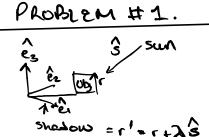


L4 CH3 Using Non-Square Matrices to do Projections Quiz

Matematika 2 (Universitas Katolik Widya Mandala Surabaya)



Get 1 in terms of r.

$$0 = r \cdot e_3 + \lambda (\hat{s} \cdot e_3)$$

>= -(.e.s)

S.e.s , only makes sense

becomes es is unit orthogonal

rector.

Laboratically now many vertical comps

and to make to maken vert of

PROBLEM # 2.

Write $\Gamma' = \Gamma - \hat{S}\left(\frac{r \cdot \hat{e}_3}{\hat{S} \cdot \hat{e}_3}\right)$ as a linear transformation of Γ .

(e.g. $A\Gamma = \Gamma'$)

Also write einstein summation convention of Ar=1!

As vectors:
$$\Gamma' = \Gamma - \frac{S \times \Gamma_3}{S_5}$$

$$\Gamma'_{i} = \Gamma_{i} - S_{i} \Gamma_{3}$$

$$\Gamma'_{i} = (T_{ij} - S_{i} T_{5j} / S_{3})$$

As matrix:

Evation:
$$\begin{bmatrix}
i = (i - s_i)_3 \\
i = (T_{ij} - s_i)_{ij}
\end{bmatrix}$$
This document is available reconstrainty of the same o

PROBLEM #3.

Criver the center sum. conv. for the mahrix

Write the component form of A.

PROBLEM # 4.

Write the third row of A from Prob#2 if the matrix went from R3-R3:

$$A_{3} = \begin{bmatrix} 0 & 0 & (1 - s_{i/s_{3}}) \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & (1 - h) \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

PROBLEM #5

Calculate to from Ax=6.

$$A = \begin{bmatrix} 1 & 0 & -si/s_3 \\ 0 & 1 & -si/s_3 \end{bmatrix} T = \begin{bmatrix} 6 \\ 2 \\ 3 \end{bmatrix} S = \begin{bmatrix} 4/13 \\ -3/13 \\ -12/13 \end{bmatrix}$$

$$b = \begin{bmatrix} (1)(6) + (6)(2) + (3)(-1)(4/3) \\ (-12/13) \end{bmatrix}$$

$$(0)(6) + (1)(2) + (3)(-1)(-3/13) \\ \hline (-12/13) \end{bmatrix}$$

$$= 6 + 1 \\ 2 - 3 = \begin{bmatrix} 7 & 3/4 \end{bmatrix}$$

=
$$\begin{bmatrix} 6+1 \\ 2-3 \end{bmatrix}$$
 = $\begin{bmatrix} 7+3/4 \end{bmatrix}$ Downloaded by Rio Bastian (riobastian 1717@gmail.com)

PROBLEM #6

A transformation F' = AF can be generalized to a matrix equation, R' = AR

where R' and R are natrices where each all corresponds to 11 and 1 vectors.

$$\begin{bmatrix} \Gamma'_{1} & S'_{1} & +'_{1} & U'_{1} & ... \\ \Gamma'_{2} & S'_{2} & +'_{2} & U'_{2} & ... \end{bmatrix} = A \begin{bmatrix} \Gamma_{1} & S_{1} & +_{1} & U_{1} \\ \Gamma_{2} & S_{2} & +_{2} & U_{2} & ... \\ \Gamma_{3} & S_{5} & +_{3} & U_{3} \end{bmatrix}$$

In sunstein's rotatation

For the same s as previous question, apply A to the matrix,

$$R = \begin{bmatrix} 5 & -1 & -3 & 7 \\ 4 & -4 & 1 & -2 \\ 9 & 3 & 0 & 12 \end{bmatrix} \qquad S = \begin{bmatrix} 4y_{13} \\ -3y_{13} \\ -12y_{13} \end{bmatrix} \qquad A = \begin{bmatrix} 1 & 0 & -siy_{s_3} \\ 0 & 1 & -siy_{s_3} \end{bmatrix}$$

$$R' = \begin{bmatrix} 1 & 0 & -si/s_3 \\ 0 & 1 & -si/s_3 \end{bmatrix} \begin{bmatrix} 5 & -1 & -3 & 7 \\ 4 & -4 & 1 & -2 \\ 9 & 3 & 0 & 12 \end{bmatrix}, \text{ using } si = \vec{S}i$$
Let $C_1 = -s_1/s_3 = (4/13)(-1)(13/-12)$, $C_2 = -s_2/s_3 = (-3/13)(-1)(13/12)$,
$$= V_3$$

$$= V_3$$

$$= -V_4$$

$$R' = \begin{bmatrix} (1)(s) + (9)C_1^3 & (-1) + 3C_1 & -3 + oC_1^0 & 7 + 12C_1 \\ 4 + 9C_2^{-1/4} & -4 + 3C_2^{-3/4} & 1 + oC_2^0 & -2 + V_2 & C_1^{-3} \end{bmatrix}$$

$$= \begin{bmatrix} 8 & 0 & -3 & 11 \\ -5 & 0 & -3 & 11 \\ -5 & 0 & 0 & 0 \end{bmatrix}$$
This downgaph is available free or charge on Definitional of the properties of the p