SMART POINTERS

LECTURE 11-3

JIM FIX, REED COLLEGE CS2-S20

TODAY'S PLAN

- CLARIFICATION ABOUT mutable KEYWORD in lambdas
- **LOOK AT MEMORY MANAGEMENT BUGS**
- ▶ AUTOMATIC MEMORY MANAGEMENT *ANIMATED*
 - MARK-AND-SWEEP GARBAGE COLLECTION
 - REFERENCE COUNTS
- ▶ LOOK AT C++ STL's SMART POINTERS
 - BOX EXAMPLE WITH shared_ptr
 - LINKED LIST EXAMPLE WITH shared_ptr

```
[capture-list] (parameters) mutable -> result { body }
```

- ▶The mutable lets the body change the new variables that are copies
- ▶(C++ makes the operator() method const otherwise.)
- ▶ This demonstrates its effect:

```
int startAt = 100;
std::function<int(void)> dbl =
    [startAt](void) mutable -> int {
        startAt *= 2; return startAt;
    };
std::cout << dbl() << " " << startAt << std::endl;
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You can also make variables that are captured by value changeable:

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        startAt *= 2; return startAt;
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std::cout << dbl() << " " << startAt << std::endl;
std::cout << dbl() << " " << startAt << std::endl;</pre>
```

This outputs:

```
200 100400 100800 100
```

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```
[capture-list] (parameters) mutable -> result { body }
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This outputs:

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```

▶ The captured copy of the variable makes the lambda (internally) stateful.

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SOME WAYS OF HAVING POINTER-BASED CODE BREAK

- You use & on a stack variable/object in a function and that pointer gets exported outside a function. You try to access the component referenced by that pointer outside that function.
- ▶ You forget to initialize a pointer component. You access that component.
- ▶ You try to access a component referenced by a null pointer.
- Two data structures share a pointer, one calls a delete on it. You try to access it through the other data structure. Or maybe you try to delete again it there.
- ▶ You don't call delete on a pointer to a component no longer used by a data structure.

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- Two data structures share a pointer, one calls a delete on it. You try to access it through the other data structure. Or maybe you try to delete again it there.
- ▶ You don't call delete on a pointer to a component no longer used by a data structure.
 - → A lot of these problems arise because of "by hand" memory management

```
class Box {
public:
  int* ptr;
 Box(int value) : {new int[value]} { }
 Box(const Box& b) : {b.ptr} { }
 Box& operator=(const Box& b) { ptr = b.ptr; return *this; }
 ~Box(void) { delete ptr; }
};
int main(void) {
                                                HEAP MEMORY
 Box b1 { 10 };
  Box b2 { b1 };
                                                 10
                            STACK FRAME
  Box b3 { 11 };
                             b1 ptr
  b3 = b2;
```

```
class Box {
public:
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  Box b3 { 11 };
                             b1 ptr
  b3 = b2;
                             b2 ptr
                             b3 ptr
```

Changed reference in b3.

This is a "memory leak" error.

```
class Box {
public:
  int* ptr;
  Box(int value) : {new int[value]} { }
  Box(const Box& b) : {b.ptr} { }
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int main(void) {
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Destructor called on b3, b3.ptr deleted.
                              b3 ptr
```

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int main(void) {
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 Box b1 { 10 };
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  Box b3 { 11 };
                             b1 ptr
  b3 = b2;
                                ptr
```

b3 ptr

Destructor called on b3, b3.ptr deleted.

Destructor called on b2, b2.ptr delete.

This is a "double delete" error.

- ▶ These kinds of bugs are so rampant in C++ code.
- ▶ Many of them go unnoticed.
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- ▶ These kinds of bugs are so rampant in C++ code.
- ▶ Many of them go unnoticed.
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 - Programming disciplines/idioms developed
 - Programming libraries developed
 - →Programming languages developed
 - Program analysis tools developed
 - →Runtime instruments developed
 - **→**Testing strategies developed.

2016 GÖDEL PRIZE

- ▶ From the European Association for Thheoretical Computer Science
 - "The... Gödel Prize is awarded to Stephen Brookes and Peter W. O'Hearn for their invention of Concurrent Separation Logic, as described in the following two papers:"
 - **S.** Brookes, "A Semantics for Concurrent Separation Logic." Theoretical Computer Science 375(1-3): 227-270 (2007)
 - P. W. O'Hearn, "Resources, Concurrency, and Local Reasoning." Theoretical Computer Science 375(1-3): 271-307 (2007)

ON "CONCURRENT SEPARATION LOGIC"

"Concurrent Separation Logic (CSL) is a revolutionary advance over previous proof systems for verifying properties of systems software, which commonly involve both pointer manipulation and shared-memory concurrency. For the last thirty years experts have regarded pointer manipulation as an unsolved challenge for program verification and shared-memory concurrency as an even greater challenge. Now, thanks to CSL, both of these problems have been elegantly and efficiently solved; and they have the same solution. Brookes and O'Hearn's approach builds on the Separation Logic for sequential programs due to O'Hearn and the late John Reynolds. The extension to treat concurrently executing programs communicating via shared state is highly non-trivial and involves a dynamic notion of resource ownership that supports modular reasoning."

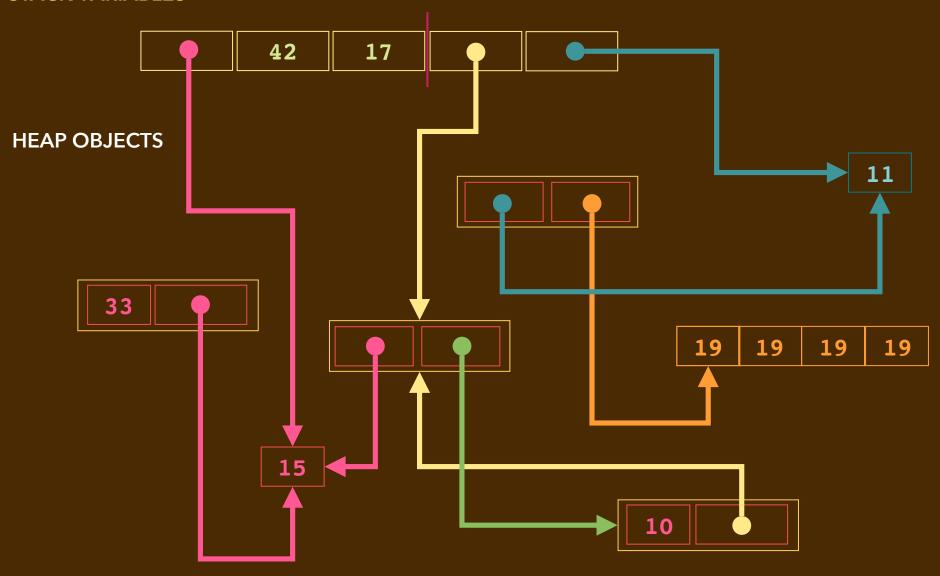
RESOURCE MANAGEMENT VIEWPOINT

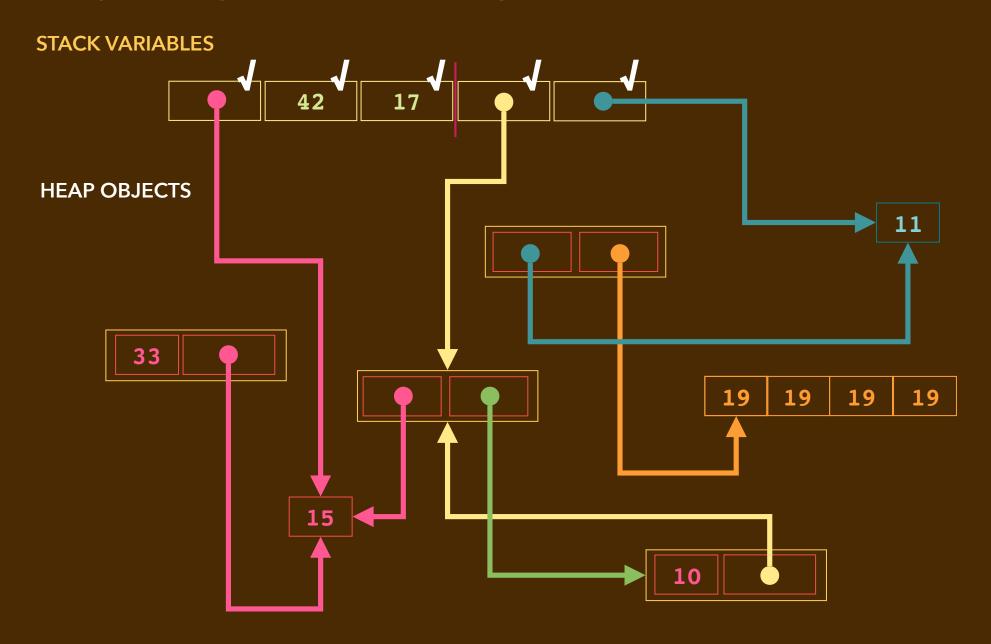
- ▶ An object's memory storage is a *resource*
 - It might be shared amongst several parts of the program
 - → If so, treat it specially. Can't delete if shared.
 - It might not be shared. Maybe only one part of the program is using it.
 - → When that part of the program is done with it, it should delete it.
- ▶ Some languages and language libraries work to make this explicit
 - They help your code manage ownership
- ▶ E.g. the Rust programming language
 - has a notion of borrowing an object; and transfer of single ownership
 - compiler has a borrow checker; based on linear types

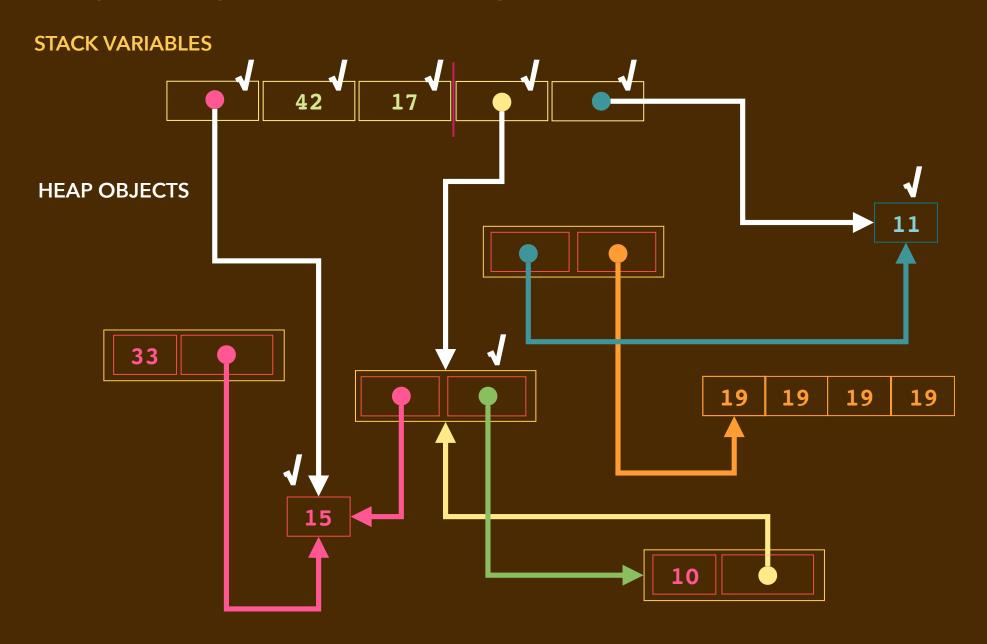
AUTOMATIC GARBAGE COLLECTION

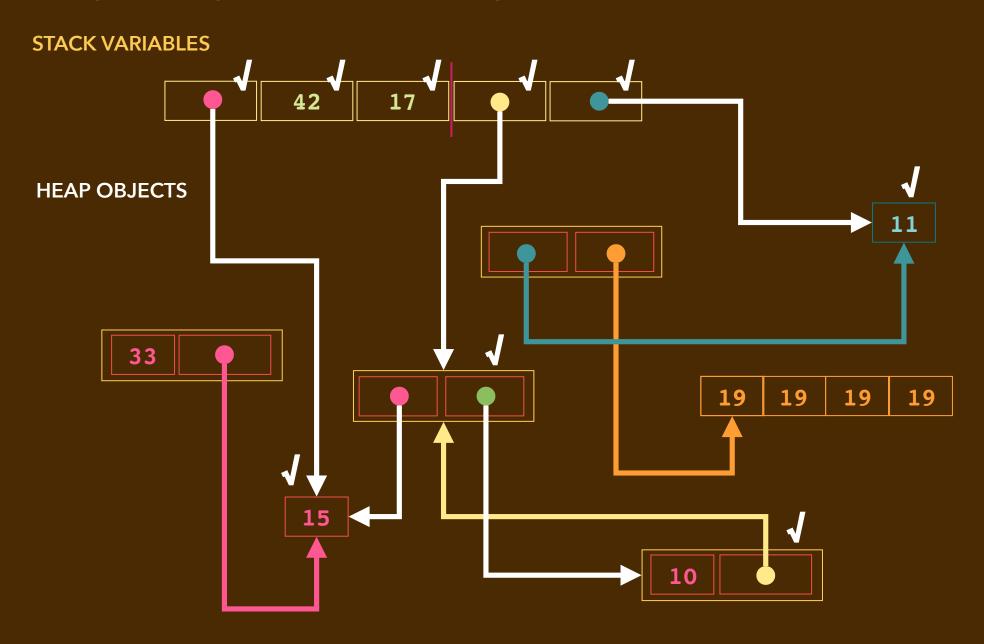
- ▶ Some problems can be prevented/solved with automatic garbage collection.
 - → A runtime component checks whether any part of the code can access an object.
 - → If not, it reclaims that object's storage.
- **▶ Question:** How does it do that?
- ► Answers: There are several ways.
 - E.g. a "stop-the-world mark-and-sweep" garbage collector halts the program, briefly, then scans through the program's stack frames and marks what objects are reachable by links. Unreachable objects are reclaimed,
 - E.g. in a "reference count" scheme, every object has a count of how many things point to it. When that count goes to 0, its storage is reclaimed.

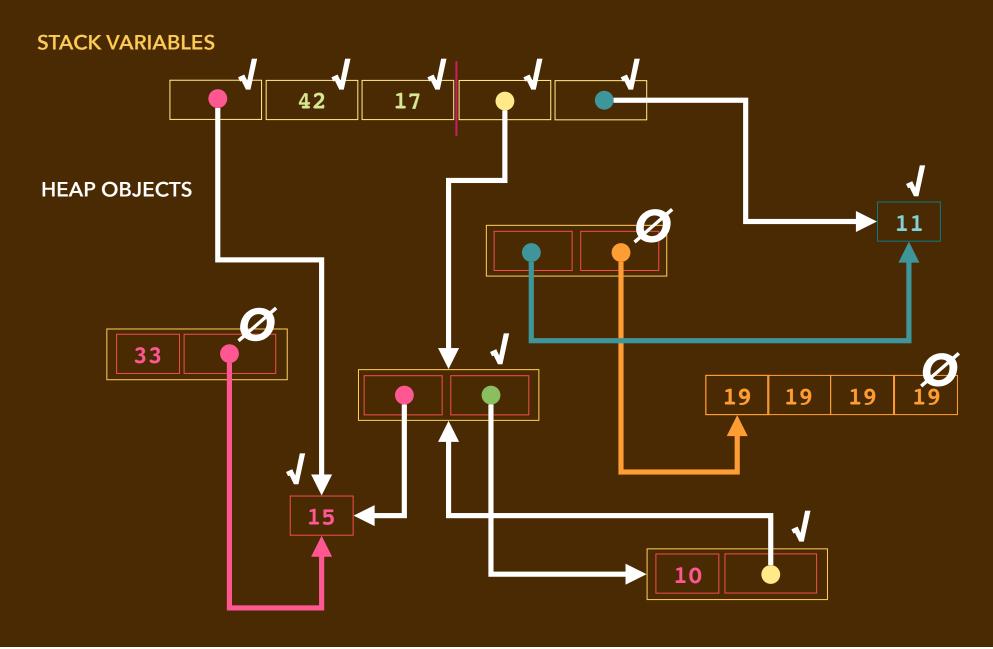
STACK VARIABLES



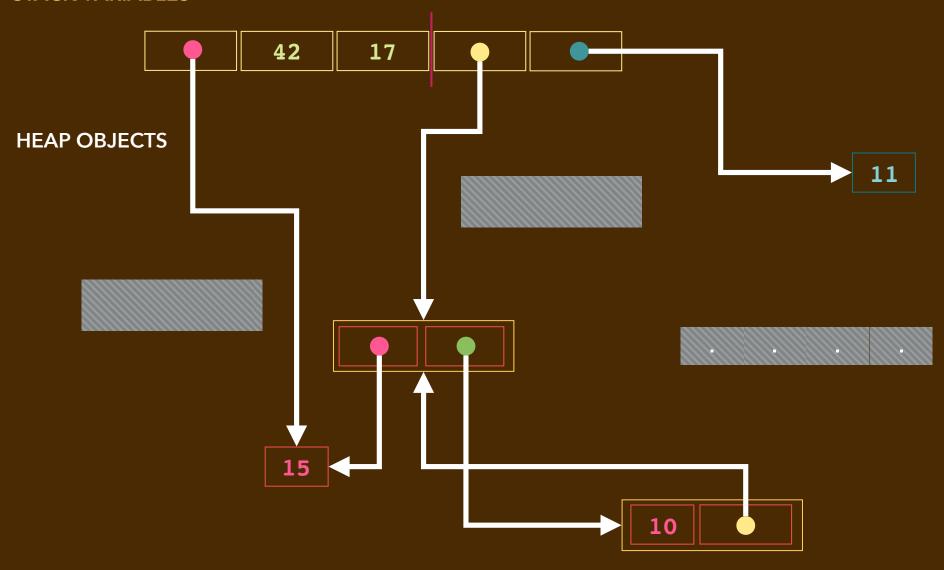




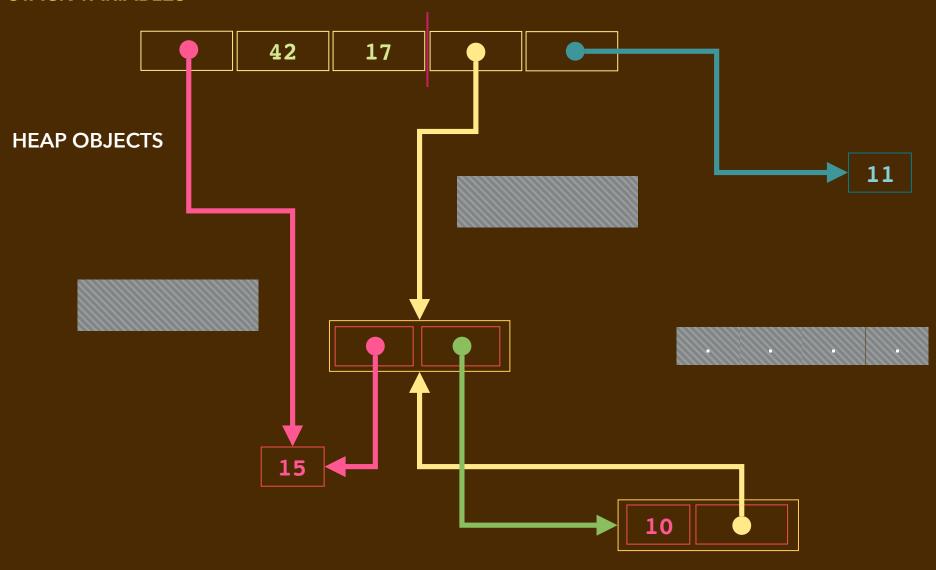




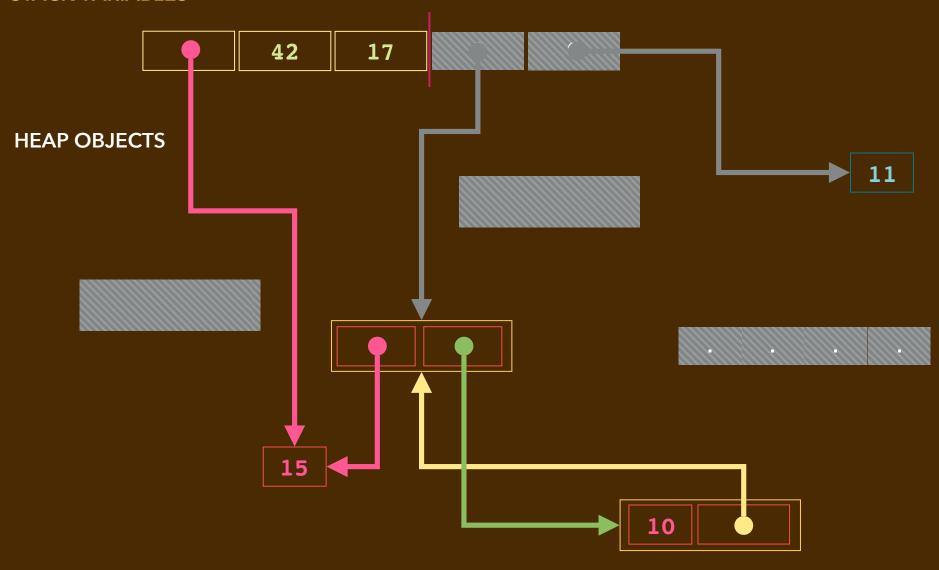
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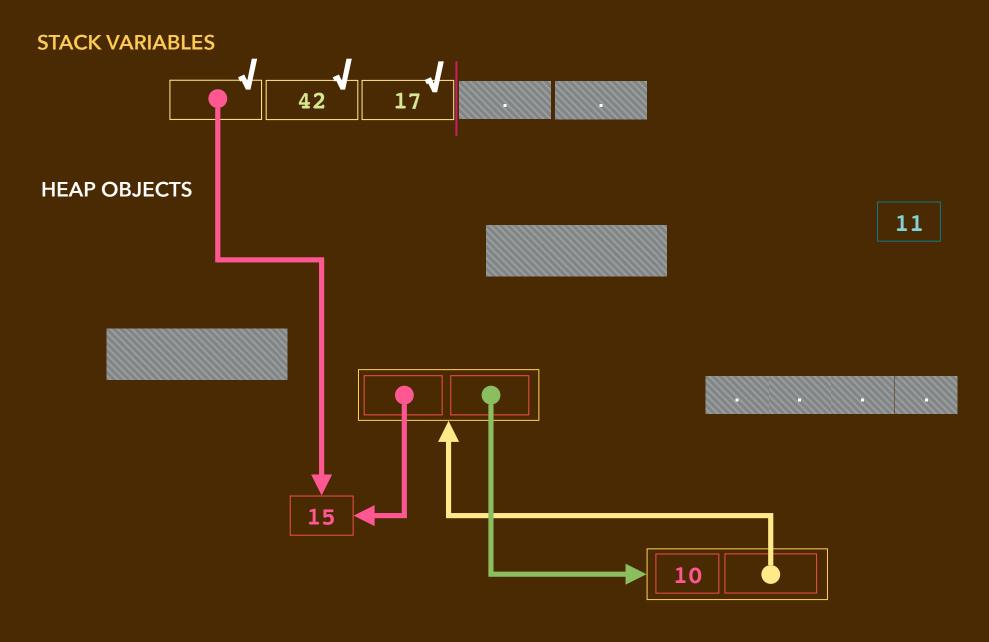


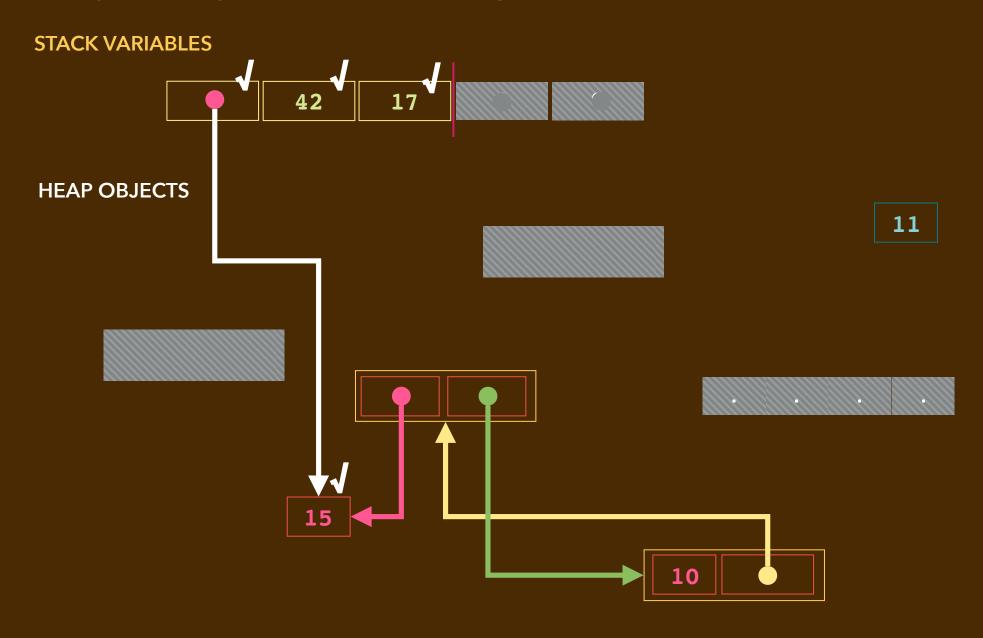
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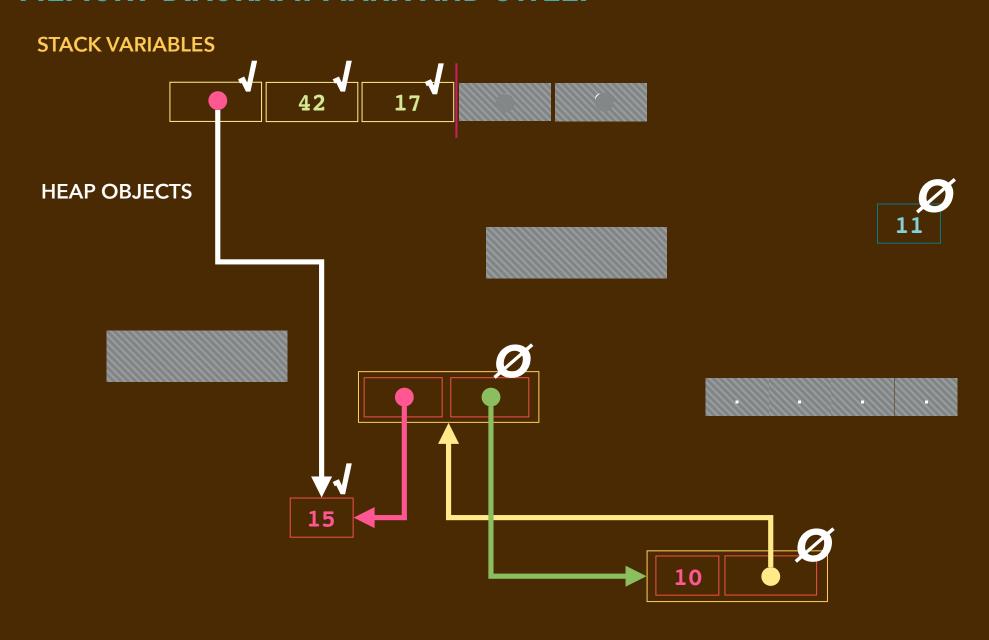


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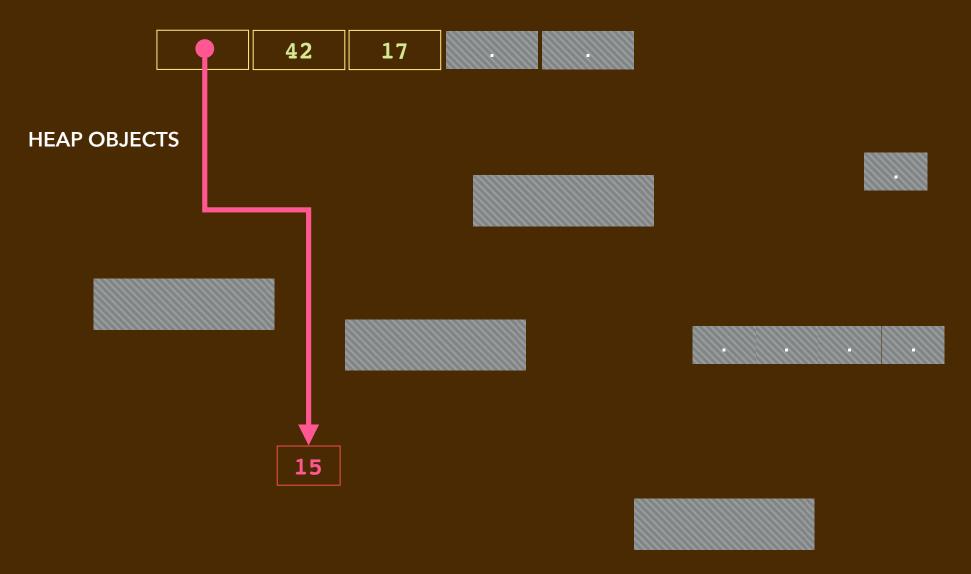








STACK VARIABLES



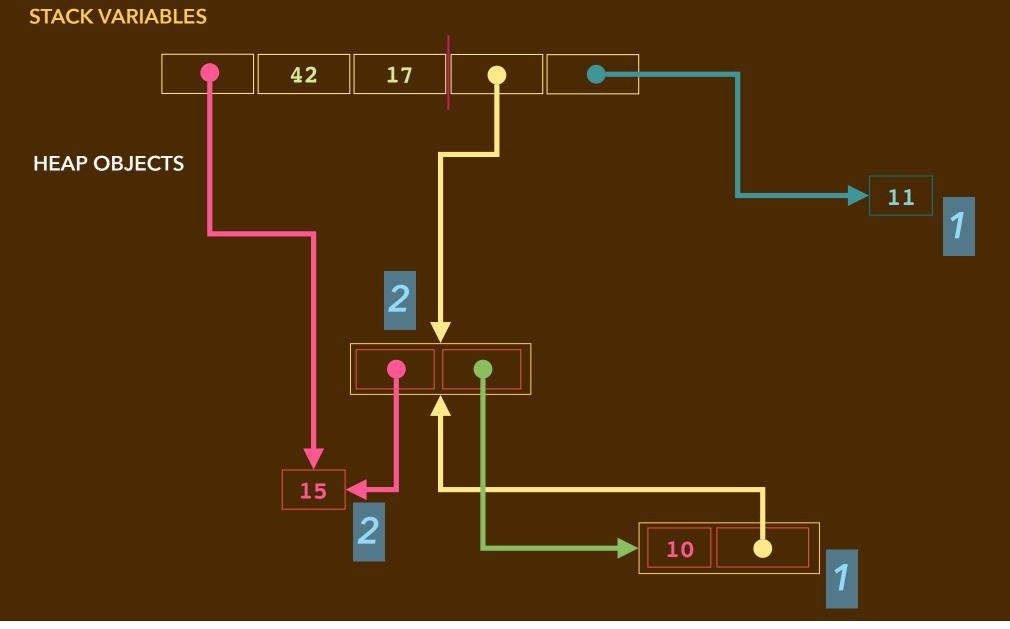
MEMORY DIAGRAM: REFERENCE COUNTS

STACK VARIABLES HEAP OBJECTS

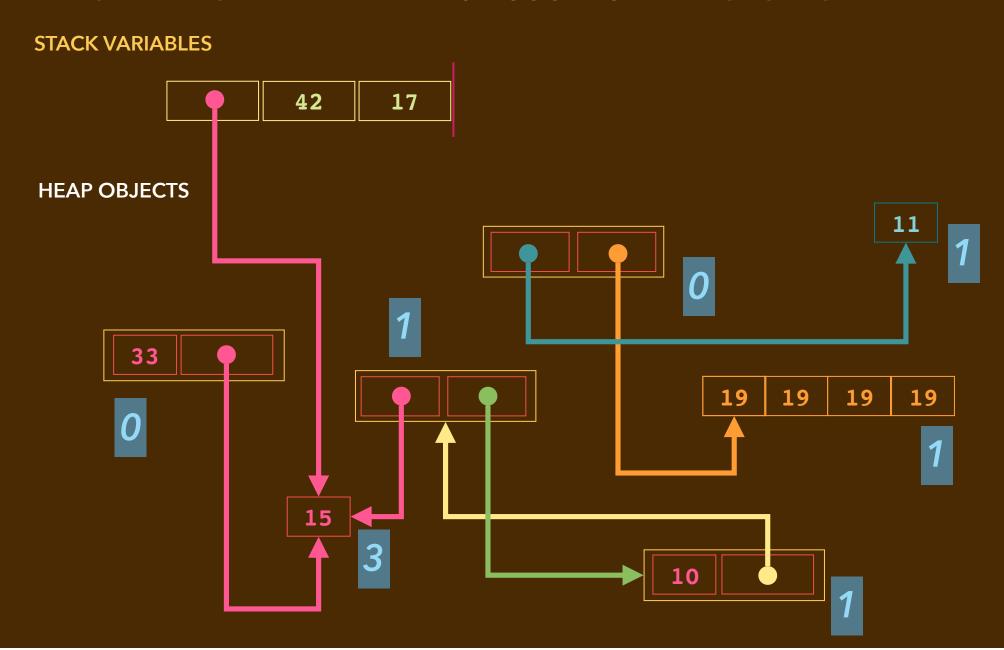
MEMORY DIAGRAM: REFERENCE COUNTS

STACK VARIABLES 42 **17 HEAP OBJECTS** 19 19 19 15

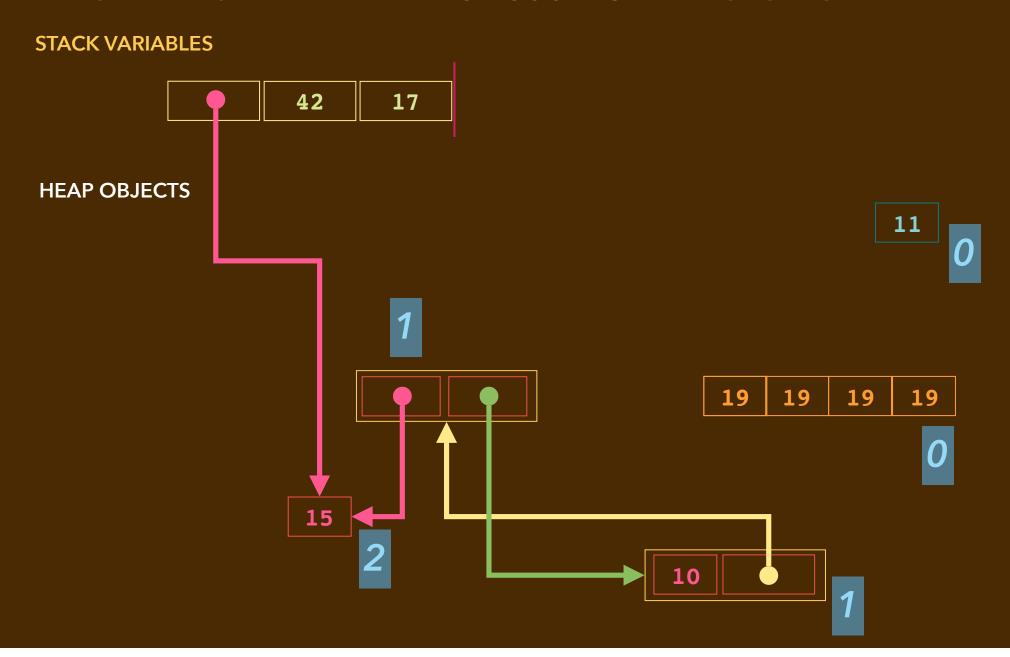
MEMORY DIAGRAM: REFERENCE COUNTS



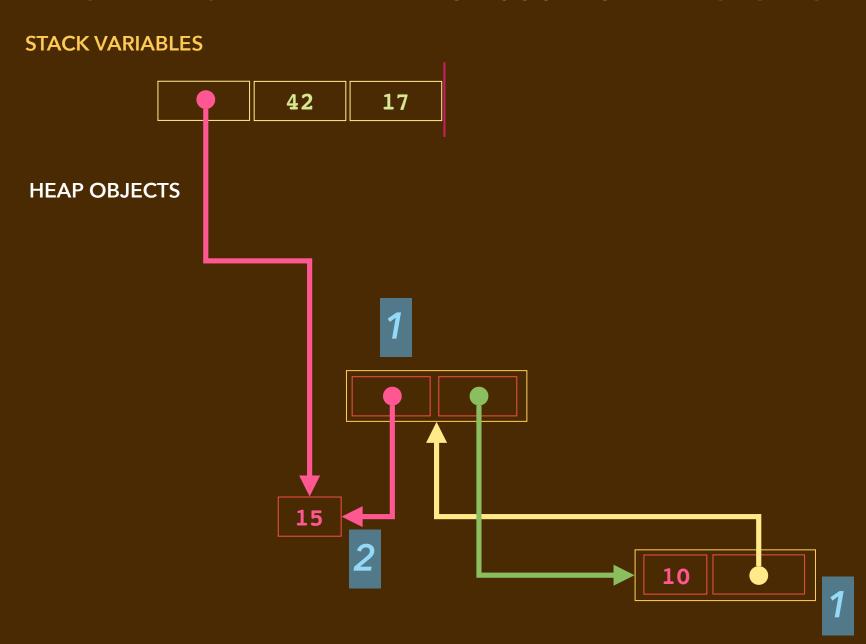
MEMORY DIAGRAM: REFERENCE COUNTS WITH CYCLES



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- ▶ As we've discussed, C++ forces you to manage memory by hand.
- ▶ There is no automatic garbage collection.
- ▶There are rampant bugs related to memory management in C++ code.
- ▶ C++11 introduced *smart pointers* with its STL.
 - These mimic some of the ideas we just surveyed.

SMART POINTERS IN THE C++ STL

- ▶The C++ STL provides three template types (#include <memory>)
 - **std::unique_ptr<T>**: used to reference an object owned by one code component (i.e. one variable). It cannot be *copied*. It can be *moved*.
 - std::shared_ptr<T>: used to reference an object shared by several code components. It maintains a count of these. *Copying* a shared pointer increments this count. If a shared_ptr variable loses scope or if an object with a shared_ptr component is deleted, it is decremented.
 - std::weak_ptr<T>: only constructable from a shared_ptr without incrementing its count. Used many ways, including in cyclic structures.

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 - std::weak_ptr<T>: only constructable from a shared_ptr without incrementing its count. Used many ways, including in cyclic structures.
- ▶ We'll look at use of shared_ptr in a linked list implementation.

```
#include <memory>
class Box {
public:
  std::shared_ptr<int> ptr;
  Box(int value) : {new int[value]} { }
 Box(const Box& b) : {b.ptr} { }
  Box& operator=(const Box& b) { ptr = b.ptr; return *this; }
 ~Box(void) { delete ptr; }
};
                                          count
                                                HEAP MEMORY
int main(void) {
  Box b1 { 10 };
                                                 10
                             STACK FRAME
  Box b2 { b1 };
                             b1 ptr
  Box b3 { 11 };
  b3 = b2;
```

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                             b2 ptr
                                                      count
                             b3 ptr
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                                                              11
                               STACK FRAME
  Box b2 { b1 };
                               b1 ptr
  Box b3 { 11 };
  b3 = b2;
                               b2 ptr
                                                         count
b1.ptr count increments to 3
                               b3 ptr
old b3.ptr decrements to 0
```

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                             b1 ptr
  Box b3 { 11 };
  b3 = b2;
                             b2 ptr
                               ptr
```

old b3.ptr 's raw pointer is deleted

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                                                   10
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  Box b2 { b1 };
                              b1 ptr
  Box b3 { 11 };
  b3 = b2;
                              b2 ptr
Destructor called on b3; decrement.
                              b3 ptr
```

Destructor called on b2; decrement.

```
#include <memory>
class Box {
public:
  std::shared ptr<int> ptr;
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  Box(const Box& b) : {b.ptr} { }
  Box& operator=(const Box& b) { ptr = b.ptr; return *this; }
 ~Box(void) { delete ptr; }
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                                            count
                                                  HEAP MEMORY
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  Box b2 { b1 };
                              b1 ptr
  Box b3 { 11 };
  b3 = b2;
                              b2 ptr
Destructor called on b3; decrement.
                              b3 ptr
```

Destructor called on b1; decrement.

```
#include <memory>
class Box {
public:
  std::shared ptr<int> ptr;
  Box(int value) : {new int[value]} { }
  Box(const Box& b) : {b.ptr} { }
  Box& operator=(const Box& b) { ptr = b.ptr; return *this; }
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                                                    HEAP MEMORY
int main(void) {
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                                                     10
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  Box b2 { b1 };
                               b1 ptr
  Box b3 { 11 };
  b3 = b2;
                               b2 ptr
Destructor called on b3; decrement.
                               b3 ptr
Destructor called on b2; decrement.
```

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#include <memory>
class Box {
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  std::shared ptr<int> ptr;
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  Box(const Box& b) : {b.ptr} { }
  Box& operator=(const Box& b) { ptr = b.ptr; return *this; }
 ~Box(void) { delete ptr; }
};
                                                   HEAP MEMORY
int main(void) {
  Box b1 { 10 };
                               STACK FRAME
  Box b2 { b1 };
                               bl ptr
  Box b3 { 11 };
  b3 = b2;
                               b2 ptr
Destructor called on b3; decrement.
                               b3 ptr
Destructor called on b2; decrement.
```

Destructor called on b1; decrement. The raw pointer of b1.ptr is deleted.

LINKED LISTS USING SMART POINTERS

- We end this lecture with a re-implementation of linked lists using C++'s shared_ptr.
- The end result is an implementation where **delete** is never explicitly called,

```
#include <memory>
class node {
public:
  int data;
  node* next;
  node(int value) : data {value}, next {nullptr} { }
~node(void) { }
};
class llist {
private:
  node* first;
  node* last;
public:
  llist(void) : first {nullptr}, last {nullptr} { }
 ~llist(void) { ... // traversal with delete of each
  void prepend(int value) { ... // new node as first
  void append(int value) { ... // new node as last
  void remove(int value) { ... // extract; delete node }
};
```

```
#include <memory>
class node {
public:
  int data;
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};
```

A SHARED_PTR SINGLY LINKED LIST

```
#include <memory>
class node {
public:
  int data;
  std::shared ptr<node> next;
  node(int value) : data {value}, next {nullptr} { }
 ~node(void) { }
};
class llist {
private:
  std::shared ptr<node> first;
  std::shared ptr<node> last;
public:
  llist(void) : first {nullptr}, last {nullptr} { }
 ~llist(void) { // NOTHING HERE!! }
  void prepend(int value);
  void append(int value);
  void remove(int value);
};
```

A SHARED_PTR SINGLY LINKED LIST

```
#include <memory>
class node {
public:
  int data;
  std::shared ptr<node> next;
  node(int value) : data {value}, next {nullptr} { }
 ~node(void) { }
};
class llist {
private:
  std::shared ptr<node> first;
  std::shared ptr<node> last;
public:
  llist(void) : first {nullptr}, last {nullptr} { }
 ~llist(void) { // NOTHING HERE!! }
  void prepend(int value);
  void append(int value);
  void remove(int value);
};
```

LINKED LIST SHARED_PTR USE

```
void llist::prepend(int value) {
  std::shared ptr<node> newNode {new node {value}};
  newNode->next = first;
  first = newNode;
  if (last == nullptr) {
   last = first;
void llist::append(int value) {
  std::shared_ptr<node> newNode {new node {value}};
  if (first == nullptr) {
    first = newNode;
  } else {
    last->next = newNode;
  last = newNode;
```

LINKED LIST SHARED_PTR NODE ALLOCATION

```
void llist::prepend(int value) {
  std::shared ptr<node> newNode {new node {value}};
  newNode->next = first;
  first = newNode;
  if (last == nullptr) {
    last = first;
                     These each initialize their shared ptr count to 1.
void llist::append(int value) {
  std::shared_ptr<node> newNode {new node {value}};
  if (first == nullptr) {
    first = newNode;
  } else {
    last->next = newNode;
  last = newNode;
```

LINKED LIST SHARED_PTR SHARING

```
void llist::prepend(int value) {
  std::shared_ptr<node> newNode {new node {value}};
  newNode->next = first;
  first = newNode;
  if (last == nullptr) {
    last = first;
                     These each initialize their shared ptr count to 1.
void llist::append(int value) {
  std::shared_ptr<node> newNode {new node {value}};
  if (first == nullptr) {
    first = newNode;
  } else {
    last->next = newNode;
  last = newNode;
                          These copy assignments each increment
```

their shared ptr count.

```
void llist::remove(int value) {
  std::shared ptr<node> follow {nullptr};
  std::shared ptr<node> current {first};
  while (current != nullptr && current->data != value) {
    follow = current;
    current = current->next;
  if (current != nullptr) {
    if (follow == nullptr) {
      first = current->next;
      if (current->next == nullptr) {
        last = first;
    } else {
      follow->next = current->next;
      if (current->next == nullptr) {
        last = follow;
```

```
void llist::remove(int value) {
  std::shared ptr<node> follow {nullptr};
  std::shared_ptr<node> current {first};
  while (current != nullptr && current->data != value) {
    follow = current;
    current = current->next;
  if (current != nullptr) {
    if (follow == nullptr) {
      first = current->next;
      if (current->next == nullptr) {
        last = first;
    } else {
      follow->next = current->next;
      if (current->next == nullptr) {
        last = follow;
```

Unlinking current decreases its shared_ptr's reference count.

```
void llist::remove(int value) {
  std::shared ptr<node> follow {nullptr};
  std::shared_ptr<node> current {first};
  while (current != nullptr && current->data != value) {
    follow = current;
    current = current->next;
  if (current != nullptr) {
    if (follow == nullptr) {
      first = current->next;
      if (current->next == nullptr) {
        last = first;
    } else {
      follow->next = current->next;
      if (current->next == nullptr)
        last = follow;
```

Unlinking current decreases

its shared_ptr's reference count.

E.g. This copy assignment takes current's shared_ptr out of follow->next.

```
void llist::remove(int value) {
  std::shared ptr<node> follow {nullptr};
  std::shared ptr<node> current {first};
  while (current != nullptr && current->data != value) {
    follow = current;
    current = current->next;
  if (current != nullptr) {
    if (follow == nullptr) {
      first = current->next;
      if (current->next == nullptr) {
        last = first;
    } else {
      follow->next = current->next;
      if (current->next == nullptr) {
        last = follow;
```

Here current goes out of scope; count goes to 0; node is reclaimed

A SHARED_PTR SINGLY LINKED LIST SUMMARY

- ▶ By using shared_ptr, every reference to a node is counted.
- ▶ When a new node is made, a shared_ptr is invented with a count of 1.
 - It has an underlying raw pointer obtained from new.
- ▶ When a relink happens:
 - → A non-null reference's count decrements.
 - → Another reference's count increments.
- ▶ When a reference count goes to 0:
 - The underlying raw pointer is **deleted**.
 - → If non-null, its **next** reference's count is decremented.
- The code never explictly calls **delete**.

CHECK OUT MY SAMPLE CODE

- ▶I have four versions of linked lists that use **shared_ptr** in samples:
 - Ilist.cc: what I just showed you with test code
 - dbllist_*.cc: three doubly-linked lists, each with test code
 - _bad.cc: because of circular paths in the data structure, memory leak
 - better.cc: detaches prev links in ~dbllist() to break cycles
 - best.cc: uses weak_ptr for prev to break shared_ptr cycles
- ▶In the last, weak_ptr back references aren't counted... one typical use.

WE'RE DONE!

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 - We'll look at the Berkeley socket library.
- ▶ Next week I'll talk about code that does several things at once.
 - It's written so that it can run on multiple processor cores.
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- ▶These is extra material; FYI; "not on the exam."
- ▶ We'll have a last homework assignment.
- ▶ We'll have a comprehensive final exam.