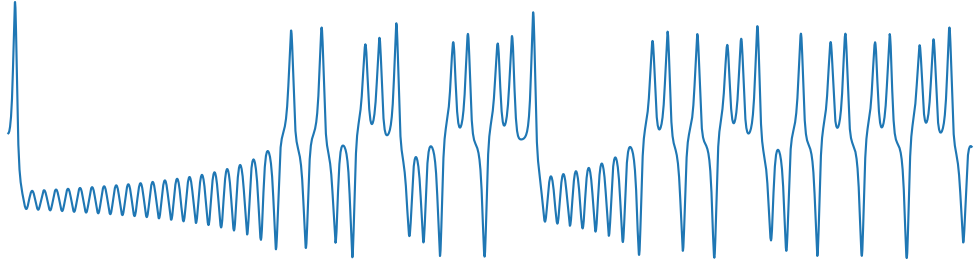
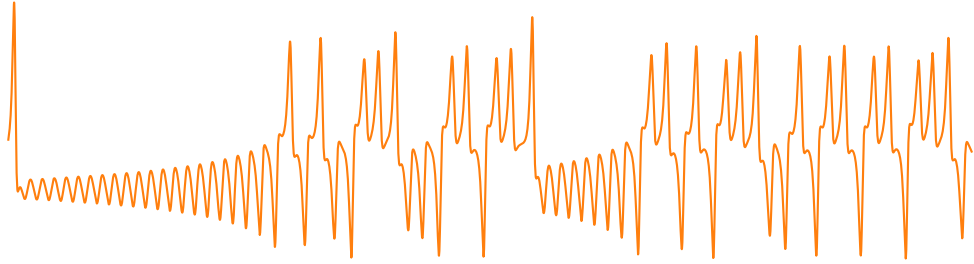


$x(t)$



$y(t)$



$z(t)$

