



Solvers for Stiff Systems

Van der Pol equation

$$z'' - \mu(1 - z^2)z' + z = 0$$

Transform 2nd order ODE
into 2 1st order ODEs:

$$y_1' = y_2$$

$$y_2' = \mu \cdot (1 - y_1^2) \cdot y_2 - y_1$$

Initial conditions for the state variables:

$$y_{1(t=0)} = 2$$

$$y_{2(t=0)} = 0$$

One parameter, μ :

- big value (1000): stiff system
- small value (1) : nonstiff

```
library(deSolve)

vdpol <- function(t, y, mu) {
  list(c(
    y[2],
    mu * (1 - y[1]^2) * y[2] - y[1]
  ))
}

yini <- c(y1 = 2, y2 = 0)

stiff <- ode(y = yini, func = vdpol, times = 0:3000, parms = 1000)

nonstiff <- ode(y = yini, func = vdpol, times = seq(0, 30, by = 0.01), parms = 1)

head(stiff, n = 3)

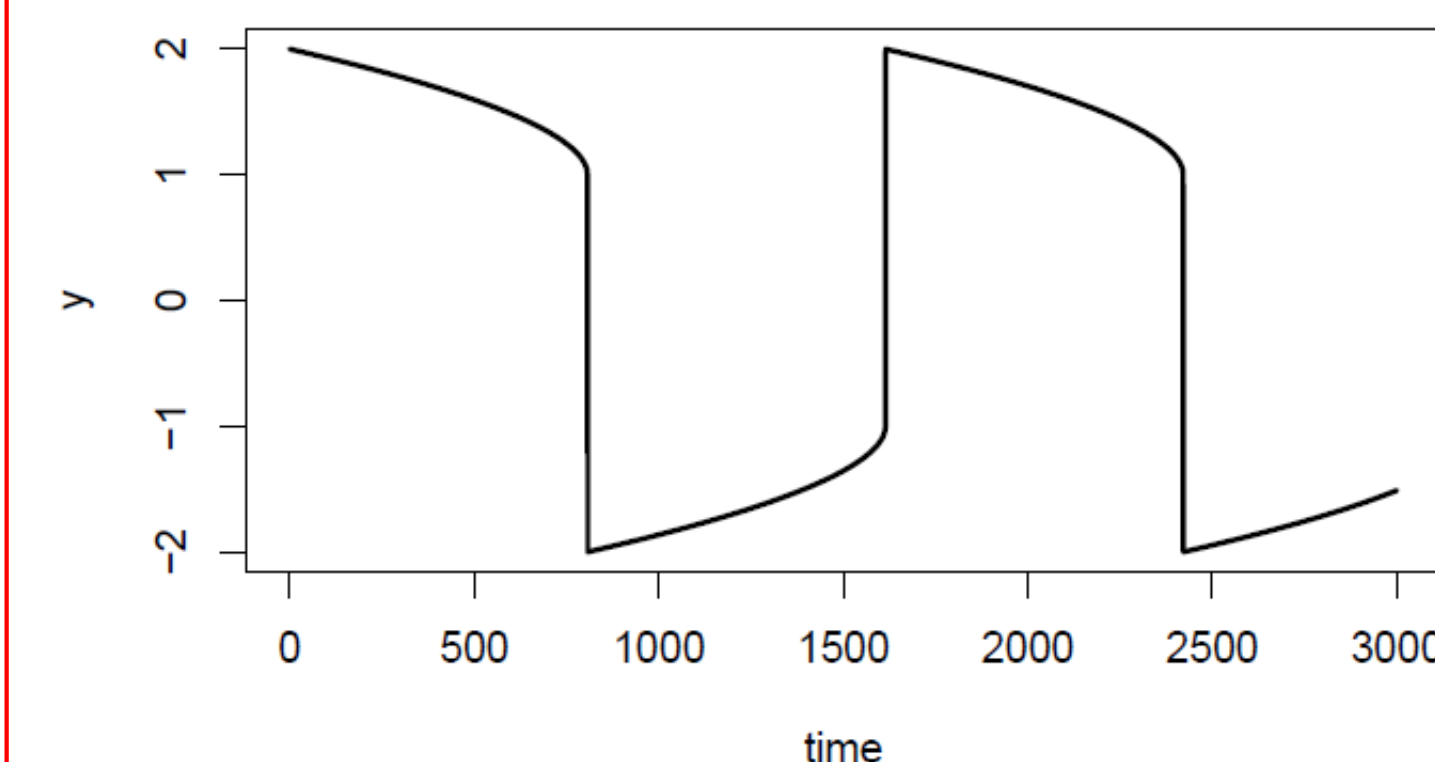
plot(stiff, type = "l", which = "y1", lwd = 2, ylab = "y", main = "IVP ODE, stiff")

plot(nonstiff, type = "l", which = "y1", lwd = 2, ylab = "y", main = "IVP ODE, nonstiff")
```

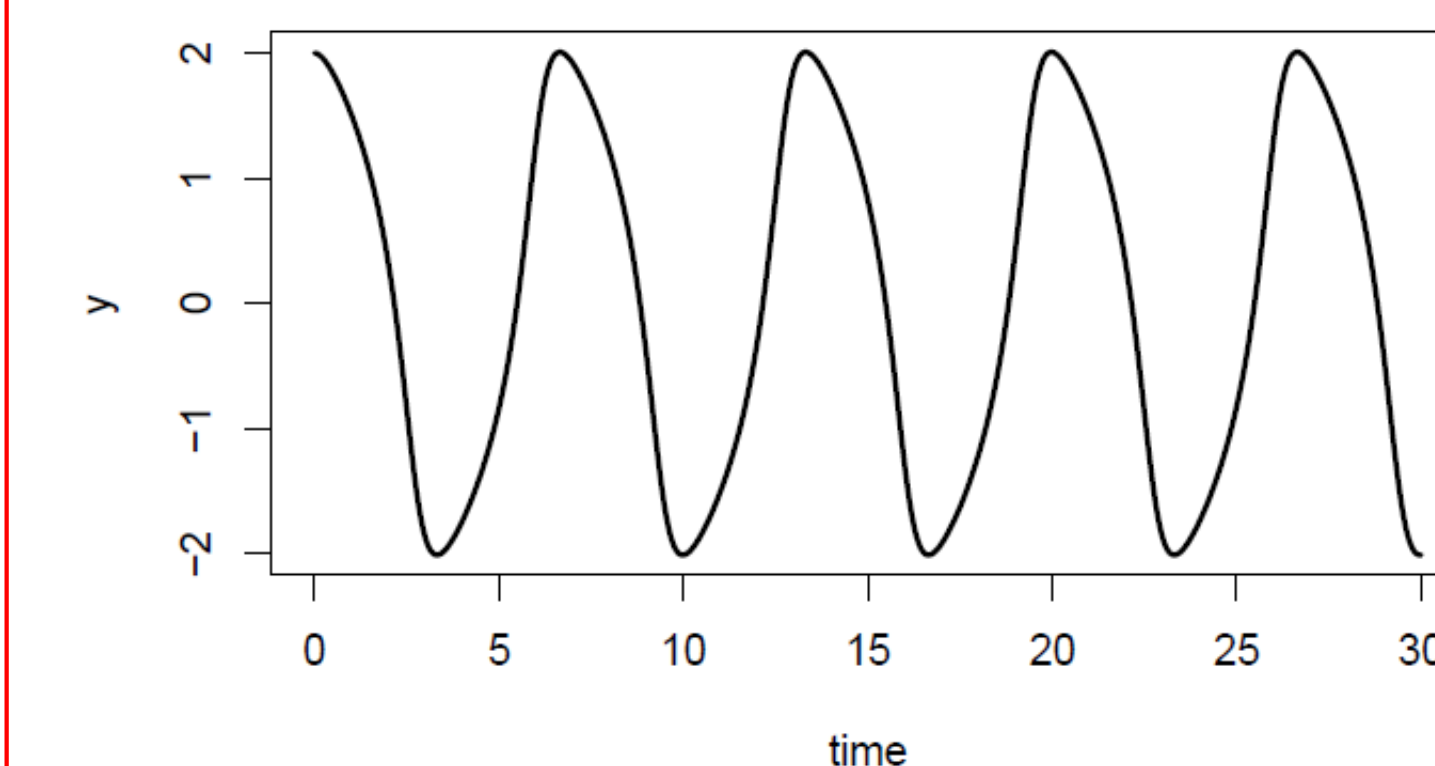
vanderpol.R

```
time    y1    y2
[1,]    0 2.000000 0.0000000000
[2,]    1 1.999333 -0.0006670373
[3,]    2 1.998666 -0.0006674088
```

IVP ODE, stiff



IVP ODE, nonstiff



Try different solver, e.g. "bdf";

```
system.time(
  stiff <- ode(y = yini, func = vdpol, times = 0:3000,
    parms = 1000, method = "bdf")
)
```

```
system.time(
  nonstiff <- ode(y = yini, func = vdpol, times = seq(0, 30, by = 0.01),
    parms = 1, method = "bdf")
)
```

Try other solvers:

"ode23", "lsoda", "adams", "bdf", "radau"
more, see ?ode

Result:

solver	non-stiff	stiff
ode23	0.37	271.19
lsoda	0.26	0.23
adams	0.13	616.13
bdf	0.15	0.22
radau	0.53	0.72

Stiff System:

Difficult to give a precise definition.

A system where some components change
much more rapidly than some others.

Difficult to solve:

- solution can be numerically unstable
- may require very small time steps (slow!)
- deSolve contains solvers that are suitable
for stiff systems
- But: "stiff solvers" less efficient for "well behaving" systems.

solver "lsoda" selects automatically between stiff solver (bdf)
and nonstiff solver (adams)

Solver Overview

Solver	Notes	stiff	$y' = f(t, y)$	$My' = f(t, y)$	$F(y', t, y) = 0$	Roots	Events	Lags (DDE)	Nesting
lsoda/lsodar	automatic method selection	auto	x			x	+	+	
lsode	bdf, adams, ...	user defined	x			+	+	+	
lsodes	sparse Jacobian	yes	x			+	+	+	
vode	bdf, adams, ...	user defined	x				+	+	
zvode	complex numbers	user defined	x				+	+	
daspk	DAE solver	yes	+	+	x		+	+	
radau	DAE; implicit RK	yes	x	x		+	+	+	
rk, rk4, euler	euler, ode23, ode45, ... rkMethod	no					+		+
iteration	returns state at t+dt	no	+				+		+

- ode, ode.band, ode.1D, ode.2D, ode.3D: top level functions (wrappers)
- red "+": functionality and/or algorithm added by us

References

Soetaert, K. Petzoldt, T. & Setzer, R. W. (2010):
Solving differential equations in R. The R Journal 2(2), 5-15.