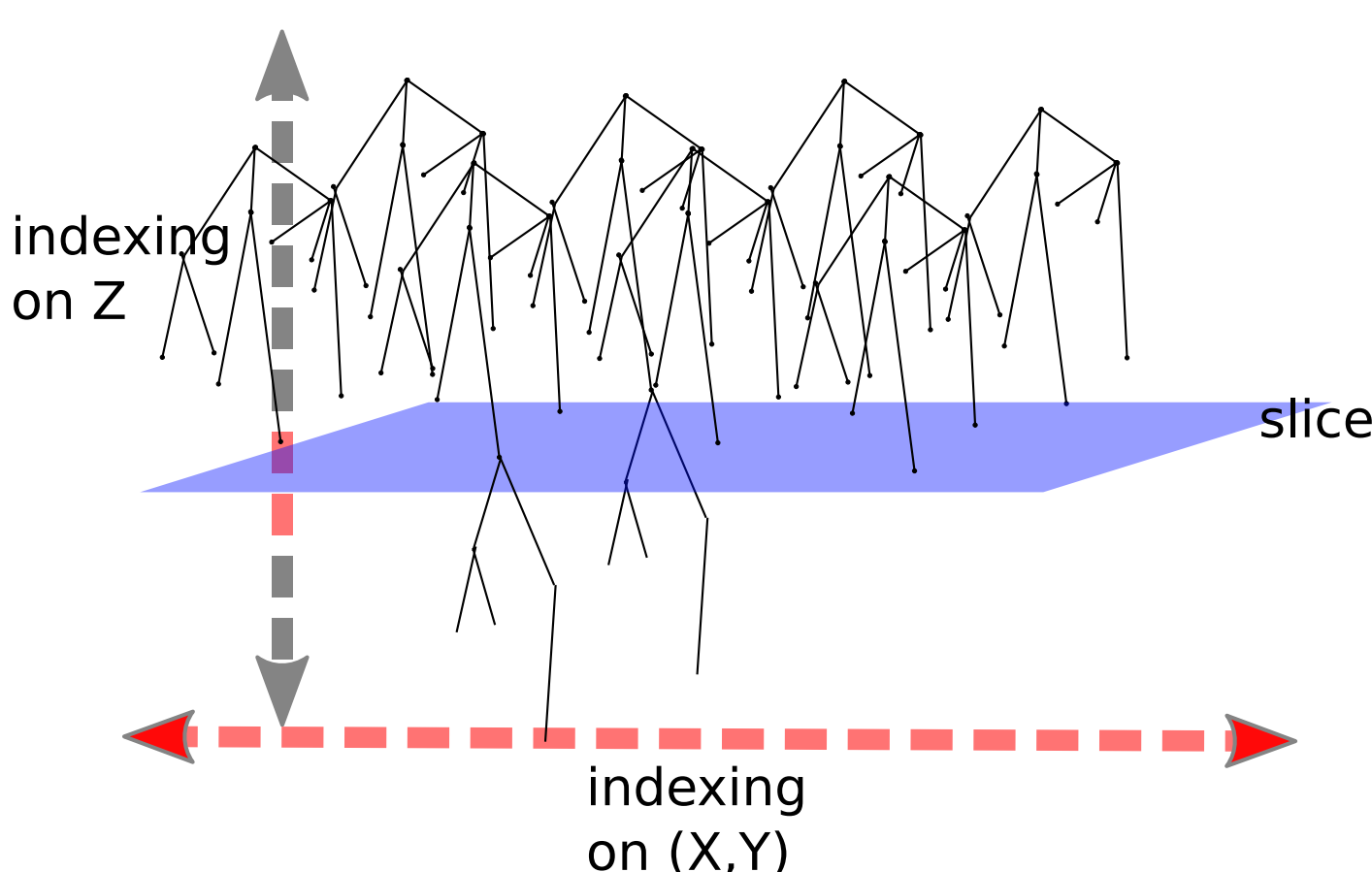
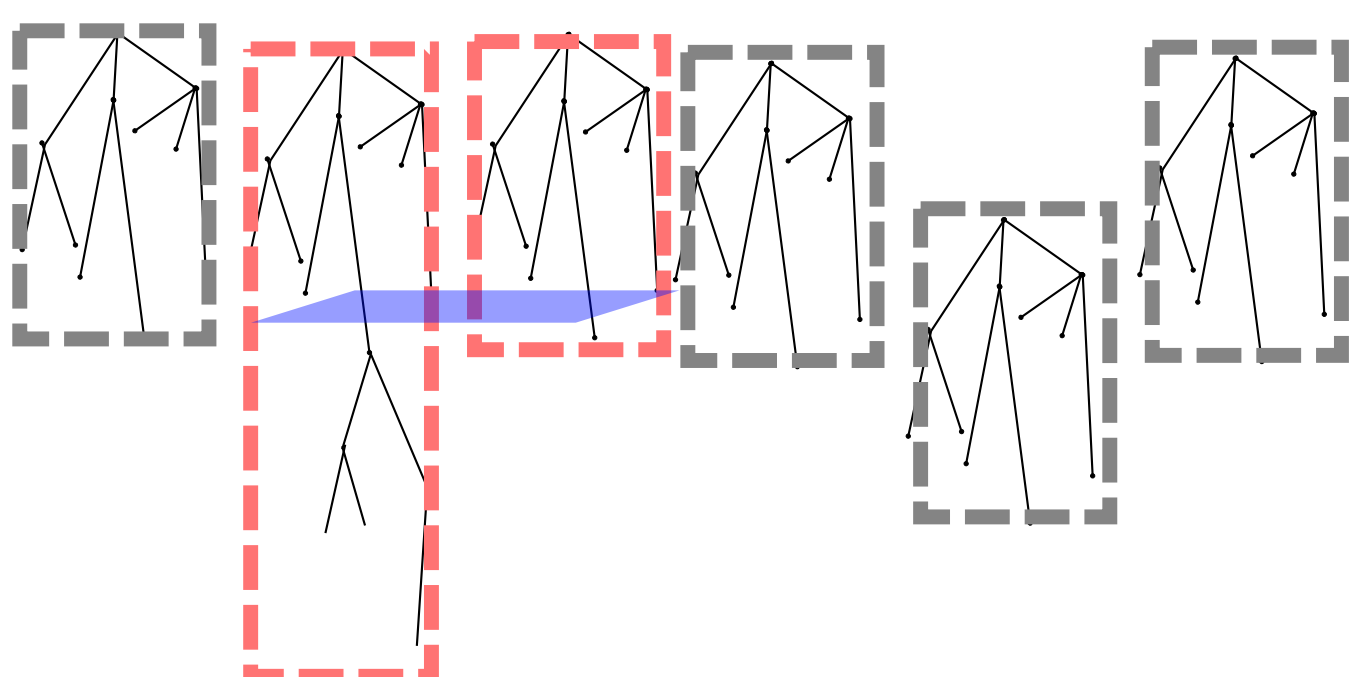


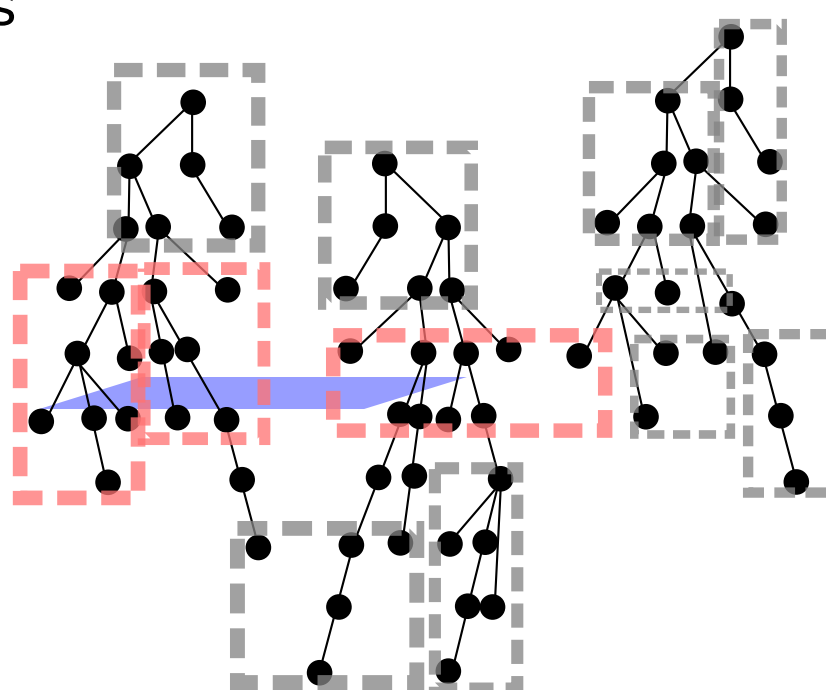
Scenario A.1 : you can separate your data using mainly Z + (X,Y)



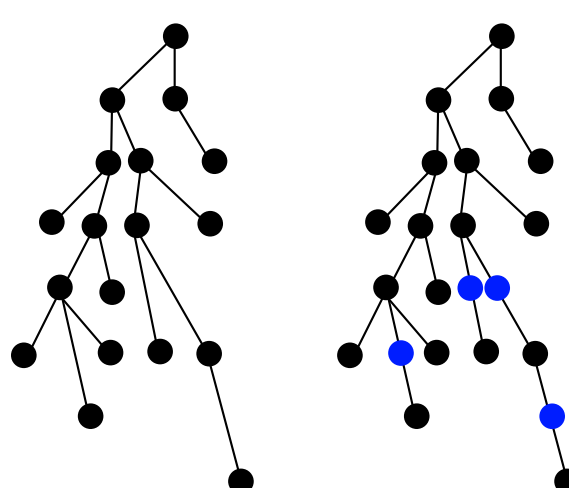
Scenario A.2 : you can separate your data based on trees bbox



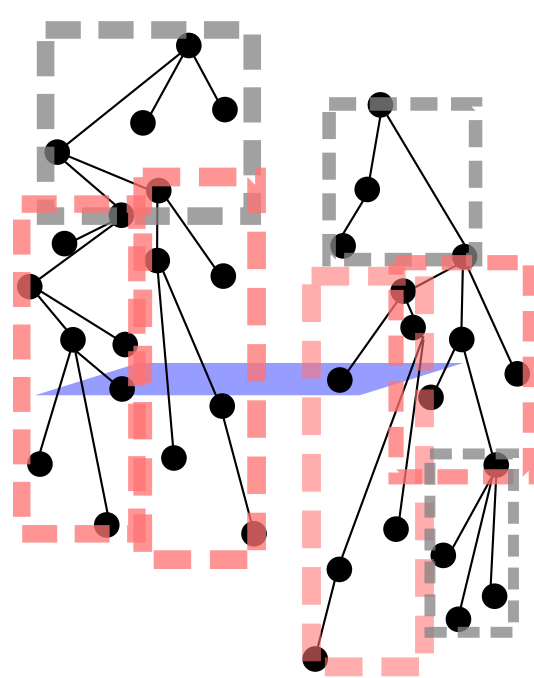
Scenario B.1.1 : your edges are logical, nodes are regularly placed in Z dimension. Work on nodes, use pgpointcloud and patches



Scenario B.1.2 : your edges are logical, nodes are **not** regularly placed in Z dimension : you can add node to be in B.1.1



Scenario B.2 : your edges are actual neuron path. Use a 2 steps strategy by creating indexed groups of edges BBox.



Scenario C : You want super scaling without hassle: partition your data across several tables.

