Numerical Recipes: Hand-In 2

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Abstract

In this report we present the problems, solutions and scripts for the exercises from the second handout for the course Numerical Recipes.

Plotting styles in this report are set using the following code

```
def set_styles():

"""For consistent plotting scheme"""

plt.style.use('default')

mpl.rcParams['axes.grid'] = True

plt.style.use('seaborn-darkgrid')

mpl.rcParams['font.family'] = 'serif'

mpl.rcParams['lines.linewidth'] = 1.5

mpl.rcParams['font.size'] = 14
```

Listing 1: Matplotlib Plotting Styles

1 Satellite Galaxies Around a Massive Central

```
# INTEGRATION
  {\color{red} \textbf{def romberg\_integration} (func \,, \,\, a \,, \,\, b \,, \,\, order \,, \,\, open\_formula=False):}
        ""Integrate a function, func, using Romberg Integration over
       the interval [a,b]
       This function usually sets h\_start = b-a to sample from the
       widest possible interval.
      If open_formula is set to True, it assumes the function is
       undefined at either a or b
       and h_{start} is set to (b-a)/2.
       This function returns the best estimate for the integrand
      # initiate all parameters
      r_{array} = np.zeros(order)
      h = b - a
      N_p = 1
      # fill in first estimate, don't do this if we cant evaluate at
14
      the edges
       if open_formula:
           # First estimate will be with h = (b-a)/2
           start_point = 0
18
       else:
           r_{array}[0] = 0.5*h*(func(b) - func(a))
19
           start\_point = 1
20
21
      # First iterations to fill out estimates of order m
22
       for i in range(start_point, order):
           delta = h
24
           h = 0.5
25
           x = a + h
27
           # Evaluate function at Np points
           for j in range(N_p):
29
               r_array[i] += func(x)
30
31
               x += delta
           # Combine new function evaluations with previous
32
33
           r_{array}[i] = 0.5*(r_{array}[i-1] + delta*r_{array}[i])
           N_p *= 2
34
35
36
      # Combine all of our estimations to cancel our error terms
37
       N_p = 1
       for i in range(1, order):
38
           N_{-p} *= 4
39
           for j in range(order-i):
40
               r_{array}[j] = (N_{p*r_{array}}[j+1] - r_{array}[j])/(N_{p-1})
41
       return r_array[0]
43
  # TODO: Improve this into a better method
45
  # DISTRIBUTION SAMPLING
46
  def rejection_sampling (func, rng, N,
                            shift_x=lambda x: x,
48
                            shift_y=lambda x: x,
49
                           x0 = 4891653):
50
      """Sample a 1D distribution using rejection sampling. This
      function generates
       two random numbers using the provided rng. It then assigns the
52
       first value as
       'x' and shifts it using the shift_x function, and assigns the
      second value as
```

```
'y' and shifts it using the shift_y function. If y<func(x) the
54
        point is accepted
        Repeat this until we have N points, and return these
        x0 is used as a starting seed for the rng
56
57
58
        sampled_points = np.zeros(N)
        num_tries = 0 # For performance testing
60
        for i in range(N):
61
            not\_sampled = True
62
63
            # Keep sampling until we find a x,y pair that fits
64
65
            while not_sampled:
                numbers, x0 = rng(2, x0=x0, return_laststate=True) #
66
       This is now U(0,1)
67
                x = shift_x (numbers [0])
68
                y = shift_y (numbers [1])
69
                 num\_tries += 1
print(x, y, func(x))
70
71
                 if y < func(x):
                     sampled_points[i] = x
73
                     not_sampled = False
74
75
        print(f'Average No. tries: {num_tries/N:.1f}')
76
77
        return sampled_points
78
79
   # DIFFERENTIATION
80
   def central_difference(func, x, h):
81
        """Comptue the derivative of a function evaluated at x, with
       step size h"",
        return (\operatorname{func}(x+h) - \operatorname{func}(x-h))/(2.*h)
83
   \begin{array}{lll} \textbf{def} & \texttt{ridders\_equation} \, (D1, \ D2, \ j \, , \ \texttt{dec\_factor} \, ) \, ; \end{array}
85
         "Ridders Equation used to combine two estimates at different
86
       h"""
        j_factor = dec_factor**(2.*(j+1.))
87
        return (j_factor * D2 - D1)/(j_factor - 1)
89
90
   def ridders_method(func, x_ar, h_start, dec_factor, target_acc,
91
        approx_array_length=15):
        """Compute the derivative of a function at a point, or points x
92
         using Ridder's Method
       The function iteratively adds in more estimates at a lower h
93
        until it achieves the provided
        target accuracy. It then returns the best estimate, and the
94
        uncertainty on this, which is
        defined as the difference between the current and previous best
95
        estimates
96
        derivative_array = np.zeros_like(x_ar, dtype=np.float64)
97
        unc_array = np.zeros_like(x_ar, dtype=np.float64)
98
99
        for ar_idx in range(len(x_ar)):
            x = x_ar[ar_idx]
101
            # Make this larger if we have not reached our target
        accuracy vet
            approximations = np.zeros(approx_array_length, dtype=np.
        float64)
```

```
104
            uncertainties = np.zeros(approx_array_length, dtype=np.
       float64)
            uncertainties [0] = np.inf # set uncertainty arbitrarily
       large for the error improvement comparison
106
            h_i = h_start
107
            approximations[0] = central_difference(func, x, h_i)
108
            best\_guess = approximations[0]
110
            for i in range(1, approx_array_length):
111
                # Add in a new estimation with smaller step size
                h_i /= dec_factor
113
                approximations [i] = central_difference (func, x, h_i)
                for j in range(i):
115
                    \# Add the new approximation into the 'tree of
116
       estimations;
                    approximations[i-j-1] = ridders\_equation(
       approximations \left[\,i-j-1\right], \ approximations \left[\,i-j\,\right], \ j\,, \ dec\_factor\,)
                uncertainties [i] = np.abs (approximations [0] -
118
       best_guess)
                # Test if we are below our target accuracy
                if (uncertainties[i] < target_acc) or (uncertainties[i]
120
        > uncertainties [i-1]):
                    derivative_array [ar_idx] = approximations [0]
                    unc_array[ar_idx] = uncertainties[i]
123
                    break
                else:
125
                    best\_guess = approximations[0]
126
       return derivative_array, unc_array
127
128
   # SORTING
130
   def sort_subarrays(a1, a2, k1, k2):
       ""Takes two subarrays 1,2 with indices a1, a2 and values k1,
       k2 and combines these
133
       into array with indices a such that the k are sorted in
       ascending order""
       N1 = len(a1)
       N2 = len(a2)
136
       # We built up a new instance of our sorting array. This is not
137
       memory efficient
       # TODO: Study the algorithm below to try and find a better
138
       method
       a_sorted = np.zeros(N1+N2)
139
140
       if N1 = 0:
141
           return a2
142
        if N2 == 0:
143
           return al
144
145
       # Walk through the left- and right- sub arrays separately
146
       idx1 = 0
147
148
       idx2 = 0
       while True:
149
           if k1[idx1] > k2[idx2]:
150
                # Then place the second element to the left of the
       first element and take
152
                # one step to the right in the right sub-array
                a\_sorted[idx1+idx2] = a2[idx2]
153
                idx2 += 1
154
```

```
155
                # Then, if there are elements remaining in the right
156
       array, keep
                # placing them to the left as long as they're smaller
157
                if idx2 < N2: # need this if statement to save us from
158
       indexing errors in the while
                    while (k1[idx1] > k2[idx2]):
                         a_sorted[idx1+idx2] = a2[idx2]
                         idx2 += 1
161
                         if idx2 >= (N2):
163
                             # No more elements left in the right array,
164
        we can fill out with the left array
                             for j in range(idx1, N1):
165
                                 a_sorted[j+idx2] = a1[j]
                             return a_sorted
167
168
                    # Now the element from the left array is smaller
169
       than the first remaining element
                    # from the right array, we can safely place it
                    a\_sorted[idx1+idx2] = a1[idx1]
171
                    idx1 += 1
172
173
                else:
                    # No more elements left in the right sub-array
                    for j in range(idx1, N1):
    a_sorted[j+idx2] = a1[j]
176
                    return a_sorted
178
            else:
179
                a_{sorted}[idx1+idx2] = a1[idx1]
180
                idx1 += 1
182
           # Check if we have reached the end of the left sub-array
183
            # If we have, fill out the rest of the array with the right
184
        sub-array
            if idx1 = N1:
185
                for j in range(idx2, N2):
186
                    a_sorted[idx1+j] = a2[j]
187
188
                return a_sorted
189
190
191
   def merge_sort(a=None, key=None):
        "" Sorts the array or list using merge sort. This function
193
       iteratively
       builds up the array from single elements which are sorted by
194
       sort_subarrays
       Note, in principle one should only provide either 'a' or 'key':
195
196
       - If 'a' is provided, that array is sorted in ascending order,
197
       and returned
198
         by this function
       If 'key' is provided, this function returns the indices
199
       corresponding to the
         order in which the array would be sorted
       - If both 'a' and 'key' are provided, this function assumes '
201
       key' has already
         been previously shuffled, and just swaps indices of the
202
       preexisting 'a'
203
       RETURNS: 'a': numpy array
204
205
```

```
if key is not None:
206
           key = np.array(key)
207
208
       if a is None and key is not None:
209
           a = np.arange(len(key))
210
211
212
       a = np.array(a)
       subsize = 1
213
       N = len(a)
214
       is\_sorted = False
215
       # Build up the array sorting arrays of increasing subsize
217
       while not is_sorted:
218
           subsize *= 2
            if subsize > N:
219
                is_sorted = True # After this iteration, the array is
       sorted
221
            for i in range(int(np.ceil(N/subsize))):
222
                \# We need the min(.. , N) to ensure that we do not
223
       exceed the length of the
               # array with our indexing
224
                subarray1 = a[i*subsize: i*subsize+int(0.5*subsize)] #
225
       First half of the interval
               subarray2 = a[i*subsize+int(0.5*subsize): np.min(((i+1)))
226
       *subsize, N))]
                if key is not None:
                    key1, key2 = key[subarray1], key[subarray2]
228
229
                    sorted_sub = sort_subarrays(subarray1, subarray2,
       key1, key2)
                else:
230
                    # we feed in 'subarrayx' twice because if we only
       sort a, a is its own key
                    sorted_sub = sort_subarrays(subarray1, subarray2,
239
       subarray1 , subarray2 )
233
                a[i*subsize:subsize*(i+1)] = sorted\_sub
234
235
       return a
236
237
238
   # ROOT FINDING
239
   def false_position(func, bracket, target_x_acc=1e-10, target_y_acc
       =1e-10, \max_{i} ter = int(1e5):
       """ Given a function f(x) and a bracket [a,b], this function
241
       a value c within that interval for which f(c) = 0 using the
242
       false
       position method. Guaranteed to converge, slow but faster than
243
       bisection.
       a, b = bracket
245
       fa, fb = func(a), func(b)
246
247
       # Test if the bracket is good
248
249
       if not (fa*fb) < 0:
           raise ValueError ("The provided bracket does not contain a
250
       root")
251
       for i in range(max_iter):
252
253
           print(a, b, fa, fb)
254
           c = a - fa*((a-b)/(fa-fb))
255
```

```
fc = func(c)
256
257
            # Check if we made our precisions
258
259
            # x-axis
            if np.abs(b-c) < target_x_acc or np.abs(a-c) < target_x_acc
260
                {\tt return}\ c\,,\ i+1
            \# relative y-axis
262
            if np.abs((fc-fb)/fc) < target_y_acc or np.abs((fc-fa)/fc)
263
       < target_y_acc:
                return c, i+1
264
265
            if (fa*fc) < 0:
266
                # Then the new interval becomes a, c
267
                # keep the number of function calls as low as possible
                b, fb = c, fc
269
            elif (fc*fb) < 0:
                # Then the new interval becomes c, b
271
                a\,,\ fa\ =\ c\,,\ fc
272
273
            else:
                print("Warning! Bracket might have diverged")
274
                return c, i+1
275
276
        print("Maximum number of iterations reached")
277
278
       return c, i
```

Listing 2: Code for all the algorithms used in this exercise

```
def to_int32(x):
       """Takes any integer x, and returns the last 32 bits"""
       binx = bin(np.uint64(x))
       # First two chars are '0b' can ignore these
       if len(binx) > 33:
           bin 32 = binx[-32:]
       else:
       bin32 = (32 - len(binx)) * '0' + binx[2:]
return int(bin32, 2) \# The '2' indicates the val is given in
       base2
  def mwc_base32(x, a):
12
13
       # Set the first 32 bits to zero
      x = np.uint64(x)
14
15
       x = a*(x \& np.uint64((2**32 - 1))) + (x >> np.uint64(32))
16
  {\tt def \ rng\_from\_mwc\,(N, \ x0=1898567, \ a=4294957665, \ return\_laststate=}
       False):
       """Sample N values using mwc_base32 with starting value x0
       The given value for a is an optimal seed. We use all 64-bits
20
       to generate the random number, but only return the last 32
21
22
       x = np.zeros(N)
23
       for i in range(N):
24
           x0 = mwc_base32(x0, a)
25
           x[i] = to_int32(x0)
26
       x \neq (2**32 - 1) \# this ensures we return U(0,1)
27
       if return_laststate:
28
29
           return x, x0
       else:
30
31
           return x
```

Listing 3: Code for the random number generator

All dynamically written results from the code corresponding to this section can be found in results/satellite_galaxies_results.txt.

In this section we will investigate the spherical distribution of satellite galaxies around a massive central galaxies. Their density distribution n can be described

$$n(x) = A \langle N_{sat} \rangle \left(\frac{x}{b}\right)^{a-3} \exp\left[-\left(\frac{x}{b}\right)^{c}\right]$$
 (1)

Where we take a=2.4, b=0.25, c=1.6 and $\langle N_{sat}\rangle=100$. x is the radius relative to the virial radius, i.e. $x\equiv r/r_{vir}$. A is a normalization constant that we do not a priori know, but is set such that the three dimensional spherical from x=0 to $x_{max}=5$ is equal to the average number of satellites, $\langle N_{sat}\rangle$:

$$\int \int \int_{V} n(x)dV = \langle N_{sat} \rangle. \tag{2}$$

```
"""Density profile of the spherical distribution of
      satellite galaxies around a central as a function of
      x = r/r_vir. The values given come from hand-in 2"""
      return A*Nsat*((x/b)**(a-3))*np.exp(-(x/b)**c)
  def full_run():
      # Parameters given in the hand-in
      a = 2.4
      b = 0.25
      c = 1.6
      A = 1 \# Need to compute this later
11
      Nsat = 100
      x_{-min} = 0
      x_max = 5
      N_sample = int(1e4)
      sample_min_x = 1e-4
15
      nbins = 20
      num_random_sample = 100
18
      results_txt = "This file contains all results from question 1\n
19
20
      set_styles()
```

Listing 4: Setup code for the first assignment

1.1 Normalization Constant

Looking at equation 1 we can see that it is independent of angle, and only depends on the radial distance. This allows us to transform the integral in equation 2 to a spherical integral over θ, ϕ, x as

$$\int \int \int_{V} n(x)dV = \int_{0}^{x_{max}} \int_{0}^{\pi} \int_{0}^{2\pi} n(x)x^{2} \sin(\theta)d\phi d\theta dx$$
$$= 4\pi \int_{0}^{x_{max}} n(x)x^{2} dx$$
$$= 4\pi \int_{0}^{x_{max}} x^{2} A \langle N_{sat} \rangle \left(\frac{x}{b}\right)^{a-3} \exp\left[-\left(\frac{x}{b}\right)^{c}\right] dx$$

Here we begin by setting A=1, and using the result of this integral to calibrate A such that equation 2 holds. We can evaluate this integral using a simple one dimensional numerical integrator. We apply a Romberg integrator with order 10 to ensure sufficient accuracy. We have to account for the fact that n(x) is not defined at x=0 because $\left(\frac{x}{b}\right)^{a-3}$ causes a division by zero if a<3, which is the case here. To combat this we set $h_{start}=\frac{b-a}{2}$ instead of $h_{start}=b-a$ to avoid evaluating n(x=0).

We find $\int_V n(x)dV = 10.88$, which means we have to set the normalization constant $A = \frac{\langle N_{sat} \rangle}{10.88} = \frac{100}{10.88} = 9.19$. We will use this value for A throughout the rest of this work.

```
# 1a. Integrate the 3D spherical integral to find A
to_integrate = lambda x: 4*np.pi*x*x* n(x, A, Nsat, a, b, c)
volume_integral = romberg_integration(to_integrate, x_min,
x_max, 10, open_formula=True)
A = Nsat/volume_integral
print(f'The volume integral evaluated from 0 to 5 returns: {
volume_integral:.6 f}')
print(f'Therefore we need a normalization constant A = {A:.2 f}')
results_txt += f"{volume_integral:.2 f}\n{A:.2 f}\n"
```

Listing 5: Code applying the integration algorithm to the algorithm in this assignment

1.2 Distribution Sampling

We want to sample the 3D distribution of satellites such that they statistically follow the distribution in equation 1. This means that the probability distribution should be $p(x)dx = N(x)dx/\langle N_{sat}\rangle$. Here N(x)dx is the number of satellites in a spherical shell of size dx at relative radius x from the center of the massive galaxy. This is equal to the result we saw for the spherical integral in the previous section, thus the probability distribution we want to sample is

$$p(x)dx = x^{2}A\left(\frac{x}{b}\right)^{a-3} \exp\left[-\left(\frac{x}{b}\right)^{c}\right]dx \tag{3}$$

In this work we will use rejection sampling to simulate this distribution. The implementation in this work first generates two random numbers generated using 32-bit multiply with carry, we call the first number x and shift it to a uniform distribution in log-space in the range $[-4,^{10}\log(5)]$ (corresponding to the range $[10^{-4}, 5]$ in linear space), and the second we call y and shift it to the range [0, 2.68] where 2.68 is the maximum of the distribution given in equation 3 as shown in figure 1. If the (x_i, y_i) point falls below the curve described

Linear Satellite Number Distribution 2.5 2.0 xp(x)d1.5 $N(x)dx/\langle N_{sat}\rangle$ Distribution Max: 2.68 1.0 0.5 0.0 0 1 2 3 4 5 $x \equiv r/r_{vir}$

Figure 1: Analytical distribution of the number of satellite galaxies in a shell around a massive galaxy with thickness dr at radius r, described by equation 3.

by equation 3 we accept it, otherwise we reject it¹. After each step we use the last generated random number as x0 for the next number. We repeat this entire process, until we have $N=10^4$ samples in total. We note that rejection sampling is far from the most efficient method to sample a distribution such as this because the majority of possible points in our (x,y) range will be rejected as is evident in figure 1. To slightly combat this we have sampled x in log- instead of linear space which means small values (<1) are sampled at a higher rate, and the algorithm finds itself in the "interesting" region of the distribution more often. Nevertheless, on average the rejection sampling algorithm still takes ~ 6 attempts (12 random numbers generated) untill it finds an accepted point.

We plot the results from our sampling algorithm as a histogram with 20 equally spaced bins in log-space in figure 2. We divided the height of each bin by 10^3 to account for the difference between $\langle N_{sat} \rangle$ and N. We can see in the figure that the analytical distribution, and our sampled distribution match almost perfectly everywhere except the edges. These edges are missing from this plot because the sampler is often unable to sample points in these regions due to the large value for p(x)dx there.

```
# 1b. Simulate the distribution
# Set Nsat = 1 because we divide n(x) by Nsat
rng = rng_from_mwc
log_distribution = lambda x: 4*np.pi*10**(2*x)*n(10**x, A, 1, a, b, c)

# Find maximum of this distribution
x = np.linspace(sample_min_x, x_max, 1000)
nx = log_distribution(np.log10(x))
```

¹In the code, we have replaced each x in equation 3 with 10^x to account for the fact we sample in log-space.

Sampled Distribution Histogram Sampled Distribution Analytical Function Solution Analytical Function Solution Analytical Function 1 Solution Analytical Function

Figure 2: Analytical distribution of satellite galaxies around a massive central overplotted on the same distribution sampled by our rejection algorithm with $N=10^4$ described in the text. The histgoram bin heights are scaled down by a factor 10^3 to enforce the same normalization.

```
log_dist_max = np.max(nx)
       # Plot this distribution in linear space for investigation
11
       purposes
       results_txt += f"\{log_dist_max:.2f\}\n"
       plt.plot(x, nx, label=r'\$N(x)dx/\langle left < N_{-}\{sat\}\rangle right > \$')
       plt.axhline(y=0, c='black', ls='-')
plt.axhline(y=log_dist_max, c='red', label=f'Distribution Max:
14
       {log_dist_max:.2f}')
       plt.xlim(x_min, x_max)
       plt.xlabel(r'\$x \equiv r/r_\{vir\\$')
plt.ylabel(r'\$p(x) dx\\$')
18
       plt.title('Linear Satellite Number Distribution')
       plt.legend()
20
       plt.savefig('results/pxdx.png', bbox_inches='tight')
21
       plt.clf()
23
       # Create shift functions to transform U(0,1) to proper
24
       boundaries
       shift_x = lambda x: x * (np.log10(x_max) - np.log10(
       sample_min_x)) + np.log10(sample_min_x)
       shift_y = lambda y: y * log_dist_max
26
27
       print('Sampling Distribution..')
       sampled\_points = rejection\_sampling(log\_distribution, rng,
29
       N_sample, shift_x=shift_x, shift_y=shift_y)
       sampled_points = 10**sampled_points # Sampled in log space, go
30
       back to linear
       # Plotting of log distribution + sample
32
       bin_heights, bin_edges = hist(sampled_points, sample_min_x,
33
```

```
x_max, nbins, log=True)
       bin_centers = np.zeros(len(bin_edges)-1)
       for i in range (bin_centers.shape [0]):
35
           bin_centers[i] = bin_edges[i] + 0.5*(bin_edges[i+1] -
36
       bin_edges[i])
37
       plt.step(np.log10(bin_centers), np.log10(bin_heights/1000),
       label='Sampled Distribution')
       plt.plot(np.log10(x), np.log10(nx), label='Analytical Function')
30
       plt.xlabel(r'$^{10}\\log~r/r_{vir}$')
plt.ylabel(r'$^{10}\\\log~p(x)\dx$')
41
       plt.title('Sampled Distribution Histogram')
42
       plt.ylim(bottom=-5)
43
       plt.legend()
       plt.savefig('results/satellite_galaxies_pdf.png', bbox_inches='
45
       tight')
       plt.clf()
```

Listing 6: Code to sample the distribution given in this assignment

1.3 Random Selection

We want to look at the cumulative distribution function (CDF) of the sampled probability distribution shown in figure 2. To do this we first select 100 random satellite galaxies following the criteria given on the handout: each galaxy is selected with equal probability, no galaxy is selected twice, and we do not reject any draws. The simple (but maybe relatively overboard) method we use to ensure these criteria are upheld is to first shuffle the array of 10^4 galaxies in a random order, and then select the first 100.

We perform the random shuffling by generating 10⁴ random numers using our random number generator mentioned earlier, and use these numbers as keys in our merge_sort algorithm on which to "sort" an array of indices. We then apply these "sorted" indices on the sampled array to shuffle it, and select the first 100 instances. Finally, we sort these 100 galaxies using the same algorithm on their radii directly. We then use this sorted array to plot a CDF, normalized to 1, and present this in figure 3.

In correspondence with the PDF we saw in figure 2, we can see there are almost no satellites present at either edges of the interval. The most satellite galaxies are found at $\sim x = 0.1$, a result we also saw earlier.

```
def hist(x, binmin, binmax, nbins, log=False):
    if log:
        bin_edges = np.logspace(np.log10(binmin), np.log10(binmax),
        nbins+1)
else:
        bin_edges = np.linspace(binmin, binmax, nbins+1)

histogram = np.zeros(nbins)
for i in range(nbins):
        bin_mask = (x>bin_edges[i]) * (x<bin_edges[i+1])
        histogram[i] = len(x[bin_mask])#/(bin_edges[i+1]-bin_edges[i])
return histogram, bin_edges</pre>
```

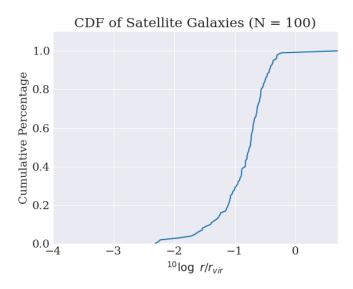


Figure 3: Cumulative distribution function normalized to 1 of p(x)dx sampled using rejection sampling with $N = 10^4$, created using only a random subset of 100 satellites.

Listing 7: Code used to compute the histogram bins

```
# Step 1: Order a list of random numbers, select the first 100
      print('Shuffling Sample..')
      random_keys = rng(N=N_sample)
      random_idxs = merge_sort(key=random_keys)
      random_sample_idxs = random_idxs [:num_random_sample]
      random_sample = sampled_points[random_sample_idxs]
      # Step 2: Order these 100 galaxies by radius
      random_sample_ordered_idxs = merge_sort(key=random_sample)
12
      random_sample_ordered = random_sample[
      random_sample_ordered_idxs]
      # Make the 'Cumulative Distribtuion Function'
      y = np.arange(num_random_sample)/num_random_sample
15
      y = np.append(y, 1) \# Add a final point to complete the CDF to
16
      random_sample_ordered = np.append(random_sample_ordered, x_max)
       plt.plot(np.log10(random_sample_ordered), y)
19
       plt.xlim(np.log10(sample_min_x), np.log10(x_max))
20
21
       plt.ylim(0, 1.1)
      plt.xlabel(r'\$^{10}\\log~r/r_{vir}\$')
22
      plt.ylabel('Cumulative Percentage')
plt.title(f'CDF of Satellite Galaxies (N = {num_random_sample}))
23
24
       plt.savefig('results/satellite_galaxies_cdf')
25
```

Listing 8: Code to generate the CDF presented in this work

1.4 Derivative

To conclude this section we will look at the derivative of n(x) (equation 1, not N(x)!) at x=1. To compute this derivative we have used Ridder's Method with $h_{start}=0.1$. Similarly to the Romberg integration earlier, we cannot choose $h_{start}=1$ because then we would have to sample n(x=0), where the function is not defined. In agreement with the assignment, we set our target accuracy at 10^{-12} . This means we stop if our uncertainty, defined as the absolute difference between the current and previous best estimates, drops below this threshold. We compare our findings to the analytical derivative of n(x) which we find to be

$$\frac{dn}{dx_{(analytical)}} = -A \langle N_{sat} \rangle \exp\left[-\left(\frac{x}{b}\right)^{c}\right] \frac{b^{3} \left(\frac{x}{b}\right)^{a} \left(c\left(\frac{x}{b}\right)^{c} - a + 3\right)}{x^{4}}$$
(4)

Now comparing the two results, using Ridder's Method we find

$$\frac{dn}{dx}_{(ridder)} = -0.625328061833 \pm 2.220 \times 10^{-14}$$

While analytically we find

$$\frac{dn}{dx}_{(analytical)} = -0.625328061833$$

These two values match exactly up to 12 digits, indicating the strength of the numerical differentiator implemented here.

```
# 1d.
to_diff = lambda x: n(x, A, Nsat, a, b, c)
x = [1]
dndx, diff_unc = ridders_method(to_diff, x, 0.1, 2, 1e-12)
dndx_analytical = analytical_derivative(x[0], A, Nsat, a, b, c)

print(f'The derivative of n(x) calculated using Ridders Method at x = {x[0]} is {dndx[0]:.12f} +/- {diff_unc[0]:.3E}')
print(f'The analytical derivative of n(x) at x = {x[0]} is {dndx_analytical:.12f}')

results_txt += f'{dndx[0]:.12f} \n{diff_unc[0]:.3E} \n{dndx_analytical:.12f}'
```

Listing 9: Analytical derivative function, and code to use Ridder's Method

2 Heating and Cooling in HII regions

In this section we will investigate the equilibrium temperature of heating and cooling rates in an HII region similar to Orion. We will search for these equilibrium temperatures using a root finding algorithm. In this work we have chosen to use only the False Position Method to maintain the convergence guarantee provided by bisection, but increase the convergence speed somewhat. We note that faster convergence is possibly by combining a faster and less accurate in the beginning, with a slower and more accurate algorithm near the root. However this is not implemented here due to time constraints.

2.1 Simple Case

First we will only consider an HII region with one heating and cooling mechanism. The heating is produced by photoionization given by

$$\Gamma_{pe} = \alpha_B n_H n_e \psi k_B T_c, \tag{5}$$

and the cooling through radiative recombination:

$$\Lambda_{rr} = \alpha_B n_H n_e \langle E_{rr} \rangle \,, \tag{6}$$

with

$$\langle E_{rr} \rangle = \left[0.684 - 0.0416 \ln \left(\frac{T_4}{Z^2} \right) \right] k_B T. \tag{7}$$

In these equations, $\alpha_B=2\times 10^{-13}~{\rm cm}^3~{\rm s}^{-1}$ is the case B recombination coefficient, $k_B=1.38\times 10^{-16}~{\rm erg}~{\rm K}^{-1}$ is the Stefan-Boltzmann constant, $\phi=0.929$ is given, $T_c=10^4~{\rm K}$ is the stellar temperature, Z=0.015 is the metallicity and $T_4\equiv \frac{T}{10^4{\rm K}}$ is the temperature. Finally, we assume the proton and electron densities to be equal, such that $n_e=n_p$.

The equilibrium temperature T_eq is given by the temperature at which the heating rate is equal to the cooling rate, $\Gamma_{pe} = \Lambda_{rr}$. We can formulate this in terms of a root finding problem by searching for the point where $\Gamma_{pe} - \Lambda_{rr} = 0$. We can work out what this should be by combining equations 5 and 6 to find that this means the following should hold

$$\psi T_c - \left[0.684 - 0.0416 \ln \left(\frac{T}{10^4 \cdot Z^2} \right) \right] \cdot T = 0.$$
 (8)

Note that the densities n, α_B and k have all dropped out of this specific equation, even though this does not represent the true difference between heating and cooling rate at other temperatures. This is not important because we are only interested in the temperature at which the above equation is true, where additional scaling factors are important.

We apply our root finding algorithm introduced earlier to this equation with an initial bracket in the range $T=\left[1,10^7\right]$ K. We aim for a temperature accuracy of 0.1 K. We present the result in figure 4, we can see that we find a root at $T=3.25\times10^4$ K, where the function has a value of -3.45×10^{-3} . This is a relatively large value, but the algorithm has converged because it is taking very small steps along the temperature axis.

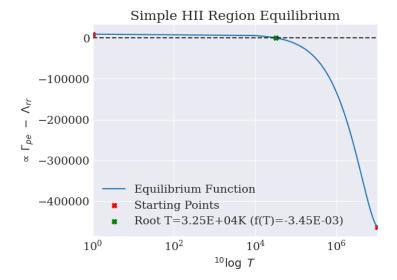


Figure 4:

2.2 More Complex Case

In addition to the singular heating and cooling mechanisms we described in the previous section, we will now setup a more realistic scenario and also include cooling through free-free emission (Λ_{ff}) and heating through cosmic rays (Σ_{cr}) and magnetohydrodynamic waves (Σ_{MHD}). These are all individually, given by the following three equations:

$$\Lambda_{ff} = 0.54 T_4^{0.37} \alpha_B n_e n_h k_B T \tag{9}$$

$$\Gamma_{cr} = A n_e \xi_{CR} \tag{10}$$

$$\Gamma_{MHD} = 8.9 \times 10^{-26} n_h T_4 \tag{11}$$

Synonymous to the previous section we can find the equilibrium temperature T_{eq} by finding the temperature for which $\Gamma - \Lambda = 0$ where Γ and Λ represent the total heating and cooling rate respectively, which are just the sums of each of the individual effects. Working this out, we find that the following equation most hold:

$$\left(\psi T_c - \left[0.684 - 0.0416\left(\frac{T}{10^4 \cdot Z^2}\right)\right] \cdot T - 0.54\left(\frac{T}{10^4}\right)T\right) \cdot k_B n_H \alpha_B$$

$$\dots + A\xi + 8.9 \times 10^{-26} n_H \frac{T}{10^4} = 0 \quad (12)$$