Implement Long Short-Term Memory Recurrent Neural Network on Grammatical Facial Expression Recognition

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**Abstract.** The abstract should summarize the contents of the paper and should contain at least 70 and at most 150 words. It should be set in 9-point font size and should be inset 1.0 cm from the right and left margins. There should be two blank (10-point) lines before and after the abstract. This document is in the required format.

**Keywords:** LSTM, Recurrent Neural Network, Kinect, Grammatical Facial Expression, Deep Learning

1 Introduction

Grammatical Facial Expression (GFE), a category sign language for people with impaired hearing [1, 2]. Combination of the hardware and software solutions can make machines learn the semantic meaning of such sign language. For the hardware part, Kinect, as known as a motion sensor device produced by the Microsoft, it can capture the facial expressions [3]. For the software part, Kinect can generate facial contour landmarks (x, y and z-axis) for each frame of recording via the Face Tracking SDK [3]. The bio-inspired deep learning algorithms can be implied to these landmarks and recognize some patterns among them.

To classify a facial expression from a time-series-based recording, deep learning can help with. In deep learning field, because Recurrent Neural Network (RNN) can memories data during a sequence of time and be implemented as a multilayer feedforward network, it is a suitable architecture to train time-series based dataset [4]. In recent work, the extensions of RNN are wildly used. Long Short-Term Memory (LSTM) is an improved extension of RNN, its gradient-based approach (adding 3 gates) can prevent the influence of the gradient that vanished or exploded in further steps [5].

In this paper, the dataset used in this experiment, the previous research which used the same facial landmark dataset or used the LSTM on facial expression, the training, testing and validation methods with LSTM architecture, the experiment results and further conclusion of the experiment will be explained in following sections.

2 Data

This data repository used in the following experiment is provided by the UCI website. In this repository [6], there are 9 types of facial signs of 2 signers’ (Signer A and Signer B): Affirmative, Double Question, Negative, Wh Question, Conditional, Yes/No Question, Empathies, Relative and Topic. Each facial expression consists of one data points file with timestamps and one file with binary labels (0 or 1). In the data file, the x, y and z coordinators of each landmark are listed as features (columns). The labels are listed in each row for each instance.

The quality and quantity of data are the reasons to choose this repository. For the quality part, this dataset is complete, there is no need to clean data set; these landmarks can be used to represent an expression during a time period. For the quantity, averagely, there are 2500 instances can be used in training process for each expression, the 300 attributes also make the deep learning get sufficient exploration on features.

3 Related Work

There are few recent papers used the same data repository as this paper. Multiple Layer Perceptron (MLP) architecture is firstly implemented on this repository by Freitas et al. [2], they did not get very high F-score on “Negative” and “Relative” expressions, most of expressions can be recognized above 0.75 (F-score). In 2016, by extracting the important facial points, Bhuvan et al [7] improved the F-score of MLP model to above 0.89. In 2017, a deep learning architecture, Convolutional Neural Network (CNN) is used by Walawalkar and Devesh [1]; their model has very good performance on each facial expression, all of expressions can have over 0.94 of F-score.

There is no paper found that used the LSTM/RNN to recognize the facial expressions of this repository, but there are two papers found used LSTM to train the similar facial landmarks. In Behzed and Mohammad’s research[8], they used the CNN to extract landmarks from videos, then they used LSTM to memories and train the landmarks; their final model can successfully recognize variety facial expressions from 4 data repositories. Alex et al [9] used unidirectional LSTM for 116 facial landmarks, the final expression recognition mean error rate is 18.2 ± 0.6%.

4 Methods

4.1 Data Preprocessing

To help classifier find the patterns, each instance is reconstructed by 11 distances, 7 angles and 100 (whole) of z-coordinators, therefore, an input entry vector for deep learning model has 118 attributes with 1 dimension. The distance and angles are specified in Freitas et al’s paper [2]. Since there are two signers, each signer performed 9 facial expressions, the two data files of both signers should be combined as one data file and normalized by Z-score method [1].

Each facial landmark has x, y, and z coordinators, the Euclidean distance between two landmarks uses x and y coordinators of two landmarks, which are and . Thus, the Euclidean distance is calculated by [10]:

**(1)**

The Signer A and Signer B have their 1D matrixes, and , for one of specified Euclidean distances. Because the Z-score can show the scaled distributions for different signers, which make the values are comparable, each distance instance of and will be calculated independently by same function, where D is a distance instance, is the mean of the 1D distance matrix and N is the number of instances in the 1D distance matrix:

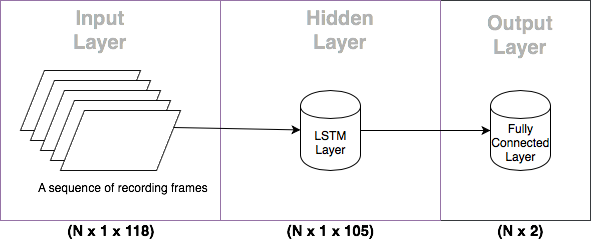
**(2)**

The angle (in cosine) between two distances ( and ) can be calculated by following function, where gets dot product, and are the norms of and respectively:

**(3)**

4.2 Deep learning Model for training

The aim of this experiment is using supervised binary classifier with LSTM architecture to classify if a frame of facial landmark belongs to a category of grammatical facial expression. As the Fig. 1 displayed, there are only one hidden layer, LSTM layer. Fully Connected (FC) layer is used as an output layer.



**Fig. 1** Training Model Architecture

For the input layer, since each instance vector has a related target label, the total N frames (training data) of 1D input entry vector with 118 attributes which given by the section 4.1, will be sent to LSTM layer. For the hidden layer, there are 3 gates and 2 memory cells used for this gradient-based approach of LSTM, which are input gate (), forget gate (), output gate (), new memory cell () and final memory cell () [5]; In the following formulas, the “t” means a timestamp, “” is the sigmoid function, “” is the input, “h” is the output, “b” is the parameter vector, “W” means the parameter matrix [8].

**(4)**

**(5)**

**(6)**

**(7)**

**(8)**

**(9)**

In this experiment, 105 of hidden neurons were found as the best choice, the output size of LSTM is .

The fully connected layer which helps map data, the input size is (). As a standard logistic function, sigmoid function can only result in 0 or 1 when the input is not 0. Thus, it can be used to indicate the target facial expression quickly.

In order to keep the balance between training and testing, 80% random data will be used in the training process. After several times of the experiments, this paper chooses the hyperparameter as Table 2 displayed.

**Table. 1** Summary of Hyperparameters in Training

|  |  |
| --- | --- |
| **Hyperparameter** | **Value** |
| Number of features(attributes) | 118 |
| Output Classes | 2 |
| Number of Hidden Neurons | 105 |
| Learning Rate | 0.0099 |
| Number of Epoch | 30 |
| Optimizer | Adam |
| Loss Function | Cross-Entropy |

Adam [11] as a first-order-gradient-based optimizer, it can achieve fast convergence and perform well in deep learning, thus by using it, less epoch will be needed [12]. Following Cross-Entropy [13] which combined with the SoftMax is used as the loss function to calculate the differences between the output values of model and the actual target value; then the gradient of cross-entropy will be calculated through backpropagation and fed to the Adam optimizer:

The x is the output given by the deep learning model, the class is the target

4.3 Model Testing and Validation

The accuracy is calculated by F-score [14], where “tp” means all prediction and actual values are negative, “fn” means prediction is positive while actual value is negative, “fp” has opposite meaning of “fn”:

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5 Results and Discussion

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6 Conclusion and Future Work

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Appendix: Specified Distances and Angles for Data Pre-processing

