Input: 3D few sequence of recording frames

Loss Function: Better square error with optimization(miinimose) value: lamda/2 |W|^2

Activation function of output layer: Relu

Reason: avoid to lose weight information(better than sigmoid)

LSTM Architecture: The several formulars(Refeerences)

Why need CNN? Need to extract landmarks?

# 1Introduction

# 2Related Work

# 3.Dataset

# 4.Method

## 4.1 Net Training

## 4.2 Net Testing

## 4.3 Net Validation

# 5. Result & Discussion

# 6.Conclusion and Future Work