

CISC 330 - ASSIGNMENT 1

RIGID BODY TRANSFORM - GROUND TRUTHS

Test 3 Ground Truth

$$a = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad b = \begin{bmatrix} 5 \\ 0 \\ 0 \end{bmatrix} \quad c = \begin{bmatrix} 0 \\ 6 \\ 0 \end{bmatrix} \rightarrow d = \begin{bmatrix} -4 \\ 6 \\ 0 \end{bmatrix} \quad e = \begin{bmatrix} -9 \\ 6 \\ 0 \end{bmatrix} \quad f = \begin{bmatrix} -4 \\ 0 \\ 0 \end{bmatrix}$$

Orthonormal
Coord. System

calculated using
function in
matlab (proven valid)

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, v_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, c = \begin{bmatrix} 5/3 \\ 2 \\ 0 \end{bmatrix} \quad e_1 = \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix}, e_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, ce = \begin{bmatrix} -17/3 \\ 4 \\ 0 \end{bmatrix}$$

$$R_{ot} = \begin{bmatrix} \text{dot}(e_1, v_1) & \text{dot}(e_1, v_2) & \text{dot}(e_1, v_3) \\ \text{dot}(e_2, v_1) & \text{dot}(e_2, v_2) & \text{dot}(e_2, v_3) \\ \text{dot}(e_3, v_1) & \text{dot}(e_3, v_2) & \text{dot}(e_3, v_3) \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{new center} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5/3 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} -5/3 \\ -2 \\ 0 \end{bmatrix}$$

$$t_{ln vec} = ctr 2 - \text{new center} = \begin{bmatrix} -4 \\ 6 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & 6 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

trans Matrix =

$$\begin{bmatrix} -1 & 0 & 0 & -4 \\ 0 & -1 & 0 & 6 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$