Course: DATS 6450 – Time Series Analysis & Modeling

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Final Term Project

Topic: Appliance Energy Prediction

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Abstract

The project work focuses on performing time series analysis and modeling on a time series data. The data used in the project is recorded based on the amount of energy consumed by appliances in a household for 4.5 months. The project applies all the analysis and preprocessing techniques for a time series data to make it prepared for the modelling phase. Different time series linear models are used to find the best suitable model to predict the appliance energy consumed in a household. The project implementation completely relies on python and the best model for the forecast is selected using different performance measures. The best model for the project was Multiple Linear Regression.

INTRODUCTION

Time series analysis is a specific way of analyzing a sequence of data points collected over an interval of time. In time series analysis, analysts record data points at consistent intervals over a set period rather than just recording the data points intermittently or randomly. Time series analysis typically requires many data points to ensure consistency and reliability. An extensive data set ensures you have a representative sample size, and that analysis can cut through noisy data. It also ensures that any trends or patterns discovered are not outliers and can account for seasonal variance. Additionally, time series data can be used for forecasting—predicting future data based on historical data.

To make better analysis, it is always recommended to have processed and prepared data. The data in the initial stage is visualized using basic information and plot to make sure it is ready to be treated for modelling. The stationarity of the data is tested using rolling mean and variances, ADF test and KPSS test. While calculating the rolling mean and variances, the plot is considered to have flat line to say the data is stationary. ADF and KPSS tests follow their own hypothesis (based on p-value and test statistics) to confirm the stationarity in the data. If it is non-stationary, appropriate differencing techniques is performed to make the data stationary. Differencing can also be performed to remove the seasonality in the data.

A time series data has various components. Separation and analysis of those components is needed to proceed further with good modelling. Decomposition can be done using techniques like SVD, STL to understand the patterns in data. Based on the strength of seasonality and trend, the data needs to be seasonally adjusted or detrended.

One of the primary methods of time series analysis is Holts-Winter method. It can be used on the data with both seasonal and trend component. It tries to capture more aspects in the data. A full model with all variables will not be a good model every time. To find a best model, feature selection is performed based on the p-value of OLS model. The variables with high p-values are correlated and unwanted, they are removed to make a better model. The model with best features is developed using multiple linear regression technique. The multiple linear regression model's performance can be tested using AIC/BIC score, R-squared/adjust R-squared values and condition number. More the R-squared value better is the model. The model with high AIC/BIC and condition number is said to be a bad model.

In the same way, the data is modelled using all the base models to understand whether the data can be forecasted using simpler models rather than moving to complex other linear models. The base models are Average, Naïve, Drift and Simple Exponential Smoothening. These models have different properties in forecasting the data. Other more appropriate way of find better model is using the technique of auto-regressive and moving-average. A better model like ARMA, ARIMA and SARIMA are developed based on these aspects using different combination of these two methods. Out of these models, the best model is selected for the final forecasting.

A detailed description about these techniques is discussed in the next chapter.

METHOD, THEORY AND PROCEDURES

Stationary data:

The data can be called stationary when the statistics of the data doesn't change over the period.

Rolling mean and variance:

Rolling in timeseries means creating a rolling window of specified size and perform statistical calculations on data. Rolling mean and variance works in a way where it calculates the mean and variance of the data under a particular window.

Mean = Sum of observations / Total number of observations

Variance = (Differences between each number in the data set and the mean)²

Number of observations in the dataset

Considering the above formulas, rolling mean and variance are calculated as follows:

During first iteration, the first sample will load and the mean and variance will be calculated. During the second iteration, the first two samples will load, and their necessary mean and variance will be calculated. In this way the iteration will happen till the last observation is loaded and their mean and variances are calculated.

This will result in the generation of two lists rolling mean and variance at every iteration which can be used to plot against time to understand whether the data is stationary or not. Using these plots, we can say a data is stationary if the mean and variance remains constant over the time.

ADF Test:

The Augmented-Dickey Fuller test is a statistical test or unit root test to test whether the data is stationary or not using the degree of hypothesis. The intuition behind this test to predict how strongly a time series defined by trend.

The ADF test has three parameters in test results: test statistic, p-value, critical values

Hypothesis of ADF test:

Null hypothesis (H_0) – If it is failed to be rejected, the times series has unit root which means the data is non-stationary

Alternate hypothesis (H_1) – If the null hypothesis is rejected, the times series has no unit root which means the data is stationary

To reject the null hypothesis, the test statistic should be more negative, and p-value should be less than the threshold (0.05).

KPSS Test:

KPSS test is another test to confirm the data is stationary or not. It is somewhat like ADF test, but the hypothesis is in opposite. KPSS is also a unit root test that tests the stationarity of the data around a deterministic trend.

Hypothesis of KPSS test:

Null hypothesis (H_0) – If it is failed to be rejected, the times series is trend stationary Alternate hypothesis (H_1) – If the null hypothesis is rejected, the times series has unit root which means the data is not stationary

To reject the null hypothesis, the test statistic should be higher than critical values, and p-value should be less than the threshold (0.05).

Autocorrelation:

Autocorrelation measures the linear relationship between lagged values of time series. Autocorrelation represents the degree of similarity between a given time series and a lagged version of itself over successive time intervals. Autocorrelation measures the relationship between a variable's current value and its past values. An autocorrelation of +1 represents a perfect positive correlation, while an autocorrelation of negative 1 represents a perfect negative correlation.

 $R^y(\tau)$ is an estimated autocorrelation for stationary time series y(t). It just depends on the lagged values of time series.

$$\hat{R_y}(\tau) = \frac{\sum_{t=\tau+1}^{T} (y_t - \overline{y})(y_{t-\tau} - \overline{y})}{\sum_{t=1}^{T} (y_t - \overline{y})^2}$$

Average method:

The forecast of all future values is equal to the average ("mean") of the historical data. The technique is very useful for forecasting short-term trends. The average method assumes that all observations are of equal importance and gives them equal weights when generating forecasts.

$$\hat{y}_{T+h|T} = \frac{y_1 + y_2 + \dots + y_T}{T}$$

Naïve method:

For the Naive forecasts, we simply set all forecasts to be the value of the last observation. Hence, the naive method assumes, that the most observation is the only important one, and all previous observations provide no information for the future. This method sometimes works remarkably well for many economic and financial time series data and sometimes it gives a big error.

$$\hat{y}_{T+h|T} = y_T$$

Drift method:

The variation on the naive method is to allow the forecast to increase or decrease over time, where the amount of change over time (called the drift) is set to be the average change seen in the historical data. This is equivalent to drawing a line between the first and last observations and extrapolating it into the future.

$$\hat{y}_{T+h|T} = y_T + \frac{h}{T-1} \sum_{t=2}^{T} (y_t - y_{t-1}) = y_T + h(\frac{y_T - y_1}{T-1})$$

Simple Exponential Smoothing (SES):

Simple exponential smoothing is calculated using weighted averages where the weights decrease exponentially as observations come from further in the past, the smallest weights are associated with the oldest observations.

$$\hat{y}_{t+1|t} = \alpha y_t + (1 - \alpha)\hat{y}_{t|t-1}$$

Mean squared error:

In statistics, the mean squared error or mean squared deviation of an estimator measures the average of the squares of the errors—that is, the average squared difference between the estimated values and the actual value.

$$MSE = mean(e_t^2)$$

Multiple linear regression model:

The multiple linear regression model is,

$$yt = \beta 0 + \beta 1x1, t + \beta 2x2, t + \cdots + \beta kxk, t + \varepsilon t$$

 β 0, β 1, ... β k are unknown values which needs to be estimated using LSE using the following equation:

$$\beta = (XT.X)^{-1} XT.Y$$

where X and Y are given as,

Matrix X has T rows and (k+1) columns where T is the number of samples and k is number of independent variables.

SVD:

Singular Value Decomposition or SVD the popular technique for dimensionality reduction. This is a linear algebra technique to create a projection of a sparse dataset prior to fitting a model.

$$s, d, v = np.linalg.svd(H)$$

Backwards stepwise regression:

- 1. Start with the model containing all potential predictors.
- 2. Remove one predictor at a time. Keep the model of it improves the measure of predictive accuracy.
- 3. Iterate until no further improvement.

Estimated Variance:

$$\hat{\sigma}_e = \sqrt{\frac{1}{T - k - 1} \sum_{t=1}^{T} e_t^2}$$

STL decomposition method:

STL stands for "Seasonal and Trend decomposition using Loess", while Loess is a method for estimating nonlinear relationships. STL has several advantages over the classical, SEATS and X11 methods: STL can handle all type of seasonality, not only monthly and quarterly data. The seasonal component is allowed to change over time and the rate of change can be controlled by the user. The smoothness of trend-cycle can be controlled by the user.

Seasonally adjusted data:

Additive decomposition: seasonally adjusted data given by: yt - St = Tt + Rt

Multiplicative decomposition: seasonally adjusted data given by: $yt/St = Tt \times Rt$

Strength of trend and seasonality:

The rubric to measure the strength of the trend is given as:

$$FT = \max\{0, 1 - Var(Rt) Var(Tt + Rt)\}\$$

For strongly trended data, the rubric FT is large.

The rubric to measure the strength of the seasonality is given as

$$FS = \max\{0, 1 - Var(Rt) Var(St + Rt)\}$$

FS close to 0 exhibits almost no seasonality, FS close to 1 exhibits strong seasonality

Auto regressive model:

In a multiple regression model, we forecast the variable of interest using linear combination of predictors. In an autoregressive model, we forecast the variable of interest using a linear combination of past values of the variable. An AR process of order na AR(na) can be written as:

$$y(t) + a1y(t-1) + a2y(t-2) + ... + ana y(t-na) = e(t)$$

where y(t) is the variable of interest and g(t) is white noise (WsN ~ (0, σ 2e).

Moving average model:

Rather than using past values of the forecast variable in aregression, a moving average model uses past forecast errors in a regression-like model:

$$y(t) = e(t) + b1e(t-1) + b2e(t-2) + ... + bnb e(t-nb)$$

where e(t) is white noise WN \sim (0, σ 2e). This is called a moving average model of order nb , MA(nb).

Generalized Partial Auto Correlation:

The generalized partial autocorrelation is used to estimate the order of ARMA model when na != 0 and nb != 0.

$$\phi_{kk}^{j} = \frac{\begin{vmatrix} \hat{R}_{y}(j) & \hat{R}_{y}(j-1) & \dots & \hat{R}_{y}(j+1) \\ \hat{R}_{y}(j+1) & \hat{R}_{y}(j) & \dots & \hat{R}_{y}(j+2) \\ \vdots & \vdots & \vdots & \vdots \\ \hat{R}_{y}(j+k-1) & \hat{R}_{y}(j+k-2) & \dots & \hat{R}_{y}(j+k) \end{vmatrix}}{\begin{vmatrix} \hat{R}_{y}(j) & \hat{R}_{y}(j-1) & \dots & \hat{R}_{y}(j-k+1) \\ \hat{R}_{y}(j) & \hat{R}_{y}(j) & \dots & \hat{R}_{y}(j-k+2) \\ \vdots & \vdots & \vdots & \vdots \\ \hat{R}_{y}(j+k-1) & \hat{R}_{y}(j+k-2) & \dots & \hat{R}_{y}(j) \end{vmatrix}}$$

Levenberg-Marquardt Algorithm:

In the gradient decent method, the sum of the squared errors is reduced by updating the parameters in the steepest-decent direction. In the Gauss-Newton method, the sum of the squared errors is reduced by assuming the least square's function is locally quadratic and finding the minimum of the quadratic. The LM method acts like a gradient-decent method when the parameters are far from their optimal value and acts more like the Gauss-Newton method when the parameters are close to their optimal value.

Seasonal ARIMA:

For seasonal time series with period s, observations that are s intervals apart are similar. SARIMA (Na, D, Nb) with period of seasonality s can be written as:

$$A(q^{-s})\nabla_s^D y_t = B(q^{-s})\epsilon_t$$

where $abla^D$ is given as

$$abla_s^D = (1 - q^{-s})^D$$
 $A(q^{-s}) = 1 - A_1 q^{-s} - A_2 q^{-2s} - \dots - A_{N_a} q^{-N_a s}$
 $B(q^{-s}) = 1 - B_1 q^{-s} - B_2 q^{-2s} - \dots - B_{N_b} q^{-N_b s}$

Procedure:

- 1. Load the dataset and provide descriptive statistics about the dependent variable.
- 2. Check for stationarity (ADF, rolling mean, etc.,) and make the dataset stationary if it is not.
- 3. Perform Time Series Decomposition
- 4. Perform Holts-winter method on train and test data
- 5. Perform feature selection

- 6. Build multiple linear regression model based on the selected features
- 7. Perform predictions on base models to find the best fit
- 8. Develop ARMA, ARIMA and SARIMA models based on orders from GPAC
- 9. Choose the final model based on the performance measure of each model
- 10. Develop a forecast function and do h-step prediction based on the selected model

EXPERIMENTAL SETUP

Required libraries:

The following python libraries are required to run the code file seamlessly.

```
import matplotlib.pyplot as plt
import numpy as np
import statsmodels.tsa.arima_model
import statsmodels.tsa.holtwinters as ets
from Toolbox import *
import pandas as pd
from sklearn.model_selection import train_test_split
from statsmodels.tsa.seasonal import STL
from sklearn.metrics import mean_squared_error
from statsmodels.stats.diagnostic import acorr_ljungbox
import statsmodels.api as sm
from numpy import linalg as la
```

DESCRIPTION OF THE DATASET:

The dataset used in the project was taken from UCI Machine Learning Repository it has 19735 rows and 29 columns. The house temperature and humidity conditions were monitored with a ZigBee wireless sensor network hence the dataset is at 10 min for about 4.5 months. Each wireless node transmitted the temperature and humidity conditions around 3.3 min. Then, the wireless data was averaged for 10 minutes periods. The energy data was logged every 10 minutes with m-bus energy meters. Weather from the nearest airport weather station (Chievres Airport, Belgium) was downloaded from a public data set from Reliable Prognosis (rp5.ru) and merged with the experimental datasets using the date and time column. Two random variables have been included in the data set for testing the regression models and to filter out non predictive attributes (parameters).

Attribute Information:

Date	time year
month	day hour:minute:second
Appliances	Energy use in Wh
Lights	Energy use of light fixtures in the house in
	Wh
T1	Temperature in kitchen area, in Celsius
RH_1	Humidity in kitchen area, in %
T2 Temperature in living room area, in Cel	
RH_2 Humidity in living room area, in %	
T3	Temperature in laundry room area
RH_3	Humidity in laundry room area, in %
T4	Temperature in office room, in Celsius
RH_4	Humidity in office room, in %
T5	Temperature in bathroom, in Celsius

7	
RH_5	Humidity in bathroom, in %
T6	Temperature outside the building (north
	side), in Celsius
RH_6	Humidity outside the building (north side),
	in %
T7	Temperature in ironing room, in Celsius
RH_7	Humidity in ironing room, in %
T8	Temperature in teenager room 2, in Celsius
RH_8	Humidity in teenager room 2, in %
T9	Temperature in parents' room, in Celsius
RH_9	Humidity in parents' room, in %
To	Temperature outside (from Chievres
	weather station), in Celsius
Pressure (from	in mm Hg
Chievres	
weather station)	
RH_out	Humidity outside (from Chievres weather
	station), in %
Wind speed	in m/s
(from Chievres	
weather station)	
Visibility (from	in km
Chievres	
weather station)	
Tdewpoint (from	°C
Chievres	
weather station)	
rv1	Random variable 1, nondimensional
rv2	Random variable 2, nondimensional

Table1: Attribute Information

Dataset source: https://archive.ics.uci.edu/ml/datasets/Appliances+energy+prediction

Looking at the dataset information, it is clear the data has been recorded from one household and there are two possible dependent variables: Appliances, Lights. Considering the dataset is for one household and attribute values, 'Appliances' is selected as the independent variable.

Pre-processing dataset:

Analyzing the dataset's basic statistics, it is evident that the dataset doesn't have any null values. Hence, the dataset doesn't require much preprocessing and the dataset is also not sliced considering already it has data only for about 4.5 months. The 'date' variable is created as an index for the dataset and the dependent variable is 'Appliances'. The project through out will be using 'Appliances' as the dependent variable with 27 other predictor variables.

Analysis of dependent variable:

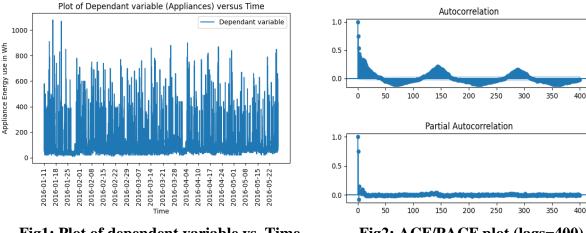


Fig1: Plot of dependent variable vs. Time

Fig2: ACF/PACF plot (lags=400)

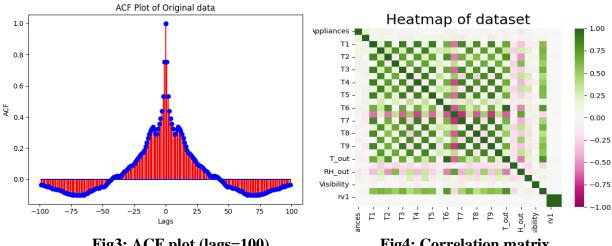


Fig3: ACF plot (lags=100)

Fig4: Correlation matrix

The plot of dependent variable over the time appears that the data can be stationary but spikes throughout the plot shows there can be some seasonality. To understand better, ACF/PACF plot was generated and as expected the ACF converges over time but there is spike in the ACF values after every 144th lag. This shows the data does have seasonality.

The symmetric ACF plot shows clear seasonality where the plot converges over the positive values of ACF for while and moves into the negative values of ACF. The seasonality at lag 144 was confirmed by the following calculation:

The dataset is recorded for every 10 minutes and there 24 hours in a day, considering 6 records for every one hour it can be concluded that the seasonality is at lag144 (10x6x24).

The PACF plot of the data cuts-off at lag of 12 and this can also be signing that data becomes stationary after lag 12. The correlation matrix has darker patterns which shows that the variables in the dataset are highly correlated with each other. So, proceeding further with model development the correlated variables should be removed to find the best model.

The dataset has been separated into train and test data based on the train test split ratio of 80:20.

STATIONARITY:

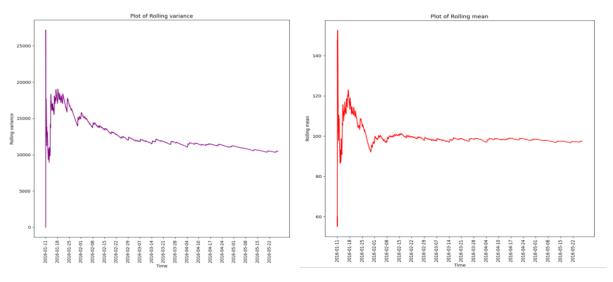


Fig5: Rolling variance (raw data)

Fig6: Rolling mean (raw data)

The plot of rolling mean and variance shows that the data is stationary because the plot converges into a flat line after few iterations. But the mean of the data is not zero. There is some uncertainty in the first few iterations due to seasonality but the data towards the end shows a flat curve. These minor spikes can be reduced by differencing the data. Though, the plot of rolling mean and variance shows that the data is stationary, ADF and KPSS test has also been performed to confirm the stationarity of the data.

ADF Statistic: -21.616378	Test Statistic	0.036599
p-value: 0.000000	p-value	0.100000
Critical Values:	Lags Used	74.000000
	Critical Value (10%)	0.347000
1%: -3.431	Critical Value (5%)	0.463000
5%: -2.862	Critical Value (2.5%)	0.574000
10%: -2.567	Critical Value (1%)	0.739000
10%. 2.307	dtype: float64	

Fig7: ADF test of raw data

Fig8: KPSS test (raw)

Looking at the ADF test, the p-value is almost zero and the ADF test statistic is more negative, so we tend to reject the null hypothesis. And say the data is stationary.

The KPSS test has p-value higher than zero and the test statistic is lesser than the any of the critical values. So, we don't reject the null hypothesis and say the data is stationary.

As, discussed earlier the data tends to have some seasonality which resulted in not having mean flattening at zero. So, the data is differenced for interval of 144 and the stationarity of the differenced data is also tested again.

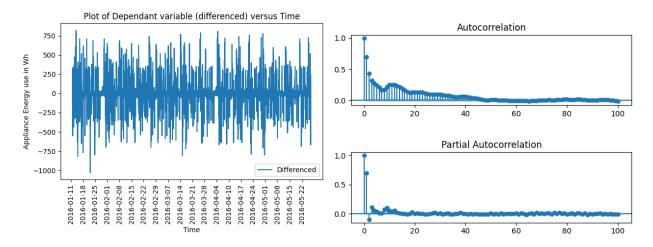


Fig9: Plot of differenced data vs. Time

Fig10: ACF/PACF plot of differenced data

The differenced data looks more leveled than the original data. The ACF of the differenced data converges after lag 45 and the PACF plot cuts-off after lag 10 or so. The seasonality from the data has been removed using a seasonal differencing of interval 144. Let's analyze the stationarity of the differenced data.

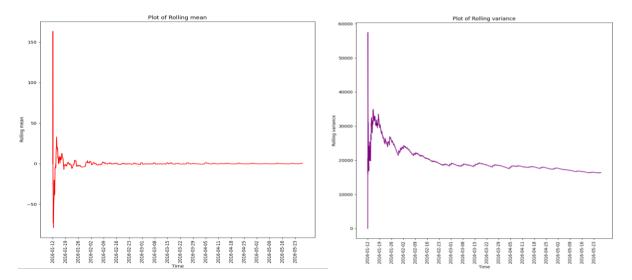


Fig11: Rolling mean (differenced)

Fig12: Rolling variance (differenced)

The rolling mean and variance of data is more leveled now and the initial spikes due to seasonality in raw data has also been reduced. As expected, the seasonal differencing has made the data to be flat at rolling mean of zero. This shows the differenced data is also perfectly stationary.

10%2.30/	
Test Statistic	0.00779
p-value	0.10000
Lags Used	62.00000
Critical Value (10%)	0.34700
Critical Value (5%)	0.46300
Critical Value (2.5%)	0.57400
Critical Value (1%)	0.73900
	Test Statistic p-value Lags Used Critical Value (10%) Critical Value (5%) Critical Value (2.5%)

Fig13: ADF test (differenced)

Fig14: KPSS test (differenced)

Looking at the ADF test, the p-value is almost zero and the ADF test statistic is more negative, so we tend to reject the null hypothesis. And say the data is stationary.

The KPSS test has p-value higher than zero and the test statistic is lesser than the any of the critical values. So, we don't reject the null hypothesis and say the data is stationary.

TIME SERIES DECOMPOSITION:

Time series decomposition of the data was performed using STL technique to understand the patterns of trend and seasonality in the data.

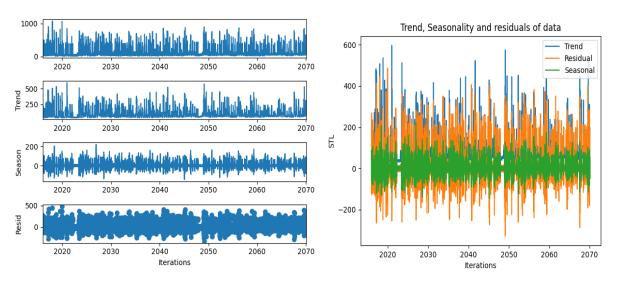


Fig15: Plot of STL decomposition

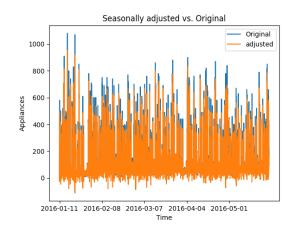
Fig16: Plot of residuals, trend and seasonal

The STL decomposition techniques helps to analyze the composition of residuals, trend, and seasonal patterns in the data. The plot of STL shows, that the residual values are scattered throughout the plot and there is some spike on the trend and seasonal plot which shows the data might be trended and seasonal. To confirm the percentage of trend and seasonality present in the data the strength of trend and seasonality was calculated.

Strength of trend: 0.7279717571942488 Strength of seasonality: 0.2882949243229801

Fig17: Strength of seasonality and trend

The strength of seasonality and trend shows the data is highly trended since the value is close to 1 and there exists some minor seasonality in the data as the value is just 0.2 which much away from 1. This shows that the data needs to be detrended and seasonally adjusted.



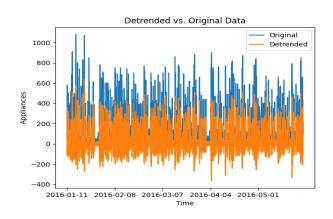
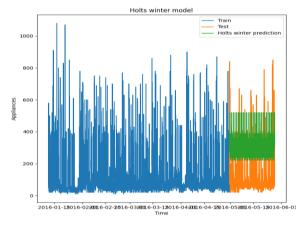


Fig18: Seasonally adjusted vs raw data

Fig19: Detrended data vs. raw data

The seasonally adjusted data follows the pattern close to the original data and the detrended data also follows the path of original data well. The original data looks like it has more variance than the detrended data.

HOLTS-WINTER METHOD:



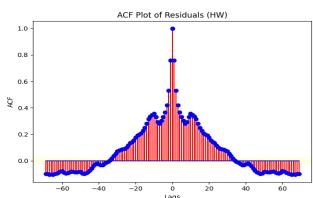


Fig20: Holts-winter method plot

Fig21: ACF plot of residuals

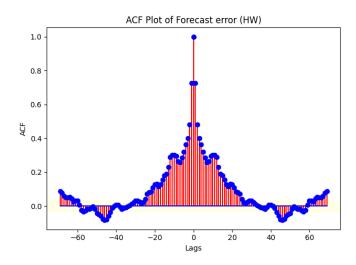


Fig22: ACF of forecast errors

The plot of holts-winter method looks like the model did not perform well on the test data as the path of forecasted follows are different from the pattern of original test values. This can be seen on the ACF plot of the residulas were the residuals are not white. This ideally shows the holts-winter method is not better for forecasting the data.

Performance metrics:

The Q-value of Box-pierce test is high (20191.89) with p-value 0.0. It shows the residual is not white for the holts-winter method. The MSE value of predictions are high (62632.91). The mean of the residual is not close to zero (-223.72) and variance is 12580.21. The RMSE value of predictions is 250.26. All these performance metrics shows the Holts-winter method is not a significant model to forecast the data.

The performance of this method on test data is given below:

MSE: 59846; Q-value: 4571; Mean of forecast: -225.63; Variance: 8937; RMSE:244.63

As expected, the MSE and mean od forecast errors are high which means the method didn't work well with the test data.

FEATURE SELECTION:

```
Singular Values: [9.49180454e+09 1.43321499e+07 6.64639821e+06 2.41644450e+06 1.71132439e+06 1.32612807e+06 1.14252067e+06 9.44023889e+05 1.65167716e+05 1.12684780e+05 9.14268363e+04 6.75353423e+04 4.80002467e+04 4.32048592e+04 4.09875639e+04 2.03833935e+04 1.26346857e+04 1.07403810e+04 9.83140093e+03 7.27434807e+03 5.34565853e+03 3.98959028e+03 3.07348563e+03 1.96329401e+03 9.85144085e+02 7.32816280e+02 7.12515963e-01 9.48420991e-07]
The condition number is 6.800018126641549e+16
```

Fig23: Singular values and condition number

The SVD analysis shows that the full model has singular values which converges to zero over the end and the condition number is relatively high. This shows the model has features which are highly correlated and they need to be removed based on the OLS summary.

Annlianese		==========
Annlianaca		
Appliances	R-squared:	0.173
OLS	Adj. R-squared:	0.172
Least Squares	F-statistic:	126.7
Wed, 08 Dec 2021	Prob (F-statistic):	0.00
14:08:22	Log-Likelihood:	-94410.
15788	AIC:	1.889e+05
15761	BIC:	1.891e+05
26		
nonrobust		
	Least Squares Wed, 08 Dec 2021 14:08:22 15788 15761 26	OLS Adj. R-squared: Least Squares F-statistic: Wed, 08 Dec 2021 Prob (F-statistic): 14:08:22 Log-Likelihood: 15788 AIC: 15761 BIC: 26

Fig24: Full model metrics

Looking at the adjusted R squared and R-squared value the model with all the variables included doesn't have better performance and the AIC,BIC are relatively high. This shows the correlated features need to be removed to find the best fit.

Using, the OLS package the p-value of the models are estimated and the features with high p-values are removed using backward stepwise regression method.

The following features are removed based on backward regression technquie: rv1, rv2, const, T7, RH_7, RH_5, T5, RH_out, Tdewpoint, RH_9, T1, Press_mm_hg

After removing the above defined features, the condition number of the model dropped below 1000 which shows the model is the best fit with all the correlated features removed.

```
The best features are Index(['lights', 'RH_1', 'T2', 'RH_2', 'T3', 'RH_3', 'T4', 'RH_4', 'T6', 'RH_6', 'T8', 'RH_8', 'T9', 'T_out', 'Windspeed', 'Visibility'], dtype='object')
```

Fig25: Best features

Using the above defined features, a better multiple linear regression model can be developed to forecast the data.

MULTIPLE LINEAR REGRESSION:

=========	=======================================		.=======	.=======		
	coef	std err	t	P> t	[0.025	0.975]
lights	2.1396	0.103	20.785	0.000	1.938	2.341
RH_1	13.8562	0.633	21.887	0.000	12.615	15.097
T2	-17.1101	1.402	-12.204	0.000	-19.858	-14.362
RH_2	-13.2627	0.739	-17.935	0.000	-14.712	-11.813
T3	25.5010	1.076	23.699	0.000	23.392	27.610
RH_3	8.6120	0.687	12.534	0.000	7.265	9.959
T4	-3.9367	1.052	-3.743	0.000	-5.998	-1.875
RH_4	-2.8629	0.677	-4.231	0.000	-4.189	-1.536
T6	8.3984	0.755	11.126	0.000	6.919	9.878
RH_6	0.3553	0.070	5.085	0.000	0.218	0.492
T8	8.5673	0.886	9.666	0.000	6.830	10.305
RH_8	-6.3745	0.321	-19.843	0.000	-7.004	-5.745
T9	-13.4323	1.560	-8.612	0.000	-16.490	-10.375
T_out	-6.1772	0.825	-7.484	0.000	-7.795	-4.559
Windspeed	1.0866	0.360	3.021	0.003	0.381	1.792
Visibility	0.2045	0.062	3.305	0.001	0.083	0.326
	========	=======	========			=======

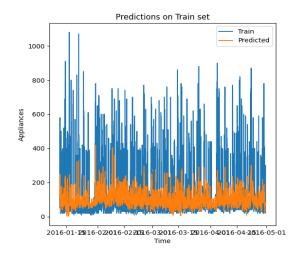
Fig26: Multiple Linear Regression model features

R-squared (uncentered):	0.557
Adj. R-squared (uncentered):	0.556
F-statistic:	1237.
Prob (F-statistic):	0.00
Log-Likelihood:	-94423.
AIC:	1.889e+05
BIC:	1.890e+05

Fig27: Performance metrics

Looking at the final model, the adjusted R-squared and R-squared values have increased better than the full model and the model's accuracy 0.557 which comparatively better than the previous model.

The predictions using the developed model are performed and the results of the performance of the model on train data are shown below.



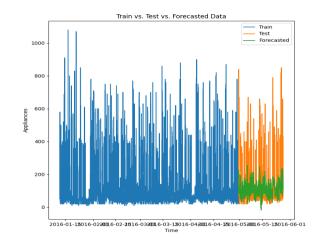


Fig28: Predictions on train data

Fig29: Plot of train vs. test vs. Forecasted

The predicted data and forecasted data closely follows the path of the original data but it doesn't completely track the drastic increase in the data.

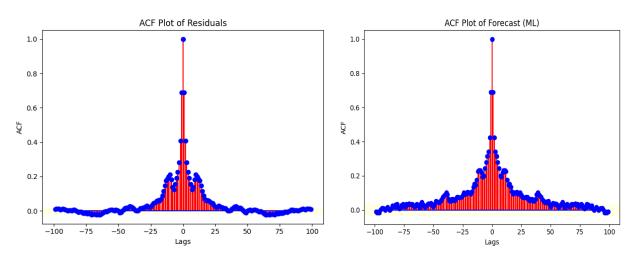


Fig30: ACF plot of residuals

Fig31: ACF plot of forecast errors

The ACF plot of residuals shows the data converges after lag 25 and in bigger picture of lags the ACF of the residual may look like a white noise. To confirm whether the model is a better for forecasting or not let's comapre the performance metrics.

Performance metrics:

The MSE value of predictions are less comparatively (9168.34). The Q-value of Box-pierce test is comparatively less (12733.0) with p-value 0.0. It shows the residual can be white for the method. The mean of the residual is close to zero (0.053) and variance is 9168.34. The RMSE value of predictions is 95.75. All these performance metrics shows the Multiple Linear regression could be a better model which can be used for forecasting the data.

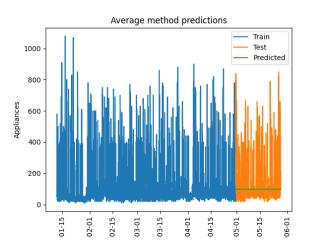
The performance of this method on test data is given below:

MSE: 7565.88; Q-value: 3753.47; Mean of forecast: -8.80; Variance: 7488.36; RMSE:86.98

As expected, the MSE and mean of forecast errors are less which means the method did work well with the test data.

BASE MODELS:

Average Method:



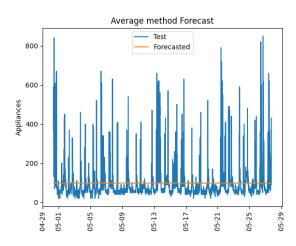


Fig32: Average method plot

Fig33: AM: Test vs. Forecasted

Looking at the plot of average method, the method is not better fit for forecasting the values for the data because it predicts the values as flat curve. The value remains throughout the test data while the original data has more spikes than the forecasted.

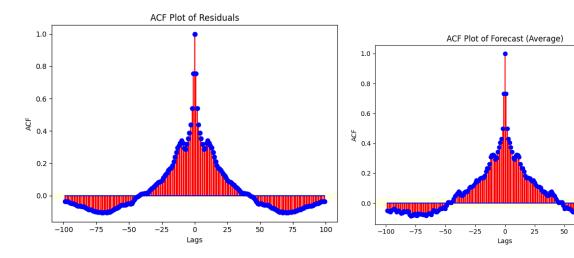


Fig34: ACF plot of residuals (Average)

Fig35: ACF plot of forecast errors

The ACF plot of the residuals clearly shows that the ACF values are not converging throughout the given lags. And the ACF of forecast errors are also not a white noise. So, the model can't be a better fit for the dataset.

Performance metrics:

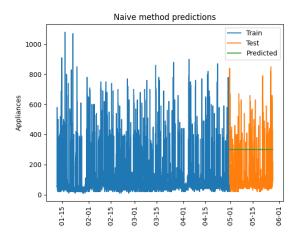
The Q-value of Box-pierce test is high (21037.19) with p-value 0.0. It shows the residual is not white for the Average method. The MSE value of predictions are high (11074.34). The mean of the residual is not close to zero (-2.008) and variance is 11070.31. The RMSE value of predictions is 95.750. All these performance metrics shows the average method is not a significant model to forecast the data.

The performance of this method on test data is given below:

MSE: 8290.72; Q-value: 4991.83; Mean of forecast: -1.64; Variance: 8288; RMSE: 86.98

As expected, the MSE and mean od forecast errors are high which means the method didn't work well with the test data.

Naive Method:



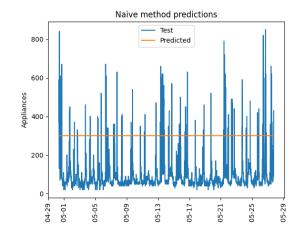


Fig36: Plot of Naïve method

Fig37: Plot of test vs. Forecasted

Looking at the plot of naive method, the method may not better fit for forecasting the values for the data because it predicts the values as flat curve. The value remains throughout the test data while the original data has more spikes than the forecasted.

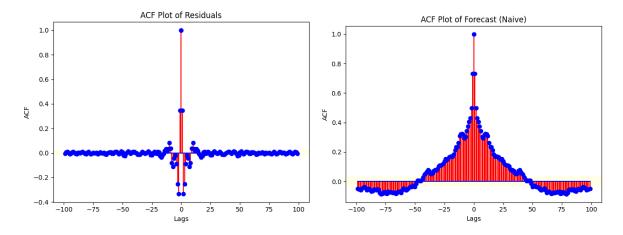


Fig38: ACF plot of residuals

Fig39: ACF plot of forecast

The ACF plot of the residuals clearly shows that the ACF values are converging throughout the given lags. This can also be a better model, let's dicuss the performance metrics below.

Performance metrics:

The Q-value of Box-pierce test is less comapred to average method (4799.30) with p-value 0.0. It shows the residual can be white for the naive method. The MSE value of predictions are high (10183.72). The mean of the residual is close to zero (0.0006) and variance is 10183.72. The RMSE value of predictions is 100.91. All these performance metrics shows the Naive method is can be a significant model to forecast the data.

The performance of this method on test data is given below:

MSE: 49750.34; Q-value 5014.17; Mean of forecast: -1.64; Variance: 8288; RMSE: 223.04

As expected, the MSE and mean of forecast errors are less compared to average method which means the method may work well with the test data (extended).

Drift Method:

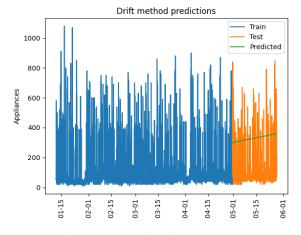


Fig40: Plot of drift method

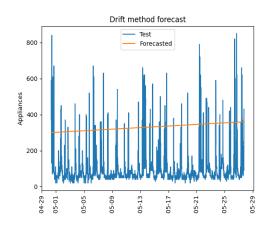


Fig41: Test vs. Forecasted

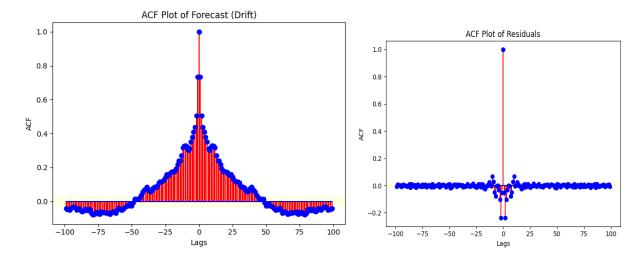


Fig41: ACF plot of forecast errors

Fig42: ACF plot of Residuals

The plot of drift method shows the forecasted data didn't trace the exact path of provided test data. But contradicting to the plot, ACF of residuals shows a white noise. While the forecast error's ACF doesn't converge over the lags. Let's discuss the performance measures to get a better understanding.

Performance metrics:

The Q-value of Box-pierce test is less comapred to average method (1128.89) with p-value 0.0. It shows the residual can be white for the drift method. The MSE value of predictions are less (5385.52). The mean of the residual is close to zero (-0.010) and variance is 5385.52. The RMSE value of predictions is 73.386. All these performance metrics shows the Naive method is can be a significant model to forecast the data.

The performance of this method on test data is given below:

MSE: 62980.33; Q-value: 5129.25; Mean of forecast: -233; Variance: 8396.18; RMSE: 250.958

As expected, the MSE and mean of forecast errors are less compared to average method which means the method may work well with the test data (extended).

Simple Exponential Smoothening Method:

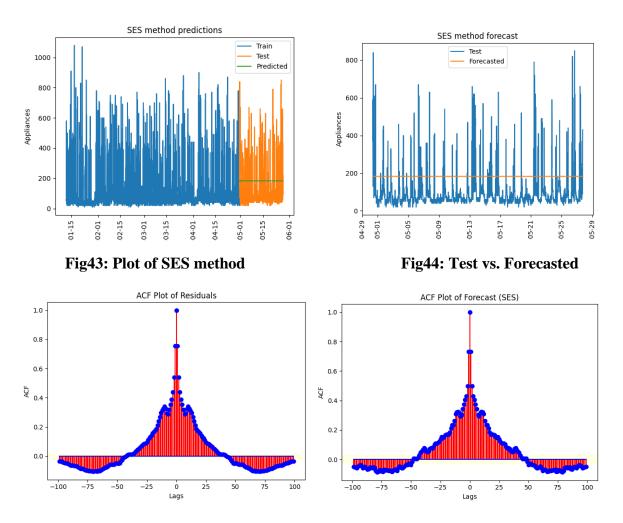


Fig45: ACF plot of residuals

Fig46: ACF plot of forecast error

Looking at the plot of SES method, the method may not better fit for forecasting the values for the data because it predicts the values as flat curve. The value remains throughout the test data while the original data has more spikes than the forecasted.

The ACF plot of the residuals clearly shows that the ACF values are not converging throughout the given lags. And the ACF of forecast errors are also not a white noise. So, the model can't be a better fit for the dataset.

Performance metrics:

The Q-value of Box-pierce test is high (21049.19) with p-value 0.0. It shows the residual is not white for the SES method. The MSE value of predictions are high (18280.09). The mean of the residual is not close to zero (-84.93) and variance is 11067.19. The RMSE value of predictions is 135.20. All these performance metrics shows the SES method is not a significant model to forecast the data.

The performance of this method on test data is given below:

MSE: 15784.70; Q-value: 5014.17; Mean of forecast: -86.58; Variance: 8288.01; RMSE: 125.63

As expected, the MSE and mean od forecast errors are high which means the method didn't work well with the test data

ARMA, ARIMA AND SARIMA MODELS:

The order determination for the model can be done visualizing the GPAC table.

GPAC:

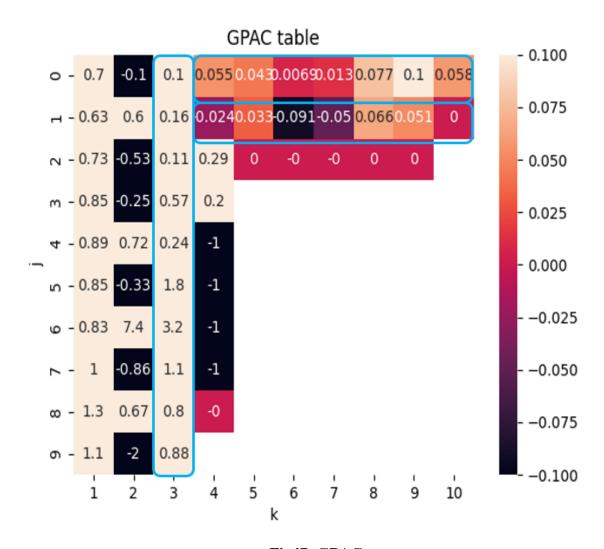


Fig47: GPAC

The GPAC table shows an order of (3,0) and (3,1) based on the column of constants and row of zeros.

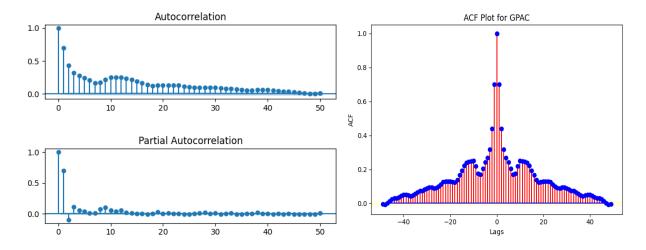


Fig48: ACF/PACF plot of GPAC

Fig49: ACF plot of GPAC

Looking at the plots of ACF/PACF generated for GPAC, we can see the ACF values converges over the lags.

ARMA (3,0):

Parameter estimation for the ARMA (3,0) is performed using the LMA algorithm.

```
The AR coefficient a0 is: 0.8826251619682011
The AR coefficient a1 is: -0.18060249327214198
The AR coefficient a2 is: 0.19154822230647062
```

Fig50: ARMA (3,0) parameter estimation

```
Confidence interval:

0 1

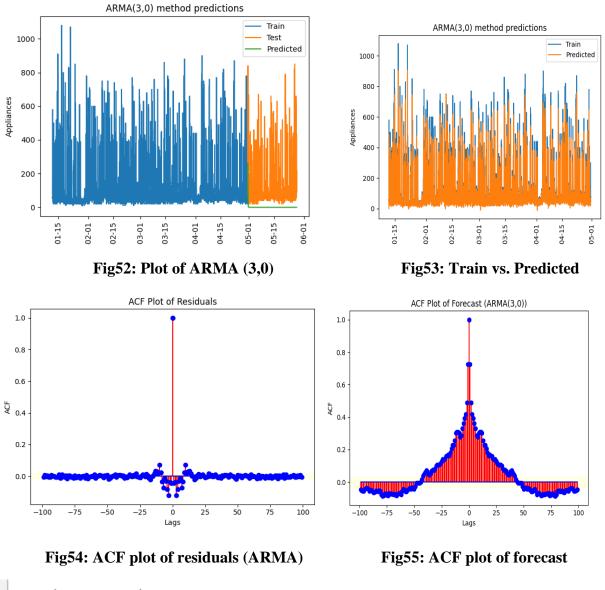
ar.L1.Appliances 0.867311 0.897940

ar.L2.Appliances -0.201005 -0.160200

ar.L3.Appliances 0.176234 0.206862
```

Fig51: Confidence Interval of ARMA (3,0)

The parameters estimated for the ARMA process doesn't include zero in their confidence interval. It shows the estimated parameters are statistically significant.



```
Covariance matrix
                     ar.L1.Appliances
                                                          ar.L3.Appliances
                                        ar.L2.Appliances
 ar.L1.Appliances
                        6.105410e-05
                                              -0.000054
                                                              7.277838e-07
 ar.L2.Appliances
                       -5.374990e-05
                                               0.000108
                                                             -5.374481e-05
 ar.L3.Appliances
                        7.277838e-07
                                              -0.000054
                                                              6.104928e-05
 Standard error: ar.L1.Appliances
                                       0.007814
 ar.L2.Appliances
                      0.010410
 ar.L3.Appliances
                      0.007813
```

Fig56: Covariance matrix and standard error

Looking at the ACF plot of residuals of ARMA(3,0) process, the ACF values are white which can be considered as a better model for forecast. But the ACF values after forecasting on test data doesn't look like white. So, it shows the model won't perform well on test data.

The plot of train versus predicted data shows the model has captured the data of train data well but looking at the forecasted values, the model didn't perform well due to the bias in the estimators.

Performance metrics:

The Q-value of Box-pierce test is high (414.215047) with p-value close to zero. The MSE value of predictions are less than our few other models (4846.33). The mean of the residual is not close to zero (10.449) and variance is 4737.13. The RMSE value of predictions is 69.615. All these performance metrics shows the model cannot be a significant model to forecast the data.

The performance of this method on test data is given below:

```
MSE: 17223.51; Q-value: 4824.96; Mean of forecast: 95.71; Variance: 8062; RMSE: 125.63
```

As expected, the MSE and mean of forecast errors are high which means the method didn't work well with the test data

ARMA (3,1):

Parameter estimation for the ARMA (3,1) is performed using the LMA algorithm.

```
The AR coefficient a0 is: 1.6812121990548763

The AR coefficient a1 is: -0.8575867746710102

The AR coefficient a2 is: 0.17117671394561582

The MA coefficient a0 is: -0.8748667168727922
```

Fig57: ARMA (3,1) parameter estimation

```
Confidence interval:

0 1

ar.L1.Appliances 1.660670 1.701755

ar.L2.Appliances -0.885630 -0.829544

ar.L3.Appliances 0.154574 0.187779

ma.L1.Appliances -0.889873 -0.859860
```

Fig58: Confidence Interval of ARMA (3,1)

The parameters estimated for the ARMA process doesn't include zero in their confidence interval. It shows the estimated parameters are statistically significant.

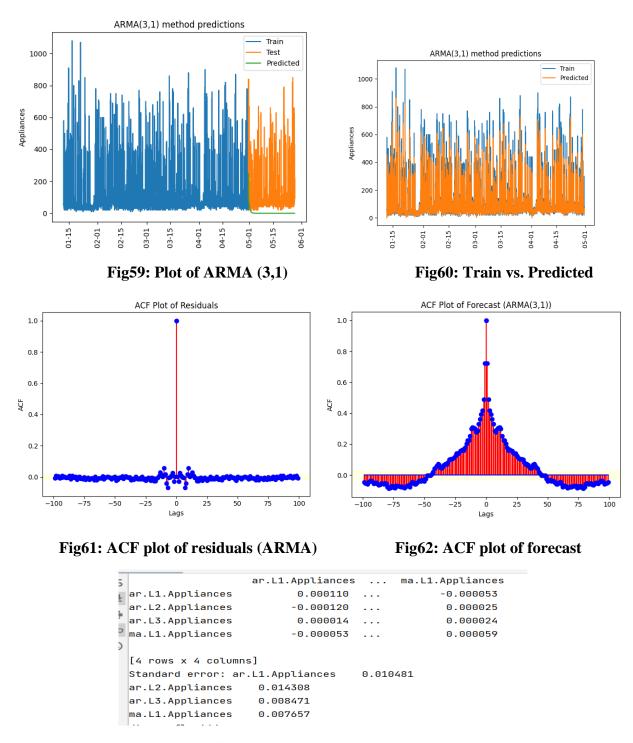


Fig63: Covariance matrix and standard error

Looking at the ACF plot of residuals of ARMA(3,1) process, the ACF values are white which can be considered as a better model for forecast. But the ACF values after forecasting on test data doesn't look like white. So, it shows the model won't perform well on test data.

The plot of train versus predicted data shows the model has captured the data of train data well but looking at the forecasted values, the model didn't perform well due to the bias in the estimators.

Performance metrics:

The Q-value of Box-pierce test is less (24.179) with p-value close to zero. The MSE value of predictions are less than our few other models (4594.58). The mean of the residual is not close to zero (4.090) and variance is 4577.84. The RMSE value of predictions is 67.78. All these performance metrics shows the model can be a significant model to forecast the data.

The performance of this method on test data is given below:

MSE: 16830.1964; Q-value: 4824.96; Mean of forecast: 93.73; Variance: 8043; RMSE: 129.73

As expected, the MSE and mean of forecast errors are high which means the method didn't work well with the test data

The ARMA models developed didn't perform well on the test data. Let's try a SARIMA model to check whether we could find a better model or not.

SARIMA Model:

Tried constructing a SARIMA model of (3,0,0)X(0,1,144) but the model was not computationally easy to work on the system. Hence, the seasonality period was reduced to 12 a model of SARIMA(3,0,0)X(0,1,0,12) was constructed.

P D	p. 00	10 0		SARIMAX	Results			
0	Dep. Varia Model:			0)x(0, 1, 0	, 12) Log	Observations: Likelihood		15788
y	Date: Time: Sample:		,	Wed, 08 Dec 15:	2021 AIC 22:27 BIC 0 HQIC	;		187598.919 187629.584 187609.068
	Covariance	=========			15788 opg ===================================	[0.025	0.9751	
	ar.L3	0.7510 -0.2198 0.1154	0.004 0.005		0.000	0.743 -0.230 0.106 8493.509	0.759 -0.209 0.125	
	Ljung-Box Prob(Q):		33.821	0.48 0.49 0.82	Jarque-Bera Prob(JB): Skew:		10555	==== 6.90 0.00 0.08

Fig64: SARIMA model

Looking at the result of SARIMA model constructed, the estimated parameters are under the confidence interval not inclusive of zero. Hence, the estimated parameters are significant but the AIC, BIC values are high which shows the model may not be a good one.

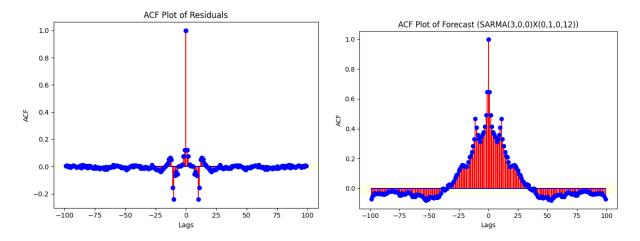


Fig65: ACF plot of residuals

Fig66: ACF plot of forecast

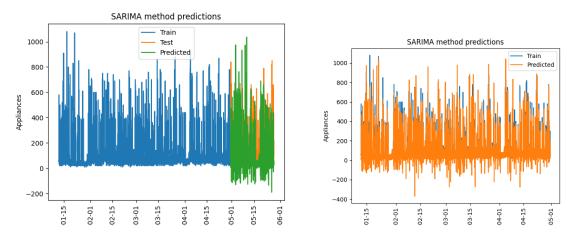


Fig67: Plot of the SARIMA

Fig68: Plot of train vs. predicted

Looking at the ACF plot of residuals, the ACF values are converging more similar to white noise. And the ACF of forecast errors also converge more to zero than the other models. The plot of test versus forecasted values shows that the model has tried capturing the values almost similarly. This shows that the SARIMA model could work better than other models if the computer was computationally high to do seasonal ARIMA of 144.

Performance metrics:

The Q-value of Box-pierce test is less (332.953388) with p-value close to zero. The MSE value of predictions are less than our few other models (5232.14). The mean of the residual is close to zero (0.065) and variance is 5232.14. The RMSE value of predictions is 72.33. All these performance metrics shows the model can be a significant model to forecast the data.

The performance of this method on test data is given below:

MSE: 21737.43; Q-value: 4351.759; Mean of forecast: -0.67; Variance: 5232.14; RMSE: 147.43

As expected, the MSE of forecast errors are high which means the method didn't work well with the test data

The SARIMA model has more chances to out perform the other models. Unfortuantely, seaonality of 12 wasn't effective much to forecast the data.

FINAL MODEL SELECTION:

Comparing all the models to select the best model.

METR ICS	HOL TS WINT ER	ML R	AVG.	NAÏ VE	DRI FT	SES	ARMA (3,0)	ARMA (3,1)	SARI MA
MSE TRAIN	62632. 91	9168 .34	.34	10183 .72	5385	.09	4846.3	4594.58 1	5232. 14
Q- VALUE	20191. 89	1273 3.0	21037 .19	4799. 30	1128 .89	21049 .19	414.21 5047	24.179	332.8 8
MEAN RESID	223.72	0.05	2.008	0.000 6	- 0.01 0	84.93	10.449	4.0905	0.06
VAR. RESID	12580. 21	9168 .34	11070 .31	10183 .72	5385	11067 .19	4737.1 34	4577.84	-0.67
RMSE TRAIN	250.26	95.7 5	95.75 0	100.9	73.3 86	135.2	69.615	67.78	72.33
MSE TEST	59846. 6	7565 .88	8290. 72	49750 .34	6298 0.3	15784 .7	17223	16830	21737 .4
RMSE TEST	244.63	86.9 8	86.98	223.0	250. 958	125.6	125.63	129.73	147.4 3

Considering the previous discussions, the ACF plot of residuals being white and less Q-values the models multiple linear regression, drift, ARMA and SARIMA seems to be better. Out of these models, considering the mean and MSE of residuals multiple linear regression, drift, ARMA and SARIMA has lesser values. It means the models predicted close to the actual values. Out of these four models, while looking at their performance on test data multiple linear regression seems to have lesser MSE value and when compared to drift and naïve method it traced the path of test data more closely.

Hence, the best model for the data forecasting is multiple linear regression.

FORECAST FUNCTION:

The forecast function for multiple linear regression can be written using the final 15 variables selected using OLS model summary.

H-STEP AHEAD PREDICTION:

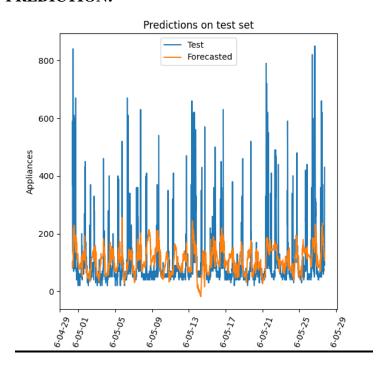


Fig69: Plot of test data

The h-step prediction on test data was conducted based on the forecast function developed. The forecast function has more closely followed the path of the test data and forecast on test data haven't covered the drastic increase or decrease of the values in the data, but it has captured better than the other models.

CONCLUSION

The Multiple Linear Regression model has been selected as the best model to predict the energy consumed in the household. The model was chosen based on the consideration of its performance on both the test and train data. Considering, other models in the competition with this model ARMA (3,1) had lower MSE on train data but on the test data the model didn't capture the exact data. While the SARIMA was limited due to computational complexities with the seasonality of 12 it performed well on train and test data but compared to the MSE on test data the Multiple Linear Regression model outperformed it too. The adjust R-squared was good (0.577) compared to the other models which were performing lesser than it.

The limitation of the selected model would be the model didn't capture well the drastic increase or decrease in the data values. To overcome this limitation SARIMA model with seasonality of 144 can be used on high computational systems and forecast more accurate results for the dataset. The future enhancement of the project would be implementing a SARIMA model with exact seasonal order or LSTM – a neural network-based model to approximate the energy consumption in households. For future modelling purposes, the data should be increased at least till one year and including more households to understand the variation in energy consumption. And variable to notify number of people in the house would also help to estimate the energy requirement for house with different dimensions.

APPENDIX

Steps to run the project file:

Run the Project_RM.py file to implement the project end-to-end.

Toolbox.py

```
import numpy as np
import pandas as pd
from pandas import Series
import matplotlib.pyplot as plt
from statsmodels.tsa.stattools import adfuller, kpss, pacf
import statsmodels.api as sm
import seaborn as sns
from scipy import signal
np.random.seed(12345)
#Function to Calculate rolling mean and variance
def cal rolling mean var(x, y):
    #calculating rolling mean and variance
    rolling mean=[]
    rolling variance=[]
    for i in range (1, len(x) + 1):
        result=np.mean(x[:i])
        result var=np.var(x[:i])
        rolling_mean.append(result)
        rolling variance.append(result var)
    print("Rolling mean:", rolling mean)
    print("Rolling variance:", rolling variance)
    print("*"*100)
    #Plotting mean
    plt.figure(figsize=(10,10))
    plt.plot(y,rolling mean, color='red')
    plt.ylabel("Rolling mean")
    plt.xlabel('Time')
    plt.xticks(y[::1000], rotation='vertical')
    plt.title('Plot of Rolling mean')
    plt.show()
    #Plotting variance
    plt.figure(figsize=(10,10))
    plt.plot(y,rolling variance, color="Purple")
    plt.xticks(y[::1000], rotation='vertical')
    plt.ylabel(f"Rolling variance")
    plt.xlabel('Time')
    plt.title('Plot of Rolling variance')
    plt.show()
#Function to perform ADF test
def ADF Cal(x):
 result = adfuller(x)
```

```
print("ADF Statistic: %f" %result[0])
 print('p-value: %f' % result[1])
 print('Critical Values:')
 for key, value in result[4].items():
    print('\t%s: %.3f' % (key, value))
#Function to perform KPSS test.
def kpss test(z):
    kpsstest = kpss(z, regression='c', nlags="auto")
    kpss output = pd.Series(kpsstest[0:3], index=['Test Statistic','p-
value','Lags Used'])
    for key, value in kpsstest[3].items():
        kpss output['Critical Value (%s)'%key] = value
    print (kpss output)
#First order differencing
def first order diff(l):
    diff=[]
    diff[0]=diff.append([np.nan])
    for j in range(1,len(l)):
        diff val=l[j]-l[j-1]
        diff.append(diff val)
    return Series(diff)
#Second order differencing
def second order diff(l):
    diff=[]
    diff[0]=diff.append([np.nan])
    diff[1] = diff.append([np.nan])
    for j in range(2,len(1)):
        diff val=l[j]-2*l[j-1]+l[j-2]
        diff.append(diff val)
    return Series(diff)
#Third order differencing
def third order diff(l):
    diff=[]
    diff[0]=diff.append([np.nan])
    diff[1] = diff.append([np.nan])
    diff[2]=diff.append([np.nan])
    for j in range (3, len(1)+2):
        diff val=l[j]-l[j-1]
        diff.append((diff val))
    return Series (diff)
#Function to calculate Corrrelation coefficient
def correlation coefficient cal(x, y):
    n=len(x)
    sum1=0
    sum2=0
    for i in x:
        sum1+=i
    meanx=sum1/n
    for j in y:
        sum2+=j
```

```
meany=sum2/n
    diff=0
    deno1=0
    deno2=0
    for i, j in zip(x,y):
        diff+=(i-meanx)*(j-meany)
        deno1+=(i-meanx)**2
        deno2+=(j-meany)**2
    den=(deno1)**0.5
    den1=(deno2)**0.5
    r=diff/(den*den1)
    return r
#Auto correlation Function
def ACF(x,lags):
    acfmean=np.mean(x)
    T=len(x)
    list1=[]
   prod1=0
    deno1=0
    for t in range (0, T):
        deno1 += (x[t] - acfmean) ** 2
    for 1 in range(0,lags):
        for t in range (1,T):
            prod1+=(x[t]-acfmean)*(x[t-1]-acfmean)
        acf=float(prod1/deno1)
        prod1=0
        list1.append(acf)
    print("ACF:", list1)
    return list1
#Function to estimate variance
def estimated var(x, k):
    sum=0
    for i in range(0,len(x)):
        sum+=i**2
    deno=1/(len(x)-k-1)
    var=np.sqrt((deno*sum))
    return var
#Function to calculate moving average
def movingaverage(data):
    m=int(input("Enter m:"))
    if m%2!=0:
       j = 0
       ma list =[]
       while (j+m)!=len(data)+1:
           sum = 0
           mean=0
           for i in range(j,j+m):
               sum+=data[i]
           mean=sum/m
           ma list.append(mean)
```

```
j+=1
           k = int((m - 1) / 2)
       return ma list,k
    elif m%2==0:
        fold=int(input("Folding order:"))
        if fold%2!=0:
            print("Invalid fold value(Fold should be even)")
        else:
            \dot{j} = 0
            ma list = []
            while (j + m) != len(data) + 1:
                sum = 0
                mean = 0
                for i in range(j, j + m):
                   sum += data[i]
                mean = sum / m
                ma list.append(mean)
                j += 1
            j=0
            final=[]
            while (j + fold) != len(ma list) + 1:
                sum = 0
                mean = 0
                for i in range(j, j + fold):
                    sum += ma list[i]
                mean = sum / fold
                final.append(mean)
                j += 1
            k=int(m/2)
            return final, k
#Function to generate arma process
def armaprocess GPAC():
    T=int(input("Enter number of samples"))
    mean=int(input("Enter the mean of white noise"))
    var=int(input("Enter variance of white noise"))
    na=int(input("Enter AR process order"))
    nb=int(input("Enter MA process order"))
    naparam=[0]*na
    nbparam=[0]*nb
    for i in range(0,na):
        naparam[i]=float(input(f"Enter the coefficient of AR:a{i+1}"))
    for i in range(0,nb):
        nbparam[i]=float(input(f"Enter the coefficient of MA:b{i+1}"))
    ar=np.r [1, naparam]
    ma=np.r [1,nbparam]
    arma process = sm.tsa.ArmaProcess(ar, ma)
    if mean==0:
        y=arma process.generate sample(T)
    else:
        mean y = mean* (1 + np.sum(nbparam)) / (1 + np.sum(naparam))
        y = arma process.generate sample(T, scale=np.sqrt(var) + mean y)
    return y
#Calculate Qvalue in the GPAC
```

```
def qvalue cal(y,an,bn):
    deno=[]
    k=an
    j=bn
    for a in range(k):
        deno.append([])
        for b in range(k):
            deno[a].append(y[np.abs(j+b)])
        j=j-1
    ddeno=round(np.linalq.det(deno),5)
    j=bn
    num=deno[:k-1]
    num.append([])
    for a in range(k):
        num[k-1].append(y[j+a+1])
    dnum=round(np.linalg.det(num),5)
    if ddeno==0:
        return float('inf')
    else:
        qval=dnum/ddeno
        return round(qval,4)
#Function to align Q-values in GPAC
def GPAC (y, k, j):
    q=[]
    for b in range(j):
        q.append([])
        for a in range (1, k+1):
            q[b].append(qvalue cal(y,a,b))
    gpac=np.array(q).reshape(j,k)
    gpactable=pd.DataFrame(gpac)
    c=np.arange(1,k+1)
    gpactable.columns=c
    print(gpactable)
    sns.heatmap(gpactable,annot=True)
    plt.xlabel('k')
    plt.ylabel('j')
    plt.title('GPAC table')
    plt.show()
#ACF plot
def acf plot(lags,acf,samples):
    x = np.arange(0, lags)
    m = 1.96 / np.sqrt(len(samples))
    plt.stem(x,acf, linefmt='r-', markerfmt='bo', basefmt='b-')
    plt.stem(-1 *x,acf,linefmt='r-',markerfmt='bo', basefmt='b-')
    plt.title("ACF")
    plt.axhspan(-m, m, alpha=.2, color='yellow')
    plt.xlabel('Lags')
    plt.ylabel('ACF')
    plt.show()
#Professor's ACF PACF plot
from statsmodels.graphics.tsaplots import plot acf , plot pacf
def ACF PACF Plot(y,lags):
 acf = sm.tsa.stattools.acf(y, nlags=lags)
 pacf = sm.tsa.stattools.pacf(y, nlags=lags)
```

```
fig = plt.figure()
 plt.subplot(211)
plt.title('ACF/PACF of the raw data')
 plot acf(y, ax=plt.gca(), lags=lags)
 plt.subplot(212)
 plot pacf(y, ax=plt.gca(), lags=lags)
 fig.tight layout(pad=3)
plt.show()
#LM algorithm
def WN(teta,na,y):
    numerator=[1]+list(teta[na:])
    denominator=[1]+list(teta[:na])
    if len(numerator)!=len(denominator):
        while len(numerator) < len(denominator):</pre>
            numerator.append(0)
        while len(denominator) < len(numerator):</pre>
            denominator.append(0)
    system=(denominator, numerator, 1)
    t, e=signal.dlsim(system, y)
    e=[i[0] for i in e]
    return np.array(e)
def step0(na,nb):
    teta o=np.zeros(shape=(na+nb,1))
    return teta o.flatten()
def step1(delta,na,nb,teta,y):
    e teta=WN(teta,na,y)
    SSE O=np.dot(e teta.T,e teta)
    X = []
    for i in range(na+nb):
        teta delta = teta.copy()
        teta delta[i]=teta[i]+delta
        en=WN(teta delta,na,y)
        Xi=(e teta-en)/delta
        X.append(Xi)
    Xfinal=np.transpose(X)
    A=np.dot(Xfinal.T,Xfinal)
    G=np.dot(Xfinal.T,e teta)
    return A, G, SSE O
def step2(A,G,mu,na,nb,teta,y):
    n=na+nb
    I=np.identity(n)
    dteta1=A+(mu*I)
    dteta inv=np.linalg.inv(dteta1)
    delta teta=np.dot(dteta inv,G)
    teta new=teta+delta teta
    e=WN(teta new,na,y)
    SSE new=np.dot(e.T,e)
    if np.isnan(SSE new):
        SSE new=10**10
    return SSE new,delta teta,teta_new
def step3(max iter, mu, delta, epsilon, mu max, na, nb, y):
    num iter=0
```

```
teta=step0(na,nb)
    SSE=[]
    while num iter<max iter:
        A, G, SSE O=step1 (delta, na, nb, teta, y)
        if num \overline{i}ter == 0:
            SSE.append(SSE 0)
        SSE new, delta teta, teta new=step2(A,G,mu,na,nb,teta,y)
        SSE.append(SSE new)
        if SSE new<SSE O:</pre>
             if np.linalg.norm(delta teta)<epsilon:</pre>
                 teta hat=teta new
                 var=SSE new/(len(y)-A.shape[0])
                 A inv=np.linalq.inv(A)
                 cov=var*A inv
                 return SSE, cov, teta hat, var
            else:
                 teta=teta new
                mu=mu/10
        while SSE new>=SSE O:
            mu=mu*10
            if mu>mu max:
                print('Mu\'s maximum limit is exceeded')
                return None, None, None, None
            SSE new, delta teta, teta new = step2(A, G, mu, na,nb, teta, y)
        num iter+=1
        teta = teta new
        if num iter>max iter:
            print('Maximum iterations exceeded')
            return None, None, None, None
with np.errstate(divide='ignore'):
    np.float64(1.0) / 0.0
#Confidence interval
def conf int(cov,params,na,nb):
    print("Confidence Interval:")
    for i in range(na):
        pos=params[i]+2*np.sqrt(cov[i][i])
        neg=params[i]-2*np.sqrt(cov[i][i])
        print (neg, f'<a{i+1}<', pos)</pre>
    for i in range(nb):
        pos=params[na+i]+2*np.sqrt(cov[na+i][na+i])
        neg=params[na+i]-2*np.sqrt(cov[na+i][na+i])
        print (neg, f'<b{i+1}<', pos)</pre>
#zero-poles cancellation
def zero poles(params, na):
    y den=[1]+list(params[:na])
    e num=[1]+list(params[na:])
    zeros=np.roots(e num)
    poles=np.roots(y den)
    print("The roots of numerator are", zeros)
    print("The roots of denominator are", poles)
#Plot of SSE
def plotSSE(SSE):
    iter=np.arange(0,len(SSE))
```

```
plt.plot(iter, SSE, label='SSE')
    plt.xlabel('Number of iterations')
    plt.ylabel('SSE')
    plt.title('SSE vs. #of Iterations')
    plt.legend()
    plt.show()
#Plot one step ahead prediction plot
def onestepplot(y, y hat):
    plt.plot(y, label='Actual/Train')
    plt.plot(y hat, label='one step predictions')
    plt.title('Plot of Actual/Train vs. One step prediction')
    plt.legend()
    plt.xlabel('Samples')
    plt.ylabel('Value')
    plt.show()
#Chi-square test
from scipy.stats import chi2
def chi test(na, nb, lags, Q, e):
    DOF=lags-na-nb
    alpha=0.01
    chi critical=chi2.ppf(1-alpha,DOF)
    if Q<chi critical:</pre>
       print('The residuals are white')
    else.
        print('The residual is not white')
    lbvalue,pvalue=sm.stats.acorr ljungbox(e,lags=[lags])
    print('From acorr ljungbox test')
    print(lbvalue)
    print(pvalue)
#differencing Professor's code
def difference(y,interval=1):
    diff=[]
    for i in range(interval, len(y)):
        value=y[i]-y[i-interval]
        diff.append(value)
    return diff
#SARIMA simulation
def sarima model():
    T=int(input('Enter number of samples'))
    mean=eval(input('Enter mean of white nosie'))
    var=eval(input('Enter variance of white noise'))
    na = int(input("Enter AR process order"))
    nb = int(input("Enter MA process order"))
    naparam = [0] * na
    nbparam = [0] * nb
    for i in range(0, na):
        naparam[i] = float(input(f"Enter the coefficient of AR:a{i + 1}"))
    for i in range(0, nb):
        nbparam[i] = float(input(f"Enter the coefficient of MA:b{i + 1}"))
    while len(naparam) < len(nbparam):</pre>
        naparam.append(0)
    while len(nbparam) < len(naparam):</pre>
        nbparam.append(0)
```

```
ar = np.r [1, naparam]
    ma = np.r [1, nbparam]
    e=np.random.normal(mean,np.sqrt(var),T)
    system=(ma, ar, 1)
    t, process=signal.dlsim(system, e)
    return process
#Base models
#average
def avg one(x):
    train=[]
    for i in range(0, len(x)):
        mean=np.mean(x[0:i])
        train.append(mean)
    return train
def avg hstep(train, test):
    forecast=np.mean(train)
    pred=[]
    for i in range(len(test)):
        pred.append(forecast)
    return pred
```

Project_RM.py:

```
import matplotlib.pyplot as plt
import numpy as np
import statsmodels.tsa.arima model
import statsmodels.tsa.holtwinters as ets
from Toolbox import *
import pandas as pd
from sklearn.model selection import train_test_split
from statsmodels.tsa.seasonal import STL
from sklearn.metrics import mean squared error
from statsmodels.stats.diagnostic import acorr ljungbox
import statsmodels.api as sm
from numpy import linalg as la
import warnings
warnings.filterwarnings('ignore')
#6.a: Preprocessing dataset
data=pd.read csv('energydata complete.csv')
print('Dataset:\n', data.head())
print('Dataset information:\n', data.info())
print('Dataset don\'t have null values')
data.date=pd.to datetime(data.date)
data.set index('date',inplace=True)
print('Let\'s look at the end of the data:\n', data.tail())
#6.b: dependant variable vs. time
print('Dependant variable:Appliances')
plt.plot(data.index,data.Appliances,label='Dependant variable')
plt.xlabel('Time')
plt.ylabel('Appliance Energy use in Wh')
plt.title('Plot of Dependant variable (Appliances) versus Time')
plt.xticks(data.index[::1000], rotation='vertical')
```

```
plt.tight layout()
plt.legend()
plt.show()
#6c: ACF/PACF of dependent variable
ACF PACF Plot(data.Appliances, 400)
print('ACF plot of dependent variable (symmetric)')
acf data=ACF(data.Appliances, 100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(data.Appliances))
plt.stem(x,acf data,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf data,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Original data')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#6d:Correlation Matrix with seaborn heatmap with the Pearson's correlation
coefficient.
cor=data.corr()
sns.heatmap(cor, vmin=-1, vmax=1, center=0, cmap='PiYG')
plt.title("Heatmap of dataset", fontsize =20)
plt.show()
#6e:split the dataset into train, test set (80:20)
#split the entire dataset into train and test set
train, test=train test split(data, test size=0.2, shuffle=False)
#7: stationarity test
#Check rolling mean and variance
cal rolling mean var(data.Appliances, data.index)
#The mean and variance are having a flat plot but the mean is not at 0.
#It looks like data need to be differenced
#ADF test
ADF Cal(data.Appliances)
#p-value is 0.000, the data is stationary
#kpss test
kpss test(data.Appliances)
#Data is stationary
#seaonal Differencing is required on data to make the rolling mean at 0
#interval of 144 is used since data has spike at every 144 lags of ACF/PACF
plot
diff=difference(data.Appliances,interval=144)
diff df=pd.DataFrame(diff,index=data.index[144:])
diff df.rename(columns={0:'Appliances'},inplace=True)
plt.plot(diff df.index,diff df.Appliances,label='Differenced')
plt.xlabel('Time')
plt.ylabel('Appliance Energy use in Wh')
plt.title('Plot of Dependant variable (differenced) versus Time')
plt.xticks(data.index[::1000], rotation='vertical')
```

```
plt.tight layout()
plt.legend()
plt.show()
#ACF/PACF
ACF PACF Plot(diff df, 100)
#stationarity
cal rolling mean var(diff df, diff df.index)
ADF Cal(diff df)
kpss test(diff df)
#The data is stationary
#8:Time series Decomposition
Appliances=data['Appliances']
Appliances=pd.Series(np.array(data['Appliances']),index =
pd.date range('2016-01-11 17:00:00',periods= len(Appliances)))
STL=STL(Appliances)
res=STL.fit()
fig=res.plot()
plt.xlabel("Iterations")
plt.tight layout()
plt.show()
T=res.trend
S=res.seasonal
R=res.resid
plt.plot(T, label="Trend")
plt.plot(R, label="Residual")
plt.plot(S, label="Seasonal")
plt.xlabel("Iterations")
plt.ylabel("STL")
plt.legend()
plt.title("Trend, Seasonality and residuals of data")
plt.show()
#Strength of trend
var=1-(np.var(R)/np.var(T+R))
Ft=np.max([0,var])
print("Strength of trend:",Ft)
#Strength of seasonality
var1=1-(np.var(R)/np.var(S+R))
Fs=np.max([0,var1])
print("Strength of seasonality:",Fs)
#seasonally adjusted data
seasonally adj=Appliances-S
plt.plot(data.index,data.Appliances,label="Original")
plt.plot(data.index, seasonally adj, label="adjusted")
plt.xlabel("Time")
plt.xticks(data.index[::4000])
plt.ylabel("Appliances")
plt.title("Seasonally adjusted vs. Original")
plt.legend()
plt.show()
```

```
#detrended data
detrended=Appliances-T
plt.plot(data.index, data.Appliances, label="Original")
plt.plot(data.index, detrended, label="Detrended")
plt.xlabel("Time")
plt.xticks(data.index[::4000])
plt.ylabel("Appliances")
plt.title("Detrended vs. Original Data")
plt.legend()
plt.show()
# Holt-Winters method
print(data.columns)
X=data[['lights', 'T1', 'RH 1', 'T2', 'RH 2', 'T3', 'RH 3', 'T4',
       'RH 4', 'T5', 'RH 5', 'T6', 'RH 6', 'T7', 'RH 7', 'T8', 'RH 8', 'T9',
       'RH 9', 'T out', 'Press mm hg', 'RH out', 'Windspeed', 'Visibility',
       'Tdewpoint', 'rv1', 'rv2']]
y=data['Appliances']
x train, x test, y train, y test=train test split(X, y, test size=0.2, shuffle=Fals
holtw= ets.ExponentialSmoothing(y train, damped trend= True, trend='add',
seasonal='add', seasonal periods=144).fit()
#HW prediction on train set
holtw predt=holtw.forecast(steps=len(y_train))
holtw dft=pd.DataFrame(holtw predt,columns=['Appliances']).set index(y train.
index)
#HW prediction on test set
holtw pred=holtw.forecast(steps=len(y test))
holtw df=pd.DataFrame(holtw pred,columns=['Appliances']).set index(y test.ind
ex)
#plot of HW model
plt.figure(figsize=(8,8))
plt.plot(y train.index,y train, label='Train')
plt.plot(y test.index,y test, label='Test')
plt.plot(holtw df.index,holtw df.Appliances,label='Holts winter prediction')
plt.legend()
plt.xlabel("Time")
plt.ylabel("Appliances")
plt.title("Holts winter model")
plt.show()
#Model performance on train and test data
#MSE
HW train mse=mean squared error(y train, holtw dft.Appliances)
print('MSE of Holts Winter method on train data:', HW train mse)
HW test mse=mean squared error(y test,holtw df.Appliances)
print('MSE of Holts Winter method on test data:', HW test mse)
#residual error
HW reserror=y train-holtw dft.Appliances
#Forecast error
HW foerror=y test-holtw df.Appliances
```

```
#ACF
acf hw res=ACF(HW reserror.values,70)
x=np.arange(0,70)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf hw res,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf hw res,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals (HW)')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf hw fore=ACF(HW foerror.values,70)
x=np.arange(0,70)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf hw fore,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf hw fore,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast error (HW)')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#0-value
hotl q t=sm.stats.acorr ljungbox(HW reserror, lags=5,return df=True)
print('Q-value (residual):', hotl q t)
lbvalue=sm.stats.acorr ljungbox(HW foerror,lags=5,return df=True)
print('Q-value (Forecast):\n', lbvalue)
#Error mean and variance
print('Holts winter: Mean of residual error is', np.mean(HW reserror), 'and
Forecast error is',np.mean(HW foerror))
print('Holts winter: Variance of residual error is',np.var(HW reserror),'and
Forecast error is',np.var(HW foerror))
#RMSE
HW train rmse=mean squared error(y train, holtw dft.Appliances, squared=False)
print('RMSE of Holts Winter method on train data:',HW train rmse)
HW test rmse=mean squared error(y test, holtw df.Appliances, squared=False)
print('RMSE of Holts Winter method on test data:',HW test rmse)
#10: Feature selection and collinearity
X mat=x train.values
Y=y train.values
X svd=sm.add constant(X mat)
H=np.matmul(X svd.T,X svd)
s,d,v=np.linalg.svd(H)
print('Singular Values: ',d)
#Condition number
print("The condition number is ",la.cond(X svd))
#the condion number is high. Collinearity exists, so we need to remove the
features using backward regression
```

```
#Feature selection
x train ols=sm.add constant(x train)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove rv1 and rv2 - high p-value
x train ols.drop(['rv1','rv2'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove const - high p-value
x train ols.drop(['const'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove T7 - high p-value
x train ols.drop(['T7'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove RH 7 - high p-value
x train ols.drop(['RH 7'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove RH 5 - high p-value
x train ols.drop(['RH 5'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove T5 - high p-value
x train ols.drop(['T5'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove RH out - high p-value
x train ols.drop(['RH out'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove Tdewpoint - high p-value
x_train_ols.drop(['Tdewpoint'],axis=1,inplace=True)
model=sm.OLS(y_train,x_train_ols).fit()
print(model.summary())
#Remove RH 9 - high p-value
x train ols.drop(['RH 9'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove T1-high std. error
x train ols.drop(['T1'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#Remove Press mm hg- high p-value
```

```
x train ols.drop(['Press_mm_hg'],axis=1,inplace=True)
model=sm.OLS(y train,x train ols).fit()
print(model.summary())
#The collinearity is removed and the best model is defined above
#12. Multiple Linear Regression
print('The best features are', x train ols.columns)
#Prediction on train data
pred train=model.predict(x train[['lights', 'RH_1', 'T2', 'RH_2', 'T3',
'RH 3', 'T4', 'RH 4', 'T6',
       'RH 6', 'T8', 'RH 8', 'T9', 'T out', 'Windspeed', 'Visibility']])
#Residual error
ml res=y train-pred train
#Prediction on test data
pred test=model.predict(x test[['lights', 'RH 1', 'T2', 'RH 2', 'T3', 'RH 3',
'T4', 'RH 4', 'T6',
       'RH 6', 'T8', 'RH 8', 'T9', 'T out', 'Windspeed', 'Visibility']])
#Forecast error
ml fore=y test-pred test
#Plot of train data
plt.figure(figsize=(6,6))
plt.plot(y train.index,y train, label='Train')
plt.plot(pred train.index,pred train, label='Predicted')
plt.legend()
plt.xlabel("Time")
plt.ylabel("Appliances")
plt.title("Predictions on Train set")
plt.show()
#Plot of test data
plt.figure(figsize=(6,6))
plt.plot(y test.index,y test, label='Test')
plt.plot(pred test.index,pred test, label='Forecasted')
plt.legend()
plt.xlabel("Time")
plt.xticks(rotation=70)
plt.ylabel("Appliances")
plt.title("Predictions on test set")
plt.show()
#Plot of train and test data
plt.figure(figsize=(8,8))
plt.plot(y train.index,y train, label='Train')
plt.plot(y test.index,y test, label='Test')
plt.plot(pred test.index,pred test, label='Forecasted')
plt.legend()
plt.xlabel("Time")
plt.ylabel("Appliances")
plt.title("Train vs. Test vs. Forecasted Data")
plt.show()
```

```
#ACF
acf ml train=ACF(ml res,100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y train))
plt.stem(x,acf ml train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf ml train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf ml test=ACF(ml fore.values, 100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf_ml_test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf ml test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast (ML)')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#Model performance on train and test data
#MSE
ML train mse=mean squared error(y train,pred train)
print('MSE of MLR on train data:',ML train mse)
ML_test_mse=mean_squared_error(y_test,pred_test)
print('MSE of MLR on test data:',ML test mse)
#0-value
q ml train=sm.stats.acorr ljungbox(ml res, lags=5, return df=True)
print('Q-value (residual):',q ml train)
q mltest=sm.stats.acorr ljungbox(ml fore,lags=5,return df=True)
print('Q-value (Forecast):\n',q mltest)
#Error mean and variance
print('MLR: Mean of residual error is', np.mean(ml res), 'and Forecast error
is', np.mean(ml fore))
print('MLR: Variance of residual error is',np.var(ml res),'and Forecast error
is',np.var(ml fore))
#RMSE
ml train rmse=mean squared error(y train, pred train, squared=False)
print('RMSE of MLR method on train data:', ml train rmse)
ml test rmse=mean squared error(y test,pred test,squared=False)
print('RMSE of MLR method on test data:',ml test rmse)
#Base models
#Average method
train pred avg=avg one(y train)
test pred avg=avg hstep(y train,y test)
#Plot of average method
```

```
plt.plot(y train.index,y train,label='Train')
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index,test pred avg,label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('Average method predictions')
plt.legend()
plt.show()
#Plot of test vs predicted
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index, test pred avg, label='Forecasted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('Average method Forecast')
plt.legend()
plt.show()
#residual and forecast error
avg res=y train-train pred avg
avg fore=y test-test pred avg
#ACF
acf avg train=ACF(avg res.values[1:],100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y train))
plt.stem(x,acf avg train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf avg train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf avg test=ACF(avg fore.values, 100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf avg test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf avg test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast (Average)')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#Model performance on train and test data
#MSE
avg train mse=mean squared error(y train[1:],train pred avg[1:])
print('MSE of Average on train data:',avg train mse)
avg test mse=mean squared error(y test, test pred avg)
print('MSE of Average on test data:', avg test mse)
```

```
#0-value
q avg train=acorr ljungbox(avg res.values[1:], lags=5,
boxpierce=True, return df=True)
print('Q-value (residual):',q avg train)
q avgtest=sm.stats.acorr ljungbox(avg fore.values[1:],lags=5,boxpierce=True,r
eturn df=True)
print('Q-value (Forecast):\n',q avgtest)
#Error mean and variance
print('Average: Mean of residual error is', np.mean(avg res), 'and Forecast
error is',np.mean(avg fore))
print('Average: Variance of residual error is', np.var(avg res), 'and Forecast
error is',np.var(avg fore))
#RMSE
avg train rmse=mean squared error(y train[1:],pred train[1:],squared=False)
print('RMSE of Average method on train data:',avg_train_rmse)
avg test rmse=mean squared error(y test,pred test,squared=False)
print('RMSE of Average method on test data:',avg test rmse)
#Naive method
train naive=[]
for i in range(len(y train[1:])):
    train naive.append(y train.values[i-1])
test naive=[y train.values[-1] for i in y test]
naive fore= pd.DataFrame(test naive).set index(y test.index)
#Plot of naive method
plt.plot(y train.index,y train,label='Train')
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index,test naive,label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('Naive method predictions')
plt.legend()
plt.show()
#Plot of test vs predicted
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index,test naive,label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('Naive method predictions')
plt.legend()
plt.show()
#residual and forecast error
naive res=y train[1:]-train naive
naive fore=y test-test naive
acf naive train=ACF(naive res.values, 100)
x=np.arange(0,100)
```

```
m=1.96/np.sqrt(len(y train))
plt.stem(x,acf naive train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf naive train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf naive test=ACF(naive fore.values, 100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf_naive_test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf naive test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast (Naive)')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#Model performance on train and test data
#MSE
naive train mse=mean squared error(y train[1:],train naive)
print('MSE of Naive on train data:', naive train mse)
naive test mse=mean squared error(y test, test naive)
print('MSE of Naive on test data:', naive test mse)
#0-value
q naive train=acorr ljungbox(naive res, lags=5, boxpierce=True,
return df=True)
print('Q-value (residual):',q naive train)
q naivetest=acorr ljungbox(naive fore, lags=5, boxpierce=True, return df=True)
print('Q-value (Forecast):\n',q naivetest)
#Error mean and variance
print('Naive: Mean of residual error is', np. mean (naive res), 'and Forecast
error is', np.mean(naive fore))
print('Naive: Variance of residual error is', np.var(naive res), 'and Forecast
error is',np.var(naive fore))
naive train rmse=mean squared error(y train[1:],train naive,squared=False)
print('RMSE of Naive method on train data:',naive train rmse)
naive test rmse=mean squared error(y test, test naive, squared=False)
print('RMSE of Naive method on test data:',naive test rmse)
#Drift method
train drift = []
value = 0
for i in range(len(y train)):
    if i > 1:
        slope val = (y train[i - 1] - y train[0]) / (i-1)
        y predict = (slope_val * i) + y_train[0]
        train drift.append(y predict)
```

else:

continue

```
test drift= []
for h in range(len(y test)):
    slope_val = (y_train.values[-1] - y train.values[0] ) /( len(y train) - 1
    y predict= y train.values[-1] + ((h +1) * slope val)
    test drift.append(y predict)
#Plot of drift method
plt.plot(y train.index,y train,label='Train')
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index,test drift,label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('Drift method predictions')
plt.legend()
plt.show()
#Plot of test vs predicted
plt.plot(y test.index,y test,label='Test')
plt.plot(y_test.index,test_drift,label='Forecasted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('Drift method forecast')
plt.legend()
plt.show()
#residual and forecast error
drift res=y train[2:]-train drift
drift fore=y test-test drift
#ACF
acf drift train=ACF(drift res.values, 100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y train))
plt.stem(x,acf drift train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf drift train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf drift test=ACF(drift fore.values,100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf drift test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf drift test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast (Drift)')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
```

```
plt.tight layout()
plt.show()
#Model performance on train and test data
#MSE
drift train mse=mean squared error(y train[2:],train drift)
print('MSE of Drift on train data:',drift train mse)
drift test mse=mean squared error(y test, test drift)
print('MSE of Drift on test data:',drift test mse)
#Q-value
q drift train=acorr ljungbox(drift res, lags=5, boxpierce=True,
return df=True)
print('Q-value (residual):',q drift train)
q drifttest=acorr ljungbox(drift fore, lags=5, boxpierce=True, return df=True)
print('Q-value (Forecast):\n',q drifttest)
#Error mean and variance
print('Drift: Mean of residual error is', np.mean(drift res), 'and Forecast
error is',np.mean(drift fore))
print('Drift: Variance of residual error is',np.var(drift res),'and Forecast
error is',np.var(drift fore))
#RMSE
drift train rmse=mean squared error(y train[2:],train drift,squared=False)
print('RMSE of Drift method on train data:', drift train rmse)
drift test rmse=mean squared error(y test, test drift, squared=False)
print('RMSE of Drift method on test data:',drift test rmse)
#SES
ses=
ets.ExponentialSmoothing(y train, trend=None, damped trend=False, seasonal=None)
.fit(smoothing level=0.5)
train ses= ses.forecast(steps=len(y train))
train ses=pd.DataFrame(train ses).set index(y train.index)
test ses= ses.forecast(steps=len(y test))
test ses=pd.DataFrame(test ses).set index(y test.index)
#Plot of SES method
plt.plot(y train.index,y train,label='Train')
plt.plot(y test.index,y test,label='Test')
plt.plot(y_test.index, test_ses[0], label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('SES method predictions')
plt.legend()
plt.show()
#Plot of test vs predicted
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index, test ses[0], label='Forecasted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
```

```
plt.title('SES method forecast')
plt.legend()
plt.show()
#residual and forecast error
ses res=y train[2:]-train ses[0]
ses fore=y test-test ses[0]
acf ses train=ACF(ses res.values[2:],100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y train))
plt.stem(x,acf ses train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf ses train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf ses test=ACF(ses fore.values,100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf ses test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf ses test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast (SES)')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#Model performance on train and test data
#MSE
ses train mse=mean squared error(y train, train ses)
print('MSE of SES on train data:', ses train mse)
ses test mse=mean squared error(y test, test ses)
print('MSE of SES on test data:', ses test mse)
#0-value
q ses train=acorr ljungbox(ses res[2:], lags=5, boxpierce=True,
return df=True)
print('Q-value (residual):',q ses train)
q sestest=acorr ljungbox(ses fore, lags=5, boxpierce=True, return df=True)
print('Q-value (Forecast):\n',q sestest)
#Error mean and variance
print('SES: Mean of residual error is',np.mean(ses res),'and Forecast error
is', np.mean(ses fore))
print('SES: Variance of residual error is',np.var(ses res),'and Forecast
error is',np.var(ses fore))
ses train rmse=mean squared error(y train, train ses, squared=False)
print('RMSE of SES method on train data:', ses train rmse)
```

```
ses test rmse=mean squared error(y test, test ses, squared=False)
print('RMSE of SES method on test data:',ses test rmse)
#13: ARMA models
#Order determination
diff train, diff test=train test split(diff df, test size=0.2, shuffle=False)
ACF PACF Plot(diff df, 50)
acf gpac=ACF(diff train.Appliances.values,50)
x=np.arange(0,50)
m=1.96/np.sqrt(len(diff df))
plt.stem(x,acf gpac,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf gpac,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot for GPAC')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#GPAC
GPAC (acf gpac, 10, 10)
#order ARMA(3,0) and ARMA(3,1)
#14: LMA algorithm
na=3
nb=0
#ARMA model
arma 30=sm.tsa.ARMA(y train,(na,nb)).fit(trend='nc',disp=0)
#Estimated parameters
for i in range(na):
    print(f"The AR coefficient a{i} is:",arma 30.params[i])
for i in range(nb):
    print(f"The MA coefficient a{i} is:",arma 30.params[i + na])
print(arma 30.summary())
#confidence interval
print('Confidence interval:\n',arma 30.conf int())
#Estimators are significant does not include zero in them
#Prediction on train set
arma30 train=arma 30.predict(start=0,end=15787)
arma30 res=y train-arma30 train
#Forecast
arma30 test=arma 30.predict(start=15788, end=19734)
arma30 fore=y test-arma30 test
#ACF
acf arma30 train=ACF(arma30 res,100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y train))
```

```
plt.stem(x,acf arma30 train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf arma30 train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals')
plt.axhspan(-m, m, alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf arma30 test=ACF(arma30 fore.values,100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf arma30 test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf arma30 test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast (ARMA(3,0))')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#Model performance on train and test data
#MSE
arma30 train mse=mean squared error(y train,arma30 train)
print('MSE of ARMA(3,0) on train data:',arma30 train mse)
arma30 test mse=mean squared error(y test,arma30 test)
print('MSE of ARMA(3,0) on test data:',arma30 test mse)
#Q-value
q_arma30_train=acorr_ljungbox(arma30 res, lags=5, boxpierce=True,
return df=True)
print('Q-value (residual):',q arma30 train)
q ar30test=acorr ljungbox(arma30 fore,lags=5,boxpierce=True,return df=True)
print('Q-value (Forecast):\n',q ar30test)
#Error mean and variance
print('ARMA(3,0): Mean of residual error is',np.mean(arma30 res),'and
Forecast error is',np.mean(arma30 fore))
print('ARMA(3,0): Variance of residual error is',np.var(arma30 res),'and
Forecast error is',np.var(arma30 fore))
#Covariance matrix
print('Covariance matrix\n', arma 30.cov params())
#standard error
print('Standard error:',arma 30.bse)
#RMSE
ar30 train rmse=mean squared error(y train,arma30 train,squared=False)
print('RMSE of ARMA(3,0) method on train data:',ar30 train rmse)
ar30 test rmse=mean squared error(y test,arma30 test,squared=False)
print('RMSE of ARMA(3,0) method on test data:',ar30_test_rmse)
#Plot of ARMA(3,0) method
plt.plot(y train.index,y train,label='Train')
```

```
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index,arma30 test,label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('ARMA(3,0) method predictions')
plt.legend()
plt.show()
#Plot of test vs forecasted
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index,arma30 test,label='Forecasted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('ARMA(3,0) method forecast')
plt.legend()
plt.show()
#Plot of train vs predicted
plt.plot(y train.index,y train,label='Train')
plt.plot(y train.index,arma30 train,label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('ARMA(3,0) method predictions')
plt.legend()
plt.show()
#The model didn't work well on test data let's try other model.
na = 3
nb = 1
# ARMA model
arma31= sm.tsa.ARMA(y train, (na, nb)).fit(trend='nc', disp=0)
print(arma31.summary())
#Estimated parameters
for i in range(na):
    print(f"The AR coefficient a{i} is:",arma31.params[i])
for i in range(nb):
    print(f"The MA coefficient a{i} is:",arma31.params[i + na])
#confidence interval
print('Confidence interval:\n',arma31.conf int())
#Estimators are significant does not include zero in them
#Prediction on train set
arma31 train=arma31.predict(start=0,end=15787)
arma31 res=y train-arma31 train
#Forecast
arma31 test=arma31.predict(start=15788, end=19734)
arma31 fore=y test-arma31 test
#ACF
```

```
acf arma31 train=ACF(arma31 res,100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y train))
plt.stem(x,acf arma31 train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf arma31 train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals')
plt.axhspan(-m, m, alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf arma31 test=ACF(arma31 fore.values, 100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf arma31 test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf arma31 test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast (ARMA(3,1))')
plt.axhspan(-m,m,alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#Model performance on train and test data
#MSE
arma31 train mse=mean squared error(y train, arma31 train)
print('MSE of ARMA(3,1) on train data:',arma31 train mse)
arma31 test mse=mean squared error(y test,arma31 test)
print('MSE of ARMA(3,1) on test data:',arma31 test mse)
#Q-value
q arma31 train=acorr ljungbox(arma31 res, lags=5, boxpierce=True,
return df=True)
print('Q-value (residual):',q arma31 train)
q ar31test=acorr ljungbox(arma30 fore, lags=5, boxpierce=True, return df=True)
print('Q-value (Forecast):\n',q ar31test)
#Error mean and variance
print('ARMA(3,1): Mean of residual error is', np.mean(arma31 res), 'and
Forecast error is',np.mean(arma31 fore))
print('ARMA(3,1): Variance of residual error is',np.var(arma31 res),'and
Forecast error is',np.var(arma31 fore))
#Covariance matrix
print('Covariance matrix\n', arma31.cov params())
#standard error
print('Standard error:', arma31.bse)
#RMSE
ar31 train rmse=mean squared error(y train,arma31 train,squared=False)
print('RMSE of ARMA(3,1) method on train data:', ar31 train rmse)
ar31 test rmse=mean squared error(y test,arma31 test,squared=False)
print('RMSE of ARMA(3,1) method on test data:',ar31 test rmse)
```

```
\#Plot\ of\ ARMA(3,1)\ method
plt.plot(y train.index, y train, label='Train')
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index,arma31 test,label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('ARMA(3,1) method predictions')
plt.legend()
plt.show()
#Plot of test vs forecasted
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index,arma31 test,label='Forecasted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('ARMA(3,1) method forecast')
plt.legend()
plt.show()
#Plot of train vs predicted
plt.plot(y train.index,y train,label='Train')
plt.plot(y train.index,arma31 train,label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('ARMA(3,1) method predictions')
plt.legend()
plt.show()
#Let's try SARIMA
\#SARIMA = (3,0,0)X(0,1,0,12)
#Seasonality of 144 is not computational there exists a memory error so
reduce it to 12
sarima=
sm.tsa.statespace.SARIMAX(y train, order=(3,0,0), seasonal order=(0,1,0,12),
                                     enforce stationarity=False,
                                     enforce invertibility=False)
results=sarima.fit()
print(results.summary())
#predictions on train data
sarima train=results.get prediction(start=0, end=len(y train), dynamic=False)
Sarima pred=sarima train.predicted mean
Sarima res= y train-Sarima pred.values[1:]
#forecast
sarima test=results.predict(start=0, end=(len(y test)))
sarima fore=y_test-sarima_test.values[1:]
#ACF
#ACF
```

```
acf sarima train=ACF(Sarima res.values,100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y train))
plt.stem(x,acf sarima train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf sarima train,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Residuals')
plt.axhspan(-m, m, alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
acf sarima test=ACF(sarima fore.values, 100)
x=np.arange(0,100)
m=1.96/np.sqrt(len(y test))
plt.stem(x,acf sarima test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.stem(-1*x,acf sarima test,linefmt='r-', markerfmt='bo', basefmt='b-')
plt.xlabel('Lags')
plt.ylabel('ACF')
plt.title('ACF Plot of Forecast (SARMA(3,0,0)X(0,1,0,12))')
plt.axhspan(-m, m, alpha = .1, color = 'yellow')
plt.tight layout()
plt.show()
#Model performance on train and test data
#MSE
sarima train mse=mean squared error(y train, Sarima pred[1:])
print('MSE of SARIMA on train data:',sarima train mse)
sarima test mse=mean squared error(y test,sarima test[1:])
print('MSE of SARIMA on test data:', sarima test mse)
#Q-value
q sarima train=acorr ljungbox(Sarima res, lags=5, boxpierce=True,
return df=True)
print('Q-value (residual):',q sarima train)
q sarimatest=acorr ljungbox(sarima fore, lags=5, boxpierce=True, return df=True)
print('Q-value (Forecast):\n',q sarimatest)
#Error mean and variance
print('SARIMA: Mean of residual error is', np.mean(Sarima res), 'and Forecast
error is', np.mean(sarima fore))
print('SARIMA: Variance of residual error is', np.var(Sarima res), 'and
Forecast error is',np.var(sarima fore))
#Covariance matrix
print('Covariance matrix\n', results.cov params())
#standard error
print('Standard error:', results.bse)
sarima train rmse=mean squared error(y train, Sarima pred[1:], squared=False)
print('RMSE of SARIMA method on train data:',sarima train rmse)
sarima test rmse=mean squared error(y test,sarima test[1:],squared=False)
print('RMSE of SARIMA method on test data:',sarima test rmse)
```

```
#Plot of SARIMA method
plt.plot(y train.index,y train,label='Train')
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index, sarima test[1:], label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('SARIMA method predictions')
plt.legend()
plt.show()
#Plot of test vs forecasted
plt.plot(y test.index,y test,label='Test')
plt.plot(y test.index, sarima test[1:], label='Forecasted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('SARIMA method forecast')
plt.legend()
plt.show()
#Plot of train vs predicted
plt.plot(y train.index,y train,label='Train')
plt.plot(y train.index, Sarima pred[1:], label='Predicted')
plt.xlabel('Time')
plt.xticks(rotation='vertical')
plt.ylabel('Appliances')
plt.title('SARIMA method predictions')
plt.legend()
plt.show()
#16:The best model with less MSE is Multiple Linear Regression
#17: Forecast function can be written as
print(model.summary())
#y hat t = 2.1396 * lights + 13.8562 * RH 1 + (-17.11) * T2 + (-13.2627) * RH 2 + (-
25.5010*T3
                      +8.6120*RH 3 + (-3.9367)*T4 + (-2.8629)*RH 4 + (8.3984)*T6 +
 (0.3553) *RH 6
                      + 8.5673*T8 + (-6.3745)*RH 8 + (-13.4323)*T9 + (-6.1772)*T out
                       + 1.0866 *Windspeed + 0.2045*Visibility
#18: H-step ahead prediction
#predictions of test data for MLR was performed previously (see at MLR part
of code)
#Let's plot the test vs forecasted values of MLR
plt.figure(figsize=(6,6))
plt.plot(y test.index,y test, label='Test')
plt.plot(pred test.index,pred test, label='Forecasted')
plt.legend()
plt.xlabel("Time")
plt.xticks(rotation=70)
plt.ylabel("Appliances")
```

plt.title("Predictions on test set")
plt.show()

REFERENCES

Luis M. Candanedo, Véronique Feldheim, Dominique Deramaix. Energy and Buildings,
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 http://dx.doi.org/10.1016/j.enbuild.2017.01.083

• https://github.com/LuisM78/Appliances-energy-prediction-data