

Light Control Service

Base UUID: **4F770000ED7D-11E4-840E-0002A5D5C51B**

Service UUID: **0x0101**

Abstract:

This service exposes measurement data and control methods for lights intended to use with a bicycle.

Summary:

Service Dependencies:

This service is not dependent upon any other service.

GATT Requirements

Sub-Procedure	Server Requirement
Write Characteristic Value	C1
Notifications	Mandatory
Indications	C1
Read Characteristic Descriptors	Mandatory
Write Characteristic Descriptors	Mandatory

C1: Mandatory if the LC Control Point characteristic is supported, otherwise excluded for this service.

Transport Dependencies

Transport	Supported
Classic	false
Low Energy	true
High Speed	false

Error Codes

Name	Code	Description

Service Characteristics

Overview	Properties		Security	Descriptors		
Name: Light Measurement Requirement: Mandatory	Property	Requirement	None	Overview	Permissions	
	Read	Optional		Name: Client Characteristic Configuration Requirement: Mandatory	Perm.	Req.
	Write	Excluded			Read	Mandatory
	WriteWithoutResponse	Excluded			Write	Mandatory
	SignedWrite	Excluded				
	Notify	Mandatory				
	Indicate	Excluded				
	WriteableAuxiliaries	Excluded				
	Broadcast	Excluded				
	ExtendedProperties					
Name: Light Feature Requirement: Mandatory	Property	Requirement	None	None		
	Read	Mandatory				
	Write	Excluded				
	WriteWithoutResponse	Excluded				
	SignedWrite	Excluded				
	Notify	Excluded				
	Indicate	Excluded				
	WriteableAuxiliaries	Excluded				
	Broadcast	Excluded				
	ExtendedProperties					
Name: Light Control Point Requirement: Optional	Property	Requirement	None	Overview	Permissions	
	Read	Excluded		Name: Client Characteristic Configuration Requirement: Mandatory	Perm.	Req.
	Write	Mandatory			Read	Mandatory
	WriteWithoutResponse	Excluded			Write	Mandatory
	SignedWrite	Excluded				
	Notify	Excluded				
	Indicate	Mandatory				
	WriteableAuxiliaries	Excluded				
	Broadcast	Excluded				
	ExtendedProperties					

Light Measurement

Characteristic UUID: 0x0102

Summary:

The Light Measurement characteristic is a variable length structure containing a Flags field and, based on the contents of the Flags field, may contain one or more additional fields as shown in the table below.

Value Fields

Names	Field Req.	Format	Additional Information				
Light Type	Mandatory	8bit	Enumeration				
			Key	Value			
			0	Helmet Light			
			1	Bike Light			
			2	Tail Light			
			3-255	Reserved for future use			
Flags	Mandatory	16bit	Bit Field				
			Bit	Size	Name	Definition	
						Key	Value
			0	1	Intensity(s) Field Present	0	False
						1	True
			1	1	Flood/Main Beam Status Field Present	0	False
						1	True
			2	1	Spot/High Beam Status Field Present	0	False
						1	True
			3	1	Flood/Main Beam Output Power Field Present	0	False
						1	True
			4	1	Spot/High Beam Output Power Field Present	0	False
						1	True
			5	1	Temperature Field Present	0	False
						1	True
			6	1	Input Voltage Field Present	0	False
						1	True
			7	1	Pitch/Inclination Field Present	0	False
						1	True
			8	1	Battery SOC Present	0	False
1	True						

			<table><tr><td rowspan="2">9</td><td rowspan="2">1</td><td rowspan="2">Taillight Output Power Field Present</td><td>0</td><td>False</td></tr><tr><td>1</td><td>True</td></tr><tr><td>10</td><td>6</td><td>Reserved fur future use</td><td colspan="2"></td></tr></table>	9	1	Taillight Output Power Field Present	0	False	1	True	10	6	Reserved fur future use																																																	
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Helmet Setup	Mandatory for Light Type “Helmet Light”, otherwise excluded	8bit	<table><tr><th colspan="5">Bit Field</th></tr><tr><th rowspan="2">Bit</th><th rowspan="2">Size</th><th rowspan="2">Name</th><th colspan="2">Definition</th></tr><tr><th>Key</th><th>Value</th></tr><tr><td rowspan="2">0</td><td rowspan="2">1</td><td rowspan="2">Flood active</td><td>0</td><td>False</td></tr><tr><td>1</td><td>True</td></tr><tr><td rowspan="2">1</td><td rowspan="2">1</td><td rowspan="2">Spot active</td><td>0</td><td>False</td></tr><tr><td>1</td><td>True</td></tr><tr><td rowspan="2">2</td><td rowspan="2">1</td><td rowspan="2">Pitch compensation</td><td>0</td><td>Disabled</td></tr><tr><td>1</td><td>Enabled</td></tr><tr><td rowspan="2">3</td><td rowspan="2">1</td><td rowspan="2">Output cloned</td><td>0</td><td>False</td></tr><tr><td>1</td><td>True</td></tr><tr><td rowspan="2">4</td><td rowspan="2">1</td><td rowspan="2">External Taillight</td><td>0</td><td>Disabled</td></tr><tr><td>1</td><td>Enabled</td></tr><tr><td rowspan="2">5</td><td rowspan="2">1</td><td rowspan="2">External Brake-light</td><td>0</td><td>Disabled</td></tr><tr><td>1</td><td>Enabled</td></tr><tr><td>6</td><td>2</td><td>Reserved fur future use</td><td colspan="2"></td></tr></table>	Bit Field					Bit	Size	Name	Definition		Key	Value	0	1	Flood active	0	False	1	True	1	1	Spot active	0	False	1	True	2	1	Pitch compensation	0	Disabled	1	Enabled	3	1	Output cloned	0	False	1	True	4	1	External Taillight	0	Disabled	1	Enabled	5	1	External Brake-light	0	Disabled	1	Enabled	6	2	Reserved fur future use		
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Helmet Intensity Information: Unit is is in percentage with a resolution of 1, in relation to maximum output power. In a setup with activated pitch compensation the unit is in lux with a resolution of 1, representing the luminescence under intended use Unit: org.bluetooth.unit.percentage org.bluetooth.unit.illuminance.lux Exponent: Decimal, 0	Optional for Light Type “Helmet Light”, otherwise excluded	uint8																																														
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Flood Output Power Information: Unit is in watts with a resolution of 1/1000.	Optional for Light Type “Helmet Light”,	uint16																																														

Unit: org.bluetooth.unit.power.watt Exponent: Decimal, -3	otherwise excluded		
Main Beam Output Power Information: Unit is in watts with a resolution of 1/1000. Unit: org.bluetooth.unit.power.watt Exponent: Decimal, -3	Optional for Light Type “Bike Light”, otherwise excluded	uint16	
Spot Output Power Information: Unit is in watts with a resolution of 1/1000. Unit: org.bluetooth.unit.power.watt Exponent: Decimal, -3	Optional for Light Type “Helmet Light”, otherwise excluded	uint16	
High Beam Output Power Information: Unit is in watts with a resolution of 1/1000. Unit: org.bluetooth.unit.power.watt Exponent: Decimal, -3	Optional for Light Type “Bike Light”, otherwise excluded	uint16	
Temperature Information: Unit is in degree Celsius with a resolution of 1. Unit: org.bluetooth.unit.thermodynamic_temperature.degree_celsius Exponent: Decimal, 0	Optional	int8	
Input Voltage Information: Unit is in volts with a resolution of 1/1000. Unit: org.bluetooth.unit.electric_potential_difference.volt Exponent: Decimal, -3	Optional	uint16	
Pitch Information: Unit is in degree with a resolution of 1. Unit: org.bluetooth.unit.plane_angle.degree Exponent: Decimal, 0	Optional for Light Type “Helmet Light”, otherwise excluded	int8	
Inclination Information: Unit is in degree with a resolution of 1. Unit: org.bluetooth.unit.plane_angle.degree Exponent: Decimal, 0	Optional for Light Type “Bike Light”, otherwise excluded	int8	
Battery State of Charge Information:	Optional	uint8	

Unit is in percentage with a resolution of 1 Unit: org.bluetooth.unit.percentage Exponent: Decimal, 0			
Taillight Output Power Information: Unit is in watts with a resolution of 1/1000. Unit: org.bluetooth.unit.power.watt Exponent: Decimal, -3	Optional	uint16	

Light Feature

Characteristic UUID: 0x0103

Summary:

The Light Feature characteristic is used to report a list of features supported by the device.

Value Fields

Names	Field Req.	Format	Additional Information				
Light Type	Mandatory	8bit	Enumeration				
			Key	Value			
			0	Helmet Light			
			1	Bike Light			
			2	Tail Light			
			3-255	Reserved for future use			
Configuration Features	Mandatory	8bit	Bit Field				
			Bit	Size	Name	Definition	
						Key	Value
			0	1	Mode Change Supported	0	False
						1	True
			1	1	Mode Configuration Supported	0	False
						1	True
			2	1	Mode Grouping Supported	0	False
						1	True
			3	1	Preferred Mode Supported	0	False
						1	True
			4	1	Temporary Mode Supported	0	False
						1	True
			5	3	Reserved for future use		
Setup Features	Mandatory	8bit	Bit Field				
			Bit	Size	Name	Definition	
						Key	Value
			0	1	LED configuration check supported	0	False
						1	True
			1	1	Sensor offset calibration supported	0	False
						1	True

			<table><tr><td rowspan="2">2</td><td rowspan="2">1</td><td rowspan="2">Current limitation supported</td><td>0</td><td>False</td></tr><tr><td>1</td><td>True</td></tr><tr><td>3</td><td>5</td><td>Reserved for future use</td><td colspan="2"></td></tr></table>	2	1	Current limitation supported	0	False	1	True	3	5	Reserved for future use																																																	
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Tail Light Feature	Mandatory for devices of type Tail Light, otherwise excluded	16bit	tbd.
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Light Control Point

Characteristic UUID: **0x0104**

Summary:

The Light Control Point characteristic is used to request a specific function to be executed on the receiving device.

Value Fields

Names	Field Req.	Format	Additional Information		
Op Codes	Mandatory	uint8	Enumerations		
			Key	Value	Description
			1	Request mode Count	Request the number of modes supported by the light. The response is Op Code 0x20 followed by the mode count (in uint8). The maximum number of supported modes is 16 and has always to be a power of 2.
			2	Set Mode	Initiate the procedure to put the light into a specific mode. The requested mode is sent as an uint8 with preceding Op Code 0x02 operand. The response to this control point is Op Code 0x20. To put the light in off mode send an invalid mode number.
			3	Request group configuration	Request current mode grouping configuration. The response is Op Code 0x20 followed by the current number of groups (in uint8) and optionally an array with the number of modes in each group. If no array is transmitted, the light doesn't support the individual modes grouping and the modes are equally distributed.
			4	Set group configuration	Initiate the procedure to change the group configuration. The new number of groups (must be a power of two if no array is added) and optionally an array with the number of modes in each group are sent as uint8s with preceding Op Code 0x04 operand. The response to this control point is Op Code 0x20.
			5	Request mode configuration	Request a list of mode configurations. The mode list start number is sent as uint8 with preceding Op Code 0x05

					<p>operand. The response to this control point is Op Code 0x20 followed by the list as response parameter.</p> <p>NOTE: If the list exceeds the maximum length of the indication packet it will be truncated. To receive the complete list of modes the host has to call this procedure multiple times with different start values.</p>
			6	Set mode configuration	<p>Initiate the procedure to change a set of mode configurations. The new configurations are sent as an uint8 (representing the first mode number to change) followed by a list of configurations (each containing an uint8 representing the setup and an uint8 representing the intensity, respectively two uint8 for main and high beam) with preceding Op Code 0x06 operand. The response to this control point is Op Code 0x20</p>
			7	Request LED configuration	<p>Request the LED configuration setup. The response is Op Code 0x20 followed by the number of installed LEDs of the flood/main beam driver followed by the number if LEDs if the spot/high beam driver.</p>
			8	Start LED configuration check	<p>Initiate the procedure to start the detection of installed LED configuration. The response to this control point is Op Code 0x20 followed by the number of installed LEDs of the flood/main beam driver followed by the number if LEDs if the spot/high beam driver.</p>
			9	Request Sensor Offset	<p>Request the current Sensor Offset Values. The response is Op Code 0x20 followed by the offset values for x, y, z axis (in int16 each). If no offset values are available yet, the response value shall be set to 0x04.</p>
			10	Start Sensor Offset Calibration	<p>Initiate the procedure to start the sensor offset calibration. The response to this control point is 0x20 followed by the new offset values for x, y and z-axis (int16 each).</p>
			11	Request Current Limit	<p>Request the current current limits. The response is Op Code 0x20 followed by the current limits (in int8 representing %)</p>

			12	Set Current Limit	Initiate the procedure to change the current limits. The new limits is sent as a pair of int8 (the first representing the limit for flood/main beam, the second for spot/high beam, both in %) with preceding Op Code 0x0C operand. The response to this control point is Op Code 0x20.
			13	Request Preferred Mode	Request the currently preferred mode. The response is Op Code 0x20 followed by the preferred mode. If no preferred mode is set, the response is an invalid mode number
			14	Set Preferred Mode	Initiate the procedure to set the preferred mode. The new preferred mode is sent as an uint8 with preceding Op Code 0x02 operand. The response to this control point is Op Code 0x20. To disable the preferred mode send an invalid mode number.
			15	Request Temporary Mode	Request the current temporary mode. The response is Op Code 0x20 followed by the preferred mode. If no temporary mode is set, the response is an invalid mode number
			16	Set Temporary Mode	Initiate the procedure to set the temporary mode. The new temporary mode is sent as an uint8 with preceding Op Code 0x02 operand. The response to this control point is Op Code 0x20. To disable the temporary mode send an invalid mode number.
			32	Response Code	The response code is followed by the requested Op Code, the response value and optionally the response parameter
			0-0	Reserved for future use	
			17-31	Reserved for future use	
			33-255	Reserved for future use	
Parameter Value	Optional	variable	Refer to the Op Code table above for additional information on the possible values for this filed		
Request Op Code Information: The Request Op Code is a sub field of the Parameter Value for "Response Code" Op Code. C1: This Field is Mandatory for	C1	uint8	Refer to the Op Code table above for additional information on the possible values for this filed		

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Response Parameter Information: The Response Parameter is a sub field of the Parameter Value for "Response Code" Op Code. C2:This Field is Optional for "Response Code" Op Code, otherwise this field is Excluded.	C2	variable	Note: The Response Parameter Value of the response to the Control Point is a variable length field to allow a list of different values defined by the Service Specification																								

