

I want to finish discussing binary sort and why it's  $O(n \log n)$ . The extra credit assignment is on Blackboard.

Then we'll head into graph topology, i.e., planar and non-planar graphs.

Recall that to conduct a binary algorithm with  $N$  possible outcomes, we need a binary tree with  $N$  leaves, and so the height of that tree must be at least  $H \geq \lceil \log_2 N \rceil$ . To sort a list of  $n$  distinct items, i.e.,

$$\{a_1, a_2, a_3, \dots, a_n\},$$

we need to accommodate  $n!$  possible outcomes. Hence, we need our binary tree to satisfy

$$H \geq \lceil \log_2(n!) \rceil.$$

### Observations.

$$\begin{aligned} \log_2 k &= \frac{\ln k}{\ln 2} = \frac{1}{\ln 2} \ln k. \\ \log_2(n!) &= \frac{1}{\ln 2} \ln(n!) = \frac{1}{\ln 2} \ln(1 \cdot 2 \cdot 3 \cdot \dots \cdot n) \\ &= \frac{1}{\ln 2} (\ln 1 + \ln 2 + \ln 3 + \dots + \ln n) \end{aligned}$$

We're down to analyzing

$$\begin{aligned} \frac{1}{\ln 2} \sum_{k=1}^n \ln k. \\ \sum_{k=1}^n \ln k < \int_1^{n+1} \ln x \, dx < \sum_{k=1}^{n+1} \ln k. \end{aligned}$$

As a consequence,

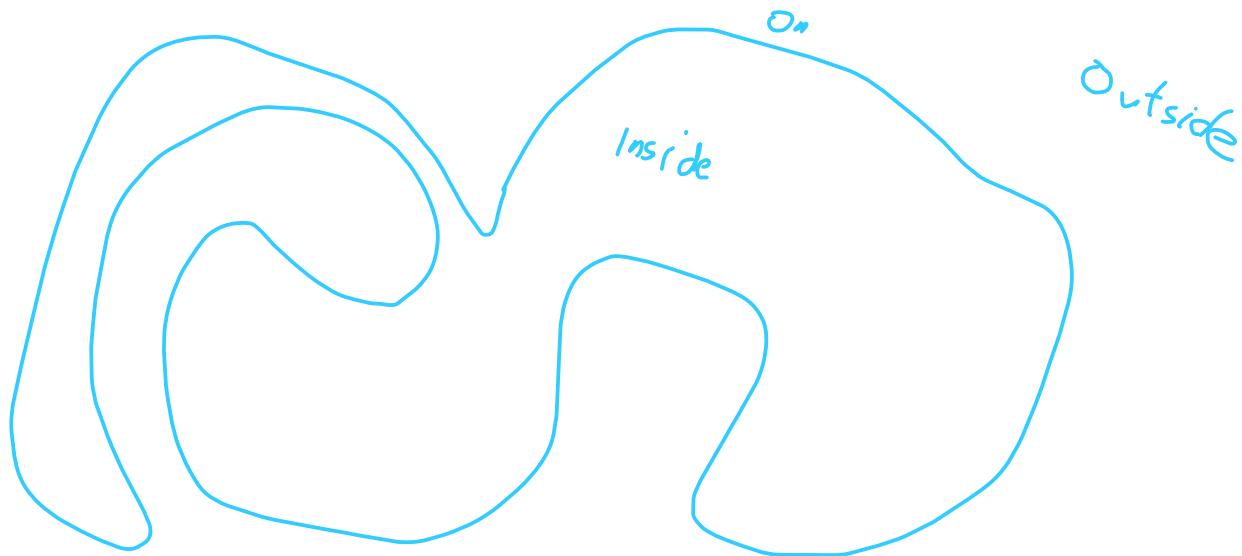
$$n \ln n - (n - 1) < \sum_{k=1}^n \ln k < (n + 1) \ln(n + 1) - n.$$

This implies

$$\log_2(n!) = O(n \log n).$$

## Chapter IV. Graph topology

### Planar or non-planar graphs



Intuitively, the Jordan curve theorem says if you have a simple closed curve  $C$  in the plane  $\mathbb{R}^2$ , then the plane is partitioned into three connected parts, the part “inside”  $C$ , the part “outside”  $C$ , and  $C$  itself.

**Intuitive definition.** A **planar graph** is a graph that can be drawn in the plane  $\mathbb{R}^2$  without edges crossing.

When we say “drawn”, we treat our vertices as elements of  $\mathbb{R}^2$ , the edges will be non-self-intersecting curves (often, they’ll be line segments) whose endpoints are the vertices drawn as elements of  $\mathbb{R}^2$ . To typeset  $\mathbb{R}$ , use \doubleR in the equation editor.

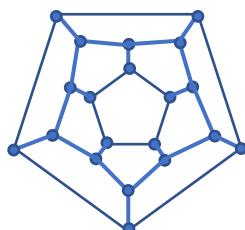
**Definition.** A **drawn graph** is a graph whose vertices are points in  $\mathbb{R}^2$  and whose edges are non-self-intersecting curves whose endpoints are the vertices drawn as points.

**Definition.** A **plane graph** is a drawn graph whose edges do not cross.

**Definition.** A **planar graph** is a graph that is isomorphic to a plane graph.

For a non-drawn graph, consider  $Q_3$  whose vertices are ordered triples of  $\{0,1\}$  where two vertices are adjacent if and only if they differ in exactly one coordinate.

Here is a drawn graph for the dodecahedron; hence, the dodecahedron is planar.



Easy examples of planar graphs: Trees.  $Q_3$ . Cycles.  $K_4, K_{2,n}$

Examples of nonplanar graphs:  $K_5, K_{3,3}, K_6$

Claim. If  $G$  is planar and  $H$  is a subgraph of  $G$ , then  $H$  is planar.

Contrapositive. If  $H$  is not planar and  $H$  is a subgraph of  $G$ , then  $G$  is not planar.

