## 1 Formalization

## 1.1 Syntax

$$f \in \mathsf{TransformerNames} \qquad \qquad t \in \mathsf{TypeNames}$$
 
$$a, x, y, z \in \mathsf{Identifiers}$$

```
Q, \mathcal{R}, \mathcal{S} ::= ! | any | nonempty | empty | every
                                                                                                                                        (type quantities)
                 := fungible | unique | immutable | consumable | asset
                                                                                                                                        (type declaration modifiers)
                 := bool | nat | type t is \overline{M} T | list \tau | \{\overline{x}: \tau\}
                                                                                                                                        (base types)
\tau, \sigma, \pi := QT
                                                                                                                                        (types)
                := x \mid x.y \mid \text{true} \mid \text{false} \mid n \mid \text{demote}(x) \mid [x] \mid \{\overline{x: \tau \mapsto x}\} \mid \text{new}(t, \overline{M}, T)
                                                                                                                                        (sources)
                 := x \mid x.y \mid var x : T \mid consume
                                                                                                                                        (destinations)
                := transformer f(\overline{x:\tau}) \to x:\tau \{\overline{\mathsf{Stmt}}\}
Dec1
                                                                                                                                        (transformers)
Stmt
                  | \mathcal{S} \to \mathcal{D} | \mathcal{S} \xrightarrow{x} \mathcal{D} | \mathcal{S} \xrightarrow{\mathcal{Q} \text{ s.t. } f(\overline{x})} \mathcal{D} | \mathcal{S} \to f(\overline{x}) \to \mathcal{D}
                        try {Stmt} catch {Stmt}
                 := \overline{Decl}:\overline{Stmt}
Proa
```

[Remove bool type? Can implement the "filter" selectors another way, e.g., by using a transformer returning a pair.]

#### 1.2 Statics

$$\Gamma \vdash S : \tau \dashv \Delta$$
  $\Gamma \vdash D : \tau \dashv \Delta$  Storage Typing

A storage is either a source or a destination.

$$\frac{b \in \{\text{true}, \text{false}\}}{\Gamma \vdash b : ! \text{ bool } + \Gamma} \text{ Bool } \frac{\overline{\Gamma \vdash n : ! \text{ nat } + \Gamma}}{\Gamma \vdash n : ! \text{ nat } + \Gamma} \text{ Nat }$$

$$\frac{c}{\Gamma \vdash x : ! T \vdash d \text{ emote}(x) : \text{ demote}(\tau) + \Gamma, x : \tau} \text{ Demote } \frac{\text{immutable } \notin \text{ modifiers}(\tau)}{\Gamma, x : \tau \vdash x : \tau \vdash \Gamma, x : \tau} \text{ Var }$$

$$\frac{\Gamma \vdash x : ! T \vdash \Delta \quad \text{immutable } \notin \text{ modifiers}(\tau) \quad \text{ fields}(T) = \overline{z} : \overline{\sigma} \quad y : \tau \in \overline{z} : \overline{\sigma}}{\Gamma \vdash x : y : \tau \vdash \Gamma} \text{ Field}$$

$$\frac{\Gamma \vdash x : y : \tau \vdash \Gamma}{\Gamma, x : Q \vdash T \vdash [x] : ! \text{ list } Q \vdash T \vdash \Gamma, x : \text{ empty } T} \text{ Single}$$

$$\frac{\Gamma, \overline{y} : Q \vdash T \vdash \{\overline{x} : Q \vdash T \mapsto y\} : ! \{\overline{x} : Q \vdash T\} \vdash \Gamma, \overline{y} : \text{ empty } T} \text{ Record}$$

$$\frac{\Gamma \vdash \text{new}(t, \overline{M}, T) : \text{ every list } ! \text{ (type } t \text{ is } \overline{M} \vdash T) \vdash \Gamma}{\Gamma \vdash \text{ consumable}} \text{ Consume }$$

$$\frac{\tau \text{ consumable}}{\Gamma \vdash \text{ consume } : \tau \vdash \Gamma} \text{ Consume}$$

$$\Gamma \vdash S$$
 ok  $\dashv \Delta$  Statement Well-formedness

$$\frac{\Gamma \vdash \mathcal{S} : \mathcal{Q} \ T \dashv \Delta \quad \text{update}(\Delta, \mathcal{S}, \Delta(\mathcal{S}) \ominus \mathcal{Q}) \vdash \mathcal{D} : \mathcal{R} \ T \dashv \Xi}{\Gamma \vdash (\mathcal{S} \to \mathcal{D}) \ \text{ok} \dashv \text{update}(\Xi, \mathcal{D}, \Xi(\mathcal{D}) \ominus \mathcal{Q})} \ \text{Ok-Flow-Every}$$

$$\frac{\Gamma \vdash \mathcal{S} : \mathcal{Q} \ T \dashv \Delta \qquad \Delta \vdash x : \operatorname{demote}(\mathcal{R} \ T) \dashv \Delta \qquad \operatorname{update}(\Delta, \mathcal{S}, \Delta(\mathcal{S}) \ominus \mathcal{Q}) \vdash \mathcal{D} : \mathcal{S} \ T \dashv \Xi}{\Gamma \vdash (\mathcal{S} \xrightarrow{x} \mathcal{D}) \ \mathbf{ok} \dashv \operatorname{update}(\Xi, \mathcal{D}, \Xi(\mathcal{D}) \oplus \mathcal{R})}$$
 OK-Flow-Var

$$\Gamma \vdash \mathcal{S} : \mathcal{Q} \ T \dashv \Delta$$

$$\frac{\mathsf{transformer}\;f\left(\overline{x}:\overline{\sigma},y:\mathsf{demote}(\mathsf{elemtype}(T))\right)\to z:!\;\mathsf{bool}\;\left\{\,\overline{\mathsf{Stmt}}\;\right\}}{\mathsf{update}(\Gamma(a_i))=\sigma_i\;\;\;\mathsf{update}(\Delta,\mathcal{S},\Delta(\mathcal{S})\ominus\mathcal{Q})\vdash\mathcal{D}:\mathcal{S}\;T\dashv\Xi}\quad\mathsf{Ok\text{-}Flow\text{-}Filter}}\\ \Gamma\vdash(\mathcal{S}\;\frac{\mathcal{R}\;\mathsf{s.t.}\;f(\overline{a})}{\longrightarrow}\mathcal{D})\;\mathsf{ok}\;\dashv\;\mathsf{update}(\Xi,\mathcal{D},\Xi(\mathcal{D})\oplus\min(\mathcal{Q},\mathcal{R}))}$$

$$\Gamma \vdash \mathcal{S} : \mathcal{Q} \ T_1 \dashv \Delta$$

$$\frac{\Gamma \vdash \overline{S_1} \ \mathbf{ok} \dashv \Delta \qquad \Gamma \vdash \overline{S_2} \ \mathbf{ok} \dashv \Xi}{\Gamma \vdash (\mathbf{try} \ \{\overline{S_1}\}) \ \mathbf{catch} \ \{\overline{S_2}\}) \ \mathbf{ok} \dashv \Delta \sqcup \Xi} \ \mathrm{O}\kappa\text{-Try}$$

## + Decl ok Declaration Well-formedness

$$\frac{\overline{x:\tau} \vdash \overline{\mathsf{Stmt}} \ \mathbf{ok} \dashv \Gamma, y:\sigma \qquad \forall \pi \in \mathsf{img}(\Gamma). \neg (\pi \ \mathsf{asset})}{\vdash (\mathsf{transformer} \ f(\overline{x:\tau}) \to y:\sigma\{\overline{\mathsf{Stmt}}\}) \ \mathbf{ok}} \ \mathsf{Ok}\text{-}\mathsf{Transformer}$$

# Prog ok Program Well-formedness

$$\frac{\vdash \overline{\mathsf{Dec1}} \ \mathbf{ok} \qquad \emptyset \vdash \overline{\mathsf{Stmt}} \ \mathbf{ok} \dashv \Gamma \qquad \forall \, \tau \in \mathsf{img}(\Gamma). \neg (\tau \ \mathsf{asset})}{(\overline{\mathsf{Dec1}}; \overline{\mathsf{Stmt}}) \ \mathbf{ok}} \, \, \mathsf{Ok}\text{-}\mathsf{Prog}$$

### 1.3 Dynamics

$$\begin{array}{lll} V & & ::= & \text{true} \mid \text{false} \mid n \mid \{\overline{x:\tau \mapsto \mathbb{N}}\} \\ \mathcal{V} & & ::= & \overline{V} \\ \text{Stmt} & ::= & \dots \mid \text{put}(\mathcal{V}, \mathcal{D}) \mid \text{revert} \mid \text{try}(\Sigma, \overline{\text{Stmt}}, \overline{\text{Stmt}}) \end{array}$$

**Definition 1.** An environment  $\Sigma$  is a tuple  $(\mu, \rho)$  where  $\mu$ : IdentifierNames  $\to \mathbb{N}$  is the variable lookup environment, and  $\rho: \mathbb{N} \to \mathcal{V}$  is the storage environment.

$$\left\langle \Sigma, \overline{\mathsf{Stmt}} \right\rangle \rightarrow \left\langle \Sigma, \overline{\mathsf{Stmt}} \right\rangle$$

Note that we abbreviate  $\langle \Sigma, \cdot \rangle$  as  $\Sigma$ , which signals the end of evaluation.

The new constructs of  $resolve(\Sigma, S)$  and put(V, D) are used to simplify the process of locating sources and updating destinations, respectively. [Can probably just make put into a function as well, like resolve.]

$$\frac{\langle \Sigma, S_1 \rangle \to \left\langle \Sigma', \overline{S_3} \right\rangle}{\left\langle \Sigma, S_1 \overline{S_2} \right\rangle \to \left\langle \Sigma', \overline{S_3} \ \overline{S_2} \right\rangle} \, \text{SeQ} \qquad \frac{}{\left\langle \Sigma, (\text{revert}) \ \overline{S} \right\rangle \to \left\langle \Sigma, \text{revert} \right\rangle} \, \, \text{Revert} \qquad \frac{}{\left\langle \Sigma, \text{skip} \right\rangle \to \Sigma} \, \, \text{Skip}$$

Here we give the rules for the new put(V, D) statement. Here V + W refers to the combine operation for relevant values. [TODO: Need to finalize how V + W works; in particular, need to make sure that you can't overwrite things that shouldn't be overwritten (e.g., a nonfungible nat). Probably need to tag types with modifiers or something.]

[NOTE: It is important that we flow an empty list in the Flow-Transformer-Done rule, otherwise we may fail to allocate a variable as expected.]

$$\frac{\ell \not\in \operatorname{dom}(\rho) \qquad \operatorname{transformer} f(\overline{y}:\overline{\tau}) \to z : \sigma \; \{\; \overline{S}\; \} \qquad \mu' = \overline{y \mapsto \mu(x)}, z \mapsto \ell \\ \left\langle \Sigma, f(\overline{x}) \right\rangle \to \left\langle (\mu', \rho[\ell \mapsto []]), \overline{S}\; \ell \right\rangle$$

We introduce a new statement,  $try(\Sigma, \overline{S_1}, \overline{S_2})$ , to implement the try-catch statement, which keeps track of the environment that we begin execution in so that we can revert to the original environment in the case of a revert.

$$\begin{split} \overline{\left\langle \Sigma, \operatorname{try}\left\{\overline{S_1}\right\} \operatorname{catch}\left\{\overline{S_2}\right\} \right\rangle} &\to \left\langle \Sigma, \operatorname{try}(\Sigma, \overline{S_1}, \overline{S_2}) \right\rangle \overset{\operatorname{Try-Start}}{=} \\ &\frac{\left\langle \Sigma, \overline{S_1} \right\rangle \to \left\langle \Sigma'', \overline{S_1'} \right\rangle}{\left\langle \Sigma, \operatorname{try}(\Sigma', \overline{S_1}, \overline{S_2}) \right\rangle \to \left\langle \Sigma'', \operatorname{try}(\Sigma', \overline{S_1'}, \overline{S_2}) \right\rangle} \overset{\operatorname{Try-Start}}{=} \\ &\overline{\left\langle \Sigma, \operatorname{try}(\Sigma', \operatorname{revert}, \overline{S_2}) \right\rangle \to \left\langle \Sigma', \overline{S_2} \right\rangle} \overset{\operatorname{Try-Revert}}{=} &\overline{\left\langle \Sigma, \operatorname{try}(\Sigma', \cdot, \overline{S_2}) \right\rangle \to \Sigma} \overset{\operatorname{Try-Done}}{=} \end{split}$$

 $resolve(\Sigma, S) = (\Sigma', \ell)$  Storage Resolution

We use  $resolve(\Sigma, S)$  to get the location storing the values of S, which returns an environment because it may need to allocate new memory (e.g., in the case of creating a new record value).

$$\begin{split} \frac{\mu(\mathcal{S}) = \ell}{\operatorname{resolve}(\Sigma, \mathcal{S}) = (\Sigma, \ell)} & \operatorname{Resolve-Var} & \frac{\rho(\mu(x)) = \{\overline{z} : \tau \mapsto \ell\}}{\operatorname{resolve}(\Sigma, x.y) = (\Sigma, k)} \\ & \frac{\ell \notin \operatorname{dom}(\rho)}{\operatorname{resolve}(\Sigma, [x]) = (\Sigma[\rho \mapsto \rho[\ell \mapsto \rho(\mu(x)), \mu(x) \mapsto []]], \ell)} & \operatorname{Resolve-Single} \\ & \frac{\ell \notin \operatorname{dom}(\rho)}{\operatorname{resolve}(\Sigma, [x]) = (\Sigma[\rho \mapsto \rho[\ell \mapsto \rho(\mu(x)), \mu(x) \mapsto []]], \ell)} & \operatorname{Resolve-Single} \\ & \frac{\ell \notin \operatorname{dom}(\rho)}{\operatorname{resolve}(\Sigma, \{x : \tau \mapsto y\}) = (\Sigma', k)} \\ & \frac{b \in \{\operatorname{true}, \operatorname{false}\} \quad \ell \notin \operatorname{dom}(\rho)}{\operatorname{resolve}(\Sigma, b) = (\Sigma[\rho \mapsto \rho[\ell \mapsto b]], \ell)} & \operatorname{Resolve-Bool} \\ & \frac{\ell \notin \operatorname{dom}(\rho)}{\operatorname{resolve}(\Sigma, n) = (\Sigma[\rho \mapsto \rho[\ell \mapsto n]], \ell)} & \operatorname{Resolve-Nat} \\ & \frac{\mu(t) = \ell}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma, \ell)} & \operatorname{Resolve-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma, \ell)} & \operatorname{Resolve-New-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\rho \mapsto \rho[\ell \mapsto \operatorname{values}(T)], \mu \mapsto \mu[t \mapsto \ell]], \ell)} & \operatorname{Resolve-New-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\rho \mapsto \rho[\ell \mapsto \operatorname{values}(T)], \mu \mapsto \mu[t \mapsto \ell]], \ell)} & \operatorname{Resolve-New-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\rho \mapsto \rho[\ell \mapsto \operatorname{values}(T)], \mu \mapsto \mu[t \mapsto \ell]], \ell)} & \operatorname{Resolve-New-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\rho \mapsto \rho[\ell \mapsto \operatorname{values}(T)], \mu \mapsto \mu[t \mapsto \ell]], \ell)} & \operatorname{Resolve-New-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\rho \mapsto \rho[\ell \mapsto \operatorname{values}(T)], \mu \mapsto \mu[t \mapsto \ell]], \ell)} & \operatorname{Resolve-New-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\rho \mapsto \rho[\ell \mapsto \operatorname{values}(T)], \mu \mapsto \mu[t \mapsto \ell]], \ell} & \operatorname{Resolve-New-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\rho \mapsto \rho[\ell \mapsto \operatorname{values}(T)], \mu \mapsto \mu[t \mapsto \ell]], \ell} & \operatorname{Resolve-New-Source} \\ & \frac{t \notin \operatorname{dom}(\mu)}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\mu) \mapsto \mu[t \mapsto \ell]], \ell} & \operatorname{Resolve-New-Source} \\ & \frac{t \mapsto \operatorname{value}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\mu) \mapsto \mu[t \mapsto \ell]], \ell}{\operatorname{resolve}(\Sigma, \operatorname{new}(t, \overline{M}, T)) = (\Sigma'[\mu) \mapsto \mu[t \mapsto \ell]], \ell} & \operatorname{Resolve-New-Source} \\ & \frac{t \mapsto \operatorname{value}(\Sigma, \operatorname{value}(\Sigma, \overline{M}, T)) = (\Sigma'[\mu) \mapsto \mu[t \mapsto \ell]}, \ell} & \operatorname{value}(\Sigma, \overline{M}, T) = (\Sigma'[\mu) \mapsto \mu[t \mapsto \ell]}, \ell} & \operatorname{value}(\Sigma, \overline{M}, T) = (\Sigma'[\mu) \mapsto$$

[TODO: Need to be sure to handle uniqueness correctly; could do this in Resolve-New-Source, or in the various flow rules.]

#### 1.4 Auxiliaries

**Definition 2.** Define  $Quant = \{empty, any, !, nonempty, every\}$ , and call any  $Q \in Quant$  a type quantity. Define empty < any < ! < nonempty < every.

τ asset Asset Types

$$(\mathcal{Q}\ T)$$
 asset  $\Leftrightarrow \mathcal{Q} \neq \mathsf{empty}$  and  $(\mathsf{asset} \in \mathsf{modifiers}(T)\ \mathsf{or}$   $(T = \mathcal{C}\ \tau\ \mathsf{and}\ \tau\ \mathsf{asset})\ \mathsf{or}$   $(T = \{\overline{y}: \overline{\sigma}\}\ \mathsf{and}\ \exists x: \tau \in \overline{y: \overline{\sigma}}.(\tau\ \mathsf{asset})))$ 

τ consumable Consumable Types

$$(\mathcal{Q}\ T)$$
 consumable  $\Leftrightarrow$  consumable  $\in$  modifiers $(T)$  or  $\neg ((\mathcal{Q}\ T)\ \text{asset})$  or  $(T = \mathcal{C}\ \tau\ \text{and}\ \tau\ \text{consumable})$  or  $(T = \{\overline{y}: \overline{\sigma}\}\ \text{and}\ \forall x: \tau \in \overline{y}: \overline{\sigma}.(\sigma\ \text{consumable}))$ 

 $\mathcal{Q} \oplus \mathcal{R}$  represents the quantity present when flowing  $\mathcal{R}$  of something to a storage already containing  $\mathcal{Q}$ .  $\mathcal{Q} \ominus \mathcal{R}$  represents the quantity left over after flowing  $\mathcal{R}$  from a storage containing  $\mathcal{Q}$ .

**Definition 3.** Let  $Q, R \in Quant$ . Define the commutative operator  $\oplus$ , called combine, as the unique function  $Quant^2 \rightarrow Quant$  such that

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\mathcal{Q} \oplus \mathsf{empty} = \mathcal{Q}
\mathcal{Q} \oplus \mathsf{every} = \mathsf{every}
\mathsf{nonempty} \oplus \mathcal{R} = \mathsf{nonempty} \quad \mathit{if} \; \mathsf{empty} < \mathcal{R} < \mathsf{every}
! \oplus \mathcal{R} = \mathsf{nonempty} \quad \mathit{if} \; \mathsf{empty} < \mathcal{R} < \mathsf{every}
\mathsf{any} \oplus \mathsf{any} = \mathsf{any}
```

Define the operator  $\ominus$ , called split, as the unique function  $Quant^2 \rightarrow Quant$  such that

$$\begin{array}{rcl} \mathcal{Q} \ominus \mathsf{empty} &=& \mathcal{Q} \\ \mathsf{empty} \ominus \mathcal{R} &=& \mathsf{empty} \\ \mathcal{Q} \ominus \mathsf{every} &=& \mathsf{empty} \\ \mathsf{every} \ominus \mathcal{R} &=& \mathsf{every} & \mathit{if} \, \mathcal{R} < \mathsf{every} \\ \mathsf{nonempty} - \mathcal{R} &=& \mathsf{any} & \mathit{if} \, \mathsf{empty} < \mathcal{R} < \mathsf{every} \\ ! - \mathcal{R} &=& \mathsf{empty} & \mathit{if} \, ! \leq \mathcal{R} \\ ! - \mathit{any} &=& \mathsf{any} & \mathit{if} \, \mathsf{empty} < \mathcal{R} < \mathsf{every} \\ \mathsf{any} - \mathcal{R} &=& \mathsf{any} & \mathit{if} \, \mathsf{empty} < \mathcal{R} < \mathsf{every} \end{array}$$

Note that we write  $(Q T) \oplus \mathcal{R}$  to mean  $(Q \oplus \mathcal{R})$  T and similarly  $(Q T) \oplus \mathcal{R}$  to mean  $(Q \ominus \mathcal{R})$  T.

**Definition 4.** We can consider a type environment  $\Gamma$  as a function IDENTIFIERS  $\rightarrow$  Types $\cup$ { $\bot$ } as follows:

$$\Gamma(x) = \begin{cases} \tau & if \ x : \tau \in \Gamma \\ \bot & otherwise \end{cases}$$

We write  $dom(\Gamma)$  to mean  $\{x \in Identifiers \mid \Gamma(x) \neq \bot\}$ , and  $\Gamma|_X$  to mean the environment  $\{x : \tau \in \Gamma \mid x \in X\}$  (restricting the domain of  $\Gamma$ ).

**Definition 5.** Let Q and R be type quantities,  $T_Q$  and  $T_R$  base types, and  $\Gamma$  and  $\Delta$  type environments. Define the following orderings, which make types and type environments into join-semilattices. For type quantities, define the partial order  $\Gamma$  as the reflexive closure of the strict partial order  $\Gamma$  given by

$$Q \sqsubset \mathcal{R} \Leftrightarrow (Q \neq \text{any and } \mathcal{R} = \text{any}) \text{ or } (Q \in \{!, \text{every}\} \text{ and } \mathcal{R} = \text{nonempty})$$

For types, define the partial order  $\leq$  by

$$Q T_Q \leq \mathcal{R} T_{\mathcal{R}} \Leftrightarrow T_Q = T_{\mathcal{R}} \text{ and } Q \sqsubseteq \mathcal{R}$$

For type environments, define the partial order  $\leq$  by

$$\Gamma \le \Delta \Leftrightarrow \forall x. \Gamma(x) \le \Delta(x)$$

Denote the join of  $\Gamma$  and  $\Delta$  by  $\Gamma \sqcup \Delta$ .

$$elemtype(T) = \tau$$

$$elemtype(T) = \begin{cases} elemtype(T') & \text{if } T = \mathsf{type} \ t \ \mathsf{is} \ \overline{M} \ T' \\ \tau & \text{if } T = \mathcal{C} \ \tau \\ ! \ T & \text{otherwise} \end{cases}$$

 $modifiers(T) = \overline{M} \mid Type Modifiers$ 

$$\operatorname{modifiers}(T) = \begin{cases} \overline{M} & \text{if } T = \mathsf{type} \ t \ \mathsf{is} \ \overline{M} \ T \\ \emptyset & \text{otherwise} \end{cases}$$

demote $(\tau) = \sigma$  demote $_*(T_1) = T_2$  **Type Demotion** demote and demote $_*$  take a type and "strip" all the asset modifiers from it, as well as unfolding named type definitions. This process is useful, because it allows selecting asset types without actually having a value of the desired asset type. Note that demoting a transformer type changes nothing. This is because a transformer is **never** an asset, regardless of the types that it operators on, because it has no storage.

$$\begin{aligned} \operatorname{demote}(\mathcal{Q}\ T) &= \mathcal{Q}\ \operatorname{demote}_*(T) \\ \operatorname{demote}_*(\operatorname{bool}) &= \operatorname{bool} \\ \operatorname{demote}_*(\operatorname{nat}) &= \operatorname{nat} \\ \operatorname{demote}_*(\{\overline{x:\tau}\}) &= \left\{\overline{x:\operatorname{demote}(\tau)}\right\} \\ \operatorname{demote}_*(\operatorname{type}\ t\ \operatorname{is}\ \overline{M}\ T) &= \operatorname{demote}_*(T) \end{aligned}$$

 $\boxed{\text{fields}(T) = \overline{x : \tau} } \text{ Fields}$ 

$$fields(T) = \begin{cases} \overline{x : \tau} & \text{if } T = \{\overline{x : \tau}\} \\ fields(T) & \text{if } T = \mathsf{type} \ t \text{ is } \overline{M} \ T \\ \emptyset & \text{otherwise} \end{cases}$$

update $(\Gamma, x, \tau)$  | Type environment modification

update(
$$\Gamma$$
,  $x$ ,  $\tau$ ) = 
$$\begin{cases} \Delta$$
,  $x$ :  $\tau$  if  $\Gamma$  =  $\Delta$ ,  $x$ :  $\sigma$  otherwise

compat(n, m, Q) The relation compat(n, m, Q) holds when the number of values sent, n, is compatible with the original number of values m, and the type quantity used, Q.

$$\begin{aligned} \operatorname{compat}(n,m,\mathcal{Q}) &\Leftrightarrow (\mathcal{Q} = \operatorname{nonempty} \text{ and } n \geq 1) \text{ or } \\ (\mathcal{Q} = ! \text{ and } n = 1) \text{ or } \\ (\mathcal{Q} = \operatorname{empty} \text{ and } n = 0) \text{ or } \\ (\mathcal{Q} = \operatorname{every} \text{ and } n = m) \text{ or } \\ \mathcal{Q} = \operatorname{any} \end{aligned}$$

values(T) = V The function values gives a list of all of the values of a given base type.

$$\label{eq:values} \begin{split} \operatorname{values}(\mathsf{bool}) &= [\mathsf{true}, \mathsf{false}] \\ \operatorname{values}(\mathsf{nat}) &= [0, 1, 2, \ldots] \\ \operatorname{values}(\mathsf{list}\ T) &= [L|L \subseteq \operatorname{values}(T), |L| < \infty] \\ \operatorname{values}(\mathsf{type}\ t\ \operatorname{is}\ \overline{M}\ T) &= \operatorname{values}(T) \\ \operatorname{values}(\{\overline{x:Q\ T}\}) &= [\{\overline{x:\tau \mapsto v}\} | \overline{v \in \operatorname{values}(T)}] \end{split}$$