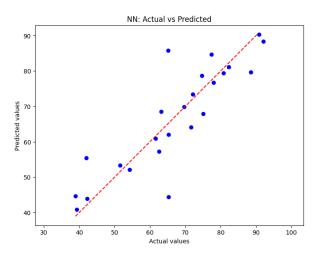
Why do overparameterized neural networks generalize?

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A real-world example



A very small noisy satellite data with 118 rows and 12 features. The picture shows the
performance of a neural network with roughly six million parameters trained on 94 points.

Statistical learning theory

• Goal: given i.i.d. samples (measurements) $(x_1, y_1), \dots, (x_N, y_N)$ from an unknown probability distribution μ over $\mathcal{X} \times \mathcal{Y}$, find a predictor $f : \mathcal{X} \to \mathcal{Y}$ from a given set \mathcal{F} for which the risk

$$R(f) := \mathbb{E}_{(x,y)\sim\mu}[\ell(f(x),y)]$$

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Example (Linear regression)

We have $\mathcal{X} = \mathcal{Y} = \mathbb{R}$ and $\ell(y, y') := (y - y')^2$. Goal is to find a predictor f from

$$\mathcal{F} := \{\beta_1 x + \beta_0 \mid \beta_1, \beta_0 \in \mathbb{R}\}$$

with small risk.

• Since μ is unknown, we can not calculate R(f) directly. In practice we estimate R(f) by calculating its empirical risk with respect to our sample $S = \{(x_1, y_1), \dots, (x_N, y_N)\}$:

$$R_{S}(f) := \frac{1}{N} \sum_{i=1}^{N} \ell(f(x_i), y_i)$$

Law of large numbers guarantees that almost surely $R_S(f) \to R(f)$ as $|S| \to \infty$.

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 - Consider for example the case where $\mathcal{X}=\mathcal{Y}=\mathbb{R}, \ell(y,y')=|y-y'|$ and

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• How to find a predictor which also has a small risk?

Example: support vector machines and ℓ_2 -regularization

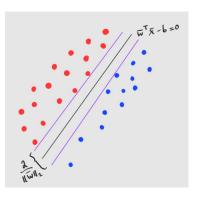
ullet Let $\mathcal{X}=\mathbb{R}^d, \mathcal{Y}=\{-1,1\}$ and

$$\ell(y,y') = egin{cases} 1 & ext{, if } y
eq y' \ 0 & ext{, otherwise} \end{cases}$$

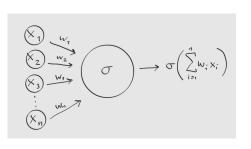
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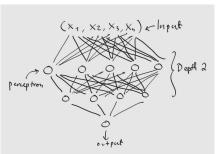
$$\mathcal{F}:=\{ ext{hyperplanes in }\mathbb{R}^d\}.$$

If $S\subseteq \mathbb{R}^d \times \{-1,1\}$ is linearly separable, then there are many predictors in $f\in \mathcal{F}$ for which $R_S(f)=0$. The main idea in support vector machines is that we should select a hyperplane with a minimal norm.



Neural networks





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$$\overline{w} \leftarrow \overline{w} - \eta \nabla R_{\{x\}}(\overline{w})$$

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Example

The CIFAR-10 image classification benchmark has 50000 training examples spread across 10 classes. The following table demonstrates the performance of a common architecture, called Inception, on CIFAR-10. Inception has more than 1.5 million parameters.

ℓ_2 -regularization	Train accuracy	Test accuracy
Yes	100.0	86.03
No	100.0	85.75

Table: Inception on CIFAR-10.

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 Furthermore, architectures that have less parameters than the number of sample points seem to be more prone to overfit.

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- The nature of this regularization is not clear and it seems to depend on SGD having a good initialization. E.g. Liu et al. (2019) gave a simple way of initializing the weights in such a way that SGD does not learn a "simple" model. (This was also mentioned in Nakkiran et al. (2019).)

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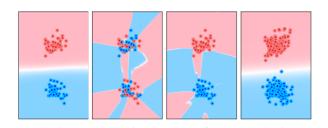


Figure: Picture from Liu et al. (2019)

Flat minimas

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- The correspondence between flat minimas and good models was emphasized already by Hochreiter and Schmidhuber (1997), who designed a learning algorithm that explicitly preferred flat minimas.
- As far as I can tell, there is no water-proof explanation for why SGD is able to find flat minimas in the overparameterized region.

Nice loss landscape

• Somewhat surprisingly, Chiang et al. (2023) demonstrated empirically that in the over-parameterized regime "most" weights that work on the sample work also outside the sample. That is, in principle one can replace SGD with a random guessing.

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Nice loss landscape

- Somewhat surprisingly, Chiang et al. (2023) demonstrated empirically that in the over-parameterized regime "most" weights that work on the sample work also outside the sample. That is, in principle one can replace SGD with a random guessing.
- More generally, they argue that the use of gradient-based optimizers is not the main source of generalization behavior of neural networks.
- The experiments were limited to the small-sample regime, so verifying them in a more realistic setting is an interesting research direction.

That's all folks!

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