

# A Spectral Approach To Meshes

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**1** Basics of Graphs

**2** Matrix Representations

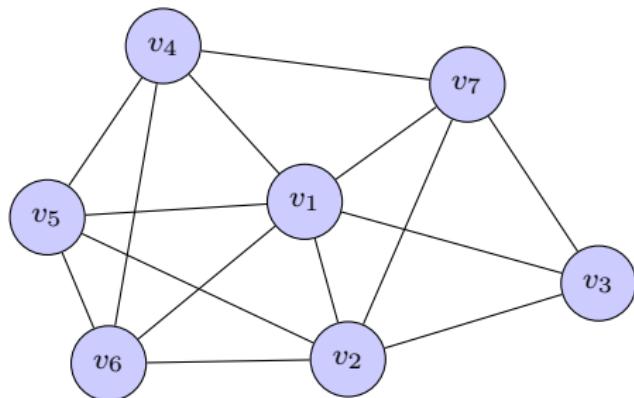
**3** Computational Geometry

## Definition (Graph)

A graph is a pair  $G = (V, E)$  where  $E$  is comprised of two element subsets of  $V$ . The elements of  $V$  are called *vertices* and the elements of  $E$  *edges*

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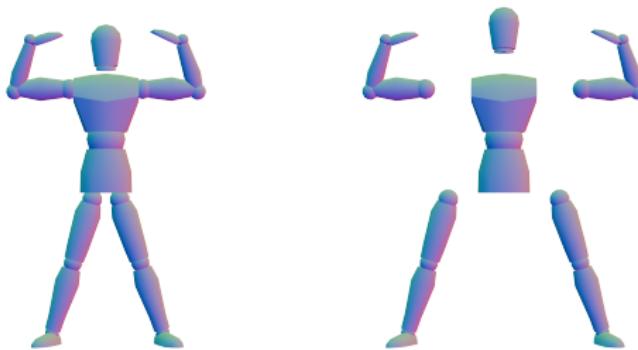
- Friend networks on social media platforms

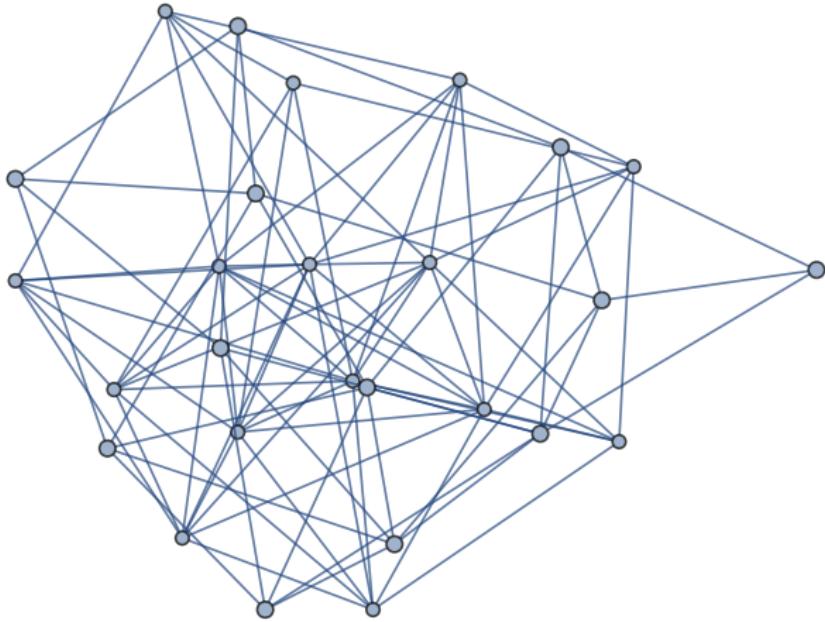
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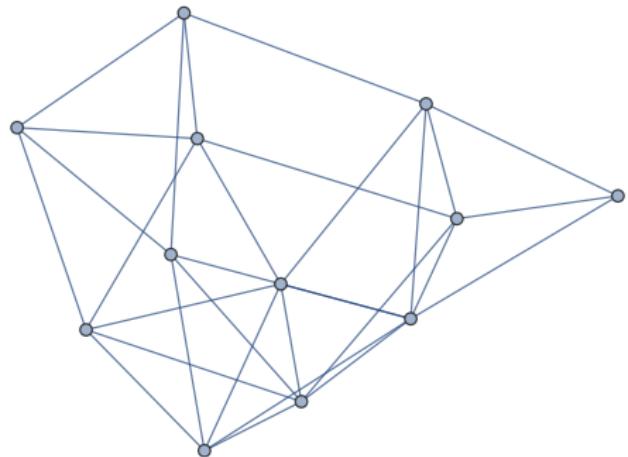
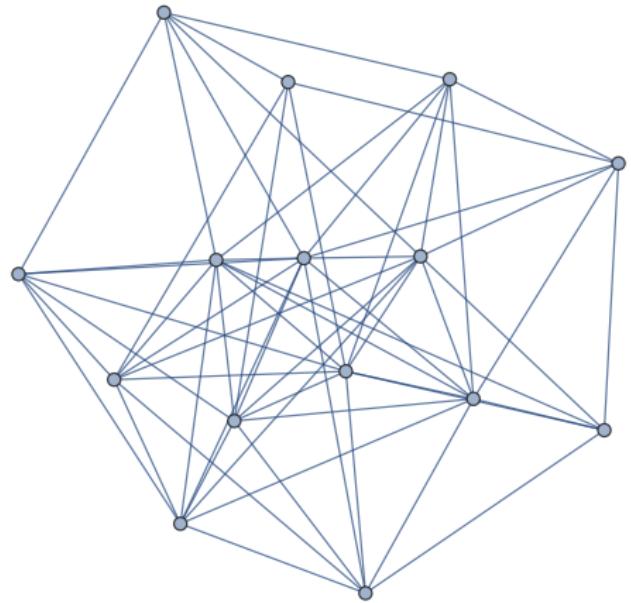
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- > Molecules and bonds between atoms in structural chemistry

Graphs at their core encode connectivity

- › Friend networks on social media platforms
- › Molecules and bonds between atoms in structural chemistry
- › Connectivity of meshes in computational geometry

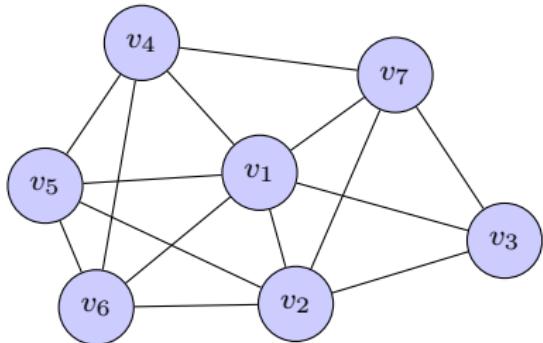






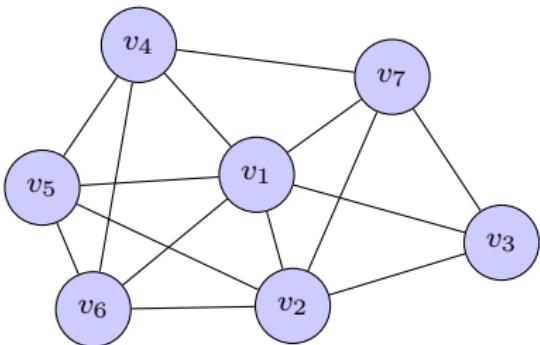
# Matrix Representations

	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$	$v_7$
$v_1$							
$v_2$							
$v_3$							
$v_4$							
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$v_7$							



# Matrix Representations

	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$	$v_7$
$v_1$		✓	✓	✓	✓	✓	✓
$v_2$	✓		✓		✓	✓	✓
$v_3$	✓	✓					✓
$v_4$	✓			✓	✓	✓	
$v_5$	✓	✓		✓		✓	
$v_6$	✓	✓		✓	✓		
$v_7$	✓	✓	✓	✓			



# Matrix Representations

	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$	$v_7$
$v_1$		✓	✓	✓	✓	✓	✓
$v_2$	✓		✓		✓	✓	✓
$v_3$	✓	✓					✓
$v_4$	✓				✓	✓	✓
$v_5$	✓	✓		✓		✓	
$v_6$	✓	✓		✓	✓		
$v_7$	✓	✓	✓	✓			

$$\xrightarrow{\hspace{1cm}} \begin{pmatrix} 0 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 1 & 0 & 0 & 0 \end{pmatrix}$$

Adjacency Matrix  $A$

## Definition (Degree Matrix)

The degree matrix of a graph  $G$  with  $n$  vertices is the  $n \times n$  matrix  $D$  such that

$$(D)_{ij} = \begin{cases} \deg(v_i) & i = j \\ 0 & i \neq j \end{cases}.$$

## Definition (Laplacian Matrix)

The Laplacian matrix of a graph  $G$  is

$$L := D - A.$$

## Theorem

*A graph has  $m$  connected components if and only if zero has algebraic multiplicity  $m$  for  $L$*

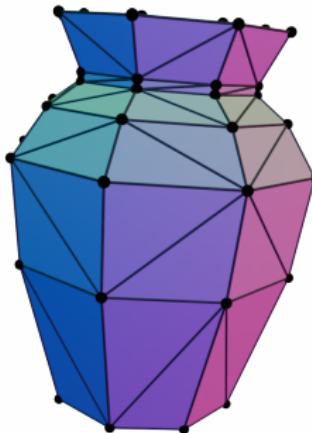
## Theorem

*The eigenvector associated with the smallest positive eigenvalue of  $L$  (called the “Fiedler Vector”) defines a well behaved partitioning scheme of a graph.*

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$K = (V, E, F)$  such that



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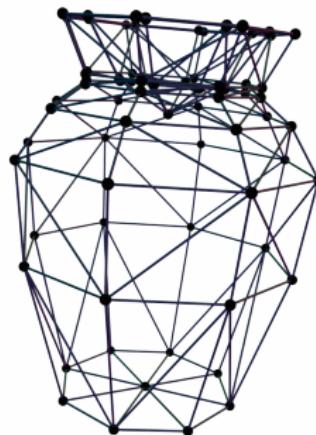


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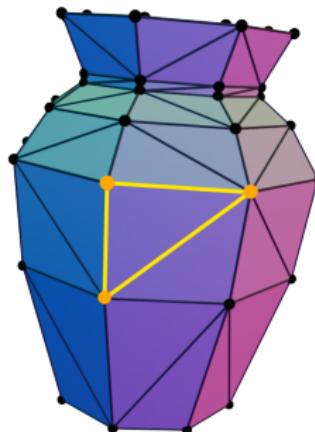
- $V \subseteq \mathbb{R}^3$  is the set of vertices
- $E \subseteq [V]^2$  is the set of representing non-intersecting edges
- $F \subseteq [E]^3$  is the set of faces such that for any  $f = \{e_1, e_2, e_3\} \in F$ ,

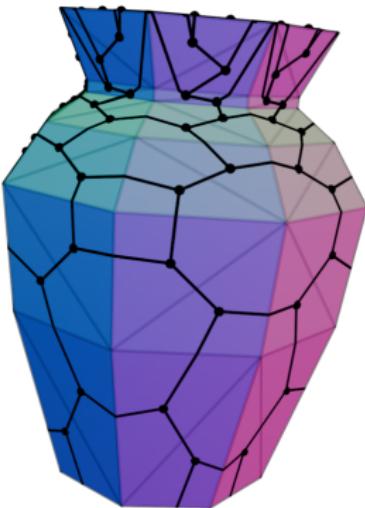
$$e_1 \cap e_2 = \{v_1\}$$

$$e_2 \cap e_3 = \{v_2\}$$

$$e_3 \cap e_1 = \{v_3\}$$

for  $v_1 \neq v_2 \neq v_3$ .





# Spectral Partitioning

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