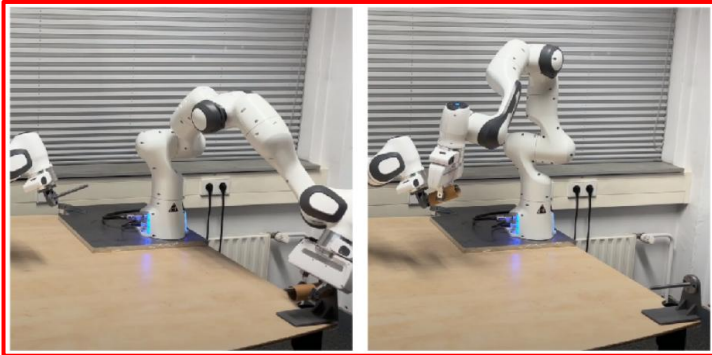
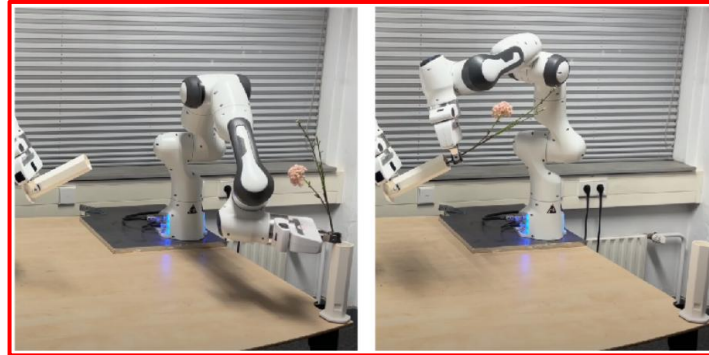


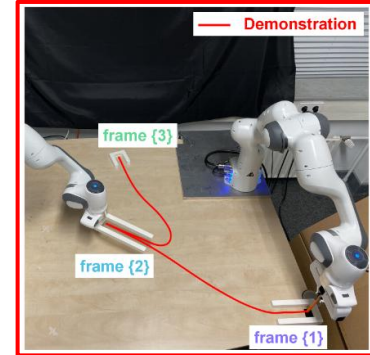
robot experiment name	material file name	number required (minimum)
roller_on_holder	holder_base.STL	1
	holder_link.STL	2
	holder_stick.STL	2
flower_in_vase	container_desk.STL	1
	container_robot.STL	1
pen_to_box	link_v2.STL	2
	box_long.STL	1
	box_short.STL	1
	box_v1.STL	1



roller_on_holder



flower_in_vase



pen_to_box