

1 Formalization

1.1 Syntax

$$\begin{array}{ll} f \in \text{TRANSFORMER NAMES} & t \in \text{TYPE NAMES} \\ a, x, y, z \in \text{IDENTIFIERS} & \end{array}$$

$$\begin{array}{ll} \mathcal{Q}, \mathcal{R}, \mathcal{S} & ::= ! \mid \text{any} \mid \text{nonempty} \mid \text{empty} \mid \text{every} \\ M & ::= \text{fungible} \mid \text{unique} \mid \text{immutable} \mid \text{consumable} \mid \text{asset} \quad (\text{type declaration modifiers}) \\ T & ::= \text{bool} \mid \text{type } t \text{ is } \overline{M} T \mid \text{list } \tau \mid \{\overline{x} : \overline{\tau}\} \\ \tau, \sigma, \pi & ::= \mathcal{Q} T \\ \mathcal{S} & ::= x \mid x.y \mid \text{true} \mid \text{false} \mid [x] \mid \{\overline{x} : \overline{\tau} \mapsto \overline{x}\} \mid \text{new}(t, \overline{M}, T) \\ \mathcal{D} & ::= x \mid x.y \mid \text{var } x : T \mid \text{consume} \\ \text{Decl} & ::= \text{transformer } f(\overline{x} : \overline{\tau}) \rightarrow x : \tau \{ \text{Stmt} \} \\ \text{Stmt} & ::= \text{pass} \\ & \quad \mid \mathcal{S} \rightarrow \mathcal{D} \mid \mathcal{S} \xrightarrow{\mathcal{Q} \text{ s.t. } f(\overline{x})} \mathcal{D} \mid \mathcal{S} \rightarrow f(\overline{x}) \rightarrow \mathcal{D} \\ & \quad \mid \text{try } \{ \text{Stmt} \} \text{ catch } \{ \text{Stmt} \} \\ \text{Prog} & ::= \overline{\text{Decl}}; \overline{\text{Stmt}} \end{array}$$

1.2 Statics

$\boxed{\Gamma \vdash \mathcal{S} : \tau \dashv \Delta} \quad \boxed{\Gamma \vdash \mathcal{D} : \tau \dashv \Delta}$ **Storage Typing**
A *storage* is either a source or a destination.

$$\begin{array}{c} \frac{b \in \{\text{true}, \text{false}\}}{\Gamma \vdash b : ! \text{bool} \dashv \Gamma} \text{Bool} \qquad \frac{\neg(\tau \text{ immutable})}{\Gamma, x : \tau \vdash x : \tau \dashv \Gamma, x : \tau} \text{Var} \\[10pt] \frac{\Gamma \vdash x : \tau \dashv \Delta \quad \neg(\tau \text{ immutable}) \quad \text{fields}(\tau) = \overline{z} : \overline{\sigma} \quad y : \mathcal{R} T \in \overline{z} : \overline{\sigma}}{\Gamma \vdash x.y : \mathcal{R} T \dashv \Gamma} \text{Field} \\[10pt] \frac{}{\Gamma, x : \mathcal{Q} T \vdash [x] : ! \text{list } \mathcal{Q} T \dashv \Gamma, x : \text{empty } T} \text{Single} \\[10pt] \frac{}{\Gamma, \overline{y} : \overline{\mathcal{Q} T} \vdash \{\overline{x} : \overline{\mathcal{Q} T} \mapsto \overline{y}\} : ! \{\overline{x} : \overline{\mathcal{Q} T}\} \dashv \Gamma, \overline{y} : \text{empty } T} \text{Record} \\[10pt] \frac{}{\Gamma \vdash \text{new}(t, \overline{M}, T) : \text{every list } ! (\text{type } t \text{ is } \overline{M} T) \dashv \Gamma} \text{New} \\[10pt] \frac{}{\Gamma \vdash (\text{var } x : T) : \text{empty } T \dashv \Gamma, x : \text{empty } T} \text{VarDef} \qquad \frac{\tau \text{ consumable}}{\Gamma \vdash \text{consume} : \tau \dashv \Gamma} \text{Consume} \end{array}$$

$\Gamma \vdash S \text{ ok} \dashv \Delta$ Statement Well-formedness

$$\begin{array}{c}
\frac{}{\Gamma \vdash \text{pass ok} \dashv \Gamma} \text{OK-PASS} \quad \frac{\Gamma \vdash S : Q \ T \dashv \Delta \quad \text{update}(\Delta, S, \Delta(S) \ominus Q) \vdash D : \mathcal{R} \ T \dashv \Xi}{\Gamma \vdash (S \rightarrow D) \text{ ok} \dashv \text{update}(\Xi, D, \Xi(D) \oplus Q)} \text{OK-FLOW-EVERY} \\
\\
\frac{\Gamma \vdash S : Q \ T \dashv \Delta \quad \text{transformer } f(\overline{x} : \overline{\sigma}, y : \text{demote}(\text{elemtype}(T))) \rightarrow z : ! \text{bool} \text{ do } \overline{\text{Stmt}} \quad \forall i. \text{demote}(\Gamma(a_i)) = \sigma_i \quad \text{update}(\Delta, S, \Delta(S) \ominus Q) \vdash D : S \ T \dashv \Xi}{\Gamma \vdash (S \xrightarrow{\mathcal{R} \text{ s.t. } f(\overline{a})} D) \text{ ok} \dashv \text{update}(\Xi, D, \Xi(D) \oplus \min(Q, \mathcal{R}))} \text{OK-FLOW-FILTER} \\
\\
\frac{\Gamma \vdash S : Q \ T_1 \dashv \Delta \quad \text{transformer } f(\overline{x} : \overline{\sigma}, y : \text{demote}(\text{elemtype}(T_1))) \rightarrow z : \mathcal{R} \ T_2 \text{ do } \overline{\text{Stmt}} \quad \forall i. \text{demote}(\Gamma(x_i)) = \sigma_i \quad \text{update}(\Delta, S, \Delta(S) \ominus Q) \vdash D : S \ T_2 \dashv \Xi}{\Gamma \vdash (S \rightarrow f(\overline{x}) \rightarrow D) \text{ ok} \dashv \text{update}(\Xi, D, \Xi(D) \oplus Q)} \text{OK-FLOW-TRANSFORMER} \\
\\
\frac{\Gamma \vdash \overline{S_1} \text{ ok} \dashv \Delta \quad \Gamma \vdash \overline{S_2} \text{ ok} \dashv \Xi}{\Gamma \vdash (\text{try } \{\overline{S_1}\} \text{ catch } \{\overline{S_2}\} \text{ ok} \dashv \Delta \sqcup \Xi)} \text{OK-TRY}
\end{array}$$

$\vdash \text{Decl ok}$ Declaration Well-formedness

$$\frac{\overline{x : \tau} \vdash \overline{\text{Stmt}} \text{ ok} \dashv \Gamma, y : \sigma \quad \forall \pi \in \text{img}(\Gamma). \neg(\pi \text{ asset})}{\vdash (\text{transformer } f(\overline{x} : \overline{\tau}) \rightarrow y : \sigma \{\overline{\text{Stmt}}\}) \text{ ok}} \text{OK-TRANSFORMER}$$

1.3 Dynamics

$$\begin{array}{ll}
V & ::= \text{true} \mid \text{false} \mid \{x : \tau \mapsto V\} \\
\mathcal{V} & ::= \overline{V} \\
\text{Stmt} & ::= \dots \mid \text{put}(\mathcal{V}, D) \mid \text{revert} \mid \text{try}(\Sigma, \overline{S}, \overline{S})
\end{array}$$

Definition 1. An environment Σ is a tuple (μ, ρ) where $\mu : \text{IDENTIFIERNAMES} \rightarrow \mathbb{N}$ is the variable lookup environment, and $\rho : \mathbb{N} \rightarrow \mathcal{V}$ is the storage environment.

$$\boxed{\langle \Sigma, \overline{\text{Stmt}} \rangle \rightarrow \langle \Sigma, \overline{\text{Stmt}} \rangle}$$

Note that we abbreviate $\langle \Sigma, \cdot \rangle$ as Σ , which signals the end of evaluation.

The new constructs of $\text{resolve}(\Sigma, S)$ and $\text{put}(\mathcal{V}, D)$ are used to simplify the process of locating sources and updating destinations, respectively.

$$\frac{\langle \Sigma, S_1 \rangle \rightarrow \langle \Sigma', \overline{S_3} \rangle}{\langle \Sigma, S_1 \overline{S_2} \rangle \rightarrow \langle \Sigma', \overline{S_3} \overline{S_2} \rangle} \text{SEQ} \quad \frac{}{\langle \Sigma, (\text{revert}) \overline{S} \rangle \rightarrow \langle \Sigma, \text{revert} \rangle} \text{REVERT} \quad \frac{}{\langle \Sigma, \text{pass} \rangle \rightarrow \Sigma} \text{PASS}$$

Here we give the rules for the new $\text{put}(\mathcal{V}, D)$ statement.

$$\frac{}{\langle \Sigma, \text{put}(\mathcal{V}, \text{consume}) \rangle \rightarrow \Sigma} \text{PUT-CONSUME} \quad \frac{\rho(\mu(A)) = \mathcal{W}}{\langle \Sigma, \text{put}(\mathcal{V}, A) \rangle \rightarrow \Sigma[\rho \mapsto \rho[\mu(A) \mapsto \mathcal{W}]]} \text{PUT-VAR} \\
\\
\frac{\ell \notin \text{dom}(\rho)}{\langle \Sigma, \text{put}(\mathcal{V}, \text{var } A : T) \rangle \rightarrow \Sigma[\mu \mapsto \mu[A \mapsto \ell], \rho \mapsto \rho[\ell \mapsto \mathcal{V}]]} \text{PUT-VARDEF}$$

$$\begin{array}{c}
\frac{\text{resolve}(\Sigma, \mathcal{S}) = (\Sigma', \ell)}{\langle \Sigma, \mathcal{S} \rightarrow \mathcal{D} \rangle \rightarrow \langle \Sigma'[\rho \mapsto \rho'[\ell \mapsto []]], \text{put}(\rho'(\ell), \mathcal{D}) \rangle} \text{FLOW-EVERY} \\
\\
\frac{\begin{array}{c} \text{resolve}(\Sigma, \mathcal{S}) = (\Sigma', \ell) \quad \rho'(\ell) = \mathcal{V} \\ \mathcal{U} = [v \in \mathcal{V} \mid \langle \Sigma', f(\bar{x}, v) \rangle \rightarrow^* \langle \Sigma'', k \rangle \text{ and } \rho''(k) = \text{true}] \quad \text{compat}(|\mathcal{U}|, |\mathcal{V}|, \mathcal{Q}) \end{array}}{\Sigma, (\mathcal{S} \xrightarrow{\mathcal{Q} \text{ s.t. } f(\bar{x})} \mathcal{D}) \rightarrow \langle \Sigma'[\rho' \mapsto \rho'[\ell \mapsto \rho'(\ell) \setminus \mathcal{U}]], \text{put}(\mathcal{U}, \mathcal{D}) \rangle} \text{FLOW-FILTER} \\
\\
\frac{\begin{array}{c} \text{resolve}(\Sigma, \mathcal{S}) = (\Sigma', \ell) \quad \rho'(\ell) = \mathcal{V} \\ \mathcal{U} = [v \in \mathcal{V} \mid \langle \Sigma', f(\bar{x}, v) \rangle \rightarrow^* \langle \Sigma'', k \rangle \text{ and } \rho''(k) = \text{true}] \quad \neg \text{compat}(|\mathcal{U}|, |\mathcal{V}|, \mathcal{Q}) \end{array}}{\Sigma, (\mathcal{S} \xrightarrow{\mathcal{Q} \text{ s.t. } f(\bar{x})} \mathcal{D}) \rightarrow \langle \Sigma, \text{revert} \rangle} \text{FLOW-FILTER-FAIL} \\
\\
\frac{\begin{array}{c} \text{resolve}(\Sigma, \mathcal{S}) = (\Sigma', \ell) \\ \rho'(\ell) = v, \mathcal{V} \quad \langle \Sigma'[\rho \mapsto \rho'[\ell \mapsto \mathcal{V}]], f(\bar{x}, v) \rangle \rightarrow^* \langle \Sigma'', k \rangle \end{array}}{\langle \Sigma, \mathcal{S} \rightarrow f(\bar{x}) \rightarrow \mathcal{D} \rangle \rightarrow \langle (\mu', \rho''), \text{put}(\rho''(k), \mathcal{D}) (\mathcal{S} \rightarrow f(\bar{x}) \rightarrow \mathcal{D}) \rangle} \text{FLOW-TRANSFORMER} \\
\\
\frac{\text{resolve}(\Sigma, \mathcal{S}) = (\Sigma', \ell) \quad \rho'(\ell) = []}{\langle \Sigma, \mathcal{S} \rightarrow f(\bar{x}) \rightarrow \mathcal{D} \rangle \rightarrow \Sigma} \text{FLOW-TRANSFORMER-DONE} \\
\\
\frac{\ell \notin \text{dom}(\rho) \quad \text{transformer } f(\bar{y} : \bar{\tau}) \rightarrow z : \sigma \text{ do } \bar{S} \quad \mu' = \overline{y \mapsto \mu(x)}, z \mapsto \ell}{\langle \Sigma, f(\bar{x}) \rangle \rightarrow \langle (\mu', \rho[\ell \mapsto []]), \bar{S} \ell \rangle} \text{CALL}
\end{array}$$

We introduce a new statement, $\text{try}(\Sigma, \bar{S}_1, \bar{S}_2)$, to implement the try-catch statement, which keeps track of the environment that we begin execution in so that we can revert to the original environment in the case of a `revert`.

$$\begin{array}{c}
\frac{}{\langle \Sigma, \text{try } \{\bar{S}_1\} \text{ catch } \{\bar{S}_2\} \rangle \rightarrow \langle \Sigma, \text{try}(\Sigma, \bar{S}_1, \bar{S}_2) \rangle} \text{TRY-START} \\
\\
\frac{\langle \Sigma, \bar{S}_1 \rangle \rightarrow \langle \Sigma'', \bar{S}_1' \rangle}{\langle \Sigma, \text{try}(\Sigma', \bar{S}_1, \bar{S}_2) \rangle \rightarrow \langle \Sigma'', \text{try}(\Sigma', \bar{S}_1', \bar{S}_2) \rangle} \text{TRY-STEP} \\
\\
\frac{}{\langle \Sigma, \text{try}(\Sigma', \text{revert}, \bar{S}_2) \rangle \rightarrow \langle \Sigma', \bar{S}_2 \rangle} \text{TRY-REVERT} \qquad \frac{}{\langle \Sigma, \text{try}(\Sigma', \cdot, \bar{S}_2) \rangle \rightarrow \Sigma} \text{TRY-DONE}
\end{array}$$

[Need to handle fungible specially (or maybe only after adding nats, I'm not sure it really has any meaning without them)]

$\text{resolve}(\Sigma, \mathcal{S}) = (\Sigma', \ell)$ **Storage Resolution**

We use $\text{resolve}(\Sigma, \mathcal{S})$ to get the location storing the values of \mathcal{S} , which returns an environment because it may need to allocate new memory (e.g., in the case of creating a new record value).

$$\begin{array}{c}
\frac{\mu(\mathcal{S}) = \ell}{\text{resolve}(\Sigma, \mathcal{S}) = (\Sigma, \ell)} \text{ RESOLVE-VAR} \quad \frac{\rho(\mu(x)) = \overline{\{z : \tau \mapsto \ell\}} \quad (y : \sigma \mapsto k) \in \overline{z : \tau \mapsto \ell}}{\text{resolve}(\Sigma, x.y) = (\Sigma, k)} \text{ RESOLVE-FIELD} \\
\\
\frac{\ell \notin \text{dom}(\rho)}{\text{resolve}(\Sigma, [x]) = (\Sigma[\rho \mapsto \rho[\ell \mapsto \rho(\mu(x)), \mu(x) \mapsto []]], \ell)} \text{ RESOLVE-SINGLE} \\
\\
\frac{k \notin \text{dom}(\rho) \cup \bar{\ell} \quad \frac{\ell \notin \text{dom}(\rho)}{\Sigma' = \Sigma[\rho \mapsto \rho[\mu(y) \mapsto [], \ell \mapsto \rho(\mu(y)), k \mapsto \{x : \tau \mapsto \ell\}]]} \text{ RESOLVE-RECORD}}{\text{resolve}(\Sigma, \{\bar{x} : \tau \mapsto \bar{y}\}) = (\Sigma', k)} \text{ RESOLVE-RECORD} \\
\\
\frac{b \in \{\text{true}, \text{false}\} \quad \ell \notin \text{dom}(\rho)}{\text{resolve}(\Sigma, b) = (\Sigma[\rho \mapsto \rho[\ell \mapsto b]], \ell)} \text{ RESOLVE-BOOL} \\
\\
\frac{\mu(t) = \ell}{\text{resolve}(\Sigma, \text{new}(t, \bar{M}, T)) = (\Sigma, \ell)} \text{ RESOLVE-SOURCE} \\
\\
\frac{t \notin \text{dom}(\mu) \quad \ell \notin \text{dom}(\rho)}{\text{resolve}(\Sigma, \text{new}(t, \bar{M}, T)) = (\Sigma'[\rho \mapsto \rho[\ell \mapsto \text{values}(T)], \mu \mapsto \mu[t \mapsto \ell]], \ell)} \text{ RESOLVE-NEW-SOURCE}
\end{array}$$

[TODO: Need to be sure to handle uniqueness correctly; could do this in RESOLVE-NEW-SOURCE, or in the various flow rules.]

1.4 Auxiliaries

Definition 2. Define $\mathbf{Quant} = \{\text{empty}, \text{any}, !, \text{nonempty}, \text{every}\}$, and call any $Q \in \mathbf{Quant}$ a type quantity. Define $\text{empty} < \text{any} < ! < \text{nonempty} < \text{every}$.

$\tau \text{ asset}$ **Asset Types**

$$\begin{aligned}
(Q \ T) \text{ asset} &\Leftrightarrow Q \neq \text{empty} \text{ and } (\text{asset} \in \text{modifiers}(T) \text{ or} \\
&\quad (T = C \ \tau \text{ and } \tau \text{ asset}) \text{ or} \\
&\quad (T = \{\bar{y} : \bar{\sigma}\} \text{ and } \exists x : \tau \in \bar{y} : \bar{\sigma}. (\tau \text{ asset})))
\end{aligned}$$

$\tau \text{ consumable}$ **Consumable Types**

$$\begin{aligned}
(Q \ T) \text{ consumable} &\Leftrightarrow \text{consumable} \in \text{modifiers}(T) \text{ or} \\
&\quad \neg((Q \ T) \text{ asset}) \text{ or} \\
&\quad (T = C \ \tau \text{ and } \tau \text{ consumable}) \text{ or} \\
&\quad (T = \{\bar{y} : \bar{\sigma}\} \text{ and } \forall x : \tau \in \bar{y} : \bar{\sigma}. (\sigma \text{ consumable}))
\end{aligned}$$

$Q \oplus R$ represents the quantity present when flowing R of something to a storage already containing Q . $Q \ominus R$ represents the quantity left over after flowing R from a storage containing Q .

Definition 3. Let $Q, R \in \mathbf{Quant}$. Define the commutative operator \oplus , called combine, as the unique

function $\mathbf{Quant}^2 \rightarrow \mathbf{Quant}$ such that

$$\begin{aligned} \mathcal{Q} \oplus \mathbf{empty} &= \mathcal{Q} \\ \mathcal{Q} \oplus \mathbf{every} &= \mathbf{every} \\ \mathbf{nonempty} \oplus \mathcal{R} &= \mathbf{nonempty} \quad \text{if } \mathbf{empty} < \mathcal{R} < \mathbf{every} \\ ! \oplus \mathcal{R} &= \mathbf{nonempty} \quad \text{if } \mathbf{empty} < \mathcal{R} < \mathbf{every} \\ \mathbf{any} \oplus \mathbf{any} &= \mathbf{any} \end{aligned}$$

Define the operator \ominus , called split, as the unique function $\mathbf{Quant}^2 \rightarrow \mathbf{Quant}$ such that

$$\begin{aligned} \mathcal{Q} \ominus \mathbf{empty} &= \mathcal{Q} \\ \mathbf{empty} \ominus \mathcal{R} &= \mathbf{empty} \\ \mathcal{Q} \ominus \mathbf{every} &= \mathbf{empty} \\ \mathbf{every} \ominus \mathcal{R} &= \mathbf{every} \quad \text{if } \mathcal{R} < \mathbf{every} \\ \mathbf{nonempty} - \mathcal{R} &= \mathbf{any} \quad \text{if } \mathbf{empty} < \mathcal{R} < \mathbf{every} \\ ! - \mathcal{R} &= \mathbf{empty} \quad \text{if } ! \leq \mathcal{R} \\ ! - \mathbf{any} &= \mathbf{any} \\ \mathbf{any} - \mathcal{R} &= \mathbf{any} \quad \text{if } \mathbf{empty} < \mathcal{R} < \mathbf{every} \end{aligned}$$

Note that we write $(\mathcal{Q} \ T) \oplus \mathcal{R}$ to mean $(\mathcal{Q} \oplus \mathcal{R}) \ T$ and similarly $(\mathcal{Q} \ T) \ominus \mathcal{R}$ to mean $(\mathcal{Q} \ominus \mathcal{R}) \ T$.

Definition 4. We can consider a type environment Γ as a function $\mathbf{IDENTIFIERS} \rightarrow \mathbf{TYPES} \cup \{\perp\}$ as follows:

$$\Gamma(x) = \begin{cases} \tau & \text{if } x : \tau \in \Gamma \\ \perp & \text{otherwise} \end{cases}$$

We write $\mathbf{dom}(\Gamma)$ to mean $\{x \in \mathbf{IDENTIFIERS} \mid \Gamma(x) \neq \perp\}$, and $\Gamma|_X$ to mean the environment $\{x : \tau \in \Gamma \mid x \in X\}$ (restricting the domain of Γ).

Definition 5. Let \mathcal{Q} and \mathcal{R} be type quantities, $T_{\mathcal{Q}}$ and $T_{\mathcal{R}}$ base types, and Γ and Δ type environments. Define the following orderings, which make types and type environments into join-semilattices. For type quantities, define the partial order \sqsubseteq as the reflexive closure of the strict partial order \sqsubset given by

$$\mathcal{Q} \sqsubset \mathcal{R} \Leftrightarrow (\mathcal{Q} \neq \mathbf{any} \text{ and } \mathcal{R} = \mathbf{any}) \text{ or } (\mathcal{Q} \in \{!, \mathbf{every}\} \text{ and } \mathcal{R} = \mathbf{nonempty})$$

For types, define the partial order \leq by

$$\mathcal{Q} \ T_{\mathcal{Q}} \leq \mathcal{R} \ T_{\mathcal{R}} \Leftrightarrow T_{\mathcal{Q}} = T_{\mathcal{R}} \text{ and } \mathcal{Q} \sqsubseteq \mathcal{R}$$

For type environments, define the partial order \leq by

$$\Gamma \leq \Delta \Leftrightarrow \forall x. \Gamma(x) \leq \Delta(x)$$

Denote the join of Γ and Δ by $\Gamma \sqcup \Delta$.

$\mathbf{elemtype}(T) = \tau$

$$\mathbf{elemtype}(T) = \begin{cases} \mathbf{elemtype}(T') & \text{if } T = \mathbf{type} \ t \text{ is } \overline{M} \ T' \\ \tau & \text{if } T = \mathcal{C} \ \tau \\ ! \ T & \text{otherwise} \end{cases}$$

$\boxed{\text{modifiers}(T) = \overline{M}}$ **Type Modifiers**

$$\text{modifiers}(T) = \begin{cases} \overline{M} & \text{if } T = \text{type } t \text{ is } \overline{M} T \\ \emptyset & \text{otherwise} \end{cases}$$

$\boxed{\text{demote}(\tau) = \sigma}$ $\boxed{\text{demote}_*(T_1) = T_2}$ **Type Demotion** demote and demote_{*} take a type and “strip”

all the asset modifiers from it, as well as unfolding named type definitions. This process is useful, because it allows selecting asset types without actually having a value of the desired asset type. Note that demoting a transformer type changes nothing. This is because a transformer is **never** an asset, regardless of the types that it operators on, because it has no storage.

$$\begin{aligned} \text{demote}(\mathcal{Q} T) &= \mathcal{Q} \text{demote}_*(T) \\ \text{demote}_*(\text{bool}) &= \text{bool} \\ \text{demote}_*({\overline{x : \tau}}) &= {\overline{x : \text{demote}(\tau)}} \\ \text{demote}_*(\text{type } t \text{ is } \overline{M} T) &= \text{demote}_*(T) \end{aligned}$$

$\boxed{\text{fields}(T) = \overline{x : \tau}}$ **Fields**

$$\text{fields}(T) = \begin{cases} \overline{x : \tau} & \text{if } T = {\overline{x : \tau}} \\ \text{fields}(T) & \text{if } T = \text{type } t \text{ is } \overline{M} T \\ \emptyset & \text{otherwise} \end{cases}$$

$\boxed{\text{update}(\Gamma, x, \tau)}$ **Type environment modification**

$$\text{update}(\Gamma, x, \tau) = \begin{cases} \Delta, x : \tau & \text{if } \Gamma = \Delta, x : \sigma \\ \Gamma & \text{otherwise} \end{cases}$$

$\boxed{\text{compat}(n, m, \mathcal{Q})}$ The relation $\text{compat}(n, m, \mathcal{Q})$ holds when the number of values sent, n , is compatible with the original number of values m , and the type quantity used, \mathcal{Q} .

$$\begin{aligned} \text{compat}(n, m, \mathcal{Q}) &\Leftrightarrow (\mathcal{Q} = \text{nonempty} \text{ and } n \geq 1) \text{ or} \\ &\quad (\mathcal{Q} = ! \text{ and } n = 1) \text{ or} \\ &\quad (\mathcal{Q} = \text{empty} \text{ and } n = 0) \text{ or} \\ &\quad (\mathcal{Q} = \text{every} \text{ and } n = m) \text{ or} \\ &\quad \mathcal{Q} = \text{any} \end{aligned}$$

$\boxed{\text{values}(T) = \mathcal{V}}$ The function values gives a list of all of the values of a given base type.

$$\begin{aligned} \text{values}(\text{bool}) &= [\text{true}, \text{false}] \\ \text{values}(\text{list } T) &= [L \mid L \subseteq \text{values}(T), |L| < \infty] \\ \text{values}(\text{type } t \text{ is } \overline{M} T) &= \text{values}(T) \\ \text{values}({\overline{x : \mathcal{Q} T}}) &= [{\overline{x : \tau \mapsto v}} \mid v \in \text{values}(T)] \end{aligned}$$