

# COMP4901Y Homework 1

## Question 1. Einstein Notation in PyTorch (15 points).

Implement the following operations according to PyTorch Einstein notations:

- 4D tensor element-wise multiplication given input tensors  $\mathbf{a}, \mathbf{b} \in \mathbb{R}^{d_1 \times d_2 \times d_3 \times d_4}$ , output should be  $\mathbf{c} \in \mathbb{R}^{d_1 \times d_2 \times d_3 \times d_4}$ ;
- Batch transposed matrix multiplication given input tensor  $\mathbf{a} \in \mathbb{R}^{d_1 \times d_2 \times d_3 \times d_4}$ ,  $\mathbf{b} \in \mathbb{R}^{d_5 \times d_4}$ , output should be  $\mathbf{c} \in \mathbb{R}^{d_1 \times d_2 \times d_3 \times d_5}$ ;
- Aggregate a 4D tensor through the 3rd dimension given input tensor  $\mathbf{a} \in \mathbb{R}^{d_1 \times d_2 \times d_3 \times d_4}$ , output should be  $\mathbf{a}' \in \mathbb{R}^{d_1 \times d_2 \times d_4}$ .

**Submission.** This part should be submitted in a python file named `question1.py` by fill the missing part in the corresponding sample code.

## Question 2. Training a two-layer MLP *without* PyTorch Autograd (25 points).

Implement an SGD training algorithm to train a simple 2-layer MLP regression model based on the L2 loss defined below *without* using pytorch autograd.

- Input:  $\mathbf{X} \in \mathbb{R}^{N \times D}$ ,  $\mathbf{Y} \in \mathbb{R}^{N \times 1}$
- Model parameters:  $\mathbf{W}_1 \in \mathbb{R}^{D \times H}$ ,  $\mathbf{W}_2 \in \mathbb{R}^{H \times 1}$
- Forward computation (each iteration samples a single data point  $(\mathbf{x}_t \in \mathbb{R}^{1 \times D}, y_t \in \mathbb{R})$ ):
  - $\mathbf{a} = \mathbf{x}_t \mathbf{W}_1$
  - $\mathbf{a}' = \text{relu}(\mathbf{a})$
  - $y' = \mathbf{a}' \mathbf{W}_2$
  - $l = (y' - y_t)^2$
- Backward computation:
  - Construct the backward computation for the linear layer as we discussed in class;
  - The derivative of the relu function can be computed by:

$$\frac{df_{\text{relu}}(a)}{da} = \begin{cases} 1 & a \geq 0 \\ 0 & a < 0 \end{cases}$$

- SGD update:
  - Use a fixed learning rate of 0.03 (tunable hyper-parameter), no momentum;
  - Implement sampling with replacement;
- Run the  $10^5$  iteration of the SGD iteration. Record the loss for every 100 iterations. Plot the results as we introduced in class.

**Submission.** This question should be submitted by:

- A Python file named `question2.py` fills in the missing part in the corresponding sample code.
- A pdf file named `question2_result.pdf` to visualize the convergence result.

## Question 3. Transfer Learning by PyTorch Autograd (20 points).

PyTorch provides a set of pre-trained models; for example, you can load a resnet18 model by the following statement:

```
resnet18_model = torchvision.models.resnet18(weights='IMAGENET1K_V1')
```

We want to use the intermediate convolutional layers defined in this resnet18\_model but change the fc layer to fit the FashionMNIST dataset, as we demoed in our class. Here are some additional notes:

- You need to change the output dimensions of the last fc layer;
- You need to change the input dimensions of the first input layer;
- You need to tune the SGD hyper-parameters in the following sets and use the optimal setting in your submitted script.
  - Batch size: 16, 64
  - Learning rate: 0.01, 0.03
  - Momentum : 0.0, 0.9
- Run the 2 epochs of the training. Record the loss and plot the results as we introduced in class.

**Submission.** This part should be submitted with:

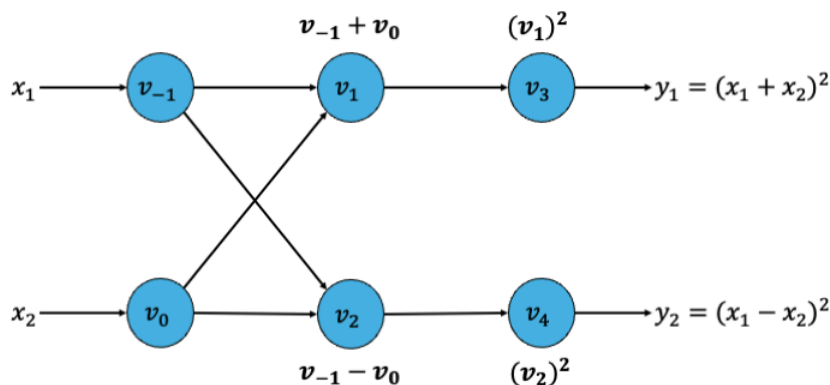
- A Python file named `question3.py` fills in the missing part in the corresponding sample code.
- A pdf file named `question3_result.pdf` of convergence result.

### Question 4. Auto-Diff Example (30 points).

Given the following function  $\mathbf{y} = f(\mathbf{x}) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by:

$$\begin{aligned} y_1 &= (x_1 + x_2)^2 \\ y_2 &= (x_1 - x_2)^2 \end{aligned}$$

One way to construct the computation graph is as follows:



Please fill the following tables to compute the Jacobin matrix at the point  $x_1 = 2, x_2 = 4$ :

- Table 1: forward mode to compute  $\frac{\partial y_1}{\partial x_1}, \frac{\partial y_2}{\partial x_1}$ :

| Forward Primal       | Value | Forward Tangent            | Value |
|----------------------|-------|----------------------------|-------|
| $v_{-1} = x_1$       | 2     | $\dot{v}_{-1} = \dot{x}_1$ | 1     |
| $v_0 = x_2$          | 4     | $\dot{v}_0 = \dot{x}_2$    | 0     |
| $v_1 = v_{-1} + v_0$ |       | $\dot{v}_1$                |       |
| $v_2 = v_{-1} - v_0$ |       | $\dot{v}_2$                |       |
| $v_3 = (v_1)^2$      |       | $\dot{v}_3$                |       |
| $v_4 = (v_2)^2$      |       | $\dot{v}_4$                |       |
| $y_1 = v_3$          |       | $\dot{y}_1 = \dot{v}_3$    |       |
| $y_2 = v_4$          |       | $\dot{y}_2 = \dot{v}_4$    |       |

- Table 2: forward mode to compute  $\frac{\partial y_1}{\partial x_2}, \frac{\partial y_2}{\partial x_2}$ :

| Forward Primal       | Value | Forward Tangent            | Value |
|----------------------|-------|----------------------------|-------|
| $v_{-1} = x_1$       | 2     | $\dot{v}_{-1} = \dot{x}_1$ | 0     |
| $v_0 = x_2$          | 4     | $\dot{v}_0 = \dot{x}_2$    | 1     |
| $v_1 = v_{-1} + v_0$ |       | $\dot{v}_1$                |       |
| $v_2 = v_{-1} - v_0$ |       | $\dot{v}_2$                |       |
| $v_3 = (v_1)^2$      |       | $\dot{v}_3$                |       |
| $v_4 = (v_2)^2$      |       | $\dot{v}_4$                |       |
| $y_1 = v_3$          |       | $\dot{y}_1 = \dot{v}_3$    |       |
| $y_2 = v_4$          |       | $\dot{y}_2 = \dot{v}_4$    |       |

- Table 3: reverse mode to compute  $\frac{\partial y_1}{\partial x_1}, \frac{\partial y_1}{\partial x_2}$ :

| Forward Primal       | Value | Reverse Adjoint            | Value |
|----------------------|-------|----------------------------|-------|
| $v_{-1} = x_1$       | 2     | $\bar{x}_1 = \bar{v}_{-1}$ |       |
| $v_0 = x_2$          | 4     | $\bar{x}_2 = \bar{v}_0$    |       |
| $v_1 = v_{-1} + v_0$ |       | $\bar{v}_{-1}$             |       |
|                      |       | $\bar{v}_0$                |       |
| $v_2 = v_{-1} - v_0$ |       | $\bar{v}_{-1}$             |       |
|                      |       | $\bar{v}_0$                |       |
| $v_3 = (v_1)^2$      |       | $\bar{v}_1$                |       |
| $v_4 = (v_2)^2$      |       | $\bar{v}_2$                |       |
| $y_1 = v_3$          |       | $\bar{y}_1 = \bar{v}_3$    | 1     |
| $y_2 = v_4$          |       | $\bar{y}_2 = \bar{v}_4$    | 0     |

- Table 4: reverse mode to compute  $\frac{\partial y_2}{\partial x_1}, \frac{\partial y_2}{\partial x_2}$ :

| Forward Primal       | Value | Reverse Adjoint            | Value |
|----------------------|-------|----------------------------|-------|
| $v_{-1} = x_1$       | 2     | $\bar{x}_1 = \bar{v}_{-1}$ |       |
| $v_0 = x_2$          | 4     | $\bar{x}_2 = \bar{v}_0$    |       |
| $v_1 = v_{-1} + v_0$ |       | $\bar{v}_{-1}$             |       |
|                      |       | $\bar{v}_0$                |       |
| $v_2 = v_{-1} - v_0$ |       | $\bar{v}_{-1}$             |       |
|                      |       | $\bar{v}_0$                |       |
| $v_3 = (v_1)^2$      |       | $\bar{v}_1$                |       |
| $v_4 = (v_2)^2$      |       | $\bar{v}_2$                |       |
| $y_1 = v_3$          |       | $\bar{y}_1 = \bar{v}_3$    | 0     |
| $y_2 = v_4$          |       | $\bar{y}_2 = \bar{v}_4$    | 1     |

- [Optional]: Think about whether the Jacobin matrix will change when we reformulate  $\mathbf{y} = f(\mathbf{x}) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  as:

$$\begin{aligned} y_1 &= x_1^2 + 2x_1x_2 + x_2^2 \\ y_2 &= x_1^2 - 2x_1x_2 + x_2^2 \end{aligned}$$

**Submission.** This part should be submitted with:

- A pdf file named **question4.pdf** to include Table 1, Table 2, Table 3, and Table 4.

### Question 5. Gradient Computation in FC Layer (10 points).

Following the computation introduced in Slides 29-31 of Lecture 4, verify that  $\frac{\partial L}{\partial \mathbf{W}} = \mathbf{X}^T \frac{\partial L}{\partial \mathbf{Y}}$ .

**Submission.** This part should be submitted with:

- A pdf file named **question5.pdf** to include the computation.
- Latex is recommended for equation editing.

### Submission Checklist.

You should submit a zip file including the following components:

- **question1.py**
- **question2.py**
- **question2\_result.pdf**
- **question3.py**
- **question3\_result.pdf**
- **question4.pdf**
- **question5.pdf**