



CAIRO UNIVERSITY - FACULTY OF ENGINEERING

COMPUTER ENGINEERING DEPARTMENT

COMPUTER NETWORKS PROJECT

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## Team One

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# 1 Overall System

Our system is a **Centralized Network**, consisting of  $N$  nodes connected to a hub, the number of nodes  $N$  are given from external file. This topology is, also, referred to as *star network*. Since, we use *full-duplex* communication, then each **node** acts as a sender and a receiver at the same time, sending data and acknowledges (*piggybacked*).

The **hub** has the following functionalities:

- Allocate sessions between nodes.
- Navigate packets and acknowledges between peers.
- It's considered the control device of access medium, so it's responsible for the different types of channel noise.
- Gather the required statistics for each node.

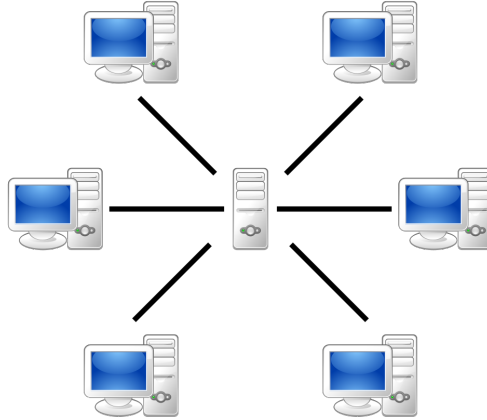


Figure 1: Centralized Star Network.

## 2 Implemented Functionalities

### 2.1 Hamming Code (Error Detection/Correction)

*Hamming code* is implemented to handle 1-bit error detection and correction. Since the message modification can only be of 1 bit, the usage of hamming code ensures that **no corrupted frames** are received. The algorithm implementation follows exactly the hamming code algorithm. *Hamming code* is applied on the message payload and the result is padded with zeros to be sent as a **string of characters**.

The implementation of the *hamming code* algorithm can be found in `src/Node.cc` under two functions :

- `string Node::computeHamming(string s, int &to_pad);`  

```
std::string Node::computeHamming(std::string s, int &to_pad)
{
    int str_length = s.length();
    int m = 8 * str_length;
    int r = 1;
    while(m + r + 1 > pow(2, r))
    {
        r++;
    }
    ...
}
```
- `string Node::decodeHamming(string s, int padding);`  

```
std::string Node::decodeHamming(std::string s, int padding)
{
    if (!s.size())
    {
        return "";
    }
    int str_length = s.length();
    int mr = 8 * str_length - padding;
    int r = 1;
    while(mr + 1 > (pow(2,r)))
    {
        r++;
    }
}
```

```

}
...
}

```

## 2.2 Character Count (Framing)

*Character Count* is implemented as a **framing method** of the transmitted message. It is applied to the **message payload** to count characters of the string and **prepend** the count as one byte to the beginning of the **message payload**. The *decoding* is done in the same manner. *Character count* framing is applied **before** hamming code.

The implementation of the *character count* algorithm can be found in `src/Node.cc` under two functions :

- `string Node::addCharCount(string msg);`

```

std::string Node::addCharCount(std::string msg)
{
    uint8_t msg_size = (uint8_t) msg.size() + 1;
    std::string framed_msg = "";
    framed_msg += msg_size;
    framed_msg += msg;
    return framed_msg;
}

```
- `bool Node::checkCharCount(string &msg);`

```

bool Node::checkCharCount(std::string &msg)
{
    if (!msg.size())
    {
        return false;
    }
    int msg_size = (int)msg[0] - 1;
    msg.erase(msg.begin());
    if (msg_size == msg.size())
    {
        return true;
    }
    return false;
}

```

## 2.3 Go Back N (Sliding Window Protocol)

The used **data link protocol** is *Go Back N*, where the sender re-transmits the whole current window upon **acknowledge timeout**. The node can receive a message (*of kind 4*) from the hub, so that it can start talking to another node. Also, the node receives a message (*of kind 5*) to mark the end of the session and it responds with a message (*of kind 4*) to indicate its last acknowledged frame. It can, also, send and receive messages (*of kind 3*) to and from the other node, which contains both data and acknowledges (*piggybacked*). Finally, the node has two kinds of self-messages. *One* is used for marking **acknowledge timeout**, so that the **window pointer** is reset. *Two* is used for sending **piggybacked messages** at certain intervals. Moreover, the node can have 3 states :

1. **Active state** : where the node is currently participating in a session.
2. **Inactive state** : where the node is not in a session.
3. **Dead state** : where the node has no more messages to send.

So, we can summarize our *Go Back N* implementation as follows :

- The node receives a message (*of kind 4*) from the hub, so that it can start transmission.
- The node sends its first **piggybacked message** with acknowledge of  $-1$  and sends a self-message (*of kind 2*) to schedule **next message** to be sent and a self-message (*of kind 1*) to set **acknowledge timeout**.
- When the node receives a message from the other node (*of kind 3*), it decodes the **incoming frame** to advance its **excepted frame count**. Also, it decodes the **incoming acknowledge** to advance its **window**.
- When the node receives self-message (*of kind 1*), it checks whether the window is advanced. Accordingly, it can reset **window pointer**.
- When the node receives self-message (*of kind 2*), it sends the next message to the hub.
- When the session times out, the node receives an "*end session*" message (*of kind 5*) from the hub. The node turns into **inactive state** and sends its last acknowledged frame to the hub.
- If the last message of the node is acknowledged, the node turns into **dead state**.

The implementation of the *Go Back N* protocol can be found in `src/Node.cc` under functions :

- `void Node::handleMessage(cMessage *msg);`

```
void Node::handleMessage(cMessage *msg)
{
    if (!this->is_dead)
    {
        if (msg->isSelfMessage() && !this->is_inactive)
        {
            switch(msg->getKind())
            {
            case 1:
            {
                ...
            }
            case 2:
            {
                ...
            }
            }
            else
            {
                if (msg->getKind() == 3 && !this->is_inactive)
                {
                    ...
                }
                else if (msg->getKind() == 4)
                {
                    ...
                }
                else if (msg->getKind() == 5 && !this->is_inactive)
                {
                    ...
                }
            }
        }
    }
}
```

- `void Node::sendMsg();`

```

void Node::sendMsg()
{
    if (this->S <= this->Sl)
    {
        std::string framed_msg = this->addCharCount(this->msgs[this->S]);
        const char* msg_payload = framed_msg.c_str();
        int padding = 0;
        ...
    }
    cMessage * send_next_self_msg = new cMessage("");
    send_next_self_msg->setKind(2);
    scheduleAt(simTime() + 1 , send_next_self_msg);
}

• void Node::post_receive_ack(cMessage *msg);

void Node::post_receive_ack(cMessage *msg)
{
    if (((Imessage_Base *)msg)->getAcknowledge() == -1)
    {
        return;
    }
    while(this->Sf <= (((Imessage_Base *)msg)->getAcknowledge()))
    {
        this->Sf ++;
    }
    ...
}

• void Node::post_receive_frame(cMessage *msg);

void Node::post_receive_frame(cMessage *msg)
{
    int received_frame_seq_num =
        ((Imessage_Base *)msg)->getSequence_number();
    if (received_frame_seq_num == this->R)
    {
        this->ack = R;
        ...
    }
    bool check = this->checkCharCount(payload);
    if (check)
    {

```



```

EV << " message char count right !" <<endl;
}
else
{
EV << " message char count wrong !" << endl;
}
}
}

```

## 2.4 Transmission Channel Noise Modelling

As mentioned, the hub acts as a **medium controller**, that is why the hub is responsible for adding **noise** and **delay** to the transmitted messages. The implemented noise types are *1-bit modification (on message payload)*, **delay**, **drop** and **duplication**. The noise is added with **random probability** and **multiple types** might be applied on a single message at once.

The implementation of the *noise modelling* can be found in `src/Hub.cc` under function :

- `int Hub::applyNoise(Imessage_Base *msg);`

```

int Hub::applyNoise(Imessage_Base * msg)
{
// generate random action from inverted actions
// ( losing , delaying , none )
int choice =uniform(0,3);
if (choice == 0)
{
EV << " message lost !" << endl;
return 0;
}
...
int prob_modify = uniform(0,1)*10;
...
if (choice == 2)
{
return 2;
}
else
{
return 3;
}
}

```

```

    }
    }
    if (choice == 2)
    {
        return 1;
    }
    // if none return 4
    return 4;
}

```

## 2.5 Centralized Network Architecture

Since we are implementing a **centralized network**, we use a **hub** to communicate between nodes. The hub is, mainly, responsible for allocating **sessions** in the following way :

- Generate a **table of pairs** at the beginning of the simulation that includes all the node pairs to communicate.
- At *each session time*, the hub starts a new session through sending the two nodes a message (*of kind 4*) to start transmission. The message contains the expected frame to be sent for the opposite nodes.
- The hub schedules a self-message (*of kind 1*), as well, in order to mark the **beginning** of a new session.
- The hub continues to *re-direct* the messages, until the session *times out*.
- Once the session times out, the hub sends to the two active nodes an "*end session*" message and receives the last acknowledged frame from each of them.
- The hub starts a *new session* between two new nodes and **ignores** any other messages.

The implementation of the *centralized network* can be found in `src/Hub.cc` under function :

```

• void handleMessage(cMessage *msg);

void Hub::handleMessage(cMessage *msg)
{
    if (msg->isSelfMessage())

```

```

{
if (msg->getKind() == 1)
{
...
}
else if (msg->getKind() == 2)
{
...
}
else if (msg->getKind() == 6)
{
...
}
}
else
{
if (msg->getKind() == 3)
{
...
}
else if (msg->getKind() == 4)
{
...
}
}
}

```

- void generatePairs();

```

void Hub::generatePairs()
{
int node1, node2;
for(int i =0; i < this->n*this->n; ++i)
{
...
}
}

```

- void startSession();

```

void Hub::startSession()
{

```

```

this->indexer ++;
if(this->indexer == this->senders.size())
{
this->indexer = 0;
}
this->sender = this->senders[this->indexer];
this->receiver = this->receivers[this->indexer];
...
}

```

- void parseMessage(Imessage\_Base \*msg);

```

void Hub::parseMessage(Imessage_Base * msg)
{
int msg_sender = msg->getSenderModule()->getIndex();
EV << " message sender id = " << msg_sender << endl;
EV << " hub sender id = " << sender << endl;
EV << " hub receiver id = " << receiver << endl;
if (msg_sender != this->sender && msg_sender != this->receiver)
{
cancelAndDelete(msg);
return;
}
int msg_receiver;
if (msg_sender == this->sender)
{
msg_receiver = this->receiver;
}
else
{
msg_receiver = this->sender;
}
int noise = applyNoise(msg);
int delay = exponential( par("mean_delay").doubleValue());
EV << " delay time = " << delay << endl;
std::string msg_payload = msg->getMessage_payload();
switch(noise)
{
...
}
this->last_sent_frames[msg_sender] =

```

```
msg->getSequence_number();
}
```

## 2.6 Statistics Gathering

The **statistics gathering** function is implemented inside the hub, since the hub is the one controlling the **whole transmission process**. Also, the **transmission noise** is created in the hub. So, the hub keeps track of the **generated**, **lost**, **re-transmitted** and **duplicated** message for every node. It sets up a self-message (*of kind 2*) to schedule the **statistics print**. **Statistics** can be printed for each node *separately* or *collective* for all nodes. So, the following statistics are printed :

1. The total number of **generated** frames.
2. The total number of **dropped** frames.
3. The total number of **re-transmitted** frames.
4. The **percentage** of useful transmitted data (*Efficiency of the system*).

The implementation of the *statistics gathering* can be found in `src/Hub.cc` under function :

```
• void Hub::initializeStats();

• void Hub::updateStats(int node_idx, int seq_num, int frame_size,
    bool is_dropped, bool is_duplicated);

void Hub::updateStats(int node_idx, int seq_num, int frame_size,
    bool is_dropped, bool is_duplicated)
{
    ...
    if(it != this->generated_frames[node_idx].end())
    {
        int index = it - this->generated_frames[node_idx].begin();
        // increase retransmission times
        this->retransmitted_frames[node_idx][index] ++;
        // increase drop times (if dropped)
        if (is_dropped)
        {
            this->is_dropped[node_idx][index] ++;
        }
    }
}
```

```

// increase duplication times (if duplicated)
if (is_duplicated)
{
this->is_duplicated[node_idx][index] ++;
}
}
else
{
...
}
}

```

- void Hub::printStats(bool collective);

```

void Hub::printStats(bool collective)
{
if (collective)
{
// count all generated frames
int total_generated = 0;
for (int i = 0; i < this->n; i++)
{
total_generated += this->generated_frames[i].size();
}
// count all dropped frames
int total_dropped = 0;
...
// count all retransmitted frames
int total_retransmitted = 0;
for (int i = 0; i < this->n; i++)
{
total_retransmitted += std::accumulate(this->
retransmitted_frames[i].begin(),
this->retransmitted_frames[i].end(), 0);
}
float useful_data = 0;
float all_data = 0;
for (int i = 0; i < this->n; i++)
{
for (int j = 0; j < this->generated_frames[i].size(); j++)
{

```

```

useful_data += this->frame_sizes[i][j];
all_data += (this->retransmitted_frames[i][j] +
this->is_duplicated[i][j] + 1) *
(4*3 + this->frame_sizes[i][j]);
}
}
float efficieny = useful_data/all_data;.
...
}
else
{
...
}
}
}

```

### 3 Workload Division

Name	Work
Remonda Talaat Eskarous	<ul style="list-style-type: none"> <li>- Centralized Network (<i>Hub</i>).</li> <li>- Transmission Channel Noise Modelling.</li> <li>- Code Integration.</li> </ul>
Mohamed Shawky Zaky	<ul style="list-style-type: none"> <li>- Character Count.</li> <li>- Statistics Gathering.</li> <li>- Code Integration.</li> <li>- Final Report.</li> </ul>
Mohamed Ahmed Mohamed Ahmed	<ul style="list-style-type: none"> <li>- Go Back N.</li> </ul>
Mohamed Ramzy Helmy	<ul style="list-style-type: none"> <li>- Hamming Code.</li> </ul>