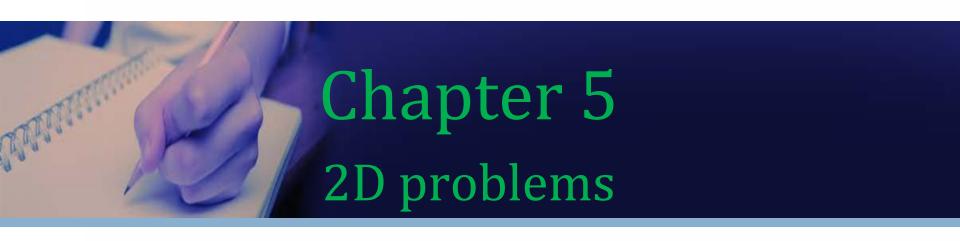


## **Structural Applications of Finite Elements**



2018-09-01



#### Outline |



- **2D** constant strain triangles
- Axisymmetric solids subjected to axisymmetric loading

#### Introduction



#### **Displacement vector**

$$\mathbf{u} = [u, v]^{\mathrm{T}}$$

#### Stresses and strain

$$\mathbf{\sigma} = [\sigma_x, \sigma_y, \tau_{xy}]^T$$

$$\boldsymbol{\epsilon} = [\epsilon_x, \epsilon_y, \gamma_{xy}]^T$$

The strain-displacement

## **Body force, traction vector** and element volume

$$\begin{cases} \mathbf{f} = [f_x, f_y]^T \\ \mathbf{T} = [T_x, T_y]^T \\ dV = t dA \end{cases}$$

$$\boldsymbol{\epsilon} = \left[ \frac{\partial u}{\partial x}, \frac{\partial v}{\partial y}, \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right]^{\mathsf{T}}$$

Stresses and strains are related

$$\sigma = D\epsilon$$

$$\mathbf{D} = \frac{E}{1 - \nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1 - \nu}{2} \end{bmatrix}$$

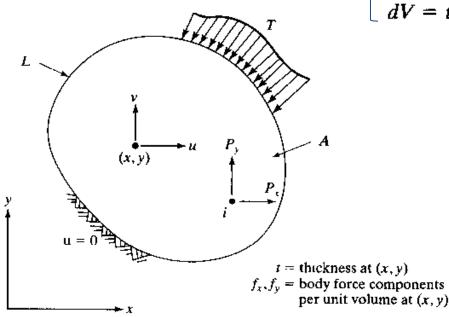


FIGURE 5.1 Two-dimensional problem.

## Finite element modeling

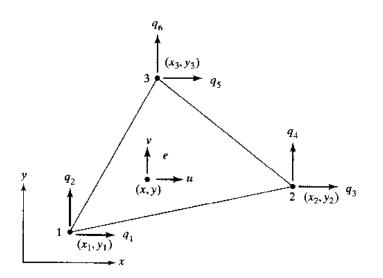


#### Global displacement vector

$$\mathbf{Q} = [Q_1, Q_2, \dots, Q_N]^{\mathrm{T}}$$

#### **Element displacement vector**

$$\mathbf{q} = [q_1, q_2, \dots, q_6]^{\mathrm{T}}$$



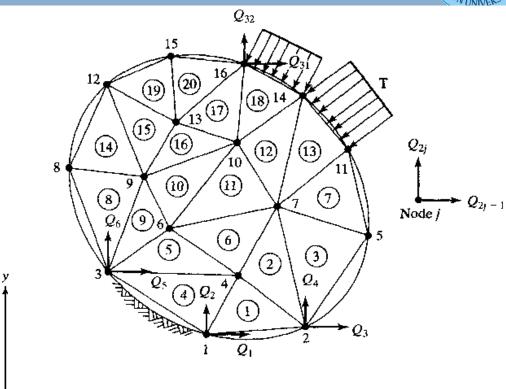


TABLE 5.1 Element Connectivity

Element number e	Three nodes		
	1	2	3
1	1	2	4
<b>2</b> :	4	2	7
11	6	7	10
20	13	16	15

## Constant strain triangle CST

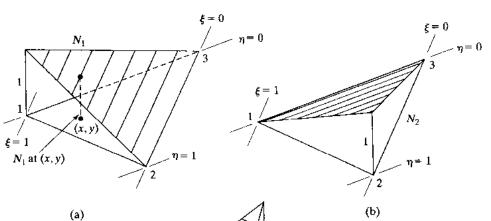


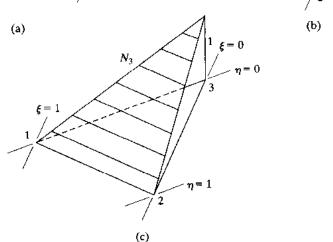
#### **Area coordinates**

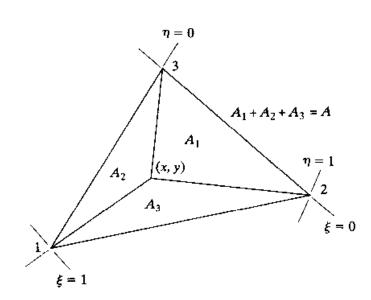
$$N_1 + N_2 + N_3 = 1$$

#### **Natural coordinates**

$$N_1 = \xi$$
  $N_2 = \eta$   $N_3 = 1 - \xi - \eta$ 







### Isoparametric representation



 $N_1 = \xi$   $N_2 = \eta$   $N_3 = 1 - \xi - \eta$ 

$$u = N_1 q_1 + N_2 q_3 + N_3 q_5$$

$$v = N_1 q_2 + N_2 q_4 + N_3 q_6$$

$$u = (q_1 + q_5)\xi + (q_3 + q_5)\eta + q_5$$

$$v = (q_2 - q_6)\xi + (q_4 - q_6)\eta + q_6$$

$$\mathbf{N} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 \end{bmatrix} \quad \mathbf{u} = \mathbf{N}\mathbf{q}$$

$$x = N_1 x_1 + N_2 x_2 + N_3 x_3$$
  
$$y = N_1 y_1 + N_2 y_2 + N_3 y_3$$

Using the notation,  $x_{ij} = x_i - x_j$  and  $y_{ij} = y_i - y_j$ ,

$$x = x_{13}\xi + x_{23}\eta + x_3$$
$$y = y_{13}\xi + y_{23}\eta + y_3$$

### Example



Using the isoparametric representation (Eqs. 5.15), we have Solution

$$3.85 = 1.5N_1 + 7N_2 + 4N_3 = -2.5\xi + 3\eta + 4$$

$$4.8 = 2N_1 + 3.5N_2 + 7N_3 = -5\xi - 3.5\eta + 7$$

These two equations are rearranged in the form

$$2.5\xi - 3\eta = 0.15$$

$$5\xi + 3.5\eta = 2.2$$

Solving the equations, we obtain  $\xi = 0.3$  and  $\eta = 0.2$ , which implies that

$$N_1 = 0.3$$

$$N_2 = 0.2$$

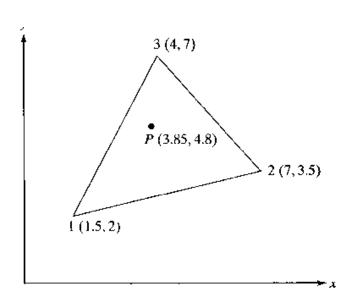
$$N_1 = 0.3$$
  $N_2 = 0.2$   $N_3 = 0.5$ 

$$x = N_1 x_1 + N_2 x_2 + N_3 x_3$$

$$y = N_1 y_1 + N_2 y_2 + N_3 y_3$$

$$x = x_{13}\xi + x_{23}\eta + x_3$$

$$y = y_{13}\xi + y_{23}\eta + y_3$$



#### Jacobian matrix



$$u = u(x(\xi, \eta), y(\xi, \eta))$$
$$v = v(x(\xi, \eta), y(\xi, \eta))$$

$$\frac{\partial u}{\partial \xi} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial \xi} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial \xi} \qquad \begin{cases} \partial u \\ \partial \xi \\ \frac{\partial u}{\partial \eta} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial \eta} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial \eta} \end{cases} \qquad \begin{cases} \partial u \\ \partial \xi \\ \frac{\partial u}{\partial \eta} \end{cases} = \begin{bmatrix} \partial x & \partial y \\ \partial \xi & \partial \xi \\ \frac{\partial u}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix} \begin{cases} \partial u \\ \partial x \\ \frac{\partial u}{\partial y} \end{cases}$$

$$x = x_{13}\xi + x_{23}\eta + x_3$$
$$y = y_{13}\xi + y_{23}\eta + y_3$$

$$\mathbf{J} = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix} \qquad \mathbf{J} = \begin{bmatrix} x_{13} & y_{13} \\ x_{23} & y_{23} \end{bmatrix}$$

$$\mathbf{J} = \begin{bmatrix} x_{13} & y_{13} \\ x_{23} & y_{23} \end{bmatrix}$$

$$\left\{ \begin{array}{l}
 \frac{\partial u}{\partial x} \\
 \frac{\partial u}{\partial y}
 \end{array} \right\} = \mathbf{J}^{-1} \left\{ \begin{array}{l}
 \frac{\partial u}{\partial \xi} \\
 \frac{\partial u}{\partial \eta}
 \end{array} \right\} \qquad \mathbf{J}^{-1} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} y_{23} & -y_{13} \\ -x_{23} & x_{13} \end{bmatrix} \\
 \det \mathbf{J} = x_{13}y_{23} - x_{23}y_{13}
 \end{array}$$

$$A = \frac{1}{2} |\det \mathbf{J}|$$

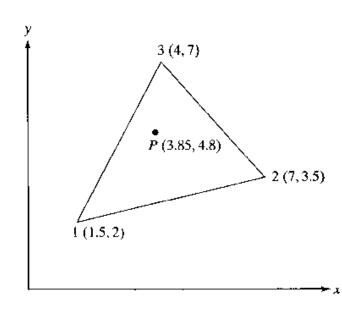
#### Example



Solution We have

$$\mathbf{J} = \begin{bmatrix} x_{13} & y_{13} \\ x_{23} & y_{23} \end{bmatrix} = \begin{bmatrix} -2.5 & -5.0 \\ 3.0 & -3.5 \end{bmatrix}$$

Thus, det J = 23.75 units. This is twice the area of the triangle. If 1, 2, 3 are in a clockwise order, then det J will be negative.



$$\mathbf{J}^{-1} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} y_{23} & -y_{13} \\ -x_{23} & x_{13} \end{bmatrix} \qquad u = (q_1 + q_5)\xi + (q_3 + q_5)\eta + q_5 \\ v = (q_2 - q_6)\xi + (q_4 - q_6)\eta + q_6$$



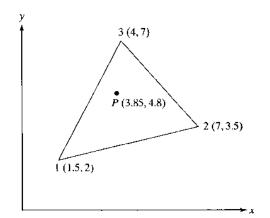
$$\epsilon = \begin{cases}
\frac{\partial u}{\partial x} \\
\frac{\partial v}{\partial y} \\
\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}
\end{cases} = \frac{1}{\det \mathbf{J}} \begin{cases}
y_{23}(q_1 - q_5) - y_{13}(q_3 - q_5) \\
-x_{23}(q_2 - q_6) + x_{13}(q_4 - q_6) \\
-x_{23}(q_1 - q_5) + x_{13}(q_3 - q_5) + y_{23}(q_2 - q_6) - y_{13}(q_4 - q_6)
\end{cases}$$

$$y_{31} = y_{13}$$
 and  $y_{12} = y_{13} - y_{23}$ 

$$\boldsymbol{\epsilon} = \frac{1}{\det \mathbf{J}} \begin{cases} y_{23}q_1 + y_{31}q_3 + y_{12}q_5 \\ x_{32}q_2 + x_{13}q_4 + x_{21}q_6 \\ x_{32}q_1 + y_{23}q_2 + x_{13}q_3 + y_{31}q_4 + x_{21}q_5 + y_{12}q_6 \end{cases}$$

$$\mathbf{B} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} y_{23} & 0 & y_{31} & 0 & y_{12} & 0 \\ 0 & x_{32} & 0 & x_{13} & 0 & x_{21} \\ x_{32} & y_{23} & x_{13} & y_{31} & x_{21} & y_{12} \end{bmatrix} \quad \mathbf{\epsilon} = \mathbf{B}\mathbf{q}$$

$$\epsilon = Bq$$



## Example

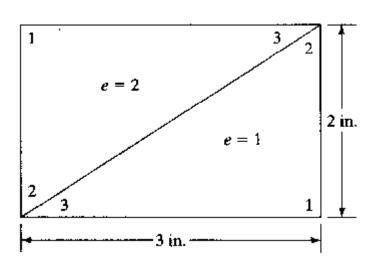


#### Solution We have

$$\mathbf{B}^{1} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} y_{23} & 0 & y_{31} & 0 & y_{12} & 0 \\ 0 & x_{32} & 0 & x_{13} & 0 & x_{21} \\ x_{32} & y_{23} & x_{13} & y_{31} & x_{21} & y_{12} \end{bmatrix}$$
$$= \frac{1}{6} \begin{bmatrix} 2 & 0 & 0 & 0 & -2 & 0 \\ 0 & -3 & 0 & 3 & 0 & 0 \\ -3 & 2 & 3 & 0 & 0 & -2 \end{bmatrix}$$

where det **J** is obtained from  $x_{13}y_{23} - x_{23}y_{13} = (3)(2) - (3)(0) = 6$ . Using the local numbers at the corners, **B**<sup>2</sup> can be written using the relationship as

$$\mathbf{B}^2 = \frac{1}{6} \begin{bmatrix} -2 & 0 & 0 & 0 & 2 & 0 \\ 0 & 3 & 0 & -3 & 0 & 0 \\ 3 & -2 & -3 & 0 & 0 & 2 \end{bmatrix}$$



## Potential energy approach



The potential energy of the system,  $\Pi$ , is given by

$$\Pi = \frac{1}{2} \int_{A} \mathbf{e}^{\mathrm{T}} \mathbf{D} \mathbf{e} t \, dA - \int_{A} \mathbf{u}^{\mathrm{T}} \mathbf{f} t \, dA - \int_{L} \mathbf{u}^{\mathrm{T}} t \, d\ell - \sum_{i} \mathbf{u}_{i}^{\mathrm{T}} \mathbf{P}_{i}$$

$$\Pi = \sum_{e} \frac{1}{2} \int_{e} \mathbf{e}^{\mathsf{T}} \mathbf{D} \mathbf{e} t \, dA - \sum_{e} \int_{e} \mathbf{u}^{\mathsf{T}} \mathbf{f} t \, dA - \int_{L} \mathbf{u}^{\mathsf{T}} \mathbf{T} t \, d\ell - \sum_{i} \mathbf{u}_{i}^{\mathsf{T}} \mathbf{P}_{i}$$

$$\Pi = \sum_{e} U_{e} - \sum_{e} \int_{e} \mathbf{u}^{\mathrm{T}} \mathbf{f} t \, dA - \int_{L} \mathbf{u}^{\mathrm{T}} \mathbf{T} t \, d\ell - \sum_{i} \mathbf{u}_{i}^{\mathrm{T}} \mathbf{P}_{i}$$

where  $U_{\varepsilon} = \frac{1}{2} \int_{\varepsilon} \mathbf{e}^{T} \mathbf{D} \mathbf{e} t \, dA$  is the element strain energy.

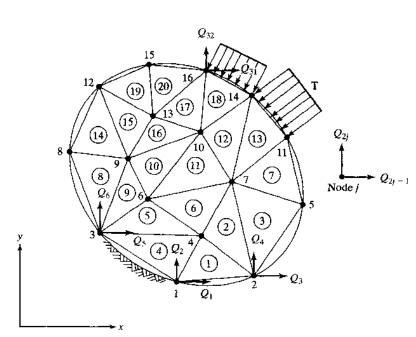


FIGURE 5.2 Finite element discretization.

## Element stiffness



$$\epsilon = Bq$$

$$U_{e} = \frac{1}{2} \int_{e} \mathbf{e}^{\mathrm{T}} \mathbf{D} \mathbf{e} t \, dA$$

$$= \frac{1}{2} \int_{e} \mathbf{q}^{\mathrm{T}} \mathbf{B}^{\mathrm{T}} \mathbf{D} \mathbf{B} \mathbf{q} t \, dA$$

$$U_{e} = \frac{1}{2} \mathbf{q}^{\mathrm{T}} \mathbf{B}^{\mathrm{T}} \mathbf{D} \mathbf{B} t_{e} \left( \int_{e} dA \right) \mathbf{q}$$

$$\int_{e} dA = A_{e} \qquad U_{e} = \frac{1}{2} \mathbf{q}^{\mathsf{T}} t_{e} A_{e} \mathbf{B}^{\mathsf{T}} \mathbf{D} \mathbf{B} \mathbf{q}$$

$$U_e = \frac{1}{2} \mathbf{q}^{\mathsf{T}} \mathbf{k}^e \mathbf{q} \qquad \mathbf{k}^e = t_e A_e \mathbf{B}^{\mathsf{T}} \mathbf{D} \mathbf{B}$$

$$U = \sum_{e} \frac{1}{2} \mathbf{q}^{\Gamma} \mathbf{k}^{e} \mathbf{q}$$
$$= \frac{1}{2} \mathbf{Q}^{T} \mathbf{K} \mathbf{Q}$$

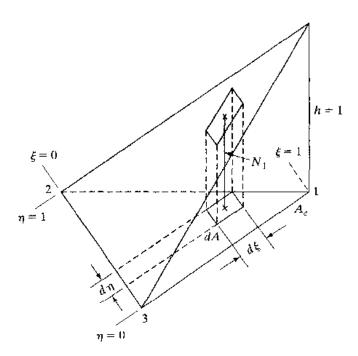
$$m_e = \max(|i_1 - i_2|, |i_2 - i_3|, |i_3 - i_1|)$$
  $NBW = 2\left(\max_{1 \le e \le NE}(m_e) + 1\right)$ 

#### Force terms

$$u = N_1 q_1 + N_2 q_3 + N_3 q_5$$
  
$$v = N_1 q_2 + N_2 q_4 + N_3 q_6$$



$$\int_{e} \mathbf{u}^{\mathrm{T}} \mathbf{f} t \, dA = t_{e} \int_{e} \left( u f_{x} + v f_{y} \right) dA$$



$$\int_{c} N_{1} dA = \frac{1}{3} \cdot A_{c} h = \frac{1}{3} \cdot A_{c}$$
or 
$$\int_{c} N_{1} dA = \int_{0}^{1} \int_{0}^{1-\xi} N_{1} \det J d\eta d\xi = 2A_{c} \int_{0}^{1} \int_{0}^{1-\xi} \xi d\eta d\xi = \frac{1}{3} \cdot A_{c}$$

$$\int_{e} \mathbf{u}^{\mathsf{T}} \mathbf{f} t \, dA = q_{1} \left( t_{e} f_{x} \int_{e} N_{1} dA \right) + q_{2} \left( t_{e} f_{y} \int_{e} N_{1} \, dA \right)$$

$$+ q_{3} \left( t_{e} f_{x} \int_{e} N_{2} \, dA \right) + q_{4} \left( t_{e} f_{y} \int_{e} N_{2} \, dA \right)$$

$$+ q_{5} \left( t_{e} f_{x} \int_{e} N_{3} \, dA \right) + q_{6} \left( t_{e} f_{y} \int_{e} N_{3} \, dA \right)$$

$$\int_{e} N_{i} \, dA = \frac{1}{3} A_{e} \quad \int_{e} N_{2} \, dA = \int_{e} N_{3} \, dA = \frac{1}{3} A_{e}$$

$$\int_{e} \mathbf{u}^{\mathsf{T}} \mathbf{f} t \, dA = \mathbf{q}^{\mathsf{T}} \mathbf{f}^{e}$$

$$\mathbf{f}^{e} = \frac{t_{e} A_{e}}{3} [f_{x}, f_{y}, f_{x}, f_{y}, f_{x}, f_{y}]^{\mathsf{T}}$$

$$\mathbf{F} \longleftarrow \sum \mathbf{f}^{e}$$



$$\int_{L} \mathbf{u}^{\mathsf{T}} \mathbf{T} t d\ell = \int_{\ell_{1-2}} (u T_x + v T_y) t \, d\ell$$

Using the interpolation relations involving the shape functions

$$u = N_1 q_1 + N_2 q_3$$

$$v = N_1 q_2 + N_2 q_4$$

$$T_v = N_1 T_{x1} + N_2 T_{x2}$$

$$T_v = N_1 T_{v1} + N_2 T_{v2}$$

and noting that

$$\int_{\ell_{1-2}} N_1^2 d\ell = \frac{1}{3} \ell_{1-2}, \qquad \int_{\ell_{1-2}} N_2^2 d\ell = \frac{1}{3} \ell_{1-2}, \qquad \int_{\ell_{1-2}} N_1 N_2 d\ell = \frac{1}{6} \ell_{1-2}$$

$$\ell_{1-2} = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

we get

$$\int_{\ell_1} \mathbf{u}^{\mathrm{T}} \mathbf{T} t \, d\ell = [q_1, q_2, q_3, q_4] \mathbf{T}^e$$

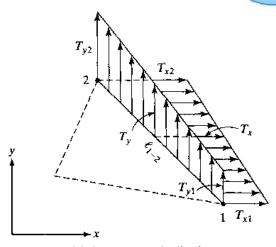
where  $T^e$  is given by

$$\mathbf{T}^{e} = \frac{t_{e}\ell_{1-2}}{6} [2T_{x1} + T_{x2}, 2T_{y1} + T_{y2}, T_{x1} + 2T_{x2}, T_{y1} + 2T_{y2}]^{T}$$

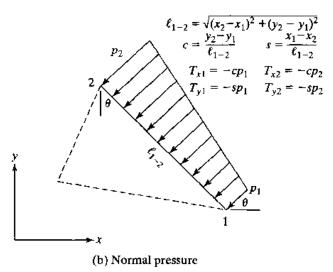
$$T_{x1} = -cp_{1}, \qquad T_{x2} = -cp_{2}, \qquad T_{y1} = -sp_{3}, \qquad T_{y2} = -sp_{2}$$

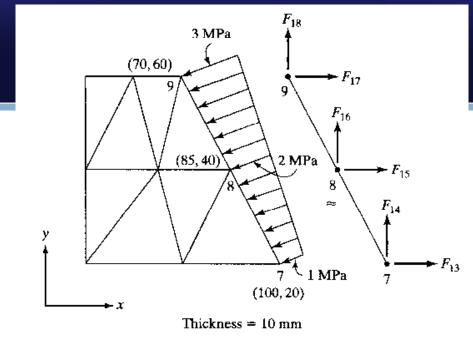
where

$$s = \frac{(x_1 - x_2)}{\ell_{1-2}}$$
 and  $c = \frac{(y_2 - y_1)}{\ell_{1+2}}$ .



(a) Component distribution





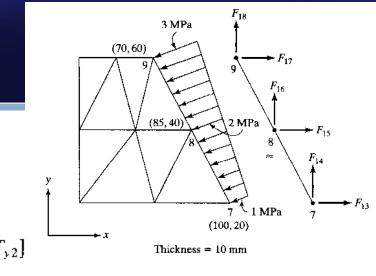
Solution We consider the two edges 7-8 and 8-9 separately and then merge them.

$$p_{1} = 1 \text{ MPa}, \quad p_{2} = 2 \text{ MPa}, \quad x_{1} = 100 \text{ mm}, \quad y_{1} = 20 \text{ mm}, \quad x_{2} = 85 \text{ mm}, \quad y_{2} = 40 \text{ mm},$$

$$\ell_{1-2} = \sqrt{(x_{1} - x_{2})^{2} + (y_{1} - y_{2})^{2}} = 25 \text{ mm}$$

$$c = \frac{y_{2} - y_{1}}{\ell_{1-2}} = 0.8, \quad s = \frac{x_{1} - x_{2}}{\ell_{1-2}} = 0.6$$

$$T_{x1} = -p_{1}c = -0.8, \quad T_{y1} = -p_{1}s = -0.6, \quad T_{z2} = -p_{2}c = -1.6,$$



$$T_{y1} = -p_2 s = -1.2$$

$$\mathbf{T}^{1} = \frac{10 \times 25}{6} [2T_{x1} + T_{x2}, 2T_{y1} + T_{y2}, T_{x1} + 2T_{x2}, T_{y1} + 2T_{y2}]$$

$$= [-133.3, -100, -166.7, -125]^{T} N$$

These loads add to  $F_{13}$ ,  $F_{14}$ ,  $F_{15}$ , and  $F_{16}$ , respectively.

$$p_{1} = 2 \text{ MPa}, \quad p_{2} = 3 \text{ MPa}, \quad x_{1} = 85 \text{ mm}, \quad y_{1} = 40 \text{ mm}, \quad x_{2} = 70 \text{ mm}, \quad y_{2} = 60 \text{ mm},$$

$$\ell_{1-2} = \sqrt{(x_{1} - x_{2})^{2} + (y_{1} - y_{2})^{2}} = 25 \text{ mm}$$

$$c = \frac{y_{2} - y_{1}}{\ell_{1-2}} = 0.8, \quad s = \frac{x_{1} - x_{2}}{\ell_{1-2}} = 0.6$$

$$T_{x1} = -p_{1}c = -1.6, \quad T_{y1} = -p_{1}s = -1.2, \quad T_{x2} = -p_{2}c = -2.4,$$

$$T_{v2} = -p_{2}s = -1.8$$

$$\mathbf{T}^{2} = \frac{10 \times 25}{6} [2T_{x1} + T_{x2}, 2T_{y1} + T_{y2}, T_{x1} + 2T_{x2}, T_{v1} + 2T_{y2}]^{T}$$

These loads add to  $F_{15}$ ,  $F_{16}$ ,  $F_{17}$ , and  $F_{18}$ , respectively. Thus,

 $= [-233.3, -175, -266.7, -200]^{\mathsf{T}} \mathsf{N}$ 

$$[F_{13} ext{ } F_{14} ext{ } F_{15} ext{ } F_{16} ext{ } F_{17} ext{ } F_{18}] = [-133.3 ext{ } -100 ext{ } -400 ext{ } -300 ext{ } -266.7 ext{ } -200] ext{ N}$$

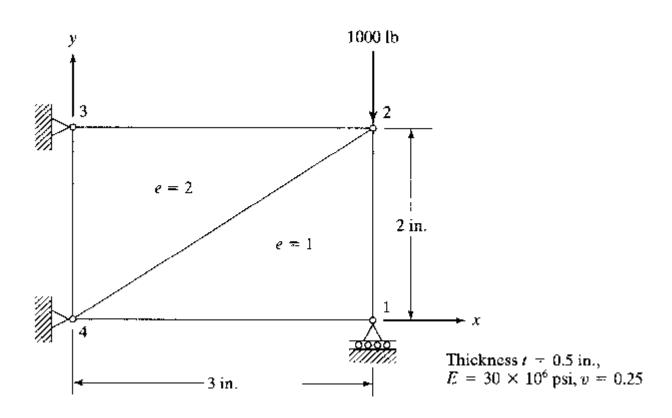


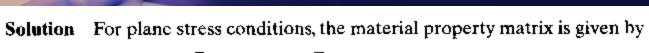
$$\mathbf{u}_{i}^{\mathbf{i}} \mathbf{P}_{i} = Q_{2i-1} P_{x} + Q_{2i} P_{y}$$

$$\Pi = \frac{1}{2} \mathbf{Q}^{\mathrm{T}} \mathbf{K} \mathbf{Q} - \mathbf{Q}^{\mathrm{T}} \mathbf{F}$$

$$\mathbf{K} \mathbf{Q} = \mathbf{F}$$









$$\mathbf{D} = \frac{E}{1 - \nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1 - \nu}{2} \end{bmatrix} = \begin{bmatrix} 3.2 \times 10^7 & 0.8 \times 10^7 & 0 \\ 0.8 \times 10^7 & 3.2 \times 10^7 & 0 \\ 0 & 0 & 1.2 \times 10^7 \end{bmatrix}$$

Using the local numbering pattern used in Fig. E5.3, we establish the connectivity as follows:

	Nodes		
Element No.	1	2	3
1	1	2	4
2	3	4	2

On performing the matrix multiplication **DB**<sup>e</sup>, we get

$$\mathbf{DB}^{1} = 10^{7} \begin{bmatrix} 1.067 & -0.4 & 0 & 0.4 & -1.067 & 0 \\ 0.267 & -1.6 & 0 & 1.6 & -0.267 & 0 \\ -0.6 & 0.4 & 0.6 & 0 & 0 & -0.4 \end{bmatrix}$$

and

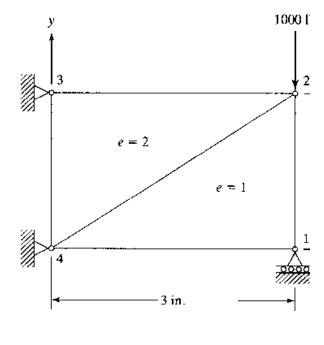
$$\mathbf{DB}^2 = 10^7 \begin{bmatrix} -1.067 & 0.4 & 0 & -0.4 & 1.067 & 0 \\ -0.267 & 1.6 & 0 & -1.6 & 0.267 & 0 \\ 0.6 & -0.4 & -0.6 & 0 & 0 & 0.4 \end{bmatrix}$$



These two relationships will be used later in calculating stresses using  $\sigma^e = \mathbf{D}\mathbf{B}^e\mathbf{q}$ . The multiplication  $t_e A_e \mathbf{B}^{e^T} \mathbf{D}\mathbf{B}^e$  gives the element stiffness matrices,

$$\mathbf{k}^1 = 10^7 \begin{bmatrix} 1 & 2 & 3 & 4 & 7 & 8 \leftarrow & Global \ 0.983 & -0.5 & -0.45 & 0.2 & -0.533 & 0.3 \ 1.4 & 0.3 & -1.2 & 0.2 & -0.2 \ 0.45 & 0 & 0 & -0.3 \ 1.2 & -0.2 & 0 \ 0.533 & 0 \ 0.2 \end{bmatrix}$$

$$\mathbf{k}^1 = 10^7 \begin{bmatrix} 5 & 6 & 7 & 8 & 3 & 4 \leftarrow & Global \ 0.983 & -0.5 & -0.45 & 0.2 & -0.533 & 0.3 \ 1.4 & 0.3 & -1.2 & 0.2 & -0.2 \ 0.45 & 0 & 0 & -0.3 \ 1.2 & -0.2 & 0 \ Symmetric & 0.533 & 0 \ 0.2 \end{bmatrix}$$
Symmetric Symmetric 0.533 0



In the previous element matrices, the global dof association is shown on top. In the problem under consideration,  $Q_2$ ,  $Q_5$ ,  $Q_6$ ,  $Q_7$ , and  $Q_8$ , are all zero. Using the elimination approach discussed in Chapter 3, it is now sufficient to consider the stiffnesses associated with



the degrees of freedom  $Q_1$ ,  $Q_3$ , and  $Q_4$ . Since the body forces are neglected, the first vector has the component  $F_4 = -1000$  lb. The set of equations is given by the matrix representation

$$10^{7} \begin{bmatrix} 0.983 & -0.45 & 0.2 \\ -0.45 & 0.983 & 0 \\ 0.2 & 0 & 1.4 \end{bmatrix} \begin{Bmatrix} Q_1 \\ Q_3 \\ Q_4 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \\ -1000 \end{Bmatrix}$$

Solving for  $Q_1, Q_3$ , and  $Q_4$ , we get

$$Q_1 = 1.913 \times 10^{-5} \,\text{in}.$$
  $Q_3 = 0.875 \times 10^{-5} \,\text{in}.$   $Q_4 = -7.436 \times 10^{-5} \,\text{in}.$ 

For element 1, the element nodal displacement vector is given by

$$\mathbf{q}^1 = 10^{-5}[1.913, 0, 0.875, -7.436, 0, 0]^T$$

The element stresses  $\sigma^1$  are calculated from  $DB^1q$  as

$$\sigma^{\dagger} = [-93.3, -1138.7, -62.3]^{\mathrm{T}} \mathrm{psi}$$

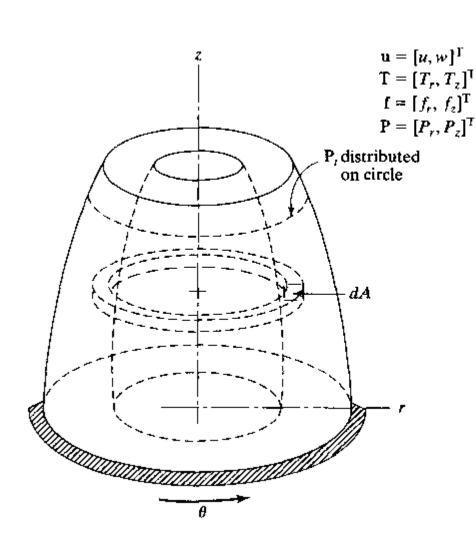
Similarly,

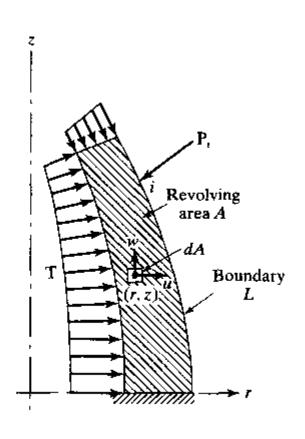
$$\mathbf{q}^2 = 10^{-5}[0, 0, 0, 0, 0.875, -7.436]^T$$
  
 $\mathbf{\sigma}^2 = [93.4, 23.4, -297.4]^T \text{ psi}$ 

The computer results may differ slightly since the penalty approach for handling boundary conditions is used in the computer program.

# Axisymmetric solids subjected to axisymmetric loading









$$\Pi = \frac{1}{2} \int_0^{2\pi} \int_A \boldsymbol{\sigma}^{\mathrm{T}} \boldsymbol{\epsilon} r \, dA \, d\theta - \int_0^{2\pi} \int_A \mathbf{u}^{\mathrm{T}} \mathbf{f} r \, dA \, d\theta - \int_0^{2\pi} \int_L \mathbf{u}^{\mathrm{T}} \mathbf{T} r \, d\ell \, d\theta - \sum_i \mathbf{u}_i^{\mathrm{T}} \mathbf{P}_i$$

$$\Pi = 2\pi \left(\frac{1}{2} \int_{A} \boldsymbol{\sigma}^{\mathrm{T}} \boldsymbol{\epsilon} r \, dA - \int_{A} \mathbf{u}^{\mathrm{T}} \mathbf{f} r \, dA - \int_{L} \mathbf{u}^{\mathrm{T}} \mathbf{T} r \, d\ell\right) - \sum_{i} \mathbf{u}_{i}^{\mathrm{T}} \mathbf{P}_{i}$$

$$\mathbf{u} = [u, w]^{\mathrm{T}}$$

$$\mathbf{f} = [f_r, f_r]^{\mathrm{T}}$$

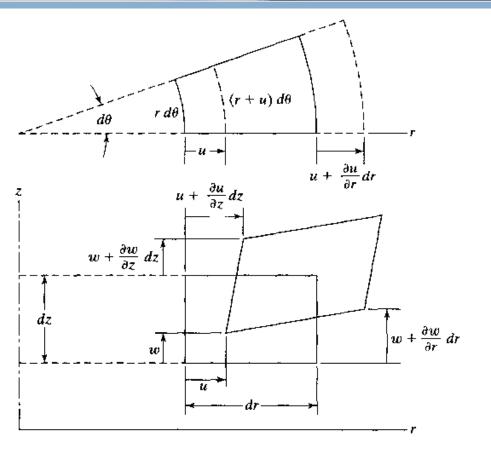
$$\mathbf{T} = [T_r, T_r]^{\mathrm{T}}$$

$$\boldsymbol{\sigma} = [\sigma_r, \sigma_z, \tau_{rz}, \sigma_\theta]^{\mathrm{T}}$$

$$\sigma = D\epsilon$$

$$\mathbf{D} = \frac{E(1-\nu)}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1 & \frac{\nu}{1-\nu} & 0 & \frac{\nu}{1-\nu} \\ \frac{\nu}{1-\nu} & 1 & 0 & \frac{\nu}{1-\nu} \\ 0 & 0 & \frac{1-2\nu}{2(1-\nu)} & 0 \\ \frac{\nu}{1-\nu} & \frac{\nu}{1-\nu} & 0 & 1 \end{bmatrix}$$





$$\boldsymbol{\epsilon} = [\boldsymbol{\epsilon}_r, \boldsymbol{\epsilon}_z, \boldsymbol{\gamma}_{rz}, \boldsymbol{\epsilon}_{\theta}]^{\mathrm{T}}$$

$$= \left[\frac{\partial u}{\partial r}, \frac{\partial w}{\partial z}, \frac{\partial u}{\partial z} + \frac{\partial w}{\partial r}, \frac{u}{r}\right]^{\mathrm{T}}$$

$$\mathbf{\Phi} = [\boldsymbol{\phi}_r, \boldsymbol{\phi}_z]^{\mathsf{T}}$$

$$\boldsymbol{\epsilon}(\mathbf{\Phi}) = \left[\frac{\partial \boldsymbol{\phi}_r}{\partial r}, \frac{\partial \boldsymbol{\phi}_z}{\partial z}, \frac{\partial \boldsymbol{\phi}_r}{\partial z} + \frac{\partial \boldsymbol{\phi}_z}{\partial r}, \frac{\boldsymbol{\phi}_r}{r}\right]^{\mathsf{T}}$$

$$2\pi \int_{A} \boldsymbol{\sigma}^{\mathrm{T}} \boldsymbol{\epsilon}(\boldsymbol{\phi}) r \, dA - \left(2\pi \int_{A} \boldsymbol{\phi}^{\mathrm{T}} \mathbf{f} r \, dA + 2\pi \int_{L} \boldsymbol{\phi}^{\mathrm{T}} \mathbf{T} r \, d\ell + \sum \boldsymbol{\phi}_{i}^{\mathrm{T}} \mathbf{P}_{i}\right) = 0$$

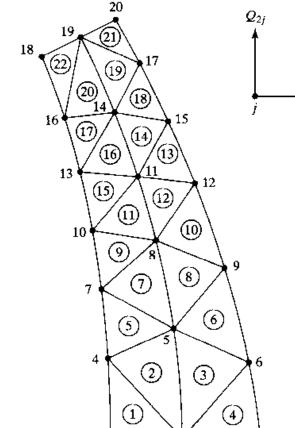


$$u = Nq$$

$$\mathbf{N} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 \end{bmatrix}$$

$$\mathbf{q} = [q_1, q_2, q_3, q_4, q_5, q_6]^T$$
  $z = \xi z_1 + \eta z_2 + (1 - \xi - \eta) z_3$ 

 $\leftarrow Q_{2j-1}$ 



$$\mathbf{u} = \mathbf{N}\mathbf{q}$$

$$\mathbf{n} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 \end{bmatrix} \quad \mathbf{u} = \xi q_1 + \eta q_3 + (1 - \xi - \eta)q_5$$

$$\mathbf{n} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 \end{bmatrix} \quad \mathbf{u} = \xi q_2 + \eta q_4 + (1 - \xi - \eta)q_6$$

$$\mathbf{r} = \xi r_1 + \eta r_2 + (1 - \xi - \eta)r_3$$

$$\mathbf{r} = \xi r_1 + \eta r_2 + (1 - \xi - \eta)r_3$$

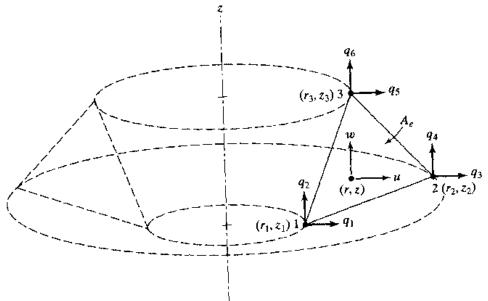
$$\mathbf{r} = \xi r_1 + \eta r_2 + (1 - \xi - \eta)r_3$$

$$\mathbf{J} = \begin{bmatrix} r_{13} & z_{13} \\ r_{23} & z_{23} \end{bmatrix}$$

$$\left\{ \frac{\partial u}{\partial \xi} \right\} = \mathbf{J} \left\{ \frac{\partial u}{\partial r} \right\} \\
 \left\{ \frac{\partial u}{\partial \eta} \right\} = \mathbf{J} \left\{ \frac{\partial u}{\partial z} \right\}$$

$$\left\{ \begin{array}{l}
 \frac{\partial w}{\partial \xi} \\
 \frac{\partial w}{\partial \eta}
 \end{array} \right\} = \mathbf{J} \left\{ \begin{array}{l}
 \frac{\partial w}{\partial r} \\
 \frac{\partial w}{\partial z}
 \end{array} \right\}$$

$$\det \mathbf{J} = r_{13} z_{23} - r_{23} z_{13}$$





$$\epsilon = \begin{cases}
\frac{z_{23}(q_1 - q_5) - z_{13}(q_3 - q_5)}{\det \mathbf{J}} \\
\frac{-r_{23}(q_2 - q_6) + r_{13}(q_4 - q_6)}{\det \mathbf{J}} \\
\frac{-r_{23}(q_1 - q_5) + r_{13}(q_3 - q_5) + z_{23}(q_2 - q_6) - z_{13}(q_4 - q_6)}{\det \mathbf{J}} \\
\frac{N_1q_1 + N_2q_3 + N_3q_5}{r}
\end{cases}$$

$$\epsilon = Bq$$

$$\mathbf{B} = \begin{bmatrix} \frac{z_{23}}{\det \mathbf{J}} & 0 & \frac{z_{31}}{\det \mathbf{J}} & 0 & \frac{z_{12}}{\det \mathbf{J}} & 0 \\ 0 & \frac{r_{32}}{\det \mathbf{J}} & 0 & \frac{r_{13}}{\det \mathbf{J}} & 0 & \frac{r_{21}}{\det \mathbf{J}} \\ \frac{r_{32}}{\det \mathbf{J}} & \frac{z_{23}}{\det \mathbf{J}} & \frac{r_{13}}{\det \mathbf{J}} & \frac{z_{31}}{\det \mathbf{J}} & \frac{r_{21}}{\det \mathbf{J}} & \frac{z_{12}}{\det \mathbf{J}} \\ \frac{N_1}{r} & 0 & \frac{N_2}{r} & 0 & \frac{N_3}{r} & 0 \end{bmatrix}$$



$$\Pi = \sum_{e} \left[ \frac{1}{2} \left( 2\pi \int_{e} \mathbf{e}^{T} \mathbf{D} \mathbf{e} r \, dA \right) - 2\pi \int_{e} \mathbf{u}^{T} \mathbf{f} r \, dA - 2\pi \int_{e} \mathbf{u}^{T} \mathbf{T} r \, d\ell \right]$$
$$- \sum_{e} \mathbf{u}_{i}^{T} \mathbf{P}_{i}$$

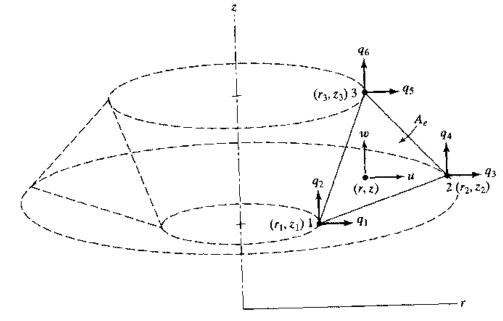
$$U_e = \frac{1}{2} \mathbf{q}^{\mathrm{T}} \left( 2\pi \int_e \mathbf{B}^{\mathrm{T}} \mathbf{D} \mathbf{B} r \, dA \right) \mathbf{q} \qquad \mathbf{k}^e = 2\pi \int_e \mathbf{B}^{\mathrm{T}} \mathbf{D} \mathbf{B} r \, dA$$

$$N_1 = N_2 = N_3 = \frac{1}{3}$$
  $\bar{r} = \frac{r_1 + r_2 + r_3}{3}$ 

$$\mathbf{k}^{e} = 2\pi \bar{r} \, \overline{\mathbf{B}}^{\mathrm{T}} \mathbf{D} \overline{\mathbf{B}} \, \int_{e} dA$$

$$\mathbf{k}^e = 2\pi \bar{r} A_e \mathbf{\bar{B}}^{\mathrm{T}} \mathbf{D} \mathbf{\bar{B}}$$

$$A_e = \frac{1}{2} |\det \mathbf{J}|$$





$$2\pi \int_{e} \mathbf{u}^{\mathrm{T}} \mathbf{f} r \, dA = 2\pi \int_{e} (u f_{r} + w f_{z}) r \, dA$$

$$= 2\pi \int_{e} \left[ (N_{1}q_{1} + N_{2}q_{3} + N_{3}q_{5}) f_{r} + (N_{1}q_{2} + N_{2}q_{4} + N_{3}q_{6}) f_{z} \right] r \, dA$$

$$2\pi \int_{e} \mathbf{u}^{\mathrm{T}} \mathbf{f} r \, dA = \mathbf{q}^{\mathrm{T}} \mathbf{f}^{e}$$

 $\mathbf{f}^e = \frac{2\pi \bar{r} A_e}{3} [\bar{f}_r, \bar{f}_z, \bar{f}_r, \bar{f}_z, \bar{f}_r, \bar{f}_z]^{\mathrm{T}}$ 

## Rotating flywheel



$$\mathbf{f} = [f_r, f_z]^{\mathrm{T}} = [\rho r \omega^2, -\rho g]^{\mathrm{T}}$$

$$\bar{f}_r = \rho \bar{r} \omega^2, \bar{f}_z = -\rho g$$

$$r = N_1 r_1 + N_2 r_2 + N_3 r_3$$

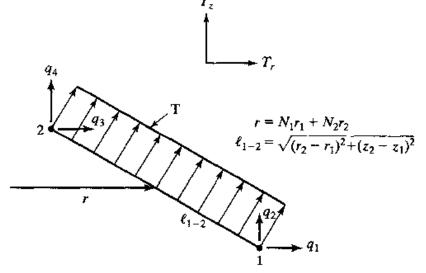
$$2\pi \int_{e} \mathbf{u}^{\mathrm{T}} \mathbf{T} r \, d\ell = \mathbf{q}^{\mathrm{T}} \mathbf{T}^{e}$$

$$\mathbf{q} = [q_1, q_2, q_3, q_4]^{\mathsf{T}}$$

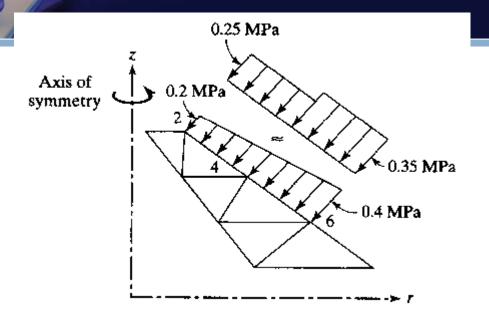
$$\mathbf{T}^e = 2\pi \ell_{1-2} [aT_r, aT_\tau, bT_r, bT_z]^{\mathsf{T}}$$

$$a = \frac{2r_1 + r_2}{6} \quad b = \frac{r_1 + 2r_2}{6}$$

$$\ell_{1-2} = \sqrt{(r_2 - r_1)^2 + (z_2 - z_1)^2}$$







#### For edge 6-4

$$p = 0.35 \,\text{MPa}, \quad r_1 = 60 \,\text{mm}, \quad z_1 = 40 \,\text{mm}, \quad r_2 = 40 \,\text{mm}, \quad z_2 = 55 \,\text{mm}$$

$$\ell_{1-2} = \sqrt{(r_1 - r_2)^2 + (z_1 - z_2)^2} = 25 \,\text{mm}$$

$$c = \frac{z_2 - z_1}{\ell_{1-2}} = 0.6, \qquad s = \frac{r_1 - r_2}{\ell_{1-2}} = 0.8$$

$$T_r = -pc = -0.21, \qquad T_z = -ps = -0.28$$

$$a = \frac{2r_1 + r_2}{6} = 26.67, \qquad b = \frac{r_1 + 2r_2}{6} = 23.33$$

$$\mathbf{T}^1 = 2\pi\ell_{1-2}[aT_r \quad aT_z \quad bT_r \quad bT_z]^T$$

$$= [-879.65 \quad -1172.9 \quad -769.69 \quad -1026.25]^T \,\text{N}$$



These loads add to  $F_{11}$ ,  $F_{12}$ ,  $F_{7}$ , and  $F_{8}$ , respectively.

For edge 4-2

$$p = 0.25 \text{ MPa}, \quad r_1 = 40 \text{ mm}, \quad z_1 = 55 \text{ mm}, \quad r_2 = 20 \text{ mm}, \quad z_2 = 70 \text{ mm}$$

$$\ell_{1/2} = \sqrt{(r_1 - r_2)^2 + (z_1 - z_2)^2} = 25 \text{ mm}$$

$$c = \frac{z_2 - z_1}{\ell_{1-2}} = 0.6, \quad s = \frac{r_1 - r_2}{\ell_{1-2}} = 0.8$$

$$T_r = -pc = -0.15, \quad T_z = -ps = -0.2$$

$$a = \frac{2r_1 + r_2}{6} = 16.67, \quad b = \frac{r_1 + 2r_2}{6} = 13.33$$

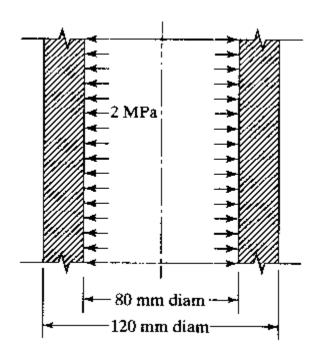
$$\mathbf{T}^1 = 2\pi\ell_{1-2}[aT_r \quad aT_z \quad bT_r \quad bT_z]^T$$

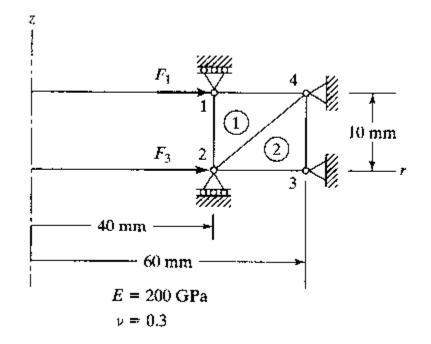
$$= [-392.7 \quad -523.6 \quad -314.16 \quad -418.88]^T \quad \mathbf{N}$$

These loads add to  $F_7$ ,  $F_8$ ,  $F_3$ , and  $F_4$ , respectively. Thus,

$$[F_3 \quad F_4 \quad F_7 \quad F_8 \quad F_{11} \quad F_{12}] = [-314.2 \quad -418.9 \quad -1162.4 \quad -1696.5 \quad -879.7 \quad -1172.9] \quad \mathbf{N}$$







		Connectivity		
Element	1	2	3	
1	1	2	4	
2	2	3	4	

	Coord	Coordinates		
Node	r	z		
1	40	10		
2	40	0		
3	60	0		
4	60	10		



$$\mathbf{D} = \begin{bmatrix} 2.69 \times 10^5 & 1.15 \times 10^5 & 0 & 1.15 \times 10^5 \\ 1.15 \times 10^5 & 2.69 \times 10^5 & 0 & 1.15 \times 10^5 \\ 0 & 0 & 0.77 \times 10^5 & 0 \\ 1.15 \times 10^5 & 1.15 \times 10^5 & 0 & 2.69 \times 10^5 \end{bmatrix}$$

$$F_1 = F_3 = \frac{2\pi r_1 \ell_e p_i}{2} = \frac{2\pi (40)(10)(2)}{2} = 2514 \text{ N}$$

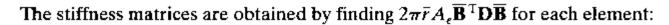
$$\overline{\mathbf{B}}^{1} = \begin{bmatrix} -0.05 & 0 & 0 & 0.05 & 0 \\ 0 & 0.1 & 0 & -0.1 & 0 & 0 \\ 0.1 & -0.05 & -0.1 & 0 & 0 & 0.05 \\ 0.0071 & 0 & 0.0071 & 0 & 0.0071 & 0 \end{bmatrix}$$

$$\overline{\mathbf{B}}^{2} = \begin{bmatrix} -0.05 & 0 & 0.05 & 0 & 0 & 0 \\ 0 & 0 & 0 & -0.1 & 0 & 0.1 \\ 0 & -0.05 & -0.1 & 0.05 & 0.1 & 0 \\ 0.00625 & 0 & 0.00625 & 0 & 0.00625 & 0 \end{bmatrix}$$



$$\mathbf{D}\overline{\mathbf{B}}^{1} = 10^{4} \begin{bmatrix} -1.26 & 1.15 & 0.082 & -1.15 & 1.43 & 0 \\ -0.49 & 2.69 & 0.082 & -2.69 & 0.657 & 0.1 \\ 0.77 & -0.385 & -0.77 & 0 & 0 & 0.385 \\ -0.384 & 1.15 & 0.191 & -1.15 & 0.766 & 0 \end{bmatrix}$$

$$\mathbf{D}\overline{\mathbf{B}}^{2} = 10^{4} \begin{bmatrix} -1.27 & 0 & 1.42 & -1.15 & 0.072 & 1.15 \\ -0.503 & 0 & 0.647 & -2.69 & 0.072 & 2.69 \\ 0 & -0.385 & -0.77 & 0.385 & 0.77 & 0 \\ -0.407 & 0 & 0.743 & -1.15 & 0.168 & 1.15 \end{bmatrix}.$$





Global dof 
$$\rightarrow$$
 1 2 3 4 7 8  
 $\mathbf{k}^1 = 10^7 \begin{bmatrix} 4.03 & -2.58 & -2.34 & 1.45 & -1.932 & 1.13 \\ 8.45 & 1.37 & -7.89 & 1.93 & -0.565 \\ 2.30 & -0.24 & 0.16 & -1.13 \\ 7.89 & -1.93 & 0 \\ Symmetric & 2.25 & 0 \\ 0.565 \end{bmatrix}$ 

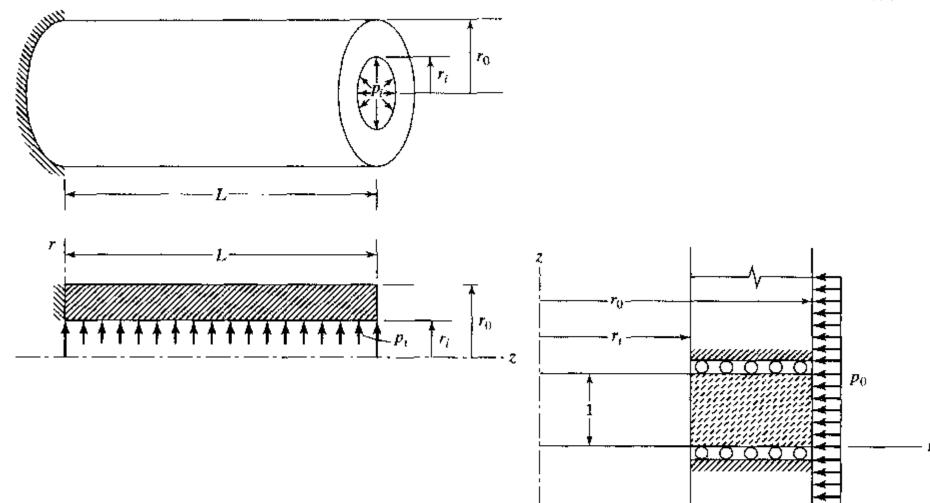
Using the elimination approach, on assembling the matrices with reference to the degrees of freedom 1 and 3, we get

$$10^7 = \begin{bmatrix} 4.03 & -2.34 \\ -2.34 & 4.35 \end{bmatrix} \begin{Bmatrix} Q_1 \\ Q_3 \end{Bmatrix} = \begin{Bmatrix} 2514 \\ 2514 \end{Bmatrix}$$

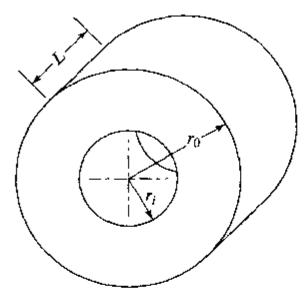
so that

$$Q_1 = 0.014 \times 10^{-2} \,\mathrm{mm}$$
  
 $Q_3 = 0.0133 \times 10^{-2} \,\mathrm{mm}$ 





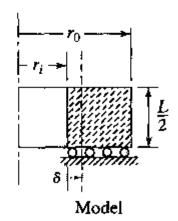




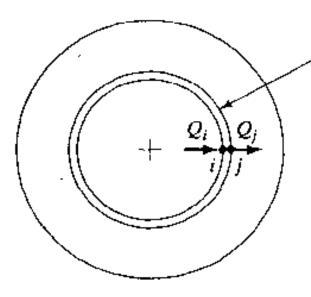
 $r_i + \delta$ 

Ring of length L

Rigid shaft



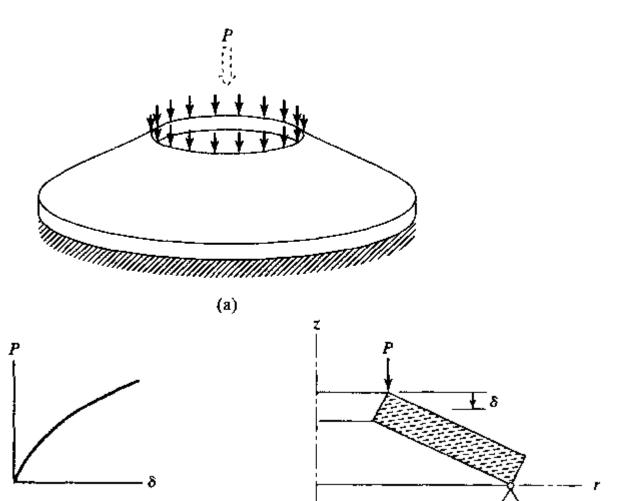




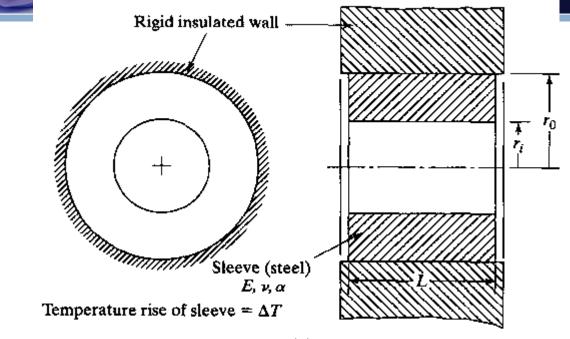
Boundaries of shaft and sleeve are shown separated for clarity

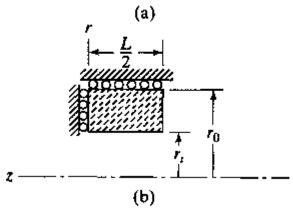
$$Q_j - Q_t = \delta$$











## Isoparametric elements



$$N_1 = 1$$
 at node 1  
= 0 at nodes 2, 3, and 4

$$N_1 = c(1-\xi)(1-\eta)$$
  $1 = c(2)(2)$   $N_1 = \frac{1}{4}(1-\xi)(1-\eta)$ 

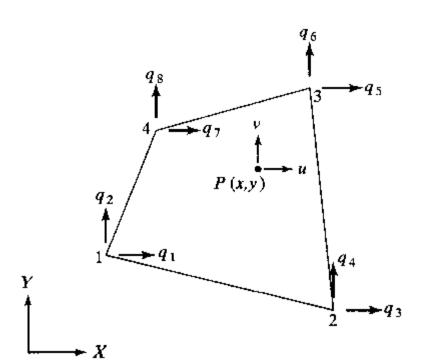
$$N_{1} = \frac{1}{4}(1 - \xi)(1 - \eta)$$

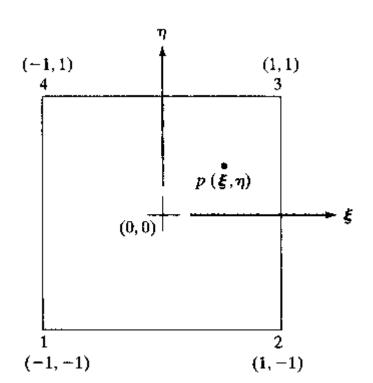
$$N_{2} = \frac{1}{4}(1 + \xi)(1 - \eta)$$

$$N_{3} = \frac{1}{4}(1 + \xi)(1 + \eta)$$

$$N_{4} = \frac{1}{4}(1 - \xi)(1 + \eta)$$

$$N_{4} = \frac{1}{4}(1 - \xi)(1 + \eta)$$







$$u = N_1 q_1 + N_2 q_3 + N_3 q_5 + N_4 q_7$$

$$v = N_1 q_2 + N_2 q_4 + N_3 q_6 + N_4 q_8$$

$$x = N_1 x_1 + N_2 x_2 + N_3 x_3 + N_4 x_4$$

$$y = N_1 y_1 + N_2 y_2 + N_3 y_3 + N_4 y_4$$

$$f = f[x(\xi, \eta), y(\xi, \eta)].$$

$$\frac{\partial f}{\partial \xi} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \xi} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \xi}$$

$$\frac{\partial f}{\partial \eta} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \eta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \eta}$$

$$\begin{cases} \frac{\partial f}{\partial \xi} \\ \frac{\partial f}{\partial \eta} \end{cases} = \mathbf{J} \begin{cases} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{cases}$$

$$\mathbf{J} = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix}$$

$$\begin{cases} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{cases} = \mathbf{J}^{-1} \begin{cases} \frac{\partial f}{\partial \xi} \\ \frac{\partial f}{\partial \eta} \end{cases}$$

$$\left\{ \begin{array}{l}
 \frac{\partial f}{\partial \xi} \\
 \frac{\partial f}{\partial \eta}
 \end{array} \right\} = \mathbf{J} \begin{cases}
 \frac{\partial f}{\partial x} \\
 \frac{\partial f}{\partial y}
 \end{cases}$$

$$u = Nq$$

$$\mathbf{N} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 & N_4 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 & 0 & N_4 \end{bmatrix}$$

$$\mathbf{J} = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix}$$

$$\mathbf{J} = \frac{1}{4} \begin{bmatrix} -(1-\eta)x_1 + (1-\eta)x_2 + (1+\eta)x_3 - (1+\eta)x_4 \\ -(1-\xi)x_1 - (1+\xi)x_2 + (1+\xi)x_3 + (1-\xi)x_4 \end{bmatrix} - (1-\eta)y_1 + (1-\eta)y_2 + (1+\eta)y_3 - (1+\eta)y_4 \\ -(1-\xi)y_1 - (1+\xi)y_2 + (1+\xi)y_3 + (1-\xi)y_4 \end{bmatrix}$$

# 🧱 dx dy = det J dξ dη 🚪



$$\mathbf{T}_{1} = \frac{\partial x}{\partial u_{1}} \mathbf{i} + \frac{\partial y}{\partial u_{1}} \mathbf{j} \qquad \mathbf{T}_{2} = \frac{\partial x}{\partial u_{2}} \mathbf{i} + \frac{\partial y}{\partial u_{2}} \mathbf{j} \qquad \mathbf{T}_{1} = \frac{\partial \mathbf{r}}{\partial u_{1}} \qquad \mathbf{T}_{2} = \frac{\partial \mathbf{r}}{\partial u_{2}} \qquad \mathbf{J}_{2} =$$

 $= \left(\frac{\partial x}{\partial u_1}\frac{\partial y}{\partial u_2} - \frac{\partial x}{\partial u_2}\frac{\partial y}{\partial u_1}\right)du_1du_2\mathbf{k}$ 

 $dA = \det \mathbf{J} du_1 du_2$ 

44

 $dV = \det \mathbf{J} d\xi d\eta d\zeta$ 



$$U = \int_{V} \frac{1}{2} \boldsymbol{\sigma}^{\mathrm{T}} \boldsymbol{\epsilon} \, dV \qquad U = \sum_{e} t_{e} \int_{\varepsilon} \frac{1}{2} \boldsymbol{\sigma}^{\mathrm{T}} \boldsymbol{\epsilon} \, dA$$

$$\boldsymbol{\epsilon} = \left\{ \begin{array}{l} \boldsymbol{\epsilon}_{x} \\ \boldsymbol{\epsilon}_{v} \\ \boldsymbol{\gamma}_{xy} \end{array} \right\} = \left\{ \begin{array}{l} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial y} \\ \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \end{array} \right\} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} J_{22} & -J_{12} \\ -J_{21} & J_{11} \end{bmatrix} \begin{bmatrix} \frac{\partial u}{\partial \xi} \\ \frac{\partial u}{\partial \eta} \\ \frac{\partial v}{\partial \xi} \\ \frac{\partial v}{\partial y} \end{bmatrix} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} J_{22} & -J_{12} \\ -J_{21} & J_{11} \end{bmatrix} \begin{bmatrix} \frac{\partial v}{\partial \xi} \\ \frac{\partial v}{\partial \xi} \\ \frac{\partial v}{\partial \eta} \end{bmatrix}$$

$$\frac{\frac{\partial v}{\partial x}}{\frac{\partial v}{\partial y}} \right\} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} J_{22} & -J_{12} \\ -J_{21} & J_{11} \end{bmatrix} \begin{cases} \frac{\partial v}{\partial \xi} \\ \frac{\partial v}{\partial \eta} \end{cases}$$

$$\boldsymbol{\epsilon} = \mathbf{A} \begin{cases} \frac{\partial u}{\partial \eta} \\ \frac{\partial v}{\partial \xi} \\ \frac{\partial v}{\partial \eta} \end{cases}$$

$$\left| \begin{array}{c} \frac{\partial u}{\partial \eta} \\ \frac{\partial v}{\partial v} \end{array} \right| = 0$$

$$\begin{cases}
\frac{\partial u}{\partial \xi} \\
\frac{\partial u}{\partial \eta} \\
\frac{\partial v}{\partial \xi} \\
\frac{\partial v}{\partial \eta}
\end{cases} = \mathbf{G}\mathbf{q}$$

$$\mathbf{G} = \frac{1}{4} \begin{bmatrix}
-(1-\eta) & 0 & (1-\eta) & 0 & (1+\eta) & 0 & -(1+\eta) & 0 \\
0 & -(1-\xi) & 0 & -(1+\xi) & 0 & (1+\eta) & 0 & -(1+\eta) & 0 \\
0 & -(1-\xi) & 0 & -(1+\xi) & 0 & (1+\eta) & 0 & -(1+\eta) & 0 \\
0 & -(1-\xi) & 0 & -(1+\xi) & 0 & (1+\eta) & 0 & -(1+\eta) & 0
\end{bmatrix}$$

$$\mathbf{5}$$



$$\boldsymbol{\epsilon} = \mathbf{A} \begin{cases} \frac{\partial u}{\partial \xi} \\ \frac{\partial u}{\partial \eta} \\ \frac{\partial v}{\partial \xi} \\ \frac{\partial v}{\partial \eta} \end{cases}$$

$$\epsilon = \mathbf{A} \begin{cases} \frac{\partial u}{\partial \xi} \\ \frac{\partial u}{\partial \eta} \\ \frac{\partial v}{\partial \xi} \\ \frac{\partial v}{\partial \eta} \end{cases} = \mathbf{G} \mathbf{q} \qquad \epsilon = \mathbf{B} \mathbf{q} \qquad \mathbf{B} = \mathbf{A} \mathbf{G}$$

$$\sigma = \mathbf{D} \mathbf{B} \mathbf{q}$$

$$U = \sum_{e} t_{e} \int_{e} \frac{1}{2} \boldsymbol{\sigma}^{\mathrm{T}} \boldsymbol{\epsilon} \, dA$$

$$U = \sum_{e} \frac{1}{2} \mathbf{q}^{T} \left[ t_{e} \int_{-1}^{1} \int_{-1}^{1} \mathbf{B}^{T} \mathbf{D} \mathbf{B} \det \mathbf{J} \, d\xi \, d\eta \right] \mathbf{q}$$

$$= \sum_{e} \frac{1}{2} \mathbf{q}^{1} \mathbf{k}^{e} \mathbf{q}$$

$$\mathbf{k}^{e} = t_{e} \int_{-1}^{1} \int_{-1}^{1} \mathbf{B}^{T} \mathbf{D} \mathbf{B} \det \mathbf{J} \, d\xi \, d\eta$$



$$\int_{V} \mathbf{u}^{\mathsf{T}} \mathbf{f} \, dV \qquad \int_{V} \mathbf{u}^{\mathsf{T}} \mathbf{f} \, dV = \sum_{e} \mathbf{q}^{\mathsf{T}} \mathbf{f}^{e}$$

$$\mathbf{f}^e = t_e \left[ \int_{-1}^{1} \int_{-1}^{1} \mathbf{N}^{\mathrm{T}} \det \mathbf{J} \, d\xi \, d\eta \right] \begin{Bmatrix} f_{\mathrm{x}} \\ f_{\mathrm{y}} \end{Bmatrix}$$

$$\mathbf{T}^{e} = \frac{t_{e}\ell_{2-3}}{2}[0 \quad 0 \quad T_{x} \quad T_{y} \quad T_{x} \quad T_{v} \quad 0 \quad 0]^{T}$$

$$\mathbf{k}^e = t_e \int_{-1}^1 \int_{-1}^1 \mathbf{B}^T \mathbf{D} \mathbf{B} \det \mathbf{J} \, d\xi \, d\eta$$

$$\mathbf{f}^e = t_e \left[ \int_{-1}^{1} \int_{-1}^{1} \mathbf{N}^{\mathrm{T}} \det \mathbf{J} \, d\xi \, d\eta \right] \begin{Bmatrix} f_{\mathrm{x}} \\ f_{\mathrm{y}} \end{Bmatrix}$$



$$I = \int_{-1}^{1} f(\xi) d\xi$$

$$I = \int_{-1}^{1} f(\xi) d\xi \approx w_{1} f(\xi_{1}) + w_{2} f(\xi_{2}) + \dots + w_{n} f(\xi_{n})$$

$$J = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix}$$

$$\int_{-1}^{1} f(\xi) d\xi \approx w_1 f(\xi_1) \qquad f(\xi) = a_0 + a_1 \xi,$$

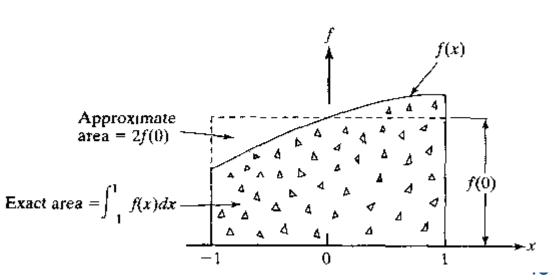
Error = 
$$\int_{-1}^{1} (a_0 + a_1 \xi) d\xi - w_1 f(\xi_1) = 0$$

Error = 
$$2a_0 - w_1(a_0 + a_1\xi_1) = 0$$

Error = 
$$a_0(2 - w_1) - w_1a_1\xi_1 =$$

$$w_1=2 \qquad \xi_1=0$$

$$I = \int_{-1}^{1} f(\xi) d\xi \approx 2f(0)$$





#### **Two-Point Formula.** Consider the formula with n = 2 as

 $w_1 \xi_1^3 + w_2 \xi_2^3 = 0$ 

$$\int_{-1}^{1} f(\xi) d\xi \approx w_1 f(\xi_1) + w_2 f(\xi_2) \qquad f(\xi) = a_0 + a_1 \xi + a_2 \xi^2 + a_3 \xi^3$$

$$\text{Error} = \left[ \int_{-1}^{1} (a_0 + a_1 \xi + a_2 \xi^2 + a_3 \xi^3) d\xi \right] - \left[ w_1 f(\xi_1) + w_2 f(\xi_2) \right]$$

$$w_{1} + w_{2} = 2$$

$$w_{1} = w_{2} = 1$$

$$w_{1} = w_{2} = 1$$

$$w_{1} = w_{2} = 1$$

$$-\xi_{1} = \xi_{2} = 1/\sqrt{3} = 0.5773502691...$$

$$w_{1} = w_{2} = 1$$

$$\int_{-1}^{1} f(\xi) d\xi \approx \sum_{i=1}^{n} w_{i} f(\xi_{i})$$

Number of points, n	Location, $\xi_r$	Weights, $w_i$	
1	0.0	2.0	
2	$\pm 1/\sqrt{3} = \pm 0.5773502692$	1.0	
3	±0.7745966692	0.555555555	
	0.0	0.888888889	
4	±0.8611363116	0.3478548451	
	±0.3399810436	0.6521451549	
5	±0.9061798459	0.2369268851	
	±0.5384693101	0.4786286705	
	0.0	0.5688888888	
6	±0.9324695142	0.1713244924	
	±0.6612093865	0.3607615730	
	±0.2386191861	0.4679139346	



#### Evaluate

$$I = \int_{-1}^{1} \left[ 3e^{x} + x^{2} + \frac{1}{(x+2)} \right] dx$$

using one-point and two-point Gauss quadrature.

**Solution** For n = 1, we have  $w_1 = 2$ ,  $x_1 = 0$ , and

$$I \approx 2f(0)$$
$$= 7.0$$

For n=2, we find  $w_1=w_2=1$ ,  $x_1=-0.57735\ldots$ ,  $x_2=+0.57735\ldots$ , and  $I\approx 8.7857$ . This may be compared with the exact solution

$$I_{\rm exact} = 8.8165$$



$$I = \int_{-1}^{1} \int_{-1}^{1} f(\xi, \eta) d\xi d\eta$$

$$I \approx \int_{-1}^{1} \left[ \sum_{i=1}^{n} w_{i} f(\xi_{i}, \eta) \right] d\eta$$
$$\approx \sum_{j=1}^{n} w_{j} \left[ \sum_{i=1}^{n} w_{i} f(\xi_{i}, \eta_{j}) \right]$$

$$I \approx \sum_{i=1}^{n} \sum_{j=1}^{n} w_i w_j f(\xi_i, \eta_j)$$

$$m_{2} = \frac{1}{\sqrt{3}}$$

$$= -\frac{1}{\sqrt{3}}$$

$$\xi_{1} = -\frac{1}{\sqrt{3}}$$

$$\xi_{2} = \frac{1}{\sqrt{3}}$$

 $\int_{-1}^{1} \int_{-1}^{1} f(\xi, \eta) \, d\xi d\eta \approx w_1^2 f(\xi_1, \eta_1) + w_2 w_1 f(\xi_2, \eta_1) + w_2^2 f(\xi_2, \eta_2) + w_1 w_2 f(\xi_1, \eta_2)$ 

$$\mathbf{k}^e = t_e \int_{-1}^1 \int_{-1}^1 \mathbf{B}^T \mathbf{D} \mathbf{B} \det \mathbf{J} \, d\xi \, d\eta$$

$$\phi(\xi,\eta) = t_e(\mathbf{B}^\mathsf{T}\mathbf{D}\mathbf{B}\det\mathbf{J})_{ij}$$

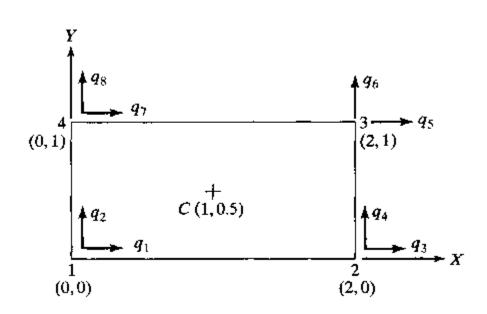
$$k_{ij} \approx w_1^2 \phi(\xi_1, \eta_1) + w_1 w_2 \phi(\xi_1, \eta_2) + w_2 w_1 \phi(\xi_2, \eta_1) + w_2^2 \phi(\eta_2, \eta_2)$$



Consider a rectangular element as shown in Fig. E7.1. Assume plane stress condition,  $E = 30 \times 10^6 \,\mathrm{psi}$ ,  $\nu = 0.3$ , and  $\mathbf{q} = [0, 0, 0.002, 0.003, 0.006, 0.0032, 0, 0]^T$  in. Evaluate **J. B.** and  $\boldsymbol{\sigma}$  at  $\boldsymbol{\xi} = 0$  and  $\boldsymbol{\eta} = 0$ .

**Solution** Referring to Eq. 7.13a, we have

$$\mathbf{J} = \frac{1}{4} \begin{bmatrix} 2(1-\eta) + 2(1+\eta) | (1+\eta) - (1+\eta) \\ -2(1+\xi) + 2(1+\xi) | (1+\xi) + (1-\xi) \end{bmatrix}$$
$$= \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix}$$





For this rectangular element, we find that J is a constant matrix. Now, from Eqs. 7.21,

$$\mathbf{A} = \frac{1}{1/2} \begin{bmatrix} \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & \frac{1}{2} & 0 \end{bmatrix}$$

Evaluating G in Eq. 7.23 at  $\xi = \eta = 0$  and using  $\mathbf{B} = \mathbf{QG}$ , we get

$$\mathbf{B}^{0} = \begin{bmatrix} -\frac{1}{4} & 0 & \frac{1}{4} & 0 & \frac{1}{4} & 0 & -\frac{1}{4} & 0 \\ 0 & -\frac{1}{2} & 0 & -\frac{1}{2} & 0 & \frac{1}{2} & 0 & \frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{4} & -\frac{1}{2} & \frac{1}{4} & \frac{1}{2} & \frac{1}{4} & \frac{1}{2} & -\frac{1}{4} \end{bmatrix}$$

The stresses at  $\xi = \eta = 0$  are now given by the product

$$\sigma^0 = \mathbf{D}\mathbf{B}^0\mathbf{q}$$

For the given data, we have

$$\mathbf{D} = \frac{30 \times 10^6}{(1 - 0.09)} \begin{bmatrix} 1 & 0.3 & 0 \\ 0.03 & 1 & 0 \\ 0 & 0 & 0.35 \end{bmatrix}$$

Thus,

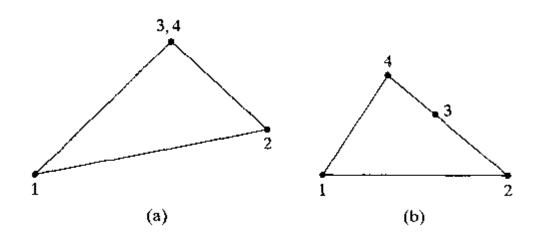
$$\sigma^0 = [66920, 23080, 40960]^T \text{ psi}$$



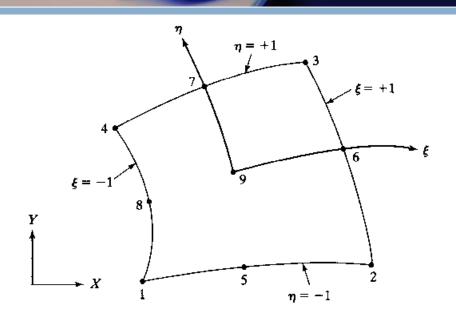
#### Stress Calculations

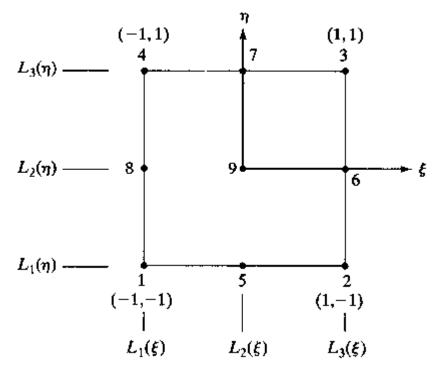
Unlike the constant-strain triangular element (Chapters 5 and 6), the stresses  $\sigma = \mathbf{DBq}$  in the quadrilateral element are not constant within the element; they are functions of  $\xi$  and  $\eta$ , and consequently vary within the element. In practice, the stresses are evaluated at the Gauss points, which are also the points used for numerical evaluation of  $\mathbf{k}^{\ell}$ , where they are found to be accurate. For a quadrilateral with  $2 \times 2$  integration, this gives four sets of stress values. For generating less data, one may evaluate stresses at one point per element, say, at  $\xi = 0$  and  $\eta = 0$ . The latter approach is used in the program QUAD.

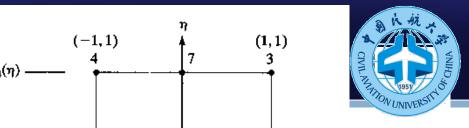












(-1,-1) (1,-1)

 $L_2(\xi)$ 

$$\mathbf{u} = \mathbf{N}\mathbf{q}$$

$$\epsilon = Bq$$

$$\mathbf{k}^e = t_e \int_{-1}^1 \int_{-1}^1 \mathbf{B}^{\mathrm{T}} \mathbf{D} \mathbf{B} \det \mathbf{J} \, d\xi \, d\eta$$

$$L_i(\xi) = 1$$
 at node  $i$   
= 0 at other two nodes

$$L_1(\xi) = -\frac{\xi(1-\xi)}{2}$$

$$L_2(\xi) = (1 + \xi)(1 - \xi)$$

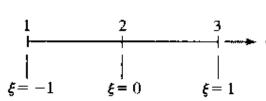
$$L_3(\xi) = \frac{\xi(1+\xi)}{2}$$

$$L_1(\eta) = -\frac{\eta(1-\eta)}{2}$$

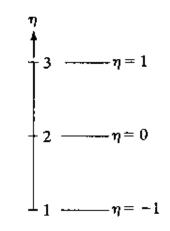
$$L_2(\eta) = (1+\eta)(1-\eta)$$

$$L_3(\eta) = \frac{\eta(1+\eta)}{2}$$

$$\xi = -1$$



 $L_1(\xi)$ 



$$N_1 = L_1(\xi)L_1(\eta)$$

$$N_8 = L_1(\xi)L_2(\eta)$$

$$N_9 = L_2(\xi)L_2(\eta)$$

$$N_1 = L_1(\xi)L_1(\eta) \qquad N_5 = L_2(\xi)L_1(\eta) \qquad N_2 = L_3(\xi)L_1(\eta)$$

$$N_8 = L_1(\xi)L_2(\eta) \qquad N_9 = L_2(\xi)L_2(\eta) \qquad N_6 = L_3(\xi)L_2(\eta)$$

 $L_3(\xi)$ 

$$N_4 = L_1(\xi)L_3(\eta)$$

$$N_4 = L_1(\xi)L_3(\eta)$$
  $N_7 = L_2(\xi)L_3(\eta)$   $N_3 = L_3(\xi)L_3(\eta)$ 

$$N_3 = L_3(\xi)L_3(\eta)$$



$$N_1 = c(1 - \xi)(1 - \eta)(1 + \xi + \eta)$$

$$N_1 = -\frac{(1-\xi)(1-\eta)(1+\xi+\eta)}{4}$$

$$N_2 = -\frac{(1+\xi)(1-\eta)(1-\xi+\eta)}{4}$$

$$N_3 = -\frac{(1+\xi)(1+\eta)(1-\xi-\eta)}{4}$$

$$N_4 = -\frac{(1-\xi)(1+\eta)(1+\xi-\eta)}{4}$$

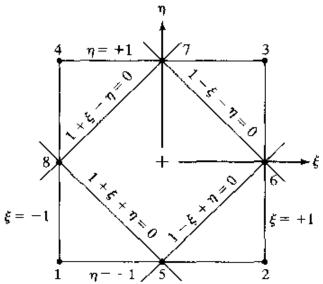
$$N_5 = c(1 - \xi)(1 - \eta)(1 + \xi)$$
  
=  $c(1 - \xi^2)(1 - \eta)$ 

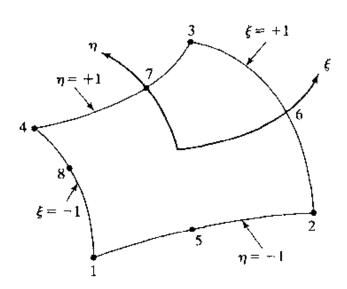
$$N_5 = \frac{(1 - \xi^2)(1 - \eta)}{2}$$

$$N_6 = \frac{(1 + \xi)(1 - \eta^2)}{2}$$

$$N_7 = \frac{(1 - \xi^2)(1 + \eta)}{2}$$

 $N_8 = \frac{(1-\xi)(1-\eta^2)}{2}$ 







$$N_1 = \xi(2\xi - 1)$$
  $N_4 = 4\xi\eta$ 

$$N_2 = \eta(2\eta - 1) \qquad N_5 = 4\zeta\eta$$

$$N_3 = \zeta(2\zeta - 1) \qquad N_6 = 4\xi\zeta$$

$$u = Nq$$

$$x = \sum N_i x_i \qquad y = \sum N_i y_i$$

$$\mathbf{k}^e = t_e \int_A \int \mathbf{B}^{\mathrm{T}} \mathbf{D} \mathbf{B} \det \mathbf{J} \, d\xi \, d\eta$$

### $\mathbf{k}^e \approx \frac{1}{2} t_e \overline{\mathbf{B}}^{\mathrm{T}} \overline{\mathbf{D}} \mathbf{B} \det \overline{\mathbf{J}}$

$$\int_0^1 \int_0^{1-\ell} f(\xi,\eta) \, d\eta \, d\xi \approx \sum_{i=1}^n w_i f(\xi_i,\eta_i)$$

No. of points,	Weight, w,	Multiplicity	€,	η,	ζ,
One	1 2	1	Į Š	<u>1</u>	1 1
Three	16	3	2	<u>l</u>	<u>1</u> 6
Three	$\frac{1}{6}$	3	1/2	1 2	0
Four $-\frac{9}{\sqrt{2}}$ $\frac{25}{96}$	1	l Š	1/3	1	
	3	3 <	l s	<u>1</u> 5	
Six	<u>1</u>	6	0.6590276223	0.2319333685	0.1090390090

