

# **Polygonal Meshes**

COS 426, Spring 2020
Princeton University
Felix Heide

# 3D Object Representations

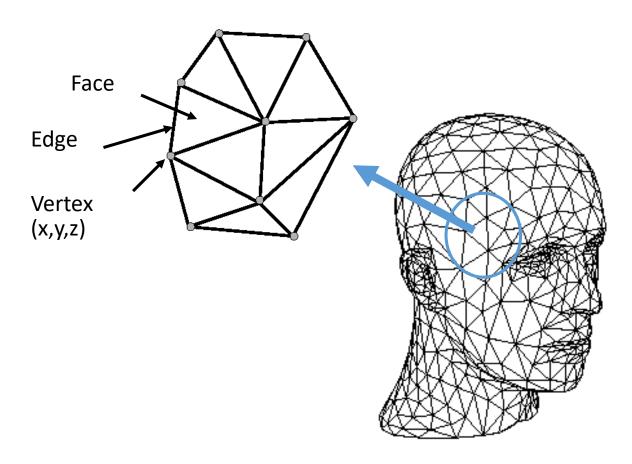


- Points
  - Range image
  - Point cloud
- Surfaces
  - ➤ Polygonal mesh
  - Parametric
  - Subdivision
  - Implicit

- Solids
  - Voxels
  - BSP tree
  - CSG
  - Sweep
- High-level structures
  - Scene graph
  - Application specific



• Set of polygons representing a 2D surface embedded in 3D





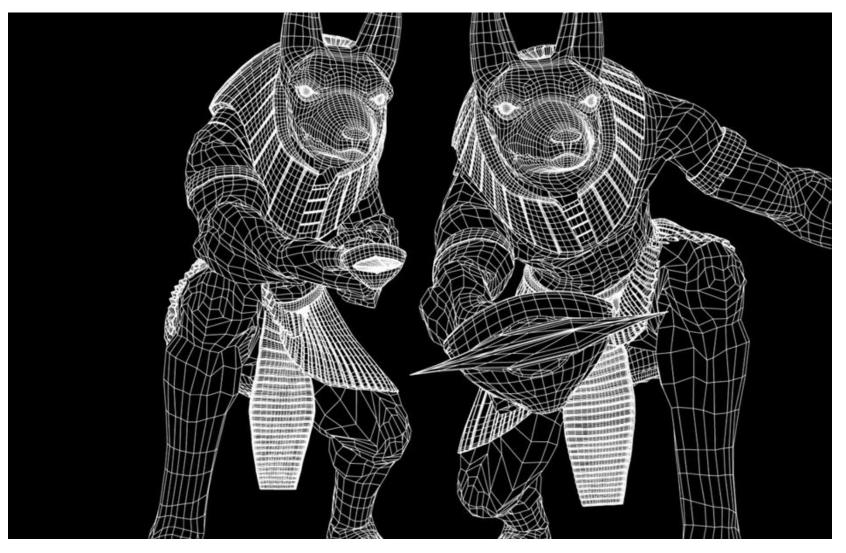
The power of polygonal meshes



Set of polygons representing a 2D surface embedded in 3D

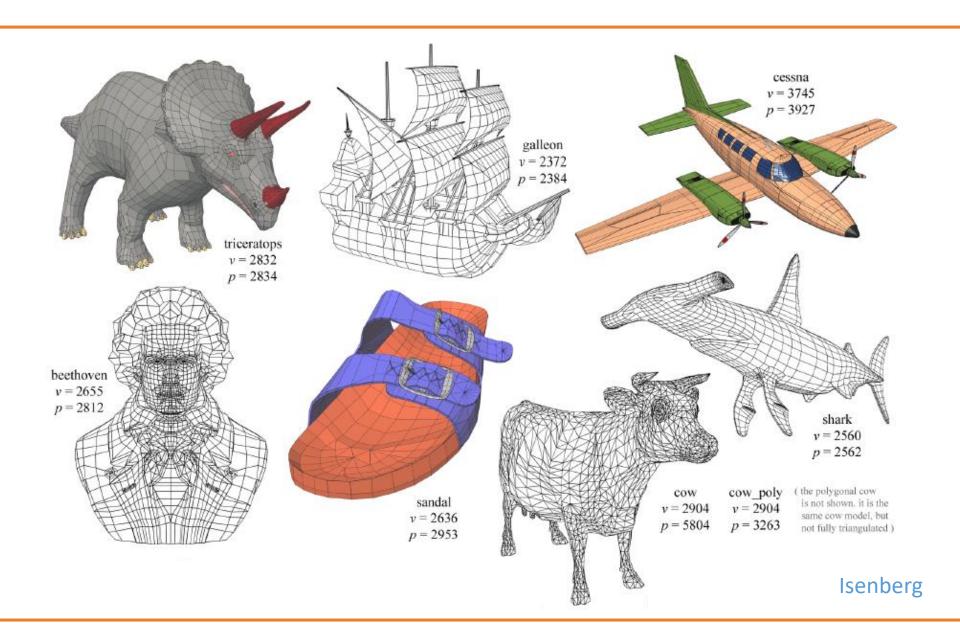
**Platonic Solids** Dodecahedron Icosahedron Tetrahedron Octahedron Cube





http://www.fxguide.com/featured/Comic\_Horrors\_Rocks\_Statues\_and\_VanDyke/







- Why are they of interest?
  - Simple, common representation
  - Rendering with hardware support
  - Output of many acquisition tools
  - Input to many simulation/analysis tools







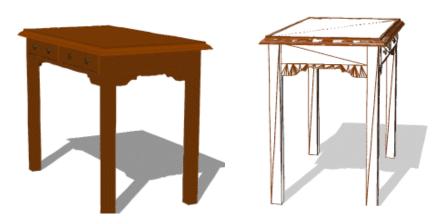




#### Properties

- ? Efficient display
- ? Easy acquisition
- ? Accurate
- ? Concise
- ? Intuitive editing
- ? Efficient editing
- ? Efficient intersections
- ? Guaranteed validity
- ? Guaranteed smoothness
- ? etc.





#### **Outline**



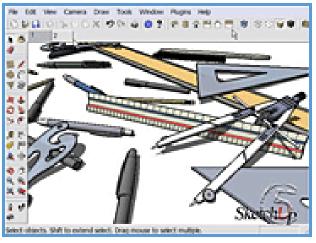
- Acquisition
- Representation
- Processing



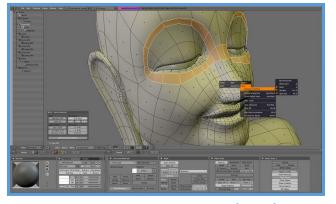
- Interactive modeling
- Scanners
- Procedural generation
- Conversion
- Simulations



- Interactive modeling
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Sketchup



Blender



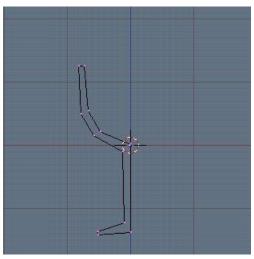
- Interactive modeling
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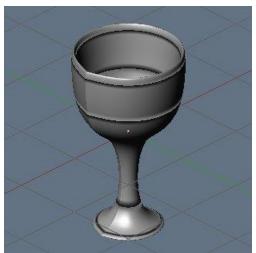


Digital Michelangelo Project Stanford



- Interactive modeling
- Scanners
- Procedural generation
- Conversion
- Simulations





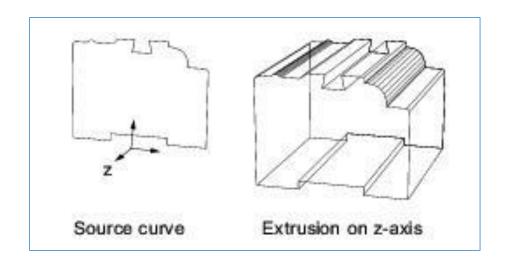


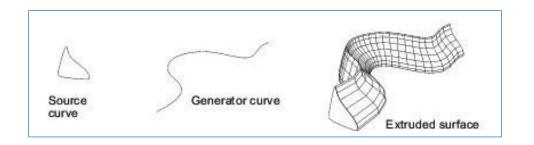
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- Interactive modeling
- Scanners
- Procedural generation
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- Simulations





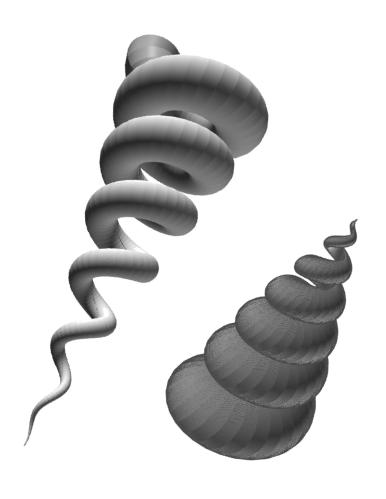


- Interactive modeling
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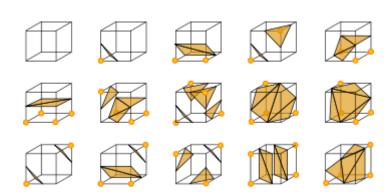




Peter Maag, COS 426, 2010



- Interactive modeling
- Scanners
- Procedural generation
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- Simulations



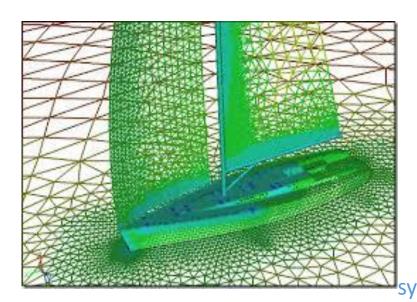


Marching cubes

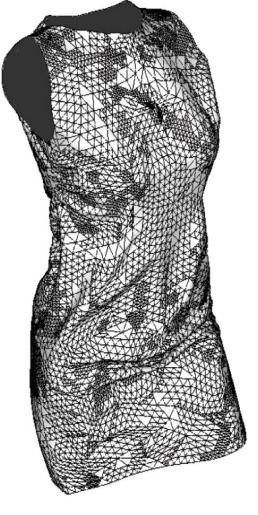




- Interactive modeling
- Scanners
- Procedural generation
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- Simulations







Lee et. al 2010

#### **Outline**



- Acquisition
- Representation

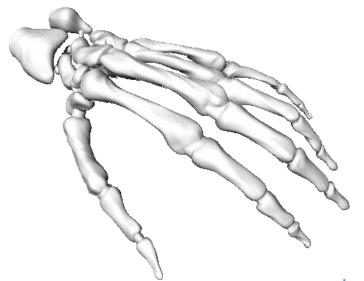


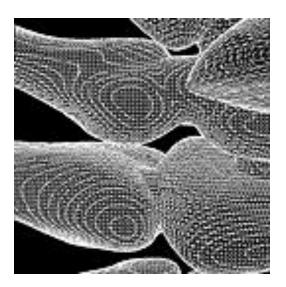
Processing

#### **Polygon Mesh Representation**



- Important properties of mesh representation?
  - Efficient traversal of topology
  - Efficient use of memory
  - Efficient updates



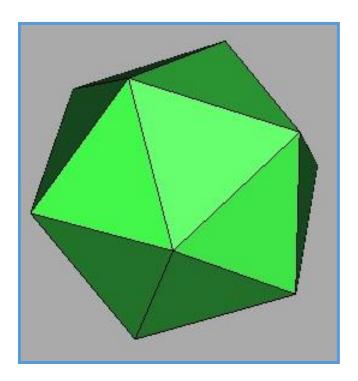


Large Geometric Model Repository Georgia Tech

### **Polygon Mesh Representation**



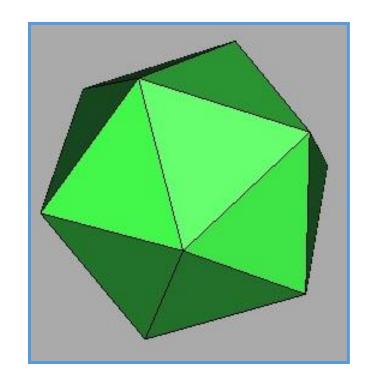
Possible data structures

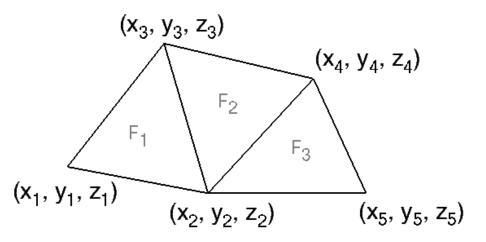


#### **Independent Faces**



- Each face lists vertex coordinates
  - Redundant vertices
  - No adjacency information



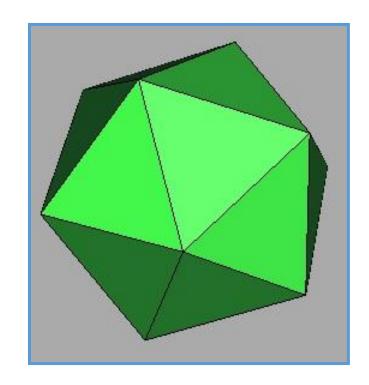


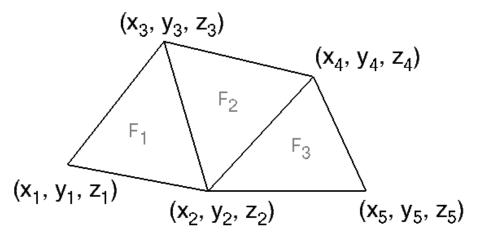
#### **FACE TABLE**

#### Vertex and Face Tables (Indexed Vertices)



- Each face lists vertex references
  - Shared vertices
  - Still no adjacency information





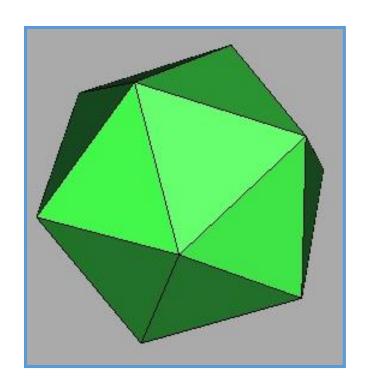
# VERTEX TABLE V<sub>1</sub> X<sub>1</sub> Y<sub>1</sub> Z<sub>1</sub> V<sub>2</sub> X<sub>2</sub> Y<sub>2</sub> Z<sub>2</sub> V<sub>3</sub> X<sub>3</sub> Y<sub>3</sub> Z<sub>3</sub> V<sub>4</sub> X<sub>4</sub> Y<sub>4</sub> Z<sub>4</sub> V<sub>5</sub> X<sub>5</sub> Y<sub>5</sub> Z<sub>5</sub>

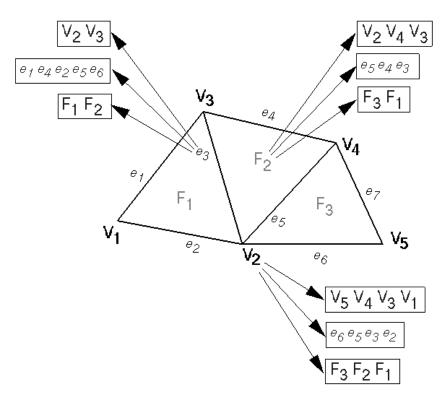
FAG	FACE TABLE			
F <sub>1</sub>	٧1	٧2	٧3	
$F_2$	٧2	$V_4$	٧3	
F <sub>3</sub>	V <sub>2</sub>	٧5	$V_4$	

#### **Adjacency Lists**



- Store all vertex, edge, and face adjacencies
  - Efficient adjacency traversal
  - Extra storage

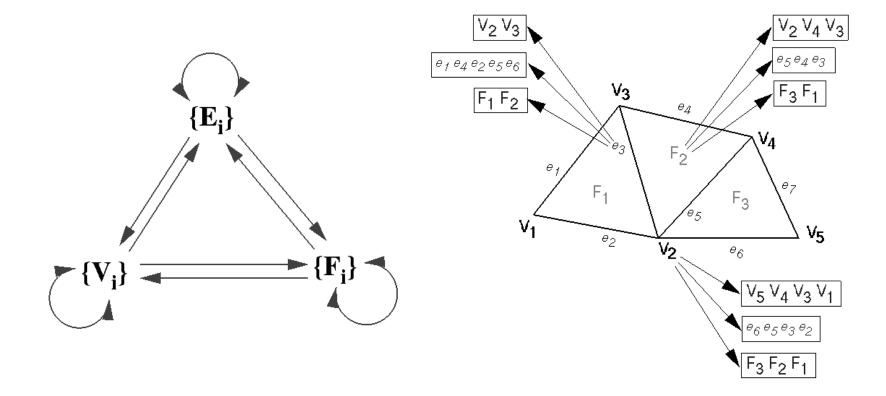




#### **Partial Adjacency Lists**



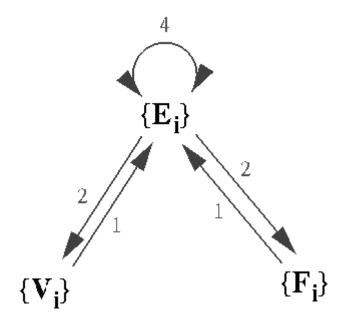
 Can we store only some adjacency relationships and derive others?

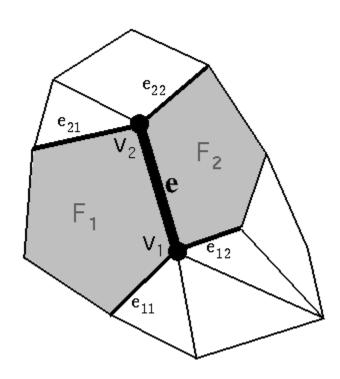


#### Winged Edge



- Adjacency encoded in edges
  - All adjacencies in O(1) time
  - Little extra storage (fixed records)
  - Arbitrary polygons

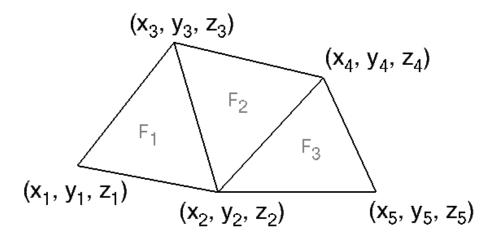




#### Winged Edge



• Example:



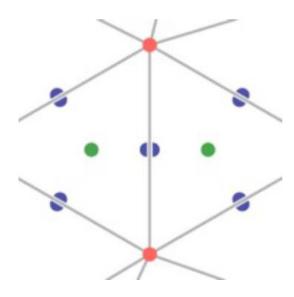
VERTEX TABLE				
٧1	X <sub>1</sub>	Y <sub>1</sub> Y <sub>2</sub> Y <sub>3</sub> Y <sub>4</sub> Y <sub>5</sub>	Z <sub>1</sub>	e <sub>1</sub>
$V_2$	X <sub>2</sub>	$Y_2$	$Z_2$	e <sub>6</sub>
٧3	Х3	Υ3	$Z_3$	ез
$V_4$	X <sub>4</sub>	$Y_4$	$Z_4$	e <sub>5</sub>
٧5	X <sub>5</sub>	Υ <sub>5</sub>	Z <sub>5</sub>	e <sub>6</sub>

ED	EDGE TABLE 11 12 21 22				22			
e <sub>1</sub>	٧1	٧3		F <sub>1</sub>	e <sub>2</sub>	e <sub>2</sub>	e <sub>4</sub>	e <sub>3</sub>
e <sub>2</sub>	٧1	$V_2$	F <sub>1</sub>		e <sub>1</sub>	e <sub>1</sub>	e <sub>3</sub>	e <sub>6</sub>
e <sub>3</sub>	٧2	٧3	F <sub>1</sub>	$F_2$	e <sub>2</sub>	e <sub>5</sub>	$e_1$	$e_4$
e <sub>4</sub>	V3	$V_4$		$F_2$	e <sub>1</sub>	$e_3$	e <sub>7</sub>	e <sub>5</sub>
e <sub>5</sub>	٧2	$V_4$	F <sub>2</sub>	$F_3$	e <sub>3</sub>	e <sub>6</sub>	$e_4$	e <sub>7</sub>
e <sub>6</sub>	V <sub>2</sub>	$V_5$	$F_3$		e <sub>5</sub>	$e_2$	$e_7$	e <sub>7</sub>
e <sub>7</sub>	٧4	V <sub>5</sub>		F <sub>3</sub>	e <sub>4</sub>	e <sub>5</sub>	e <sub>6</sub>	e <sub>6</sub>

	FACE TABLE		
F <sub>1</sub>	e <sub>1</sub>		
F <sub>2</sub>	e <sub>3</sub>		
F <sub>3</sub>	e <sub>5</sub>		

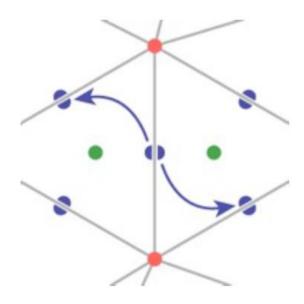


- Each half-edge stores:
  - Its twin half-edge



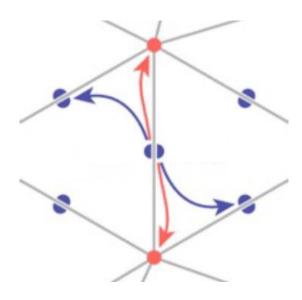


- Each half-edge stores:
  - Its twin half-edge
  - The next half-edge



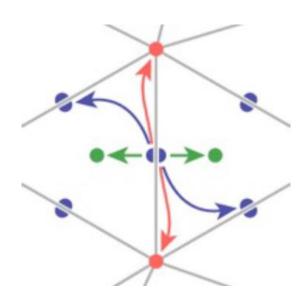


- Each half-edge stores:
  - Its twin half-edge
  - The next half-edge
  - The next vertex



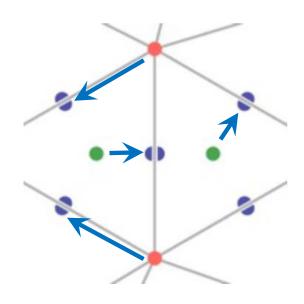


- Each half-edge stores:
  - Its twin half-edge
  - The next half-edge
  - The next vertex
  - The incident face



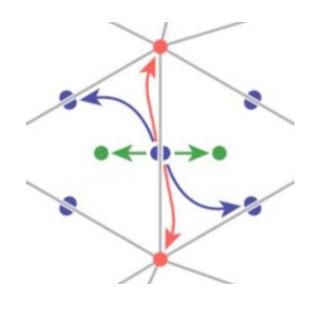


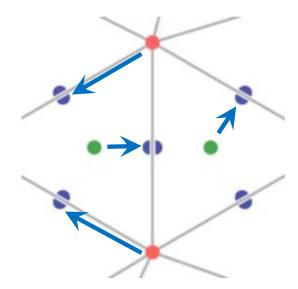
- Each half-edge stores:
  - Its twin half-edge
  - The next half-edge
  - The next vertex
  - The incident face
- Each face stores:
  - 1 adjacent half-edge
- Each vertex stores:
  - 1 outgoing half-edge

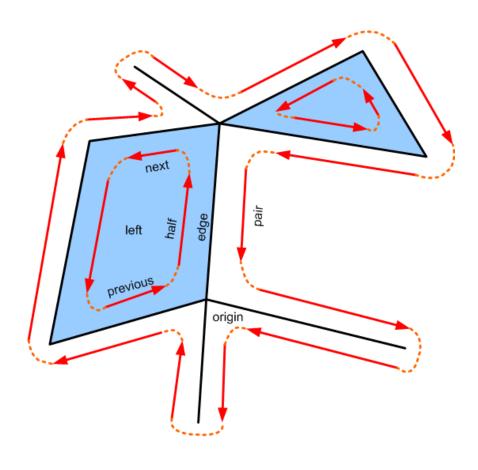




- Queries. How do you find:
  - All faces incident to an edge?
  - All vertices of a face?
  - All faces incident to a face?
  - All vertices incident to a vertex?

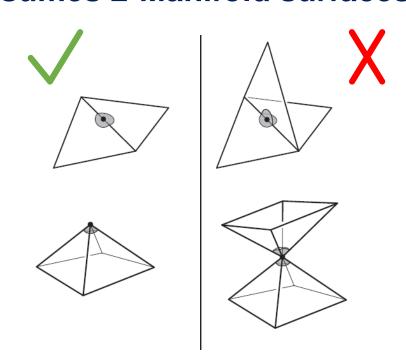


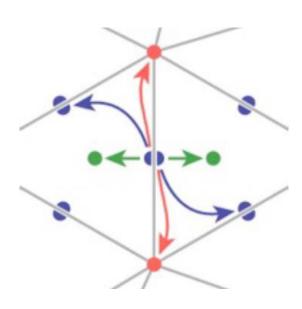






- Adjacency encoded in edges
  - All adjacencies in O(1) time
  - Little extra storage (fixed records)
  - Arbitrary polygons
  - Assumes 2-Manifold surfaces





#### **Outline**



- Acquisition
- Representation
- Processing

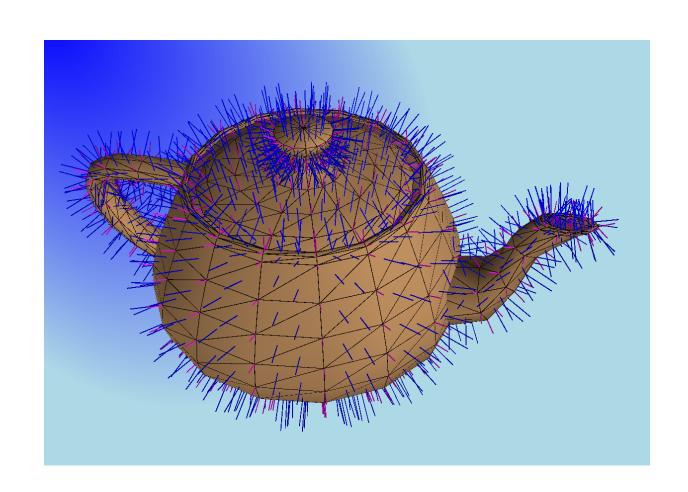




- Analysis
  - Normals
  - Curvature
- Warps
  - Rotate
  - Deform
- Filters
  - Smooth
  - Sharpen
  - Truncate
  - Bevel



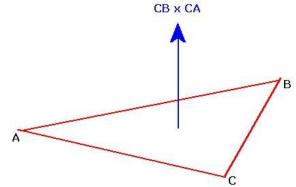
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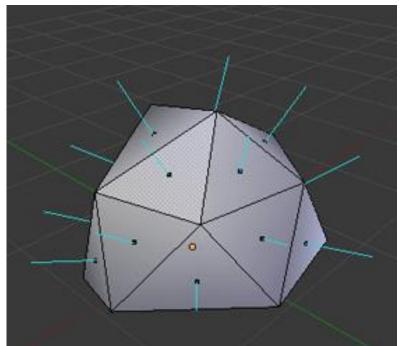




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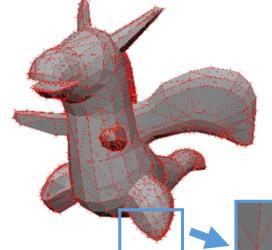


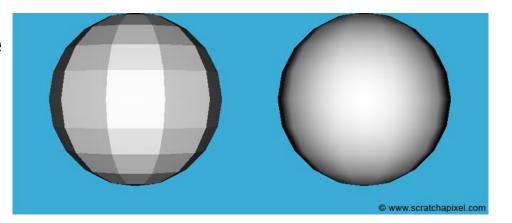


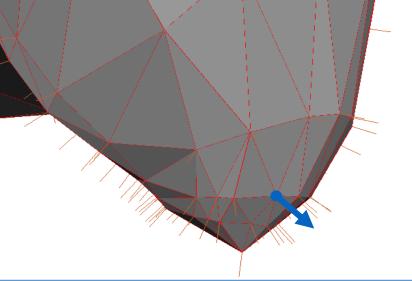


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#### Vertex normals:



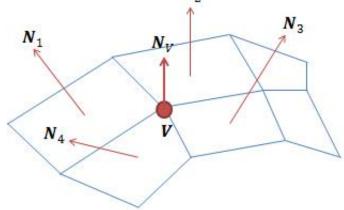






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Vertex normals:



$$N_V = \frac{\sum_{k=1}^n N_k}{\left|\sum_{k=1}^n N_k\right|}$$

for each face

- -calculate face normal
- -add normal to each connected vertex normal

for each face normal

-normalize

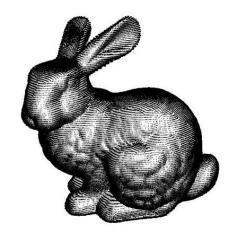
for each vertex normal

-normalize



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The Next Dual

"The bunny with normal vertices shown.

Reminded me of an album cover so I made it into one."



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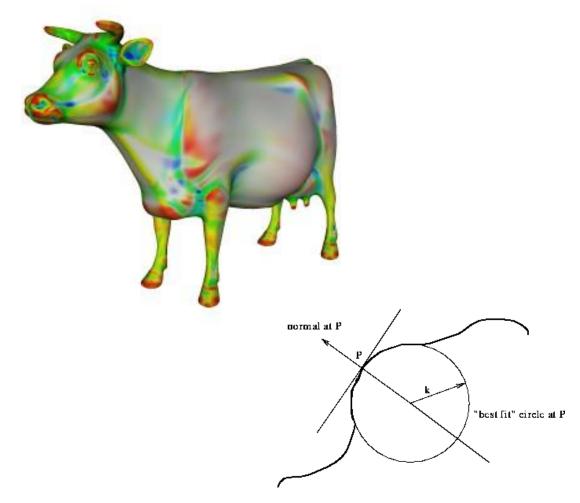
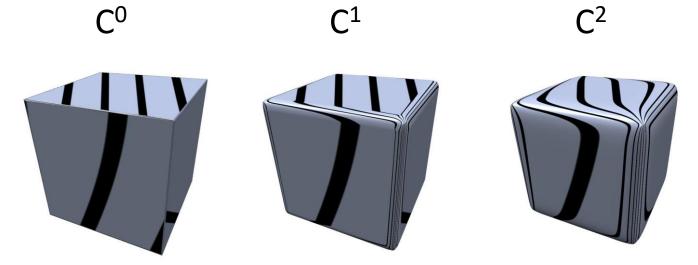
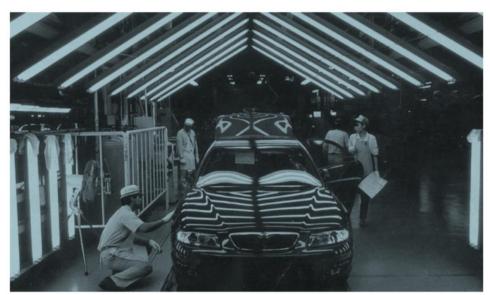


Figure 32: curvature of curve at P is 1/k



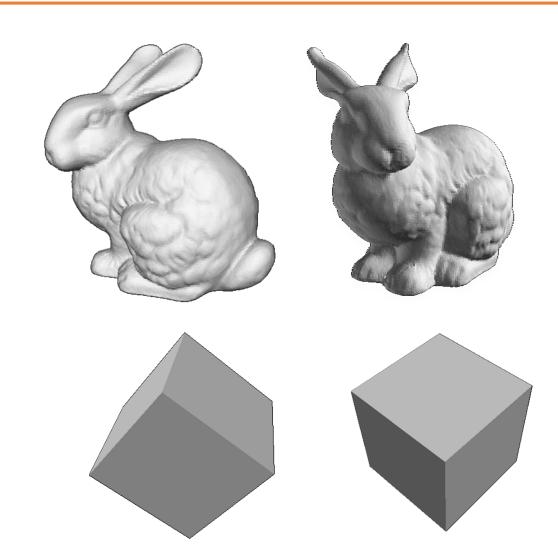
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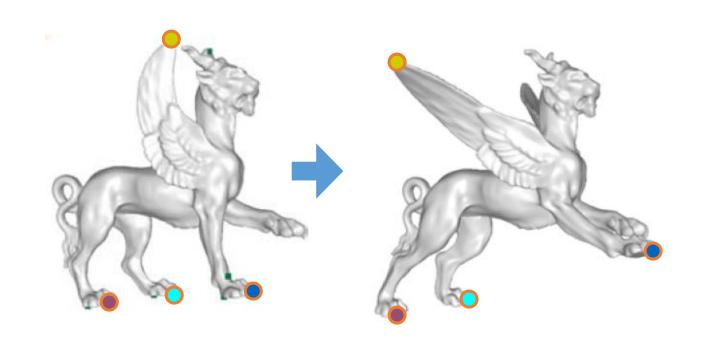


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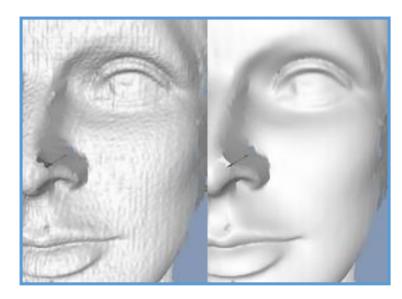


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Thouis "Ray" Jones

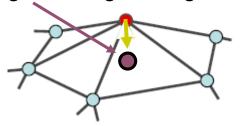
How?



#### Mesh formulation:

$$p_i = \frac{\Sigma_{j \in 1_{ring_i}} p_j}{\#1_{ring_i}}$$

Average of Neighboring Vertices



Olga Sorkine

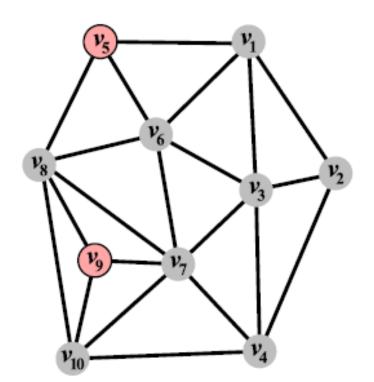


The Laplacian operator Δ

$$L(p_i) = \Delta(p_i) = \frac{\sum_{j \in 1_{ring_i}} p_j - p_i}{\#1_{ring_i}}$$

• In matrix form:

$$L_{ij} = \begin{cases} -w_{ij} & i \neq j \\ \Sigma_{j \in 1_{ring_i}} w_{ij} & i = j \\ 0 & else \end{cases}$$



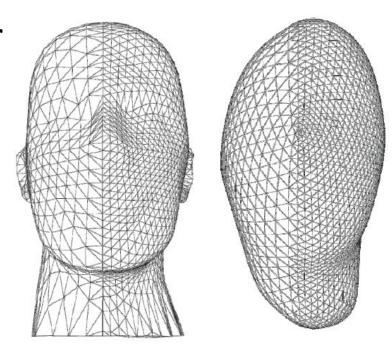
4	-1	-1		-1	-1				
-1	3	-1	-1						
-1	-1	5	-1		-1	-1			
	-1	-1	4			-1			-1
-1					-1				
-1		-1		-1	5	-1	-1		
		-1	-1		-1	6	-1	-1	-1
				-1	-1	-1	5	-1	-1
						-1	-1	3	-1
			-1			-1	-1	-1	4



The Laplacian operator Δ

$$L(p_i) = \Delta(p_i) = \frac{\sum_{j \in 1_{ring_i}} p_j - p_i}{\#1_{ring_i}}$$

However, Meshes are irregular



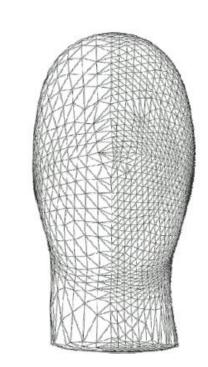


$$L(p_i) = \Delta(p_i) = \frac{\sum_{j \in 1_{ring_i}} p_j - p_i}{\#1_{ring_i}}$$

- However, Meshes are irregular
  - Cotangent weights:

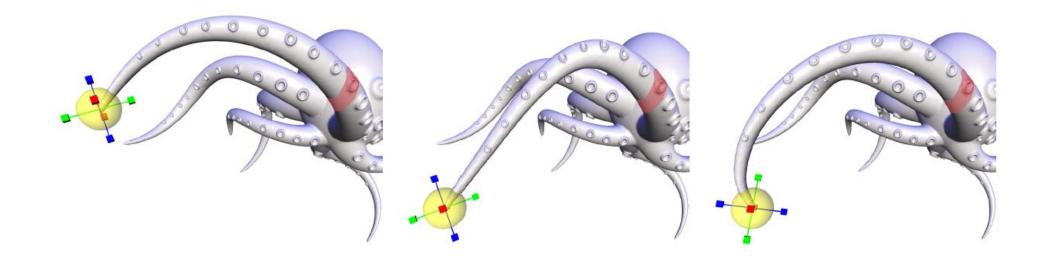
$$L(p_i) = \frac{\sum_{j \in 1_{ring_i}} w_{ij} \cdot p_j}{\sum_{j \in 1_{ring_i}} w_{ij}} - p_i$$

$$w_{ij} = \frac{\cot(\alpha_{ij}) + \cot(\beta_{ij})}{2}$$



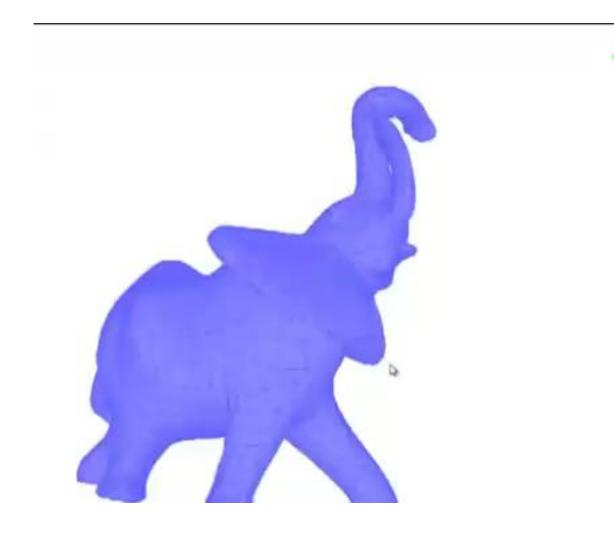


- Applicable to:
  - Deformation, by adding constraints



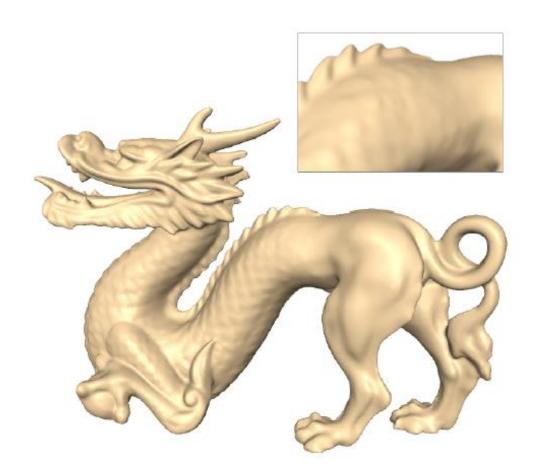


**Deformation** 



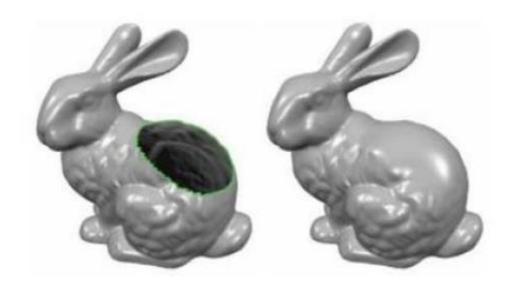


- Applicable to:
  - Deformation, by adding constraints
  - Blending, by concatenating rows



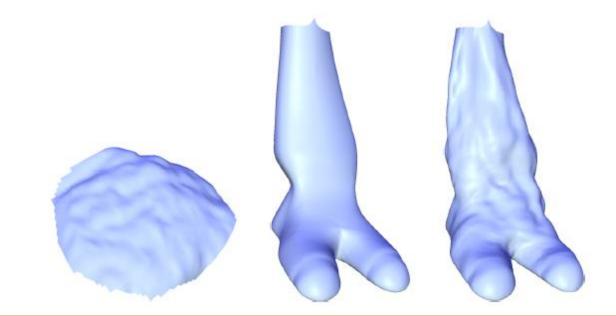


- Applicable to:
  - Deformation, by adding constraints
  - Blending, by concatenating rows
  - Hole filling, by 0's on the RHS



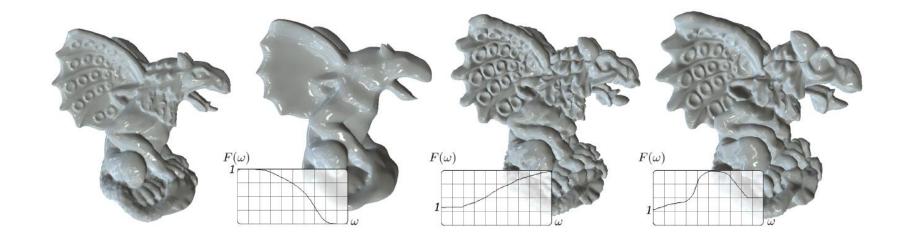


- Applicable to:
  - Deformation, by adding constraints
  - Blending, by concatenating rows
  - Hole filling, by 0's on the RHS
  - Coating (or detail transfer), by copying RHS values (after filtering)



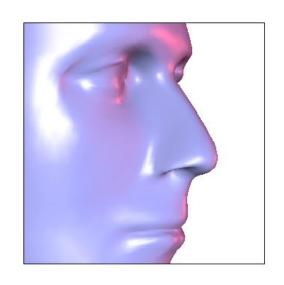


- Applicable to:
  - Deformation, by adding constraints
  - Blending, by concatenating rows
  - Hole filling, by 0's on the RHS
  - Coating (or detail transfer), by copying RHS values (after filtering)
  - Spectral mesh processing, through eigen analysis



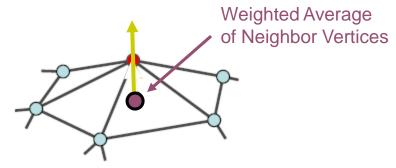


- Analysis
  - Normals
  - Curvature
- Warps
  - Rotate
  - Deform
- Filters
  - Smooth
  - **≻**Sharpen
  - Truncate
  - Bevel





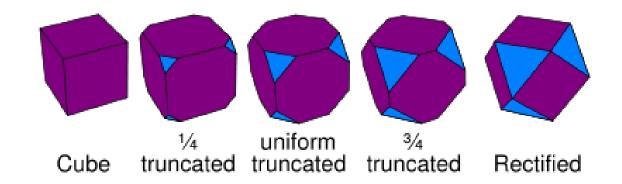
Desbrun

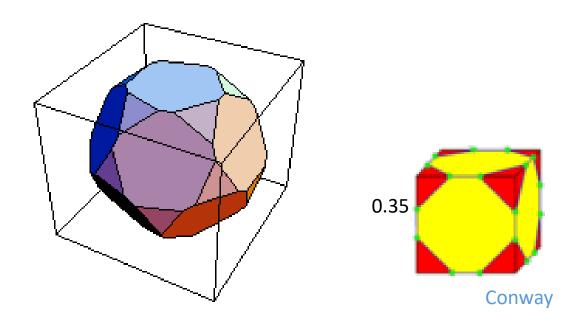


Olga Sorkine



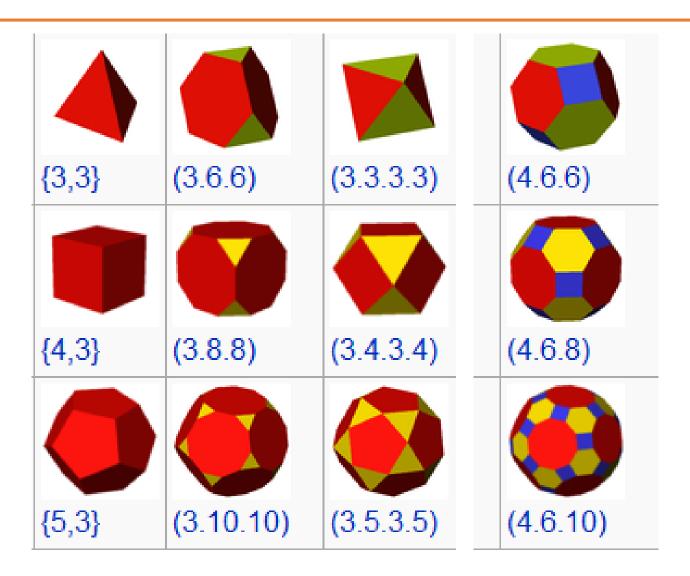
- Analysis
  - Normals
  - Curvature
- Warps
  - Rotate
  - Deform
- Filters
  - Smooth
  - Sharpen
  - >Truncate
  - Bevel





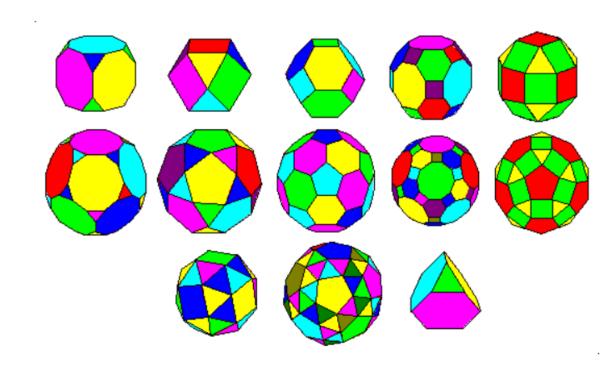


- Analysis
  - Normals
  - Curvature
- Warps
  - Rotate
  - Deform
- Filters
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- Analysis
  - Normals
  - Curvature
- Warps
  - Rotate
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  - Bevel



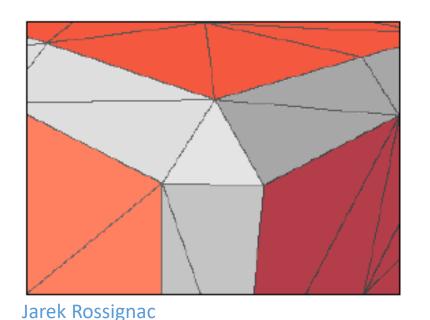
Archimedean Polyhedra

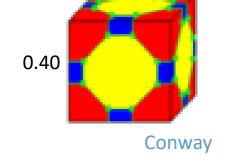
http://www.uwgb.edu/dutchs/symmetry/archpol.htm



- Analysis
  - Normals
  - Curvature
- Warps
  - Rotate
  - Deform
- Filters
  - Smooth
  - Sharpen
  - Truncate
  - **≻**Bevel







Wikipedia

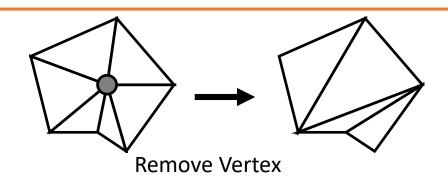


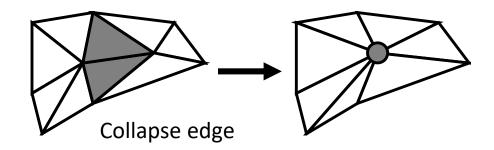
- Remeshing
  - Subdivide
  - Resample
  - Simplify
- Topological fixup
  - Fill holes
  - Fix self-intersections
- Boolean operations
  - Crop
  - Subtract

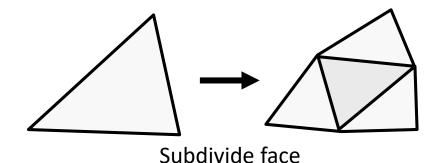


#### Remeshing

- Subdivide
- Resample
- Simplify
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  - Fix self-intersections
- Boolean operations
  - Crop
  - Subtract

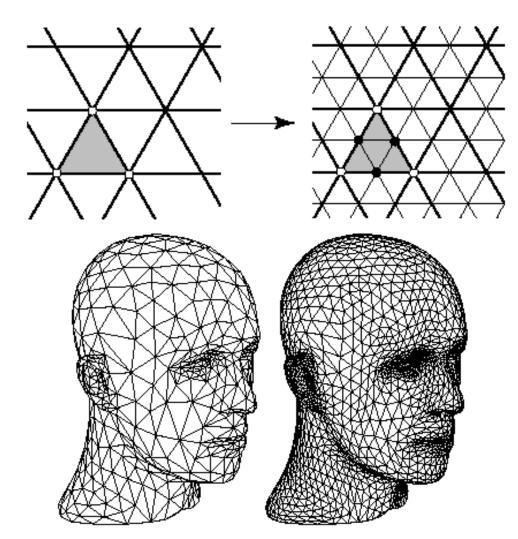








- Remeshing
  - **≻**Subdivide
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Zorin & Schroeder

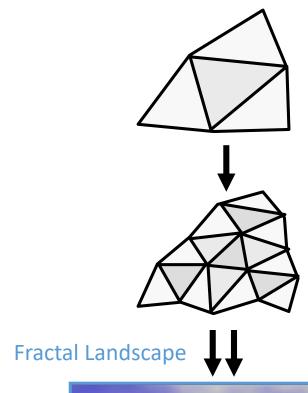


- Remeshing
  - **≻**Subdivide
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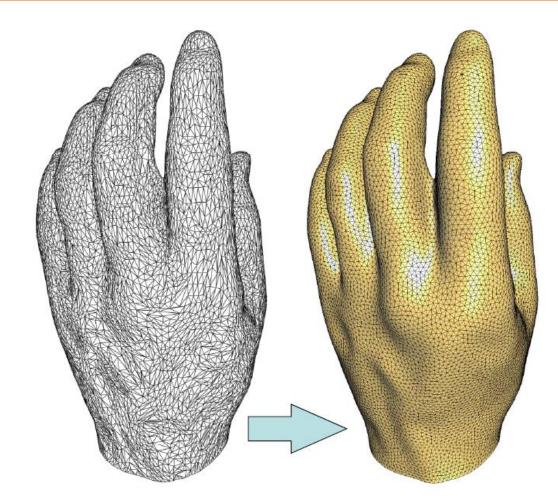




Dirk Balfanz, Igor Guskov, Sanjeev Kumar, & Rudro Samanta,



- Remeshing
  - Subdivide
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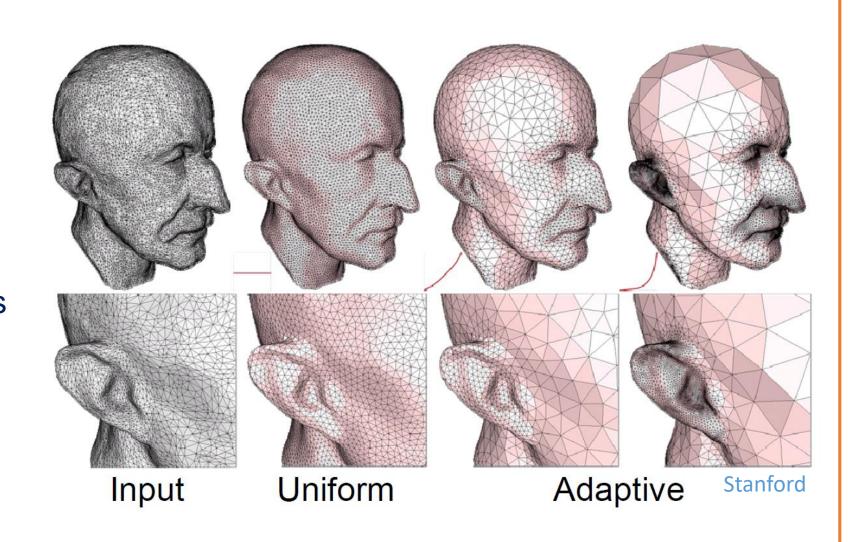


Stanford

- more uniform distribution
- triangles with nicer aspect

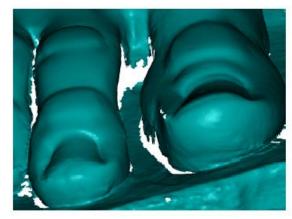


- Remeshing
  - Subdivide
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  - **>**Simplify
- Topological fixup
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- Remeshing
  - Subdivide
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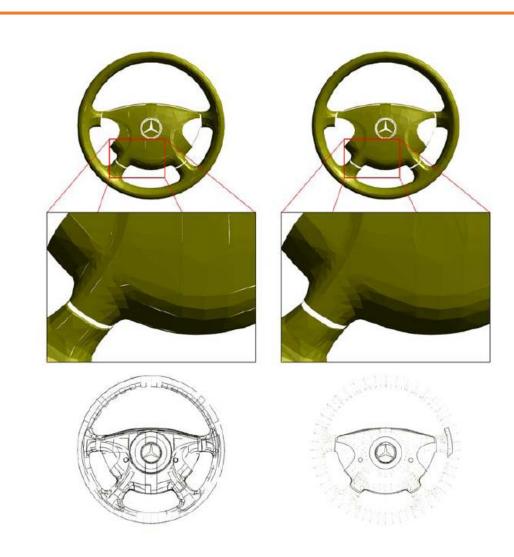






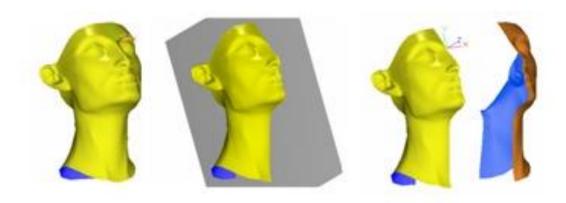


- Remeshing
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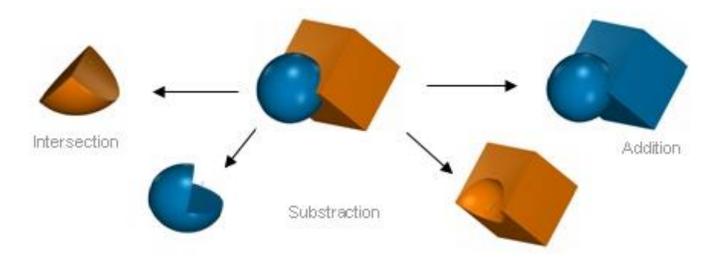




- Remeshing
  - Subdivide
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  - Simplify
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  - Fix self-intersections
- Boolean operations
  - **≻**Crop
  - **≻**Subtract
  - >Etc.



Mesh separation processed by a boolean operation.



Several Boolean operations with 3DReshaper®

## **Summary**



- Polygonal meshes
  - Most common surface representation
  - Fast rendering
- Processing operations
  - Must consider irregular vertex sampling
  - Must handle/avoid topological degeneracies
- Representation
  - Which adjacency relationships to store depend on which operations must be efficient

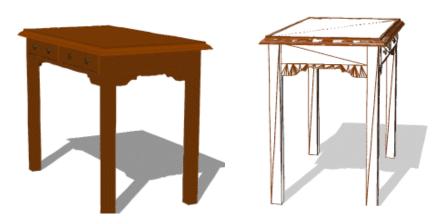
#### 3D Polygonal Meshes



#### Properties

- ? Efficient display
- ? Easy acquisition
- ? Accurate
- ? Concise
- ? Intuitive editing
- ? Efficient editing
- ? Efficient intersections
- ? Guaranteed validity
- ? Guaranteed smoothness
- ? etc.





#### 3D Polygonal Meshes



- Properties
  - ©Efficient display
  - ©Easy acquisition
  - **Accurate**
  - **©**Concise
  - Intuitive editing
  - **®**Efficient editing
  - **©**Efficient intersections
  - **⊗Guaranteed validity**
  - ⊗Guaranteed smoothness



