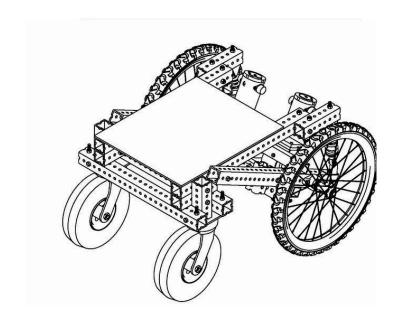
UGV Design



Why design the frame from scratch?

Using an existing base will require require a lot of modification





Why design the frame from scratch? (Continued)

- The effort required to make modifications will approximately be the same designing the frame from scratch
- More freedom in the design process
- Flexibility to add components/features later down the line
- Making the frame from scratch would assure 100% reproducibility

Components and Budget (Rough Calculation)

	Item	Quantity	Price per item (Rs)
1	Hub Wheel Motor + Motor Controller	4	12,000
2	Car Frame	1	20,000
3	Battery	1	14,000
4	Arduino Mega	1	1200
			Total = 83200

Project Division

The project will be divided in a total of 5 parts

Milestone 1	Milestone 2	Milestone 3	Milestone 4	Milestone 5
Design and Fabrication of the car	Configuring the electronics	Implementing low level control	Fine tuning the motion	Implementation of high level algorithms
 CAD design Stress Analysis Frame Assembly Fitting the motors 	 Setting up power supply Configuring the motor controllers Designing the circuits as needed 	 Making a low level API for the control Establishing tethered control Establishing untethered control Establishing RC control 	 Applying a pid loop to achieve precise motion Applying Sensor fusion techniques to combine and extract the relevant data from the sensors 	 Computer Vision Slam Synchronization with a drone for a complex task

Timeline

Milestones 1-4 will take up a total of 2 months

	Description	Duration
Milestone 1	Designing and Fabrication	1 month
Milestone 2	Configuring the Electronics	10 Days
Milestone 3	Implementation of Low level control	10 days
Milestone 4	Fine tuning of motion	10 days

Is the project feasible in my opinion?

The project is achievable within a span of 2 months given the availability of

- Relevant Manpower
- Relevant tools
- Components