# CSE517a Final

## Good luck!

## May 2015

NAME:	
Student ID:	
Email:	

General ML	
Kernls	
Neural Networks	
GPs	
Unsupervised Learning	
TOTAL	

#### 1 [??] General Machine Learning

Either circle **T** or **F**. Questions declared as **True** require no explanation (worth 1 point). Questions declared as **False** require a **one sentence** explanation (worth 2 points).

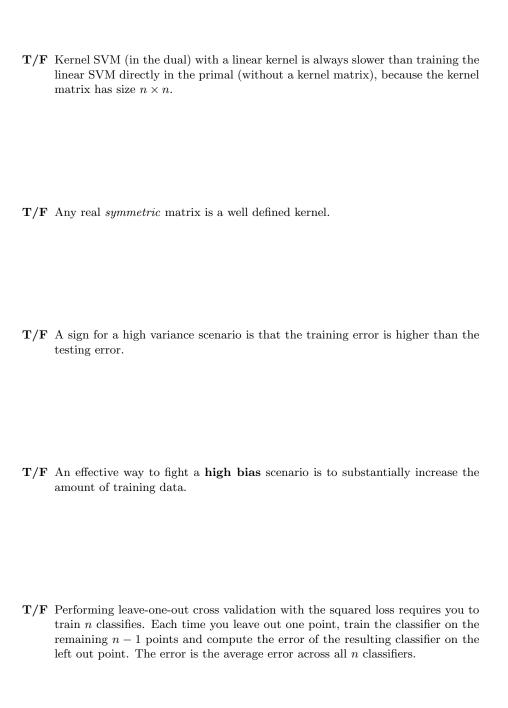
T/F The fundamental difference between Bayesian and Frequentist Statistics boils down to the definition of good pop music. (For example, "Bayesians" love Meghan Trainor's song "All about the Bayes" and just cannot hear enough of it, whereas "Frequentists" believe strongly that this song has been played way too frequently on the media in recent months. Frequentists are also concerned that certain passages may be inappropriate, in particular when the singer refers to shaking her posterior, which should be changed to likelihood.)

 ${f T/F}$  The difference between Parametric and Non-parametric algorithms is that non-parametric algorithms have no hyper-parameters to tune.

 $\mathbf{T}/\mathbf{F}$  Platt scaling is used to scale features to be between 0 and 1.

 $\mathbf{T}/\mathbf{F}$  One advantage of 1 vs. 1 multi-class classification over 1 vs. all is that the problems are more likely to be class balanced.

T/F	After convergence, the K-means cluster centers are always original data points.
T/F	SVD decomposes a matrix $\mathbf{X}$ (with data as column vectors) into three terms $\mathbf{X} = \mathbf{U}\mathbf{S}\mathbf{V}^{\top}$ . The matrix $\mathbf{S}$ is diagonal and non-negative, the matrix $\mathbf{U}$ is the projection matrix of PCA the matrix $V$ is the whitened data.
T/F	The $i^{th}$ largest eigenvalue of the covariance corresponds to the amount of variance captured in the $i^{th}$ principal component.
T/F	The Support Vector Machine with the RBF kernel is non-parametric.
T/F	K-means is a non-parametric algorithm



### 2 [20] Kernels

1. (5) Assume  $\Omega$  is a set of all words in the English dictionary,  $|\Omega|=d$ . We define a text document as the set of all the words that are in the document,  $S\subseteq\Omega$ . Proof that the following kernel over such documents is well-defined (*i.e.* positive semi-definite)

$$k(S_1, S_2) = \exp\left(\frac{|S_1 \cap S_2|}{|S_1| |S_2|}\right).$$

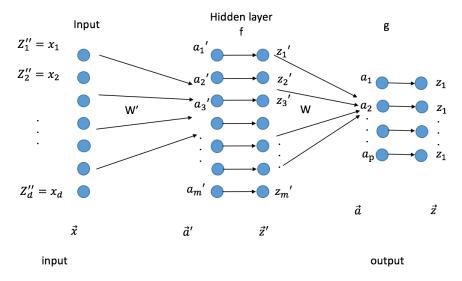
(Hint: It helps to write  $\Omega = \{\omega_1, \dots, \omega_n\}$  and represent a set S as a binary vector  $x \in \{0,1\}^d$ , where the  $i^{th}$  dimension  $x_i = 1$  if and only if  $\omega_i \in S$ .)

- 2. (10) Assume you are given a data set  $D = \{(\vec{x}_1, y_1), \dots, (\vec{x}_n, y_n)\}$  with  $\vec{x}_i \in \mathbb{R}^d$  and  $y_i \in \{+1, -1\}$ . The Perceptron algorithm learns a separating hyper-plane in the following way:
  - (a) Initialize  $\mathbf{w} = \vec{0}$
  - (b) Pick  $(\vec{x}_i, y_i)$  randomly from D.
  - (c) If  $y_i \mathbf{w}^{\top} \vec{x}_i \leq 0$  then make the update  $\mathbf{w} \leftarrow \mathbf{w} + y_i \vec{x}_i$ , otherwise do nothing.
  - (d) Goto step (b) and repeat until convergence.

Show that this algorithm can be kernelized. First show that  $\mathbf{w}$  can be written as a linear combination of the inputs. State the kernelized classifier h() and the kernelized version of the learning algorithm.

3. (5) Joe wants to combine the power of kernel machines with that of neural networks. He trains a neural network with one hidden layer on his training data. Then he defines the mapping  $f(\vec{x}) = \vec{z}'$  to be the mapping of his input to the first hidden layer (after the transition function has been applied). (See the neural network figure on the next page for an illustration.) He then defines his kernel matrix  $k(\vec{x}_1, \vec{x}_2) = f(\vec{x}_1)^{\top} f(\vec{x}_2)$  to train an SVM. Is this kernel function well defined?

# 3 [18] Neural Networks



1. (3) Write z and z' in terms of x, a', a, W', W and the transition functions f and g.

(5) Given  $\delta_j = \frac{\partial L}{\partial a_j}$ , derive  $\delta'_j = \frac{\partial L}{\partial a'_j}$ .

2.	(4) Batman is frustrated about how slow his super deep Neural Network is. He decides to remove all non-linear transition functions to speed it up. To his surprise, this change drastically increases his training error. Can you explain why?
3.	(3) Rectified Linear Units have become more popular transition function than Sigmoids. Name one advantage of Rectified linear Units over sigmoid functions.
4.	(3) Why is it often impractical to use Newton's method to train a neural network?

### 4 [11] Gaussian Processes

1. (5) What are the assumptions of Gaussian Process Regression (with mean  $\vec{\mu}_x$  and variance  $\mathbf{K}_x$ ) about the distribution of the labels  $y_1, \ldots, y_n$  and a test label  $y_t$ ?

2. (5) The mean prediction of GPR is identical to kernel regression. So why can't we easily use kernel regression for hyper-parameter optimization with the Upper Confidence Bound (UCB) exploration / exploitation strategy?

3. (5) You are using Bayesian Global Optimization to optimize the hyper-parameters of an SVM ( $\sigma$  and C) with Upper Confidence Bound (UCB). After a small number of training points have been sampled your model predicts that the setting  $\sigma_m, C_m$  yields the highest predicted accuracy on the validation set. Explain a scenario where your optimization algorithm would pick a different set of hyper-parameters  $\sigma', C'$  to explore with lower predicted accuracy.

### 5 [19] Unsupervised Learning

1. (4) Batman wants to use k-means to cluster a data set of n data points. He doesn't know how many clusters k the data set has so he tries every possible setting k=1,...,n and computes the squared reconstruction loss on his training data for each one. Then his algorithm selects the clustering with the lowest reconstruction error and outputs it as the final answer. After the algorithm is done he is amazed to note that the best reconstruction error is in fact zero. He sees this as a clear indication that his data has strong cluster structure, which he has now uncovered. Do you share his opinion? What value of k did the algorithm select?

2. (5) In the K-means optimization algorithm, we use the following update rule for each cluster where  $\vec{\mu}_i$  is the center of the *i*-th cluster.

$$\gamma_{ij} = \begin{cases} 1 & : j = \min_{j} (\vec{x}_i - \vec{\mu}_j)^2 \\ 0 & : \text{else} \end{cases}$$

$$\vec{\mu}_j = rac{1}{\sum\limits_i \gamma_{ij}} \sum\limits_i \gamma_{ij} \vec{x}_i$$

Prove that this minimizes the squared Euclidean distance between each point  $\vec{x}_i$  and its cluster center  $\vec{\mu}_j$ .

3. (5) James Bond collects facial images of all the bad guys and good guys form all his past movies to train a good guy/bad guy classifier. He manages to get the images well aligned (each with black background). Unfortunately most of the old movies were made in the 1960s and are of pretty bad quality (assume additive Gaussian noise on the input pixels). How could he use PCA to remove this noise? How would he know what is data and what is noise?

4. (5) Being a butterfly enthusiast, he also collects a data set of images of butterflies. Unfortunately he accidentally mixes it up with his data set of facial images. Given the PCA projection matrix (obtained from facial images) **U** and the mean face  $\vec{m}$ , how can he identify which images  $\vec{x}_i$  are butterflies and which faces (without looking at the images - after all he can't see very well because he is wearing that ridiculous helmet with only tiny see-through slits for the eyes)?