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Pure Exploratio

Lower Bound

.

Conclusion

Pure Exploration by Solving Games

Rémy Degenne, Wouter M. Koolen and Pierre Ménard

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Main recipe

Take two adversarial strategies for regret minimization.

Add optimism.

Get one stochastic bandit algorithm for pure exploration.

Paper: R.D., Wouter M. Koolen and Pierre Ménard, Non-Asymptotic Pure Exploration by Solving Games, NeurIPS 2019. _____

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Usual Queries

- Best Arm Identification
- Thresholding Bandit

Our setting

- Bandit parametrized by means $\mu \in \mathcal{M} \subset \mathbb{R}^K$.
- Answers \mathcal{I} . Correct answer function $i^* : \mathcal{M} \to \mathcal{I}$.
- Fixed confidence $\delta \in [0, 1]$.
- Algorithm stops at time τ_{δ} , returns $\hat{\imath}$.

Goal: δ -correct algorithm, such that

$$\forall \mu \in \mathcal{M} \quad \mathbb{P}_{\mu}(\hat{\imath} \neq i^*(\mu)) \leq \delta \;, \qquad \mathbb{E}_{\mu} \, \tau_{\delta} \; \text{is minimal}.$$

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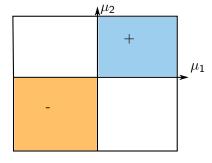
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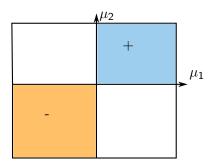
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This talk: about sampling rules.

Use GLRT stopping rule from Garivier and Kaufmann, 2016.

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Any δ -correct algorithm on \mathcal{M} must verify for all $\mu \in \mathcal{M}$,

$$\mathbb{E}_{\boldsymbol{\mu}}[\tau_{\delta}] \max_{\boldsymbol{w} \in \triangle_{K}} \inf_{\boldsymbol{\lambda} \in \neg i^{*}(\boldsymbol{\mu})} \sum_{k=1}^{K} w^{k} d(\mu^{k}, \lambda^{k}) \geq \mathsf{kl}(\delta, 1 - \delta)$$

Sample complexity: what is

"minimal"?

$$\neg i = \{ \lambda \in \mathcal{M} : i^*(\lambda) \neq i \}.$$

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Sample complexity: what is "minimal"?

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Follow the lower bound: attempt 1 Track and Stop

Compute estimated problem $\hat{\mu}_t$.

Compute the solution \boldsymbol{w}_t^* to

$$\underset{w \in \triangle_K}{\operatorname{argmax}} \inf_{\boldsymbol{\lambda} \in \neg i^*(\hat{\boldsymbol{\mu}}_t)} \sum_{k=1}^K w^k d(\hat{\boldsymbol{\mu}}_t^k, \boldsymbol{\lambda}^k) \,.$$

If an arm is sampled less than \sqrt{t} , sample it (forced exploration).

Otherwise, sample arm $k_t = \operatorname{argmin} N_{t-1}^k - (w_t^*)^k$ (tracking).

[Garivier and Kaufmann, Optimal Best Arm Identification with Fixed Confidence, 2016]

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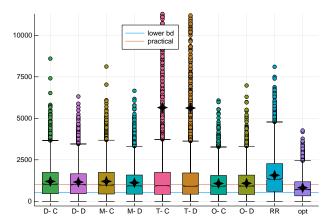
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Track-and-Stop

- · Asymptotically optimal,
- But sometimes only asymptotically.

$$\liminf_{\delta \to 0} \frac{\mathbb{E}_{\mu} \, \tau_{\delta}}{\log(1/\delta)} \leq \frac{1}{\sup_{\boldsymbol{w} \in \triangle_{K}} \inf_{\boldsymbol{\lambda} \in \neg i^{*}(\mu)} \sum_{k=1}^{K} w^{k} d(\mu^{k}, \lambda^{k})} \, .$$



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Follow the lower bound: attempt 2 with games!

A Game

Suppose μ , $i = i^*(\mu)$ known.

- k-Player plays in $\{1, \dots, K\}$.
- λ -Player plays in $\neg i$.
- zero-sum. reward for k-player: $d(\mu^k, \lambda^k)$.

After t iterations: reward $\sum_{s=1}^{t} d(\mu^{k_s}, \lambda_s^{k_s})$.

Algorithms

- Regret-minimizing algorithm for k: AdaHedge.
- Regret-minimizing algorithm for λ : Best-Response.
- Result: value $\frac{1}{t} \sum_{s=1}^{t} d(\mu^{k_s}, \lambda_s^{k_s})$ converges to max-min.

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Algorithm

Algorithm for Pure Exploration

At stage $t \in \mathbb{N}$,

- Compute $\hat{\mu}_t$, define candidate answer i_t .
- Define game with optimistic reward $\max_{\xi \in [\hat{u}_{+}^{k} \pm ...]} d(\xi, \lambda^{k})$.
- Do 1 iteration of each learner on optimistic game.
- Sample the arm prescribed by the k-player (tracking).

And stop according to GLRT stopping rule.

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Computational Complexity

Track-and-Stop: solves one "max-min" at each stage.

$$\underset{w \in \triangle_K}{\operatorname{argmax}} \inf_{\boldsymbol{\lambda} \in \neg i^*(\hat{\boldsymbol{\mu}}_t)} \sum_{k=1}^K w^k d(\hat{\mu}_t^k, \lambda^k).$$

AdaHedge + Best-response: solves one "min" at each stage.

$$\underset{\lambda \in \neg i_t}{\operatorname{argmin}} \sum_{k=1}^K w_t^k d(\hat{\mu}_t^k, \lambda^k).$$

Examples

- Threshlolding: closed form vs closed form.
- BAI: (line search)² vs line-search.
- Many Problems (sparse, lipschitz, unimodal): complicated? vs convex.

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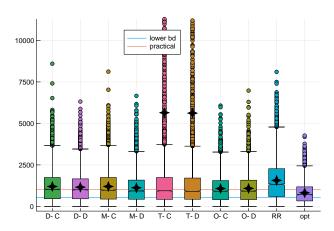
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For all $\mu \in \mathcal{M}$,

$$\mathbb{E}_{\mu} \, \tau_{\delta} \leq \frac{\log(1/\delta)}{\max\inf \sum_{k=1}^K w^k d(\mu^k, \lambda^k)} \left(1 + \mathcal{O}\left(\frac{1}{\sqrt{\log(1/\delta)}}\right)\right) \; .$$



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Remarks

Variants

- Solve max-max-min at each stage ⇒ lowest sample complexity.
- Use a learner for $\lambda \Rightarrow$ no tracking needed:
 - Follow the perturbed leader: always available but t samples at stage t,
 - Easy if union of few simple convex regions.

Open problem

What if only few samples are available? What if we want $\delta = 1/4$?

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- Pure Exploration is a very broad setting.
- The game point of view is successful.
- Many other applications possible in bandits.
- The small confidence regime is still unclear.

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Thank you!