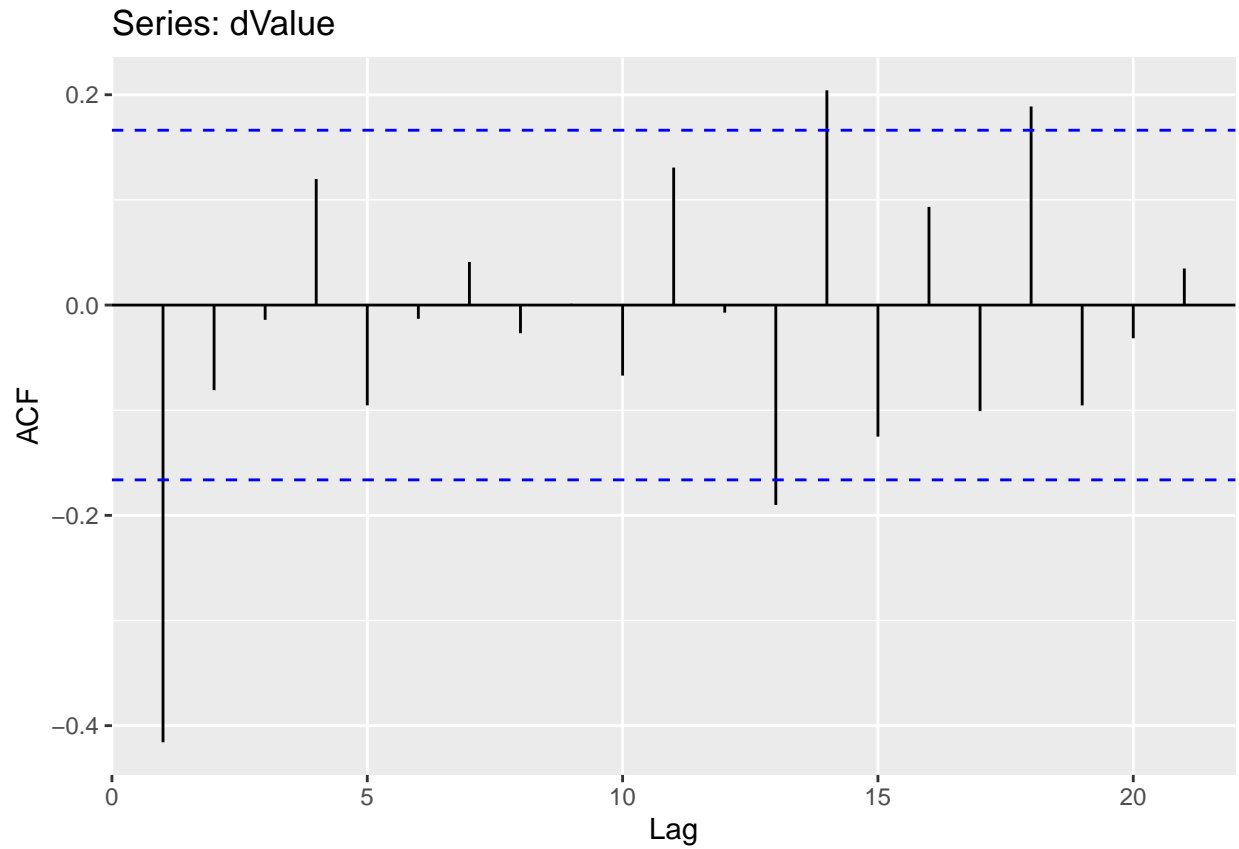
We observe right skewness and flat (excess) Kurtosis in the distribution histogram.

diff(Value) normalcy: Q-Q Plot



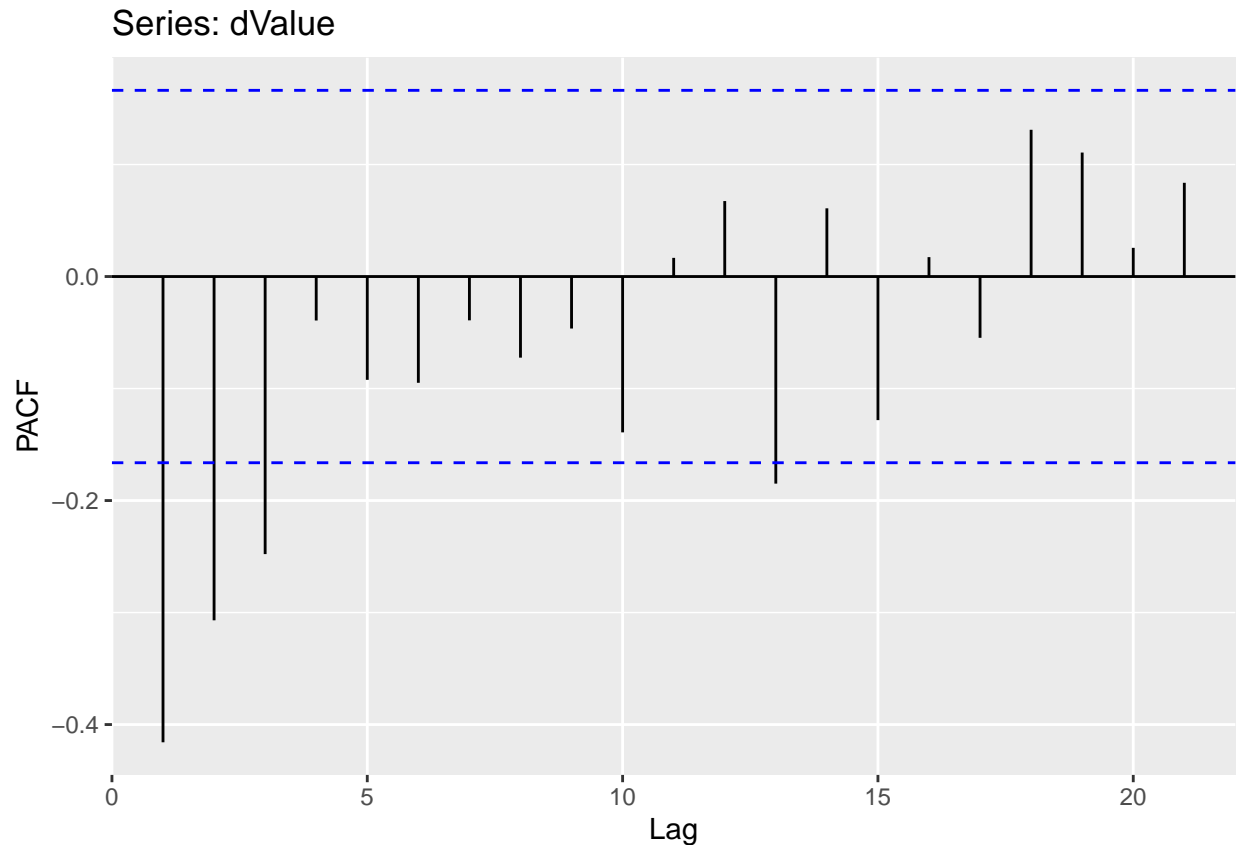
We see slight skewness and kurtosis at the ends of the the Q-Q plot, indicating `diff(Value)` time series data is not normal in respect to a Gaussian PDF.

ACF plot: `diff(Value)`



The ACF plot above shows us to choose $q=1$ in our `ARMA()` model.

PACF Plot: `diff(Value)`:



The PACF plot above shows us to choose $p=1$ in our `ARMA()` model.

`diff(Value)` t-test for mean 0:

```
##
## One Sample t-test
##
## data: data
## t = 0.53782, df = 138, p-value = 0.5916
## alternative hypothesis: true mean is not equal to 0
## 95 percent confidence interval:
## -0.02195121 0.03835409
## sample estimates:
## mean of x
## 0.008201439
##
## T-Test: mean is statistically zero, linear trend *REMOVED* ->
## *FAIL* to reject H0

## [1] TRUE
```

The 95% CI of the t-test interval contains 0, therefore the mean of `diff(Value)` is statistically 0, and that the linear trend is removed.

`diff(Value)` normalcy: skewness

```
##      skew      lwr.ci      upr.ci
```

```
## 0.09067321 0.07957289 0.09876035
## Skew: has *RIGHT* skewness,
## property does *NOT* conform to normality and Gaussian PDF

## [1] FALSE
```

We observe right skewness, indicating `diff(Value)` time series data is not normal in respect to a Gaussian PDF.

`diff(Value)` normalcy: (excess) Kurtosis

```
##      kurt      lwr.ci      upr.ci
## -0.3409097 -0.3372517 -0.3090822
## Kurt: has *FLAT thin-tailed* (excess) kurtosis,
## property does *NOT* conform to normality and Gaussian PDF

## [1] FALSE
```

We observe flat (excess) Kurtosis, indicating `diff(Value)` time series data is not normal in respect to a Gaussian PDF.

`diff(Value)` constant variance: Breusch-Pagan test

```
##
## studentized Breusch-Pagan test
##
## data:  lm(data ~ seq(1, length(data)))
## BP = 0.0040774, df = 1, p-value = 0.9491
##
## Breusch-Pagan: constant variance, homoscedastic ->
## *FAIL* to reject H0

## BP
## TRUE
```

We observe constant variance in the `diff(Value)` time series data.

`diff(Value)` lag independence: Box-Ljung test

```
##
## Box-Ljung test
##
## data:  data
## X-squared = 62.999, df = 30, p-value = 0.0003931
##
## Box-Ljung: implies dependency present over 30 lags,
## autocorrelation present -> reject H0

## [1] FALSE
```

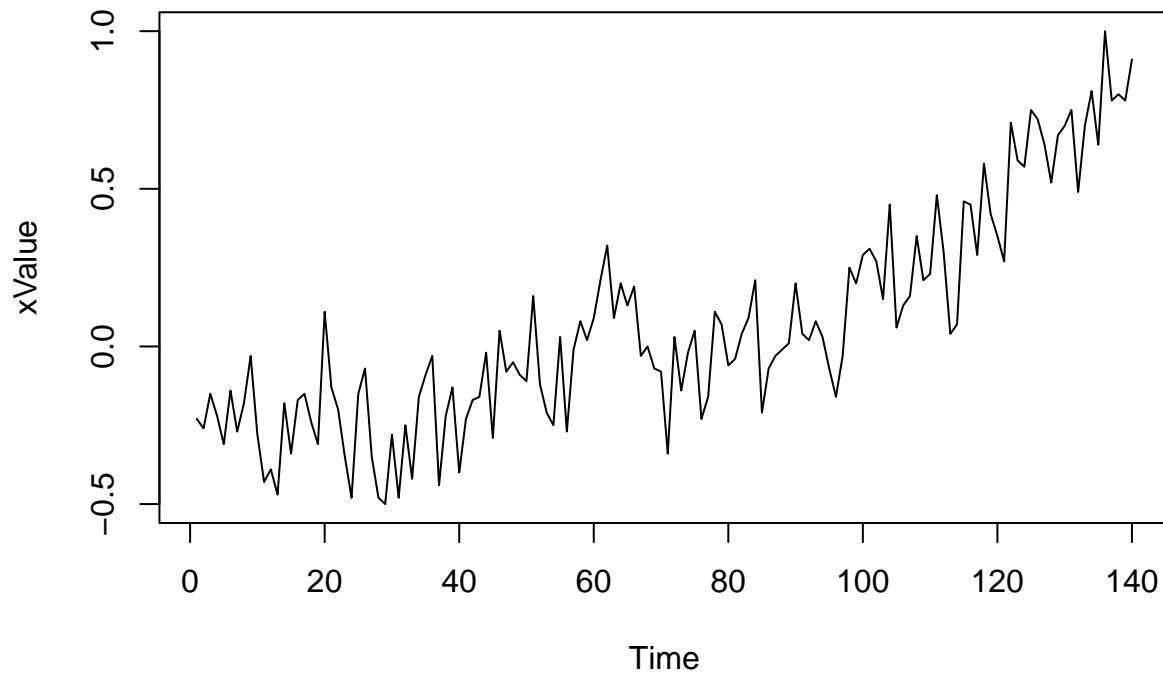
The Box-Ljung test indicates lag dependence within the `diff(Value)` time series data.

2. Seasonal Autoregressive Moving Average (SARMA) Models (20 points)

Based on the EDA from part 1, construct a SARMA model for the global land and ocean temperature anomalies as follows.

2.1. Your EDA should have identified a trend. Justify that this trend has been removed.

Our EDA had a plot of the time series data with the following:



We can see an upward trend throughout the plot.

Our t-test for mean zero gives us the following:

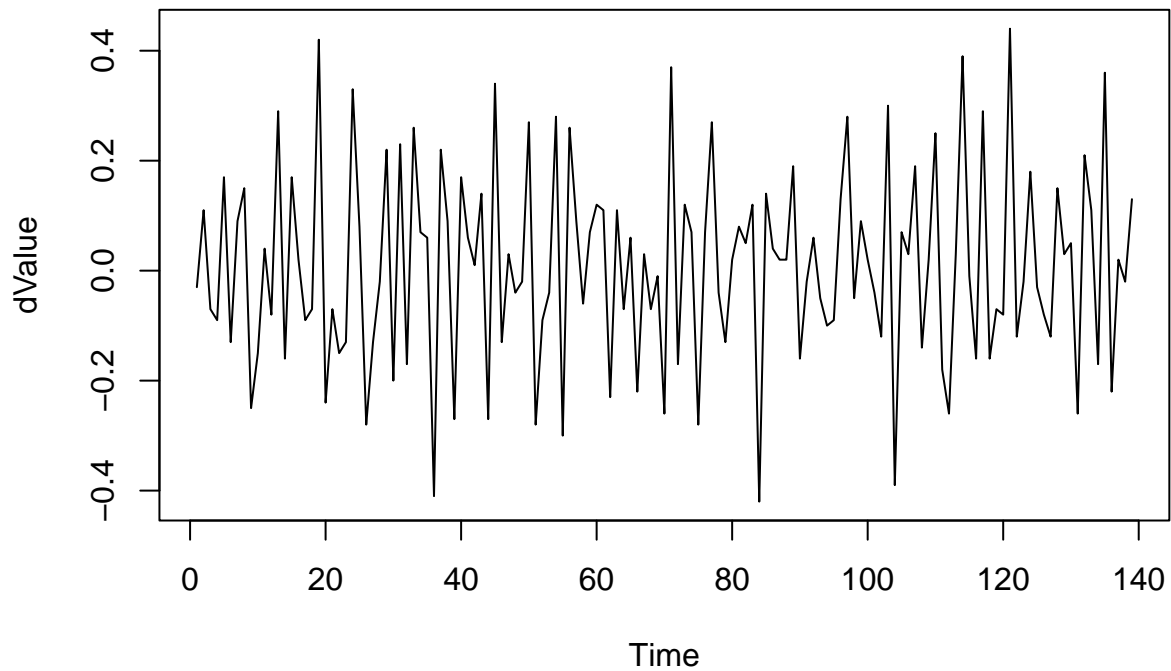
```
##
## One Sample t-test
##
## data: data
## t = 2.1663, df = 139, p-value = 0.03199
## alternative hypothesis: true mean is not equal to 0
## 95 percent confidence interval:
## 0.005480935 0.120090494
## sample estimates:
## mean of x
## 0.06278571
##
## T-Test: mean *NOT* statistically zero, linear trend present ->
## reject H0
```

```
## [1] FALSE
```

The 95% Confidence Interval (CI) of the t-test does not contain zero, therefore the mean of the Value data is not anywhere close to zero.

Because of the plot and a non-zero mean, we can confirm a linear trend in the Value data.

We transform the data by taking the first difference $\text{diff}(\text{Value})$ and create the following plot:



We can eyeball a non-linear trend in the plot by its linear flatless (and we also notice constant variance), but we'll perform a t-test for mean 0 to confirm our findings.

```
##
## One Sample t-test
##
## data: data
## t = 0.53782, df = 138, p-value = 0.5916
## alternative hypothesis: true mean is not equal to 0
## 95 percent confidence interval:
## -0.02195121 0.03835409
## sample estimates:
## mean of x
## 0.008201439
##
## T-Test: mean is statistically zero, linear trend *REMOVED* ->
## *FAIL* to reject H0

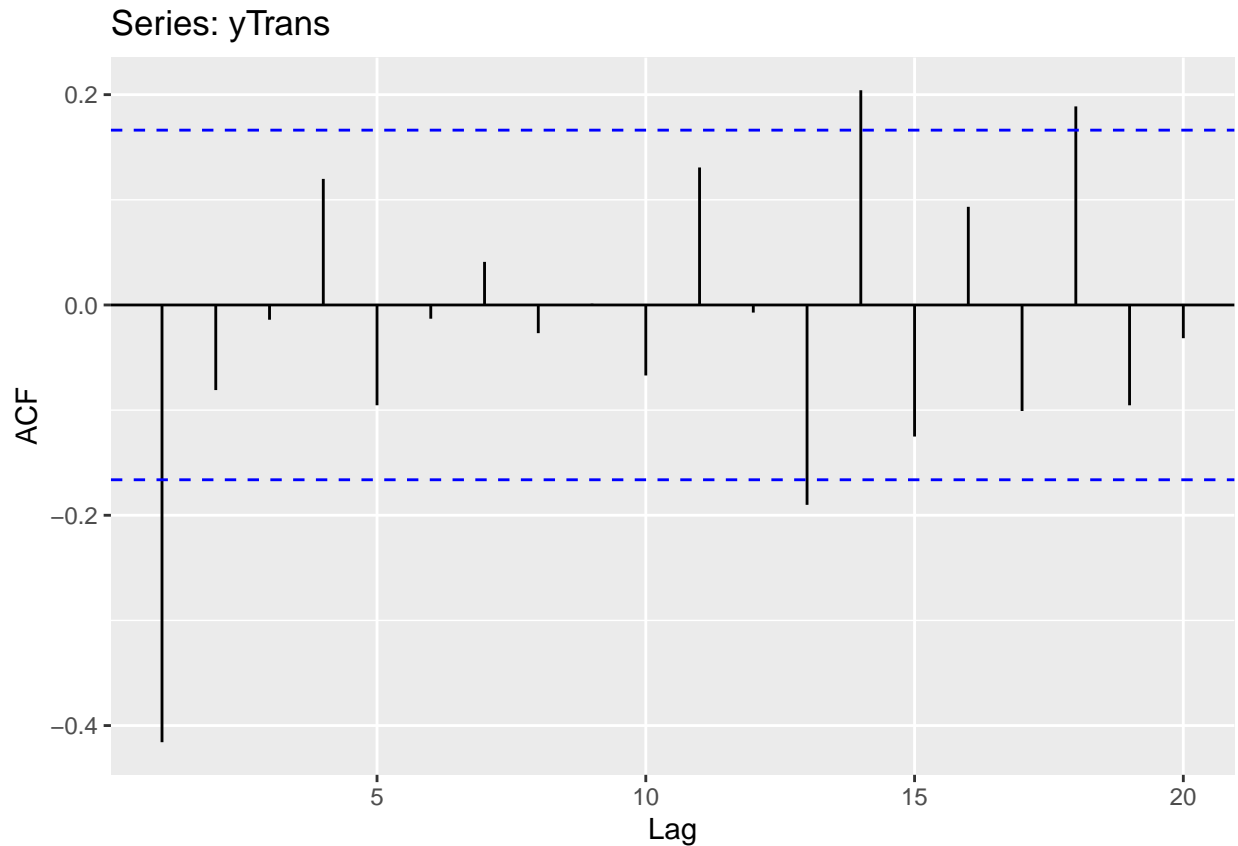
## [1] TRUE
```

The 95% CI of the t-test does contains zero, therefore the mean of the diff(Value) is statistically zero.

With the linear flatnes and mean zero of diff(Value), we can confirm that the linear trend is removed in a diff(Value) transformation.

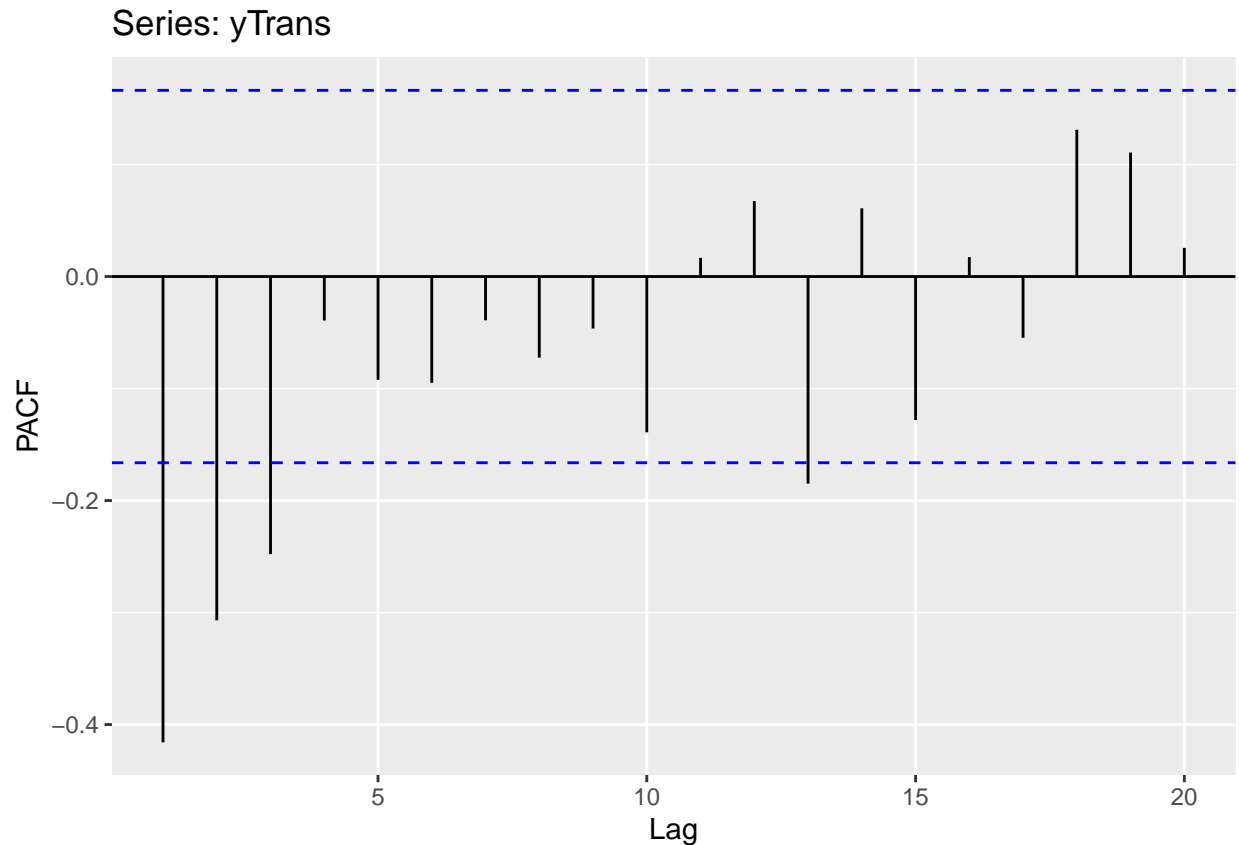
2.2. Write the equation ($x_t = c + \phi_1 x_{t-1} + \dots + \phi_1 z_t + \phi_2 z_{t-1} + \dots =$) of a $ARMA(p, q)$ model then construct an $ARMA(p, q)$ model both based on your choice of d for the temperature deviation series. Perform model checking using $lag = 20$. Is the model adequate? Why?

The ACF plot for diff(Value) is the following:



The plot implies a 1st order Moving-Average model, or MA(1).

The PACF plot for diff(Value) is the following:



The plot implies a 3rd order Moving-Average model, or AR(3).

Combined, we have an ARMA(3,1) model with the following summary:

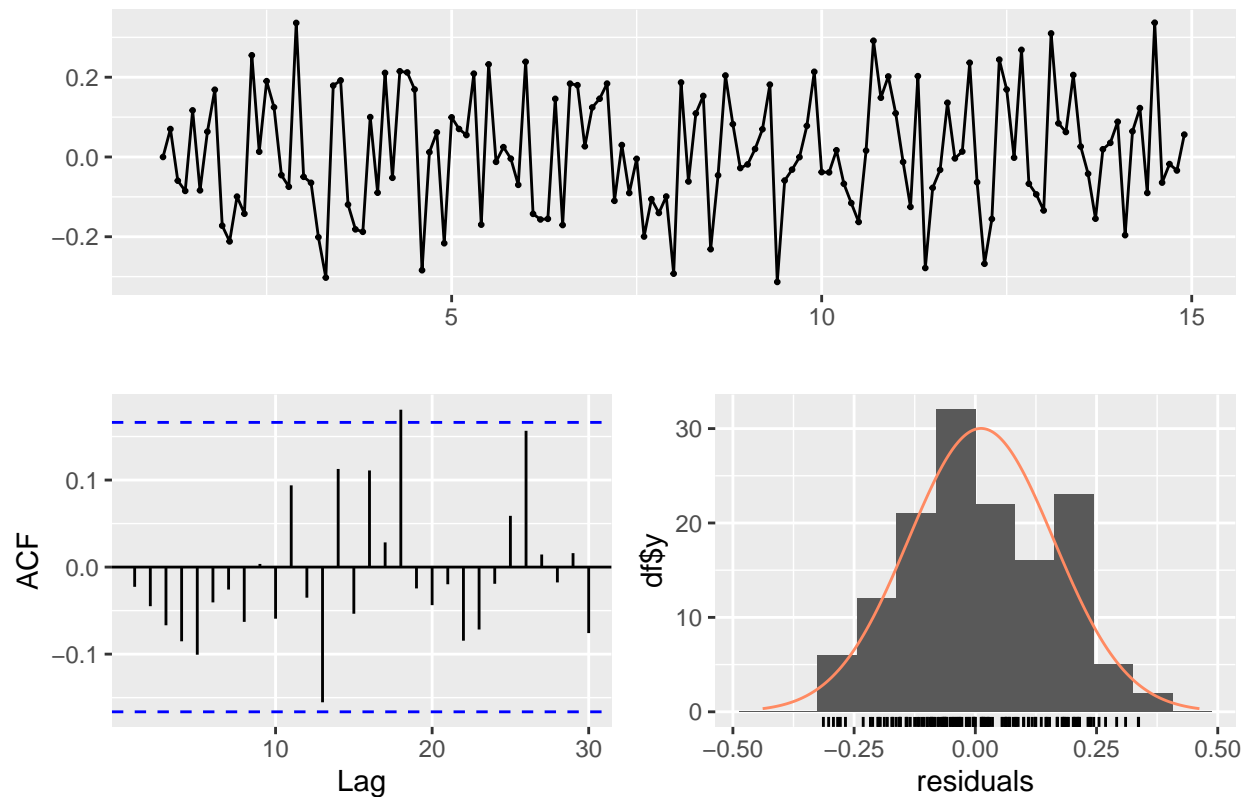
```
## Series: yTrans
## ARIMA(3,1,1)
##
## Coefficients:
##      ar1      ar2      ar3      ma1
##      -0.6130 -0.4320 -0.2398 -1.0000
## s.e.   0.0826   0.0902   0.0819   0.0466
##
## sigma^2 = 0.02335:  log likelihood = 61.88
## AIC=-113.77  AICc=-113.31  BIC=-99.13
##
## Training set error measures:
##              ME      RMSE      MAE      MPE      MAPE      MASE
## Training set 0.01177432 0.1500453 0.1235745 76.54708 140.338 0.5901931
##              ACF1
## Training set -0.02266654
```

Given the coefficients above, we have the following ARMA(3,1) equation:

$$x_t = -0.613x_1 - 0.4320x_2 - 0.2398x_3 - z_1$$

Check residuals for ARMA(3,1):

Residuals from ARIMA(3,1,1)



```
##
##  Ljung-Box test
##
## data:  Residuals from ARIMA(3,1,1)
## Q* = 20.552, df = 16, p-value = 0.1964
##
## Model df: 4.    Total lags used: 20
```

The residuals plot looks like it have constant variance with mean 0. The ACF plot looks stationary with only one lag exceeding the 95% CI threshold. The distribution of residuals look to have some skew and a relatively flat kurtosis, implying it might not be normal in respect to a Gaussian PDF.

ARMA(3,1) T-Test for mean 0:

```
##
##  One Sample t-test
##
## data:  data
## t = 0.92469, df = 138, p-value = 0.3567
## alternative hypothesis: true mean is not equal to 0
## 95 percent confidence interval:
##  -0.01340332  0.03695195
## sample estimates:
##  mean of x
##  0.01177432
##
```

```
## T-Test: mean is statistically zero, linear trend *REMOVED* ->
## *FAIL* to reject H0
```

```
## [1] TRUE
```

The t-test 95% CI contains zero, therefore the mean of the residuals is statistically zero, and that the linear trend has been removed.

ARMA(3,1) normality: skewness

```
##      skew      lwr.ci      upr.ci
## 0.022883405 0.005976316 0.022646889
## Skew: has *RIGHT* skewness,
## property does *NOT* conform to normality and Gaussian PDF
```

```
## [1] FALSE
```

ARMA(3,1) shows some slight right skewness, therefore not normal in respect to a Gaussian PDF.

ARMA(3,1) normality: (excess) Kurtosis

```
##      kurt      lwr.ci      upr.ci
## -0.7330116 -0.7431841 -0.7231341
## Kurt: has *FLAT thin-tailed* (excess) kurtosis,
## property does *NOT* conform to normality and Gaussian PDF
```

```
## [1] FALSE
```

ARMA(3,1) shows some slight flat (excess) Kurtosis, therefore not normal in respect to a Gaussian PDF.

ARMA(3,1) stationarity: KPSS

```
##
## #####
## # KPSS Unit Root Test #
## #####
##
## Test is of type: tau with 4 lags.
##
## Value of test-statistic is: 0.0275
##
## Critical value for a significance level of:
##          10pct  5pct 2.5pct  1pct
## critical values 0.119 0.146 0.176 0.216
##
## KPSS: *NO* unit roots, *NO* linear trend, slope zero,
## series is trend stationary -> *FAIL* to reject H0
```

```
## [1] TRUE
```

The ARMA(3,1) KPSS test shows no unit roots, therefore the model residuals are stationary.

ARMA(3,1) stationarity: ADF

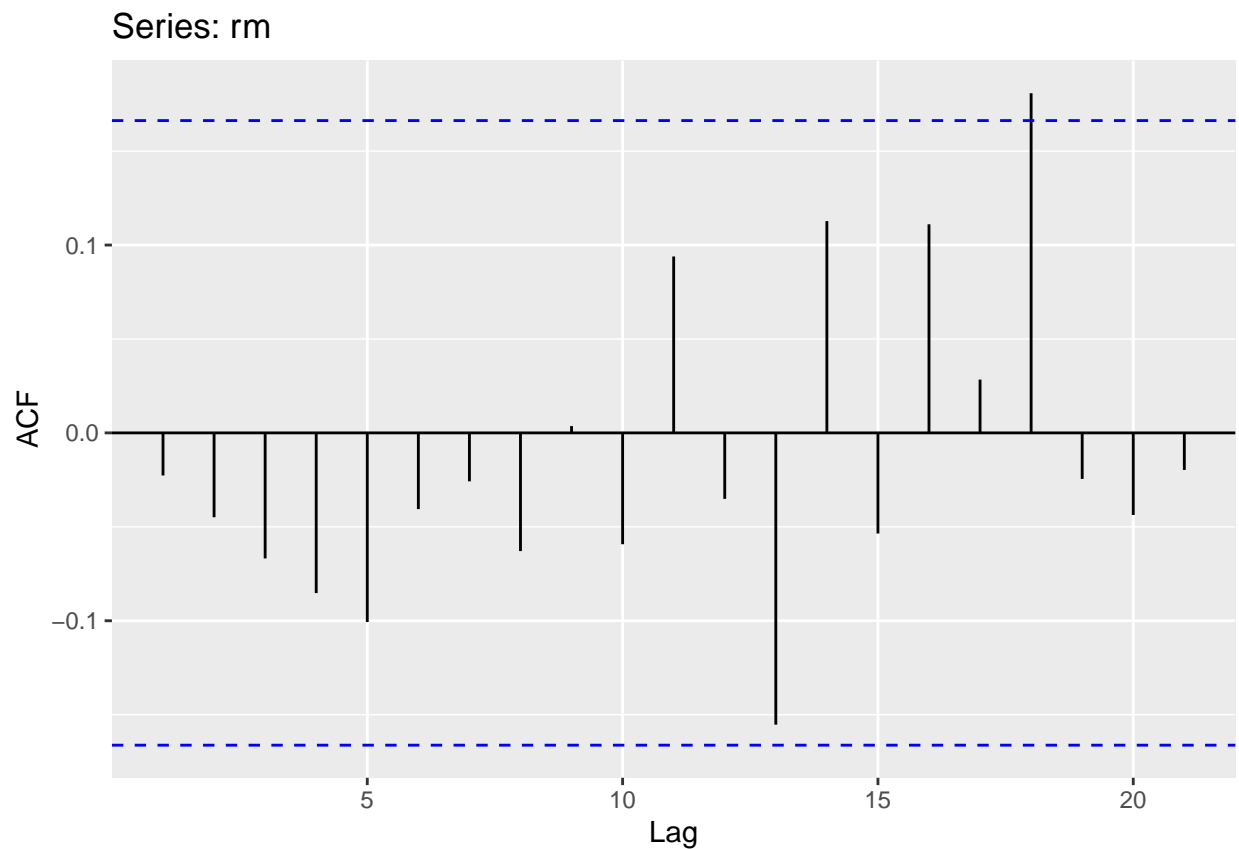
```

##
## Title:
## Augmented Dickey-Fuller Test
##
## Test Results:
## PARAMETER:
## Lag Order: 20
## STATISTIC:
## Dickey-Fuller: -1.8502
## P VALUE:
## 0.06479
##
## Description:
## Tue Mar 28 19:50:28 2023 by user: Reed
##
## ADF: presence of unit roots over 20 lags, indicates mean drift,
## business cycles present, series is *NOT* stationary -> *FAIL* to reject H0

##
## TRUE

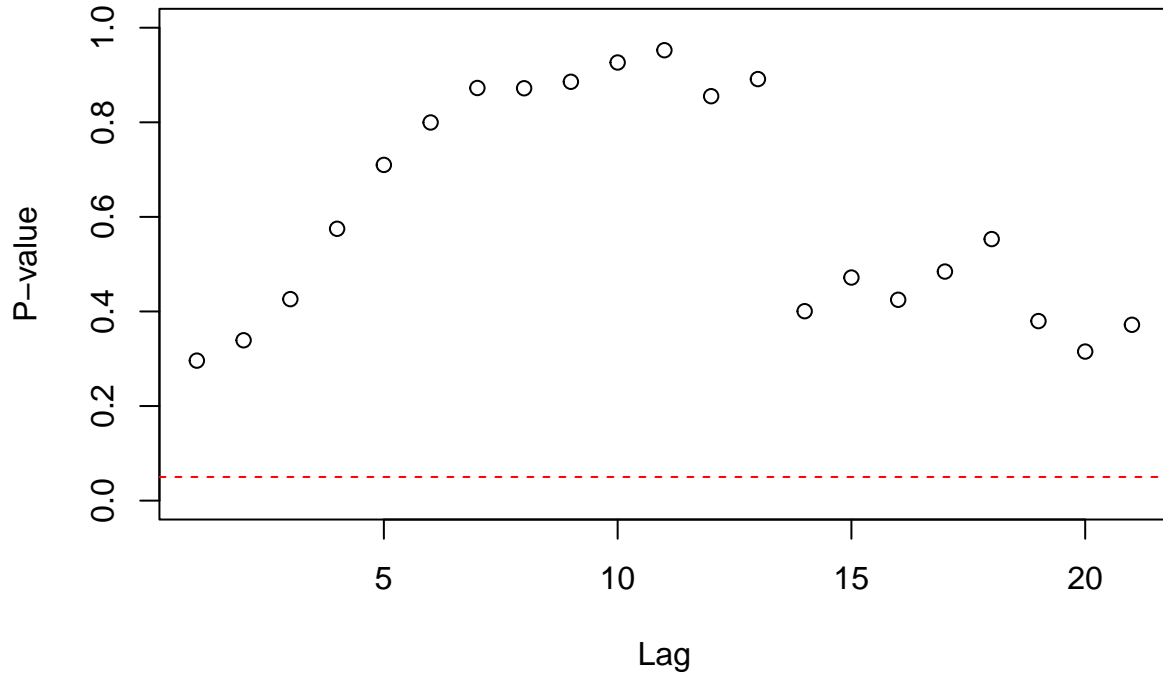
```

Contrary to the KPSS test, the ADF test shows the ARMA(3,1) model residuals are not stationary, with the p-value just greater than the 0.05 critical value. Given the ACF plot:



We can visually see the residuals look fairly stationary. The ADF test could be taking slight mean drift into account. But since two of three indicators of stationarity, the KPSS test and the ACF plot, show the residuals are stationary, we will go with the narrative that the model residuals are stationary overall.

ARMA(3,1) constant variance: McLeod-Li



```
## McLeod-Li: constant variance, homoscedastic -> *FAIL* to reject H0
```

```
## [1] TRUE
```

While the residuals plot showed signs of constant variance within the ARMA(3,1) model residuals, the McLeod-Li further supports it.

ARMA(3,1) constant variance: Breush-Pagan

```
##
## studentized Breusch-Pagan test
##
## data:  lm(data ~ seq(1, length(data)))
## BP = 0.28308, df = 1, p-value = 0.5947
##
## Breusch-Pagan: constant variance, homoscedastic ->
## *FAIL* to reject H0
##
## BP
## TRUE
```

The Breusch-Pagan test further supports constant variance within the ARMA(3,1) model residuals.

ARMA(3,1) lag dependence: Box-Ljung

```
##
## Box-Ljung test
##
## data: data
## X-squared = 20.552, df = 20, p-value = 0.4239
##
## Box-Ljung: implies independence over 20 lags,
## *NO* autocorrelation -> *FAIL* to reject H0

## [1] TRUE
```

The ARMA(3,1) model residuals are shown to have lag independence via the Box-Ljung test.

ARMA(3,1) business cycles:

```
## [1] 6.229 2.605
```

We find that the ARMA(3,1) model residuals show two business cycles, a 6-year and 3-year cycles.

Given that the model is not normal, contains two business cycles, and mostly stationary, I feel this is still an adequate model to be used for forecasting.

2.3. Fit a seasonal model for the temperature series using the command (d from your EDA):

```
ms <- arima(y, order = c(0,0,0), seasonal = list(order = c(1,d,1)), include.mean = F)
```

Perform model checking including using lag=20 and adjust P and Q to improve the model if needed. Is the seasonal model adequate? Why?

Given we are taking the first difference of Value, or diff(Value), we will set d = 1.

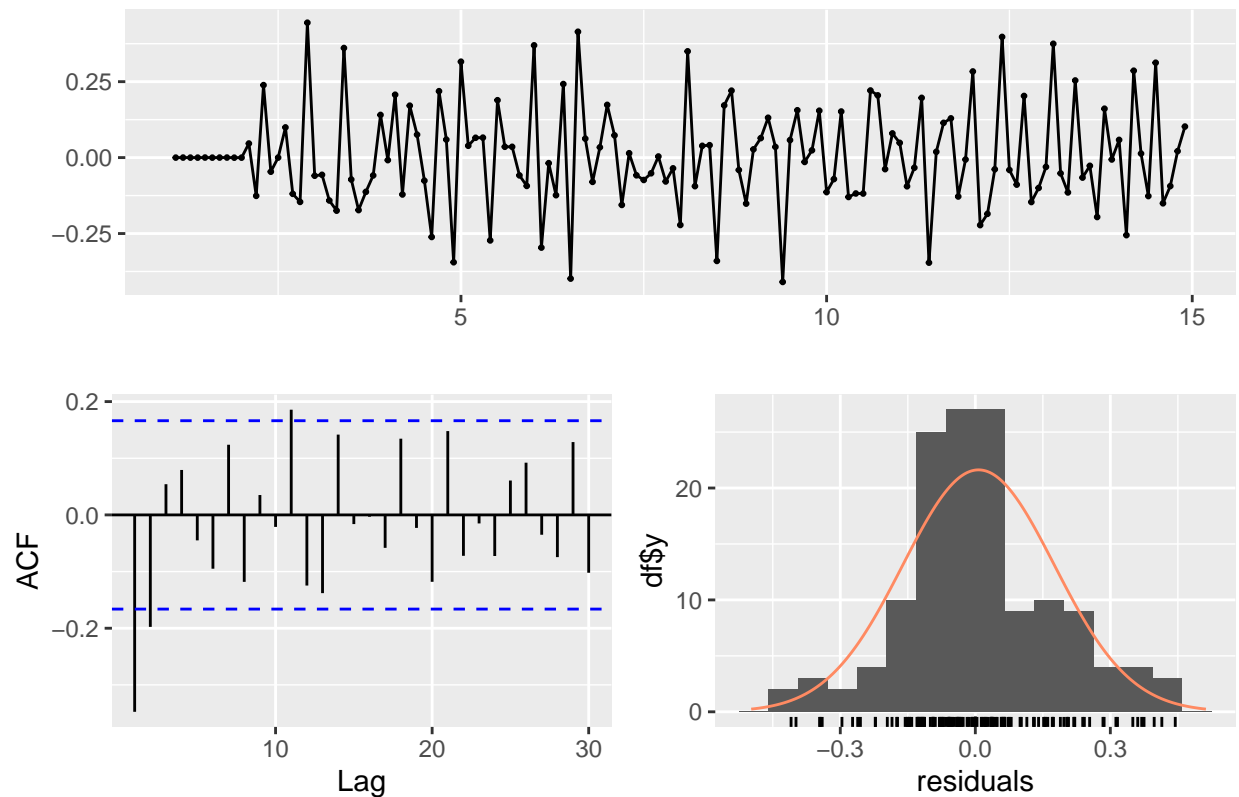
Here is our SARMA(1,1,1) model:

```
# d <- 1
m2 <- Arima(yTrans, order=c(0,0,0), seasonal=list(order=c(1,d,1)), include.mean=F)
summary(m2)
```

```
## Series: yTrans
## ARIMA(0,0,0)(1,1,1)[10]
##
## Coefficients:
##          sar1      sma1
##       -0.1210  -1.0000
## s.e.    0.0928   0.0901
##
## sigma^2 = 0.03086: log likelihood = 28.01
## AIC=-50.03   AICc=-49.83   BIC=-41.45
##
## Training set error measures:
##              ME      RMSE      MAE      MPE      MAPE      MASE
## Training set 0.007172386 0.1679241 0.1266331 100.7622 117.9439 0.6048009
##              ACF1
## Training set -0.3475076
```

SARMA(1,1,1) check residuals:

Residuals from ARIMA(0,0,0)(1,1,1)[10]



```
##
##  Ljung-Box test
##
## data:  Residuals from ARIMA(0,0,0)(1,1,1)[10]
## Q* = 50.012, df = 18, p-value = 7.516e-05
##
## Model df: 2.   Total lags used: 20
```

The residuals plot looks like it have constant variance with mean 0. The ACF plot looks fairly stationary with three lags exceeding the 95% CI threshold. The distribution of residuals look to have some skew and a relatively flat kurtosis, implying it might not be normal in respect to a Gaussian PDF.

SARMA(1,1,1) t-test for mean 0:

```
##
##  One Sample t-test
##
## data:  data
## t = 0.50221, df = 138, p-value = 0.6163
## alternative hypothesis: true mean is not equal to 0
## 95 percent confidence interval:
##  -0.02106668  0.03541145
## sample estimates:
##  mean of x
## 0.007172386
##
```

```
## T-Test: mean is statistically zero, linear trend *REMOVED* ->
## *FAIL* to reject H0
```

```
## [1] TRUE
```

The t-test 95% CI contains zero, therefore the mean of the residuals is statistically zero, and that the linear trend has been removed.

SARMA(1,1,1) normality: skewness

```
##      skew      lwr.ci      upr.ci
## 0.2535558 0.2337455 0.2559845
## Skew: has *RIGHT* skewness,
## property does *NOT* conform to normality and Gaussian PDF
```

```
## [1] FALSE
```

SARMA(1,1,1) shows some slight right skewness, therefore not normal in respect to a Gaussian PDF.

SARMA(1,1,1) normality: (excess) Kurtosis

```
##      kurt      lwr.ci      upr.ci
## 0.1839347 0.1754081 0.2131140
## Kurt: has *TALL thick-tailed* (excess) kurtosis,
## property does *NOT* conform to normality and Gaussian PDF
```

```
## [1] FALSE
```

SARMA(1,1,1) shows some slight tall (excess) Kurtosis, therefore not normal in respect to a Gaussian PDF.

SARMA(1,1,1) stationarity: KPSS

```
##
## #####
## # KPSS Unit Root Test #
## #####
##
## Test is of type: tau with 4 lags.
##
## Value of test-statistic is: 0.0271
##
## Critical value for a significance level of:
##          10pct  5pct 2.5pct  1pct
## critical values 0.119 0.146 0.176 0.216
##
## KPSS: *NO* unit roots, *NO* linear trend, slope zero,
## series is trend stationary -> *FAIL* to reject H0
```

```
## [1] TRUE
```

The SARMA(1,1,1) KPSS test shows no unit roots, therefore the model residuals are stationary.

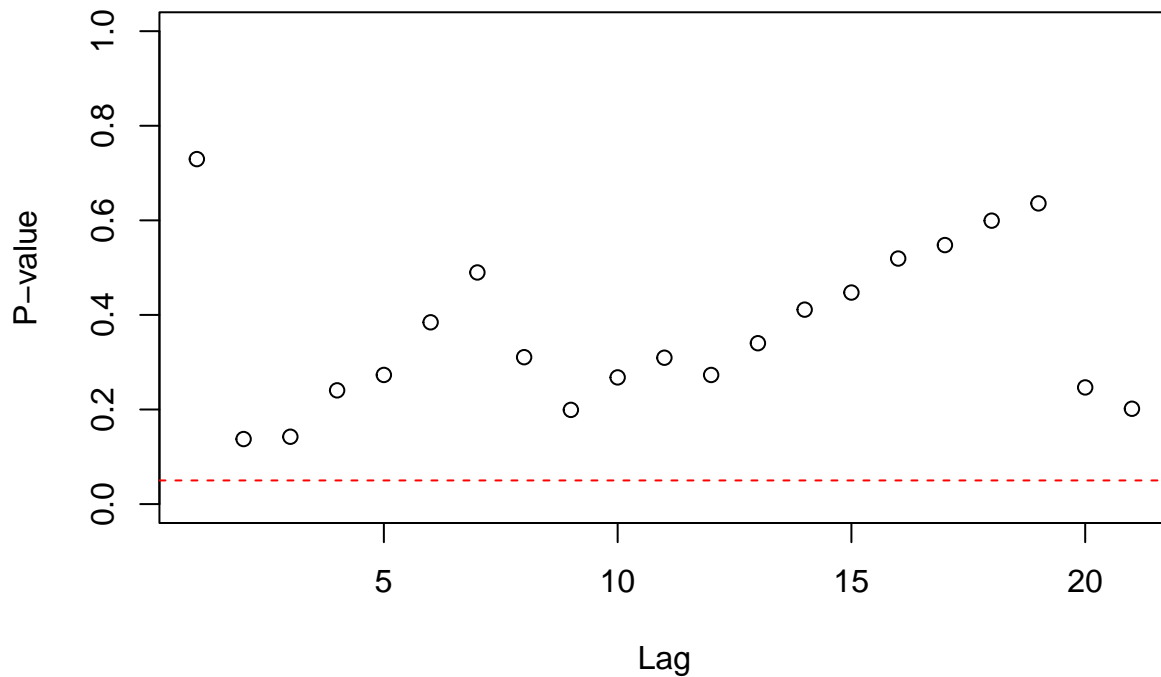
SARMA(1,1,1) stationarity: ADF


```
##
## Title:
## Augmented Dickey-Fuller Test
##
## Test Results:
## PARAMETER:
## Lag Order: 20
## STATISTIC:
## Dickey-Fuller: -2.0551
## P VALUE:
## 0.04086
##
## Description:
## Tue Mar 28 19:50:29 2023 by user: Reed
##
## ADF: contains *NO* unit roots over 20 lags, indicates *NO* mean drift,
## business cycles *NOT* present, series is stationary -> reject H0

##
## FALSE
```

The ADF test for SARMA(1,1,1) also support that its model residuals are stationary.

SARMA(1,1,1) constant variance: McLeod-Li



```
## McLeod-Li: constant variance, homoscedastic -> *FAIL* to reject H0
```

```
## [1] TRUE
```

While the residuals plot showed signs of constant variance within the SARMA(1,1,1) model residuals, the McLeod-Li further supports it.

SARMA(1,1,1) constant variance: Breush-Pagan

```
##
## studentized Breusch-Pagan test
##
## data:  lm(data ~ seq(1, length(data)))
## BP = 0.3432, df = 1, p-value = 0.558
##
## Breusch-Pagan: constant variance, homoscedastic ->
## *FAIL* to reject H0

## BP
## TRUE
```

The Breusch-Pagan test further supports constant variance within the SARMA(1,1,1) model residuals.

SARMA(1,1,1) lag dependence: Box-Ljung

```
##
## Box-Ljung test
##
## data:  data
## X-squared = 50.012, df = 20, p-value = 0.0002206
##
## Box-Ljung: implies dependency present over 20 lags,
## autocorrelation present -> reject H0

## [1] FALSE
```

The SARMA(1,1,1) model residuals are shown to have lag dependence via the Box-Ljung test.

Checking for SARMA(1,1,1) business cycles:

```
## [1] 3.852
```

We find that the SARMA(1,1,1) model show a 4-year business cycle.

Given that the model and its residuals are not normal, contains a business cycle, and lag dependency, I feel this is still an adequate model to be used for forecasting.

We will attempt to see if Auto Arima function can result in an improved SARMA() model:

```
maa <- auto.arima(yTrans, max.p=0, max.q=0, max.d=0, max.D=1, stationary=F, seasonal=T)
summary(maa)
```

```
## Series: yTrans
## ARIMA(0,0,0) with zero mean
##
## sigma^2 = 0.03216: log likelihood = 41.64
```

```
## AIC=-81.29   AICc=-81.26   BIC=-78.36
##
## Training set error measures:
##           ME      RMSE      MAE MPE MAPE      MASE      ACF1
## Training set 0.008201439 0.1793273 0.1440288 100 100 0.6878827 -0.4158355
```

Auto Arima results in a white noise ARMA(0,0) model with zero mean, and will not continue model diagnostics on it.

2.4. Based on in-sample fitting, which model is preferred? Why?

Compare AIC/BIC/RMSE/MAE between ARMA(3,1) and SARMA(1,1,1):

```
## Series: yTrans
## ARIMA(3,1,1)
##
## Coefficients:
##           ar1      ar2      ar3      ma1
##          -0.6130 -0.4320 -0.2398 -1.0000
## s.e.      0.0826  0.0902  0.0819  0.0466
##
## sigma^2 = 0.02335: log likelihood = 61.88
## AIC=-113.77   AICc=-113.31   BIC=-99.13
##
## Training set error measures:
##           ME      RMSE      MAE      MPE      MAPE      MASE
## Training set 0.01177432 0.1500453 0.1235745 76.54708 140.338 0.5901931
##           ACF1
## Training set -0.02266654
```

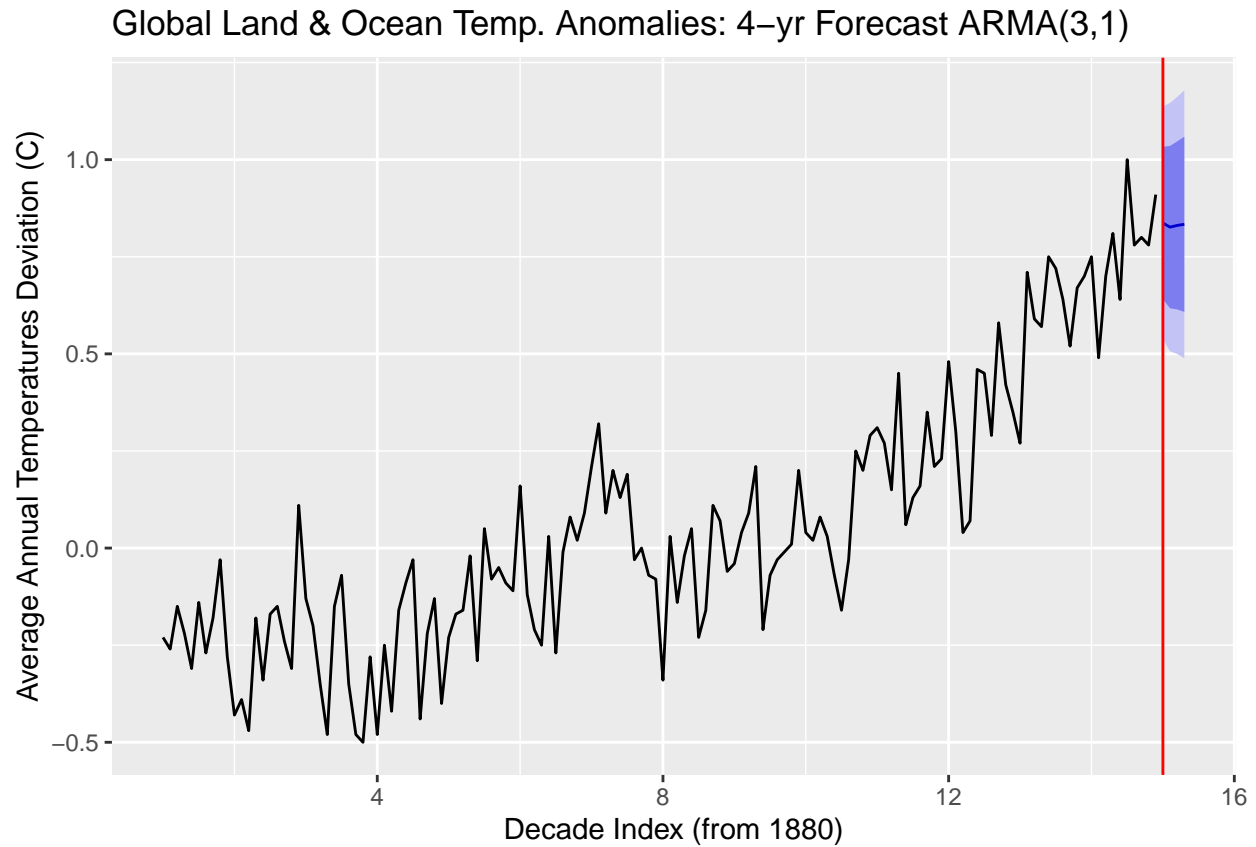
```
## Series: yTrans
## ARIMA(0,0,0)(1,1,1)[10]
##
## Coefficients:
##           sar1      sma1
##          -0.1210 -1.0000
## s.e.      0.0928  0.0901
##
## sigma^2 = 0.03086: log likelihood = 28.01
## AIC=-50.03   AICc=-49.83   BIC=-41.45
##
## Training set error measures:
##           ME      RMSE      MAE      MPE      MAPE      MASE
## Training set 0.007172386 0.1679241 0.1266331 100.7622 117.9439 0.6048009
##           ACF1
## Training set -0.3475076
```

AIC/BIC/RMSE/MAE comparisons seem to favor ARMA(3,1) over SARMA(3,1,1), as ARMA(3,1) has lower values, indicating better performance.

2.5. Consider out-of-sample predictions. Use $t = 100$ as the starting forecast origin. Which model is preferred based on the out-of-sample predictions?

4-year Forecasting: ARMA(3,1) vs SARMA(3,1,1)

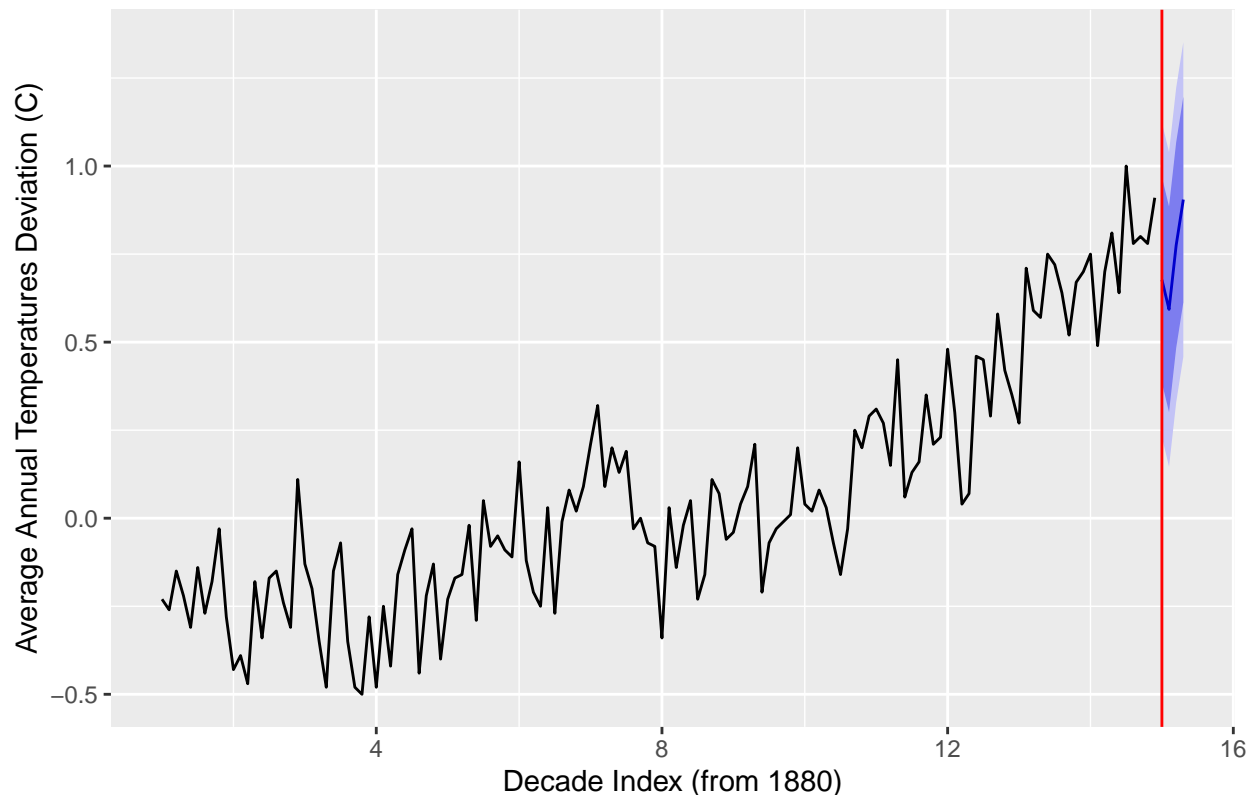
ARMA(3,1):



The ARMA(3,1) forecast shows a fairly constant point forecast with a slight dip, indicated by the dark blue line. The forecast fails to demonstrate seasonality that the time series shows. That being said, the range of the 80% CI shown by the blue area and the 95% CI shown by the lighter blue are not too wide.

SARMA(1,1,1):

Global Land & Ocean Temp. Anomalies: 4-yr Forecast SARMA(1,1,1)



The ARMA(3,1) forecast attempts to demonstrate some of the seasonality shown by the time series, indicated by the dark blue line. That being said, the range of the 80% CI shown by the blue area and the 95% CI shown by the lighter blue is fairly larger than the ARMA(3,1) model.

3. ARMA X SARMA Models (20 points)

Continuing with the global land and ocean temperature anomalies data, construct an ARMA X SARMA model as follows:

3.1. Fit a seasonal model for the temperature series based the ACF and PACF and your choice of d using the command:

```
ms <- Arima(y, order = c(p,d,q), seasonal = list(order = c(1,0,1)), include.mean = F)
```

Perform model checking including using $lag = 20$ and adjust p , q , P , and Q to improve the model if needed. Is the seasonal model adequate? Why?

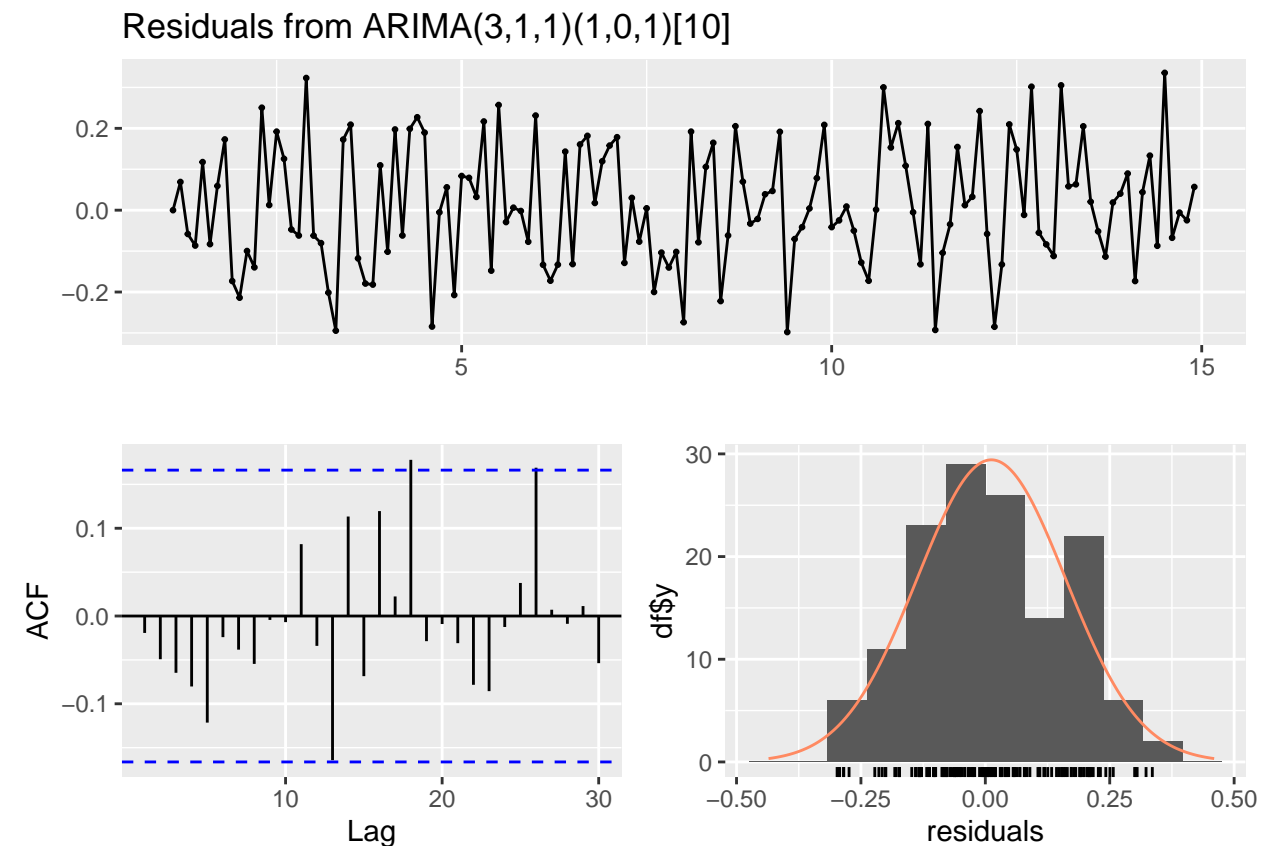
Given we are taking the first difference of Value, or `diff(Value)`, we will set $d = 1$, and $D = 0$ for the seasonal component.

Here is our ARMA(3,1)xSARMA(1,0,1) model:

```
# p <- 3
# d <- 1
# q <- 1
# D <- 0
m3 <- Arima(yTrans, order=pdq, seasonal=list(order=c(1,D,1)), include.mean=F)
summary(m3)
```

```
## Series: yTrans
## ARIMA(3,1,1)(1,0,1)[10]
##
## Coefficients:
##          ar1          ar2          ar3          ma1          sar1          sma1
##        -0.6255   -0.4303   -0.2592   -1.0000    0.6932   -0.7609
## s.e.    0.0872    0.0905    0.0848    0.0751    0.4061    0.3807
##
## sigma^2 = 0.02344:  log likelihood = 62.35
## AIC=-110.69   AICc=-109.83   BIC=-90.2
##
## Training set error measures:
##              ME      RMSE      MAE      MPE      MAPE      MASE
## Training set 0.01211695 0.1492069 0.1224664 76.54038 135.8759 0.5849008
##              ACF1
## Training set -0.01927195
```

ARMA(3,1)xSARMA(1,0,1) check residuals:



```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(3,1,1)(1,0,1)[10]
## Q* = 20.646, df = 14, p-value = 0.1111
##
## Model df: 6. Total lags used: 20
```

The residuals plot looks like it have constant variance with mean 0. The ACF plot shows only one lag exceeding the 95% CI threshold. The distribution of residuals look to have some skew and a relatively flat kurtosis, implying it might not be normal in respect to a Gaussian PDF.

ARMA(3,1)xSARMA(1,0,1) t-test for mean 0:

```
##
## One Sample t-test
##
## data: data
## t = 0.95715, df = 138, p-value = 0.3402
## alternative hypothesis: true mean is not equal to 0
## 95 percent confidence interval:
## -0.0129145 0.0371484
## sample estimates:
## mean of x
## 0.01211695
##
## T-Test: mean is statistically zero, linear trend *REMOVED* ->
## *FAIL* to reject H0

## [1] TRUE
```

The t-test 95% CI contains zero, therefore the mean of the residuals is statistically zero, and that the linear trend has been removed.

ARMA(3,1)xSARMA(1,0,1) normality: skewness

```
##      skew      lwr.ci      upr.ci
## 0.06663183 0.05590854 0.07226337
## Skew: has *RIGHT* skewness,
## property does *NOT* conform to normality and Gaussian PDF

## [1] FALSE
```

ARMA(3,1)xSARMA(1,0,1) shows some slight right skewness, therefore not normal in respect to a Gaussian PDF.

ARMA(3,1)xSARMA(1,0,1) normality: (excess) Kurtosis

```
##      kurt      lwr.ci      upr.ci
## -0.7240697 -0.7465902 -0.7262800
## Kurt: has *FLAT thin-tailed* (excess) kurtosis,
## property does *NOT* conform to normality and Gaussian PDF

## [1] FALSE
```

ARMA(3,1)xSARMA(1,0,1) shows some slight flat (excess) Kurtosis, therefore not normal in respect to a Gaussian PDF.

ARMA(3,1)xSARMA(1,0,1) stationarity: KPSS

```
##
## #####
## # KPSS Unit Root Test #
## #####
##
## Test is of type: tau with 4 lags.
##
## Value of test-statistic is: 0.0288
##
## Critical value for a significance level of:
##          10pct  5pct 2.5pct  1pct
## critical values 0.119 0.146  0.176 0.216
##
## KPSS: *NO* unit roots, *NO* linear trend, slope zero,
## series is trend stationary -> *FAIL* to reject H0

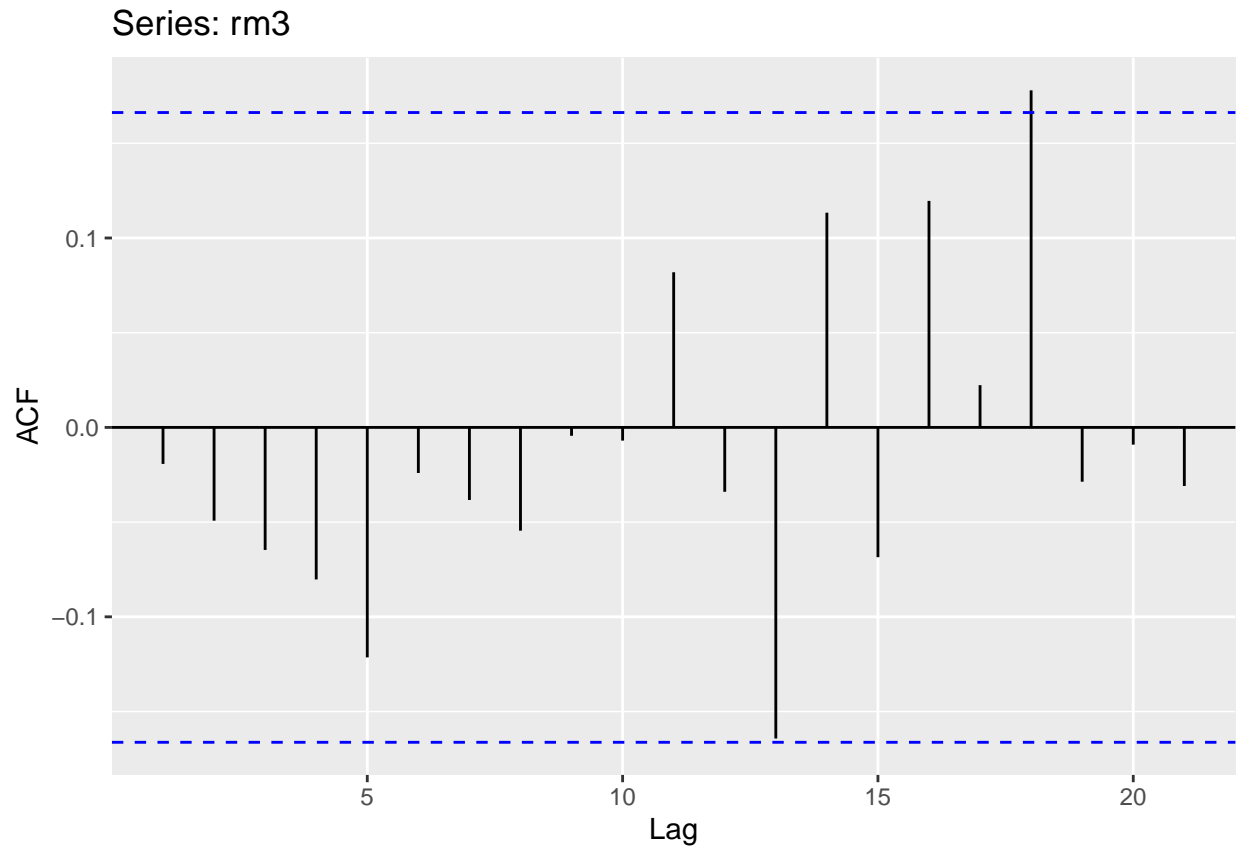
## [1] TRUE
```

ARMA(3,1)xThe SARMA(1,1,1) KPSS test shows no unit roots, therefore the model residuals are stationary.
 ARMA(3,1)xSARMA(1,0,1) stationarity: ADF

```
##
## Title:
##   Augmented Dickey-Fuller Test
##
## Test Results:
##   PARAMETER:
##     Lag Order: 20
##   STATISTIC:
##     Dickey-Fuller: -1.7408
##   P VALUE:
##     0.081
##
## Description:
##   Tue Mar 28 19:50:30 2023 by user: Reed
##
## ADF: presence of unit roots over 20 lags, indicates mean drift,
## business cycles present, series is *NOT* stationary -> *FAIL* to reject H0

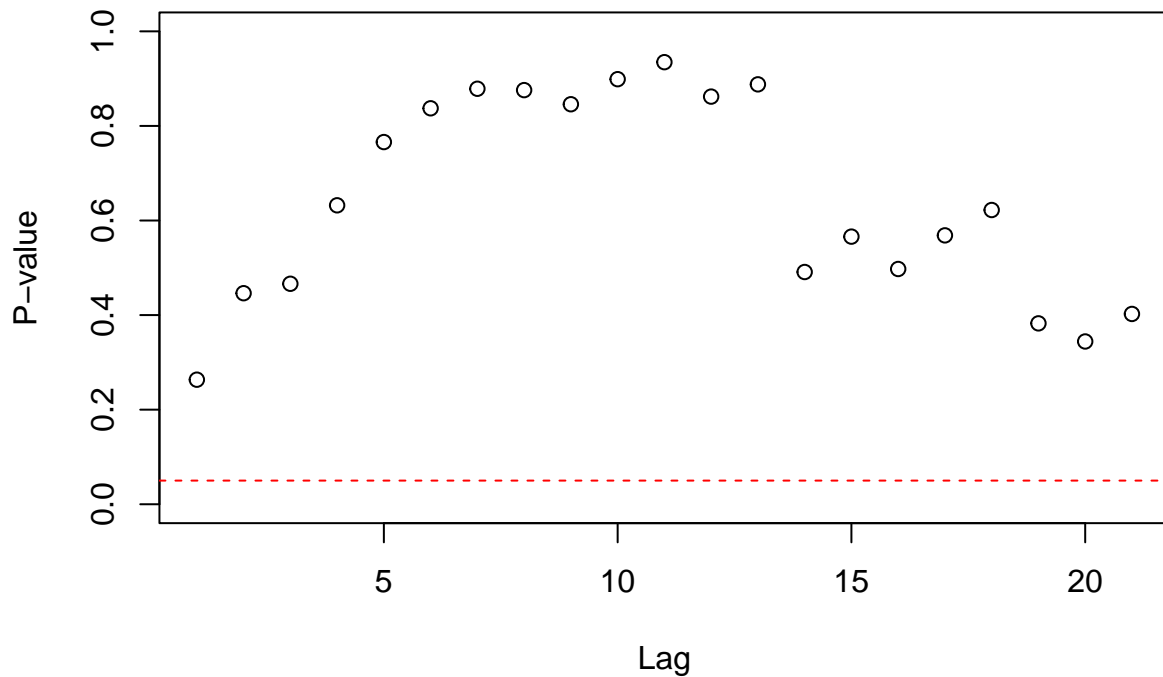
##
## TRUE
```

Contrary to the KPSS test, and like we've seen with testing stationary in the ARMA(3,1) model, the ADF test shows the ARMA(3,1)xSARMA(1,0,1) model residuals are not stationary, with the p-value greater than the 0.05 critical value. Given the ACF plot:



We can visually see the residuals look fairly stationary. The ADF test could be taking slight mean drift into account. But since two of three indicators of stationarity, the KPSS test and the ACF plot, show the residuals are stationary, we will go with the narrative that the model residuals are stationary overall.

ARMA(3,1)xSARMA(1,0,1) constant variance: McLeod-Li



```
## McLeod-Li: constant variance, homoscedastic -> *FAIL* to reject H0
```

```
## [1] TRUE
```

While the residuals plot showed signs of constant variance within the ARMA(3,1)xSARMA(1,0,1) model residuals, the McLeod-Li further supports it.

ARMA(3,1)xSARMA(1,0,1) constant variance: Breush-Pagan

```
##
## studentized Breusch-Pagan test
##
## data:  lm(data ~ seq(1, length(data)))
## BP = 0.31932, df = 1, p-value = 0.572
##
## Breusch-Pagan: constant variance, homoscedastic ->
## *FAIL* to reject H0
```

```
## BP
## TRUE
```

The Breusch-Pagan test further supports constant variance within the ARMA(3,1)xSARMA(1,0,1) model residuals.

ARMA(3,1)xSARMA(1,0,1) lag dependence: Box-Ljung

```
##
## Box-Ljung test
##
## data: data
## X-squared = 20.646, df = 20, p-value = 0.4182
##
## Box-Ljung: implies independence over 20 lags,
## *NO* autocorrelation -> *FAIL* to reject H0

## [1] TRUE
```

The ARMA(3,1)xSARMA(1,0,1) model residuals are shown to have lag independence via the Box-Ljung test.

Checking for ARMA(3,1)xSARMA(1,0,1) business cycles:

```
## [1] 4.463 2.490 8.189
```

We find that the ARMA(3,1)xSARMA(1,0,1) model show 8-year, 2.5-year, and 4.5-year business cycles.

Given that the model and its residuals are not normal, contains 3 business cycles, I feel this is an adequate model to be used for forecasting.

We will attempt to see if Auto Arima function can result in an improved ARMA()xSARMA() model:

```
m2aa <- auto.arima(yTrans, max.p=20,max.d=20, max.q=20, max.P=20, max.D=20, max.Q=20, stationary=F, seas
summary(m2aa)
```

```
## Series: yTrans
## ARIMA(0,0,1) with non-zero mean
##
## Coefficients:
##          ma1      mean
##        -0.7232  0.0078
## s.e.    0.0680  0.0036
##
## sigma^2 = 0.02254: log likelihood = 66.99
## AIC=-127.97   AICc=-127.79   BIC=-119.17
##
## Training set error measures:
##              ME      RMSE      MAE      MPE      MAPE      MASE
## Training set -0.0002933016 0.1490444 0.1225303 68.12748 147.5567 0.585206
##              ACF1
## Training set 0.05309556
```

Auto Arima only results in an MA(1) model with no seasonal component.

Let's create a ARMA(1,1)xSARMA(1,0,1) model with a slightly smaller value of p than ARMA(3,1)xSARMA(1,0,1):

```
m4 <- Arima(yTrans, order=c(1,1,1), seasonal=list(order=c(1,D,1)), include.mean=F)
summary(m4)
```

```
## Series: yTrans
## ARIMA(1,1,1)(1,0,1)[10]
##
## Coefficients:
##          ar1          ma1          sar1          sma1
##      -0.4096   -1.0000   -0.7909    0.7690
## s.e.    0.0775    0.0212    0.4900    0.5063
##
## sigma^2 = 0.02747: log likelihood = 51.32
## AIC=-92.64   AICc=-92.18   BIC=-78
##
## Training set error measures:
##              ME          RMSE          MAE          MPE          MAPE          MASE
## Training set 0.006731606 0.1627339 0.1331121 79.29788 130.8099 0.6357444
##              ACF1
## Training set -0.1330428
```

ARMA(3,1)xSARMA(1,0,1) summary:

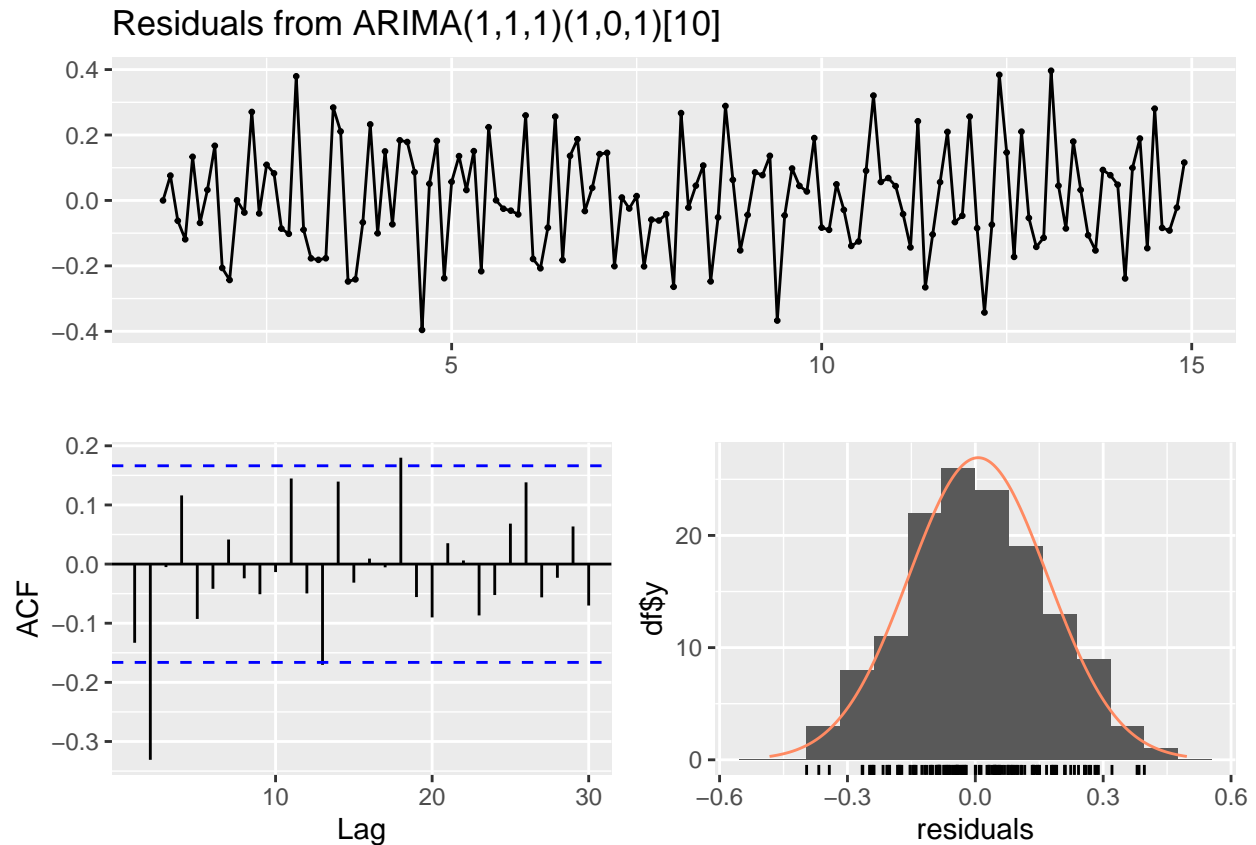
```
## Series: yTrans
## ARIMA(3,1,1)(1,0,1)[10]
##
## Coefficients:
##          ar1          ar2          ar3          ma1          sar1          sma1
##      -0.6255   -0.4303   -0.2592   -1.0000    0.6932   -0.7609
## s.e.    0.0872    0.0905    0.0848    0.0751    0.4061    0.3807
##
## sigma^2 = 0.02344: log likelihood = 62.35
## AIC=-110.69   AICc=-109.83   BIC=-90.2
##
## Training set error measures:
##              ME          RMSE          MAE          MPE          MAPE          MASE
## Training set 0.01211695 0.1492069 0.1224664 76.54038 135.8759 0.5849008
##              ACF1
## Training set -0.01927195
```

Based on the model summaries above, ARMA(3,1)xSARMA(1,0,1) has better AIC, BIC, RMSE, and MAE than the ARMA(1,1)xSARMA(1,0,1) model we just created. I would prefer the ARMA(3,1)xSARMA(1,0,1) model due to these better statistics.

3.2. Based on in-sample fitting, which model is preferred? Why?

We will perform in-sample testing for ARMA(1,1)xSARMA(1,0,1).

ARMA(1,1)xSARMA(1,0,1) check residuals:



```
##
##  Ljung-Box test
##
## data:  Residuals from ARIMA(1,1,1)(1,0,1)[10]
## Q* = 40.835, df = 16, p-value = 0.0005872
##
## Model df: 4.    Total lags used: 20
```

The residuals plot looks like it have constant variance with mean 0. The ACF plot is fairly stationary with only two lags exceeding the 95% CI threshold. The distribution of residuals look to have some skew and a relatively flat kurtosis, implying it might not be normal in respect to a Gaussian PDF.

ARMA(1,1)xSARMA(1,0,1) t-test for mean 0:

```
##
##  One Sample t-test
##
## data:  data
## t = 0.48635, df = 138, p-value = 0.6275
## alternative hypothesis: true mean is not equal to 0
## 95 percent confidence interval:
##  -0.02063620  0.03409942
## sample estimates:
##  mean of x
##  0.006731606
##
```

```
## T-Test: mean is statistically zero, linear trend *REMOVED* ->
## *FAIL* to reject H0
```

```
## [1] TRUE
```

The t-test 95% CI contains zero, therefore the mean of the residuals is statistically zero, and that the linear trend has been removed.

ARMA(1,1)xSARMA(1,0,1) normality: skewness

```
##      skew      lwr.ci      upr.ci
## 0.08969398 0.07640567 0.09596362
## Skew: has *RIGHT* skewness,
## property does *NOT* conform to normality and Gaussian PDF
```

```
## [1] FALSE
```

ARMA(1,1)xSARMA(1,0,1) shows some slight right skewness, therefore not normal in respect to a Gaussian PDF.

ARMA(1,1)xSARMA(1,0,1) normality: (excess) Kurtosis

```
##      kurt      lwr.ci      upr.ci
## -0.4222157 -0.4234518 -0.3947436
## Kurt: has *FLAT thin-tailed* (excess) kurtosis,
## property does *NOT* conform to normality and Gaussian PDF
```

```
## [1] FALSE
```

ARMA(1,1)xSARMA(1,0,1) shows some slight flat (excess) Kurtosis, therefore not normal in respect to a Gaussian PDF.

ARMA(1,1)xSARMA(1,0,1) stationarity: KPSS

```
##
## #####
## # KPSS Unit Root Test #
## #####
##
## Test is of type: tau with 4 lags.
##
## Value of test-statistic is: 0.0235
##
## Critical value for a significance level of:
##          10pct  5pct 2.5pct  1pct
## critical values 0.119 0.146 0.176 0.216
##
## KPSS: *NO* unit roots, *NO* linear trend, slope zero,
## series is trend stationary -> *FAIL* to reject H0
```

```
## [1] TRUE
```

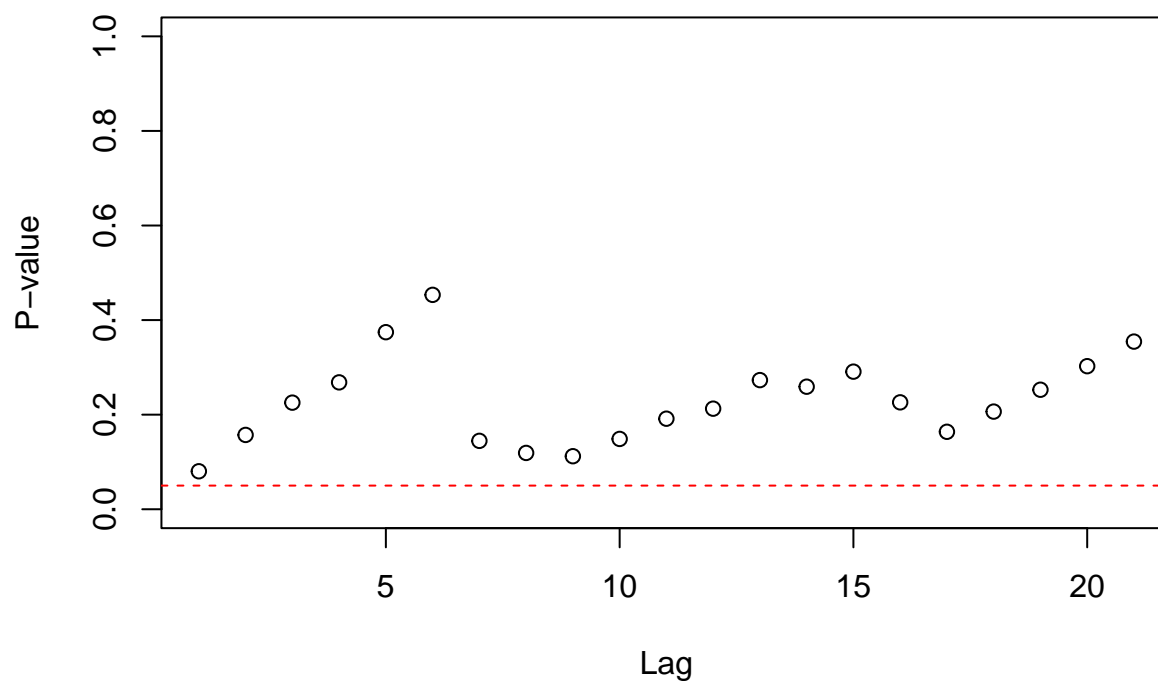
ARMA(1,1)xThe SARMA(1,1,1) KPSS test shows no unit roots, therefore the model residuals are stationary.

ARMA(1,1)xSARMA(1,0,1) stationarity: ADF

```
##
## Title:
## Augmented Dickey-Fuller Test
##
## Test Results:
## PARAMETER:
## Lag Order: 20
## STATISTIC:
## Dickey-Fuller: -1.8175
## P VALUE:
## 0.06964
##
## Description:
## Tue Mar 28 19:50:31 2023 by user: Reed
##
## ADF: presence of unit roots over 20 lags, indicates mean drift,
## business cycles present, series is *NOT* stationary -> *FAIL* to reject H0
##
## TRUE
```

The the ARMA(3,1)xSARMA(1,0,1) model, the ADF test for ARMA(1,1)xSARMA(1,0,1) shows

ARMA(1,1)xSARMA(1,0,1) constant variance: McLeod-Li



```
## McLeod-Li: constant variance, homoscedastic -> *FAIL* to reject H0
```

```
## [1] TRUE
```

While the residuals plot showed signs of constant variance within the ARMA(1,1)xSARMA(1,0,1) model residuals, the McLeod-Li further supports it.

ARMA(1,1)xSARMA(1,0,1) constant variance: Breush-Pagan

```
##
## studentized Breusch-Pagan test
##
## data:  lm(data ~ seq(1, length(data)))
## BP = 0.0010462, df = 1, p-value = 0.9742
##
## Breusch-Pagan: constant variance, homoscedastic ->
## *FAIL* to reject H0
```

```
## BP
## TRUE
```

The Breusch-Pagan test further supports constant variance within the ARMA(1,1)xSARMA(1,0,1) model residuals.

ARMA(1,1)xSARMA(1,0,1) lag dependence: Box-Ljung

```
##
## Box-Ljung test
##
## data:  data
## X-squared = 40.835, df = 20, p-value = 0.003911
##
## Box-Ljung: implies dependency present over 20 lags,
## autocorrelation present -> reject H0
```

```
## [1] FALSE
```

The ARMA(1,1)xSARMA(1,0,1) model residuals are shown to have lag dependence via the Box-Ljung test.

Checking for ARMA(1,1)xSARMA(1,0,1) business cycles:

```
## [1] 4.083
```

We find that the ARMA(1,1)xSARMA(1,0,1) model show a 4-year business cycle.

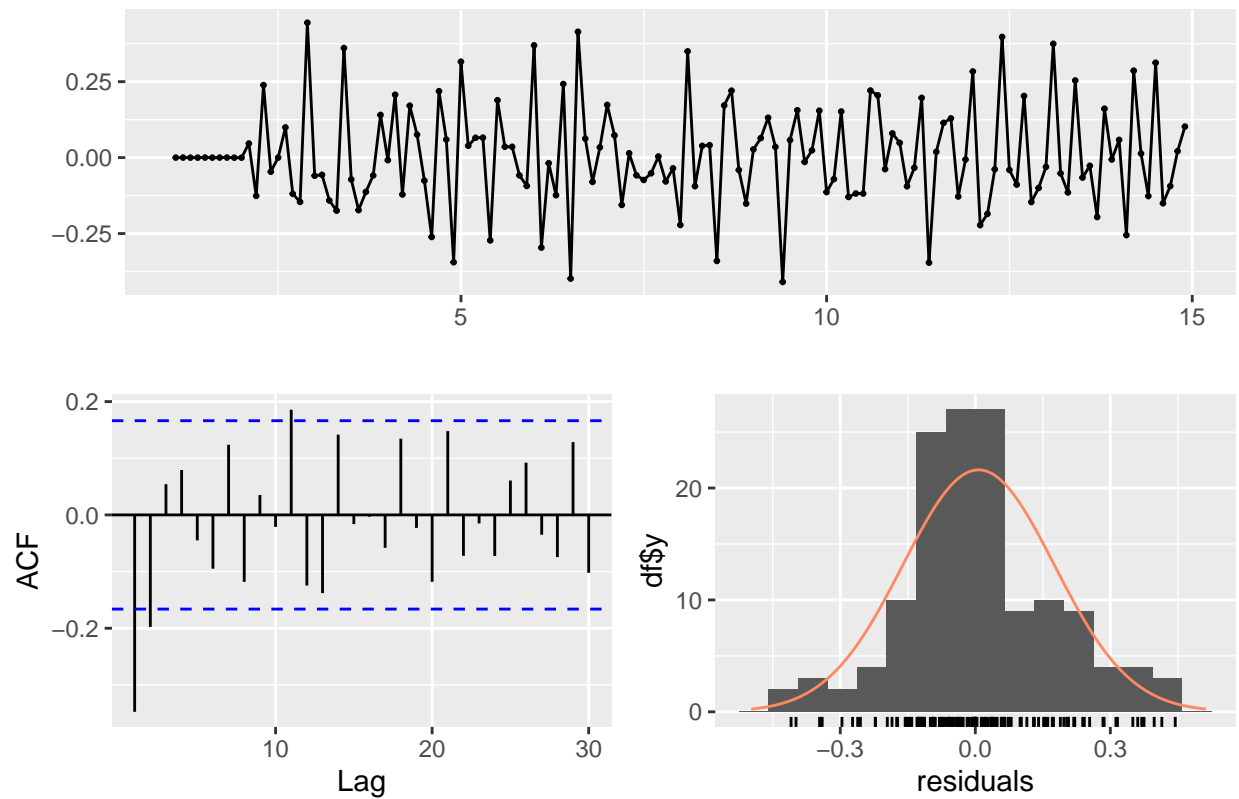
From the in-sample tests above, the ARMA(1,1)xSARMA(1,0,1) model compromised such that it is not fully normal, has lag dependence, and 1 business cycle.

The ARMA(3,1)xSARMA(1,0,1) model and its residuals are not normal and contains 3 business cycles. Despite the 3 business cycles, I would prefer the ARMA(3,1)xSARMA(1,0,1) model more.

3.4. Compare your SARMA model with your ARMA X SARMA model using the model diagnostics and choose which is better.

SARMA(1,1,1):

Residuals from ARIMA(0,0,0)(1,1,1)[10]

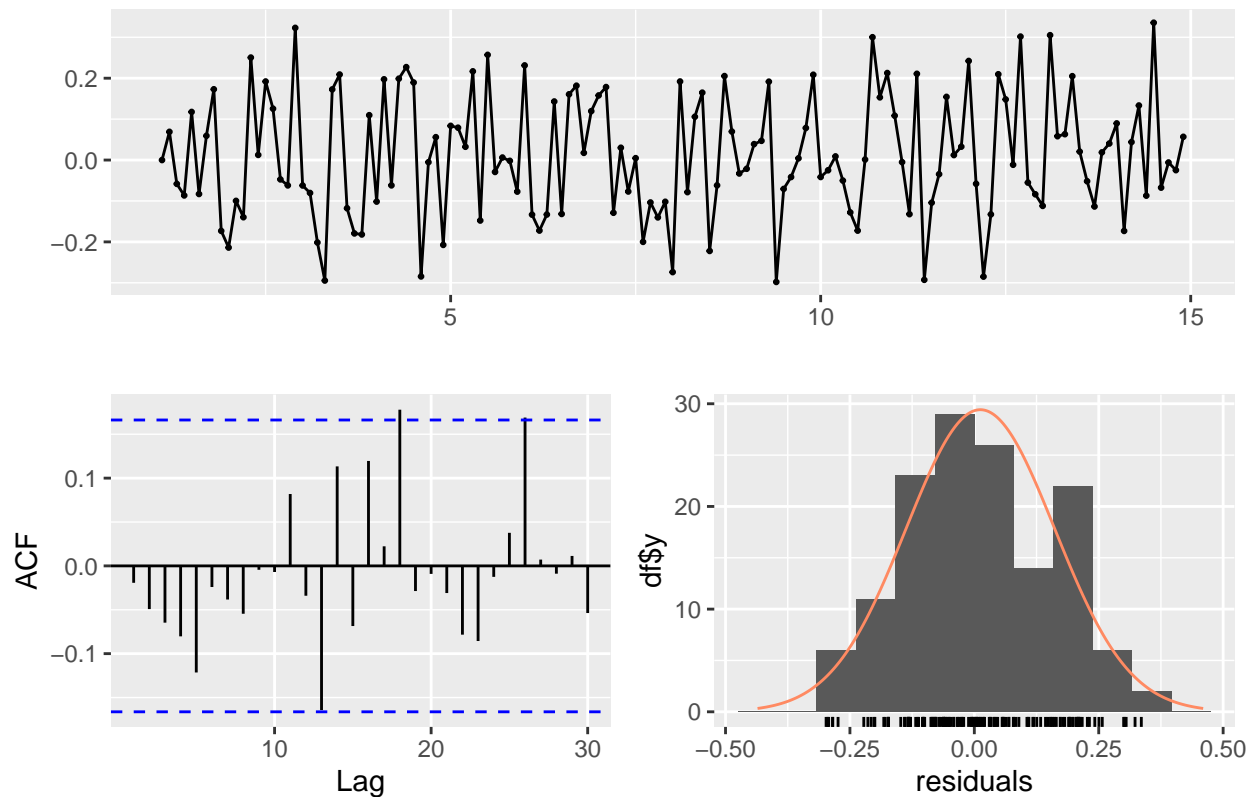


```
##
##  Ljung-Box test
##
## data:  Residuals from ARIMA(0,0,0)(1,1,1)[10]
## Q* = 50.012, df = 18, p-value = 7.516e-05
##
## Model df: 2.   Total lags used: 20
```

With the the in-sample model diagnostics performed in section 2.3, we found the SARMA(1,1,1) model is compromised by non-normalcy from skew and (excess) Kurtosis, lag dependency from the Box-Ljung test, and contains a 4-year business cycle.

ARMA(3,1)xSARMA(1,0,1):

Residuals from ARIMA(3,1,1)(1,0,1)[10]



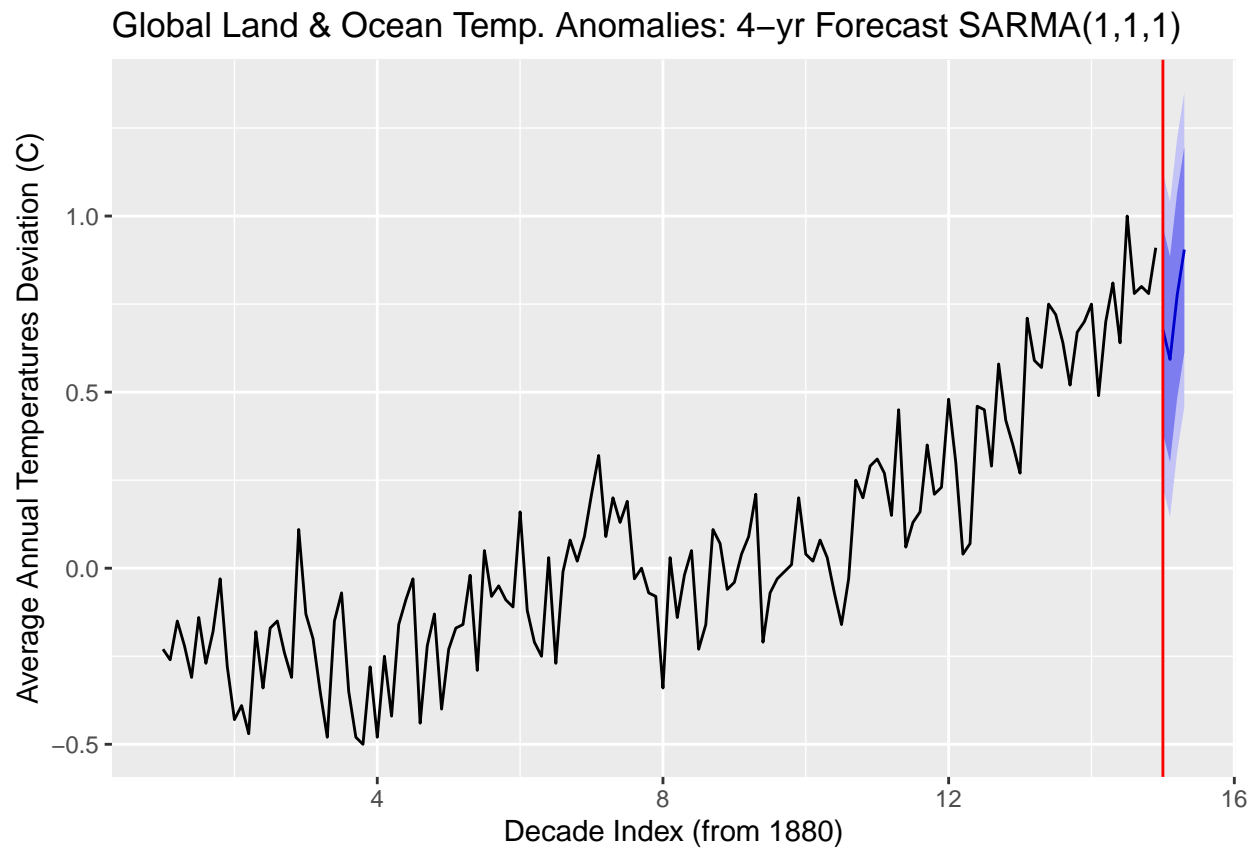
```
##
##  Ljung-Box test
##
## data:  Residuals from ARIMA(3,1,1)(1,0,1)[10]
## Q* = 20.646, df = 14, p-value = 0.1111
##
## Model df: 6.    Total lags used: 20
```

With the in-sample model diagnostics performed in section 3.1, we found the ARMA(3,1)xSARMA(1,0,1) model is compromised by non-normalcy from skew and (excess) Kurtosis, and contains three business cycle, and its conflicting ADF test questioning its overall stationarity.

Based on these in-sample model diagnostics, I would slightly favor the ARMA(3,1)xSARMA(1,0,1) as it is less compromised compared to the SARMA(1,1,1) model despite having more business cycles. We will see forecast performance in the next section (3.5).

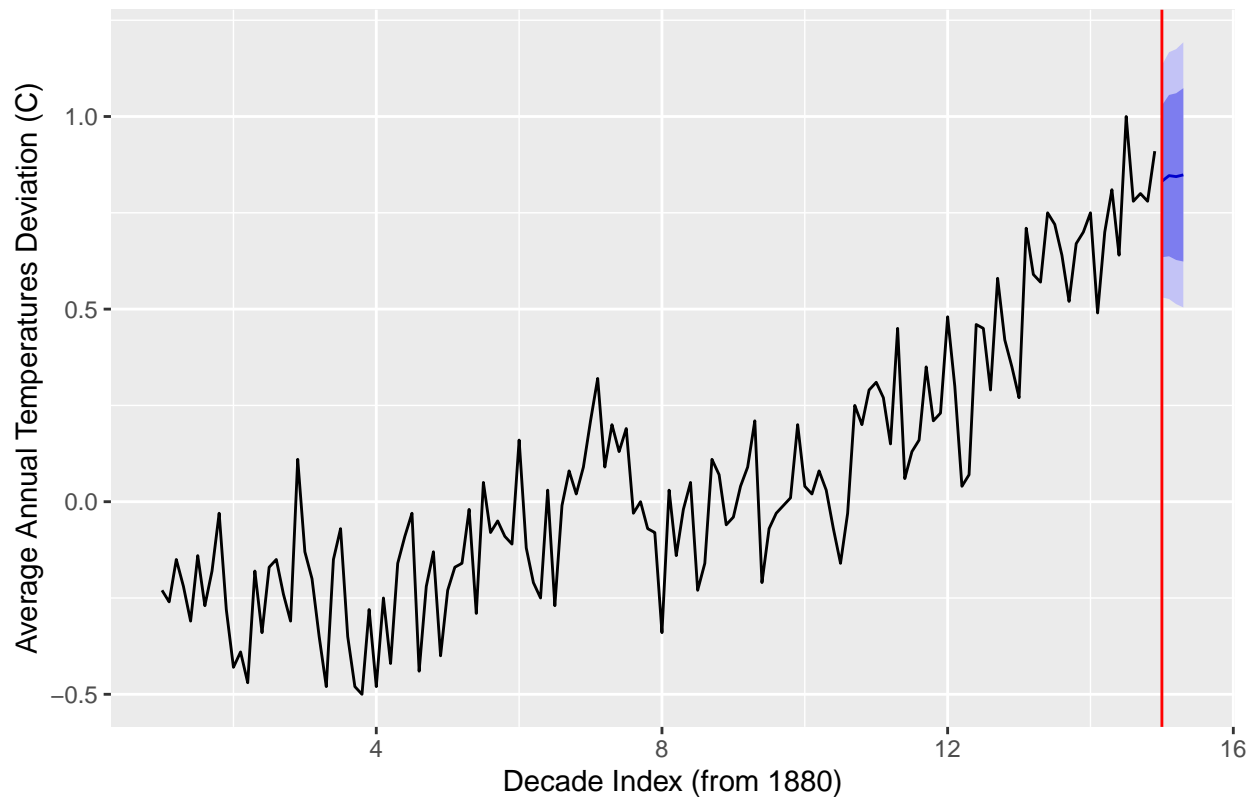
3.5. Compare your SARMA model with your ARMA X SARMA model using the model fit statistics and forecasting ability. Which is better? Do the two comparison methods agree?

SARMA(1,1,1) 4-year forecast:



ARMA(3,1)xSARMA(1,0,1) 4-year forecast:

Global Land & Ocean Temp Anomalies: 4-Yr Forecast ARMA(3,1)xSARMA(1,1)



While we found the ARMA(3,1)xSARMA(1,0,1) to have better overall in-sample model diagnostics in section 3.4, the SARMA(1,1,1) model seems to capture the seasonality when it comes to forecasting, but also has a larger CI range of variance in doing so. The ARMA(3,1)xSARMA(1,0,1) model does not demonstrate much seasonality, if at all. Because of that, I would give the edge to the SARMA(1,1,1) model due to its better seasonality forecast, despite the larger CI range.

(NOTE: The the gap of the start of the forecast in both charts is due to the one-year gap from the last datapoint in the time series, and is not drawn to connect them.)

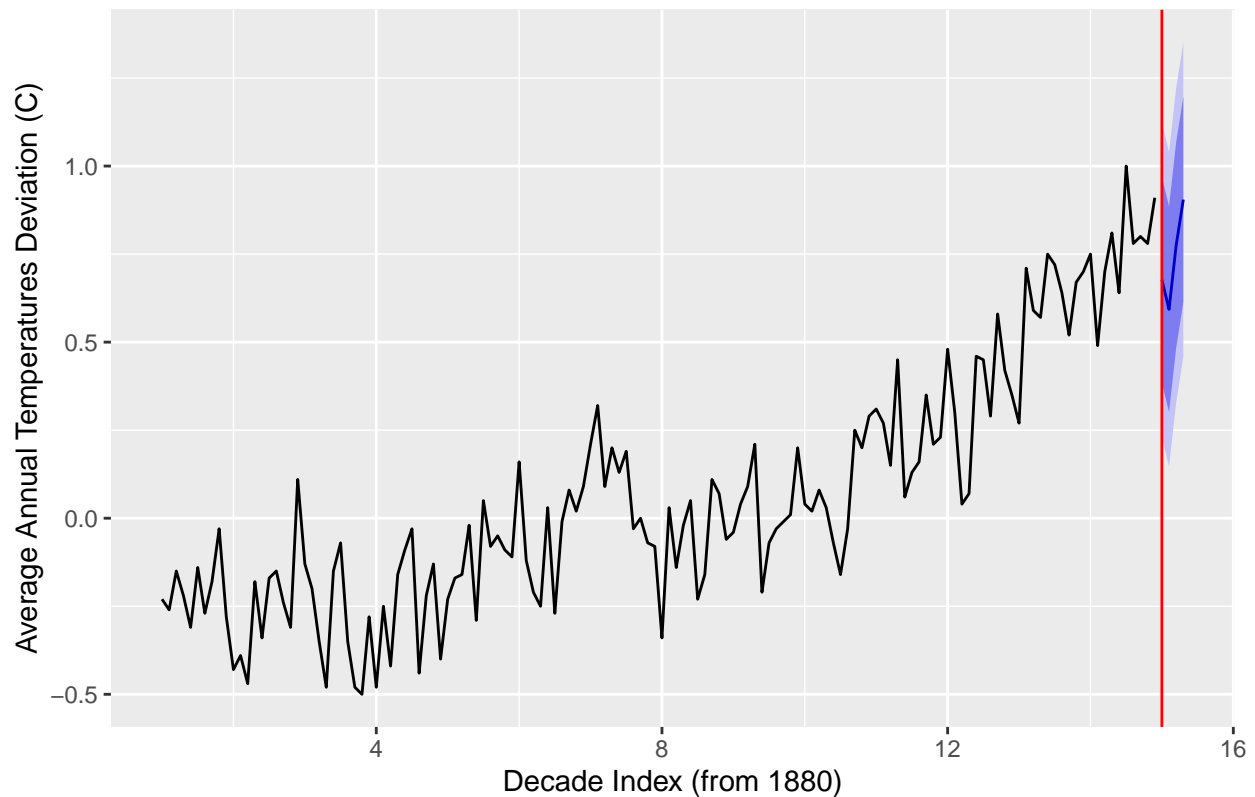
4. Report (20 points)

For the global land and ocean temperature anomalies, describe to a client or employer your best model. The report requires information from which decisions can be made or actions taken.

(Based on the analysis, modelling, testing, and forecasting performed in sections 2 and 3, we will use the SARMA(1,1,1) model as noted in section 3.5 for our forecasting executive report.)

SARMA(1,1,1) 4-year forecast:

Global Land & Ocean Temp. Anomalies: 4-yr Forecast SARMA(1,1,1)



This forecasting model attempts to predict global land and ocean temperature (C) changes for the next four years. The data is sourced from the National Centers for Environmental Information website which contains annual temperature changes from 1880 to 2019. The forecast presented here is based from an evaluation of several working models that have been tested and compared, and selected the best one based on the tools we currently have available.

The forecast model shows the dark blue point forecast line emulating the seasonal cycles shown by the previous time series data, showing drops and even greater climbs of temperature changes over the next four years. In addition to the point forecast line we also have an 80% confidence interval (CI) shown by the blue area of possible values that could occur, as well as a 95% CI expanded in the lighter blue area. The range of these CIs also follow the seasonal changes like that of the point forecast line, as opposed to generalizing an overall area.

Given the current tools and methodologies we have at our disposal we are limiting ourselves by making short-term recommendations with this forecast model at this time. With this short-term perspective and the range of the 80% CI we can anticipate a change of as low as 0.3 degrees Celsius to as high as 1.1 degrees Celsius. While the range might be rather large, it somewhat supports the greater theme of rising temperatures as a result of climate change. That said, we consider four years could be enough time, if planned well and efficiently, to be aware of, anticipate, and implement climate change-related policies that can effect the day-to-day business and make changes as needed. But we should not only accommodate those policies, and if possible, take steps to put things in place for longer-term planning as well to help curb climate change and find ways to reduce our carbon footprint in respect to the business.

We will keep improving upon this model by iteration as our toolsets expand over time to provide a more accurate and long-term forecast.